### 15-213

"The course that gives CMU its Zip!"

# **Dynamic Memory Allocation November 2, 2000**

### **Topics**

- · Simple explicit allocators
- · Data structures
- Mechanisms
- Policies

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# **Dynamic Memory Allocation**

Application **Dynamic Memory Allocator Heap Memory** 

### **Explicit vs. Implicit Memory Allocator**

- Explicit: application allocates and frees space
  - -E.g., malloc and free in C
- · Implicit: application allocates, but does not free space
  - E.g. garbage collection in Java, ML or Lisp

### Allocation

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- · In both cases the memory allocator provides an abstraction of memory as a set of blocks
- Doles out free memory blocks to application

### Will discuss simple explicit memory allocation today

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# Harsh Reality #3

### **Memory Matters**

### Memory is not unbounded

- · It must be allocated and managed
- Many applications are memory dominated
  - Especially those based on complex, graph algorithms

### Memory referencing bugs especially pernicious

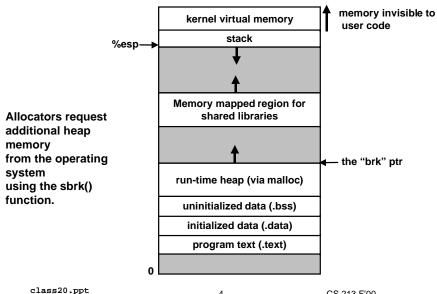
· Effects are distant in both time and space

### Memory performance is not uniform

- Cache and virtual memory effects can greatly affect program performance
- Adapting program to characteristics of memory system can lead to major speed improvements

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# **Process memory image**



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# Malloc package

### #include <stdlib.h>

void \*malloc(size\_t size)

- · if successful:
  - -returns a pointer to a memory block of at least **size** bytes, aligned to 8-byte boundary.
  - -if size==0, returns NULL
- if unsuccessful: returns NULL

### void free(void \*p)

- · returns the block pointed at by p to pool of available memory
- p must come from a previous call to malloc or realloc.

### void \*realloc(void \*p, size\_t size)

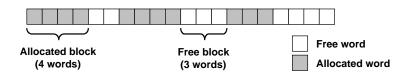
- · changes size of block p and returns ptr to new block.
- · contents of new block unchanged up to min of old and new size.

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# **Assumptions**

### Assumptions made in this lecture

memory is word addressed (each word can hold a pointer)



# Malloc example

```
void foo(int n, int m) {
     int i, *p;
      /* allocate a block of n ints */
     if ((p = (int *) malloc(n * sizeof(int))) == NULL) {
       perror("malloc");
       exit(0);
     for (i=0; i<n; i++)
       p[i] = i;
      /* add m bytes to end of p block */
     if ((p = (int *) realloc(p, (n+m) * sizeof(int))) == NULL) {
       perror("realloc");
       exit(0);
     for (i=n; i < n+m; i++)
       p[i] = i;
     /* print new array */
     for (i=0; i<n+m; i++)
       printf("%d\n", p[i]);
     free(p); /* return p to available memory pool */
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```

# Allocation examples

```
p1 = malloc(4)

p2 = malloc(5)

p3 = malloc(6)

free(p2)

p4 = malloc(2)
```

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## **Constraints**

### **Applications:**

- Can issue arbitrary sequence of allocation and free requests
- · Free requests must correspond to an allocated block

### **Allocators**

- · Can't control number or size of allocated blocks
- . Must respond immediately to all allocation requests
  - -i.e., can't reorder or buffer requests
- · Must allocate blocks from free memory
  - i.e., can only place allocated blocks in free memory
- Must align blocks so they satisfy all alignment requirements

   usually 8 byte alignment
- Can only manipulate and modify free memory
- · Can't move the allocated blocks once they are allocated
  - -i.e., compaction is not allowed

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# Performance goals: throughput

Given some sequence of malloc and free requests:

•  $R_0, R_1, ..., R_k, ..., R_{n-1}$ 

# Want to maximize throughput and peak memory utilization.

· These goals are often conflicting

### Throughput:

- · Number of completed requests per unit time
- Example:
  - -5,000 malloc calls and 5,000 free calls in 10 seconds
  - -throughput is 1,000 operations/second.

# Goals of good malloc/free

### **Primary goals**

- Good time performance for malloc and free
  - Ideally should take constant time (not always possible)
  - -Should certainly not take linear time in the number of blocks
- Good space utilization
  - -User allocated structures should be large fraction of the heap.
  - -want to minimize "fragmentation".

### Some other goals

- · Good locality properties
  - -structures allocated close in time should be close in space
  - -"similar" objects should be allocated close in space
- Robust
  - -can check that free(p1) is on a valid allocated object p1
  - -can check that memory references are to allocated space

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# Performance goals: peak memory utilization

### Given some sequence of malloc and free requests:

R<sub>0</sub>, R<sub>1</sub>, ..., R<sub>k</sub>, ..., R<sub>n-1</sub>

### Def: aggregate payload $P_k$ :

- malloc(p) results in a block with a payload of p bytes..
- After request R<sub>k</sub> has completed, the aggregate payload P<sub>k</sub> is the sum of currently allocated payloads.

### Def: current heap size is denoted by H,

Note that H<sub>k</sub> is monotonically nondecreasing

### Def: peak memory utilization:

• After k requests, peak memory utilization is:

$$-U_k = (\max_{i < k} P_i) / H_k$$

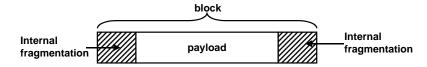
# **Internal Fragmentation**

### Poor memory utilization caused by fragmentation.

Comes in two forms: internal and external fragmentation

### Internal fragmentation

 For some block, internal fragmentation is the difference between the block size and the payload size.

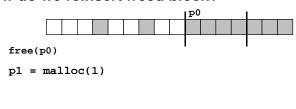


- Caused by overhead of maintaining heap data structures, padding for alignment purposes, or explicit policy decisions (e.g., not to split the block).
- Depends only on the pattern of previous requests, and thus is easy to measure.

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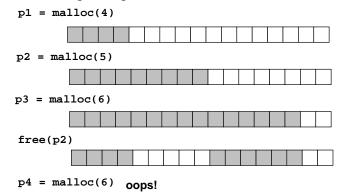
# Implementation issues

- How do we know how much memory to free just given a pointer?
- How do we keep track of the free blocks?
- What do we do with the extra space when allocating a structure that is smaller than the free block it is placed in?
- How do we pick a block to use for allocation -- many might fit?
- How do we reinsert freed block?



# **External fragmentation**

Occurs when there is enough aggregate heap memory, but no single free block is large enough



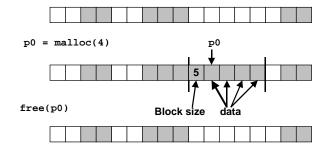
External fragmentation depends on the pattern of future requests, and thus is difficult to measure.

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# Knowing how much to free

### Standard method

- keep the length of a structure in the word preceding the structure
   This word is often called the header field or header
  - This word is often called the header held of header
- requires an extra word for every allocated structure



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# **Keeping track of free blocks**



• <u>Method 2</u>: explicit list among the free blocks using pointers within the free blocks



- Method 3: segregated free lists
  - · Different free lists for different size classes
- <u>Method 4</u>: blocks sorted by size
  - Can use a balanced tree (e.g. Red-Black tree) with pointers within each free block, and the length used as a key

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# Implicit list: finding a free block

### First fit:

· Search list from beginning, choose first free block that fits

- Can take linear time in total number of blocks (allocated and free)
- In practice it can cause "splinters" at beginning of list

### Next fit:

- Like first-fit, but search list from location of end of previous search
- Research suggests that fragmentation is worse

### **Best fit:**

• Search the list, choose the free block with the closest size that fits

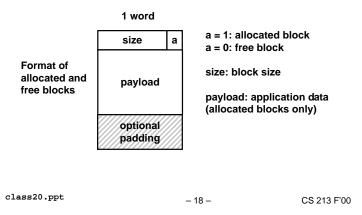
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- Keeps fragments small --- usually helps fragmentation
- · Will typically run slower than first-fit

# **Method 1: implicit list**

### Need to identify whether each block is free or allocated

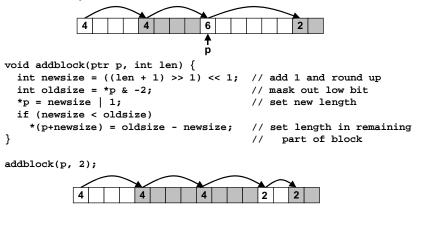
- Can use extra bit
- Bit can be put in the same word as the size if block sizes are always multiples of two (mask out low order bit when reading size).



# Implicit list: allocating in a free block

### Allocating in a free block - splitting

 Since allocated space might be smaller than free space, we might want to split the block



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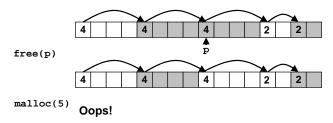
# Implicit list: freeing a block

### Simplest implementation:

Only need to clear allocated flag

void free\_block(ptr p) { \*p= \*p & -2}

But can lead to "false fragmentation"



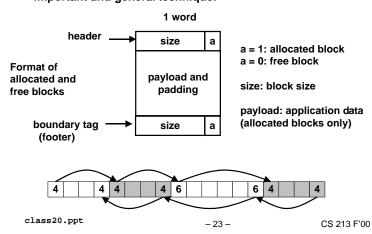
There is enough free space, but the allocator won't be able to find it

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# Implicit list: bidirectional

### **Boundary tags [Knuth73]**

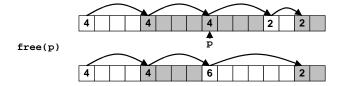
- · replicate size/allocated word at bottom of free blocks
- Allows us to traverse the "list" backwards, but requires extra space
- Important and general technique!



# Implicit list: coalescing

### Join with next and/or previous block if they are free

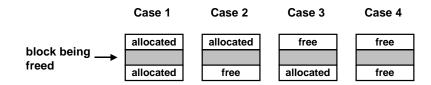
Coalescing with next block



But how do we coalesce with previous block?

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# Constant time coalescing

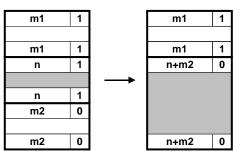


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# **Constant time coalescing (case 1)**

# m1 1 m1 1 n 1 n 1 m2 1 m2 1 m1 1 n 0 m2 1 m2 1

# **Constant time coalescing (case 2)**



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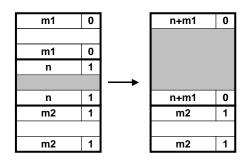
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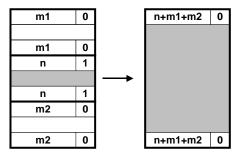
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# **Constant time coalescing (case 3)**



# **Constant time coalescing (case 4)**



# Summary of key allocator policies

### Placement policy:

- · first fit, next fit, best fit, etc.
- · trades off lower throughput for less fragmentation
  - Interesting observation: segregated free lists (next lecture) approximate a best fit placement policy without having the search entire free list.

### **Splitting policy:**

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- · When do we go ahead and split free blocks?
- · How much internal fragmentation are we willing to tolerate?

### Coalescing policy:

- immediate coalescing: coalesce adjacent blocks each time free is called
- Deferred coalescing: try to improve performance of free by deferring coalescing until needed. e.g.,
  - -coalesce as you scan the free list for malloc.
  - coalesce when the amount of external fragmentation reaches some threshold.

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# **Implicit lists: Summary**

- Implementation: very simple
- Allocate: linear time worst case
- Free: constant time worst case -- even with coalescing
- Memory usage: will depend on placement policy
  - · First fit, next fit or best fit

Not used in practice for malloc/free because of linear time allocate. Used in many special purpose applications.

However, the concepts of splitting and boundary tag coalescing are general to *all* allocators.

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