15-745: Optimizing Compilers for Modern Architectures

Lecture 1: Introduction

What would you get out of this course?

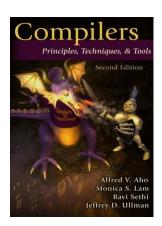
Structure of a Compiler

Optimization Example

Course Logistics

- If you are on the waitlist, come see me after class
 - This course is not intended to be your first compiler course
- Let Pratik know if can't get on Piazza or Canvas for this course

Need to get the book







Let's run through the course webpage at http://www.cs.cmu.edu/~15745/

Carnegie Mellon

15-745: Introduction 2 Phillip B. Gibbons

What Do Compilers Do?

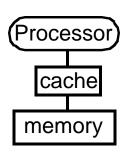
- 1. Translate one language into another
 - e.g., convert C++ into x86 object code
 - difficult for "natural" languages, but feasible for computer languages

- 2. Improve (i.e. "optimize") the code
 - e.g., make the code run 3 times faster
 - or more energy efficient, more robust, etc.
 - driving force behind modern processor design

How Can the Compiler Improve Performance?

Execution time = Operation count * Machine cycles per operation

- Minimize the number of operations
 - arithmetic operations, memory accesses
- Replace expensive operations with simpler ones
 - e.g., replace 4-cycle multiplication with 1-cycle shift
- Minimize cache misses
 - both data and instruction accesses
- Perform work in parallel
 - instruction scheduling within a thread
 - parallel execution across multiple threads

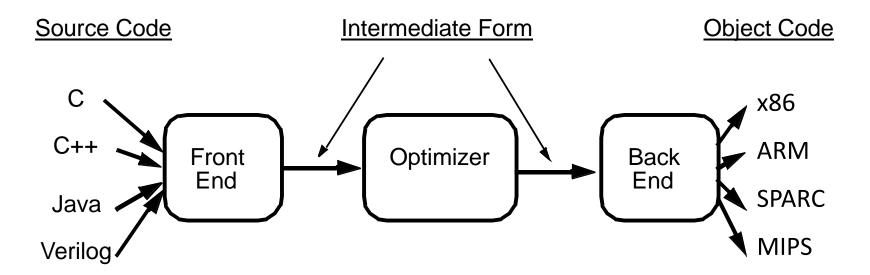


More accurately, machine cycles per operation must account for instruction overlap

What Would You Get Out of This Course?

- Basic knowledge of existing compiler optimizations
- Hands-on experience in constructing optimizations within a fully functional research compiler
- Basic principles and theory for the development of new optimizations

II. Structure of a Compiler



- Optimizations are performed on an "intermediate form"
 - similar to a generic RISC instruction set
- Allows easy portability to multiple source languages, target machines

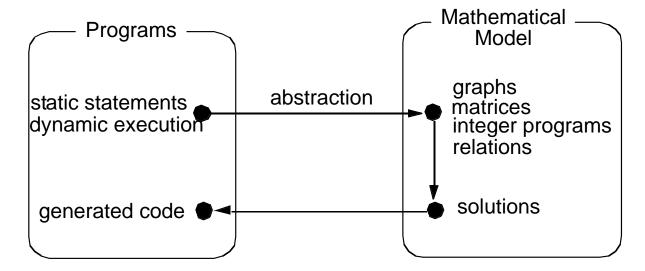
Ingredients in a Compiler Optimization

Formulate optimization problem

- Identify opportunities of optimization
 - applicable across many programs
 - affect key parts of the program (loops/recursions)
 - amenable to "efficient enough" algorithm

Representation

Must abstract essential details relevant to optimization



Ingredients in a Compiler Optimization

- Formulate optimization problem
 - Identify opportunities of optimization
 - applicable across many programs
 - affect key parts of the program (loops/recursions)
 - amenable to "efficient enough" algorithm
- Representation
 - Must abstract essential details relevant to optimization
- Analysis
 - Detect when it is desirable and safe to apply transformation
- Code Transformation
- Experimental Evaluation (and repeat process)

Representation: Instructions

Three-address code

```
A := B op C
LHS: name of variable e.g. x, A[t] (address of A + contents of t)
```

• RHS: value

Typical instructions

```
A := B op C

A := unaryop B

A := B

GOTO s

IF A relop B GOTO s

CALL f

RETURN
```

III. Optimization Example: Bubblesort

- Bubblesort program that sorts an array A that is allocated in static storage:
 - an element of A requires four bytes of a byte-addressed machine
 - elements of A are numbered 1 through n (n is a variable)
 - A[j] is in location &A+4* (j-1)

```
for (i = n-1; i >= 1; i--) {
  for (j = 1; j <= i; j++)
    if (A[j] > A[j+1]) {
      temp = A[j];
      A[j] = A[j+1];
      A[j+1] = temp;
}
```

Translated (Pseudo) Code

```
i := n-1
                                           t8 := j-1
  L5: if i<1 goto L1
                                           t9 := 4*t8
       i := 1
                                           temp := A[t9] ; temp:=A[j]
  L4: if j>i goto L2
                                          t10 := j+1
       t1 := j-1
                                          t11:= t10-1
       t2 := 4*t1
                                          t12 := 4*t11
       t3 := A[t2] ; A[i]
                                          t13 := A[t12] ; A[j+1]
       t4 := j+1
                                          t14 := j-1
       t5 := t4-1
                                          t15 := 4*t14
       t6 := 4*t5
                                          A[t15] := t13 ; A[j] := A[j+1]
       t7 := A[t6] ; A[j+1]
                                          t16 := j+1
       if t3<=t7 goto L3
                                          t17 := t16-1
                                          t18 := 4*t17
                                          A[t18]:=temp ; A[j+1]:=temp
for (i = n-1; i >= 1; i--) {
                                      L3: j := j+1
  for (j = 1; j \le i; j++)
                                          goto L4
    if (A[i] > A[i+1]) {
                                      L2: i := i-1
     temp = A[j];
                                                           29 in outer loop
                                          goto L5
      A[\dot{j}] = A[\dot{j}+1];
                                                           25 in inner loop
                                      L1:
      A[j+1] = temp;
    }
```

}

Instructions

Representation: a Basic Block

- Basic block = a sequence of 3-address statements
 - only the first statement can be reached from outside the block (no branches into middle of block)
 - all the statements are executed consecutively if the first one is (no branches out or halts except perhaps at end of block)
- We require basic blocks to be maximal
 - they cannot be made larger without violating the conditions
- Optimizations within a basic block are *local* optimizations

Find the Basic Blocks

L1:

```
i := n-1
                            B1
    if i<1 goto L1
L5:
                            B2
                            B3
     j := 1
L4:
    if j>i goto L2
                            B4
    t1 := j-1
                            B5
     t2 := 4*t1
     t3 := A[t2] ; A[i]
     t4 := j+1
     t5 := t4-1
     t6 := 4*t5
     t7 := A[t6] ; A[j+1]
     if t3<=t7 goto L3
```

Basic Block:
Only enter at first
Only exit at last

```
t8 := j-1
                               B6
    t9 := 4*t8
    temp := A[t9] ; temp:=A[j]
    t10 := j+1
    t11:= t10-1
    t12 := 4*t11
    t13 := A[t12] ; A[j+1]
    t14 := j-1
    t15 := 4*t14
    A[t15] := t13 ; A[j] := A[j+1]
    t16 := j+1
    t17 := t16-1
    t18 := 4*t17
    A[t18] := temp ; A[j+1] := temp
L3: j := j+1
                               B7
    goto L4
L2: i := i-1
                               B8
   goto L5
```

Flow Graphs

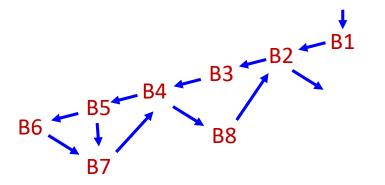
- Nodes: basic blocks
- Edges: B_i -> B_j, iff B_j can follow B_i immediately in some execution
 - Either first instruction of B_i is target of a goto at end of B_i
 - Or, B_i physically follows B_i, which does not end in an unconditional goto.
- The block led by first statement of the program is the start, or entry node.

Example Flow Graph

```
i := n-1
                          B1
                                     t8 := j-1
                                                               B6
L5:
    if i<1 goto L1
                          B2
                                     t9 := 4*t8
                           B3
    i := 1
                                     temp := A[t9] ; temp:=A[j]
L4:
    if j>i goto L2
                          B4
                                     t10 := j+1
    t1 := j-1
                          B5
                                     t11:= t10-1
     t2 := 4*t1
                                     t12 := 4*t11
     t3 := A[t2] ; A[j]
                                     t13 := A[t12] ; A[j+1]
     t4 := j+1
                                     t14 := j-1
    t5 := t4-1
                                     t15 := 4*t14
    t6 := 4*t5
                                     A[t15] := t13 ;A[j]:=A[j+1]
    t7 := A[t6] ; A[j+1]
                                     t16 := j+1
     if t3<=t7 goto L3
                                     t17 := t16-1
                                     t18 := 4*t17
                                     L3: j := j+1
                                                               B7
                         B1
                    B2
                                     goto L4
                B3
                                 L2: i := i-1
                                                               B8
          B4
      B5
                                     goto L5
 B6
                B8
                                 L1:
      B7
```

Example Flow Graph

```
i := n-1
                            B1
L5:
    if i<1 goto L1
                            B2
                            B3
     j := 1
    if j>i goto L2
L4:
                            B4
     t1 := j-1
                            B5
     t2 := 4*t1
     t3 := A[t2] ; A[j]
     t4 := j+1
     t5 := t4-1
     t6 := 4*t5
     t7 := A[t6] ; A[j+1]
     if t3 \le t7 goto L3
```



```
B6
   t8 := j-1
   t9 := 4*t8
   temp := A[t9] ; temp:=A[j]
   t10 := j+1
   t11:= t10-1
   t12 := 4*t11
   t13 := A[t12] ; A[j+1]
   t14 := j-1
   t15 := 4*t14
   A[t15] := t13 ;A[j]:=A[j+1]
   t16 := j+1
   t17 := t16-1
   t18 := 4*t17
   L3: j := j+1
                            B7
   goto L4
L2: i := i-1
                            B8
   goto L5
L1:
```

Sources of Optimizations

Algorithm optimization

Algebraic optimization

$$A := B+0 => A := B$$

- Local optimizations
 - within a basic block -- across instructions
- Global optimizations
 - within a flow graph -- across basic blocks
- Interprocedural analysis
 - within a program -- across procedures (flow graphs)

Local Optimizations

- Analysis & transformation performed within a basic block
- No control flow information is considered
- Examples of local optimizations:
 - local common subexpression elimination analysis: same expression evaluated more than once in a block transformation: replace with single calculation

 local constant folding or elimination analysis: expression can be evaluated at compile time transformation: replace by constant, compile-time value

dead code elimination

Local Optimization (Redundancy in Address Calculation)

```
t8 := j-1
    t9 := 4*t8
    temp := A[t9] ; temp:=A[j]
    t10 := j+1
    t11:= t10-1
    t12 := 4*t11
   t13 := A[t12] ; A[j+1]
   t14 := j-1
    t15 := 4*t14
    A[t15] := t13 ; A[j] := A[j+1]
    t16 := j+1
    t17 := t16-1
    t18 := 4*t17
    A[t18]:=temp ; A[j+1]:=temp
L3: j := j+1
    goto L4
L2: i := i-1
    goto L5
L1:
```

Local Optimization Example

L1:

```
i := n-1
L5: if i<1 goto L1
    j := 1
L4: if j>i goto L2
    t1 := j-1
                         B5
     t2 := 4*t1
     t3 := A[t2] ; A[j]
    t6 := 4*j
    t7 := A[t6] ; A[j+1]
     if t3<=t7 goto L3
```

```
t8 :=j-1
    t9 := 4*t8
    temp := A[t9] ; temp:=A[j]
    t10 := j+1
    t11:= t10-1
    t12 := 4*t11
   t13 := A[t12] ; A[j+1]
    t14 := j-1
    t15 := 4*t14
    A[t15] := t13 ; A[j] := A[j+1]
    t16 := j+1
    t17 := t16-1
    t18 := 4*t17
    A[t18] := temp ; A[j+1] := temp
L3: i := i+1
    goto L4
L2: i := i-1
    goto L5
```

Local Optimization Example

```
i := n-1
L5: if i<1 goto L1
j := 1
L4: if j>i goto L2
t1 := j-1
t2 := 4*t1
t3 := A[t2] ;A[j]
t6 := 4*j
t7 := A[t6] ;A[j+1]
if t3<=t7 goto L3</pre>
```

```
t8 :=j-1
                              B6
    t9 := 4*t8
    temp := A[t9] ; temp:=A[j]
    t10 := j+1
    t11:=t10-1
    t12 := 4*t11
    t13 := A[t12] ; A[j+1]
   t14 := j-1
    t15 := 4*t14
   A[t15] := t13 ; A[i] := A[i+1]
   t16 := j+1
    t17 := t16-1
    t18 := 4*t17
    A[t18]:=temp ; A[j+1]:=temp
L3: i := i+1
    goto L4
L2: i := i-1
   goto L5
L1:
```

After Local Optimization

```
t8 :=j-1
   i := n-1
                                                                 B6
L5: if i<1 goto L1
                                      t9 := 4*t8
    j := 1
                                      temp := A[t9] ; temp:=A[j]
L4: if j>i goto L2
                                     t12 := 4*j
                                     t13 := A[t12] ; A[j+1]
    t1 := j-1
   t2 := 4*t1
                                     A[t9] := t13 ; A[j] := A[j+1]
    t3 := A[t2] ; A[j]
                                     A[t12]:=temp
                                                    ;A[j+1]:=temp
                                 L3: j := j+1
   t6 := 4*j
   t7 := A[t6] ; A[j+1]
                                     goto L4
                                 L2: i := i-1
    if t3<=t7 goto L3
                                     goto L5
                                 L1:
```

Instructions
20 in outer loop
16 in inner loop

(Intraprocedural) Global Optimizations

Global versions of local optimizations

- global common subexpression elimination
- global constant propagation
- dead code elimination

Loop optimizations

- reduce code to be executed in each iteration
- code motion
- induction variable elimination

Other control structures

 Code hoisting: eliminates copies of identical code on parallel paths in a flow graph to reduce code size.

Global (Across Basic Blocks) Optimization Example

```
B6
   i := n-1
                                  t8 :=j-1
                                  t9 := 4*t8
L5: if i<1 goto L1
   j := 1
                                  temp := A[t9] ; temp:=A[j]
L4: if j>i goto L2
                                  t12 := 4*j
   t1 := j-1
                                  t13 := A[t12] ;A[j+1]
                      B5
   t2 := 4*t1
                                  A[t9]:= t13 | ;A[j]:=A[j+1]
   t3 := A[t2] ; A[j]
                                  L3: j := j+1
   t6 := 4*j
   t7 := A[t6] ; A[j+1]
                                  goto L4
                              L2: i := i-1
   if t3<=t7 goto L3
                                  goto L5
                              L1:
```

After Global Subexpression Elimination

```
A[t2] := t7 ;A[j]:=A[j+1] B6
A[t6] := t3 ;A[j+1]:=old_A[j]
L3: j := j+1
goto L4
L2: i := i-1
goto L5
L1:
```

Instructions
15 in outer loop
11 in inner loop

Induction Variable Elimination

Intuitively

- Loop indices are induction variables (counting iterations)
- Linear functions of the loop indices are also induction variables (for accessing arrays)
- Analysis: detection of induction variable
- Optimizations
 - strength reduction:
 - replace multiplication by additions
 - elimination of loop index:
 - replace termination by tests on other induction variables

Induction Variable Elimination Example

```
i := n-1
L5: if i<1 goto L1
    i := 1
L4: if j>i goto L2
    t1 := j-1
    t2 := 4*t1
    t3 := A[t2]
   t6 := 4*j
    t7 := A[t6]
    if t3<=t7 goto L3
    A[t2] := t7
    A[t6] := t3
L3: j := j+1
    goto L4
L2: i := i-1
    goto L5
L1:
```

After Induction Variable Elimination

```
i := n-1
    i := n-1
                                  L5: if i<1 goto L1
L5: if i<1 goto L1
                                       t2 := 0
    i := 1
                                       t6 := 4
L4: if j>i goto L2
                                      t19 := 4*i
                                  L4:
    t1 := j-1
                                      if t6>t19 goto L2
    t2 := 4*t1
                                      t3 := A[t2]
    t3 := A[t2]
                                      t7 := A[t6]
   t6 := 4*j
                                       if t3<=t7 goto L3
    t7 := A[t6]
                                       A[t2] := t7
    if t3<=t7 goto L3
                                       A[t6] := t3
    A[t2] := t7
                                  L3: t2 := t2+4
    A[t6] := t3
                                       t6 := t6+4
L3: j := j+1
                                       goto L4
    goto L4
                                  L2: i := i-1
L2: i := i-1
                                       goto L5
    goto L5
                                  L1:
L1:
```

<u>Instructions</u>

15 in outer loop 10 in inner loop

Loop Invariant Code Motion

Analysis

- a computation is done within a loop and
- result of the computation is the same as long as we keep going around the loop

Transformation

move the computation outside the loop

Loop Invariant Code Motion Example

```
i := n-1
                                      A[t2] := t7
L5: if i<1 goto L1
                                      A[t6] := t3
    t2 := 0
                                  L3: t2 := t2+4
                        B3
    t6 := 4
                                      t6 := t6+4
L4: t19 := 4*i
                        B4
                                      goto L4
    if t6>t19 goto L2
                                  L2: i := i-1
    t3 := A[t2]
                                      goto L5
    t7 := A[t6]
                                  L1:
    if t3<=t7 goto L3
```

Final Code

B3

B4

L4: if t6>t19 goto L2

$$t3 := A[t2]$$

$$t7 := A[t6]$$

$$A[t2] := t7$$

$$A[t6] := t3$$

L3:
$$t2 := t2+4$$

$$t6 := t6+4$$

L1:

Before Optimizations

29 in outer loop 25 in inner loop

After Optimizations

15 in outer loop 9 in inner loop

Machine Dependent Optimizations

- Register allocation
- Instruction scheduling
- Memory hierarchy optimizations
- etc.

Friday's Class

- Pratik will present "LLVM Compiler: Getting Started"
 - part 1 of 2 on LLVM
- Assignment 1 will be handed out

Reminder: Wait listed students see me now

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