CNBC Matlab Mini-Course

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Day 2: More Stuff

Scientific Functions

Trig: sin, cos, tan, asin, acos, atan sinh, cosh, tanh, asinh, acosh, ...

Rounding: floor, ceil, round, fix

Modular: rem, mod

Exponential: exp, log, log2, log10, sqrt

Primes: factor, primes

Polynomials: roots, polyfit, polyval

Matrix Functions

Determinant:detInverse:inv, pinvEigenvalues:eig, svdFourrier:fft

And many, many more...

Inf and NaN

3/0 returns Inf

0/0 returns NaN

3+Inf

Inf/Inf



Complex Numbers

sqrt(-16)

3.5i

2 - 3.5i

(2+3i) * (4+5i)

Predicates

```
isreal(3)
isprime(1:13)
isnumeric([2 3 5])
isempty([ ])
isinf(Inf)
isnan(NaN)
islogical(1 == 1)
ischar('a')
isequal('foo', 'aardvark')
```

What percentage of the first 1000 integers is prime? mean(isprime(1:1000))

Return Values

Functions can return multiple values:

$$A = rand(5, 3);$$

s = size(A)

[rows, cols] = size(A)

Optional Return Values

Functions can choose whether to return values, depending on if the user is asking for values.

plot([1 2 3], [3 1 2])

no return value

h = plot([1 2 3], [3 1 2]) set(h, 'LineStyle', '--') set(h, 'LineWidth', 8) single return value

Variable Number of Arguments

Some functions accept a variable number of arguments:

peaks

peaks(10)

Variable In and Out

```
hist(randn(2000,1))
```

```
hist(randn(2000,1), 50)
```

```
counts = hist(randn(2000,1), 5)
```

```
[counts, centers] = hist(randn(2000,1), 5)
```

nargin and nargout

Inside a function, **nargin** is the number of input arguments supplied with the call.

nargout is the number of output arguments requested with the call.

Testing nargin/nargout

```
function [x,y,z] = nargtest(p,q,r,s,t)
 if nargout >= 1
  x = 50;
  if nargout >= 2
    y = 'foo';
                            Try:
    if nargout >= 3
                             a = nargtest(5,6,7)
     z = 3:7;
                              [a, b] = nargtest(3)
    end
                              [a, \sim, c] = nargtest(9,8)
  end
 end
 whos % show the local workspace
end
```



- **Base workspace:** variables created outside of any function exist in the base workspace.
- Local workspaces: each function executes in a separate local workspace holding the arguments, return variables, and any local variables created by the function.

Functions cannot access variables of the base workspace.

Name Spaces (cont.)

• **Global workspace:** variables declared global by a function are accessed in the global workspace.

It's a good idea to also declare the variable global in the base workspace.

Global Variables

```
global pts
pts = 0 : pi/20 : 2*pi ;
```

```
function h = circ(x,y)
  % draws a circle centered on (x,y)
  global pts
  hh = plot(x+cos(pts), y+sin(pts));
  if nargout > 0
    h = hh; % return h only if requested
  end
end
end
```

Scripts Called By Functions

- Scripts do not have their own workspaces.
- A script called from the keyboard executes in the base workspace.
- A script called from within a function executes in the function's local workspace.

Resetting Variables

clear x removes variable x and undoes any global declaration

You can also click on a variable in the workspace pane and hit the Delete key, or right-click on the variable and choose from the menu.

clear all clears everything

clear global clears global declarations

whos global shows all global variables



Taking Apart A Figure

```
clf, plot(rand(5, 3))
```

```
ax = get(gcf, 'Children')
get(ax)
```

```
lines = get(gca, 'Children')
get(lines(1))
```

Multiple Axes: Subplot

clf

Row-major order subplot(2,2,1), plot(rand(5, 5)) subplot(2,2,2), bar3(rand(5, 3)) subplot(2,2,3), a=rand(15, 1); pie(a, a > 0.7) subplot(2,2,4), polar(cos(0:150))

set(gca, 'Position', [0.32 0.1 0.4 0.4])

Exploring Graphics Objects

set(gca,'Units') set(gca)

propedit(gca) *click on "More Properties"*

Matlab online documentation: Help pulldown menu or '?' icon: > Documentation > MATLAB > Graphics > Graphics Objects

3D Graphics

peaks

rotate3d on

or put mouse in figure area and click on the 3D rotation arrow in the toolbar

set(gca, 'CameraViewAngleMode', 'manual') or right-click in the figure, select Rotate Options, then select Fixed Aspect Ratio Axes

Plotting Surfaces

[x, y, z] = peaks;

surf(x, y, z, z)

surf(x, y, z, x)

surf(x, y, z, rand(length(x)))

Plotting in 3D

Don't type all this in! Download this file: www.cs.cmu.edu/~dst/Tutorials/Matlab/helix.m or cd /afs/andrew/usr/dst/matlab

function helix pts = 0 : pi/20 : 4*pi;

$$x1 = cos(pts); y1 = sin(pts);$$

 $x2 = cos(pts+pi); y2 = sin(pts+pi);$

$$z = pts/(2*pi);$$

```
clf, whitebg(gcf, [0 0 0]), hold on
plot3(x1, y1, z, 'y')
plot3(x2, y2, z, 'w')
axis([ -3 3 -3 3 0 2])
view(95, 9)
end
```

Helix (cont.)

```
colors = 'rgbm';
```

```
for i = 4 : 4 : length(pts)-4
    plot3([x1(i) x2(i)], [y1(i) y2(i)], z([i i]), ...
        colors(ceil(rand(1)*length(colors))), 'LineWidth', 3)
end
```

```
axis off
set(gcf, 'Color', 'k')
set(gca, 'CameraViewAngleMode', 'manual')
az = -180;
while true
view(az, 9), pause(0.05)
az = az + 5;
end
```

Color Maps

- clf reset, peaks, colorbar
- m = colormap; whos m
- colormap(spring) brighten(0.5)
- colormap(jet)
- colormap(parula) colormap(bone) colormap(hot)
- colormapeditor



Northern parula

2D Data

```
[x, y] = meshgrid(-2 : 0.05 : 2);
z = sin(x) \cdot cos(y);
contour(z, 20)
imagesc(z)
colormap(hot)
imagesc(x(:), y(:), z)
surf(z), colormap(jet)
surfc(z)
```

Surface Objects

sphere

```
[x,y,z] = sphere(20);
x(1 : 5 : 21*21) = NaN;
surf(x, y, z)
alpha(0.7)
Use the rotate tool to rotate the sphere; set
Fixed Aspect Ratio Axes first.
```

```
surf(x, y, z, rand(size(x)))
shading interp, grid off, axis off
set(gcf, 'Color', 'w')
```

Data From Files

Create a file temps.txt: Use the "New Script" button.

Enter this data:

- 38 50
 42 53
 33 57
- 45 56
- 44 4641 40

Save the file as temps.txt

load temps.txt

plot(temps)

Importing Data From Files

• You can import data from Excel (and many other file formats) using the Import Data button.

Select the file you want to import; the wizard will guide you through the rest.

 There are also built-in functions specifically for dealing with Excel files: doc xlsread doc xlswrite

Curve Fitting for Extrapolation

- x = randn(1, 2000);
- y = sin(x) + 0.2 * randn(1, 2000) ; clf, hold on, plot(x, y, '.')
- c = polyfit(x, y, 3) Example polynomial representation: c = [5 - 1 4 3] $5x^3 - x^2 + 4x + 3$
- pts = min(x) : range(x)/100 : max(x);
- plot(pts, polyval(c, pts), 'r', 'LineWidth', 3)

Saving Variables

clear all

- a = 'aardvark'
- [x, y, z] = sphere(5);

save stuff.mat

clear all

whos -file stuff.mat

load stuff.mat

save junk.dat x y -ascii type junk.dat

General Operating System Stuff

pwd

cd

dir

ls *.m

delete stuff.mat

!ps -a

Debugging

Poor man's debugger:

Remove semicolons from assignments. Add 'quoted strings' in appropriate places. Add a call to **keyboard**. (Use **return** to return from keyboard input mode.)

function y = buggy(vec)
p = vec > 5
'got this far'
keyboard
z = p * vec
y = sin(z);
end

Try: buggy([4 6]) Type 'return' to exit keboard mode and continue.

The Matlab Debugger

- dbtype helix
- dbstop helix 5
- helix
- dbstep
- dbstep 7
- whos

Look at the Stack pulldown menu in the toolbar. dbstep 30 dbquit dbclear helix doc debug

Formatted Output

for i = 1 : 10 fprintf('The square root of %2d is %f \n', ... i, sqrt(i)) end

doc fprintf

title(sprintf('f(x) over range %g to %g', ... -3.5, 5.125))