

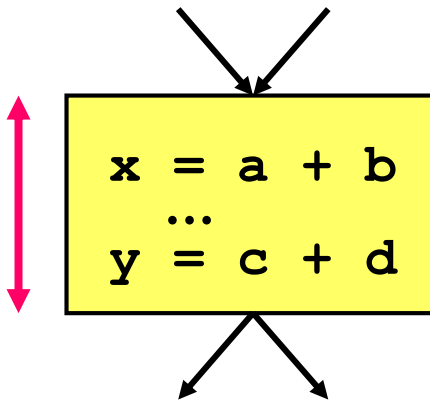
# Lecture 20

## Global Scheduling

- I. Legal code motions
- II. Basic Algorithm

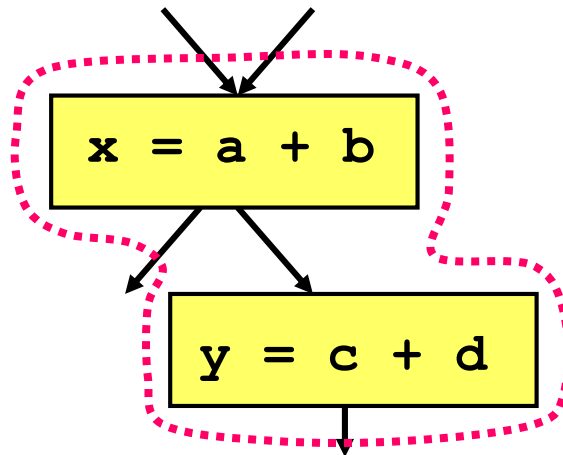
[ALSU 10.4]

# Scheduling Roadmap



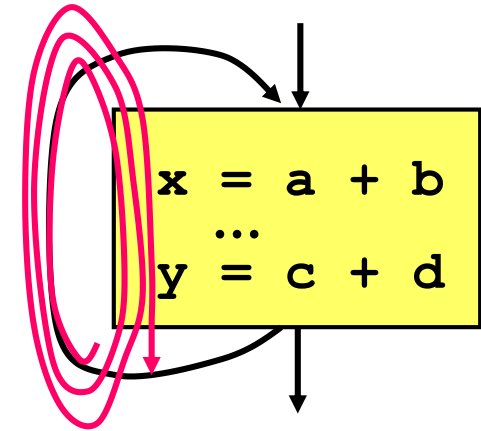
## List Scheduling:

- *within* a basic block  
(prior lecture)



## Global Scheduling:

- *across* basic blocks



## Software Pipelining:

- *across* loop iterations

## Review: List Scheduling

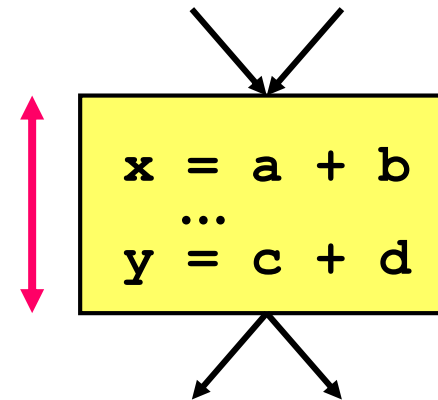
- The most common technique for scheduling instructions **within a basic block**

We don't need to worry about:

- control flow

We do need to worry about:

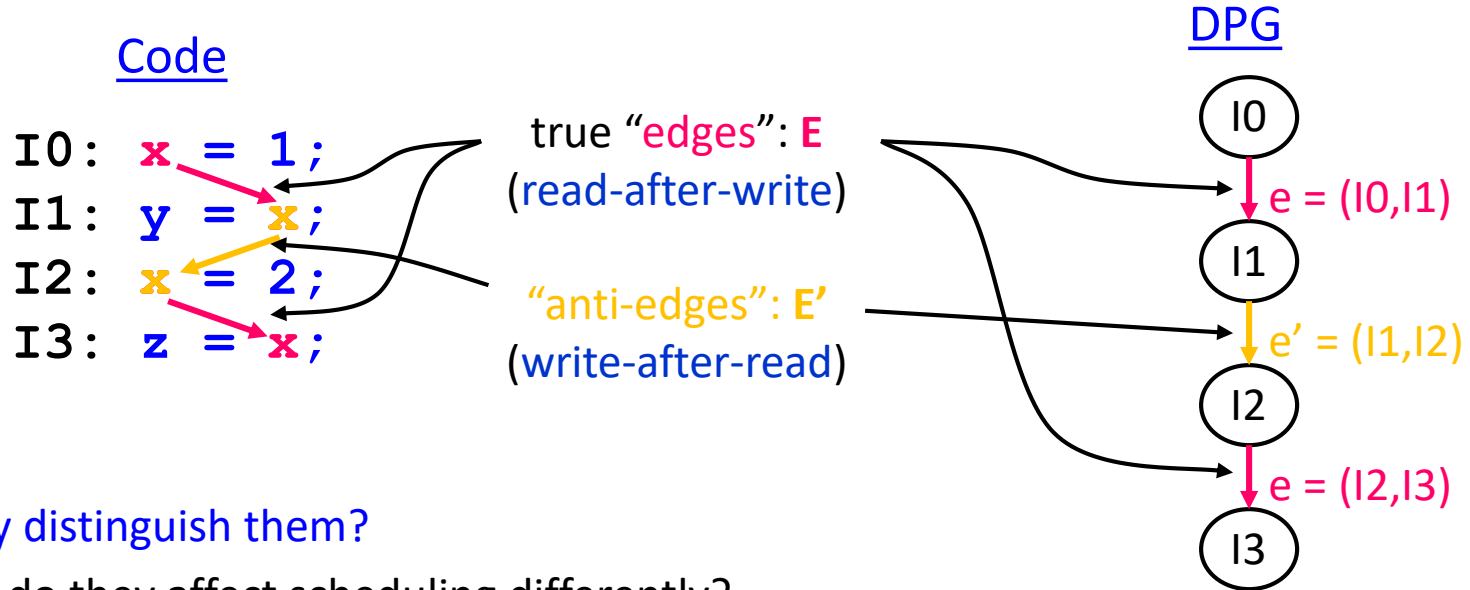
- data dependences
- hardware resources



- Even without control flow, the problem is still **NP-hard**

# Review: Representing Data Dependences: The Data Precedence Graph (DPG)

- Two different kinds of edges:



- Why distinguish them?

- do they affect scheduling differently?

RAW: read waits for value to be computed

WAR: write only needs ensure it's not started ahead of the read

- What about output dependences?

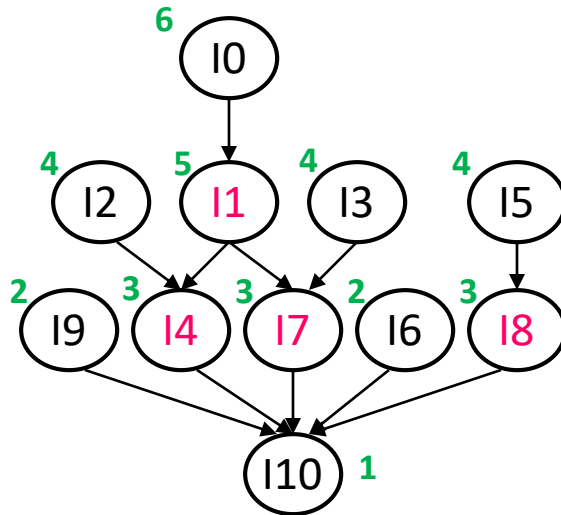
WAW: earlier write is removed by Dead Code Elimination

(recall we are scheduling a single basic block, so WAW is unconditional)

## Review: List Scheduling

$$\text{priority}(x) = \begin{cases} \text{latency}(x) & \text{if } x \text{ is a leaf} \\ \max(\text{latency}(x) + \max_{(x,y) \in E}(\text{priority}(y)), & \\ \max_{(x,y) \in E'}(\text{priority}(y))) & \text{otherwise.} \end{cases}$$

**I0:** a = 1  
**I1:** f = a + x  
**I2:** b = 7  
**I3:** c = 9  
**I4:** g = f + b  
**I5:** d = 13  
**I6:** e = 19  
**I7:** h = f + c  
**I8:** j = d + y  
**I9:** z = -1  
**I10:** JMP L1

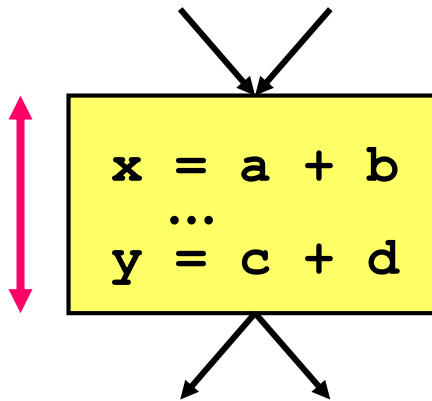


|     |     | <u>Cycle</u> |
|-----|-----|--------------|
| I0  | I2  | 0            |
| I1  | I3  | 1            |
| I5  | I6  | 2            |
| I4  | I7  | 3            |
| I8  | I9  | 4            |
| NOP | NOP | 5            |
| I10 | NOP | 6            |

- 2 identical **fully-pipelined** FUs
- **adds take 2 cycles**; all other insts take 1 cycle

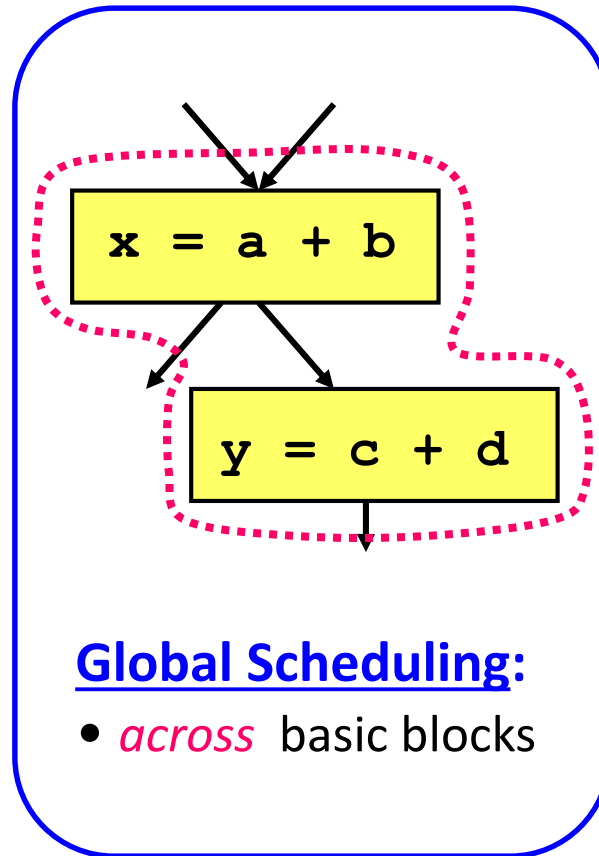
Break ties by lower instruction number

# Scheduling Roadmap



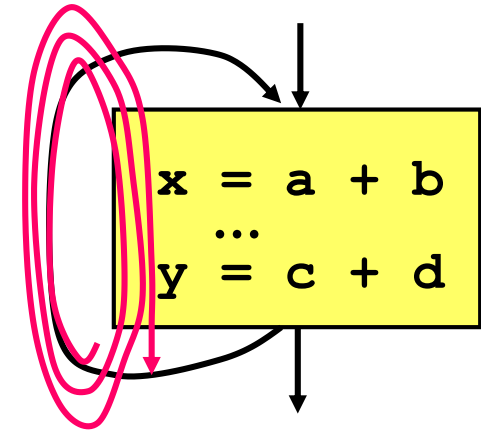
## List Scheduling:

- *within* a basic block



## Global Scheduling:

- *across* basic blocks



## Software Pipelining:

- *across* loop iterations

# Introduction to Global Scheduling

Assume each clock can execute  
 2 operations of any kind  
 Assume LD takes 2 cycles, fully pipelined

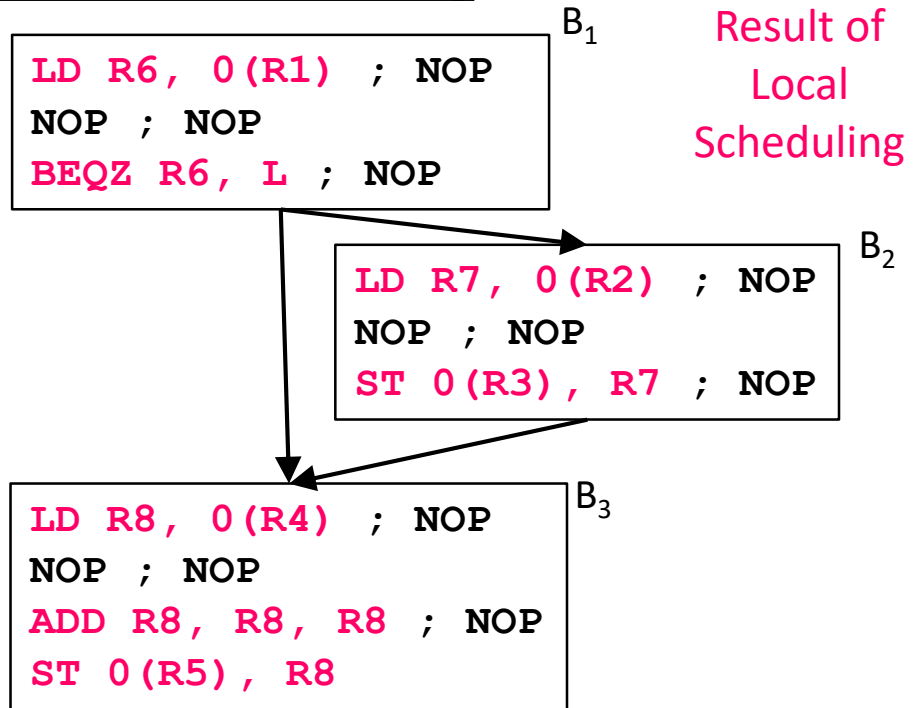
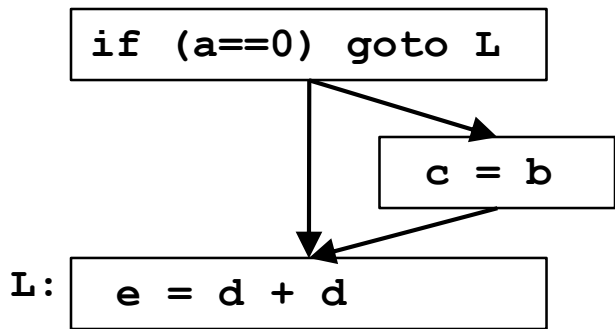
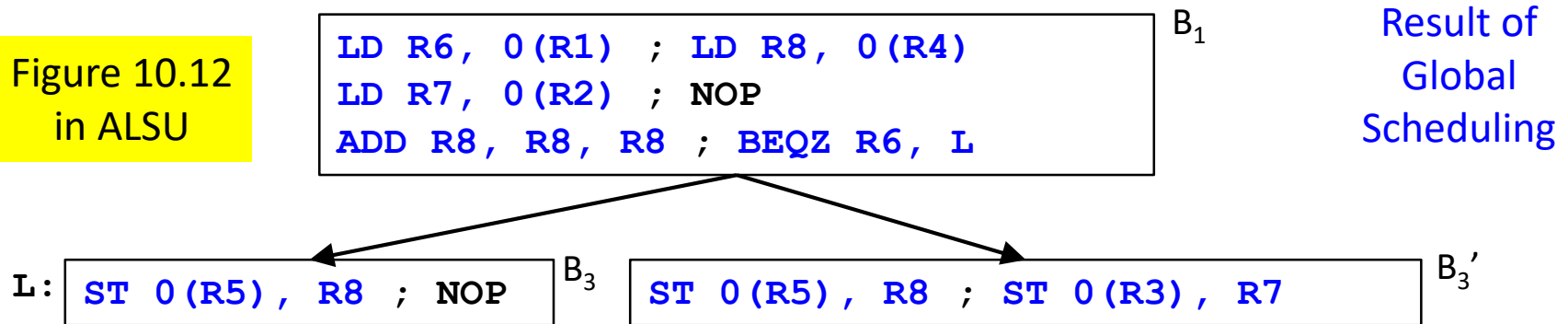


Figure 10.12  
 in ALSU



# Terminology

## Control equivalence:

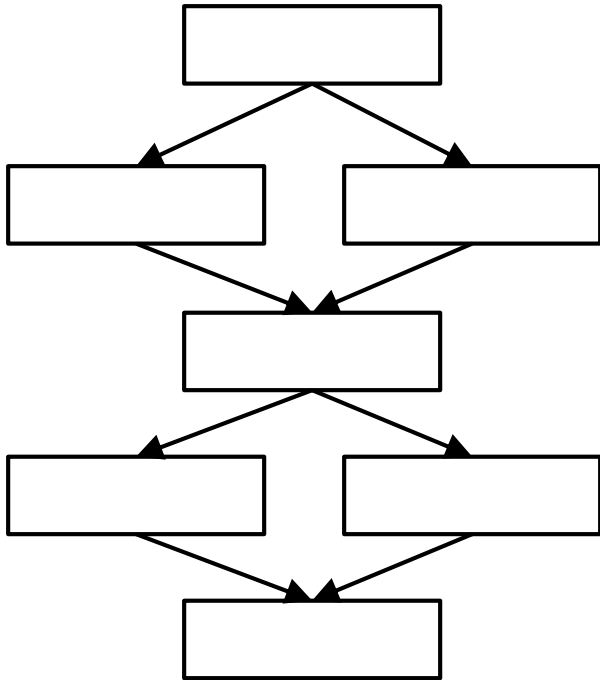
- Two operations  $o_1$  and  $o_2$  are *control equivalent* if  $o_1$  is executed if and only if  $o_2$  is executed.

## Control dependence:

- An op  $o_2$  is *control dependent* on op  $o_1$  if the execution of  $o_2$  depends on the outcome of  $o_1$ .

## Speculation:

- An operation  $o$  is *speculatively* executed if it is executed before all the operations it depends on (control-wise) have been executed.
- Requirements to execute operation speculatively?
  - No side-effects, does not raise an exception
  - Does not violate data dependences





## Code Motion

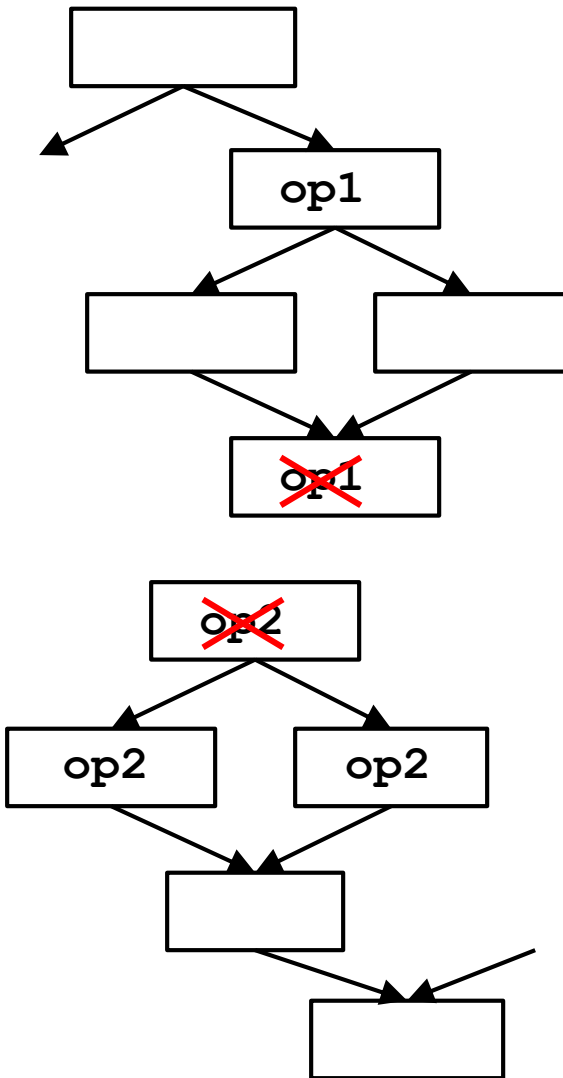
Goal: Shorten execution time **probabilistically**  
(based on estimated frequency of control path)

Moving instructions **up**:

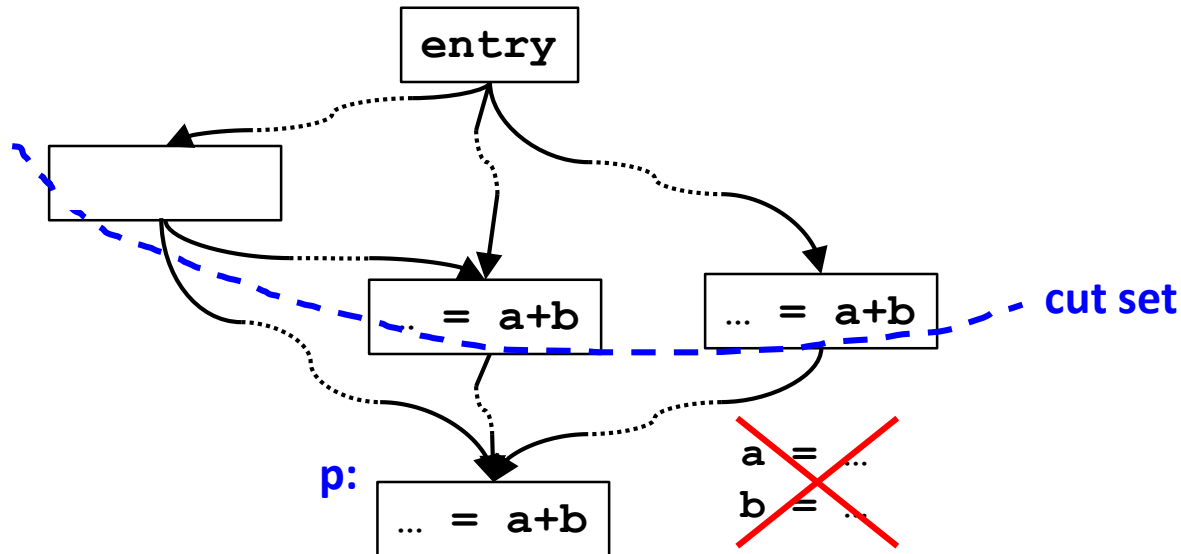
- Move instruction to a cut set (from entry)
- Speculation: even when not anticipated

Moving instructions **down**:

- Move instruction to a cut set (from exit)
- May execute extra instruction
- Can duplicate code



## Review: Code Motion for Partial Redundancy Elimination



- **Partial redundancy at p: redundant on some but not all paths**
  - Add operations to create a cut set containing `a+b`
  - Note: Moving operations up can eliminate redundancy
- **Constraint on placement: no wasted operation**
  - `a+b` is “anticipated” at B if its value computed at B will be used along ALL subsequent paths
  - `a, b` not redefined, no branches that lead to exit without use
- **Range where `a+b` is anticipated → Choice**

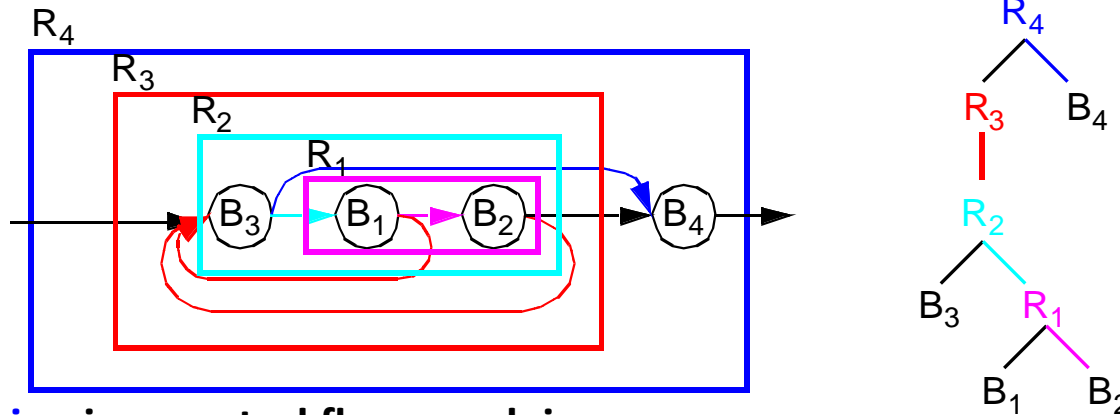
# General-Purpose Applications

- **Lots of data dependences**
- **Key performance factor: memory latencies**
- **Move memory fetches up**
  - Speculative memory fetches can be expensive
- **Control-intensive: get execution profile**
  - **Static estimation**
    - Innermost loops are frequently executed
      - back edges are likely to be taken
    - Edges that branch to exit and exception routines are not likely to be taken
  - **Dynamic profiling**
    - Instrument code and **measure** using representative data

## A Basic Global Scheduling Algorithm

- **Schedule innermost loops first**
- **Only upward code motion, to either:**
  - a “control-equivalent” block (non-speculative), or
  - a control-equivalent block of a dominating predecessor (speculative, 1 branch)
- **No creation of copies**

# Program Representation



- **Recall: A region in a control flow graph is:**
  - a set of **basic blocks** and all the **edges** connecting these blocks (expect possibly back edges into the header)
  - such that control from outside the region **must enter through the header**
- **A procedure is represented as a hierarchy of loop regions**
  - The entire control flow graph is a region
  - Each natural loop (single entry with back edge to it) in the flow graph is a region
  - Natural loops are hierarchically nested
- **Schedule regions from inner to outer**
  - treat inner loop as a black box unit: can **schedule around it but not into it**
  - **ignore all the loop back edges** → get an acyclic graph

## Useful Definitions

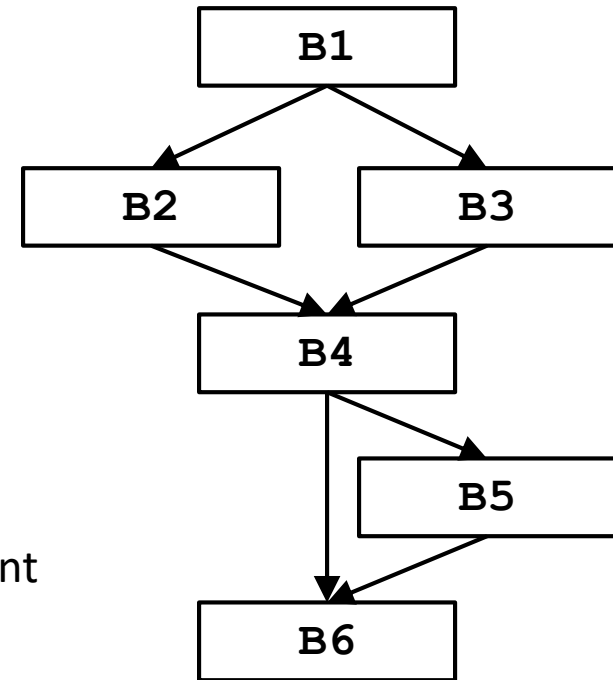
- Blocks B and B' are **control equivalent** if
  - B is executed if and only if B' is executed
  - E.g., which sets of blocks are control equivalent?

{B1,B4,B6}, {B1}, {B2},...,{B6}

Note: Two ops (instructions) are control equivalent iff their basic blocks are control equivalent (could be from same basic block)

- **NonSpeculative(B)** = all blocks that are control equivalent to B and dominated by B
- **Speculative(B)** = all blocks B' not control equivalent to B such that
  - B' is a successor of at least one block B'' that is control equivalent to B, and
  - B' is dominated by B''

Move up to a control-equivalent block or a control-equivalent block of a dominating predecessor



NonSpeculative(B1)? {B1,B4,B6}

NonSpeculative(B2)? {B2}

Speculative(B1) ? {B2,B3,B5}

Speculative(B2) ? {}

# Basic Algorithm

Compute **data dependences**;

For each **region R** in the hierarchy of loop regions **from inner to outer** {

For each **basic block B** of R in **prioritized topological order** {

**CandInsts** = ready instructions in **NonSpeculative(B)  $\cup$  Speculative(B)**;

For (**t = 1, 2, ... until all instructions from B are scheduled**) { // schedule time slots in order

For (**n in CandInst in priority order**) { // may or may not be from B

if (**ok to move n to B && n has no resource conflicts at time t**) {

**S(n) = < B, t >**; // instruction n is mapped to basic block B and time slot t

Update resource commitments;

Update data dependences;

}

}

Update **CandInsts**; // scheduled insts will often make new insts ready

}

}

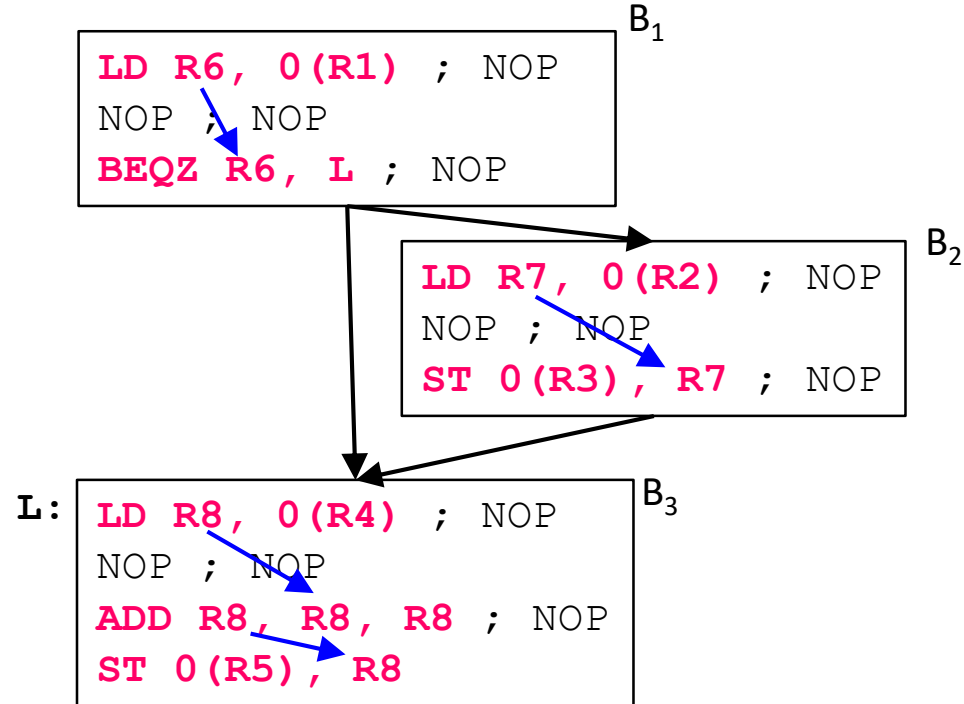
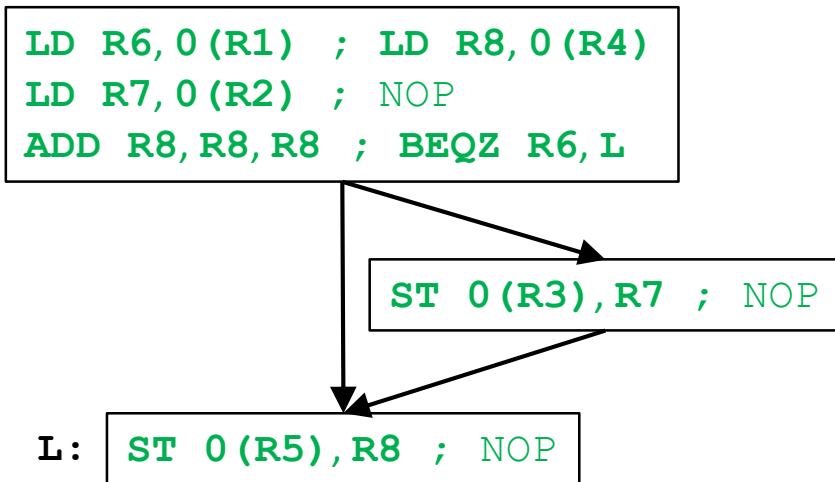
}

**Priority functions:** Non-speculative before speculative, and otherwise use same priority as in list scheduling

**Ok to move:** Don't speculatively move a store instruction, don't move a procedure call, etc

# Basic Algorithm Example

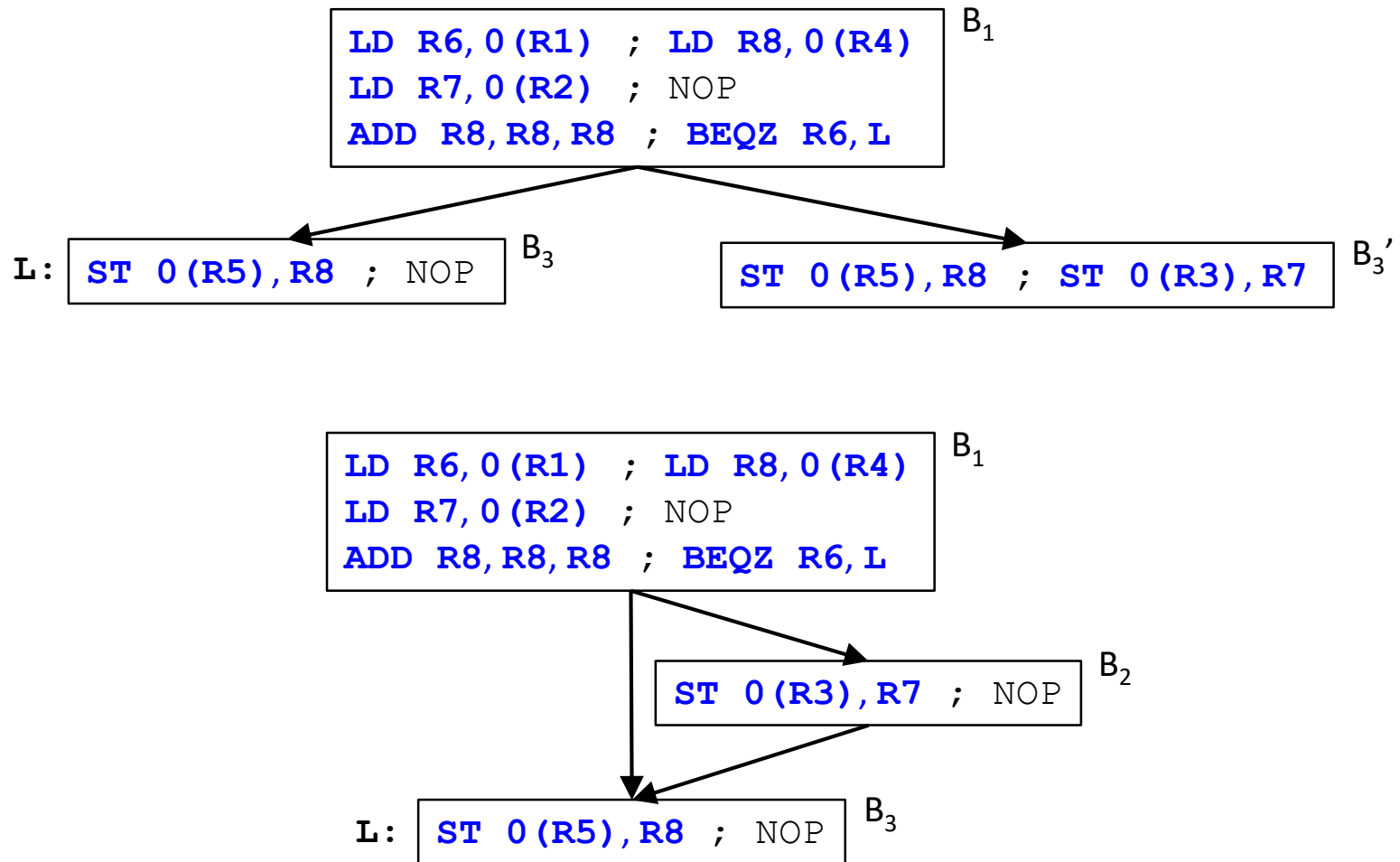
- Each clock: 2 operations of any kind
- LD takes 2 cycles, fully pipelined
- Priority order of blocks:  $B_1, B_2, B_3$
- Data dependences? **blue arcs at right**
- Control equivalent Blocks?  $\{B_1, B_3\}, \{B_2\}$
- NonSpeculative( $B_1$ )?  $\{B_1, B_3\}$
- Speculative( $B_1$ )?  $\{B_2\}$
- CandInsts?  $\{LD\ R6; LD\ R8; LD\ R7\}$



- t=2?  $\{ADD\ R8; BEQZ\ R6; LD\ R7\}$
- t=3?  $\{ADD\ R8; BEQZ\ R6; ST\ R7\}$
- NonSpeculative( $B_2$ )?  $\{B_2\}$
- Speculative( $B_2$ )?  $\{\}$
- CandInsts for  $B_2$ ?  $\{ST\ R7\}$
- CandInsts for  $B_3$ ?  $\{ST\ R8\}$

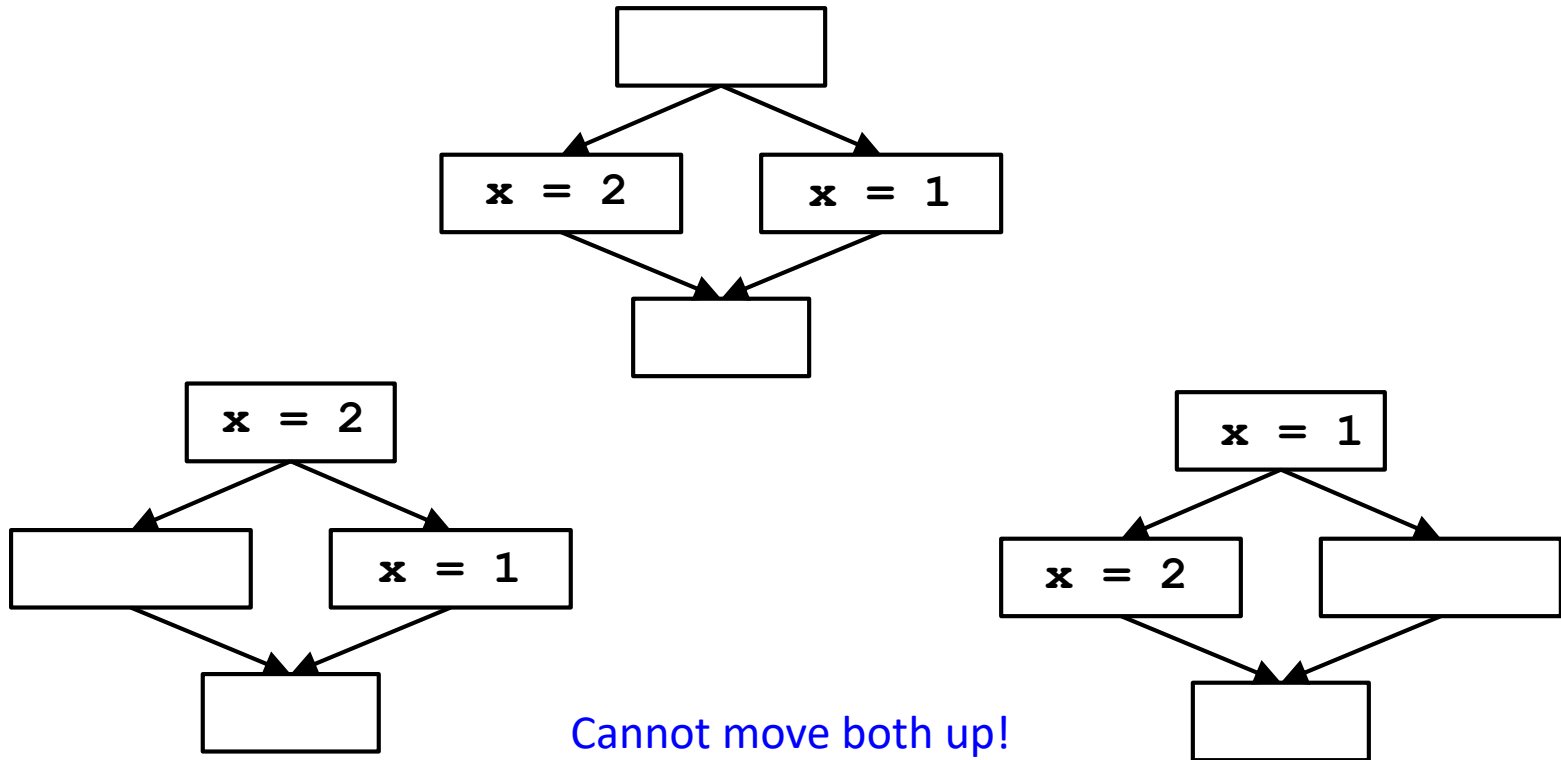


## Comparison to Earlier Global Schedule



Basic Algorithm's schedule requires one more cycle when branch not taken

## Updating Data Dependence after Code Motion



If a variable is live at a program point, then we cannot move a speculative definition to the variable above that program point

## Extension

- In region-based scheduling, loop iteration boundary limits code motion: operations from one iteration cannot overlap with those from another
- Prepass before scheduling: **loop unrolling**
- Especially important to move operation up loop back edges

```
for (i = 0; i < N; i++) {  
    S(i);  
}
```

Original Loop

```
for (i = 0; i+4 < N; i+=4) {  
    S(i);  
    S(i+1);  
    S(i+2);  
    S(i+3);  
}  
for ( ; i < N; i++) {  
    S(i);  
}
```

Unrolled Loop

## Today's Class: Global Scheduling

- I. Legal code motions
- II. Basic Algorithm

## Monday's Class

- Software Pipelining & Prefetching
  - ALSU 10.5, ALSU 11.11.4