

## Lecture 14

### SSA-Style Optimizations

(Slides courtesy of Seth Goldstein.)

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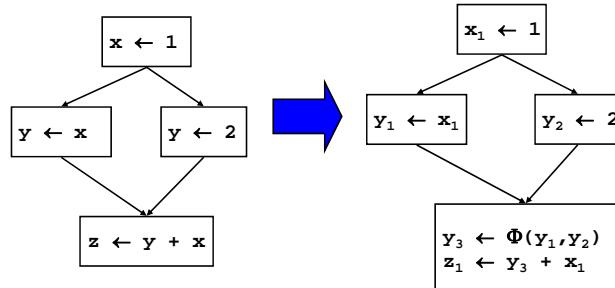
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#### Review: Minimal SSA

- Each assignment generates a fresh variable.
- At each join point insert  $\Phi$  functions for all variables with **multiple outstanding defs**.



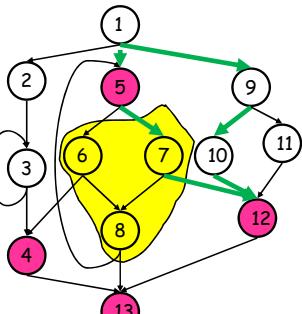
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#### Review: Dominance Frontier and Path Convergence



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#### Constant Propagation

- If " $v \leftarrow c$ ", replace all uses of  $v$  with  $c$
- If " $v \leftarrow \Phi(c, c, c)$ ", replace all uses of  $v$  with  $c$

```

W <- list of all defs
while !W.isEmpty {
    Stmt S <- W.removeOne
    if S has form "v <- Φ(c,...,c)"
        replace S with V <- c
    if S has form "v <- c" then
        delete S
        foreach stmt U that uses v,
            replace v with c in U
        W.add(U)
}

```

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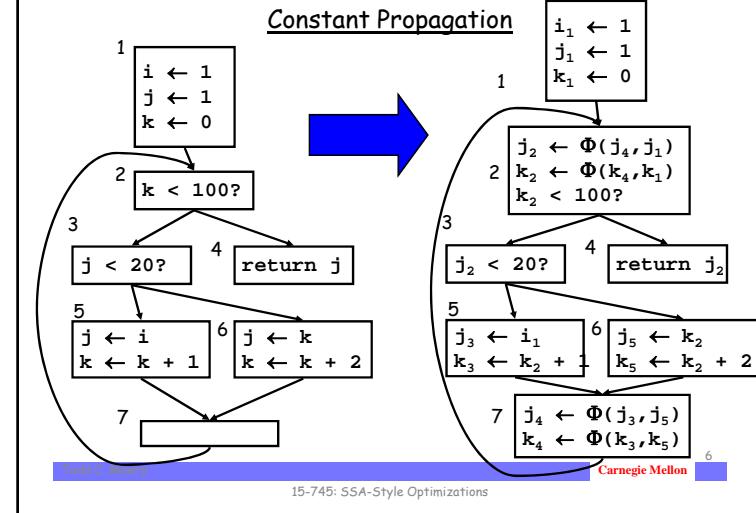
### Other Optimizations with SSA

- **Copy propagation**
  - delete " $x \leftarrow \Phi(y, y, y)$ " and replace all  $x$  with  $y$
  - delete " $x \leftarrow y$ " and replace all  $x$  with  $y$
- **Constant Folding**
  - (Also, constant conditions too!)
- **Unreachable Code**
  - Remember to delete all edges from unreachable block

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### Constant Propagation

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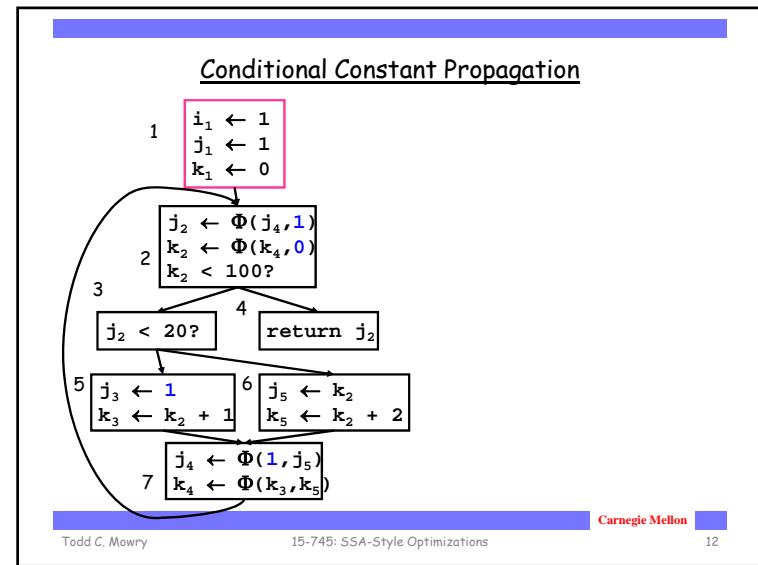
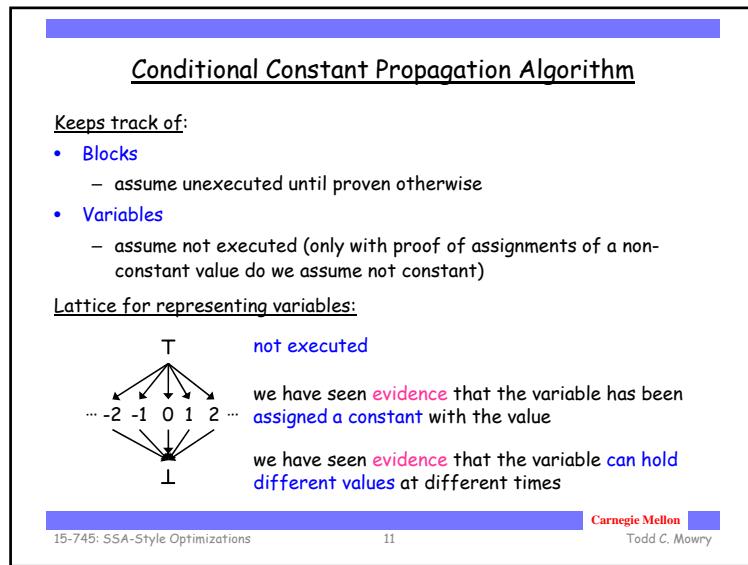
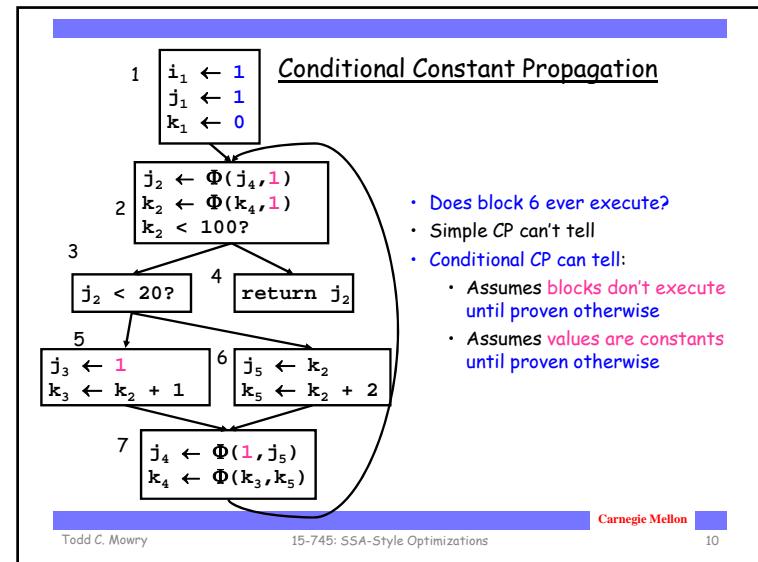
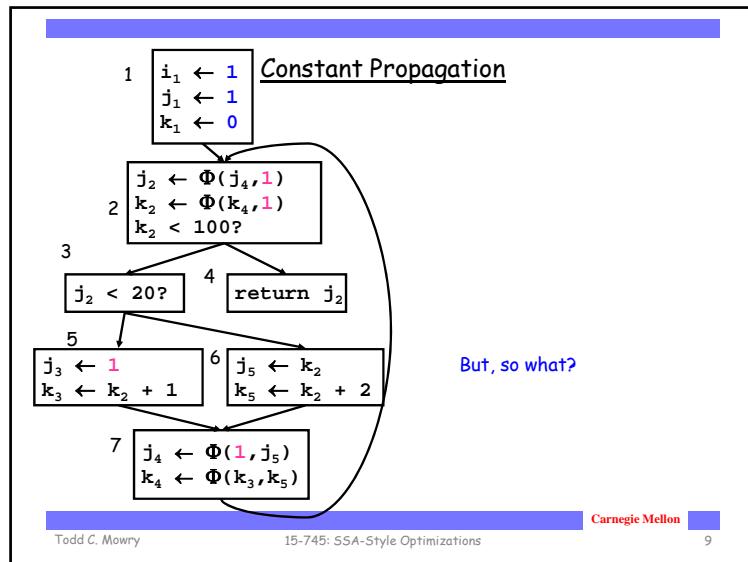
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### Constant Propagation

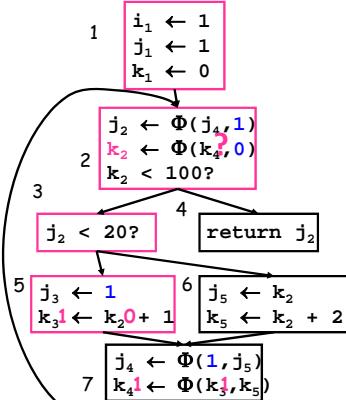
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### Conditional Constant Propagation

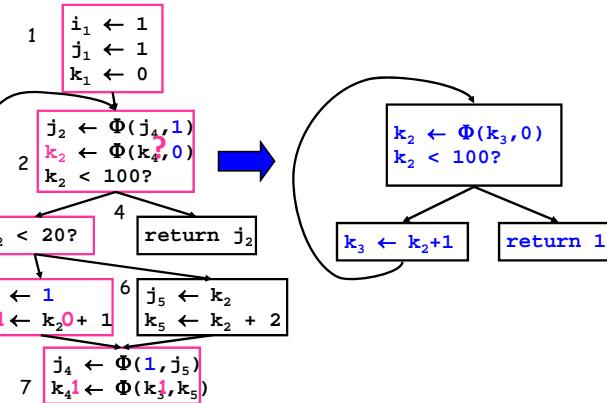


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### Conditional Constant Propagation



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### Dead Code Elimination

```

W ← list of all defs
while !W.isEmpty {
    Stmt S ← W.removeOne
    if |S.users| != 0 then continue
    if S.hasSideEffects() then continue
    foreach def in S.definers {
        def.users <- def.users - {S}
        if |def.users| == 0 then
            W ← W UNION {def}
    }
    delete S
}
  
```

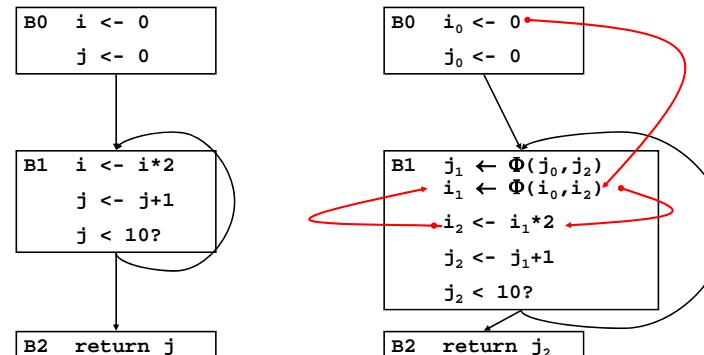
Since we are using SSA, this is just a list of all variable assignments.

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### Example DCE



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### Aggressive Dead Code Elimination

Assume a statement is dead until proven otherwise.

```

init:
    mark as live all stmts that have side-effects:
        - I/O
        - stores into memory
        - returns
        - calls a function that MIGHT have side-effects
    As we mark S live, insert S.defs into W

while (|W| > 0) {
    S <- W.removeOne()
    if (S is live) continue;
    mark S live, insert S.defs into W
}

```

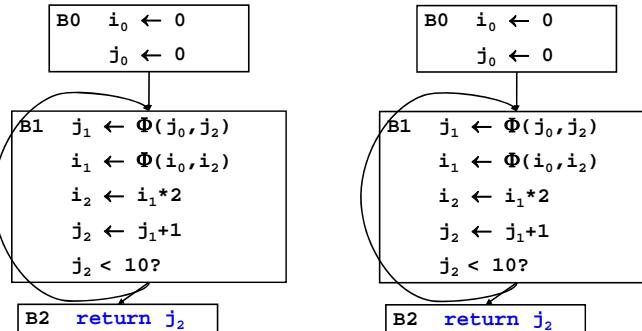
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### Example DCE



Problem!

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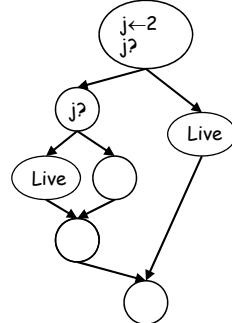
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### Fixing DCE

if S is live, then

if T determines if S can execute, T should be live



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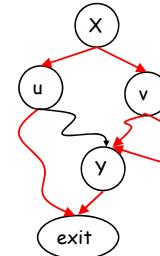
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### Control Dependence

y is control-dependent on X if

- X branches to u and v
- $\exists$  a path  $u \rightarrow \text{exit}$  which does not go through Y
- $\forall$  paths  $v \rightarrow \text{exit}$  go through Y

i.e. X can determine whether or not Y is executed.



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### Aggressive Dead Code Elimination

Assume a statement is dead until proven otherwise.

```

while (|W| > 0) {
    S <- W.removeOne()
    if (S is live) continue;
    mark S live, insert:
        - forall operands, S.operand.definers into W
        - S.CD-1 into W
}

```

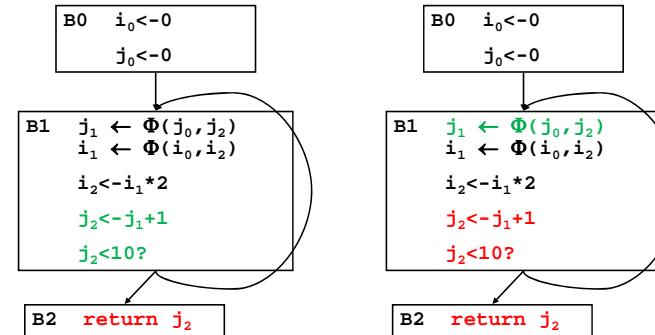
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### Example DCE



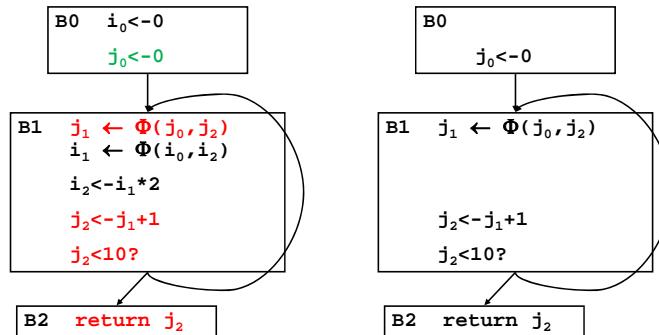
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### Example DCE



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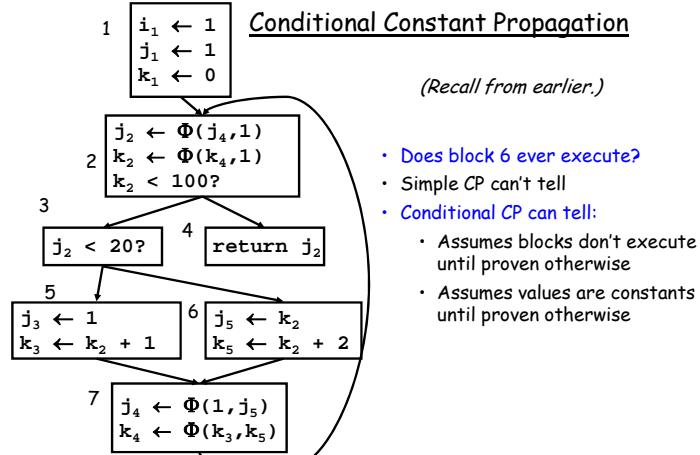
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### Conditional Constant Propagation

(Recall from earlier.)



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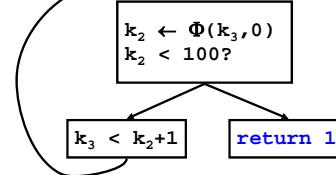
### Applying Dead Code Elimination to the Result of CCP

After CCP

```
i1 ← 1
j1 ← 1
k1 ← 0
```

After DCE

return 1



Small problem.

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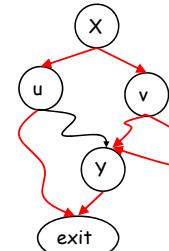
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### Finding the Control Dependence Graph

**y** is control-dependent on **x** if

- X branches to u and v
- ∃ a path u→exit which does not go through Y
- ∀ paths v→exit go through Y

i.e. X can determine whether or not Y is executed.

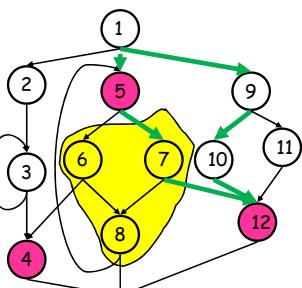


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### Dominance Frontier and Path Convergence



Any ideas?

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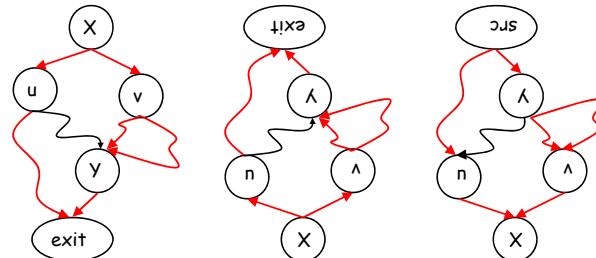
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### Finding the Control Dependence Graph

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### Finding the CDG

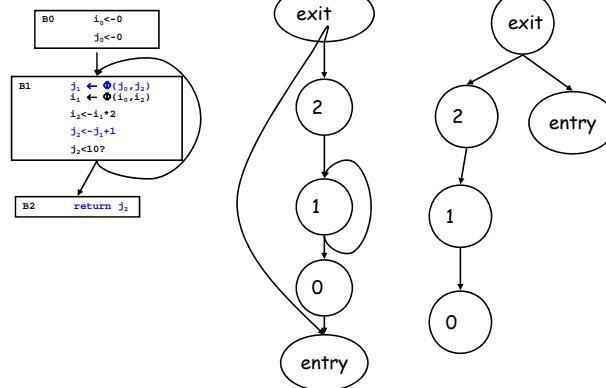
- Construct CFG
- Add entry node and exit node
- Add (entry,exit)
- Create  $G'$ , the reverse CFG
- Compute D-tree in  $G'$  (post-dominators of  $G$ )
- Compute  $DF_G(y)$  for all  $y \in G'$  (post-DF of  $G$ )
- Add  $(x,y) \in G$  to CDG if  $x \in DF_G(y)$

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### CDG of example

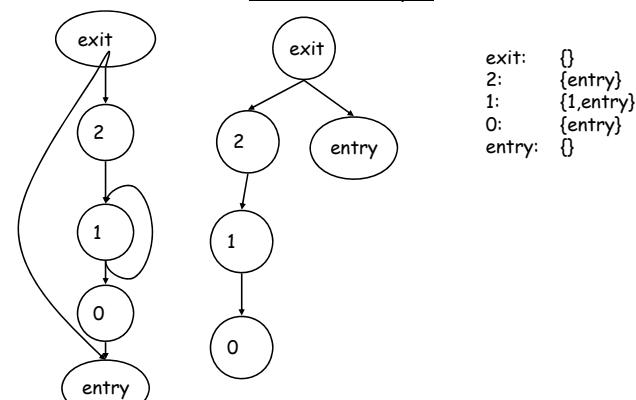


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### CDG of example



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