

# Efficient Coding of Natural Sounds

**Michael Lewicki**

Center for the Neural Basis of Cognition &  
Department of Computer Science  
Carnegie Mellon University

How does the brain encode complex sensory signals?

# Outline

Motivations

Efficient coding theory

Application to natural sounds

Interpretation of experimental data

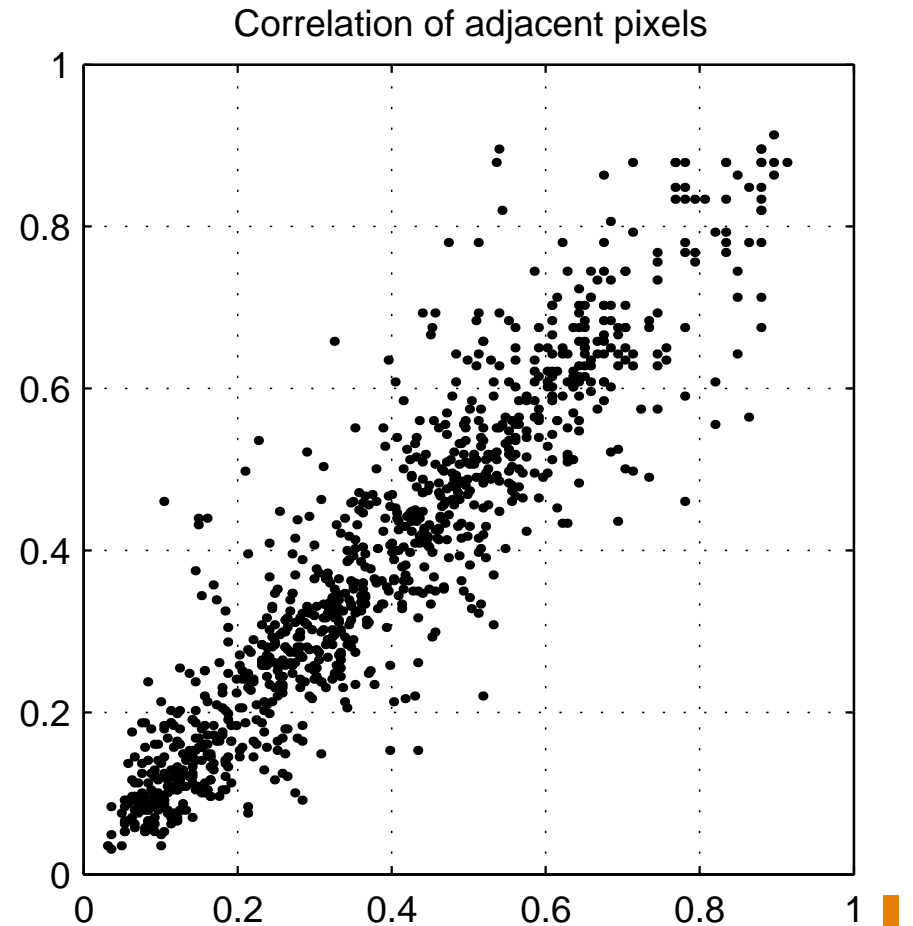
Efficient coding in population spike codes



*A wing would be a most mystifying structure  
if one did not know that birds flew.*

Horace Barlow, 1961

# Natural signals are redundant



Efficient coding hypothesis (Attneave, 1954; Barlow, 1961; et al):

Sensory systems encode only non-redundant structure

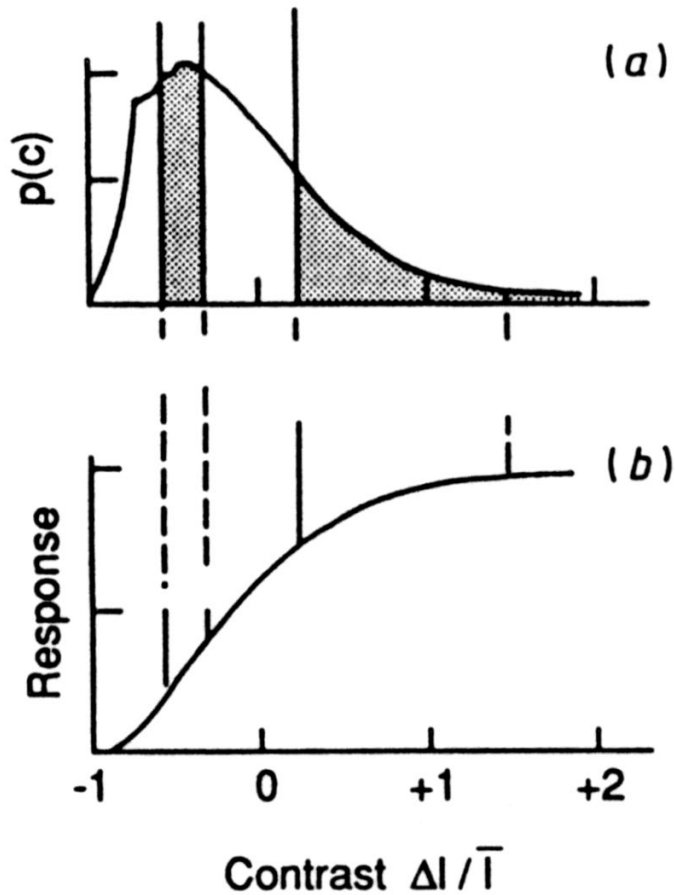
# Why code efficiently?

Information bottleneck of sensory coding:

- restrictions on information flow rate
  - channel capacity of sensory nerves
  - computational bottleneck
  - $5 \times 10^6 \rightarrow 40 - 50$  bits/sec■
- facilitate pattern recognition
  - independent features are more informative
  - better sensory codes could simplify further processing■
- other ideas
  - efficient energy use
  - faster processing time■

How do we use this hypothesis to predict sensory codes?■

# A simple example: efficient coding of a single input



(from Atick, 1992)

## How to set sensitivity?

- too high  $\Rightarrow$  response saturated
- too low  $\Rightarrow$  range under utilized

- inputs follow distribution of sensory environment
- encode so that output levels are used with equal frequency
- each response state has equal area ( $\Rightarrow$  equal probability)
- continuum limit is cumulative pdf of input distribution

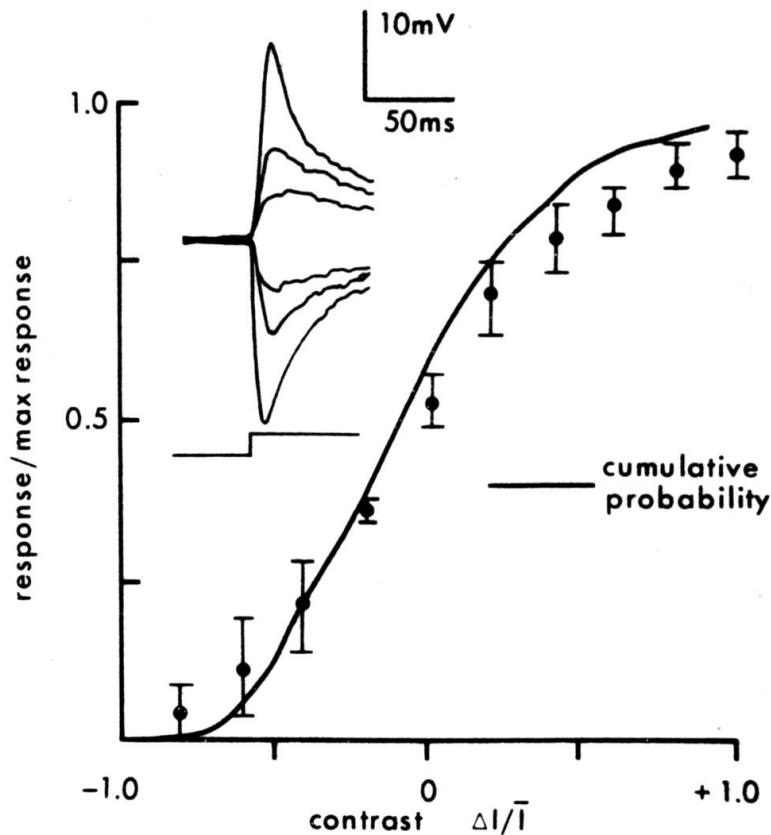
For  $y = g(c)$

$$\frac{y}{y_{max}} = \int_{c_{min}}^c P(c') dc'$$

# Testing the theory: Laughlin, 1981

Laughlin, 1981:

- predict response of fly LMC (large monopolar cells)
  - interneuron in compound eye
- output is graded potential



- collect natural scenes to estimate stimulus pdf
- predict contrast response function  
⇒ fly LMC transmits information efficiently

What about complex sensory patterns?

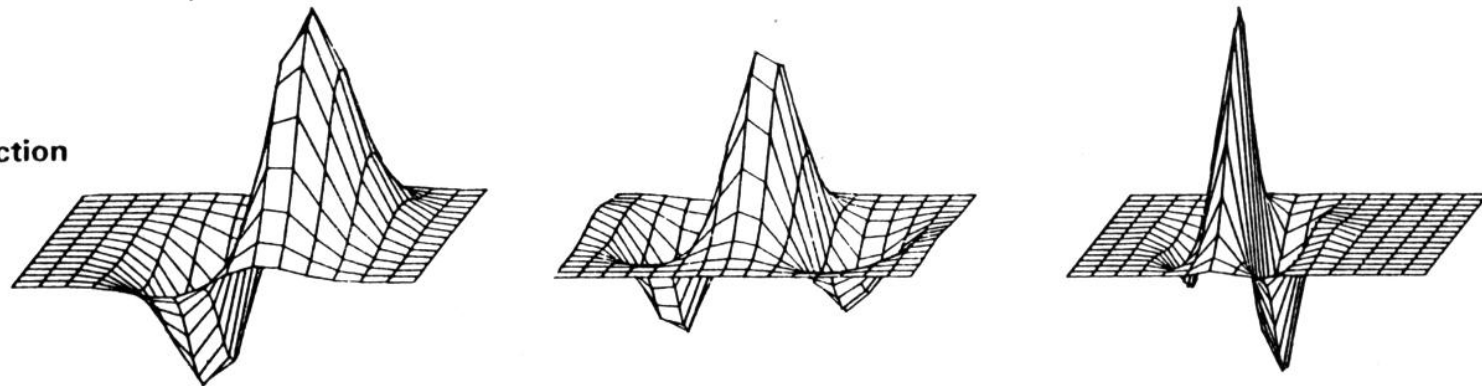


# V1 receptive fields are consistent with efficient coding theory

2D Receptive Field



2D Gabor Function



Difference



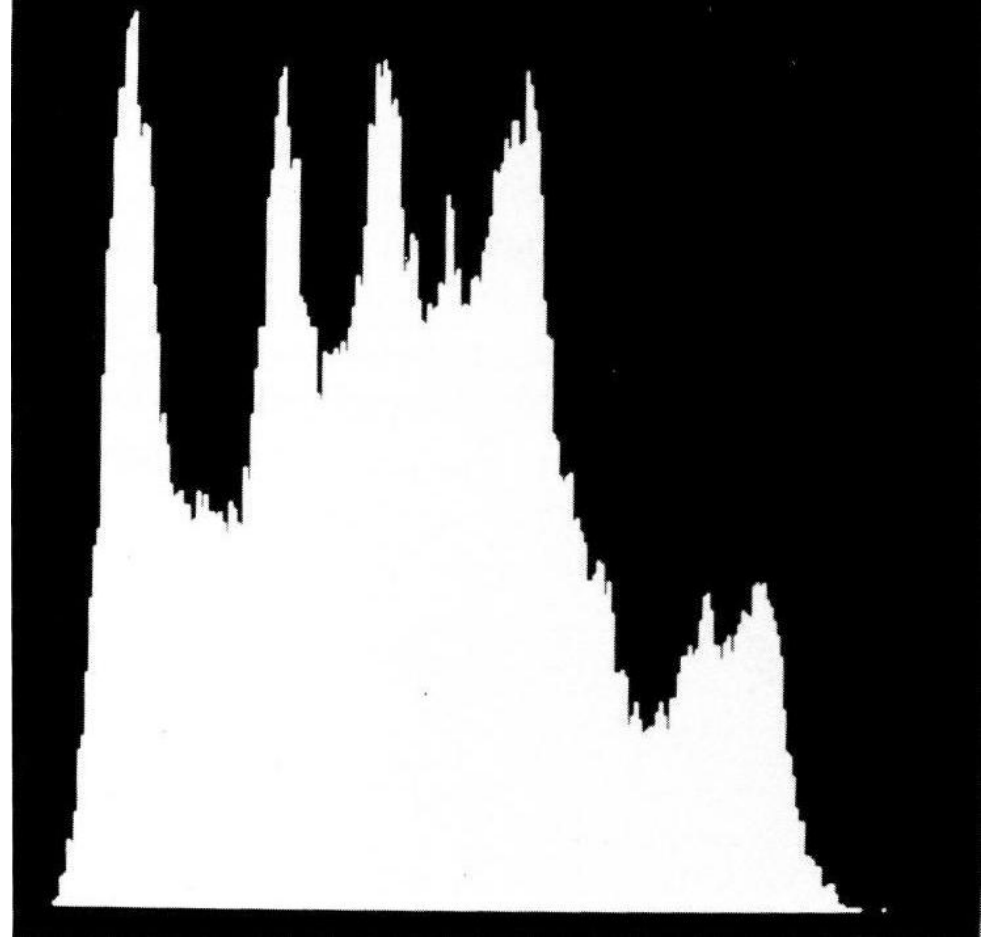
V1 receptive fields are well-fit by 2D Gabor functions (Jones and Palmer, 1987).■

Does this yield an efficient code?■

# Coding images with pixels (Daugman, 1988)



Lena

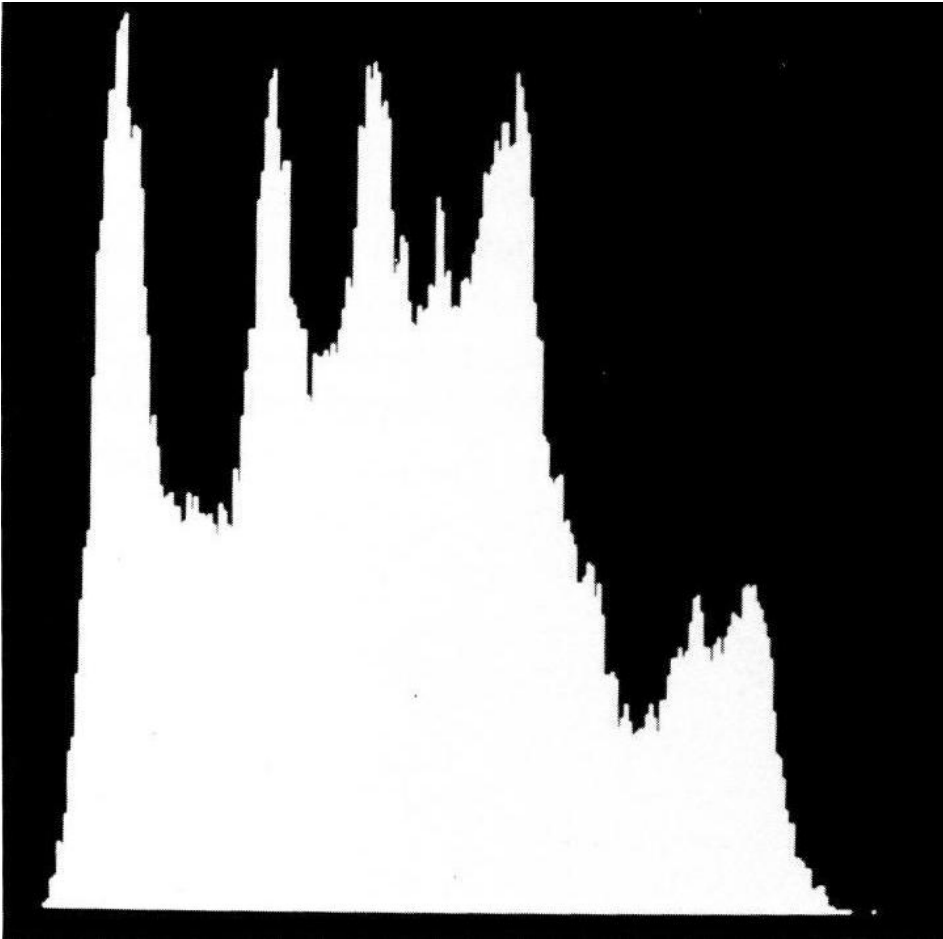


histogram of pixel values

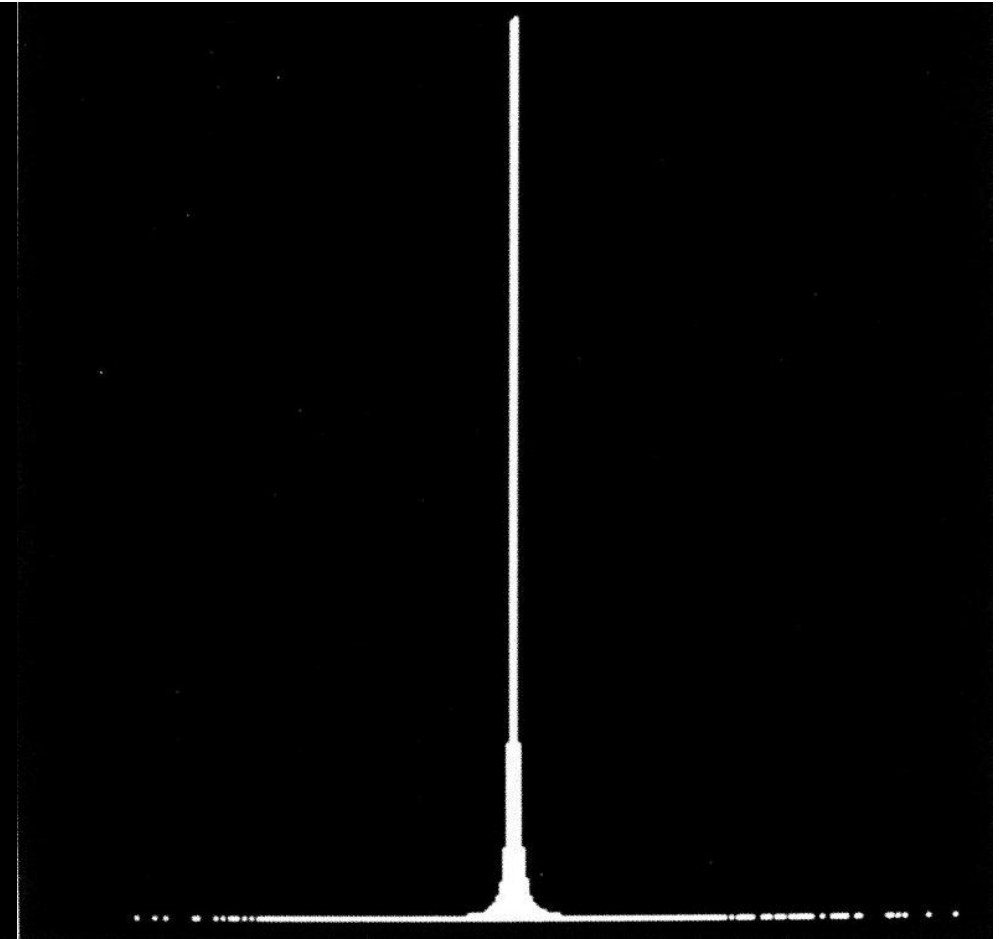
Entropy = 7.57

High entropy means high redundancy  $\Rightarrow$  a very *inefficient* code

# Recoding with Gabor functions (Daugman, 1988)



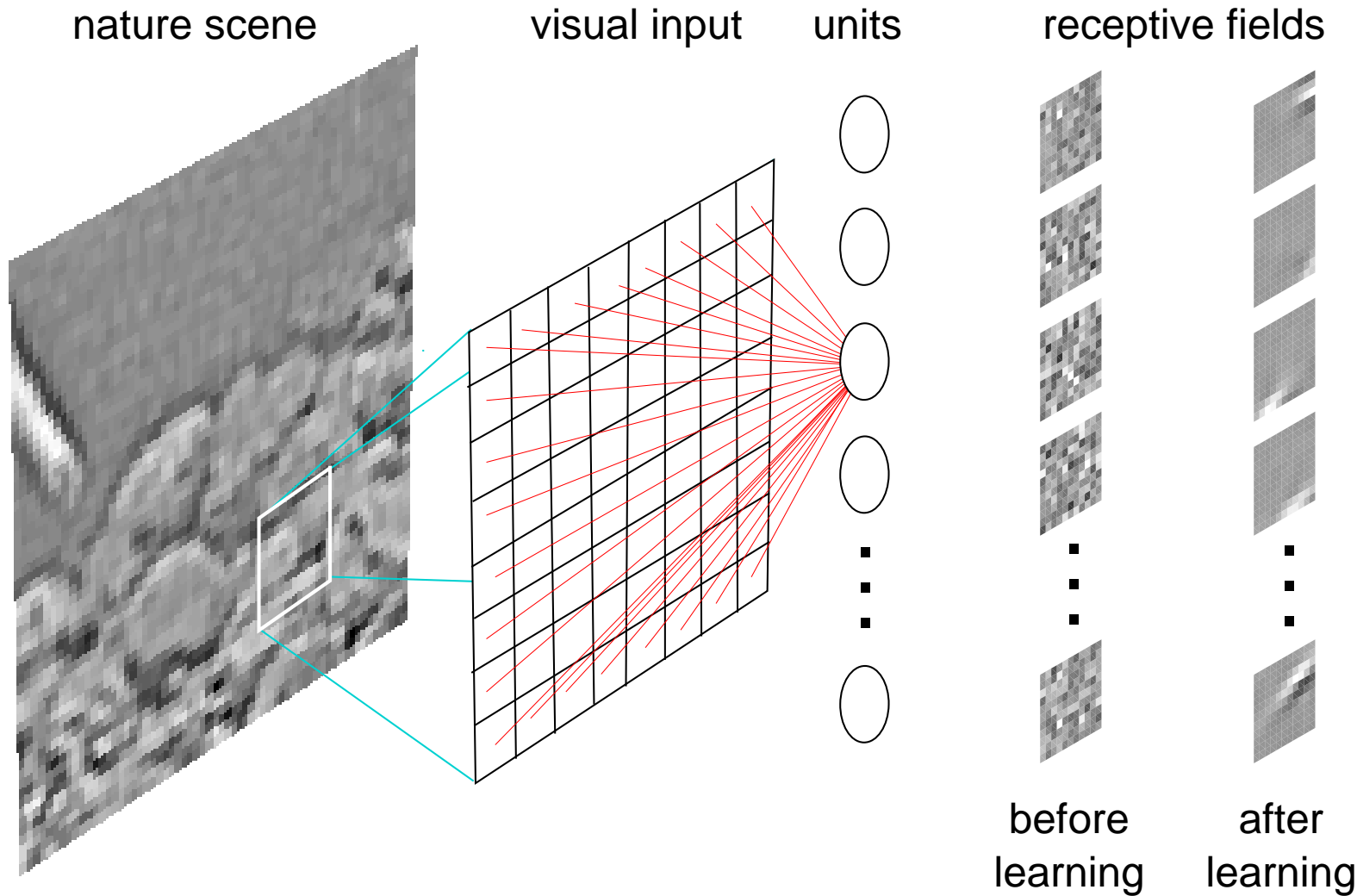
Pixel entropy = 7.57 bits



Recoding with 2D Gabor functions  
Filter output entropy = 2.55 bits. ■

Can these codes be predicted?

# Sparse coding of natural images (Olshausen and Field, 1996)

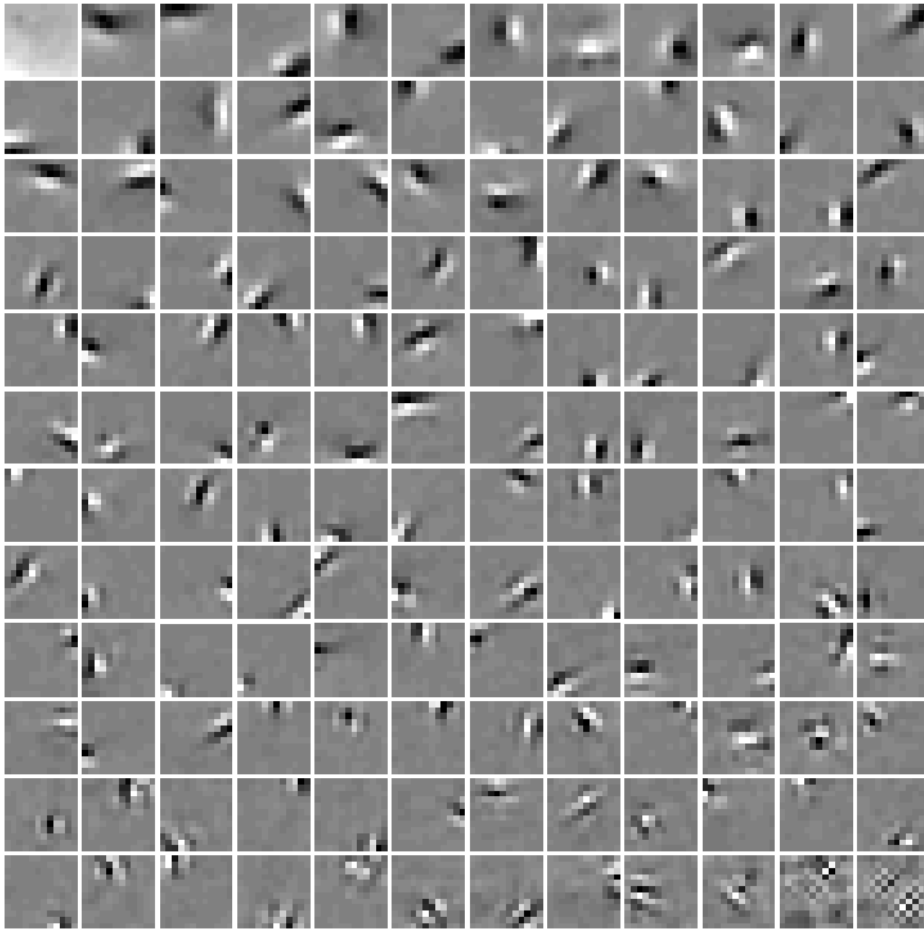


Adapt population of receptive fields to

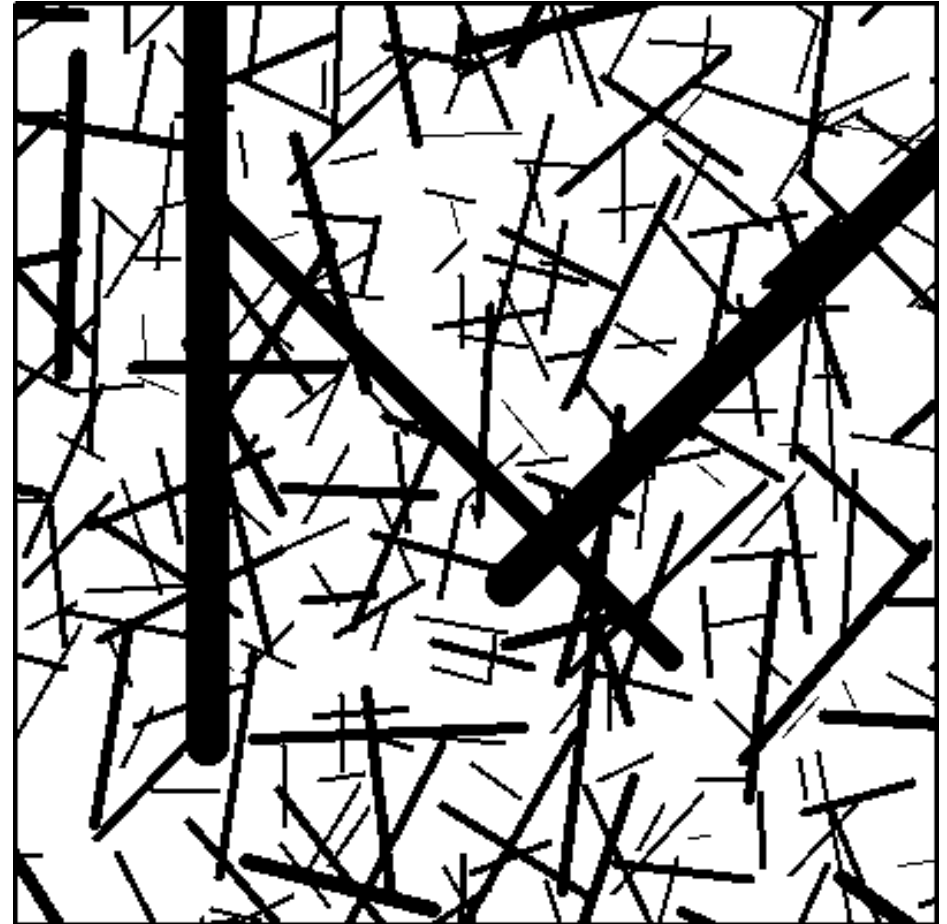
- accurately encode an ensemble of natural images
- maximizing the sparseness of the output, i.e. minimizing entropy.

# Theory predicts entire population of receptive fields

(Lewicki and Olshausen, 1999)

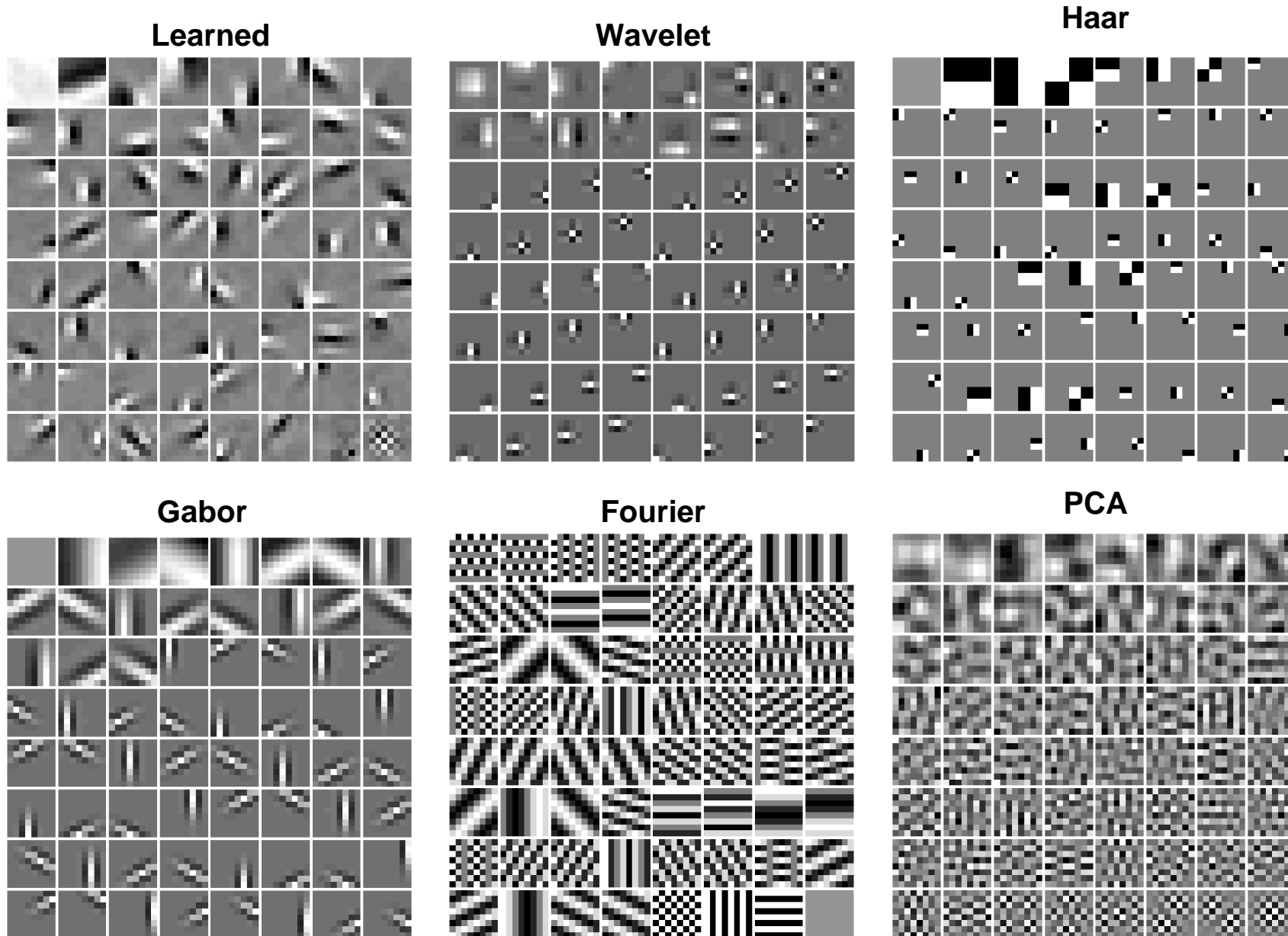


Population of receptive fields.  
(black = inhibitory; white = excitatory) ■



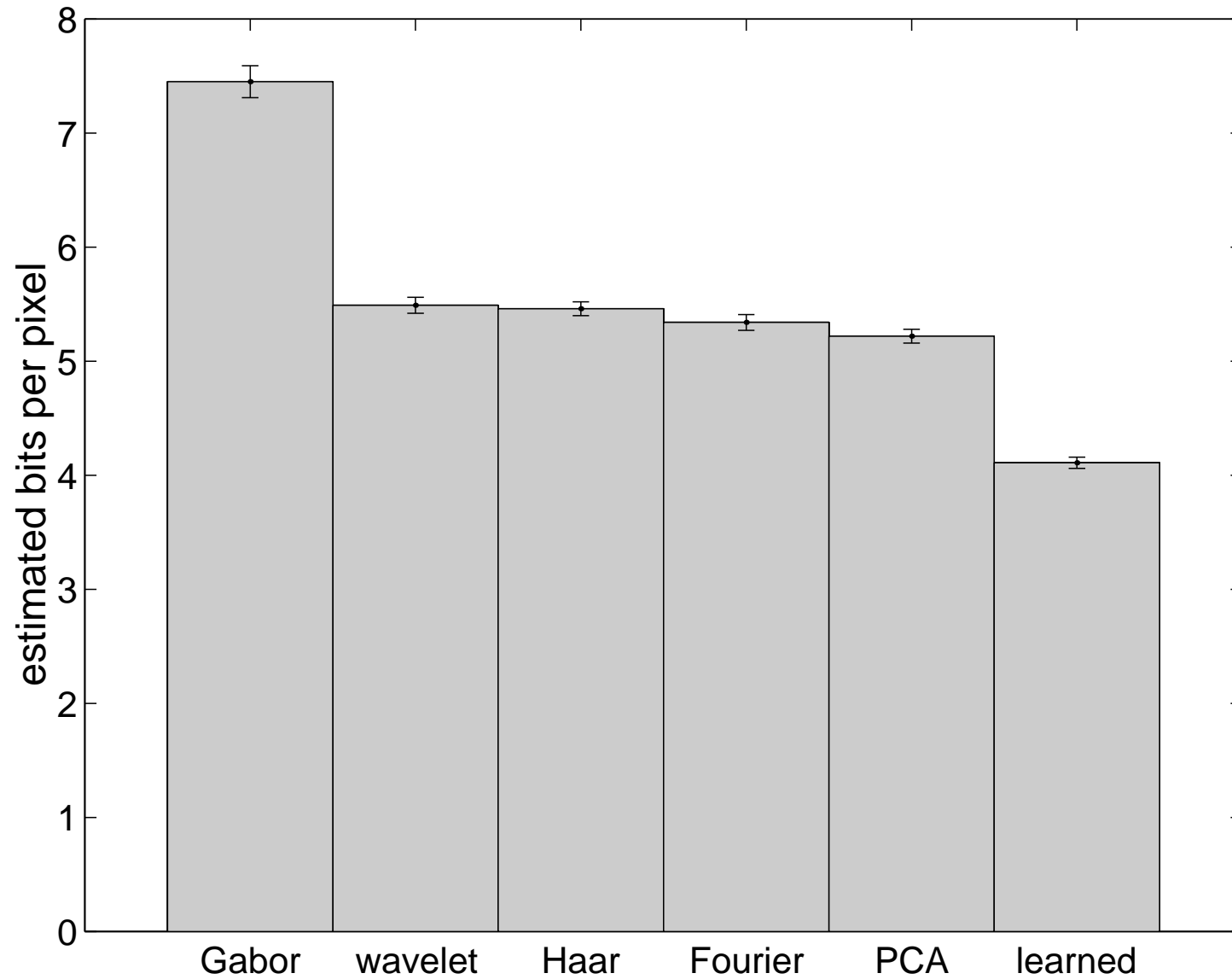
Overlaid response property schematics. ■

# Algorithm selects best of many possible sensory codes



(Lewicki and Olshausen, 1999) Theoretical perspective:  
*Not edge “detectors” but an efficient way to describe natural, complex images.*

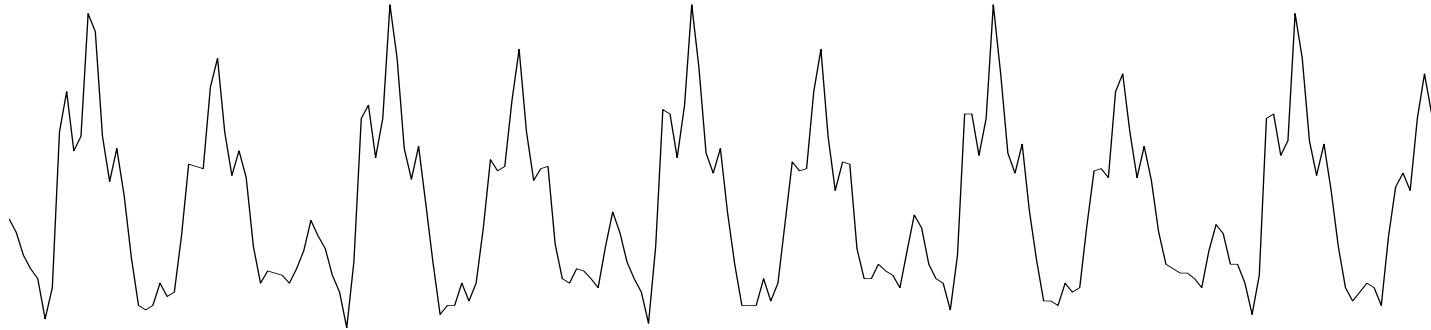
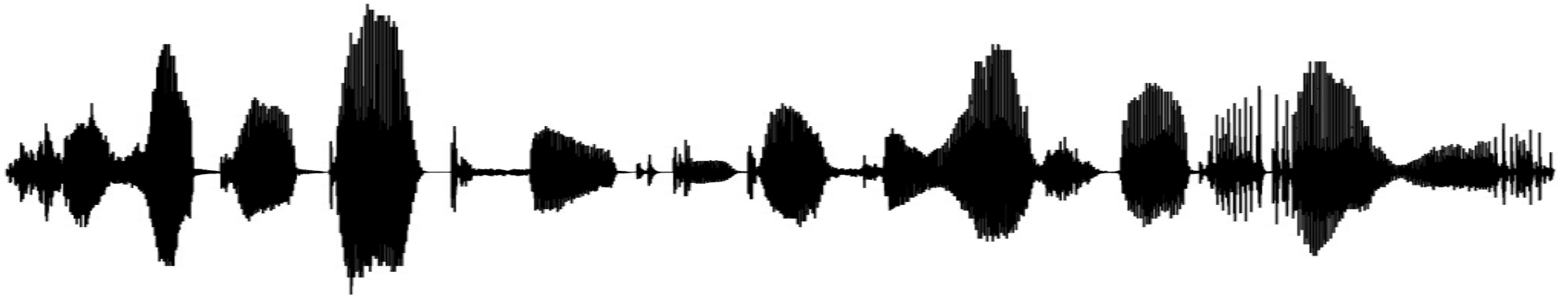
## Comparing codes on natural images



## *Efficient coding of natural sounds*



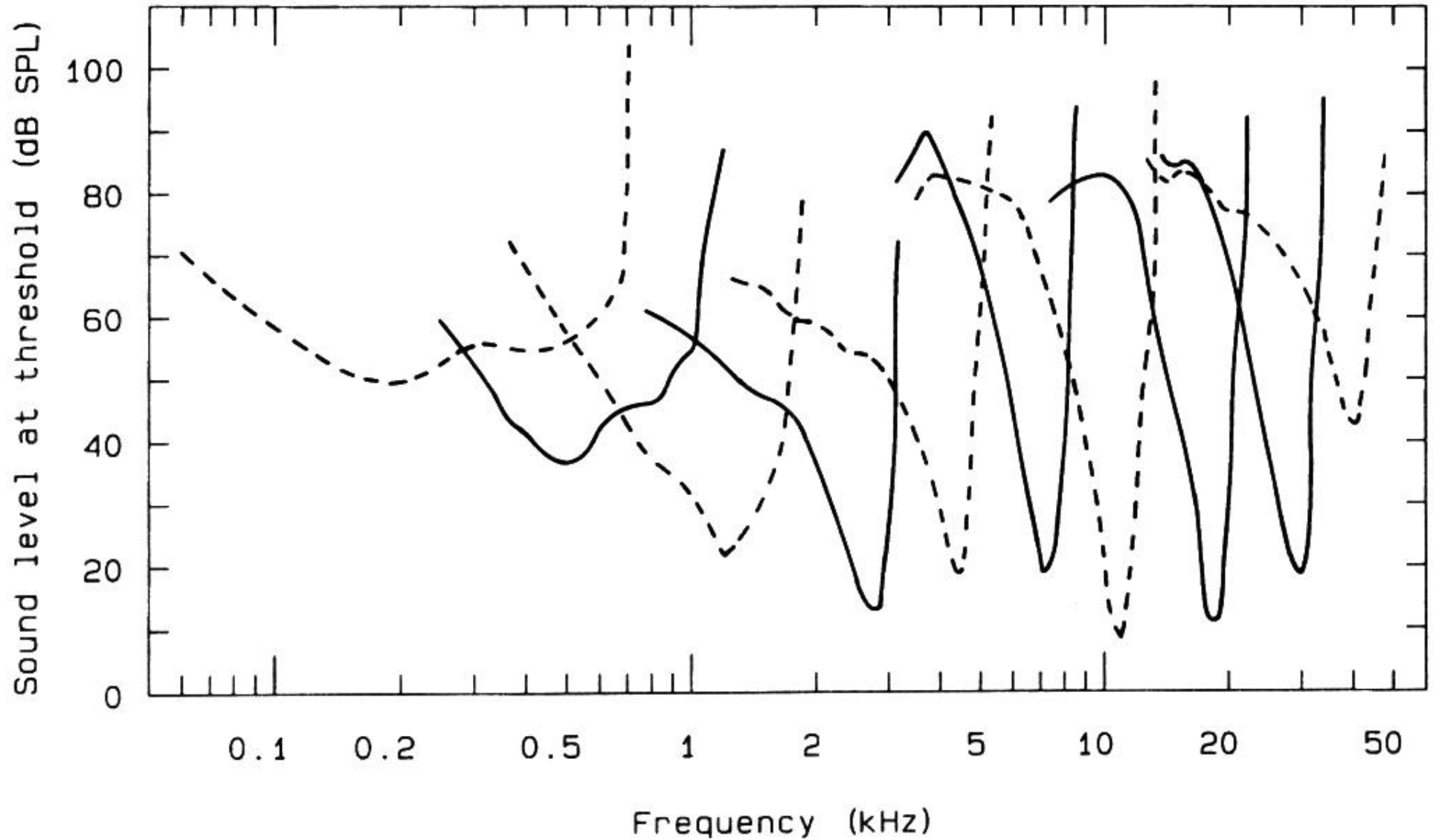
# Efficient coding: focus on coding waveform directly



Goal:

*Predict optimal transformation of acoustic waveform  
from statistics of the acoustic environment.*

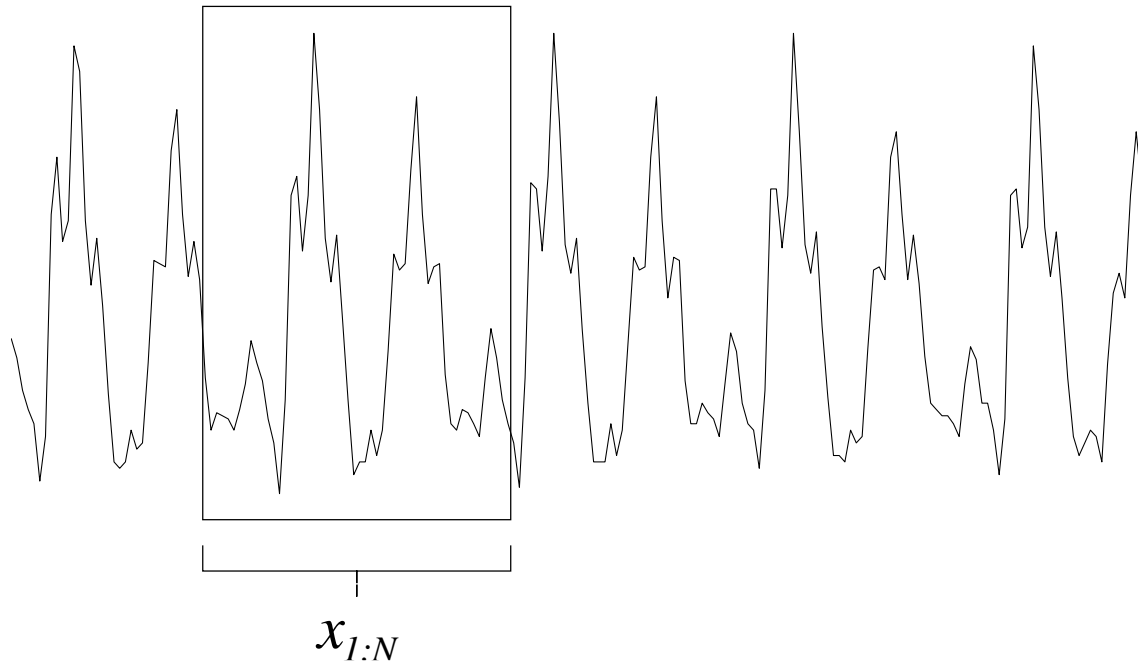
# Why encode sound by frequency?



Auditory tuning curves.

# A simple model of waveform encoding

Data consists of waveform segments sampled randomly from a sound ensemble:



Filterbank model:

$$a_i(t) = \sum_{\tau=0}^{N-1} x(t - \tau) h_i(\tau)$$

How do derive the filter shapes  $h_i(t)$  that optimize coding efficiency? ■

Model only describes signals within the window of analysis. ■

# Information theoretic viewpoint

Use Shannon's source coding theorem.

$$\begin{aligned}\mathcal{L} = E[l(X)] &\geq \sum_x p(x) \log \frac{1}{q(x)} \blacksquare \\ &= \sum_x p(x) \log \frac{p(x)}{q(x)} + \sum_x p(x) \log \frac{1}{p(x)} \\ &= D_{KL}(p||q) + H(p) \blacksquare\end{aligned}$$

If model density  $q(x)$  equals true density  $p(x)$  then  $D_{KL} = 0$ .

$\Rightarrow q(x)$  gives *lower bound* on average code length.

*greater coding efficiency*  $\Leftrightarrow$  *more learned structure*  $\blacksquare$

## Principle

*Good codes capture the statistical distribution of sensory patterns.*  $\blacksquare$

How do we describe the distribution?  $\blacksquare$

# Describing signals with a simple statistical model

Goal is to *encode* the data to desired precision

$$\begin{aligned}\mathbf{x} &= \vec{a}_1 s_1 + \vec{a}_2 s_2 + \cdots + \vec{a}_L s_L + \vec{\epsilon} \\ &= \mathbf{A}\mathbf{s} + \boldsymbol{\epsilon}\end{aligned}$$

Can solve for  $\hat{\mathbf{s}}$  in the no noise case

$$\hat{\mathbf{s}} = \mathbf{A}^{-1}\mathbf{x}$$

Want algorithm to choose optimal  $\mathbf{A}$  (i.e. the basis matrix).

# Algorithm for deriving efficient codes

Learning objective:

*maximize coding efficiency*

⇒ maximize  $P(\mathbf{x}|\mathbf{A})$  over  $\mathbf{A}$  (basis for analysis window, or filter shapes).■

Probability of pattern ensemble is:

$$P(\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N|\mathbf{A}) = \prod_k P(\mathbf{x}_k|\mathbf{A}) \quad \blacksquare$$

To obtain  $P(\mathbf{x}|\mathbf{A})$  marginalize over  $\mathbf{s}$ :

$$\begin{aligned} P(\mathbf{x}|\mathbf{A}) &= \int d\mathbf{s} P(\mathbf{x}|\mathbf{A}, \mathbf{s})P(\mathbf{s}) \\ &= \frac{P(\mathbf{s})}{|\det \mathbf{A}|} \quad \blacksquare \end{aligned}$$

Using *independent component analysis* (ICA) to optimize  $\mathbf{A}$ :

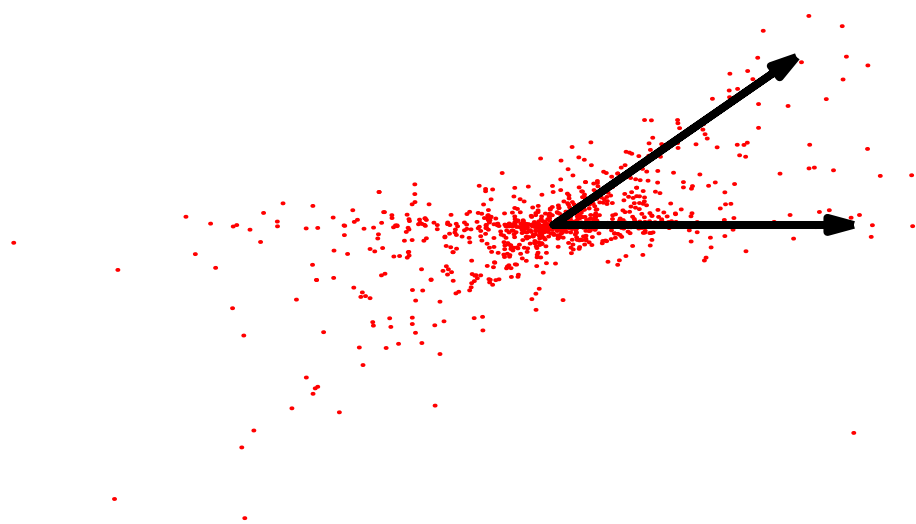
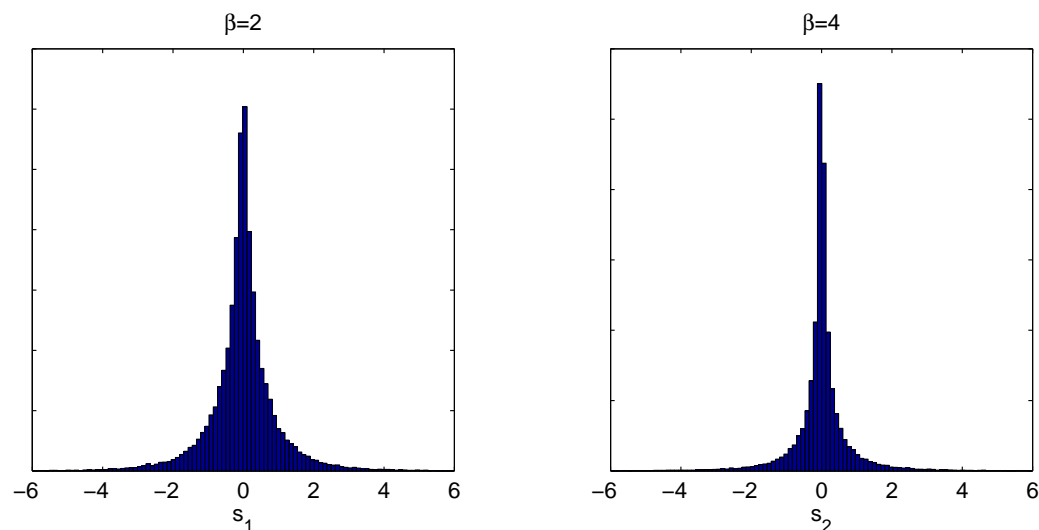
$$\begin{aligned} \Delta \mathbf{A} &\propto \mathbf{A}\mathbf{A}^T \frac{\partial}{\partial \mathbf{A}} \log P(\mathbf{x}|\mathbf{A}) \\ &= -\mathbf{A}(\mathbf{z}\mathbf{s}^T - \mathbf{I}), \end{aligned}$$

where  $\mathbf{z} = (\log P(\mathbf{s}))'$ . Use  $P(s_i) \sim \text{Expwr}(s_i|\mu, \sigma, \beta_i)$ .■

This learning rule:

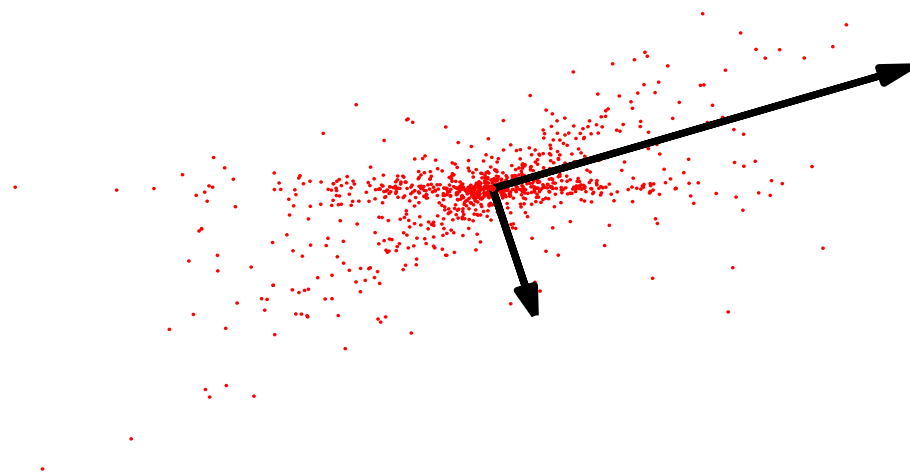
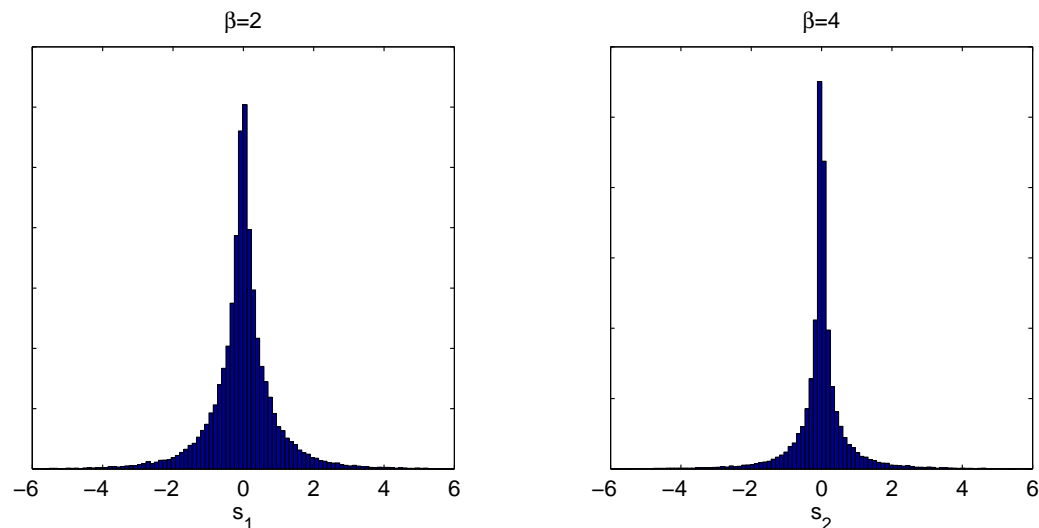
- learns features that capture the most structure
- optimizes the efficiency of the code■

# Modeling Non-Gaussian distributions with ICA



- Typical coeff. distributions of natural signals are *non-Gaussian*.
- Independent component analysis (ICA) describes the statistical distribution of non-Gaussian distributions
- The distribution is fit by optimizing the filter shapes.
- Unlike PCA, vectors are not restricted to be orthogonal.
- This permits a much better description of the actual distribution of natural signals.

# Modeling Non-Gaussian distributions with ICA



- Typical coeff. distributions of natural signals are *non-Gaussian*.
- Independent component analysis (ICA) describes the statistical distribution of non-Gaussian distributions
- The distribution is fit by optimizing the filter shapes.
- Unlike PCA, vectors are not restricted to be orthogonal.
- This permits a much better description of the actual distribution of natural signals.



# Efficient coding of natural sounds: Learning procedure

To derive the filters:

- select sound segments randomly from sound ensemble
- optimize filter shapes to maximize coding efficiency■

*What sounds should we use?■*

What are auditory systems adapted for?

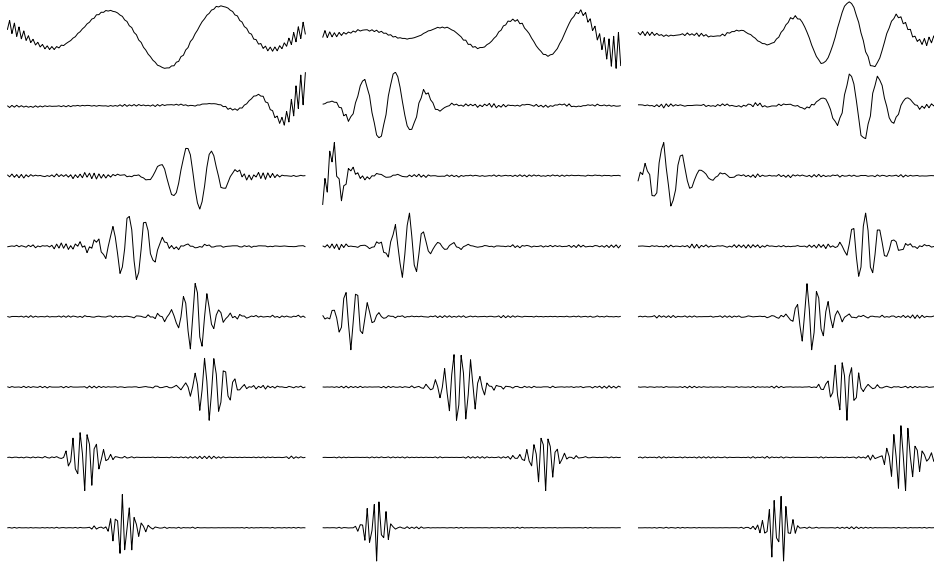
- localization / environmental sounds?
- communication / vocalizations?
- specific tasks, e.g sound discrimination?■

We used the following sound ensembles:

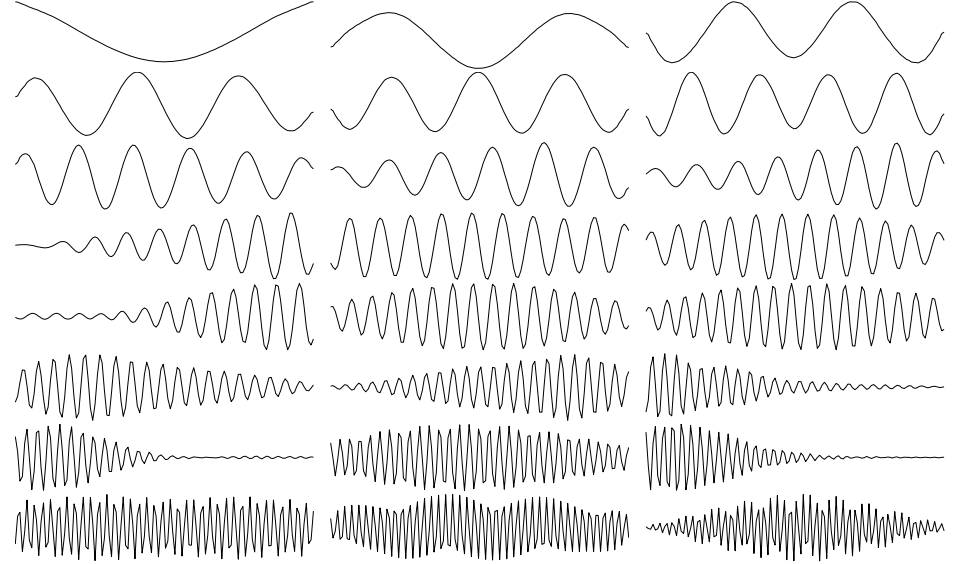
- non-harmonic environmental sounds (e.g. [footsteps](#), [stream sounds](#), etc.)
- animal vocalizations (rainforest mammals, e.g [chirping](#), [screeching](#), [cries](#), etc.)
- [speech](#) (samples from 100 male and female speakers from the TIMIT corpus)■

# Results of adapting filters to different sound classes

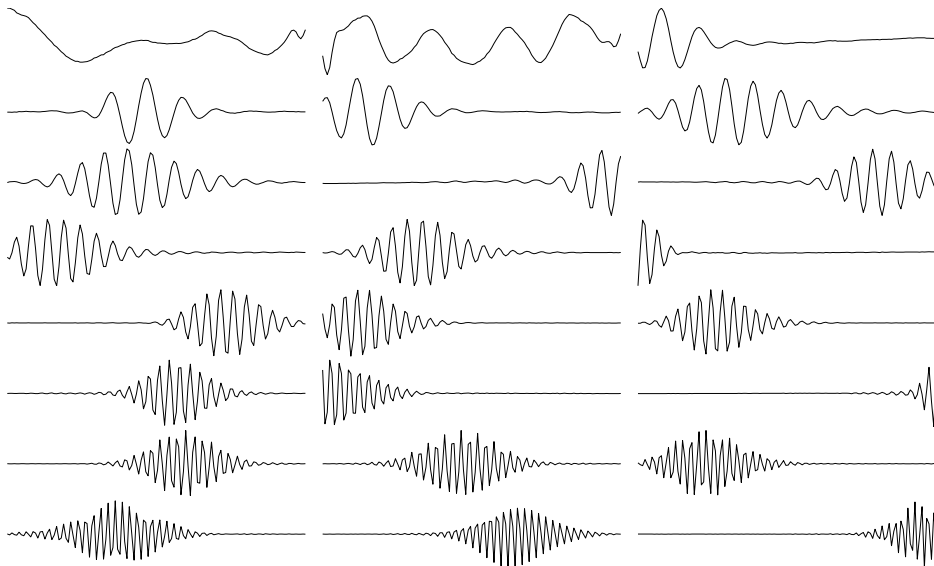
Efficient filters for environmental sounds:



Efficient filters for animal vocalizations:

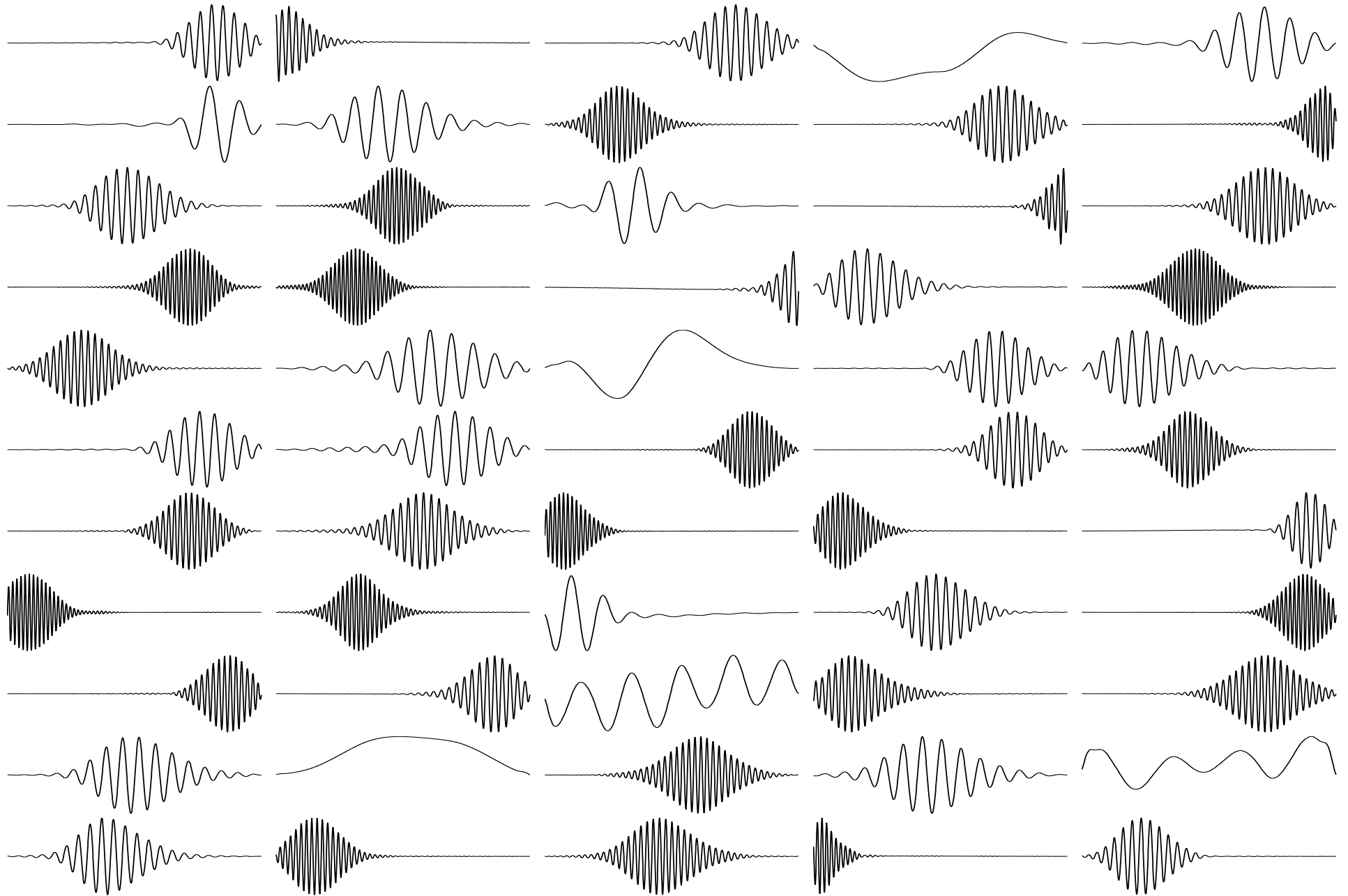


Efficient filters for speech:



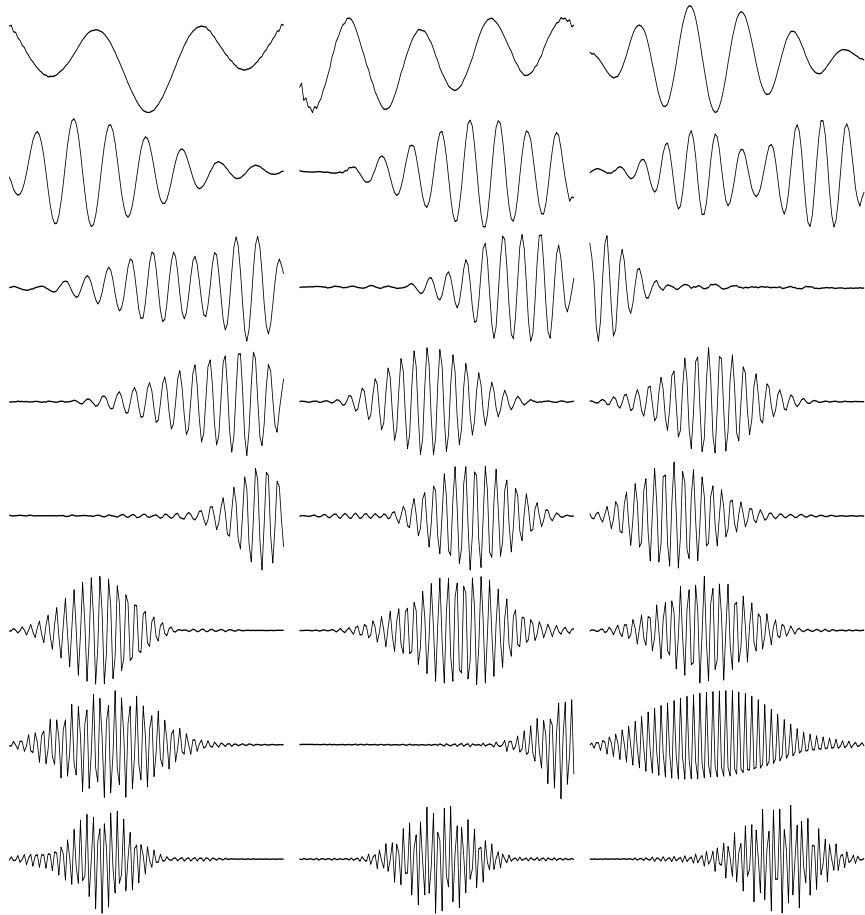
- Each result shows only a subset
- Auditory nerve filters best match those derived from environmental sounds and speech
- [learning movie](#)

# Upsampling removing aliasing due to periodic sampling

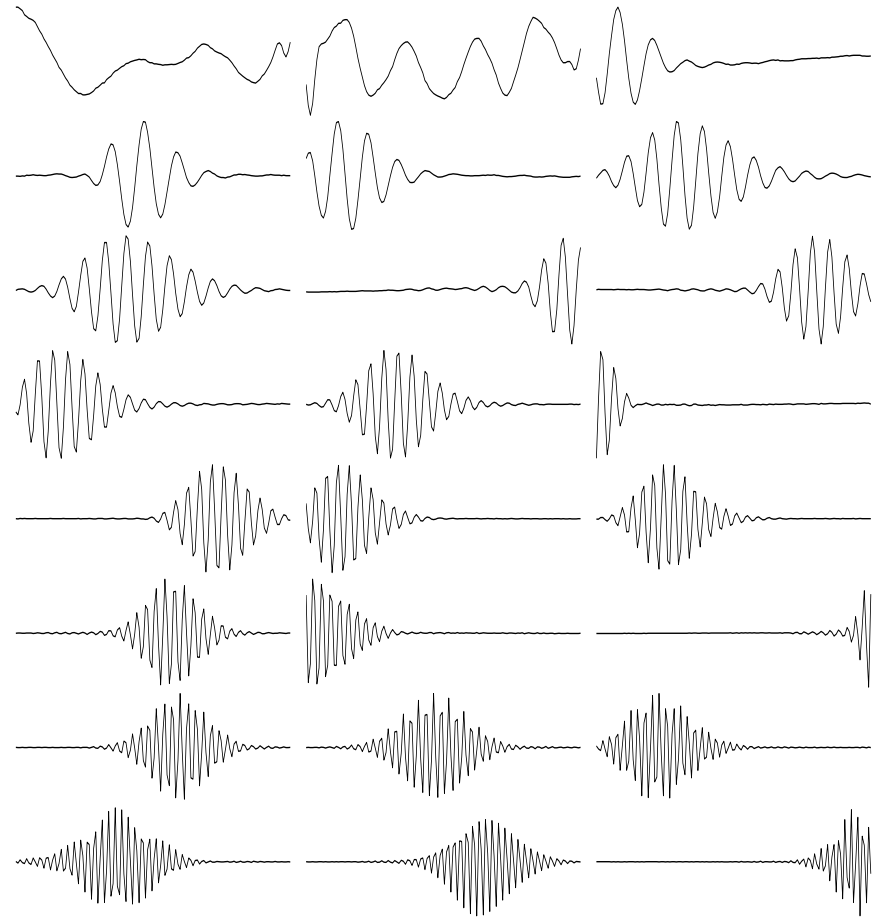


# A combined ensemble: env. sounds and vocalizations

Efficient filters for combined



Efficient filters for speech:



Can vary along the continuum by changing relative proportion, best match is 2:1  
⇒ speech is well-matched to the auditory code

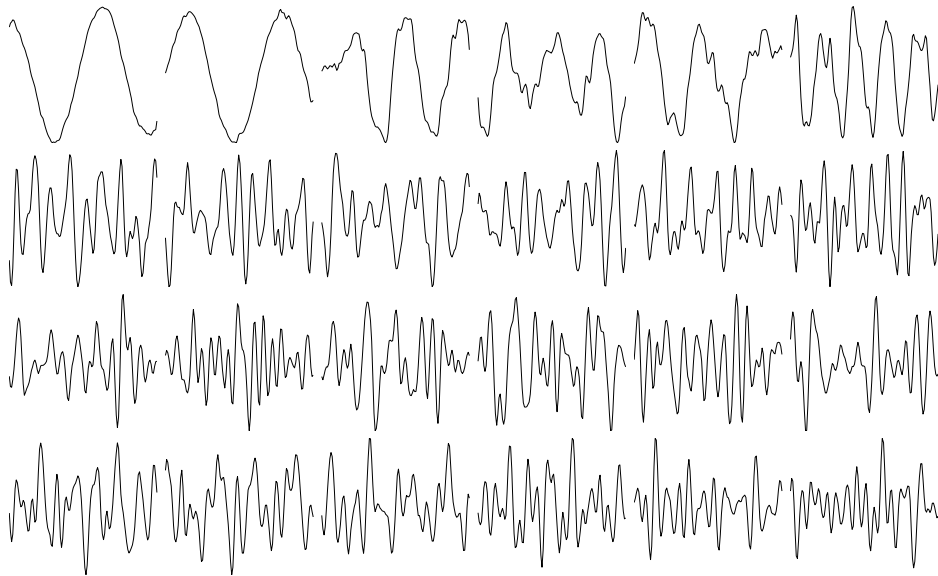
# Can decorrelating models also explain data?

Redundancy reduction models that adapt weights to decorrelate output activities assume a Gaussian model:

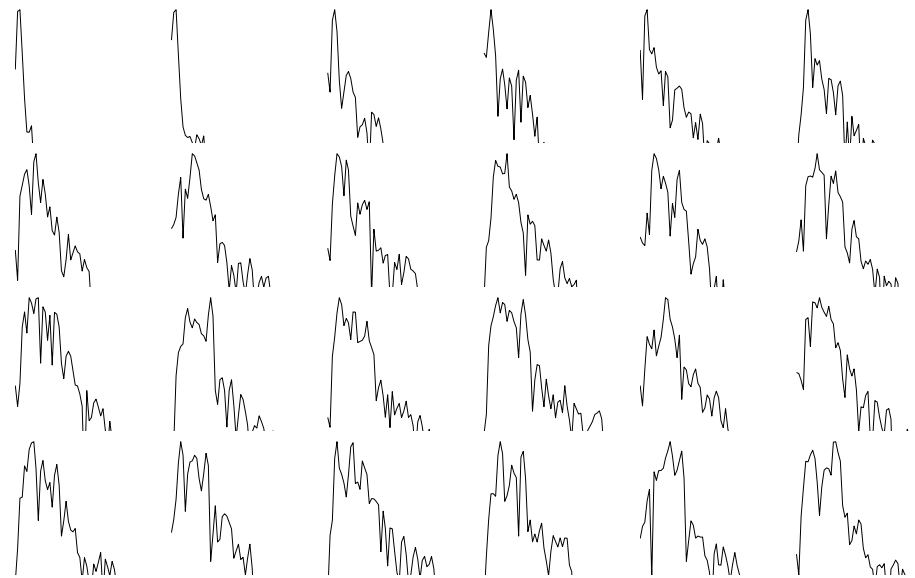
$$\mathbf{x} \sim \mathcal{N}(\mathbf{x}|\mu, \sigma)$$

Under this model, the filters can be derived with principal component analysis.

PCs of Environmental Sounds:



Corresponding Power Spectra:



⇒ just decorrelating the outputs does not yield time-frequency localized filters.

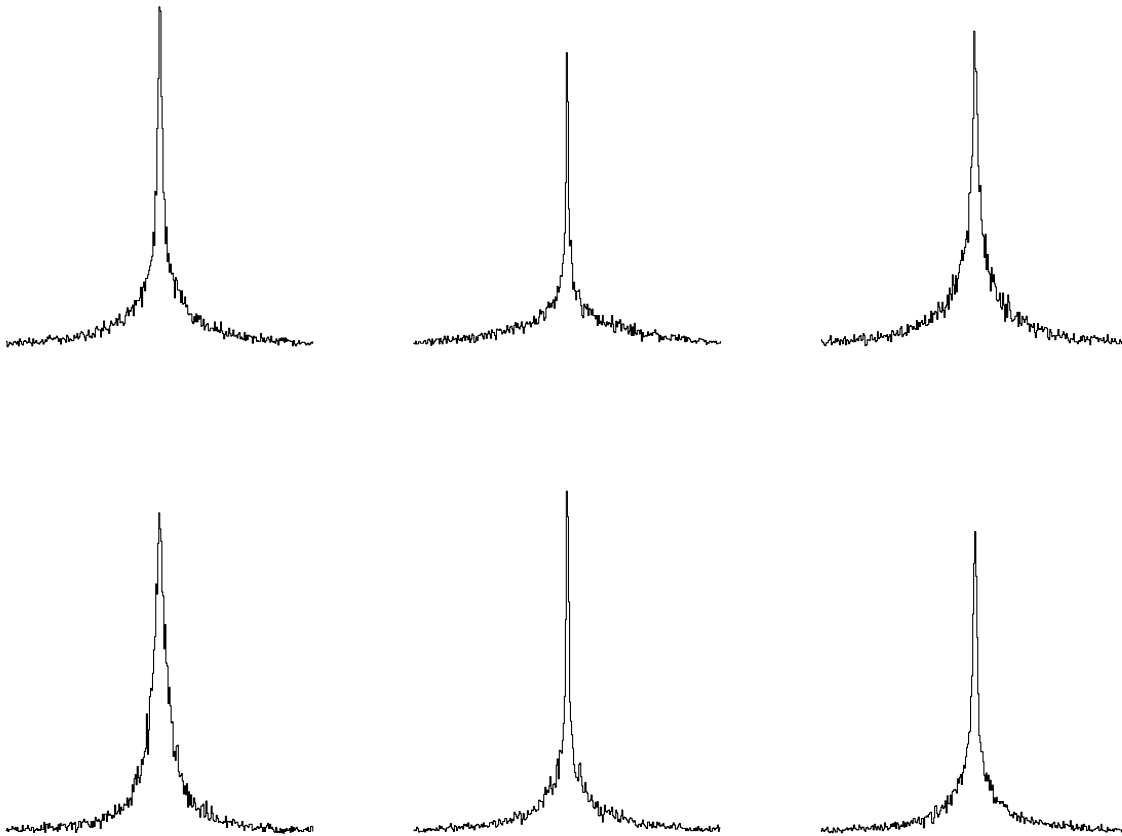
# Why doesn't PCA work?

Check assumptions:

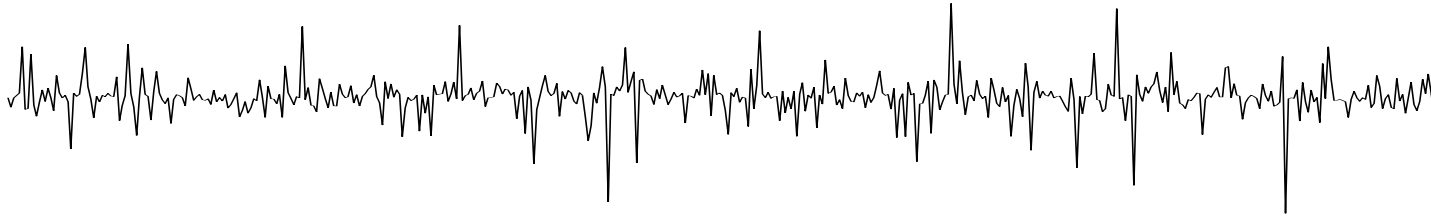
$$\mathbf{x} = \mathbf{A}\mathbf{s} \text{ and } \mathbf{x} \sim \mathcal{N}(\mathbf{x}|\mu, \sigma)$$

$\Rightarrow$  distribution of  $\mathbf{s}$  should also be Gaussian.

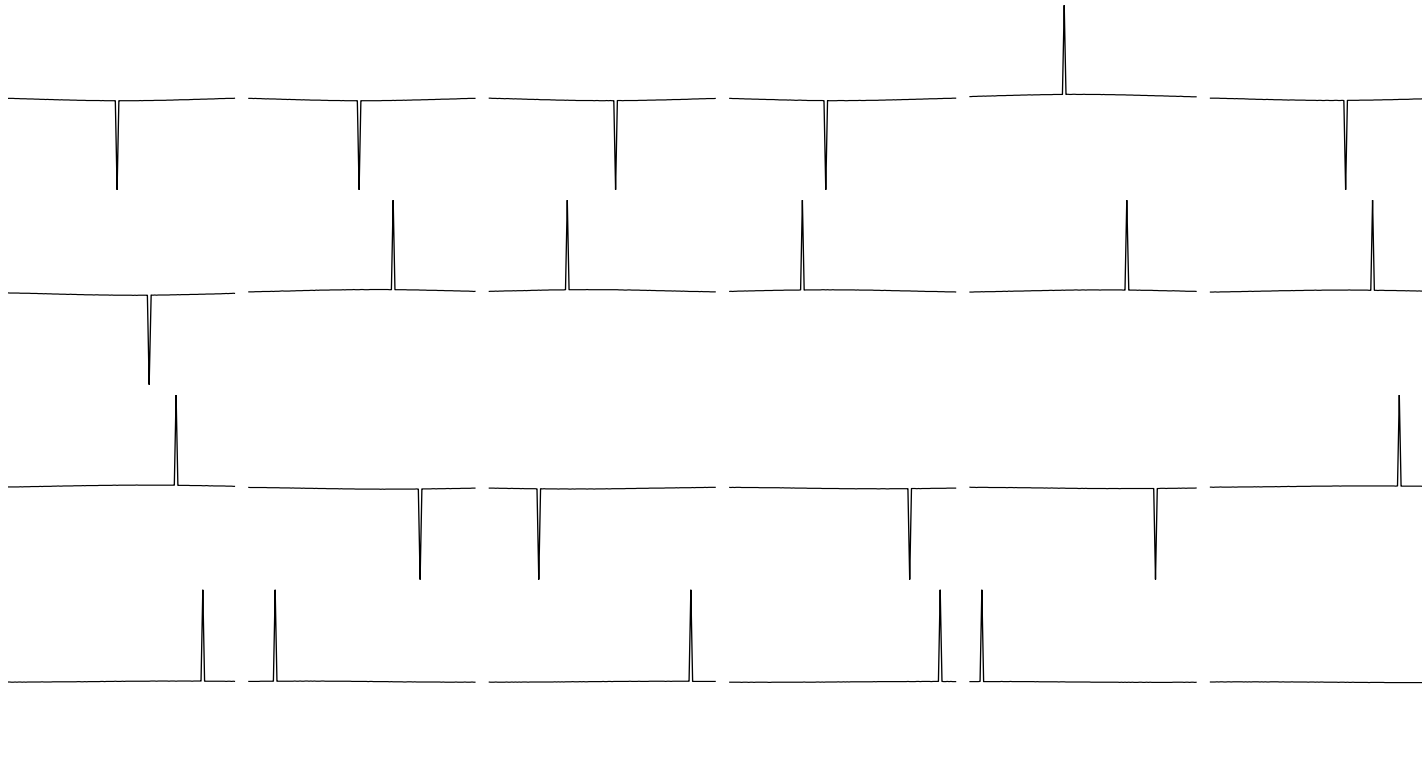
Actual distribution of filter coefficients:



# Efficient coding of sparse noise



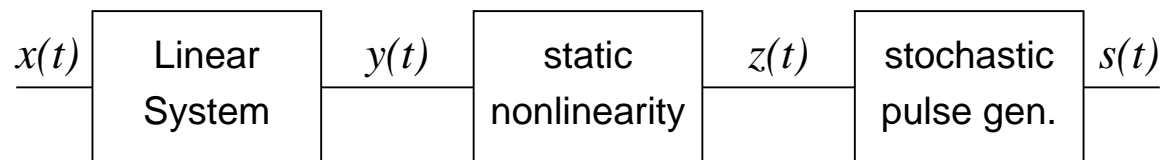
Learned sparse noise filters:



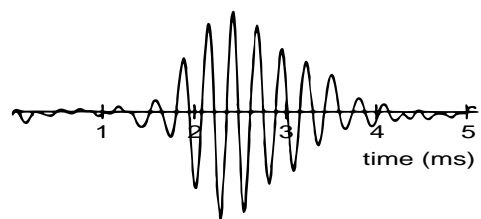
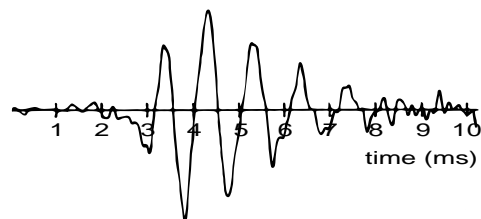
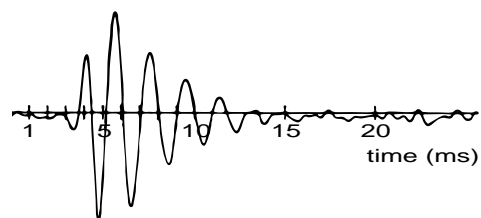
Efficient filters are delta functions that represent different time points in the analysis window.

...but what about the auditory system?

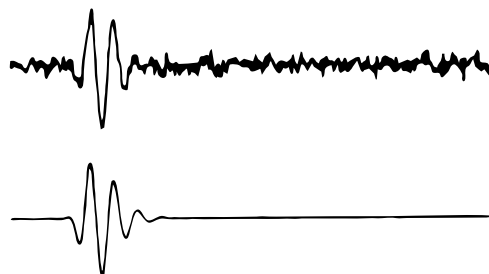
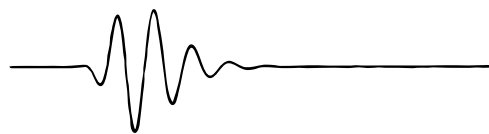
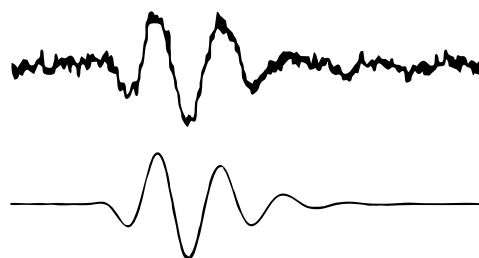
# Auditory filters estimated by reverse correlation



Cat auditory "revcor" filters:



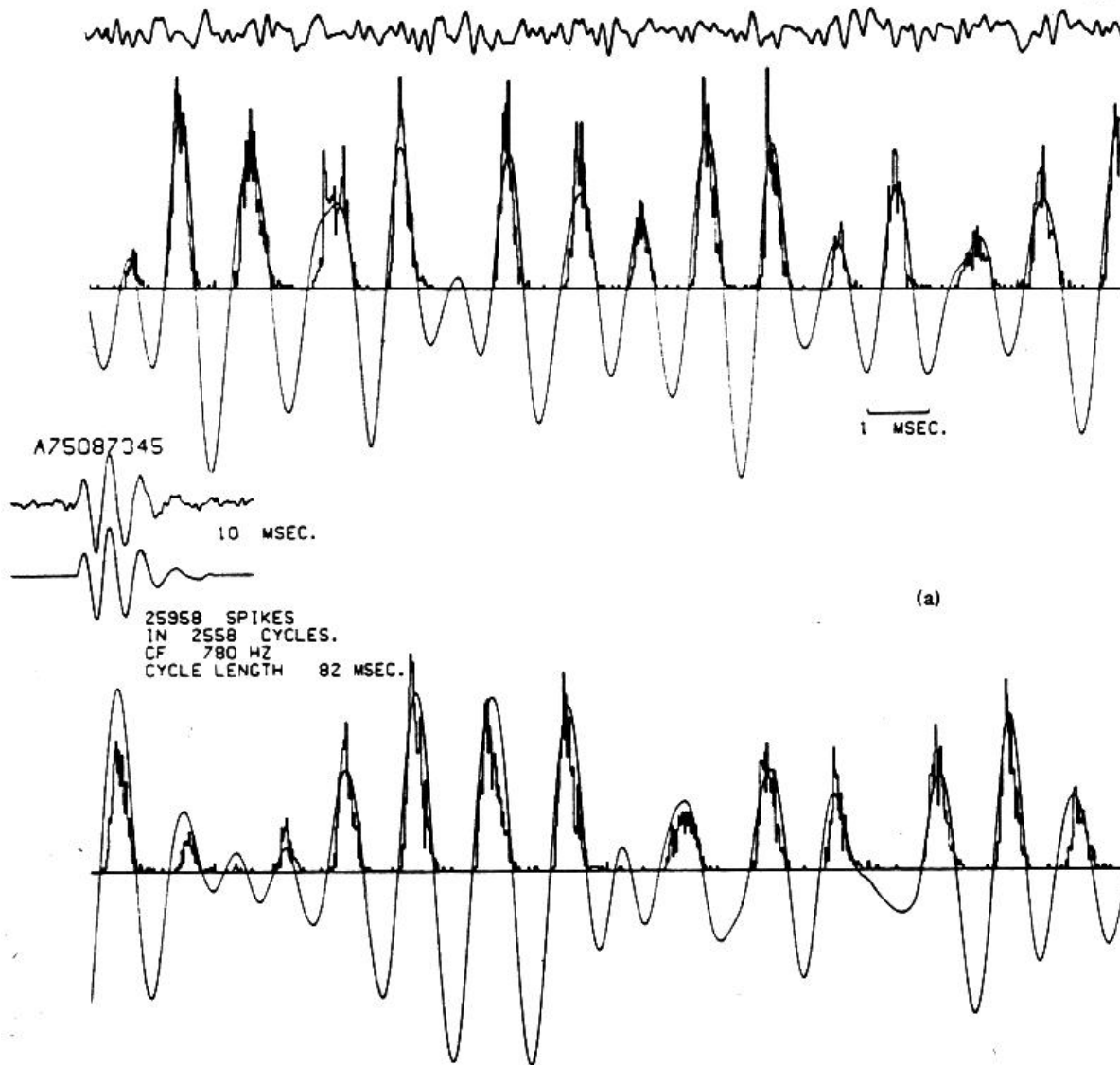
deBoer and deJongh, 1978



Carney and Yin, 1988



# Revcor filter predictions of auditory nerve response



(from de Boer and de Jongh, 1978).

- stimulus is white noise
- histogram: measured auditory nerve response
- smooth curve: predicted response

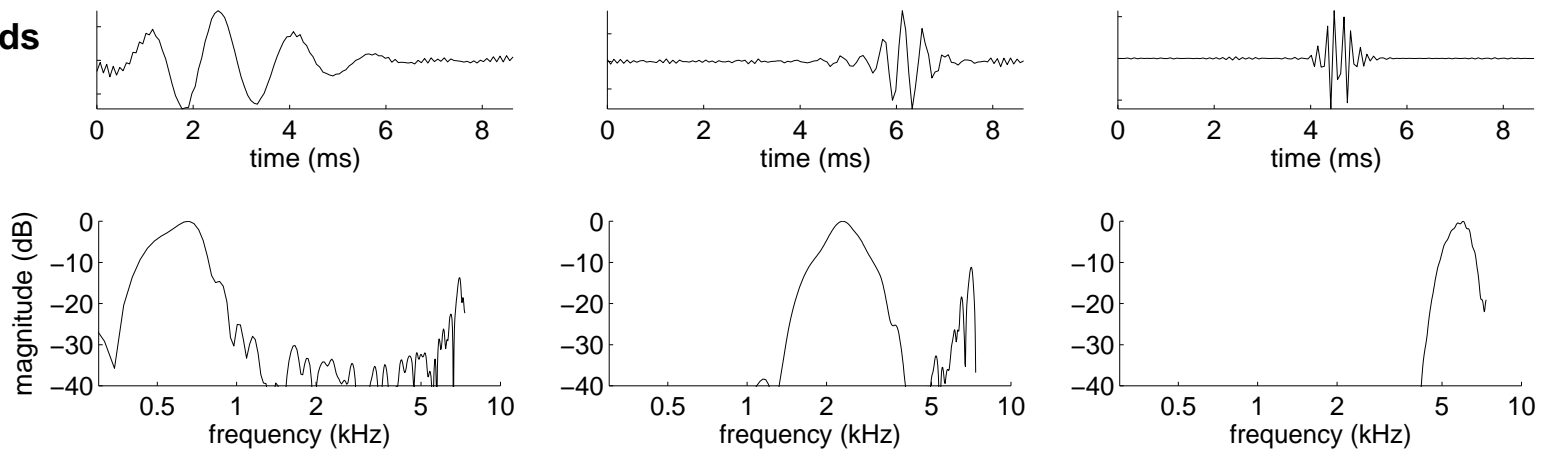
Conclusion:

*Shape and distribution of revcor filters account for a large part of the auditory sensory code.*

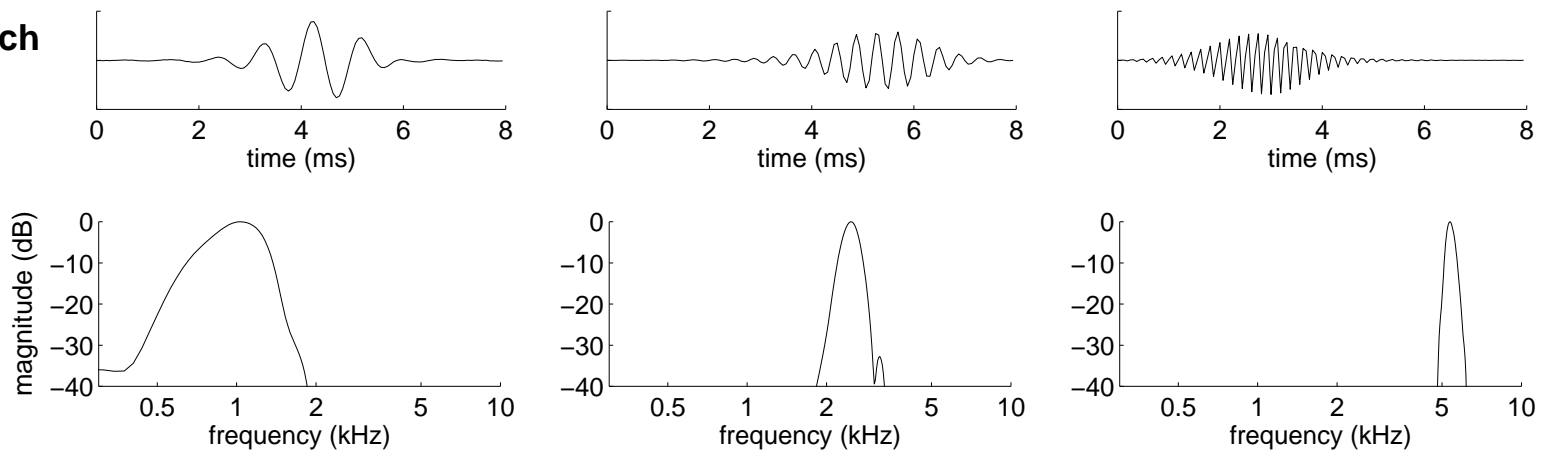
We want to match more than just individual filters:

*How do we characterize the population?*

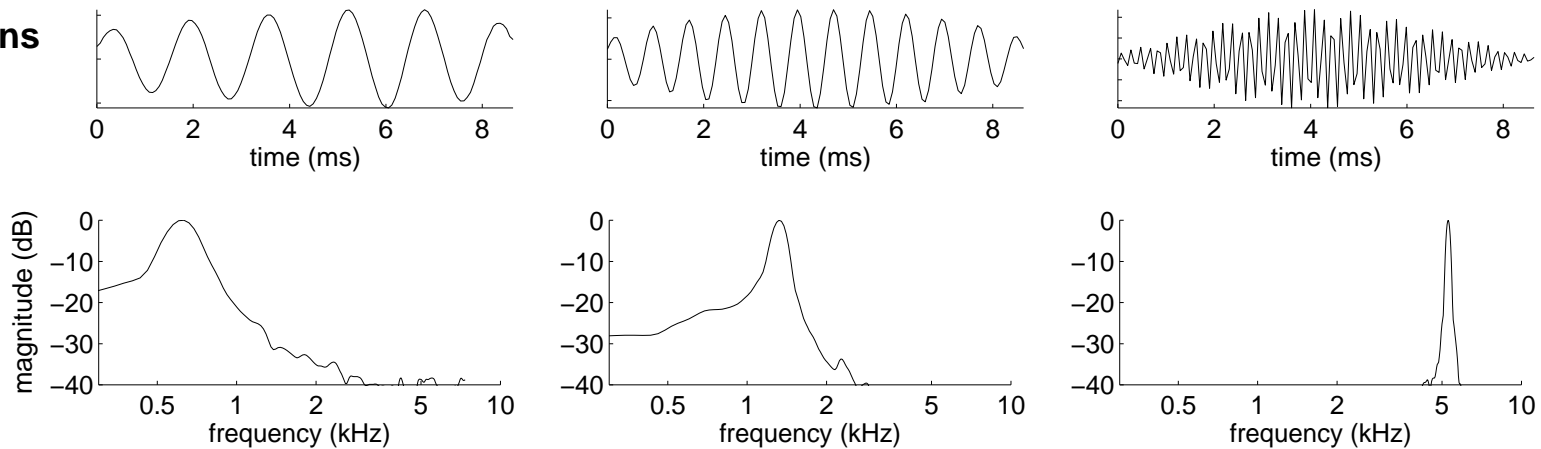
### env. sounds



### speech



### vocalizations

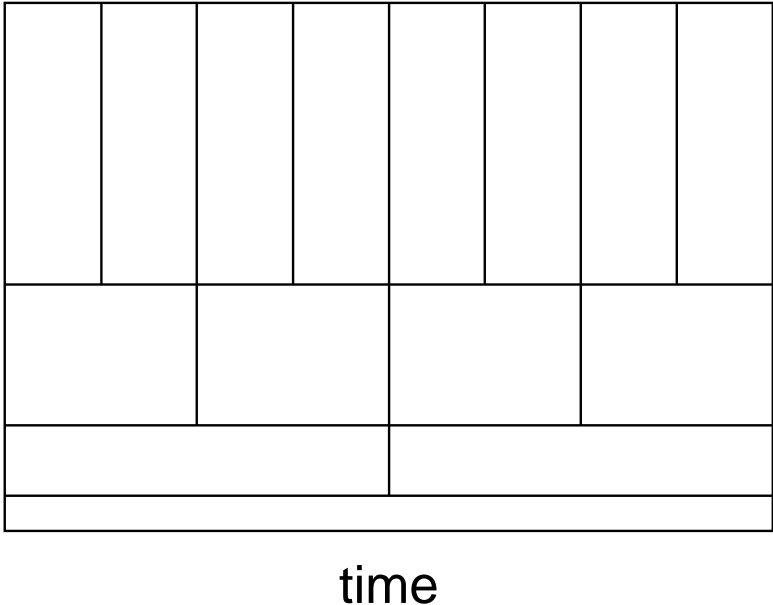


# Schematic time-frequency distributions

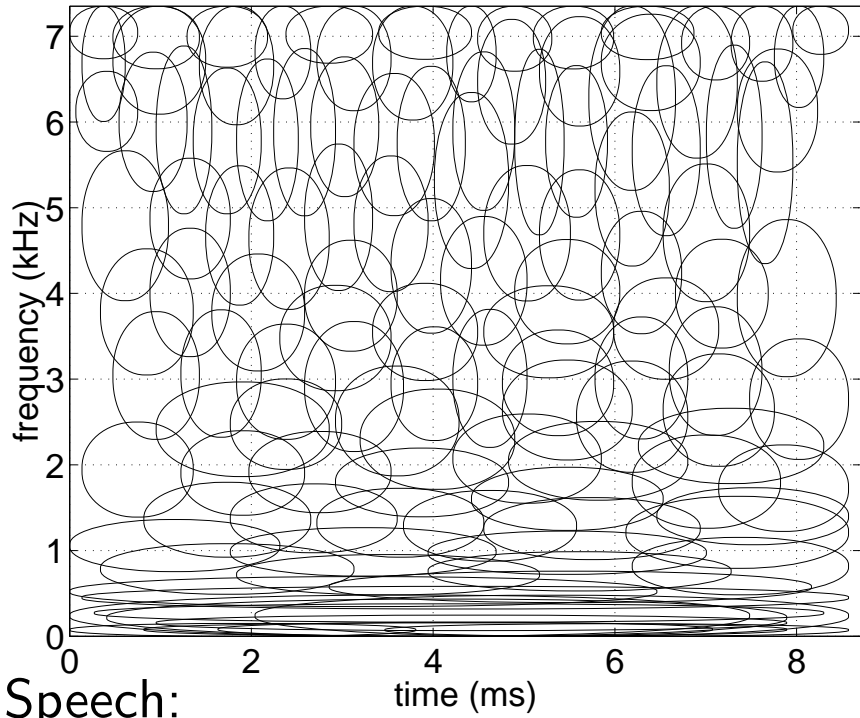
Fourier



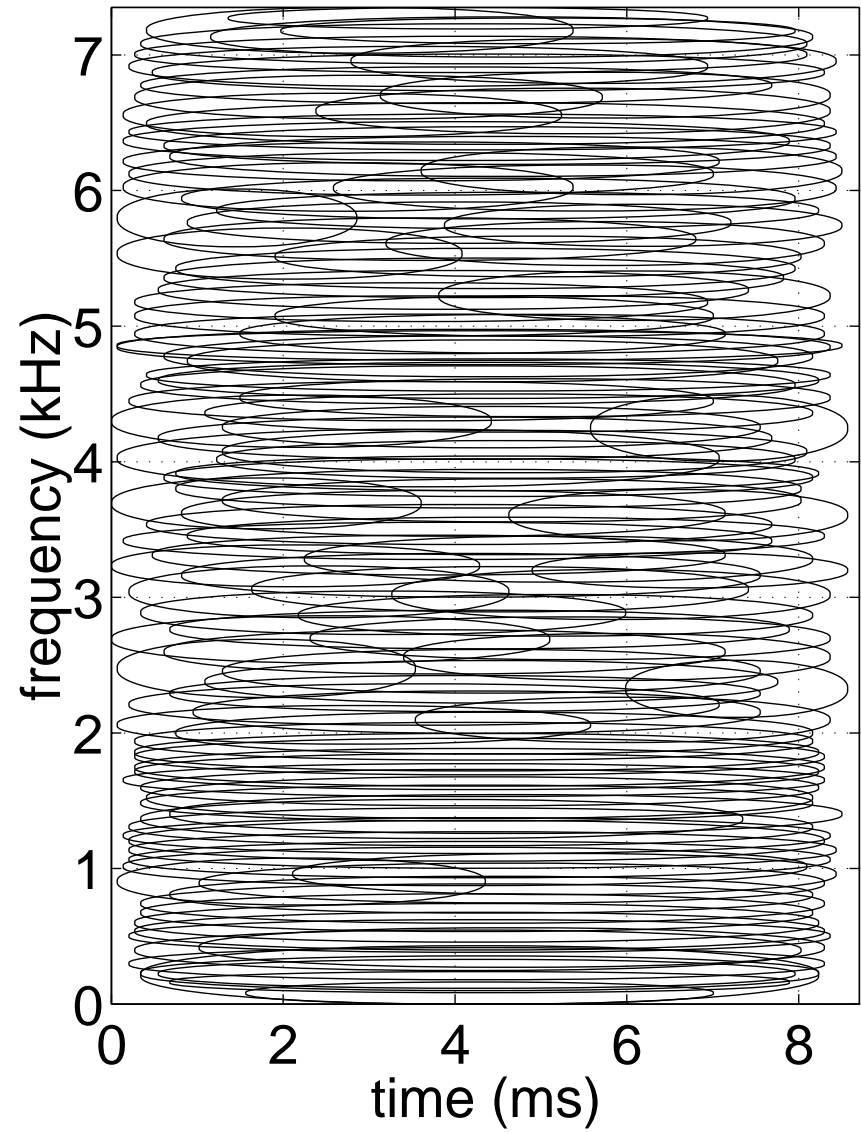
typical wavelet



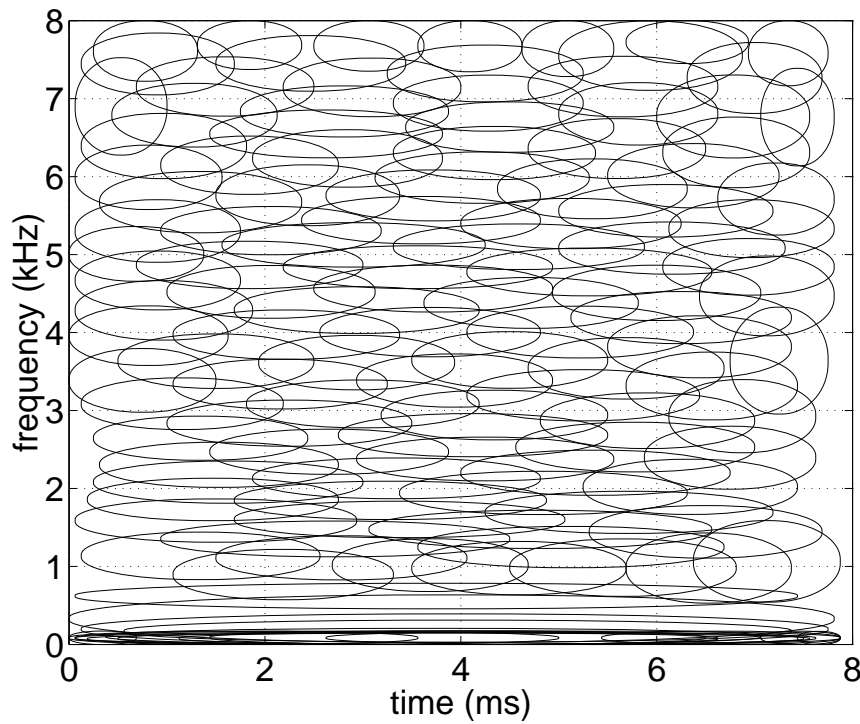
Environmental sounds:



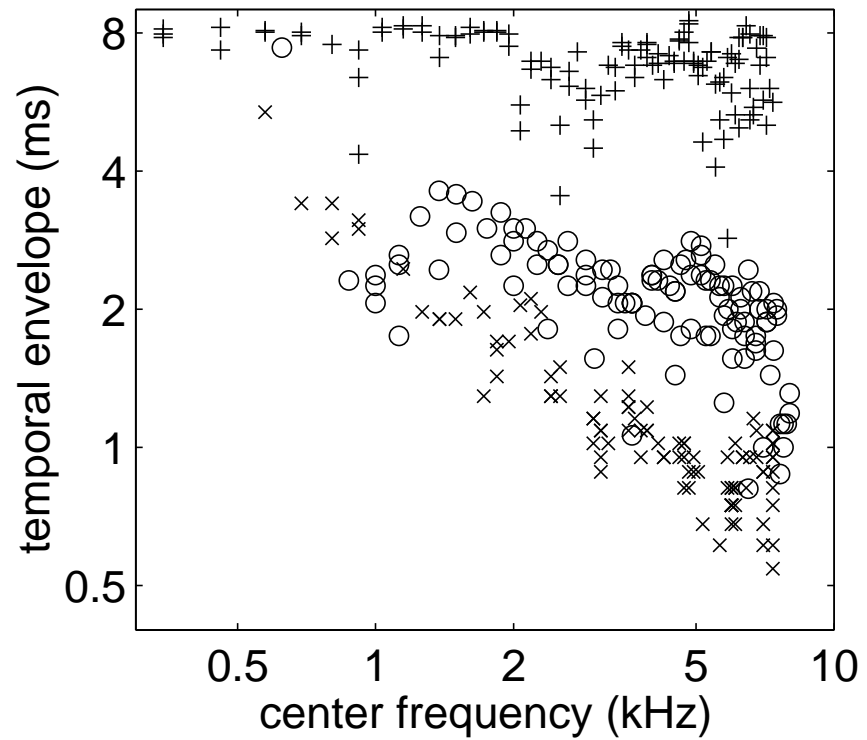
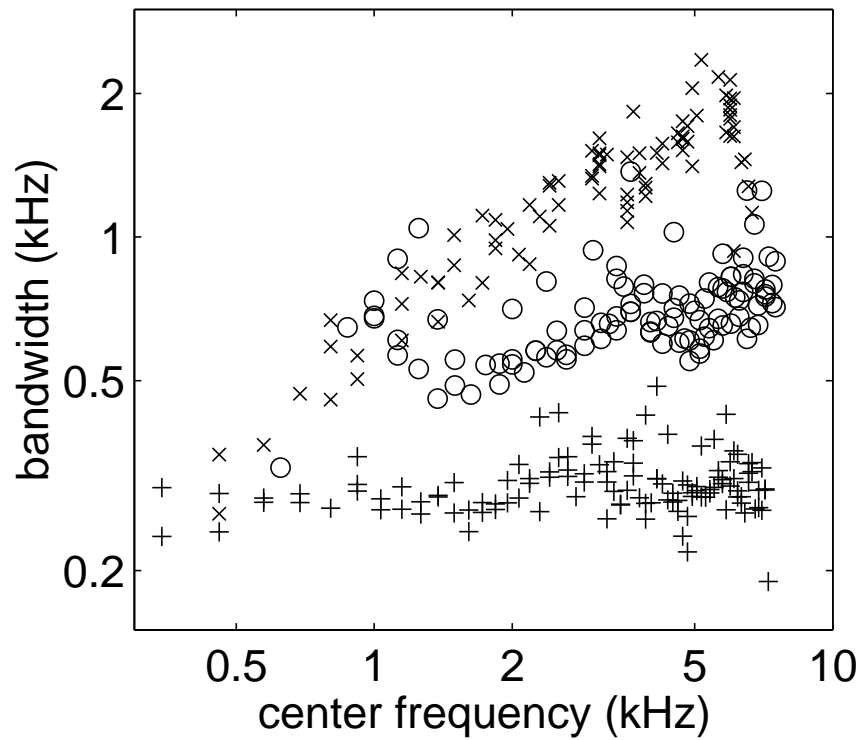
Animal vocalizations:



Speech:



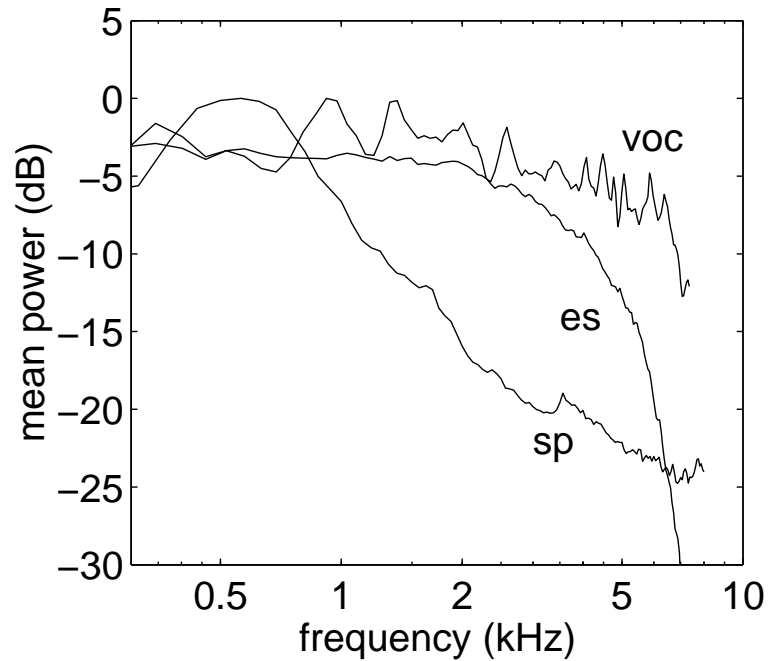
# Tiling trends follow power law



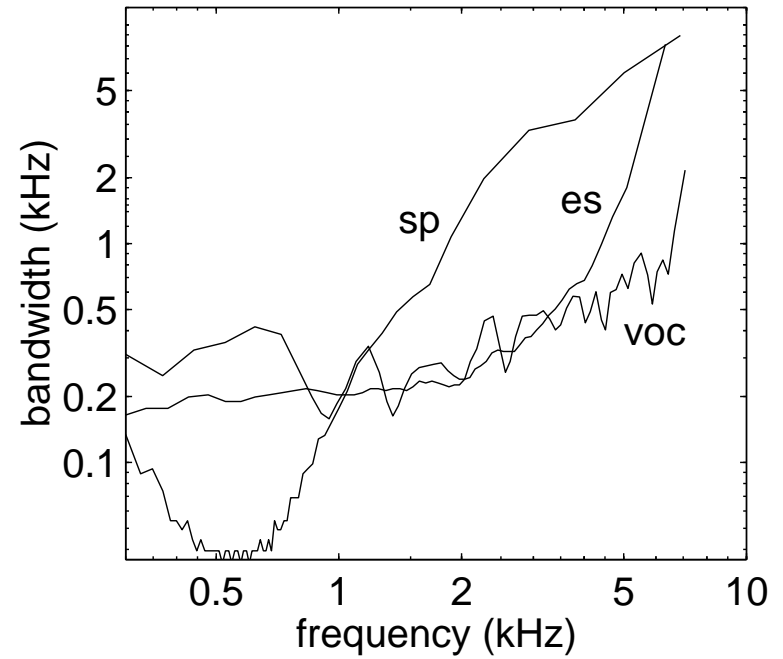
'x' = environmental sounds    'o' = speech    '+' = vocalizations

# Does equalization of power explain these data?

Average power spectra:

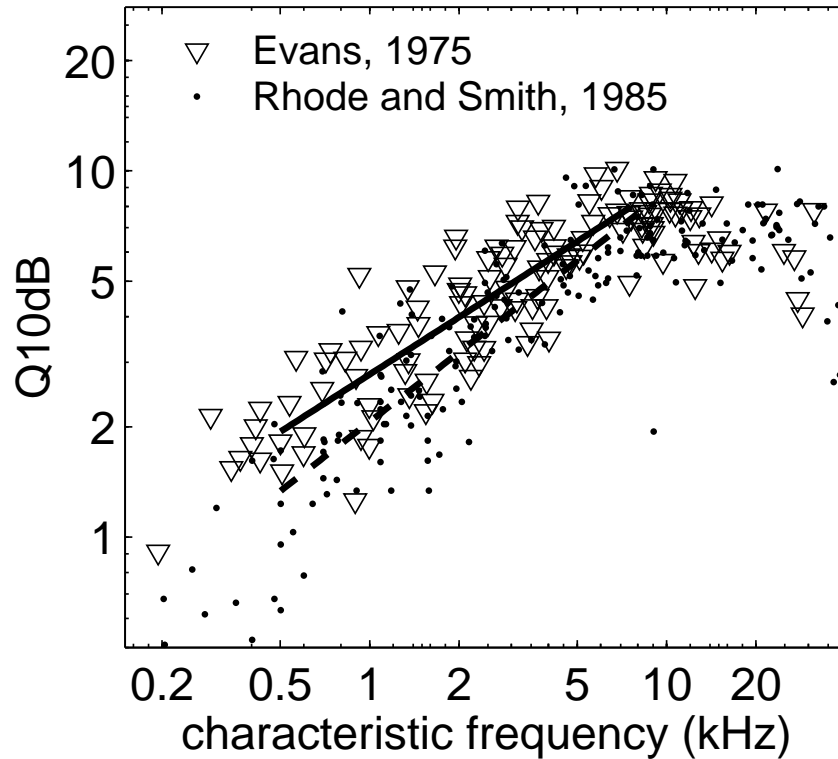


Equal power across frequency bands:

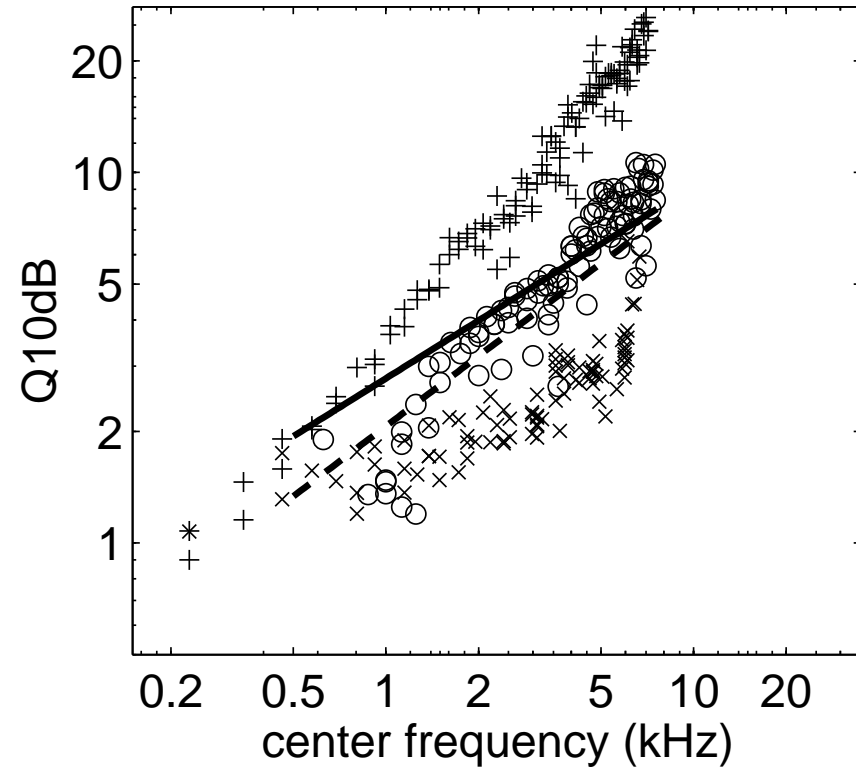


# Comparison to auditory population code

Cat auditory nerves



Derived filters



Filter sharpness characterizes how bandwidth changes as a function of frequency

- '+' vocalizations
- 'o' speech
- 'x' environmental sounds

$$Q_{10dB} = f_c / w_{10dB}$$

# Summary

Information theory and efficient coding:

- can be used to *derive* optimal codes for different pattern classes.
- explains important properties of sensory codes in both the auditory and visual system.
- gives insight into how our sensory systems are adapted to the natural environment.■

Caveats

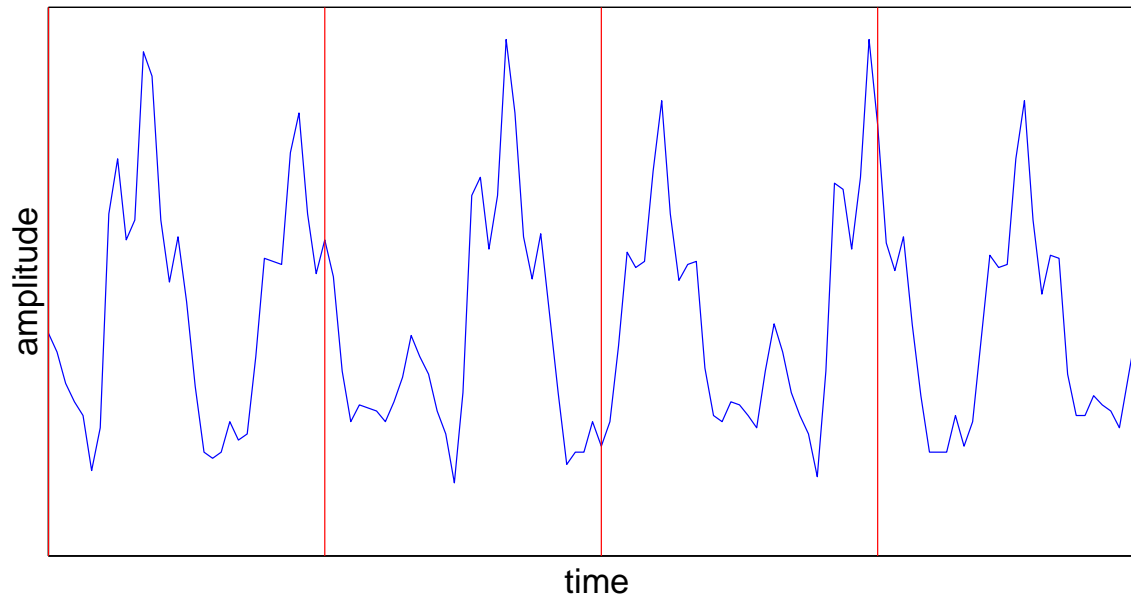
- Codes can only be derived within a small window
- Does not explain non-linear aspects of coding
- Models do not capture higher order structure■



*Coding natural sounds with spikes*

# Addressing some limitations of the current theory

The current model assumes the sound waveform is dividing into blocks:



Problems with block coding:

- signal structure is arbitrarily aligned
- code depends on block alignment
- difficult to encode non-periodic structure, e.g. rapid onsets

# An efficient, shift-invariant model

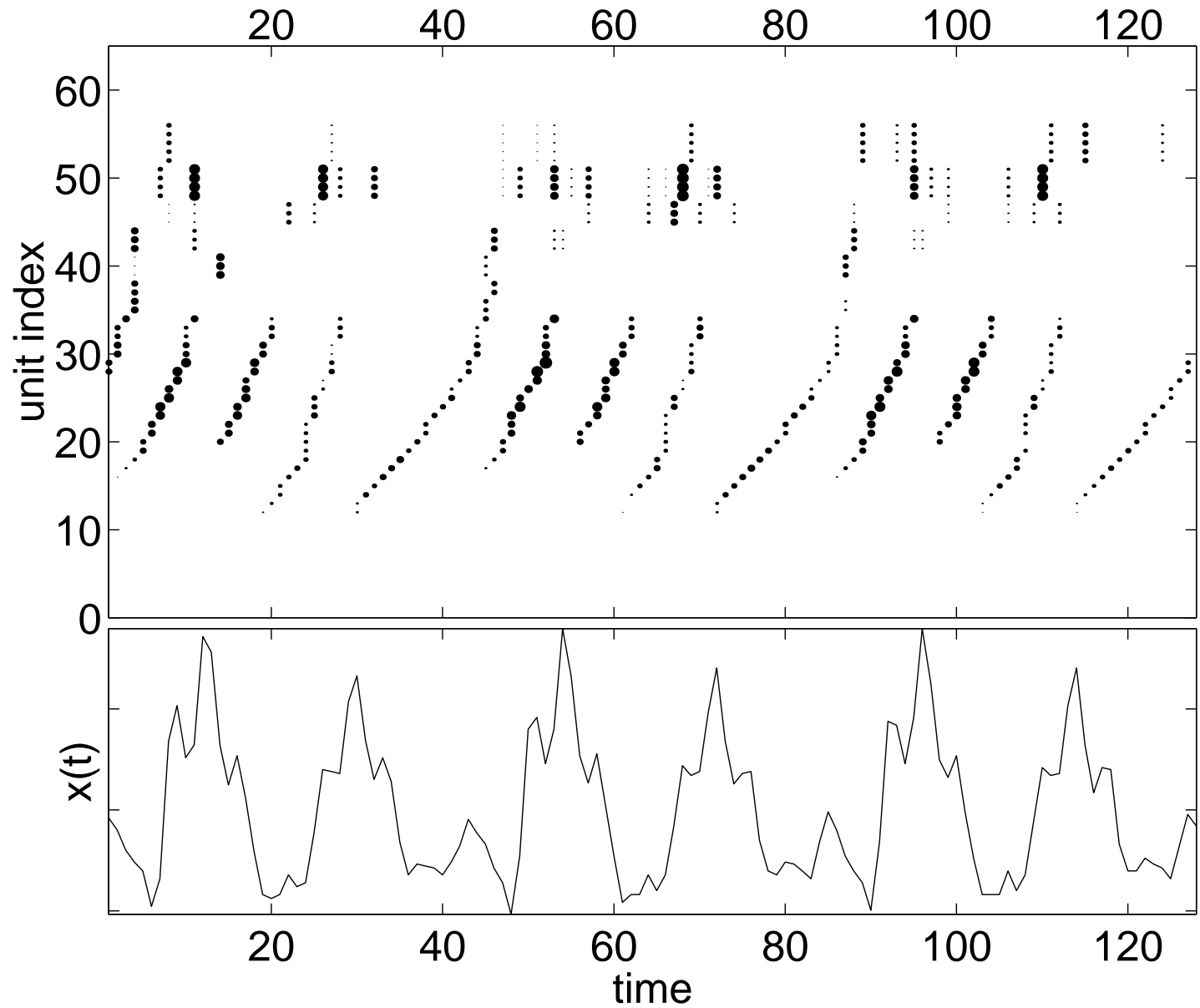
The signal is modeled by a sum of events plus noise:

$$x(t) = s_1\phi_1(t - \tau_1) + \cdots + s_M\phi_M(t - \tau_M) + \epsilon(t).$$

The events  $\phi_m(t)$ :

- can be placed at arbitrary time points  $\tau_m$
- are scaled by coefficients  $s_m$

# Solution after optimization: 105 dB SNR



# Time shifting

