

Cache Memories

Oct. 2, 2003

Topics

- Generic cache memory organization
- Direct mapped caches
- Set associative caches
- Impact of caches on performance

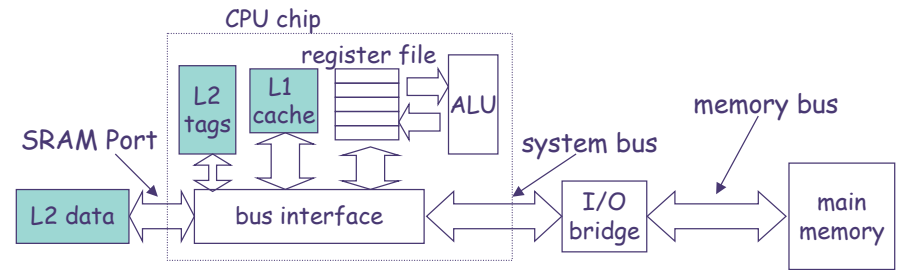
Cache Memories

Cache memories are small, fast SRAM-based memories managed automatically in hardware.

- Hold frequently accessed blocks of main memory

CPU looks first for data in L1, then in L2, then in main memory.

Typical system structure:

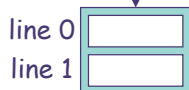


Inserting an L1 Cache Between the CPU and Main Memory

The transfer unit between the CPU register file and the cache is a 4-byte block.

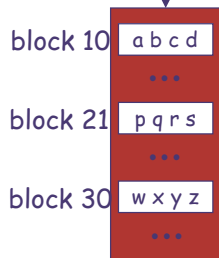


The tiny, very fast CPU register file has room for four 4-byte words.



The small fast L1 cache has room for two 4-word blocks.

The transfer unit between the cache and main memory is a 4-word block (16 bytes).



The big slow main memory has room for many 4-word blocks.

General Organization of a Cache

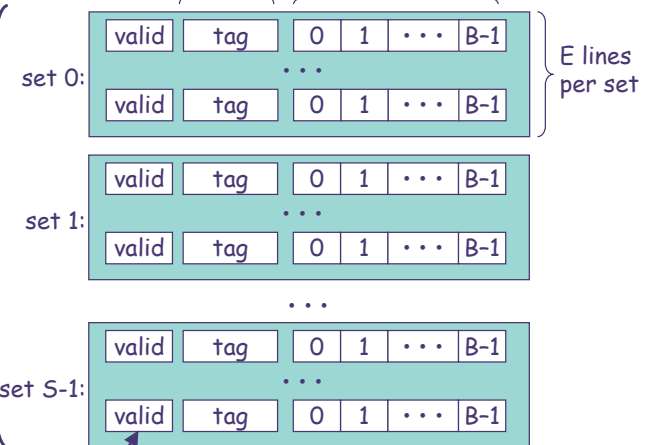
Cache is an array of sets.

Each set contains one or more lines.

Each line holds a block of data.

$$S = 2^s \text{ sets}$$

† tag bits per line $B = 2^b$ bytes per cache block

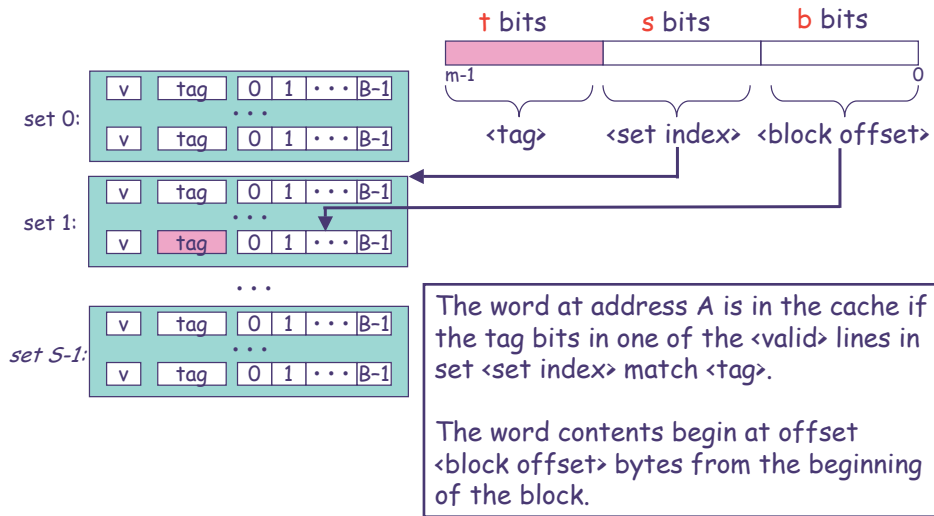


1 valid bit per line

Cache size: $C = B \times E \times S$ data bytes

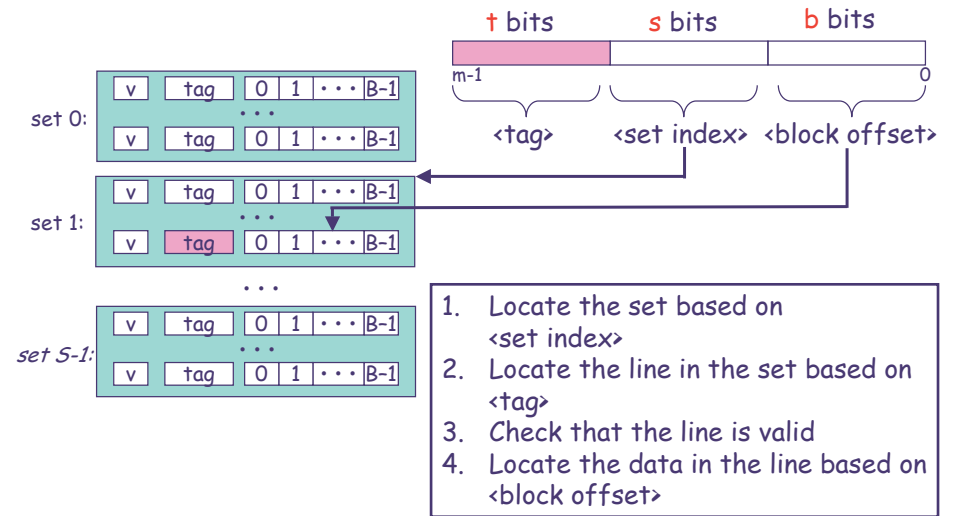
Addressing Caches

Address A:



Addressing Caches

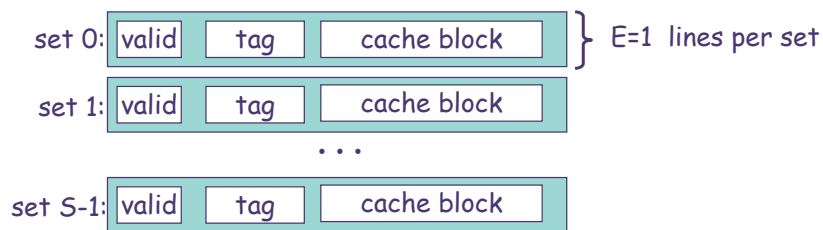
Address A:



Direct-Mapped Cache

Simplest kind of cache, easy to build
(only 1 tag compare required per access)

Characterized by exactly one line per set.

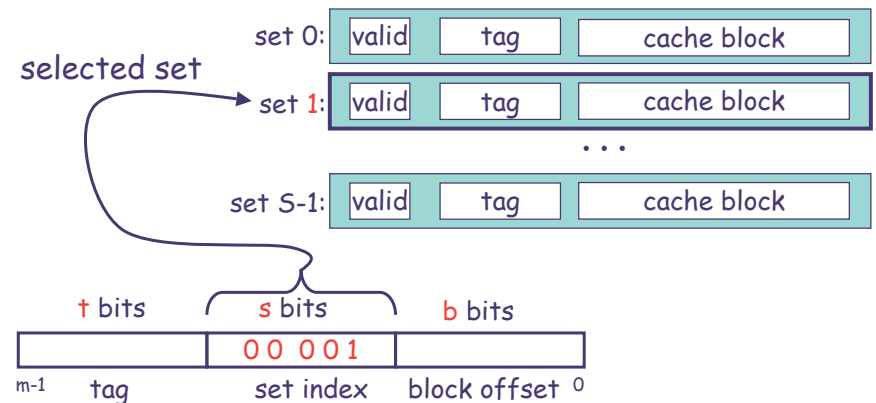


Cache size: $C = B \times S$ data bytes

Accessing Direct-Mapped Caches

Set selection

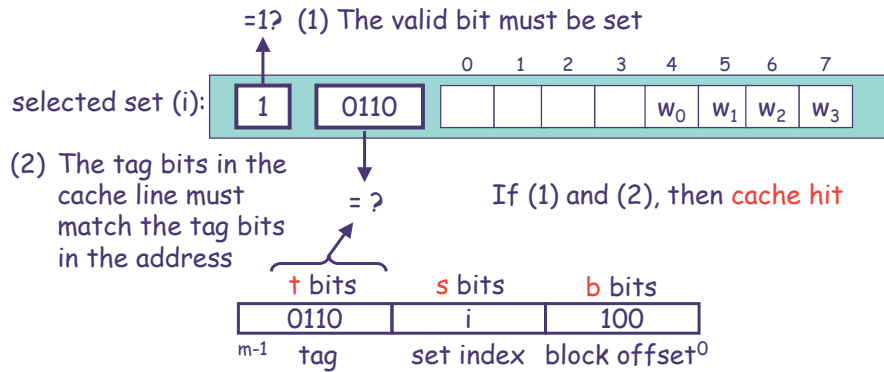
- Use the set index bits to determine the set of interest.



Accessing Direct-Mapped Caches

Line matching and word selection

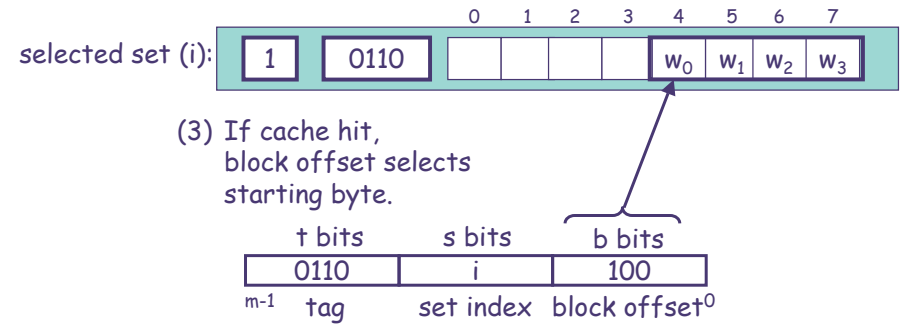
- **Line matching:** Find a valid line in the selected set with a matching tag
- **Word selection:** Then extract the word



Accessing Direct-Mapped Caches

Line matching and word selection

- **Line matching:** Find a valid line in the selected set with a matching tag
- **Word selection:** Then extract the word



Direct-Mapped Cache Simulation

$M=16$ byte addresses, $B=2$ bytes/block,
 $S=4$ sets, $E=1$ entry/set

$t=1$ $s=2$ $b=1$

x	xx	x
---	----	---

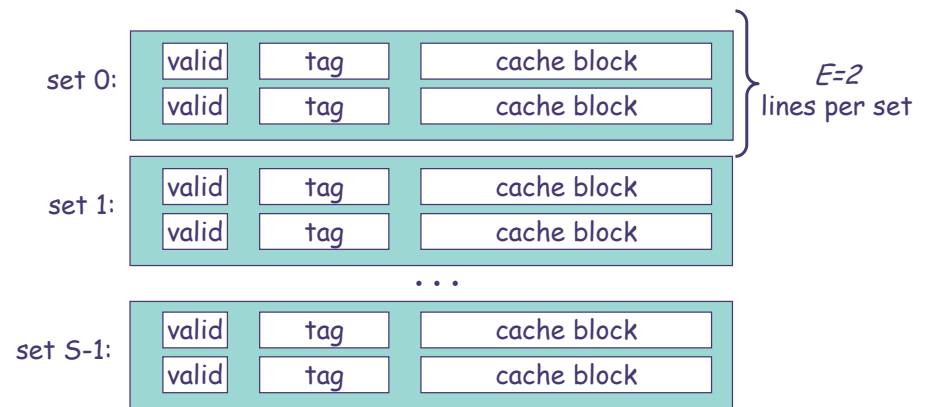
Address trace (reads):

0	[0000 ₂],	miss
1	[0001 ₂],	hit
7	[0111 ₂],	miss
8	[1000 ₂],	miss
0	[0000 ₂]	miss

v	tag	data
1	0	$M[0-1]$
1	0	$M[6-7]$

Set Associative Caches

Characterized by more than one line per set

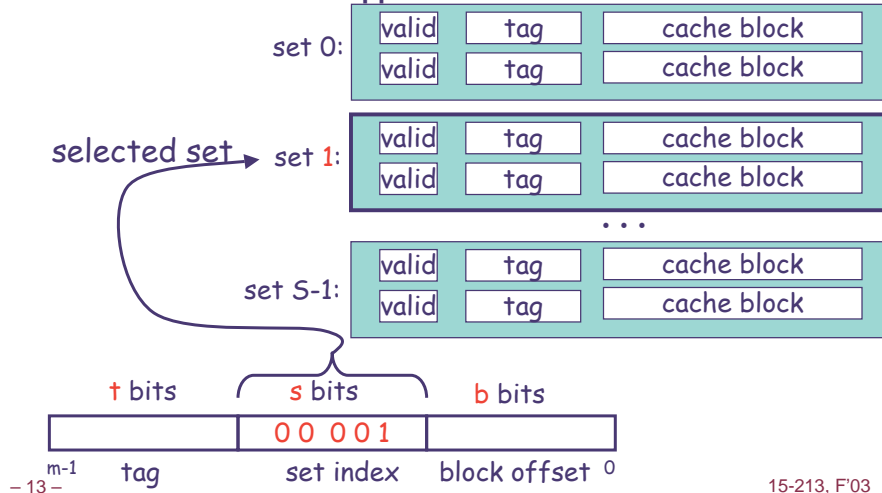


E-way associative cache

Accessing Set Associative Caches

Set selection

- identical to direct-mapped cache



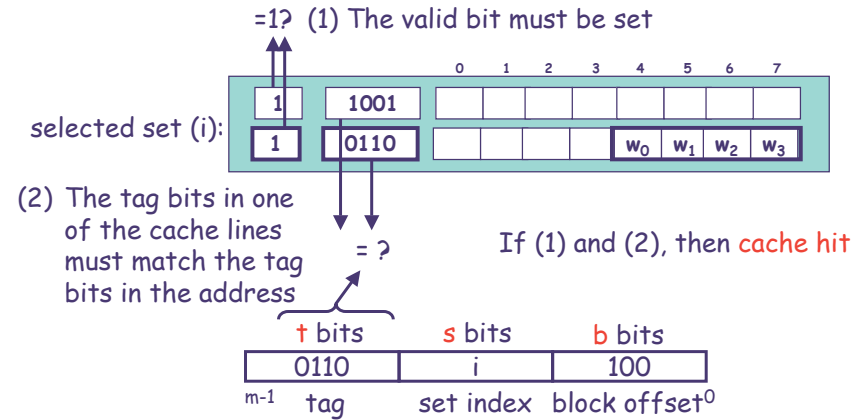
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Accessing Set Associative Caches

Line matching and word selection

- must compare the tag in each valid line in the selected set.



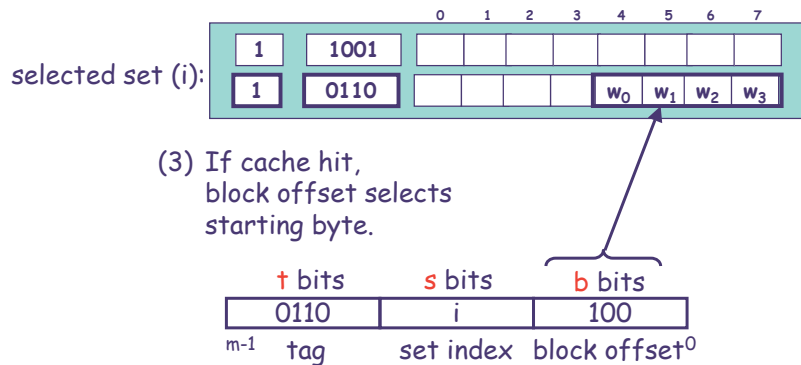
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Accessing Set Associative Caches

Line matching and word selection

- Word selection is the same as in a direct mapped cache



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2-Way Associative Cache Simulation

$M=16$ byte addresses, $B=2$ bytes/block,
 $S=2$ sets, $E=2$ entry/set

$t=2$	$s=1$	$b=1$
XX	X	X

Address trace (reads):

0	[0000 ₂]	miss
1	[0001 ₂]	hit
7	[0111 ₂]	miss
8	[1000 ₂]	miss
0	[0000 ₂]	hit

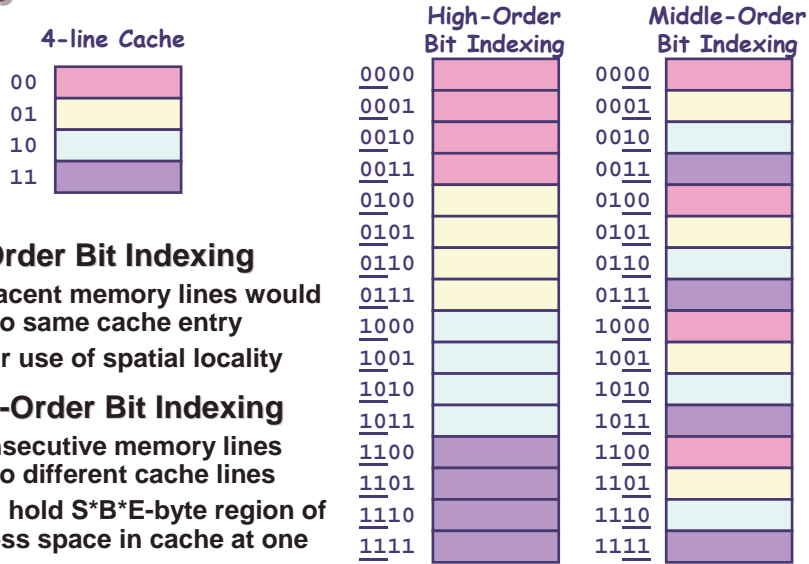
v tag data

1	00	$M[0-1]$
1	10	$M[8-9]$
1	01	$M[6-7]$
0		

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Why Use Middle Bits as Index?



High-Order Bit Indexing

- Adjacent memory lines would map to same cache entry
- Poor use of spatial locality

Middle-Order Bit Indexing

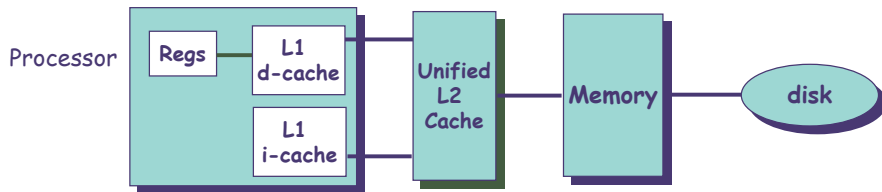
- Consecutive memory lines map to different cache lines
- Can hold S*B*E-byte region of address space in cache at one time

Maintaining a Set-Associate Cache

- How to decide which cache line to use in a set?
 - Least Recently Used (LRU), Requires $\lceil \lg_2(E!) \rceil$ extra bits
 - Not recently Used (NRU)
 - Random
- Virtual vs. Physical addresses:
 - The memory system works with physical addresses, but it takes time to translate a virtual to a physical address. So most L1 caches are virtually indexed, but physically tagged.

Multi-Level Caches

Options: separate data and instruction caches, or a unified cache



size:	200 B	8-64 KB	1-4MB SRAM	128 MB DRAM	30 GB
speed:	3 ns	3 ns	6 ns	60 ns	8 ms
\$/Mbyte:			\$100/MB	\$1.50/MB	\$0.05/MB
line size:	8 B	32 B	32 B	8 KB	

larger, slower, cheaper

What about writes?

Multiple copies of data exist:

- L1
- L2
- Main Memory
- Disk

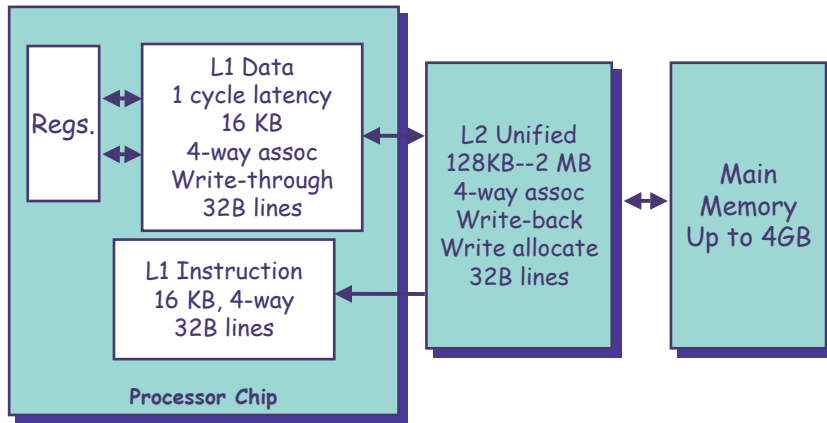
What to do when we write?

- Write-through
 - need a dirty bit
 - What to do on a write-miss?
- Write-back

What to do on a replacement?

- Depends on whether it is write through or write back

Intel Pentium III Cache Hierarchy



Cache Performance Metrics

Miss Rate

- Fraction of memory references not found in cache (misses / references)
- Typical numbers:
 - 3-10% for L1
 - can be quite small (e.g., < 1%) for L2, depending on size, etc.

Hit Time

- Time to deliver a line in the cache to the processor (includes time to determine whether the line is in the cache)
- Typical numbers:
 - 1-2 clock cycle for L1
 - 5-20 clock cycles for L2

Aside for architects:
 -Increasing cache size?
 -Increasing block size?
 -Increasing associativity?

Miss Penalty

- Additional time required because of a miss
 - Typically 50-200 cycles for main memory (Trend: increasing!)

Writing Cache Friendly Code

- Repeated references to variables are good (**temporal locality**)
- Stride-1 reference patterns are good (**spatial locality**)
- Examples:
 - cold cache, 4-byte words, 4-word cache blocks

```
int sum_array_rows(int a[M][N])
{
    int i, j, sum = 0;

    for (i = 0; i < M; i++)
        for (j = 0; j < N; j++)
            sum += a[i][j];

    return sum;
}
```

Miss rate = 1/4 = 25%

```
int sum_array_cols(int a[M][N])
{
    int i, j, sum = 0;

    for (j = 0; j < N; j++)
        for (i = 0; i < M; i++)
            sum += a[i][j];

    return sum;
}
```

Miss rate = 100%

Detecting the Cache Parameters

How can one determine the cache parameters?

- Size of cache?
- Size of cache block?
- Hit time?
- Miss penalty?
- Associativity?
- Number of levels in memory hierarchy?

Complicating factors

- Prefetch support (hardware and software)
- Non-blocking caches ("Hit-under-Miss" support)
- Superscalar processors with multiple, concurrent memory operations
- Victim caches, stream buffers, line-reservation

The Memory Mountain

Read throughput (read bandwidth)

- Number of bytes read from memory per second (MB/s)

Memory mountain

- Measured read throughput as a function of spatial and temporal locality.
- Compact way to characterize memory system performance.

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Memory Mountain Test Function

```
/* The test function */
void test(int elems, int stride) {
    int i, result = 0;
    volatile int sink;

    for (i = 0; i < elems; i += stride)
        result += data[i];
    sink = result; /* So compiler doesn't optimize away the loop */
}

/* Run test(elems, stride) and return read throughput (MB/s) */
double run(int size, int stride, double Mhz)
{
    double cycles;
    int elems = size / sizeof(int);

    test(elems, stride); /* warm up the cache */
    cycles = fcyc2(test, elems, stride, 0); /* call test(elems, stride) */
    return (size / stride) / (cycles / Mhz); /* convert cycles to MB/s */
}
```

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Memory Mountain Main Routine

```
/* mountain.c - Generate the memory mountain. */
#define MINBYTES (1 << 10) /* Working set size ranges from 1 KB */
#define MAXBYTES (1 << 23) /* ... up to 8 MB */
#define MAXSTRIDE 16 /* Strides range from 1 to 16 */
#define MAXElems MAXBYTES/sizeof(int)

int data[MAXElems]; /* The array we'll be traversing */

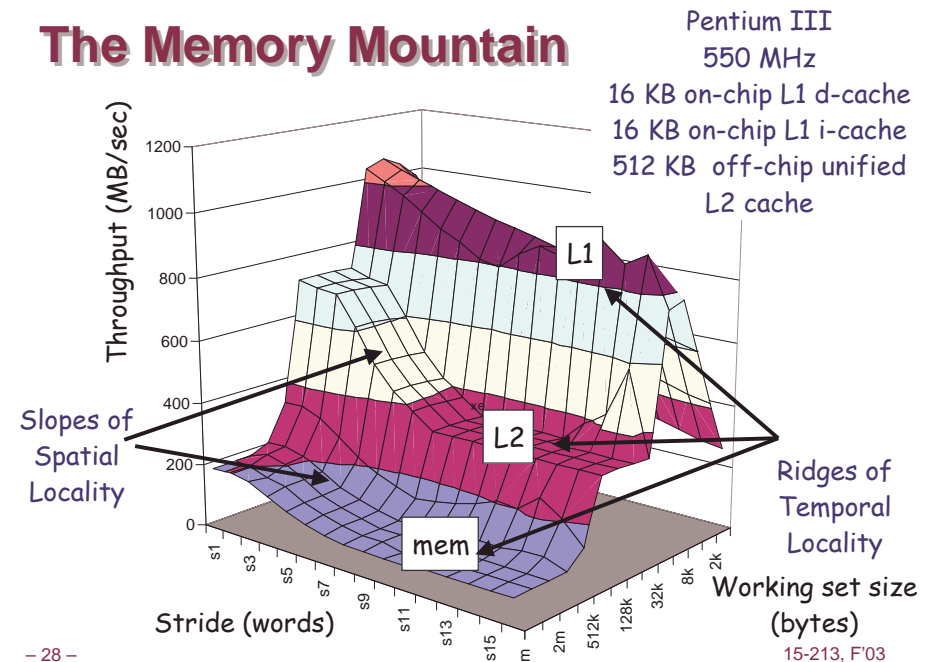
int main()
{
    int size; /* Working set size (in bytes) */
    int stride; /* Stride (in array elements) */
    double Mhz; /* Clock frequency */

    init_data(data, MAXElems); /* Initialize each element in data to 1 */
    Mhz = mhz(0); /* Estimate the clock frequency */
    for (size = MAXBYTES; size >= MINBYTES; size >= 1) {
        for (stride = 1; stride <= MAXSTRIDE; stride++)
            printf("%.1f\t", run(size, stride, Mhz));
        printf("\n");
    }
    exit(0);
}
```

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The Memory Mountain



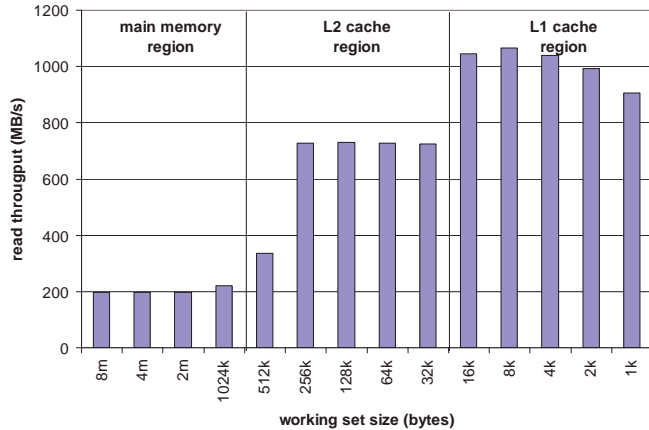
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Ridges of Temporal Locality

Slice through the memory mountain with stride=1

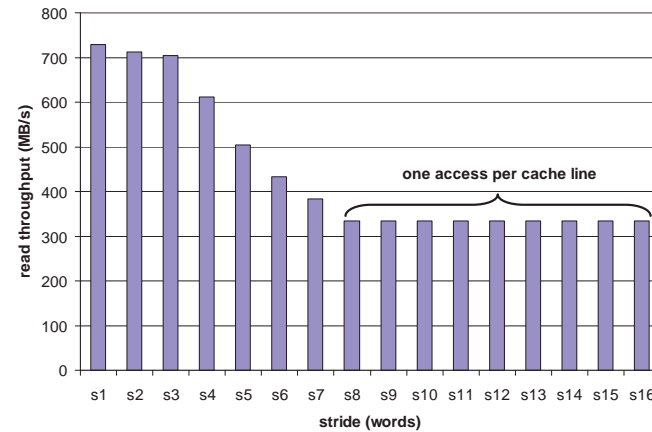
- illuminates read throughputs of different caches and memory



A Slope of Spatial Locality

Slice through memory mountain with size=256KB

- shows cache block size.



Matrix Multiplication Example

Major Cache Effects to Consider

- Total cache size
 - Exploit temporal locality and keep the working set small (e.g., use blocking)
- Block size
 - Exploit spatial locality

```

/* ijk */
for (i=0; i<n; i++) {
  for (j=0; j<n; j++) {
    sum = 0.0;
    for (k=0; k<n; k++)
      sum += a[i][k] * b[k][j];
    c[i][j] = sum;
  }
}
    
```

Variable sum held in register (pointing to sum = 0.0;)

Description:

- Multiply N x N matrices
 - O(N³) total operations
 - Accesses
 - N reads per source element
 - N values summed per destination
- » but may be able to hold in register

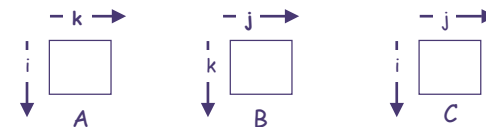
Miss Rate Analysis for Matrix Multiply

Assume:

- Line size = 32B (big enough for four 64-bit words)
- Matrix dimension (N) is very large
 - Approximate 1/N as 0.0
- Cache is not even big enough to hold multiple rows

Analysis Method:

- Look at access pattern of inner loop



Layout of C Arrays in Memory (review)

C arrays allocated in row-major order

- each row in contiguous memory locations

Stepping through columns in one row:

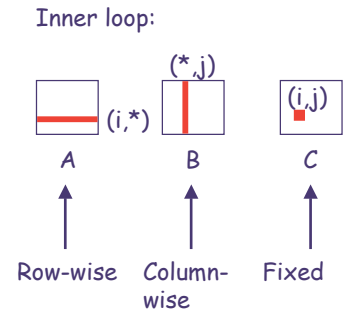
- for (i = 0; i < N; i++)
sum += a[0][i];
- accesses successive elements
- if block size (B) > 4 bytes, exploit spatial locality
 - compulsory miss rate = 4 bytes / B

Stepping through rows in one column:

- for (i = 0; i < n; i++)
sum += a[i][0];
- accesses distant elements
- no spatial locality!
 - compulsory miss rate = 1 (i.e. 100%)

Matrix Multiplication (ijk)

```
/* ijk */
for (i=0; i<n; i++) {
  for (j=0; j<n; j++) {
    sum = 0.0;
    for (k=0; k<n; k++)
      sum += a[i][k] * b[k][j];
    c[i][j] = sum;
  }
}
```

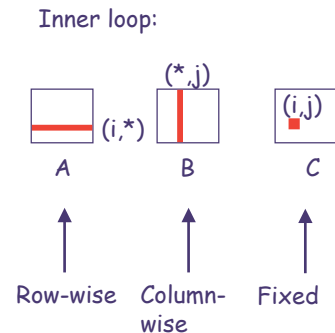


Misses per Inner Loop Iteration:

<u>A</u>	<u>B</u>	<u>C</u>
0.25	1.0	0.0

Matrix Multiplication (jik)

```
/* jik */
for (j=0; j<n; j++) {
  for (i=0; i<n; i++) {
    sum = 0.0;
    for (k=0; k<n; k++)
      sum += a[i][k] * b[k][j];
    c[i][j] = sum;
  }
}
```

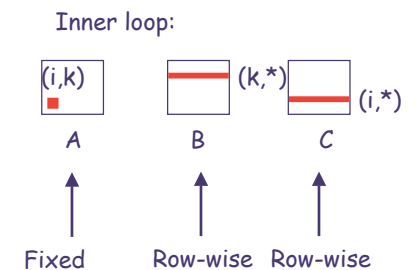


Misses per Inner Loop Iteration:

<u>A</u>	<u>B</u>	<u>C</u>
0.25	1.0	0.0

Matrix Multiplication (kij)

```
/* kij */
for (k=0; k<n; k++) {
  for (i=0; i<n; i++) {
    r = a[i][k];
    for (j=0; j<n; j++)
      c[i][j] += r * b[k][j];
  }
}
```



Misses per Inner Loop Iteration:

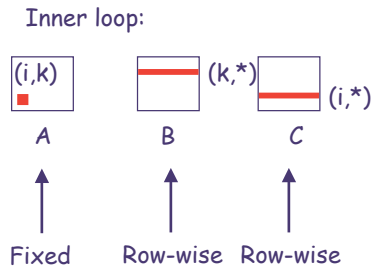
<u>A</u>	<u>B</u>	<u>C</u>
0.0	0.25	0.25

Matrix Multiplication (ikj)

```

/* ikj */
for (i=0; i<n; i++) {
  for (k=0; k<n; k++) {
    r = a[i][k];
    for (j=0; j<n; j++)
      c[i][j] += r * b[k][j];
  }
}

```



Misses per Inner Loop Iteration:

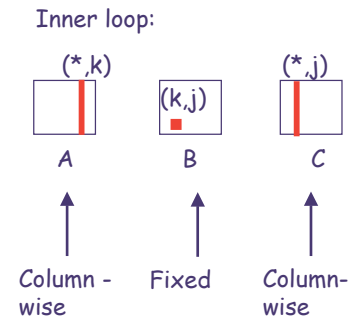
$\frac{A}{0.0}$	$\frac{B}{0.25}$	$\frac{C}{0.25}$
-----------------	------------------	------------------

Matrix Multiplication (jki)

```

/* jki */
for (j=0; j<n; j++) {
  for (k=0; k<n; k++) {
    r = b[k][j];
    for (i=0; i<n; i++)
      c[i][j] += a[i][k] * r;
  }
}

```



Misses per Inner Loop Iteration:

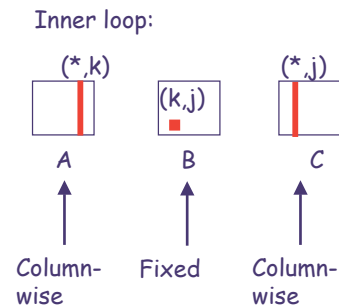
$\frac{A}{1.0}$	$\frac{B}{0.0}$	$\frac{C}{1.0}$
-----------------	-----------------	-----------------

Matrix Multiplication (kji)

```

/* kji */
for (k=0; k<n; k++) {
  for (j=0; j<n; j++) {
    r = b[k][j];
    for (i=0; i<n; i++)
      c[i][j] += a[i][k] * r;
  }
}

```



Misses per Inner Loop Iteration:

$\frac{A}{1.0}$	$\frac{B}{0.0}$	$\frac{C}{1.0}$
-----------------	-----------------	-----------------

Summary of Matrix Multiplication

```

for (i=0; i<n; i++) {
  for (j=0; j<n; j++) {
    sum = 0.0;
    for (k=0; k<n; k++)
      sum += a[i][k] * b[k][j];
    c[i][j] = sum;
  }
}

```

ijk (& jik):

- 2 loads, 0 stores
- misses/iter = 1.25

```

for (k=0; k<n; k++) {
  for (i=0; i<n; i++) {
    r = a[i][k];
    for (j=0; j<n; j++)
      c[i][j] += r * b[k][j];
  }
}

```

kij (& ikj):

- 2 loads, 1 store
- misses/iter = 0.5

```

for (j=0; j<n; j++) {
  for (k=0; k<n; k++) {
    r = b[k][j];
    for (i=0; i<n; i++)
      c[i][j] += a[i][k] * r;
  }
}

```

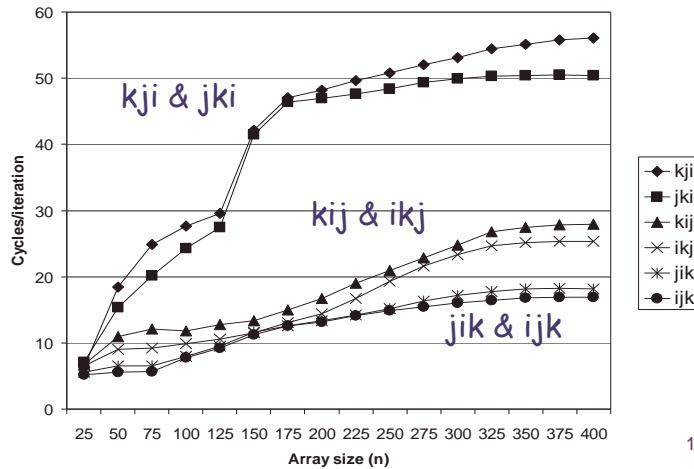
jki (& kji):

- 2 loads, 1 store
- misses/iter = 2.0

Pentium Matrix Multiply Performance

Miss rates are helpful but not perfect predictors.

- Code scheduling matters, too.



Improving Temporal Locality by Blocking

Example: Blocked matrix multiplication

- “block” (in this context) does not mean “cache block”.
- Instead, it mean a sub-block within the matrix.
- Example: $N = 8$; sub-block size = 4

$$\begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} \times \begin{bmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{bmatrix} = \begin{bmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{bmatrix}$$

Key idea: Sub-blocks (i.e., A_{xy}) can be treated just like scalars.

$$\begin{aligned} C_{11} &= A_{11}B_{11} + A_{12}B_{21} & C_{12} &= A_{11}B_{12} + A_{12}B_{22} \\ C_{21} &= A_{21}B_{11} + A_{22}B_{21} & C_{22} &= A_{21}B_{12} + A_{22}B_{22} \end{aligned}$$

Blocked Matrix Multiply (bijk)

```

for (jj=0; jj<n; jj+=bsize) {
    for (i=0; i<n; i++)
        for (j=jj; j < min(jj+bsize,n); j++)
            c[i][j] = 0.0;

    for (kk=0; kk<n; kk+=bsize) {
        for (i=0; i<n; i++) {
            for (j=jj; j < min(jj+bsize,n); j++) {
                sum = 0.0
                for (k=kk; k < min(kk+bsize,n); k++) {
                    sum += a[i][k] * b[k][j];
                }
                c[i][j] += sum;
            }
        }
    }
}
    
```

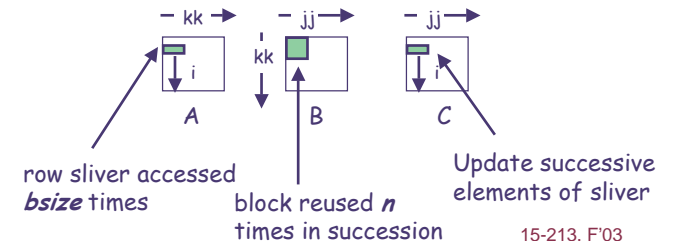
Blocked Matrix Multiply Analysis

- Innermost loop pair multiplies a $1 \times bsize$ sliver of A by a $bsize \times bsize$ block of B and accumulates into $1 \times bsize$ sliver of C
- Loop over i steps through n row slivers of A & C , using same B

```

for (i=0; i<n; i++) {
    for (j=jj; j < min(jj+bsize,n); j++) {
        sum = 0.0
        for (k=kk; k < min(kk+bsize,n); k++) {
            sum += a[i][k] * b[k][j];
        }
        c[i][j] += sum;
    }
}
    
```

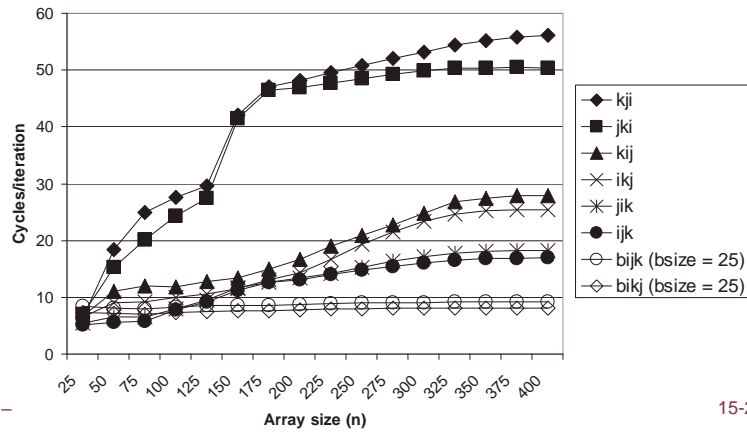
Innermost Loop Pair



Pentium Blocked Matrix Multiply Performance

Blocking (bijk and bikj) improves performance by a factor of two over unblocked versions (ijk and jik)

- relatively insensitive to array size.



Concluding Observations

Programmer can optimize for cache performance

- How data structures are organized
- How data are accessed
 - Nested loop structure
 - Blocking is a general technique

All systems favor “cache friendly code”

- Getting absolute optimum performance is very platform specific
 - Cache sizes, line sizes, associativities, etc.
- Can get most of the advantage with generic code
 - Keep working set reasonably small (temporal locality)
 - Use small strides (spatial locality)