

Lecture 11

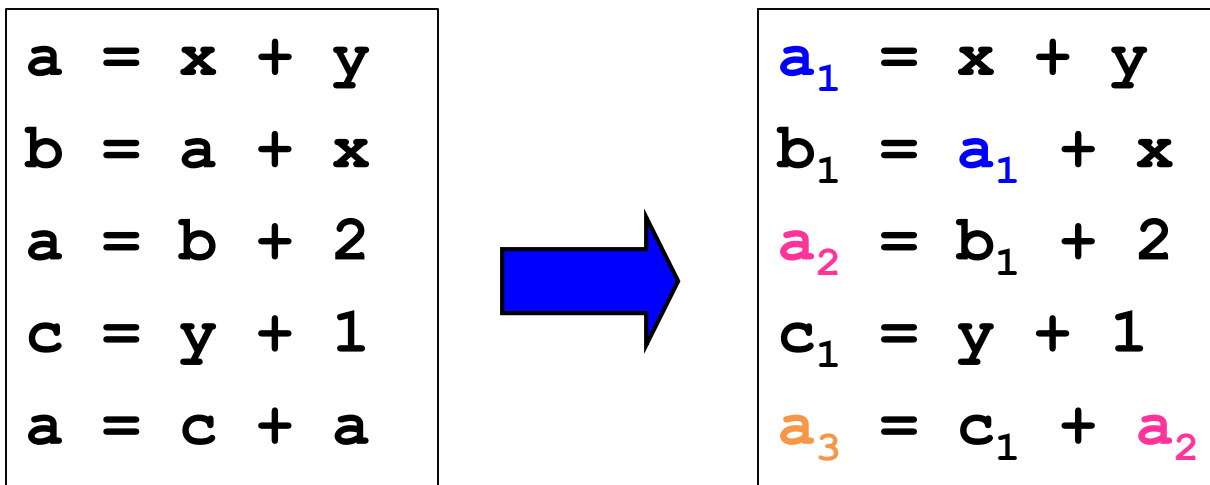
Static Single Assignment (SSA)

- I. Review: Intro to SSA
- II. When/Where to Insert Φ
- III. Example
- IV. Constant Propagation with SSA

ALSU 6.2.4

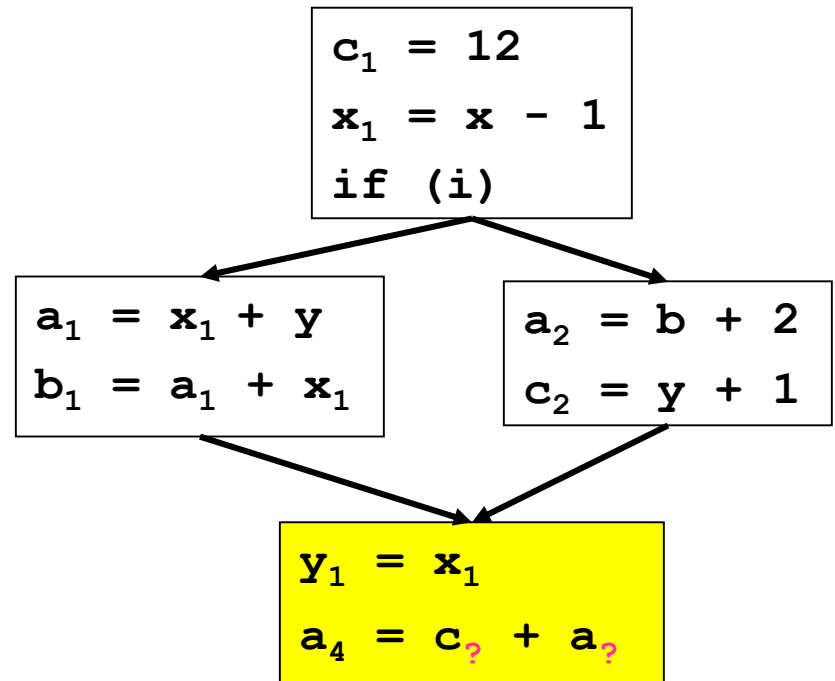
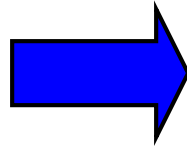
I. Review: Static Single Assignment (SSA)

- **Static single assignment** is an IR where **every variable is assigned a value at most once** in the program text
- Easy for a basic block (reminiscent of Value Numbering):
 - Visit each instruction in program order:
 - LHS: **assign** to a **fresh version** of the variable
 - RHS: **use** the **most recent version** of each variable



Review: What about Joins in the CFG?

```
c = 12
x = x - 1
if (i) {
  a = x + y
  b = a + x
} else {
  a = b + 2
  c = y + 1
}
y = x
a = c + a
```

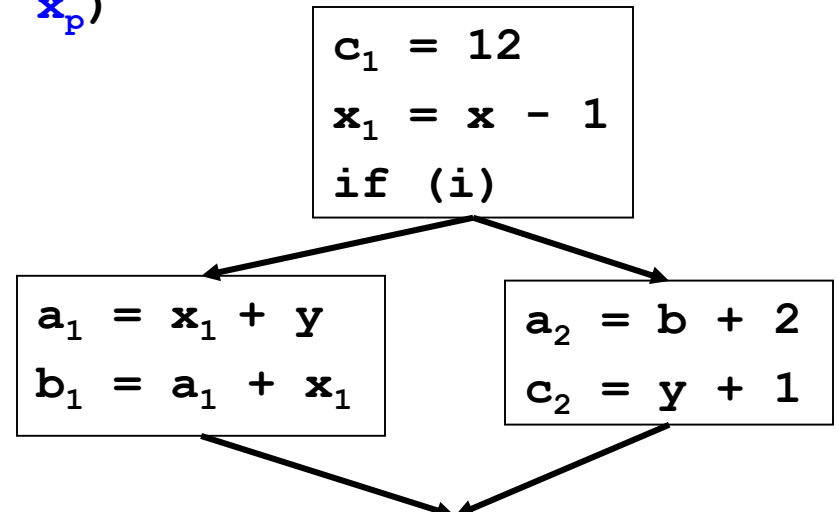


→ Use a notational convention (fiction): a Φ function

Review: The Φ function

- Φ merges multiple definitions along multiple control paths into a single definition.
- At a basic block with p predecessors, there are p arguments to the Φ function.

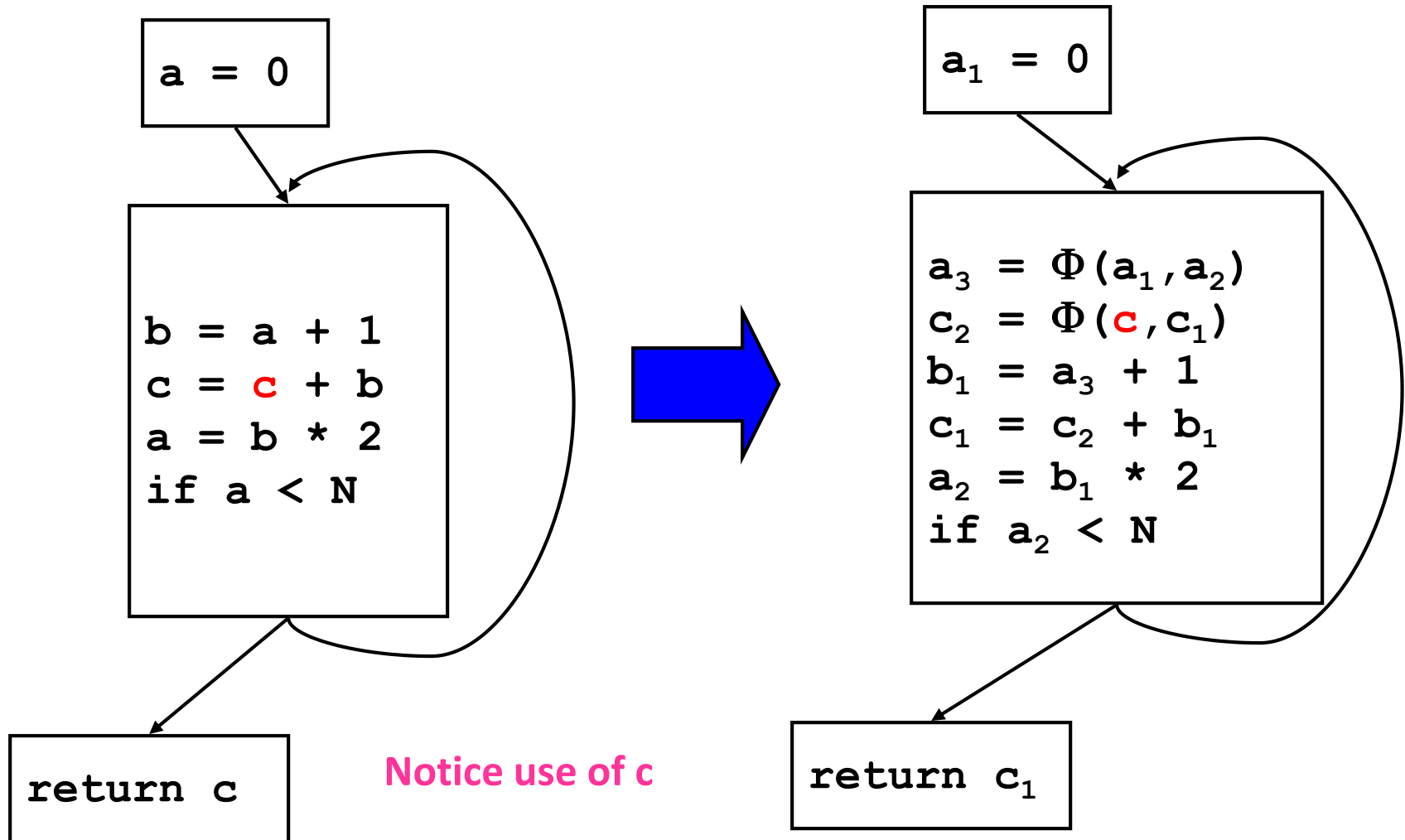
$$x_{\text{new}} = \Phi(x_1, x_2, x_3, \dots, x_p)$$



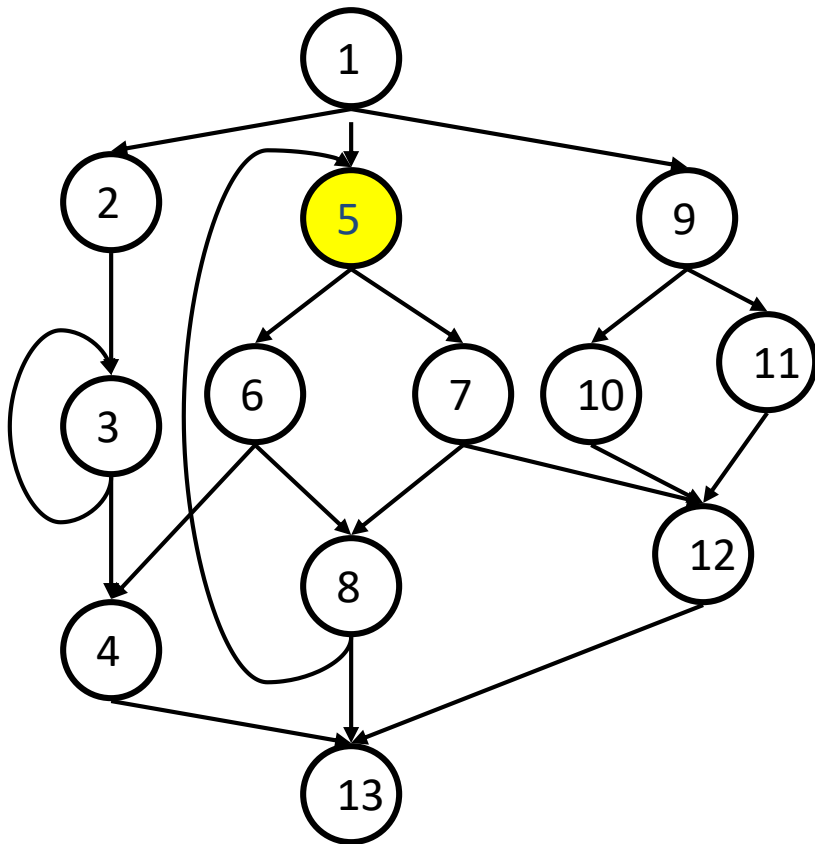
- Minimal SSA:** At each join point, insert Φ functions for **all live variables** with **multiple outstanding defs**

$a_3 = \Phi(a_1, a_2)$
 ~~$b_2 = \Phi(b_1, b)$~~ ← keep iff **b** is live
 $c_3 = \Phi(c_1, c_2)$
 ~~$x_2 = \Phi(x_1, x_1)$~~
 ~~$y_1 = x_2$~~ $y_1 = x_1$
 $a_4 = c_3 + a_3$

Another Example



II. When/Where to Insert Φ ?

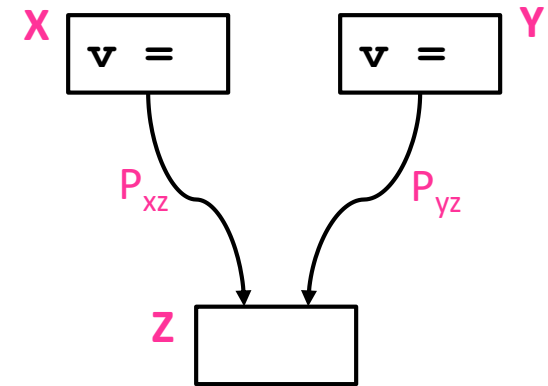


If there is a def of **a** in block 5, which nodes need a $\Phi()$?

Control Flow Graph (CFG)

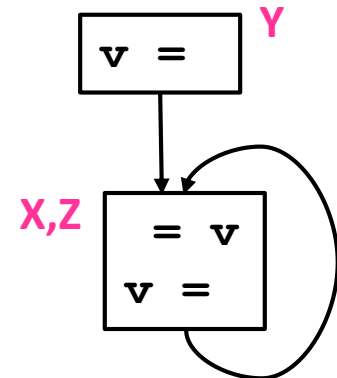
When/Where to insert Φ ?

- We insert a Φ function for variable v in block Z iff:
 - v was defined more than once before
 - (i.e., v defined in X and Y AND $X \neq Y$)
 - There exists nonempty paths P_{xz} from X to Z and P_{yz} from Y to Z s.t. Z is the first node common to the two paths
 - Nonempty = at least one edge
 - Note: one of X or Y can be Z



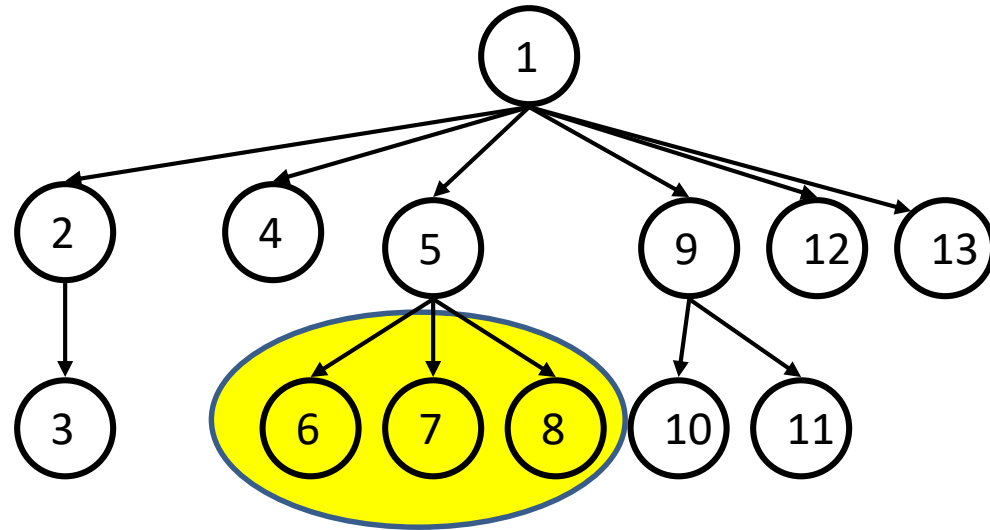
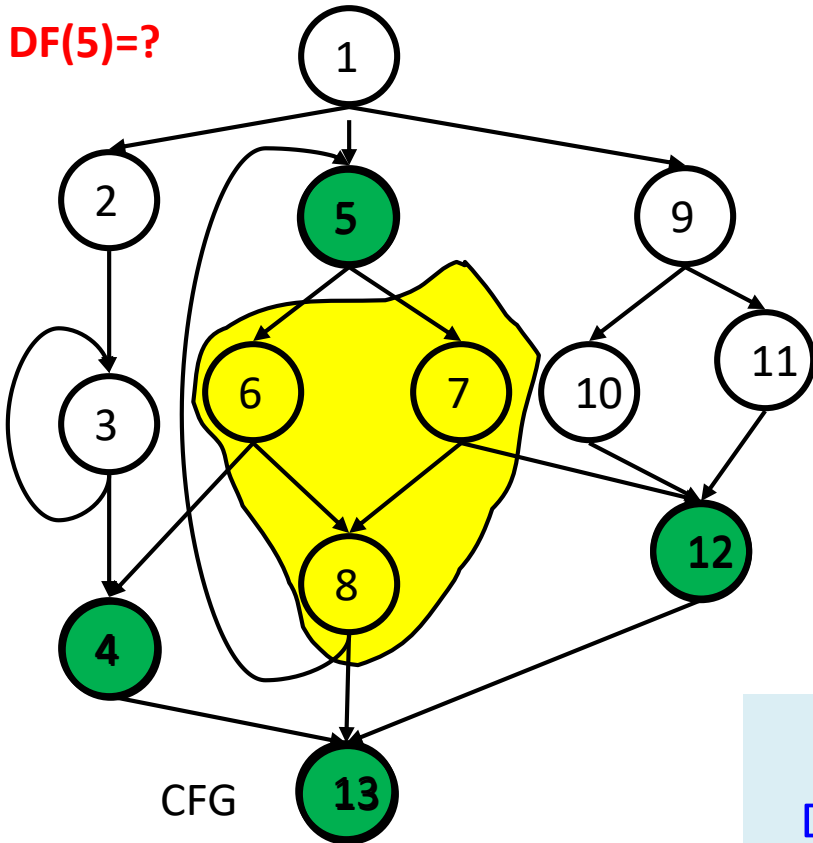
Path Convergence

- **Entry block** contains an implicit def of all vars
- Note: $v = \Phi(\dots)$ is a def of v



Dominance Frontier

DF(5)=?



Dominance Tree

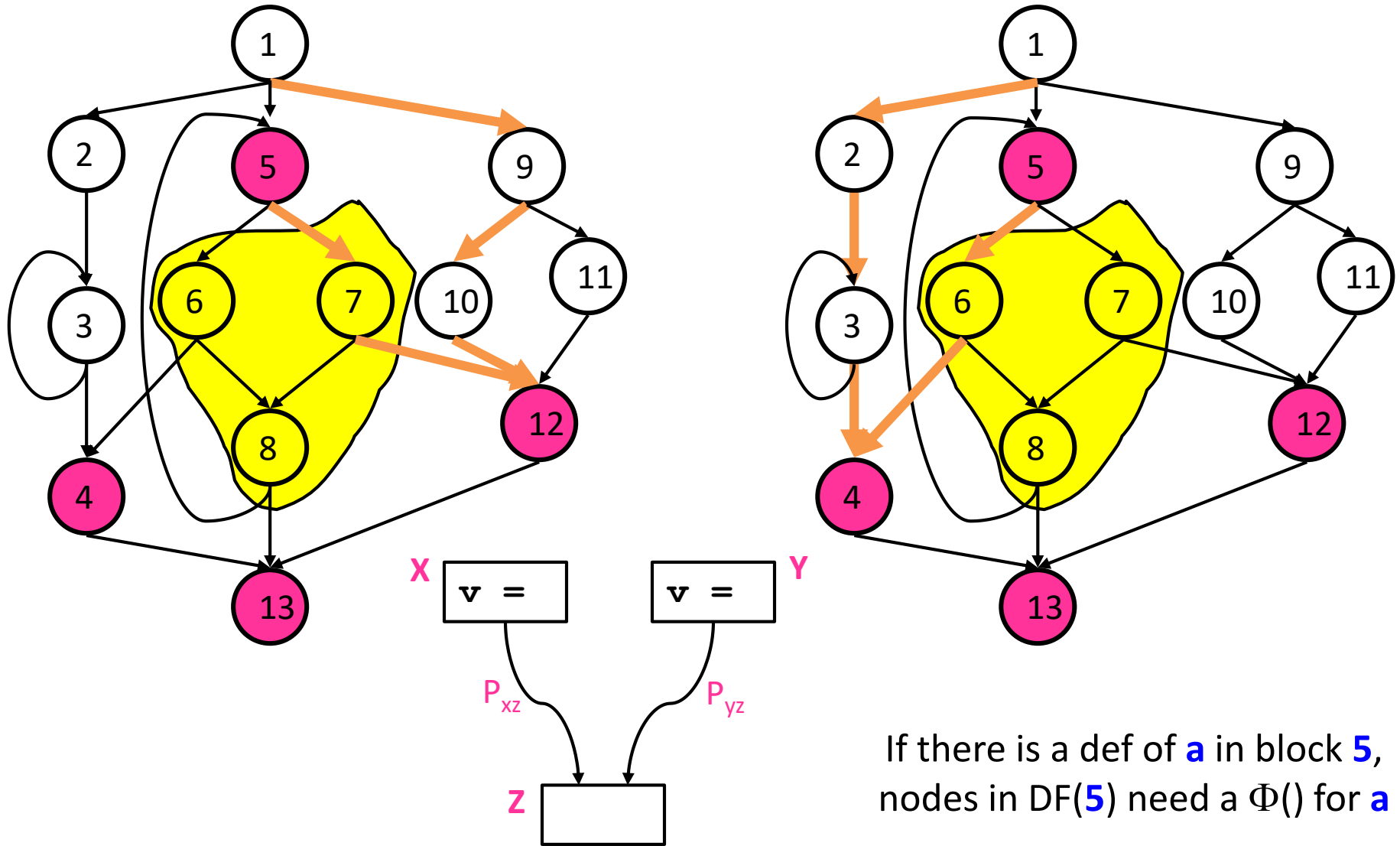
$x \text{ sdom } w$ iff x is a proper ancestor of w

The **Dominance Frontier** of a node x
 $DF(x) = \{ w \mid x \text{ dom } \text{pred}(w) \text{ AND } \neg(x \text{ sdom } w) \}$

x **strictly dominates** w ($x \text{ sdom } w$) iff impossible to reach w without passing through x first

x **dominates** w ($x \text{ dom } w$) iff $x \text{ sdom } w$ OR $x = w$

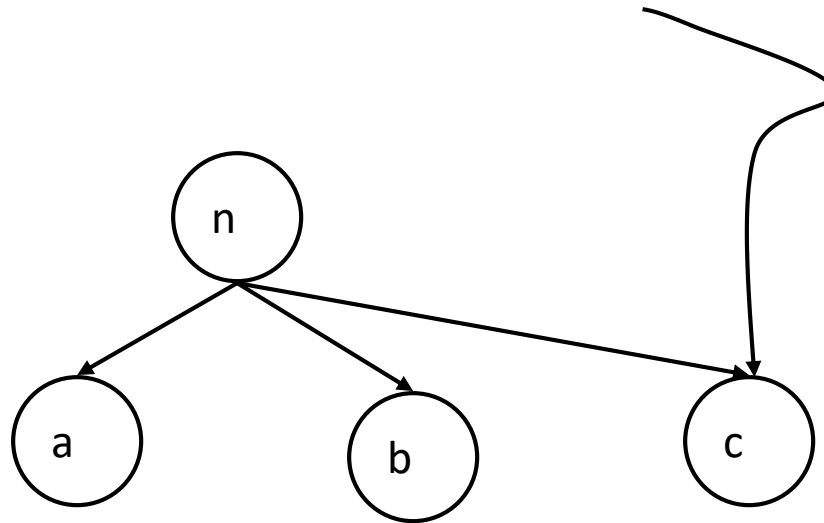
Dominance Frontier (DF) and Path Convergence



If there is a def of **a** in block **5**, nodes in DF(**5**) need a $\Phi()$ for **a**

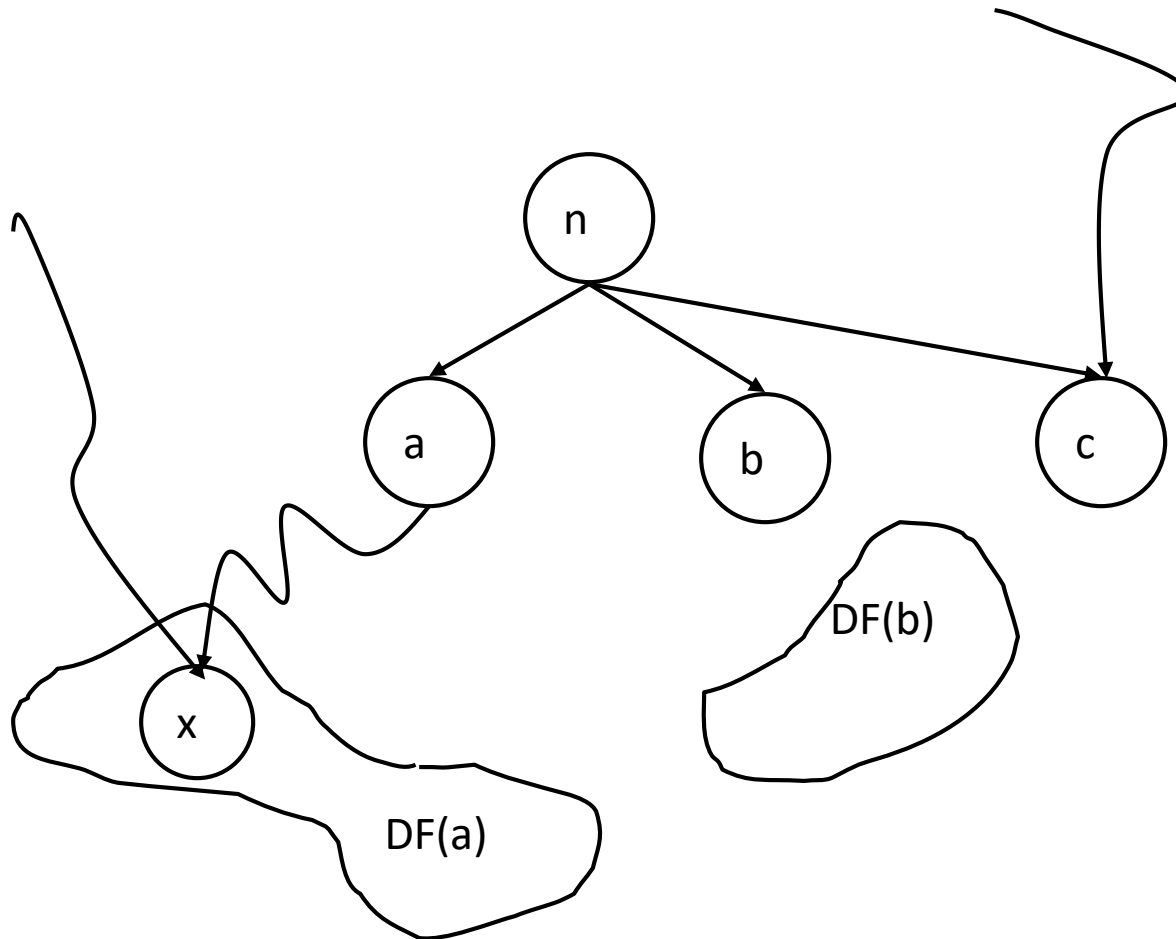
Computing DF(n)

$$DF(x) = \{ w \mid x \text{ dom pred}(w) \text{ AND } !(x \text{ sdom } w) \}$$



n dom n
n dom a
n dom b
!(n dom c)

Computing DF(n)



$n \text{ dom } n$
 $n \text{ dom } a$
 $n \text{ dom } b$
 $!(n \text{ dom } c)$

Computing the Dominance Frontier

$$DF(n) = \{ w \mid n \text{ dom pred}(w) \text{ AND } !(n \text{ sdom } w) \}$$

compute-DF(n)

$S = \{ \}$

foreach node c in succ[n]

if !(n sdom c)

$S = S \cup \{ c \}$ // e.g., node c on previous slide

foreach child a of n in the Dominance Tree

compute-DF(a)

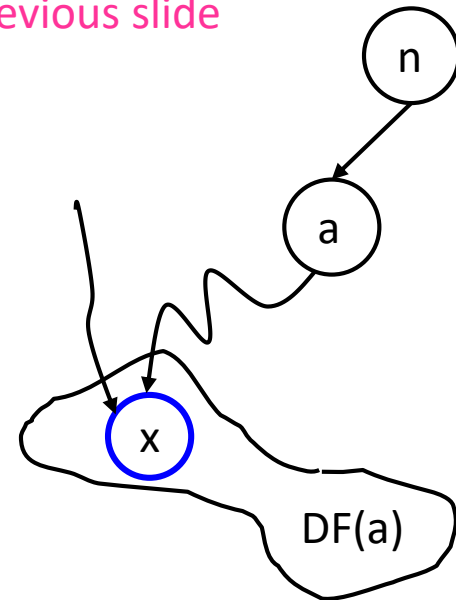
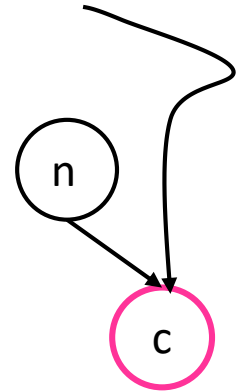
foreach x in DF[a]

if !(n dom x)

$S = S \cup \{ x \}$

// e.g., node x on previous slide

$DF[n] = S$



Using Dominance Frontier to Compute SSA: Overview

1. Place all $\Phi()$
2. Rename all variables

Using Dominance Frontier to Place $\Phi()$

- Gather all the defsites of every variable
- Then, for every variable
 - foreach defsite
 - foreach node in DominanceFrontier(defsite)
 - if we haven't put $\Phi()$ in node, then put one in
 - if this node didn't define the variable before, then add this node to the defsites (because Φ counts as def)
- This essentially computes the Iterated Dominance Frontier on the fly, inserting the minimal number of $\Phi()$ necessary

Using Dominance Frontier to Place $\Phi()$: Algorithm

```
 $\forall n, v$ : initialize orig[n], defsites[v], PHI[v] to empty set
foreach node n {
  foreach variable v defined in n {
    orig[n]  $\cup = \{v\}$  // variables defined in basic block n
    defsites[v]  $\cup = \{n\}$  // basic blocks that define variable v
  }
}
foreach variable v {
  W = defsites[v] // work list of basic blocks
  while W not empty {
    n = remove node from W
    foreach y in DF[n]
      if  $y \notin \text{PHI}[v]$  {
        insert " $v \leftarrow \Phi(v, v, \dots)$ " at top of y
         $\text{PHI}[v] = \text{PHI}[v] \cup \{y\}$  // BBs containing a  $\Phi$  for v
        if  $v \notin \text{orig}[y]$ :  $W = W \cup \{y\}$  // add BB to work list
      }
  }
}
}
```

Renaming Variables

- Algorithm:
 - Walk the Dominance Tree, renaming variables as you go
 - Replace uses with more recent renamed def
- For straight-line code this is easy
- What if there are branches and joins?
 - use the **closest def such that the def is above the use in the Dominance Tree**

- Easy implementation:
 - Call **rename**(entry)

rename(B):

for each statement in B:

replace (non- Φ) use of v with top of stack(v)

replace def of v with v_{new} , push v_{new} onto stack(v)

for each successor S of B in CFG:

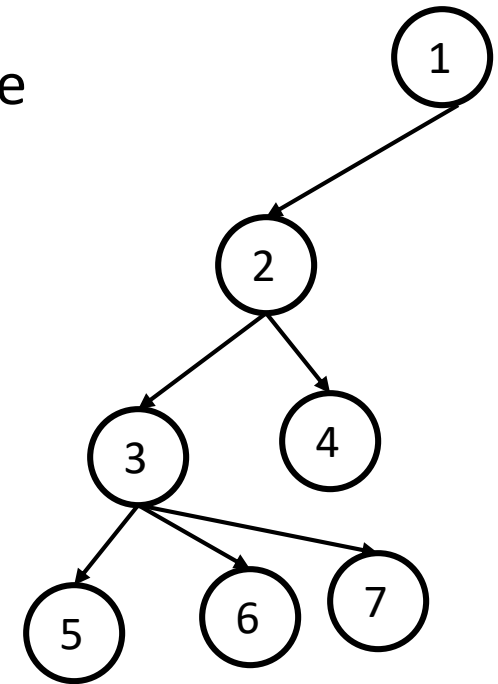
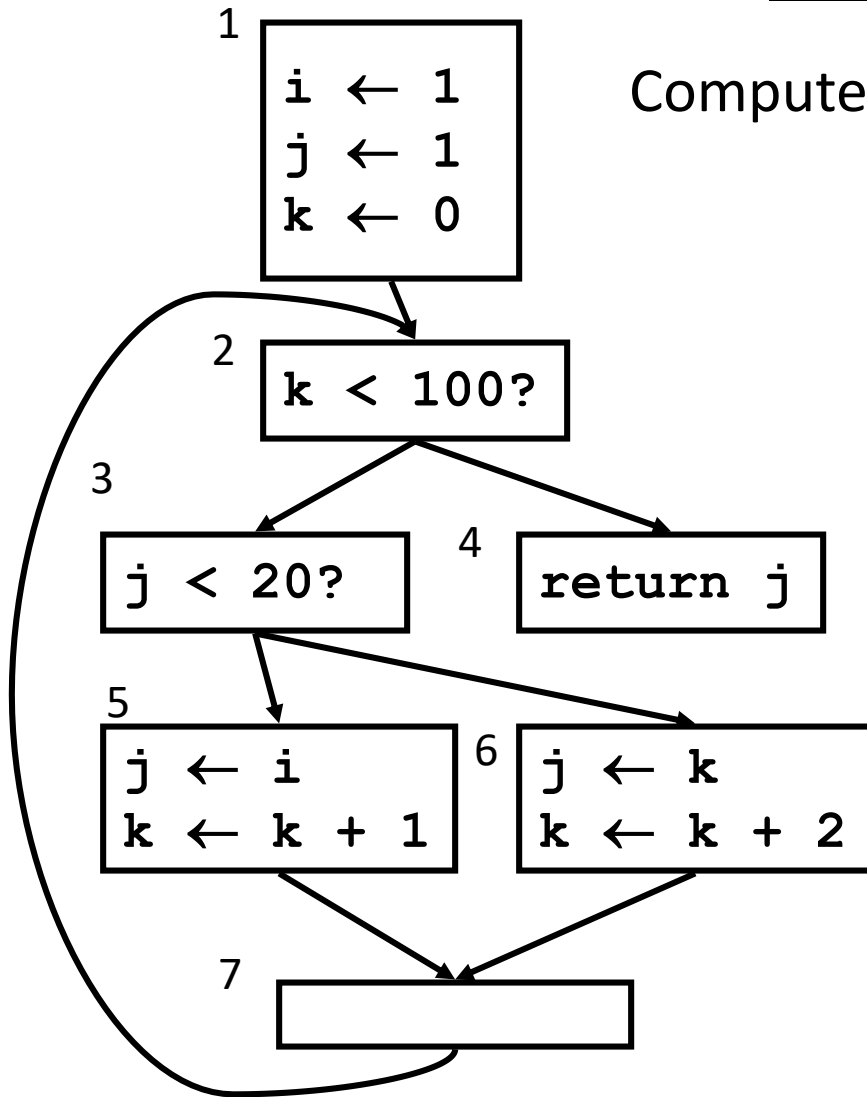
replace k 'th arg. of $\Phi(\mathbf{v}, \dots, \mathbf{v})$ with top of stack(v),
where B is k 'th predecessor of S

call **rename**(C) on all children C of B in Dominance Tree

pop all defs in B from stacks

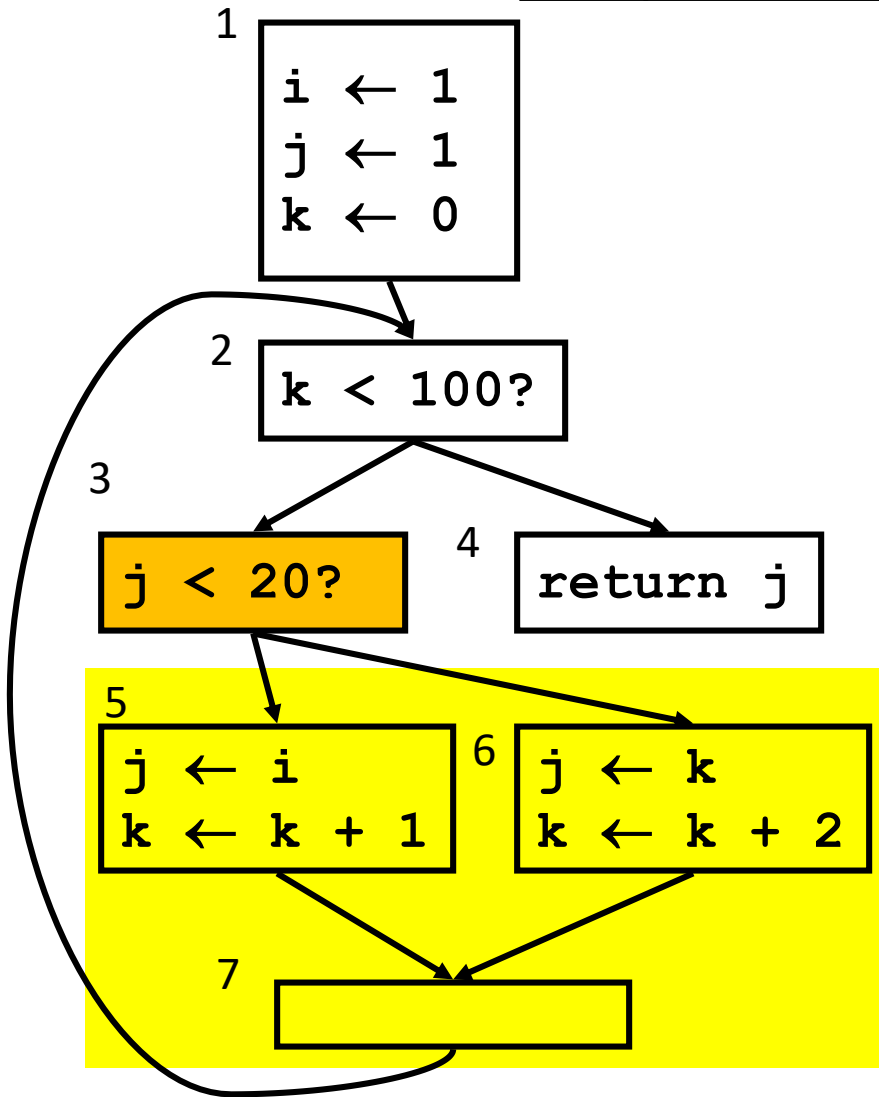
III. Example

Compute Dominance Tree



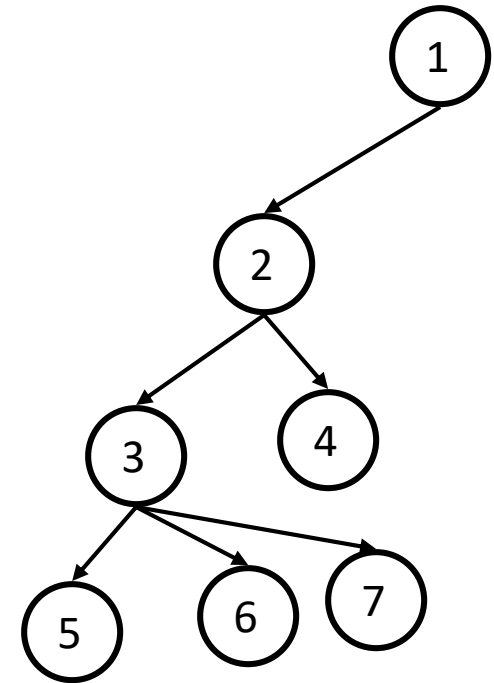
Dominance Tree

Compute Dominance Frontiers



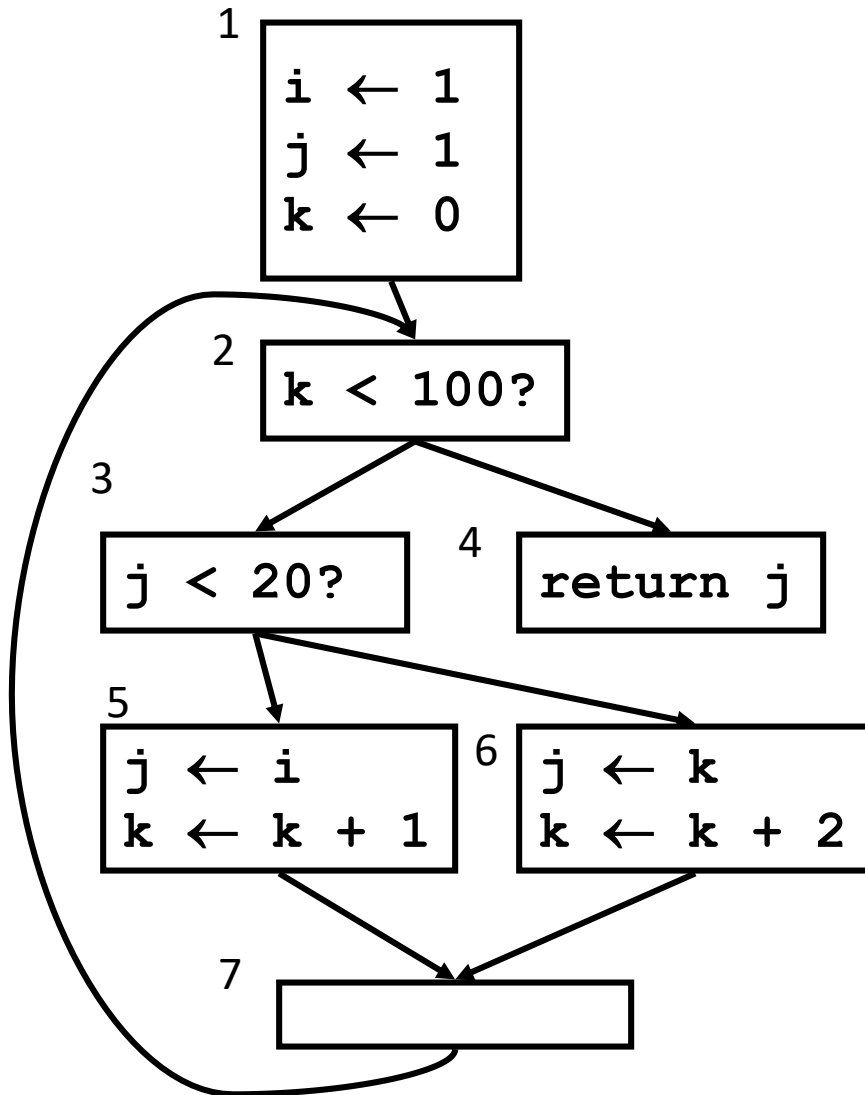
DFs

1	{}
2	{2}
3	?? {2}
4	{}
5	{7}
6	{7}
7	{2}



$$DF(x) = \{ w \mid x \text{ dom pred}(w) \text{ AND } !(x \text{ sdom } w) \}$$

Insert $\Phi()$



DFs

1	{}
2	{2}
3	{2}
4	{}
5	{7}
6	{7}
7	{2}

$orig[n]$ = variables defined in n

1	{i,j,k}
2	{}
3	{}
4	{}
5	{j,k}
6	{j,k}
7	{}

$defsites[v]$

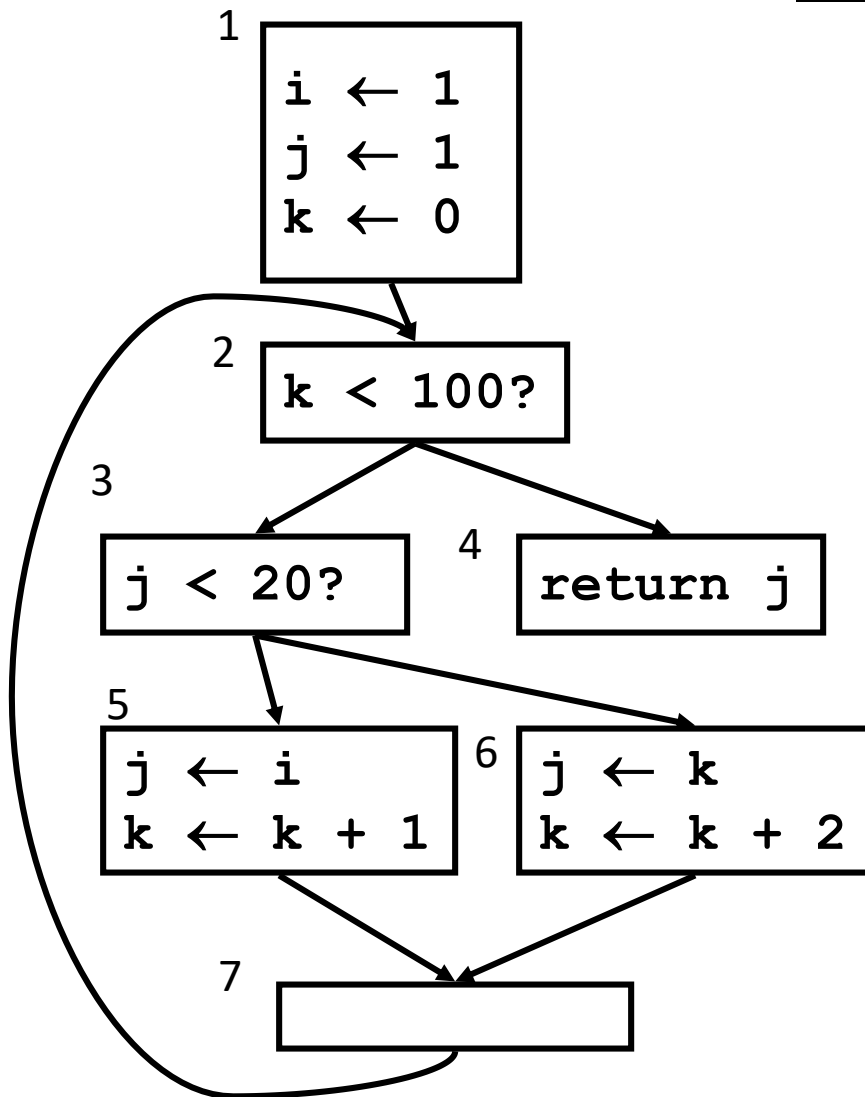
i	{1}
j	{1,5,6}
k	{1,5,6}

```

foreach variable v {
  W = defsites[v]
  while W not empty {
    n = remove node from W
    ...
  }
}
  
```

var i: $W=\{1\}$

Insert $\Phi()$



DFs

1	{}
2	{2}
3	{2}
4	{}
5	{7}
6	{7}
7	{2}

orig[n]

1	{i,j,k}
2	{}
3	{}
4	{}
5	{j,k}
6	{j,k}
7	{}

PHI[v]

j	{}
k	{}
defsites[v]	
i	{1}
j	{1,5,6}
k	{1,5,6}

```

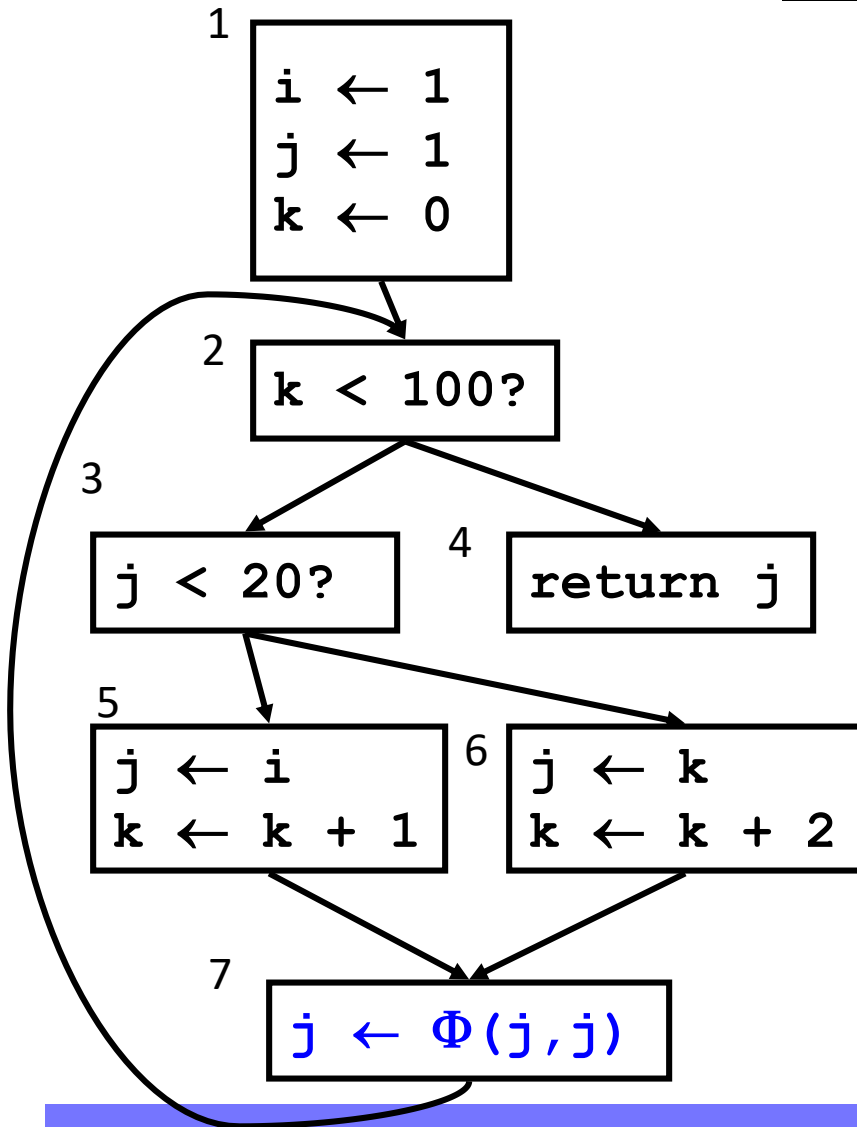
foreach y in DF[n]
  if y ∉ PHI[v] {
    insert "v ← Φ(v,v,...)" in y
    PHI[v] = PHI[v] ∪ {y}
    if v ∉ orig[y]: W = W ∪ {y}
  }
  
```

var i: W={1} ~~DF{1}~~

var j: W={1,5,6}

~~DF{1}~~ DF{5}

Insert $\Phi()$



DFs

1	{}
2	{2}
3	{2}
4	{}
5	{7}
6	{7}
7	{2}

orig[n]

1	{i,j,k}
2	{}
3	{}
4	{}
5	{j,k}
6	{j,k}
7	{}

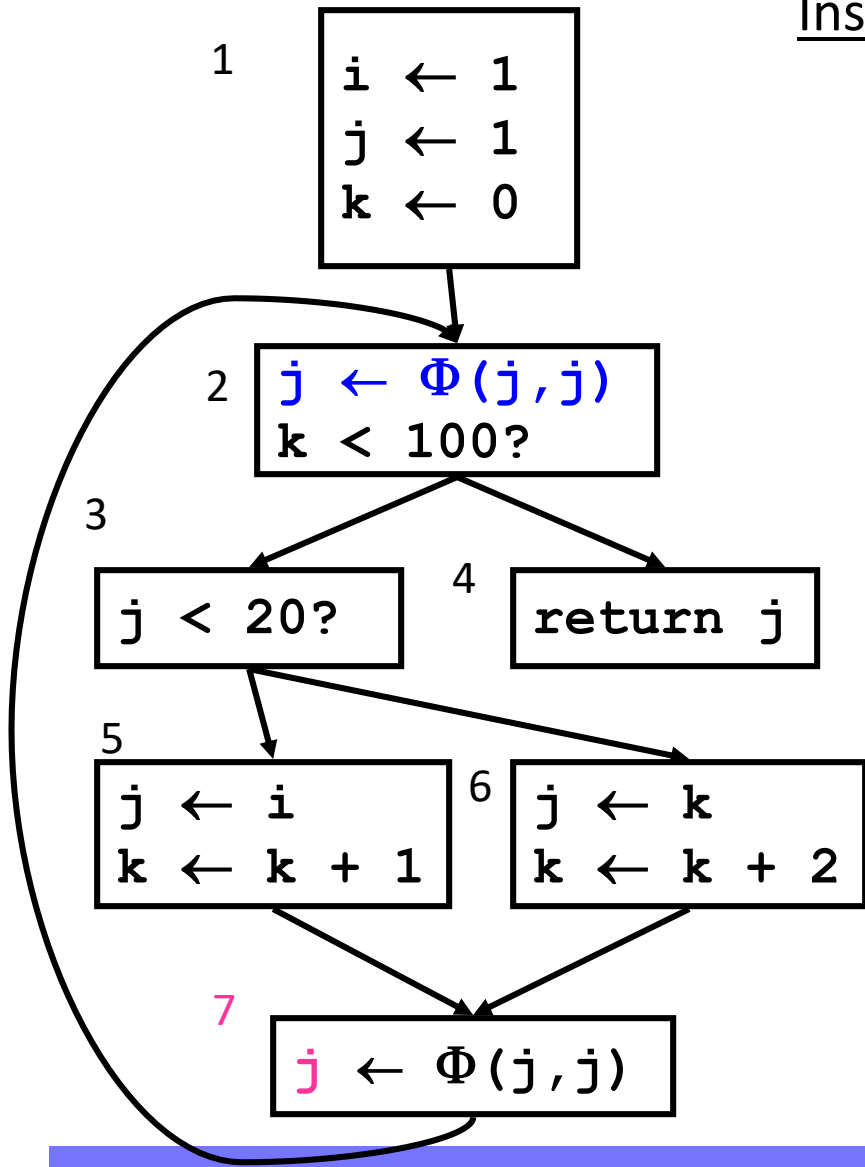
PHI[v]

j	{7}
k	{}
defsites[v]	
i	{1}
j	{1,5,6}
k	{1,5,6}

```

foreach y in DF[n]
  if y ∉ PHI[v] {
    insert "v ← Φ(v,v,...)" in y
    PHI[v] = PHI[v] ∪ {y}
    if v ∉ orig[y]: W = W ∪ {y}
  }
  
```

var j: W={5,6}
~~DF{1}~~ DF{5}



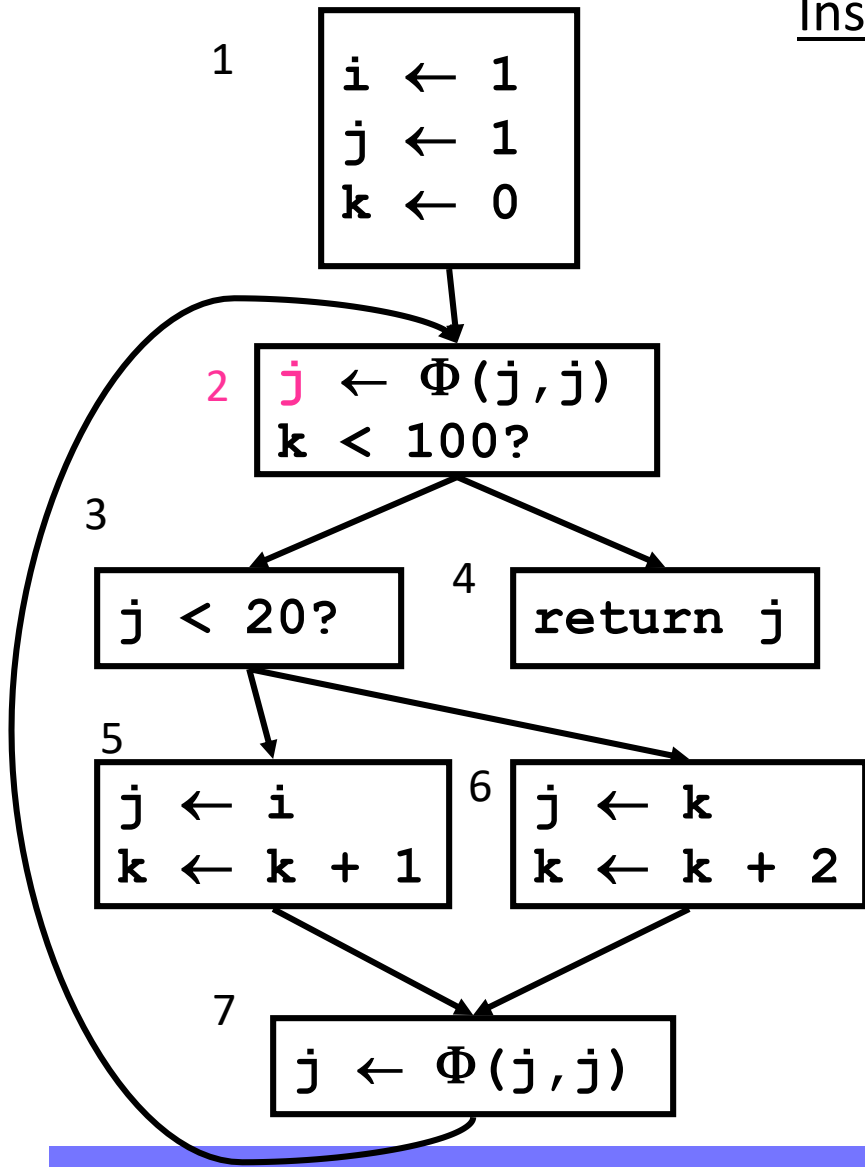
Insert $\Phi()$

DFs	orig[n]	PHI[v]	defsites[v]
1 {}	1 {i,j,k}	j {2,7}	
2 {2}	2 {}	k {}	
3 {2}	3 {}		
4 {}	4 {}		
5 {7}	5 {j,k}	i {1}	
6 {7}	6 {j,k}	j {1,5,6}	
7 {2}	7 {}	k {1,5,6}	

```

foreach y in DF[n]
  if y ∉ PHI[v] {
    insert "v ← Φ(v,v,...)" in y
    PHI[v] = PHI[v] ∪ {y}
    if v ∉ orig[y]: W = W ∪ {y}
  }
  
```

var j: W={7,6}
~~DF{1}~~ ~~DF{2}~~ DF{7}



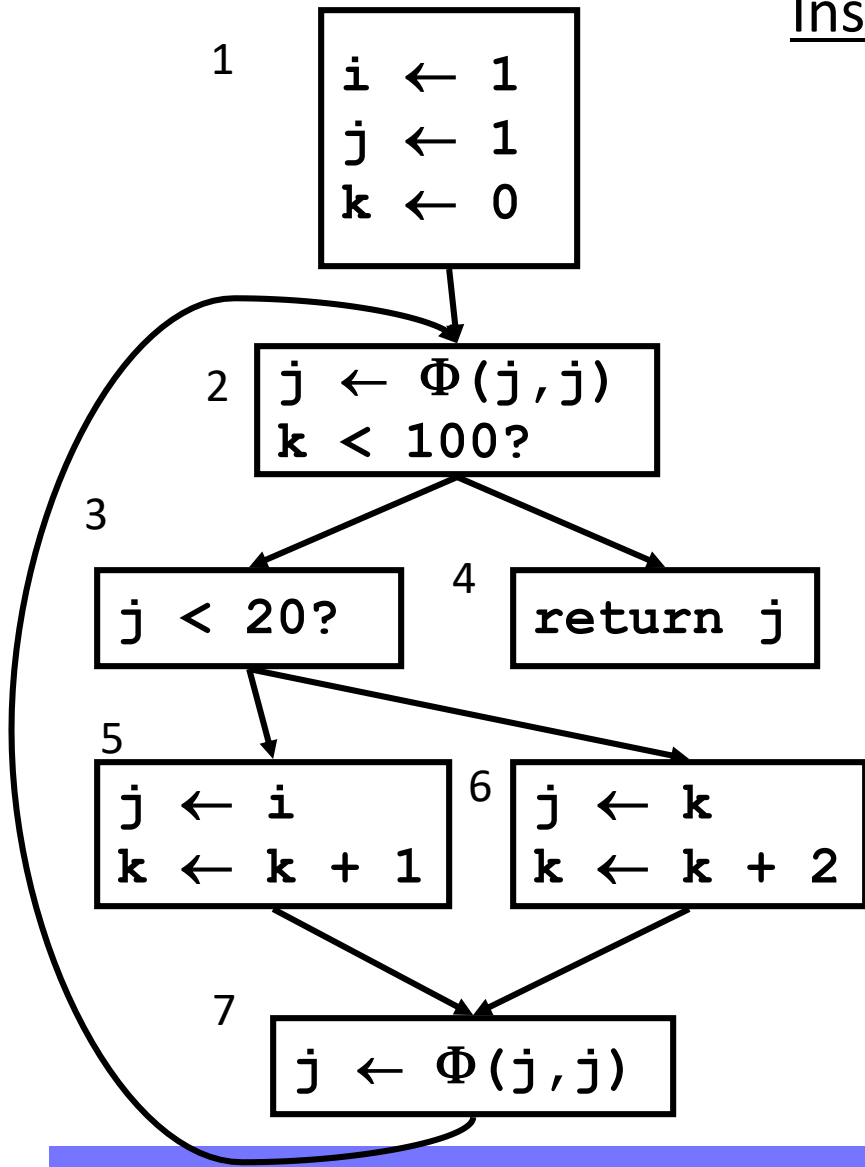
Insert $\Phi()$

DFs	orig[n]	PHI[v]	defsites[v]
1 {}	1 {i,j,k}	j {2,7}	
2 {2}	2 {}	k {}	
3 {2}	3 {}		
4 {}	4 {}		
5 {7}	5 {j,k}	i {1}	
6 {7}	6 {j,k}	j {1,5,6}	
7 {2}	7 {}	k {1,5,6}	

```

foreach y in DF[n]
  if y ∉ PHI[v] {
    insert "v ← Φ(v,v,...)" in y
    PHI[v] = PHI[v] ∪ {y}
    if v ∉ orig[y]: W = W ∪ {y}
  }
  
```

var j: W={2,6}
~~DF{1}~~ ~~DF{3}~~ ~~DF{7}~~ DF{2}



Insert $\Phi()$

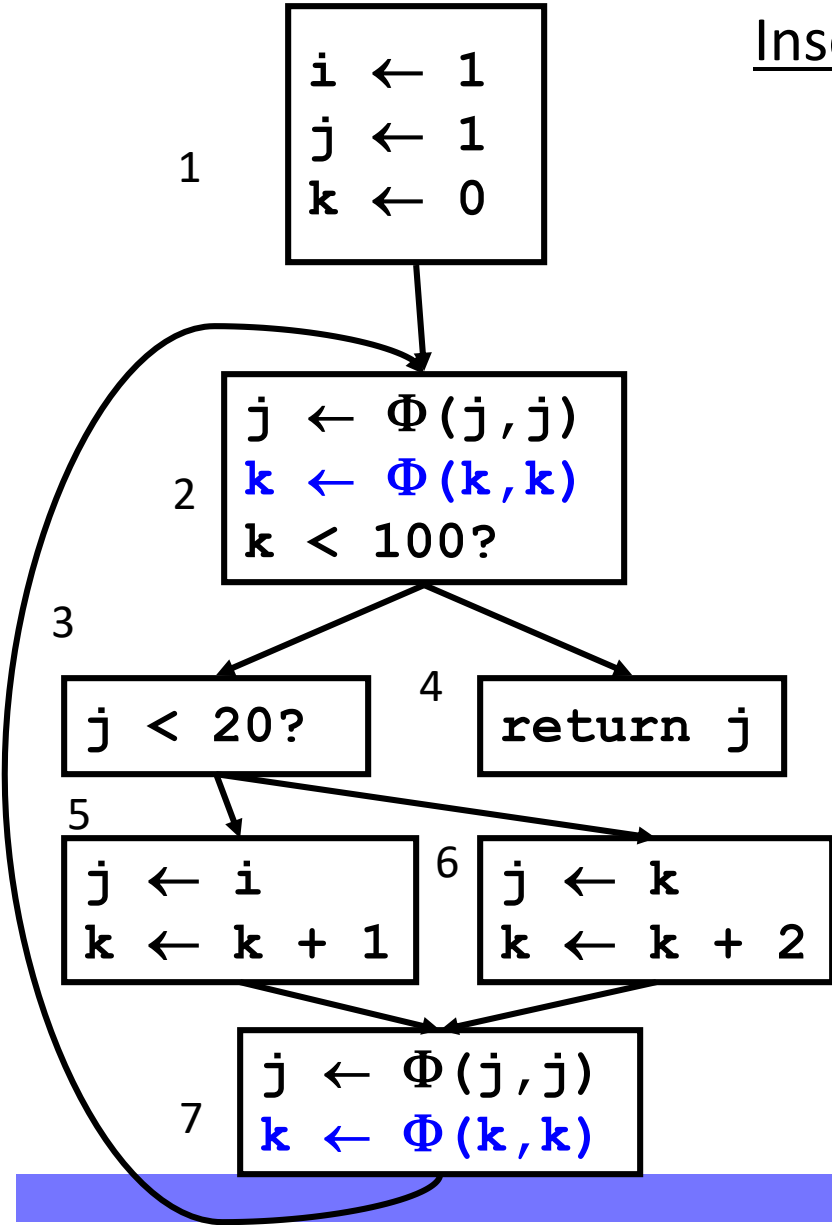
DFs	orig[n]	PHI[v]	defsites[v]
1 {}	1 {i,j,k}	j {2,7}	
2 {2}	2 {}	k {}	
3 {2}	3 {}		
4 {}	4 {}		
5 {7}	5 {j,k}	i {1}	
6 {7}	6 {j,k}	j {1,5,6}	
7 {2}	7 {}	k {1,5,6}	

```

foreach y in DF[n]
  if y ∉ PHI[v] {
    insert "v ← Φ(v,v,...)" in y
    PHI[v] = PHI[v] ∪ {y}
    if v ∉ orig[y]: W = W ∪ {y}
  }

```

var j: W={6} ~~D[5,6]~~
~~D[1]~~ ~~D[3]~~ ~~D[7]~~ ~~D[2]~~



Insert $\Phi()$

DFs	orig[n]	PHI[v]	defsites[v]
1 {}	1 {i,j,k}	j	{2,7}
2 {2}	2 {}	k	{2,7}
3 {2}	3 {}		
4 {}	4 {}		
5 {7}	5 {j,k}	i	{1}
6 {7}	6 {j,k}	j	{1,5,6}
7 {2}	7 {}	k	{1,5,6}

```

foreach y in DF[n]
  if y ∉ PHI[v] {
    insert "v ← Φ(v,v,...)" in y
    PHI[v] = PHI[v] ∪ {y}
    if v ∉ orig[y]: W = W ∪ {y}
  }
  
```

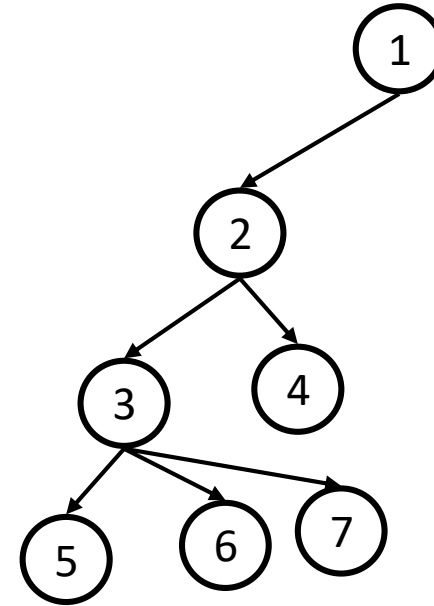
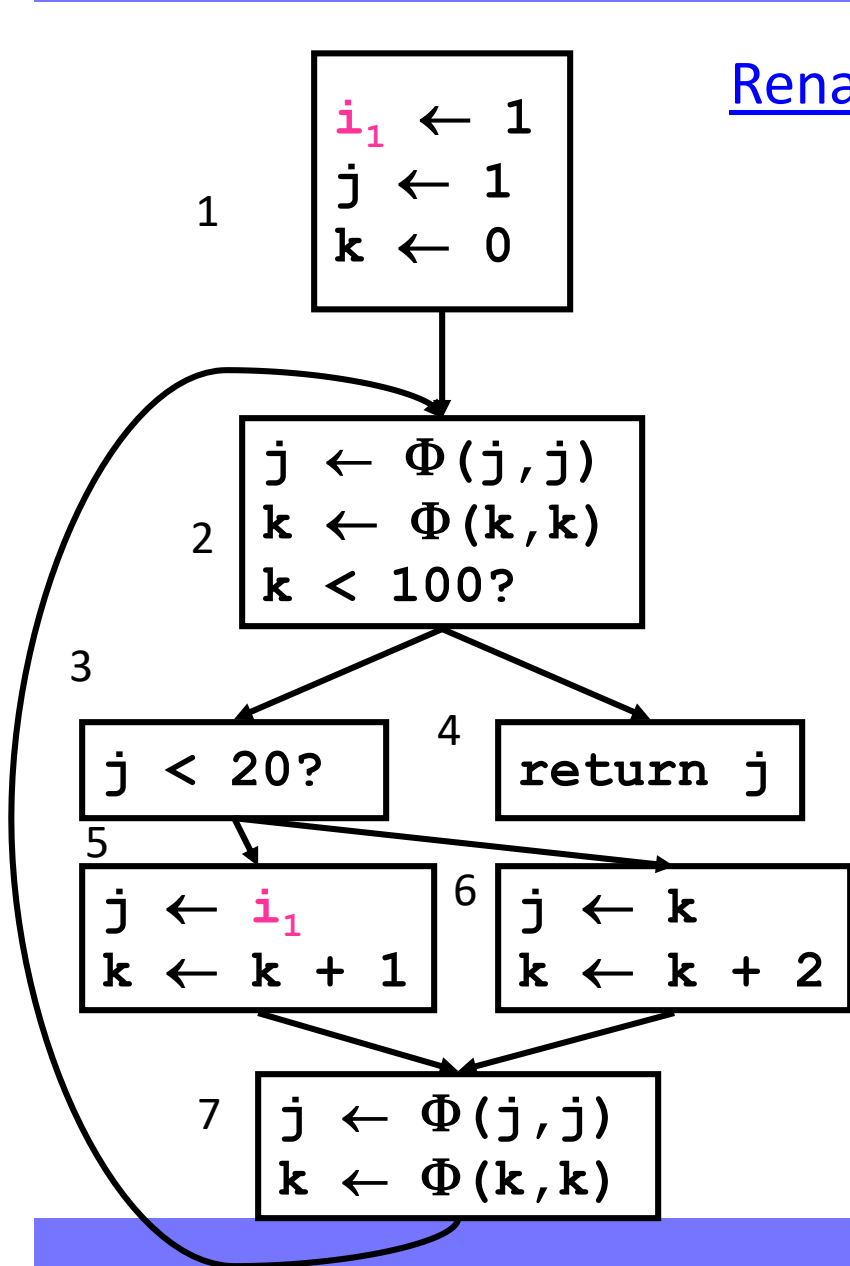
var k: W={1,5,6}

Same as var j: adds Φ to 7 and 2

Done inserting $\Phi()$ s...Time to rename vars



Rename Vars



i_1
stack(i)

rename(B):

for each statement in B:

replace (non- Φ) use of v with top of stack(v)

replace def of v with v_{new} ,

push v_{new} onto stack(v)

for each successor S of B in CFG:

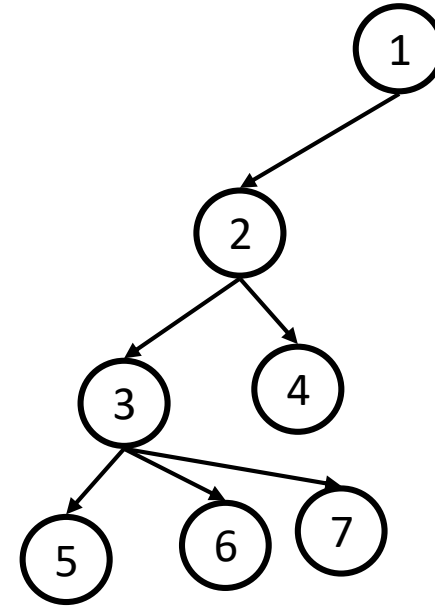
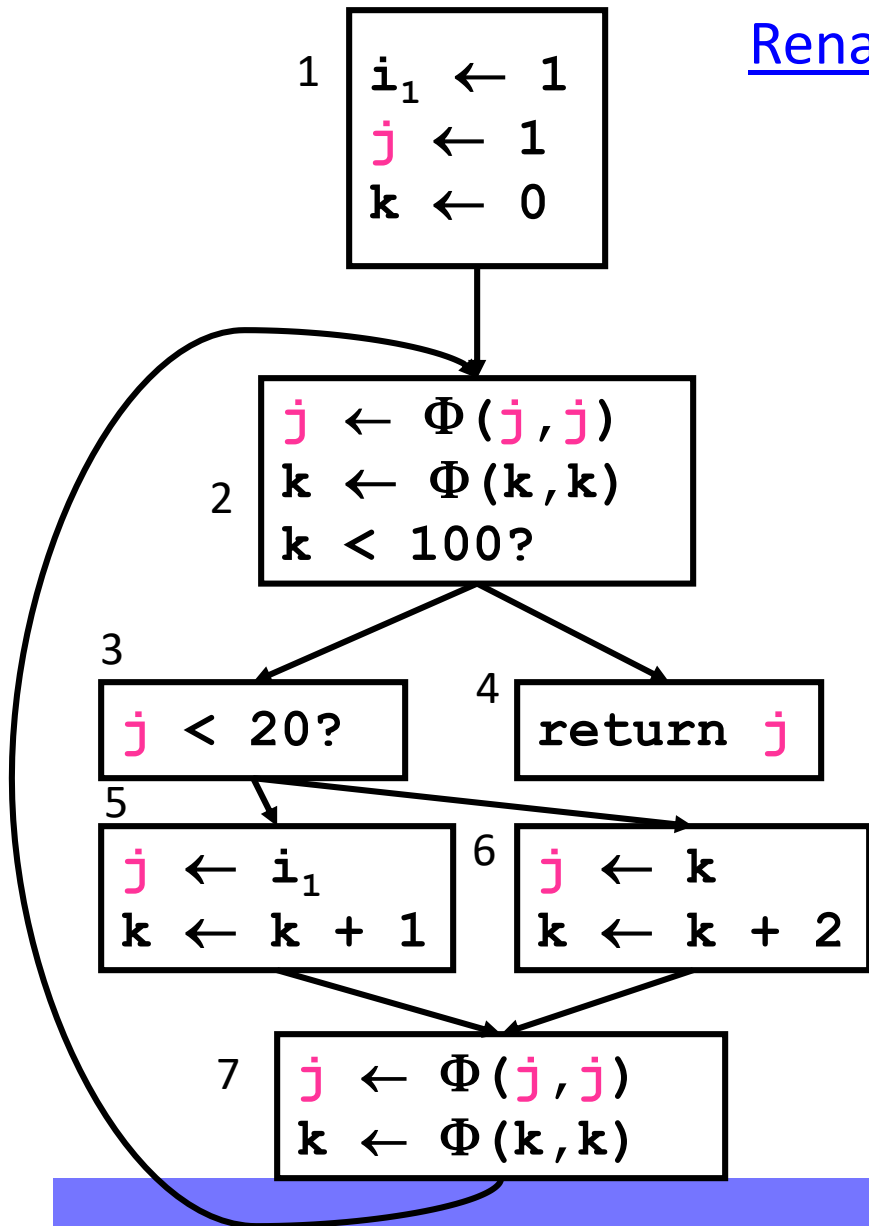
replace k 'th arg. of $\Phi(\mathbf{v}, \dots, \mathbf{v})$ with top of stack(v), where B is k 'th predecessor of S

call rename(C) on all children C of B

in Dominance Tree

pop all defs in B from stacks

Rename Vars



rename(B):

for each statement in B:

replace (non- Φ) use of v with top of stack(v)

replace def of v with v_{new} ,

push v_{new} onto stack(v)

for each successor S of B in CFG:

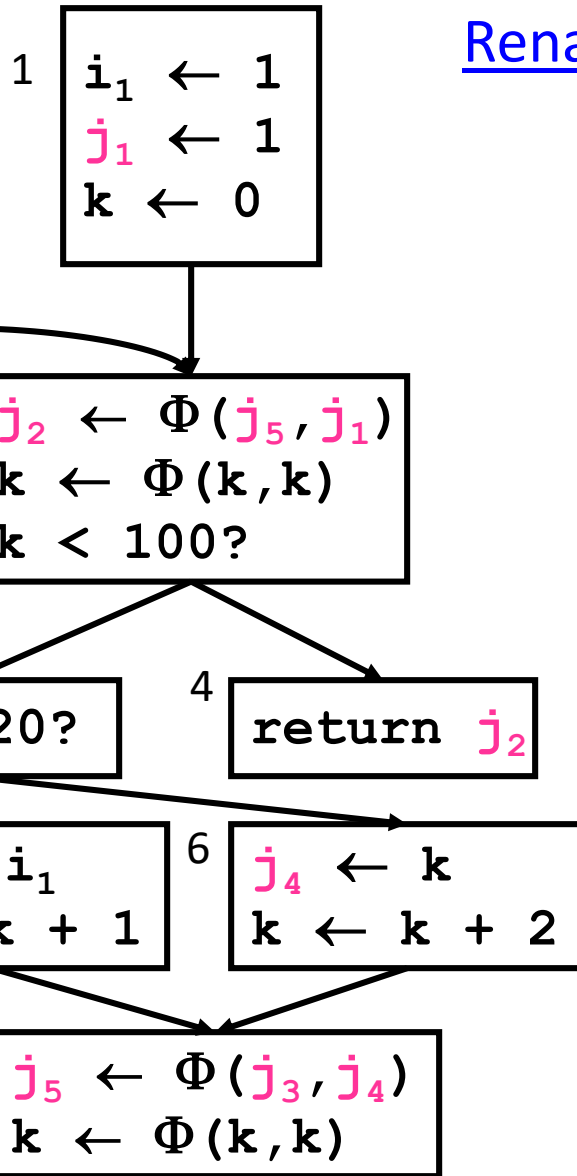
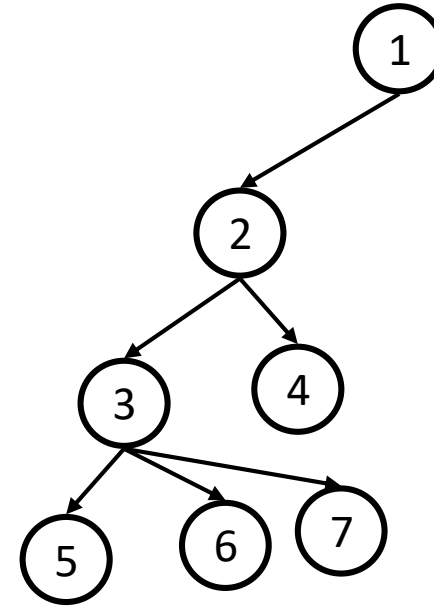
replace k 'th arg. of $\Phi(\mathbf{v}, \dots, \mathbf{v})$ with top of stack(v), where B is k 'th predecessor of S

call **rename(C)** on all children C of B

in Dominance Tree

pop all defs in B from stacks

Rename Vars



rename(B):

for each statement in B:

replace (non- Φ) use of v with top of stack(v)

replace def of v with v_{new} ,

push v_{new} onto stack(v)

for each successor S of B in CFG:

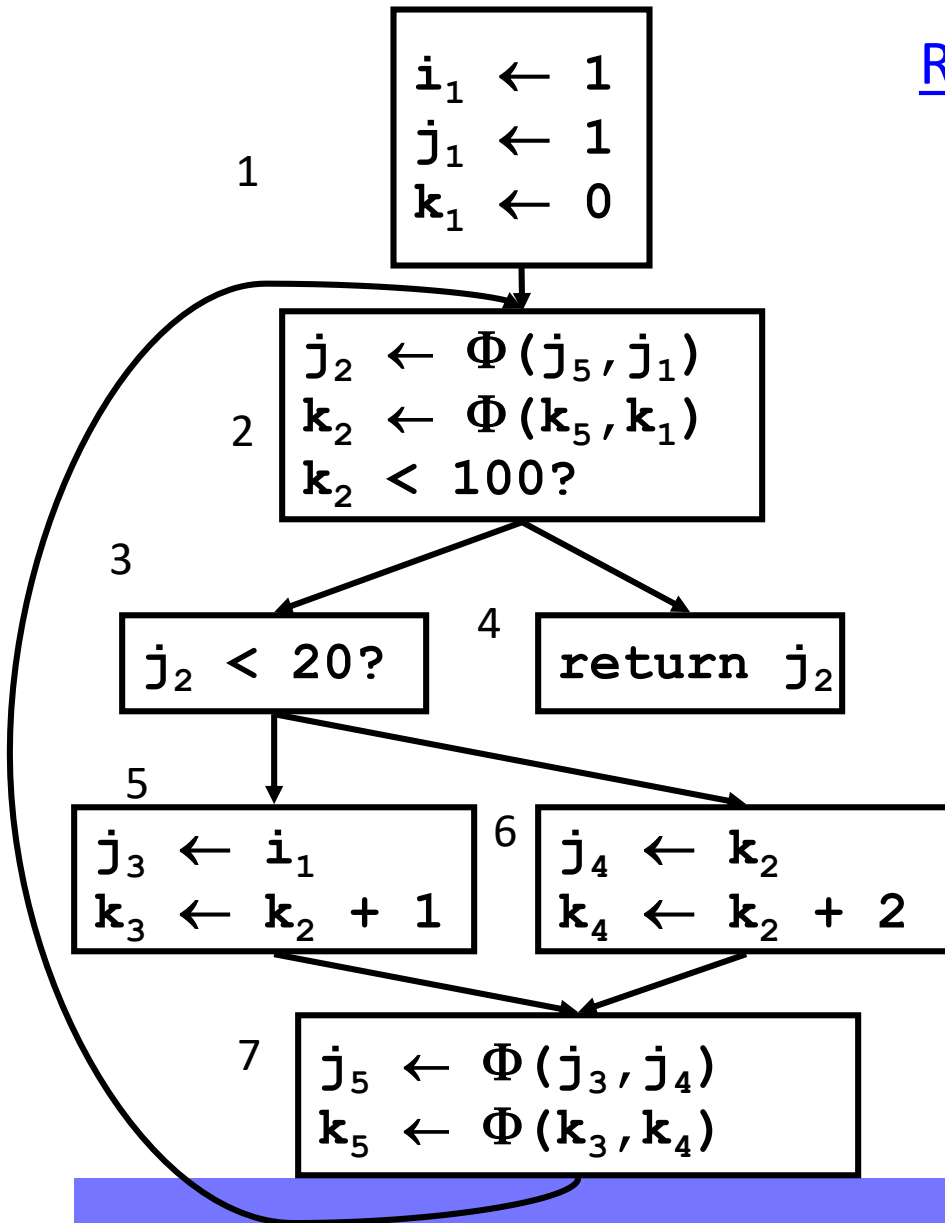
replace k 'th arg. of $\Phi(\mathbf{v}, \dots, \mathbf{v})$ with top of stack(v), where B is k 'th predecessor of S

call **rename(C)** on all children C of B

in Dominance Tree

pop all defs in B from stacks

Rename Vars: Final Result

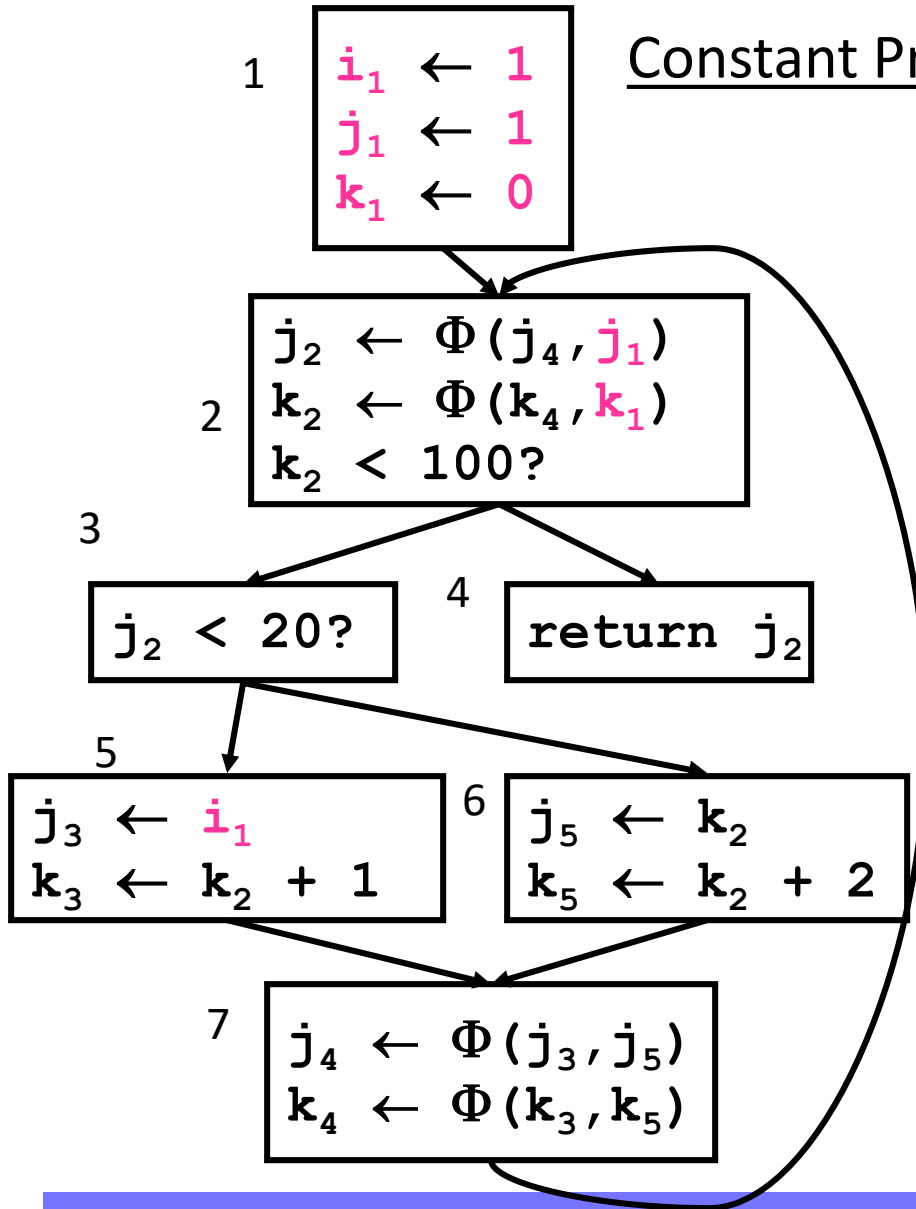


IV. Constant Propagation with SSA

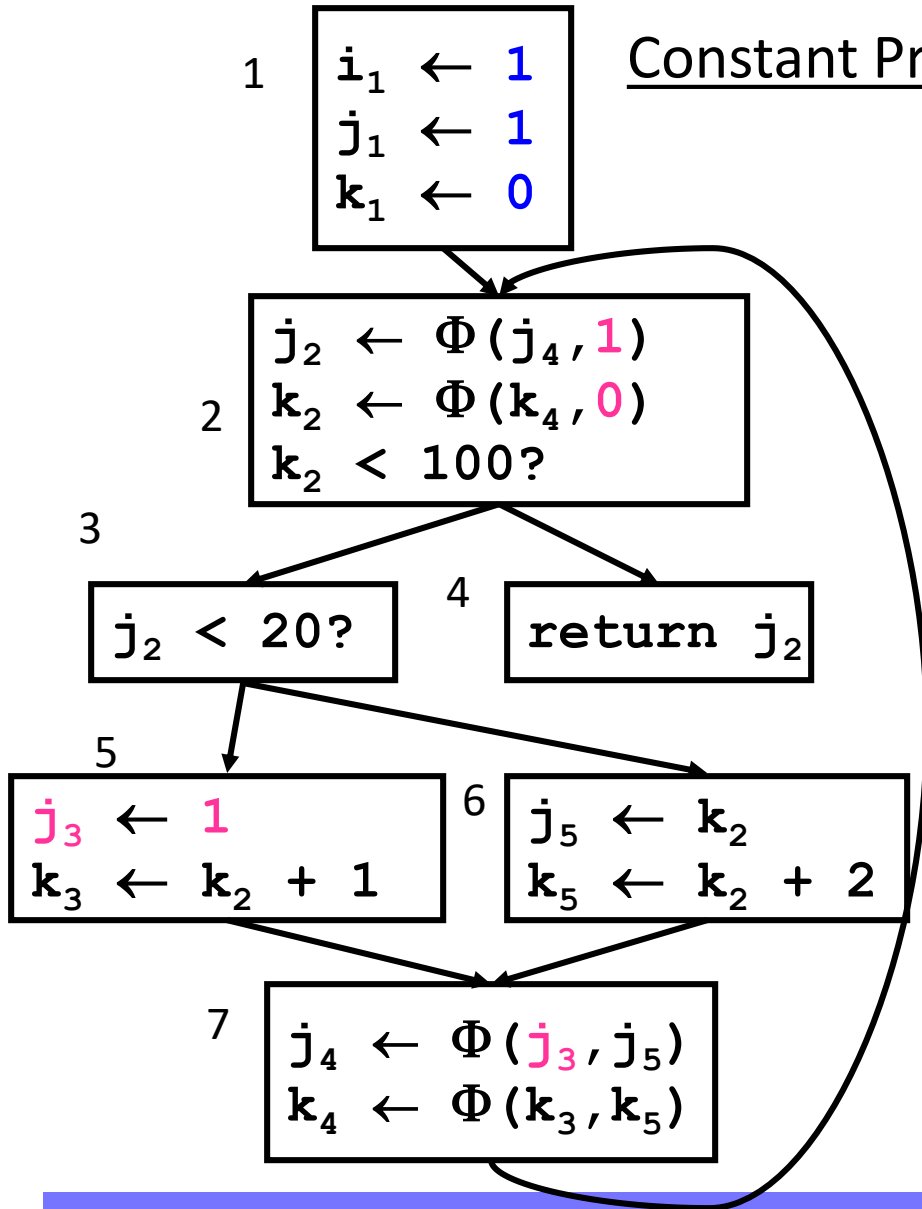
- If " $v \leftarrow c$ ", replace all uses of v with c
- If " $v \leftarrow \Phi(c,c,c)$ " (each input is the same constant), replace all uses of v with c

```
W ← list of all defs
while !W.isEmpty {
  Statement S ← W.removeOne
  if ((S has form " $v \leftarrow c$ ") ||
      (S has form " $v \leftarrow \Phi(c, \dots, c)$ ")) then {
    delete S
    foreach statement U that uses v {
      replace v with c in U
      W.add(U)
    }
  }
}
```

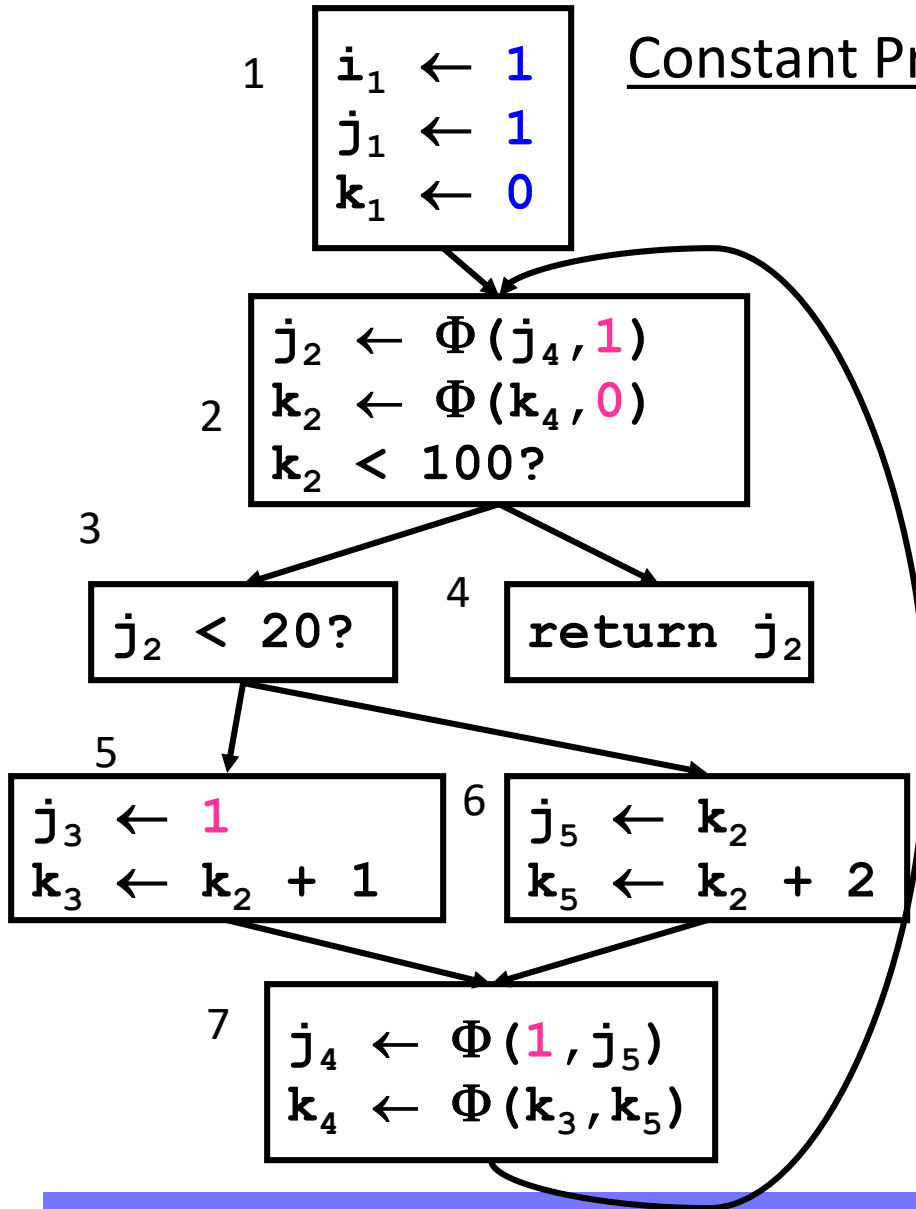
Constant Propagation



Constant Propagation

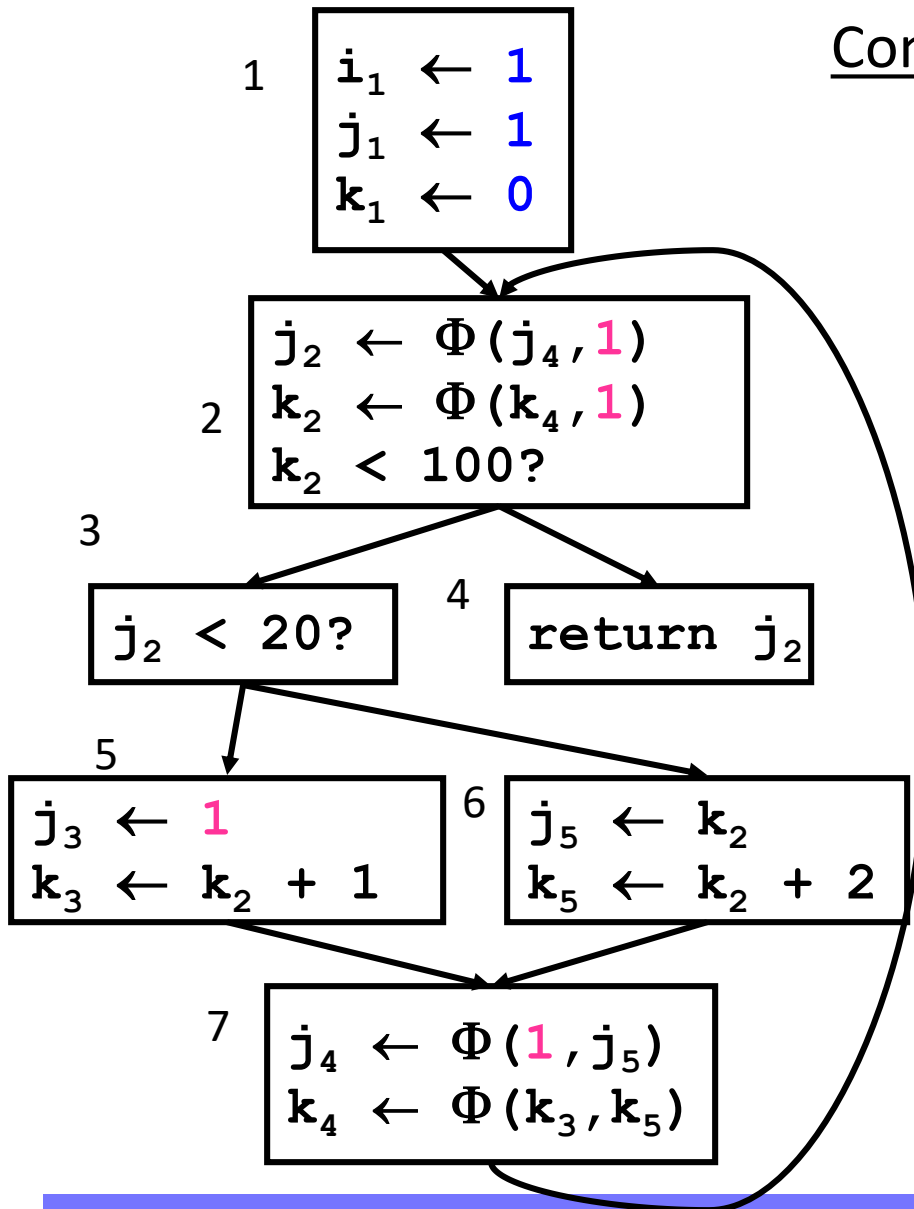


Constant Propagation



Not a very exciting result (yet)...

Conditional Constant Propagation



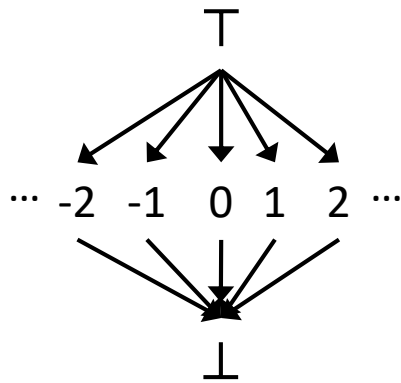
- Does block 6 ever execute?
- Simple Constant Propagation can't tell
- But "Conditional Const. Prop." *can* tell:
 - Assumes **blocks don't execute** until proven otherwise
 - Assumes **values are constants** until proven otherwise

Conditional Constant Propagation Algorithm

Keeps track of:

- **Blocks**
 - assume unexecuted until proven otherwise
- **Variables**
 - assume not executed (only with proof of assignments of a non-constant value do we assume not constant)

Lattice for representing variables:

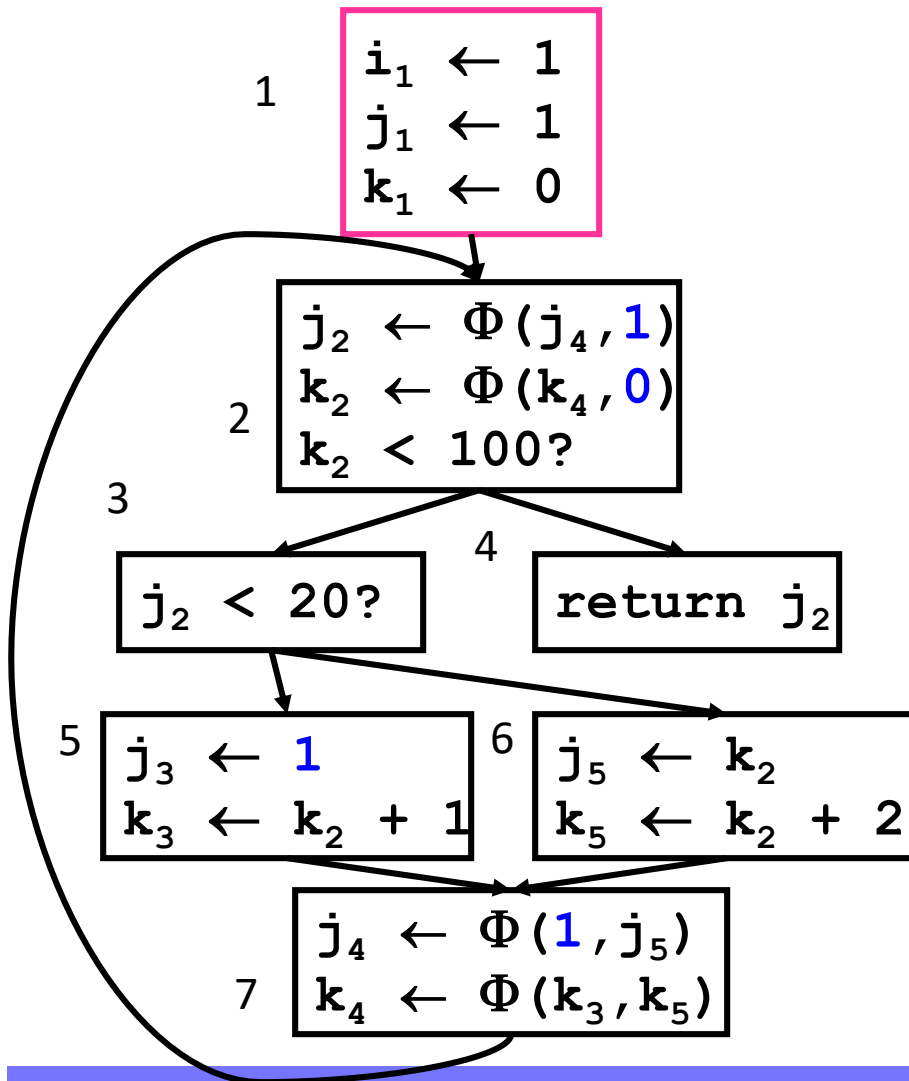


not executed

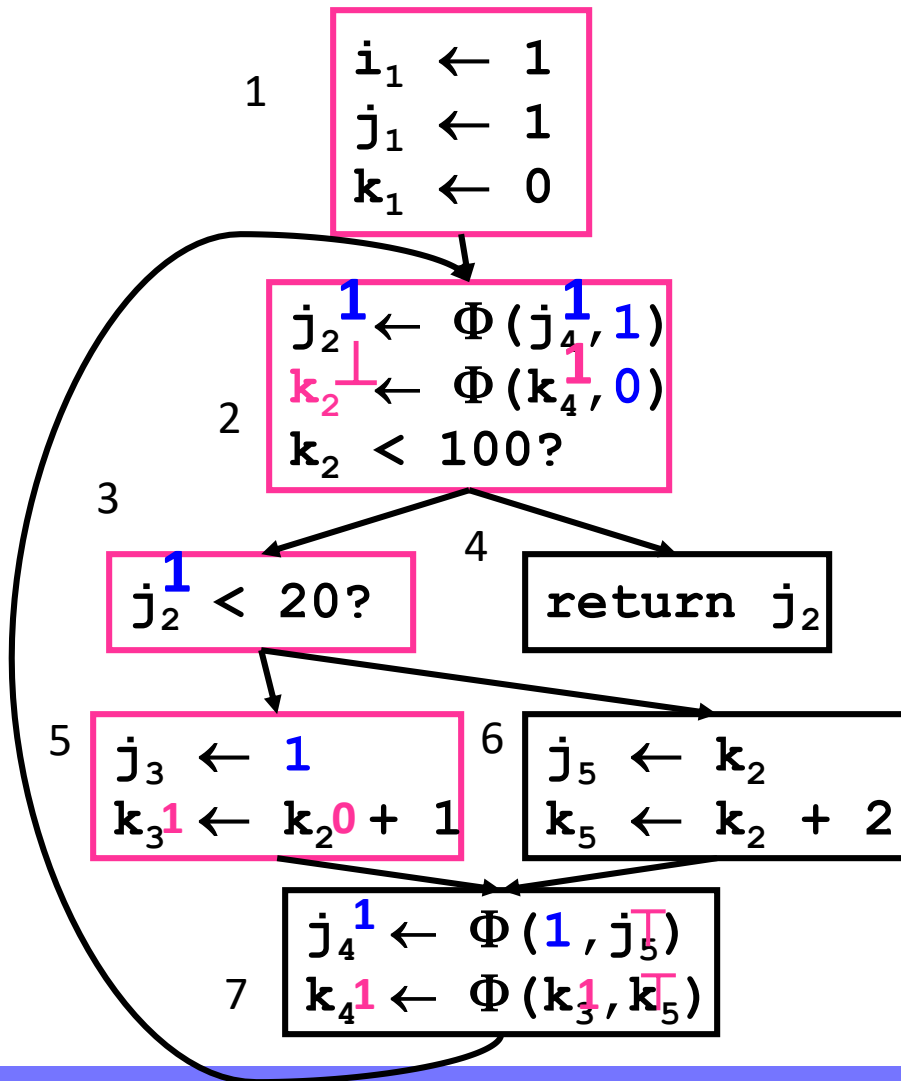
we have seen **evidence** that the variable has been **assigned a constant** with the value

we have seen **evidence** that the variable **can hold different values** at different times

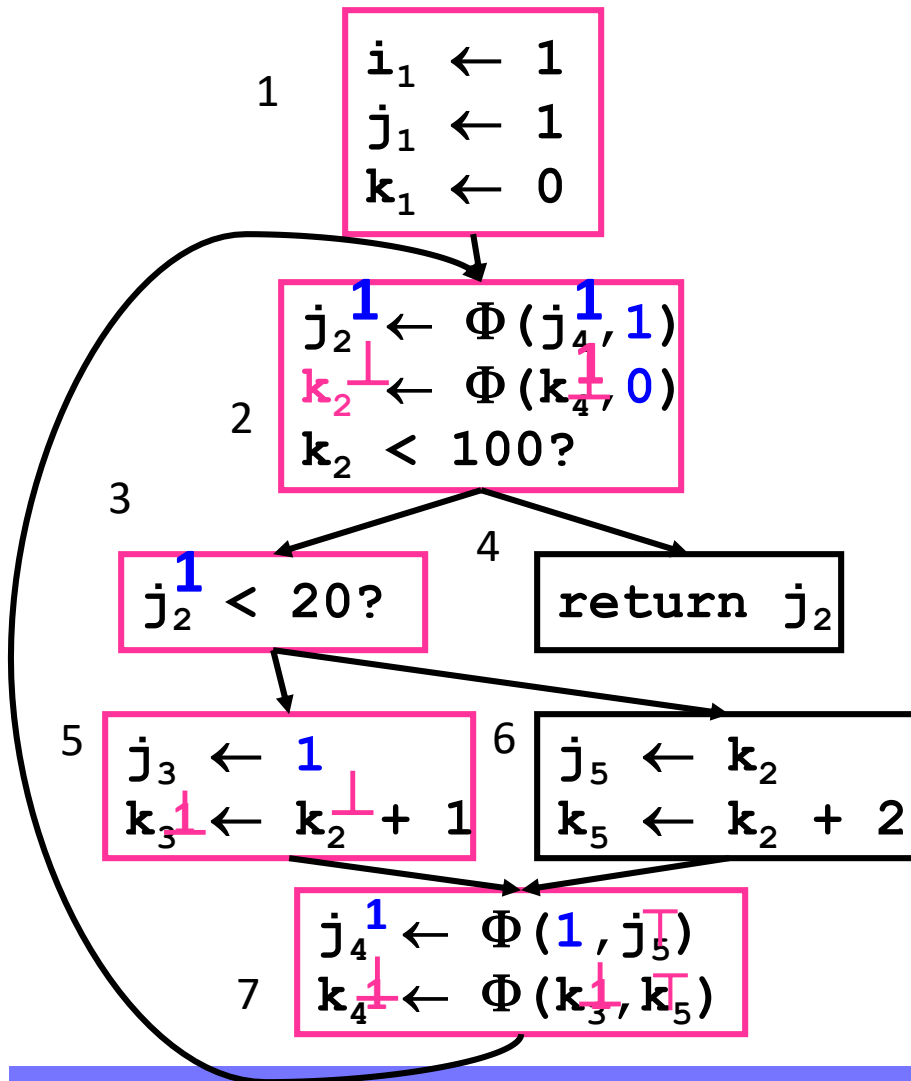
Conditional Constant Propagation



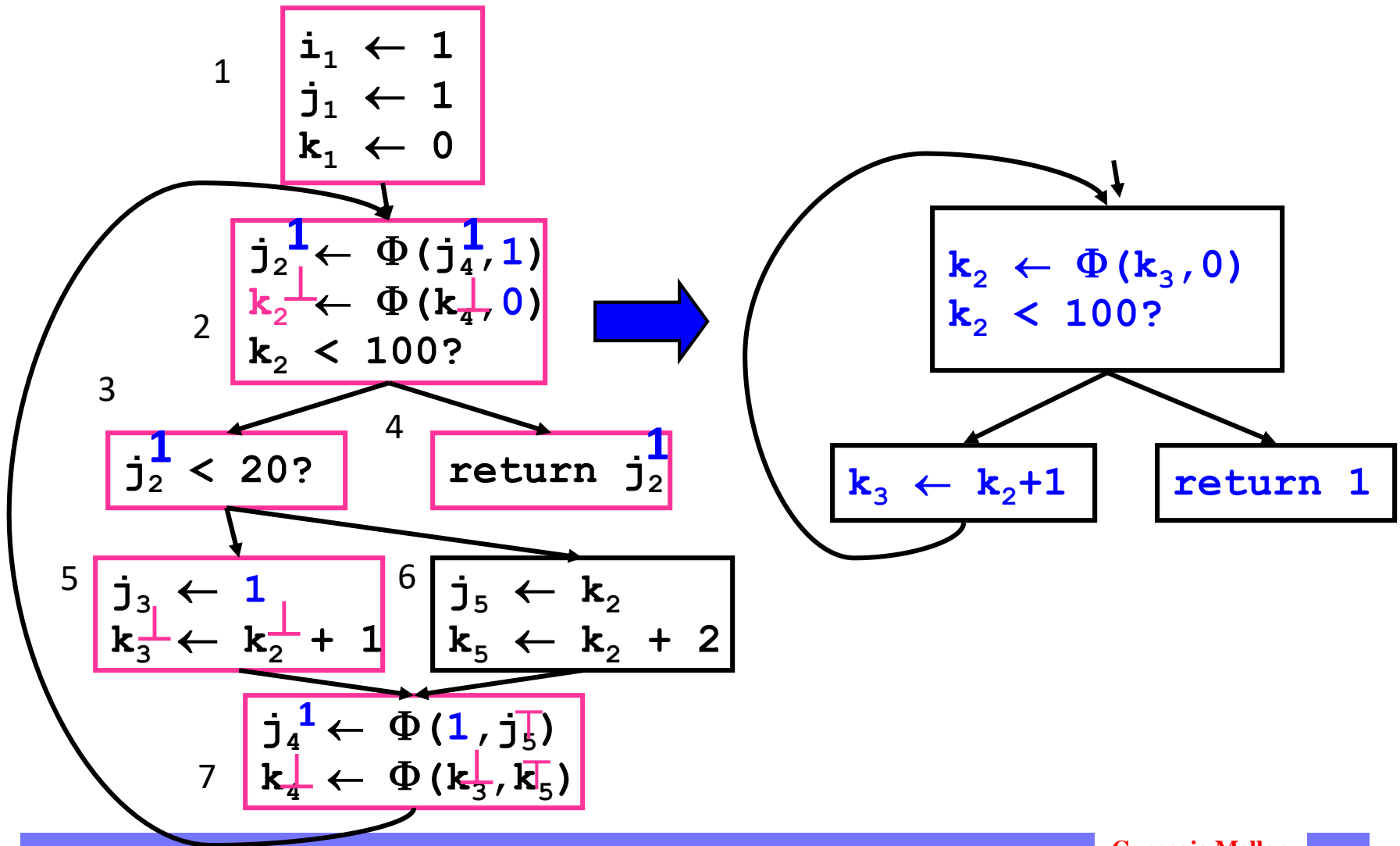
Conditional Constant Propagation



Conditional Constant Propagation



Conditional Constant Propagation



Today's Class

- I. Review: Intro to SSA
- II. When/Where to Insert Φ
- III. Example
- IV. Constant Propagation with SSA

Wednesday's Class

- Register Allocation
 - ALSU 8.8