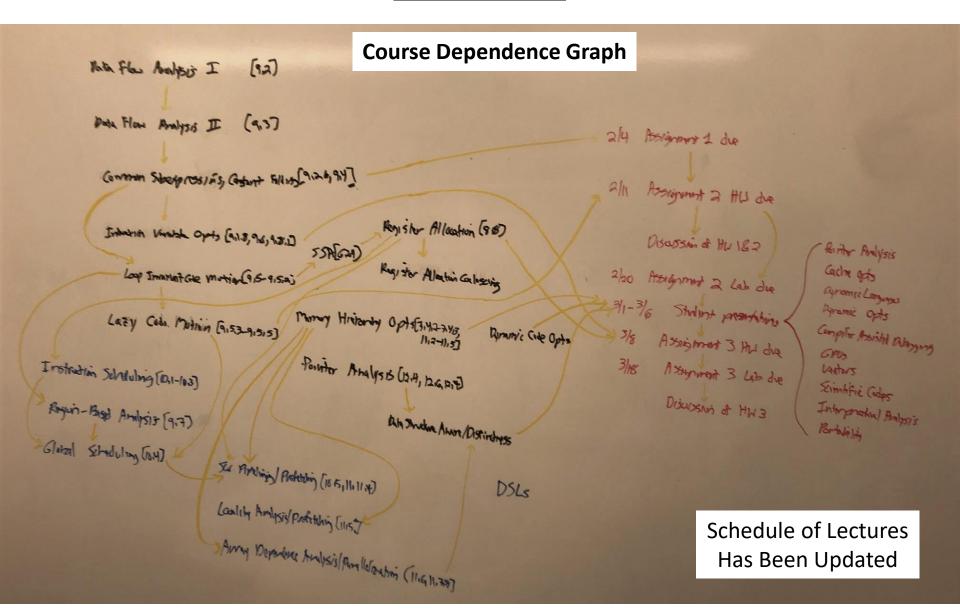
Lecture 5

Introduction to Data Flow Analysis

- I. Structure of data flow analysis
- II. Example 1: Reaching definition analysis
- III. Example 2: Liveness analysis
- IV. Framework

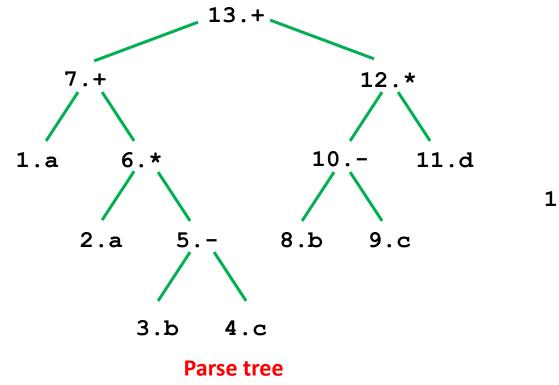
What is This?

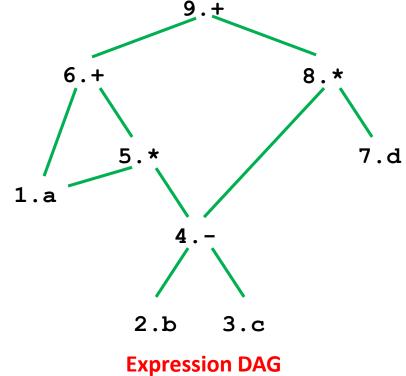


Review: Expression DAG

Example 1:

- grammar (for bottom-up parsing): E -> E + T | E T | T, T -> T*F | F, F -> (E) | id
- expression: a+a*(b-c)+(b-c)*d

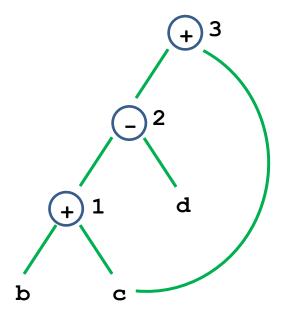




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Review: Value Numbering

Data structure:



What is Data Flow Analysis?

Local analysis (e.g. value numbering)

- analyze effect of each instruction
- compose effects of instructions to derive information from beginning of basic block to each instruction

Data flow analysis

- analyze effect of each basic block
- compose effects of basic blocks to derive information at basic block boundaries
- from basic block boundaries, apply local technique to generate information on instructions

[ALSU 9.2]

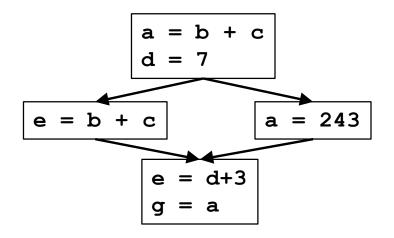
What is Data Flow Analysis? (Cont.)

Data flow analysis:

- Flow-sensitive: sensitive to the control flow in a function
- Intraprocedural analysis

Examples of optimizations:

- Constant propagation
- Common subexpression elimination
- Dead code elimination



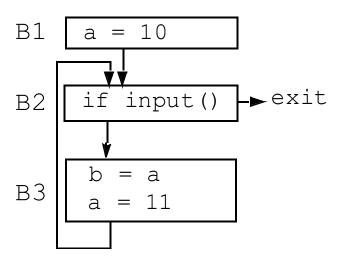
For each variable x, determine:

Value of x?

Which "definition" defines x?

Is the definition still meaningful (live)?

Static Program vs. Dynamic Execution



- Statically: Finite program
- **Dynamically**: Can have infinitely many possible execution paths
- Data flow analysis abstraction:
 - For each point in the program:
 combines information of all the instances of the same program point.
- Example of a data flow question:
 - Which definition defines the value used in statement "b = a"?

Effects of a Basic Block

- Effect of a statement: a = b+c
 - Uses source variables (b and c)
 - Kills an old definition (old definition of a)
 - Defines a new definition (a)
- Compose effects of statements -> Effect of a basic block
 - A **locally exposed use** in a b.b. is a use of a data item that is not preceded in the b.b. by a definition of the data item.
 - Any definition of a data item in the b.b. kills all other definitions of the same data item.
 - A locally available definition = last definition of data item in b.b.

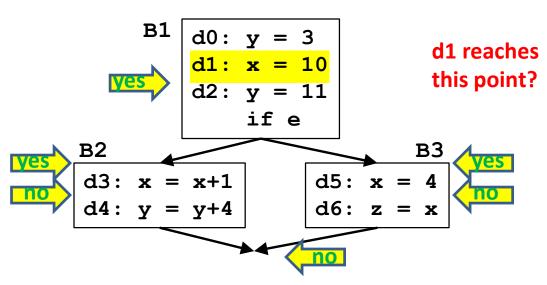
locally exposed uses? r1

kills any definitions? Any other defn of t2 in program

locally available definition? t2

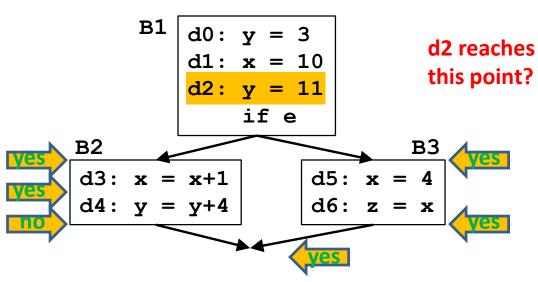
ALSU 9.2.4

II. Reaching Definitions



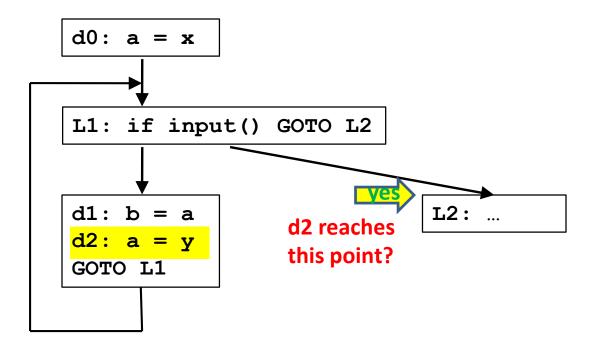
- Every assignment is a definition
- A definition d reaches a point p
 if there exists path from the point immediately following d to p
 such that d is not killed (overwritten) along that path.
- Problem statement
 - For each point in the program, determine if each definition in the program reaches the point
 - A bit vector per program point, vector-length = #defs

Reaching Definitions

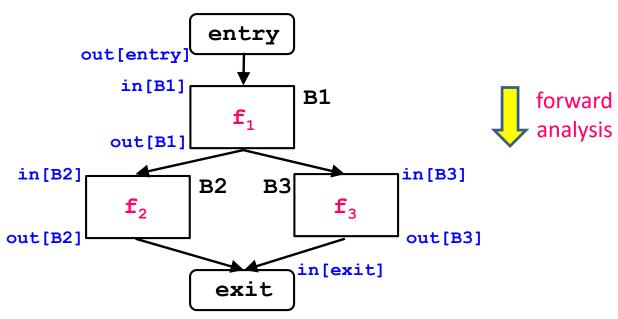


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Reaching Definitions: Another Example

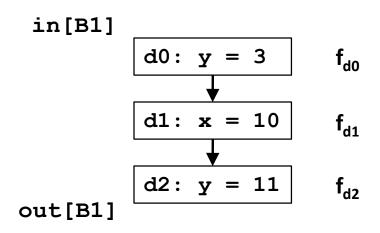


Data Flow Analysis Schema



- Build a flow graph (nodes = basic blocks, edges = control flow)
- Set up a set of equations between in[b] and out[b] for all basic blocks b
 - Effect of code in basic block:
 - Transfer function f_b relates in[b] and out[b], for same b
 - Effect of flow of control:
 - relates out[b], in[b'] if b and b' are adjacent
- Find a solution to the equations

Effects of a Statement



- f_s: A transfer function of a statement
 - abstracts the execution with respect to the problem of interest
- Consider Reaching Definitions. For a statement s (e.g., d: x = y + z):
 out[s] = f_s(in[s]) = Gen[s] U (in[s]-Kill[s])
 - Gen[s]: definitions generated: Gen[s] = {d}
 - Propagated definitions: in[s] Kill[s],
 where Kill[s]=set of all other defs to x in the rest of program

Effects of a Basic Block

in [B1]
$$d0: y = 3$$

$$0 = f_{d0}$$

$$d1: x = 10$$

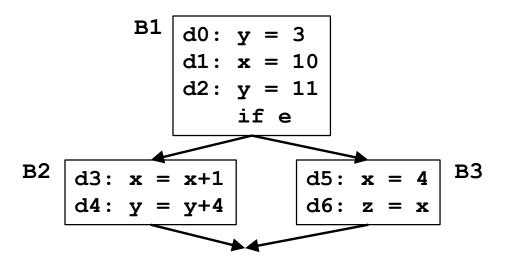
$$d2: y = 11$$

$$d2: y = 11$$

$$f_{d2}$$

- Transfer function of a statement s:
 - out[s] = $f_s(in[s])$ = Gen[s] U (in[s]-Kill[s])
- Transfer function of a basic block B:
 - Composition of transfer functions of statements in B
- out[B] = $f_B(in[B]) = f_{d2}f_{d1}f_{d0}(in[B])$
 - $= \operatorname{Gen}[d_2] \cup ((\operatorname{Gen}[d_1] \cup ((\operatorname{Gen}[d_0] \cup (\operatorname{in}[B] \operatorname{Kill}[d_0])) \operatorname{Kill}[d_1])) \operatorname{Kill}[d_2])$
 - = $Gen[d_2] U (Gen[d_1] U (Gen[d_0] Kill[d_1]) Kill[d_2]) U$ $(in[B] - (Kill[d_0] U Kill[d_1] U Kill[d_2]))$
 - = Gen[B] U (in[B] Kill[B])
 - Gen[B]: locally available definitions (defined locally & reaches end of bb)
 - Kill[B]: set of definitions killed by B

Reaching Definitions Example

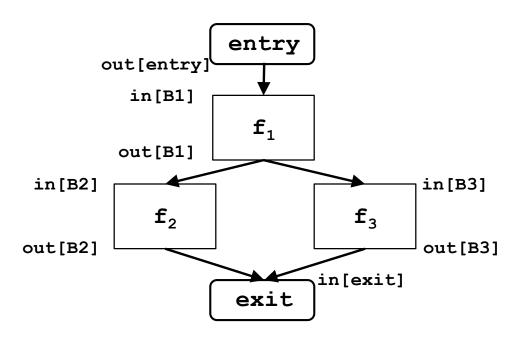


```
f Gen Kill
1 {1,2} {0,2,3,4,5}
2 {3,4} {0,1,2,5}
3 {5,6} {1,3}
```

Subtlety: d0 & d2 kill each other, but d2 is still generated

- transfer function f_b of a basic block b: OUT[b] = f_b(IN[b])
 incoming reaching definitions -> outgoing reaching definitions
- A basic block b
 - generates definitions: Gen[b],
 - set of definitions in b that reach end of b
 - kills definitions: in[b] Kill[b],
 where Kill[b]=set of defs killed by defs in b
- out[b] = Gen[b] U (in(b)-Kill[b])

Effects of the Edges (acyclic)

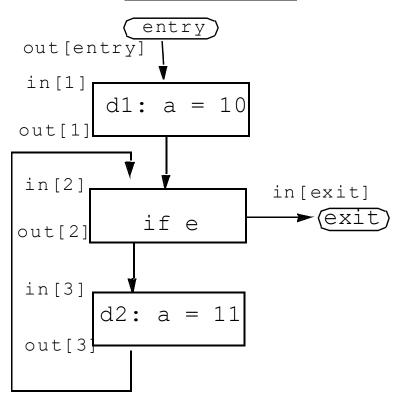


- out[b] = f_b(in[b])
- Join node: a node with multiple predecessors
- meet operator:

in[b] = out[
$$p_1$$
] U out[p_2] U ... U out[p_n], where p_1 , ..., p_n are all the predecessors of b

in[exit] = out[B2] U out[B3]

Cyclic Graphs



- Equations still hold
 - out[b] = $f_b(in[b])$
 - $in[b] = out[p_1] \cup out[p_2] \cup ... \cup out[p_n], p_1, ..., p_n pred.$
- Find: fixed point solution

in[B2] = out[B1] U out[B3]

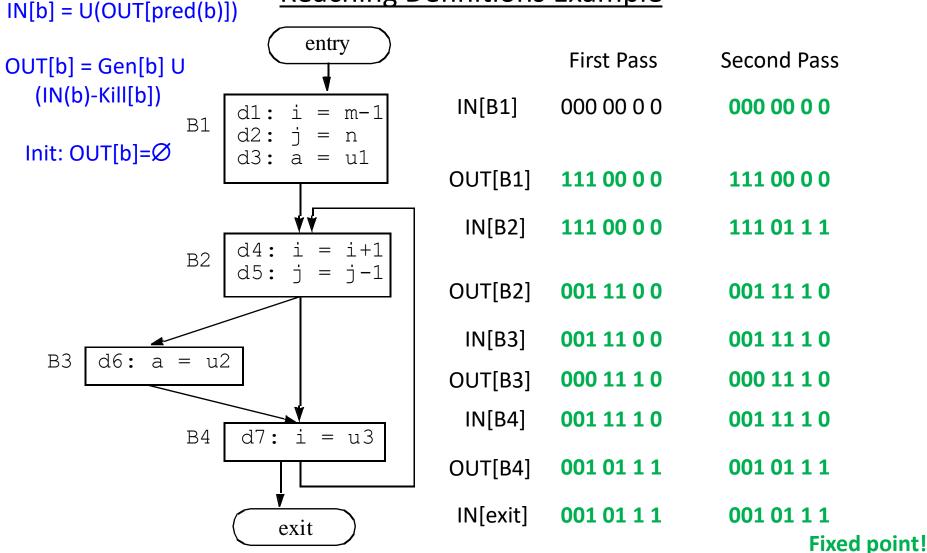
Reaching Definitions: Iterative Algorithm

```
input: control flow graph CFG = (N, E, Entry, Exit)
// Boundary condition
   out[Entry] = \emptyset
// Initialization for iterative algorithm
   For each basic block B other than Entry
      out[B] = \emptyset
// iterate
   While (changes to any out[] occur) {
      For each basic block B other than Entry {
         in[B] = U(out[p]), for all predecessors p of B
         out[B] = f_B(in[B]) // out[B] = gen[B] U(in[B] - kill[B])
```

Reaching Definitions: Worklist Algorithm

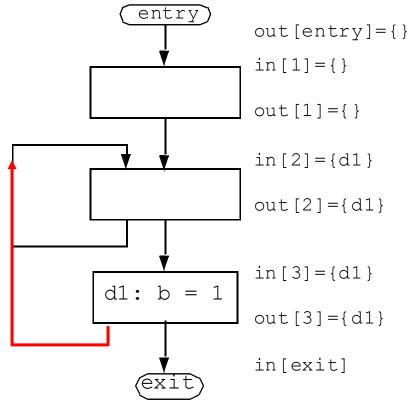
```
input: control flow graph CFG = (N, E, Entry, Exit)
// Initialize
    out[Entry] = \emptyset
                            // could set out[Entry] to special def
                            // if reaching then undefined use
    For all nodes i
        out[i] = \emptyset
                             // could optimize by out[i]=gen[i]
    ChangedNodes = N
// iterate
    While ChangedNodes \neq \emptyset {
        Remove i from ChangedNodes
        in[i] = U(out[p]), for all predecessors p of i
        oldout = out[i]
        out[i] = f_i(in[i]) // out[i]=gen[i] U(in[i]-kill[i])
        if (oldout # out[i]) {
            for all successors s of i
                 add s to ChangedNodes
```

Reaching Definitions Example



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A valid solution to Reaching Definitions?



Fixed point: another iteration of algorithm won't change in/out values

- Is the solution a fixed point? yes Is it valid? no
- Will the worklist algorithm generate this answer? no
- What if add control flow edge shown in red? yes

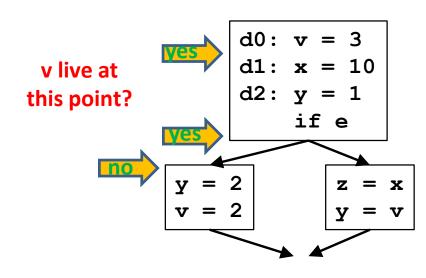
III. Live Variable Analysis

Definition

- A variable \mathbf{v} is **live** at point p if
 - the value of \mathbf{v} is used along some path in the flow graph starting at p.
- Otherwise, the variable is dead.

Motivation

• e.g. register allocation



Problem statement

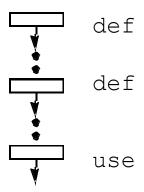
- For each basic block
 - determine if each variable is live in each basic block
- Size of bit vector: one bit for each variable

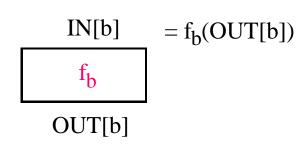
Live Variables: Effects of a Basic Block (Transfer Function)

Insight: Trace uses backwards to the definitions

an execution path

control flow







A basic block b can

- generate live variables: Use[b]
 - set of locally exposed uses in b
- propagate incoming live variables: OUT[b] Def[b],
 - where Def[b]= set of variables defined in b.b.
- transfer function for block b:

$$in[b] = Use[b] U (out[b]-Def[b])$$

<u>example</u>

$$d4: d = 1$$

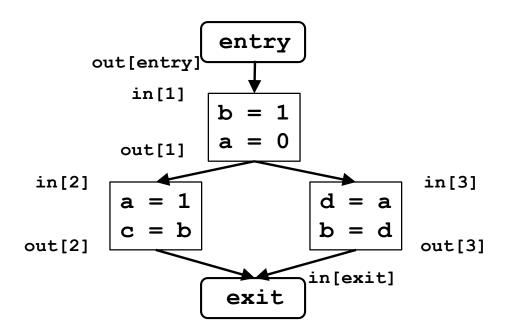
$$d5: c = a$$

$$d6: a = 4$$

$$IN[b] =$$

$${a} U (OUT[b] - {a,c,d})$$

Flow Graph



```
f Use Def
1 {} {a,b}
2 {b} {a,c}
3 {a} {b,d}
```

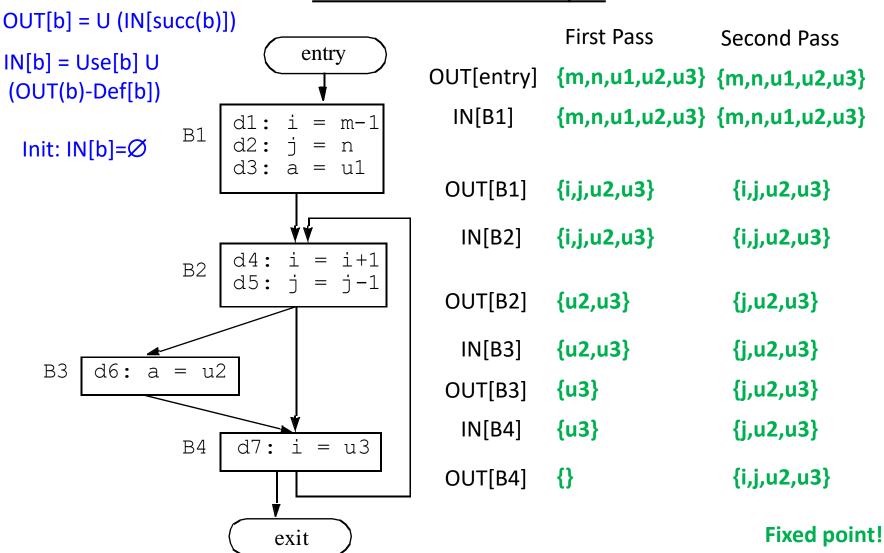
- $in[b] = f_b(out[b])$
- Join node: a node with multiple successors
- meet operator:

out[b] =
$$in[s_1]$$
 U $in[s_2]$ U ... U $in[s_n]$, where $s_1, ..., s_n$ are all successors of b

<u>Live Variables: Iterative Algorithm</u>

```
input: control flow graph CFG = (N, E, Entry, Exit)
// Boundary condition
   in[Exit] = \emptyset
// Initialization for iterative algorithm
   For each basic block B other than Exit
      in[B] = \emptyset
// iterate
   While (changes to any in[] occur) {
      For each basic block B other than Exit {
         out[B] = U(in[s]), for all successors s of B
         in[B] = f_B(out[B]) // in[B]=Use[B] \cup (out[B]-Def[B])
```

Live Variables Example



IV. Framework

	Reaching Definitions	Live Variables
Domain	Sets of definitions	Sets of variables
Direction	forward: out[b] = $f_b(in[b])$ $in[b] = \land out[pred(b)]$	backward: $in[b] = f_b(out[b])$ $out[b] = \land in[succ(b)]$
Transfer function	$f_b(x) = Gen_b \cup (x - Kill_b)$	$f_b(x) = Use_b \cup (x - Def_b)$
Meet Operation (∧)	U	
Boundary Condition	$out[entry] = \emptyset$	$in[exit] = \emptyset$
Initial interior points	out[b] = ∅	in[b] = ∅

Other Data Flow Analysis problems fit into this general framework, e.g., Available Expressions [ALSU 9.2.6]

Key Questions

- Correctness
 - equations are satisfied, if the analysis algorithm terminates.
- Precision: how good is the answer?
 - is the answer ONLY a union of all possible executions?
- Convergence: will the analysis terminate?
 - or, could there always be some nodes that change?
- Speed: how fast is the convergence?
 - how many times will we visit each node?

Friday

When it's 3 AM and the lecture episode ends with a cliffhanger



Today's Class

- Structure of data flow analysis
- II. Example 1: Reaching definition analysis
- III. Example 2: Liveness analysis
- IV. Framework

Monday's Class

- Foundations of Data Flow Analysis
 - ALSU 9.3