

15-494/694: Cognitive Robotics

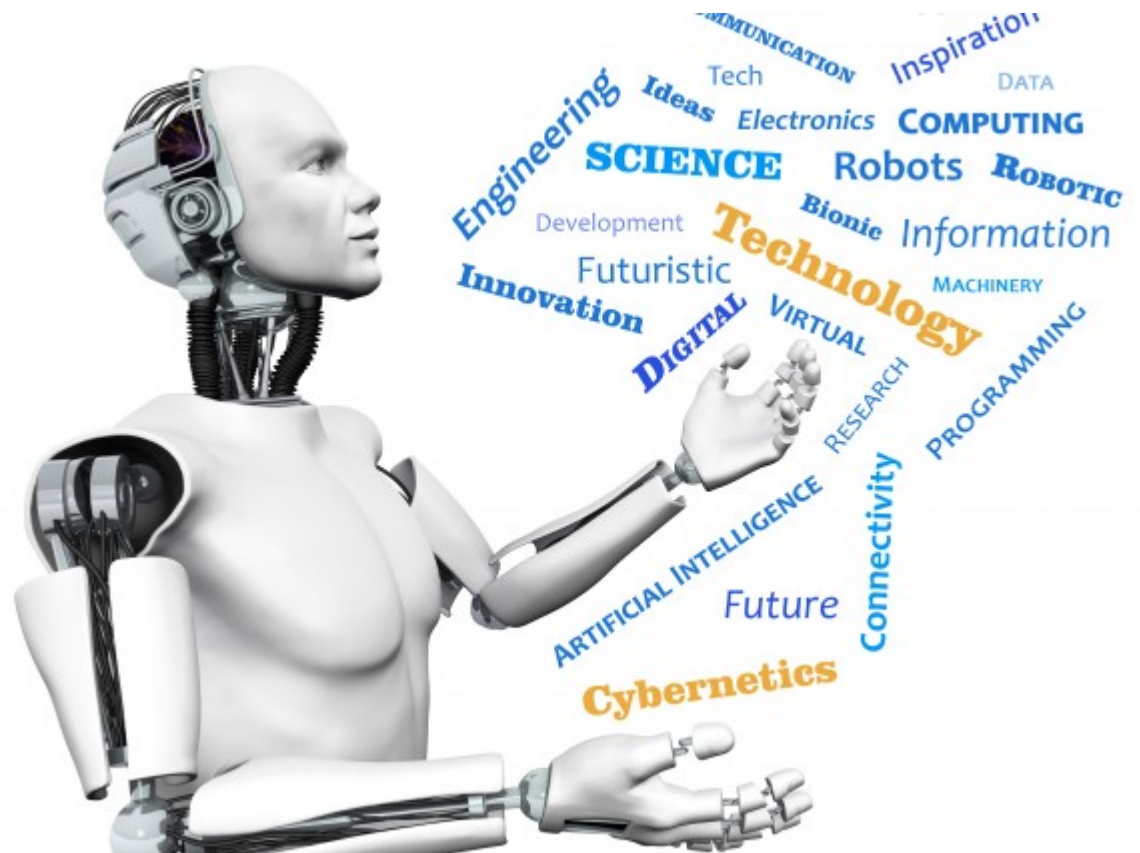
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Lecture 2:

VEX AIM Software
Architecture

and

Python Control Structure



Robot Software Architecture

- A robot is a complex collection of interacting hardware/software systems.
- Example: navigation isn't just motion.
 - Need vision to find landmarks.
 - Head + body motion to point the camera.
- Layers of control:
 - Low level: control one actuator
 - Middle level: coordinate multiple actuators (e.g., wheels and kicker) for one task.
 - High level: goal-directed behaviors.

Python Control Concepts

- To understand the vex-aim-tools architecture, you must be familiar with:
 - Iterators
 - Generators
 - Coroutines
 - Asyncio: event loops and tasks
 - Threads

Iterators

```
>>> nums = [1,2,3,4]
```

```
>>> for x in nums: print(f'x = {x}')
```

```
x=1
```

```
x=2
```

```
x=3
```

```
x=4
```

```
>>> [x*x for x in nums] ← list comprehension
```

```
[1, 4, 9, 16]
```

What Makes an Object Iterable?

Defines an `__iter__()` method that returns an iterator.

```
>>> nums.__iter__
```

```
<method-wrapper '__iter__' of list  
object at 0x7ffa366baf48>
```

```
>>> nums.__iter__()
```

```
<list_iterator object at 0x7ffa34aa3c88>
```

What Is an Iterator?

References a sequence and defines a `__next__()` method that returns the next item or raises `StopIteration` if there are no more items.

```
>>> a = nums.__iter__()
```

```
>>> a.__next__()
```

1

```
>>> a.__next__()
```

2

StopIteration

```
>>> a.__next__()
```

```
3
```

```
>>> a.__next__()
```

```
4
```

```
>>> a.__next__()
```

```
Traceback: ... StopIteration
```

How a For Loop Works

```
for x in nums: print(f'x = {x}')
```

```
it = nums.__iter__()  
try:  
    while True:  
        x = it.__next__()  
        print(f'x = {x}')except StopIteration:  
    pass
```


Lots of Things Are Iterable

```
>>> '__iter__' in dir([1,2,3])           list  
True
```

```
>>> '__iter__' in dir(range(3,5))       range  
True
```

```
>>> '__iter__' in dir({1,2,3})         set  
True
```

```
>>> '__iter__' in dir({'foo' : 3})     dictionary  
True
```

Make Your Own Iterable Thing

Needs an `__iter__` method.

```
class MyIterable():  
  
    def __init__(self, vals):  
        self.vals = vals  
  
    def __iter__(self):  
        return MyIterator(self.vals) ←
```

Make Your Own Iterator

Needs a `__next__` method.

```
class MyIterator():
    def __init__(self, vals):
        self.vals = vals
        self.index = 0

    def __next__(self): ←
        if self.index == len(self.vals):
            raise StopIteration
        else:
            self.index += 1
            return self.vals[self.index-1]
```

Testing MyIterable

```
>>> a = MyIterable([1, 2, 3, 4])
>>> for x in a: print(f'x = {x}')
x = 1
x = 2
x = 3
x = 4

>>> [x**3 for x in a]
[1, 8, 27, 64]
```

Generators

- Generators are *coroutines* that suspend their state using the **yield** keyword.
- Generators are represented by **generator** objects instead of functions.
- Generators can be used either as *producers* (similar to iterators) or as *consumers*.

Generator As Producer

```
def myproducer(vals):  
    print('myproducer called')  
    index = 0  
    while index < len(vals):  
        print('yielding')  
        yield vals[index] ←  
        index += 1  
    raise StopIteration
```

Because “yield” appears in myproducer, calling myproducer doesn't actually run the function; it returns a generator object.

Generator As Producer

```
>>> g = myproducer(['foo', 'bar'])  
<generator object myproducer at ...>
```

```
>>> next(g)  
myproducer called ←  
yielding  
'foo'
```

```
>>> next(g)  
yielding  
'bar'
```

Generator Expressions

Like a list comprehension, but uses parentheses instead of brackets: lazy.

```
>>> g = (x**2 for x in [1,2,3,4,5])  
<generator object <genexpr> at ...>
```

```
>>> next(g)  
1
```

```
>>> g.__next__()  
4
```


list() exhausts a generator

```
>>> g  
<generator object <genexpr> at ...>
```

```
>>> list(g)  
[9, 16, 25]
```

Generator As Consumer

```
def myconsumer():  
    print('myconsumer called')  
    try:  
        while True:  
            x = yield ←  
            print(f'{x} squared is {x**2}')  
    except GeneratorExit:  
        print('Generator closed.')
```

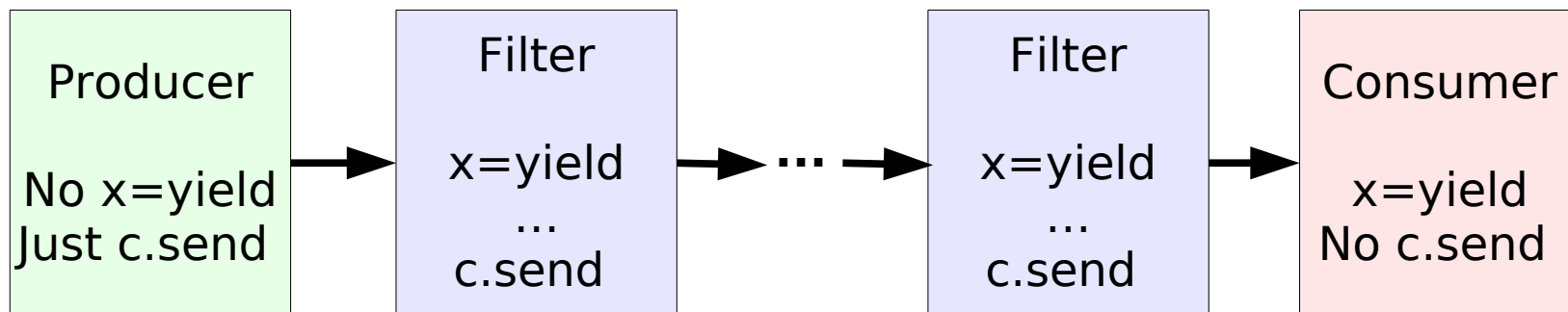
A statement 'x = yield' marks a *consumer* generator, which must be primed.

Generator As Consumer

```
>>> c = myconsumer()  
<generator object myconsumer at ...>  
>>> c.send(None)  
myconsumer called ←  
>>> for x in range(1,5): c.send(x)  
1 squared is 1  
2 squared is 4  
...  
>>> c.close()  
Generator closed.
```

Generator Pipeline

Generators can be chained together for complex processing tasks.



That's all we're going to say about generators. What about coroutines?

Coroutines Since Python 3.5

- In computer science, coroutines are procedures that repeatedly cede control to other coroutines and get it back again.
- In CS terms, Python generators can be regarded as coroutines: they “yield”.
- But in Python, coroutines are part of the **asyncio** module and do *not* use yield. So generators are *not* “coroutines” in Python.

asyncio

- A Python coroutine is defined using the keywords **async def** instead of the usual **def**.
- Coroutines use the **await** keyword to cede control:
 await mycor()
and to receive values:
 x = **await** mycor()
- They return a value using **return**.
- Coroutines cannot use **yield**.

asyncio event loop

- The **asyncio** module provides for the *asynchronous* execution of coroutines. How?
- asyncio provides a task scheduler called an *event loop*.
- You can create tasks manually with `loop.create_task()`.
- You can also give the loop a coroutine object and it will create a task for you.

Coroutine Example

```
import asyncio
```

```
async def yourcor(i):  
    await asyncio.sleep(1)  
    return i**2
```



```
async def mycor():  
    for i in range(1,5):  
        print(f'i={i}', end=' ')  
        x = await yourcor(i)  
        print(f' x={x}')
```



Testing the Coroutine Example

```
>>> loop = asyncio.get_event_loop()  
<_UnixSelectorEventLoop ...>
```

```
>>> c = mycor()  
<coroutine object mycor at ...>
```

```
>>> loop.run_until_complete(c)  
i=1 x=1  
i=2 x=4  
i=3 x=9  
i=4 x=16
```

Adding Tasks To the Queue

```
>>> t = loop.create_task(yourcor(5))  
<Task pending coro=yourcor() ...>
```

```
>>> loop.run_until_complete(t)  
25
```

Scheduling Non-Coroutines

- What if you want the event loop to execute a regular function instead of a coroutine?
- Use `loop.call_soon()` or `loop.call_later()`
- Instead of creating a `Task`, this creates a `Handle` or `TimerHandle` and schedules it for immediate or delayed execution.

Scheduling Non-Coroutines

```
def goof(i):  
    print('i=', i)
```

```
>>> loop.call_soon(goof, 150)
```

```
<Handle goof(150) at ...>
```

```
>>> loop.call_later(3, goof, 250)
```

```
<TimerHandle when=...>
```

```
>>> loop.run_forever()
```

```
i=150
```

```
i=250
```

Futures

- A Future is an object representing a value that might not have been computed yet.
- Created by `loop.create_future()`
- A coroutine can return a Future and then later some other coroutine can fill in the value.
- You can test whether a Future has completed, or set up a callback that will be called when the Future completes.

Threads

- Threads are lightweight units of execution within a process that run simultaneously.
- Threads share one address space.
- If two threads modify the same memory at the same time, bad things may happen.
- “Thread-safe” code uses interlocks to prevent this.
- `loop.call_soon_threadsafe()` lets secondary threads access the event loop.

VEX AIM SDK Robot Interaction

- Uses websockets to talk to the robot.
- Four secondary threads:
 - **Image thread** receives camera frames
 - **Status thread** receives status updates:
 - Sensor values and odometry
 - Object detection results (“aivision”)
 - Actions in progress (motion, sound)
 - **Command thread** transmits commands to the robot
 - **Audio thread** transmits audio files to the robot

VEX AIM SDK: Files

- `aim.py` contains most of the SDK
- `vex.py` contains type definitions and important constants

VEX AIM SDK: Low-Level Control

- The SDK only provides simple, low-level primitives.
- Example: how to drive forward 50 mm?
- `robot.move_for(50, 0)`
 - Waits until move is complete.
 - No other processing can take place while waiting. *This is not a good thing!*
- `robot.move_for(50, 0, wait=False)`
 - Doesn't wait. Now it's your responsibility to notice when the robot stops moving.

vex-aim-tools

- Built on top of the VEX AIM SDK.
- Supports event-based programming so actions run asynchronously and you can be notified when the robot finishes an action.
- Runs an asyncio event loop in a secondary thread so the main thread is available for the Python REPL: debug your program while it runs.
- User programs run in the secondary thread, using the event loop.

vex-aim-tools

- Provides asynchronous services:
 - speech recognition
 - speech generation
 - GPT-4 interface
 - other computationally intensive things
- Runs visualization tools (camera viewer, worldmap viewer, etc.) in their own threads.

Does This Look Like Fun? No???

- Explicitly managing asynchronous actions and events could be a real pain.
- Is there a better way?



- State machines. See next lecture.