10-701 Midterm Exam, Fall 2007

1. Personal info:
   - Name:
   - Andrew account:
   - E-mail address:
2. There should be 17 numbered pages in this exam (including this cover sheet).
3. You can use any material you brought: any book, class notes, your print outs of class materials that are on the class website, including my annotated slides and relevant readings, and Andrew Moore's tutorials. You cannot use materials brought by other students. Calculators are not necessary. Laptops, PDAs, phones and Internet access are not allowed.
4. If you need more room to work out your answer to a question, use the back of the page and clearly mark on the front of the page if we are to look at what's on the back.
5. Work efficiently. Some questions are easier, some more difficult. Be sure to give yourself time to answer all of the easy ones, and avoid getting bogged down in the more difficult ones before you have answered the easier ones.
6. Note there are extra-credit sub-questions. The grade curve will be made without considering students' extra credit points. The extra credit will then be used to try to bump your grade up without affecting anyone else's grade.
7. You have 80 minutes.
8. Good luck!

Question	Topic	Max. score	Score
1	Short questions	20 + 0.1010 extra	
2	Loss Functions	12	
3	Kernel Regression	12	
4	Model Selection	14	
5	Support Vector Machine	12	
6	Decision Trees and Ensemble Methods	30	

1 [20 Points] Short Questions

The following short questions should be answered with at most two sentences, and/or a picture. For yes/no questions, make sure to provide a *short* justification.

1. [2 point] Does a 2-class Gaussian Naive Bayes classifier with parameters μ_{1k}, σ_{1k}, μ_{2k}, σ_{2k} for attributes $k = 1, ..., m$ have exactly the same representational power as logistic regression (i.e., a linear decision boundary), given no assumptions about the variance values σ_{ik}^2?

   ★ **SOLUTION:** No. Gaussian Naive Bayes classifier has more expressive power than a linear classifier if we don't restrict the variance parameters to be class-independent. In other words, Gaussian Naive Bayes classifier is a linear classifier if we assume $\sigma_{1k} = \sigma_{2k}$, $\forall k$.

2. [2 points] For linearly separable data, can a small slack penalty ("C") hurt the training accuracy when using a linear SVM (no kernel)? If so, explain how. If not, why not?

   ★ **SOLUTION:** Yes. If the optimal values of α's (say in the dual formulation) are greater than C, we may end up with a sub-optimal decision boundary with respect to the training examples. Alternatively, a small C can allow large slacks, thus the resulting classifier will have a small value of w^2 but can have non-zero training error.

3. [3 points] Consider running AdaBoost with Multinomial Naive Bayes as the weak learner for two classes and k binary features. After t iterations, of AdaBoost, how many parameters do you need to remember? In other words, how many numbers do you need to keep around to predict the label of a new example? Assume that the weak-learner training error is non-zero at iteration t. Don't forget to mention where the parameters come from.

   ★ **SOLUTION:** Recall that we predict the label of an example using AdaBoost by $y = sign(\sum_{t'} \alpha_{t'} h_{t'}(x))$. Hence for each iteration of adaboost we need to remember the parameters of $h_{t'}(x)$ and $\alpha_{t'}$. Since our weak classifier is Multinomial Naive Bayes, we need $2k + 1$ parameters for it including $2k$ for $P(X_i|Y = 0)$, $P(X_i|Y = 1)$ for $k = 1, ..., k$ and the prior $P(Y = 1)$. Hence for each iteration we have $2k + 2$ parameters including $\alpha_{t'}$, and after t iterations we have $t(2k + 2)$ parameters.

4. [2 points] In boosting, would you stop the iteration if the following happens? Justify your answer with at most two sentences each question.

   - The error rate of the combined classifier on the original training data is 0.

★ **SOLUTION:** No. Boosting is robust to overfitting. Test error may decrease even after the training error is 0.

- The error rate of the current weak classifier on the weighted training data is 0.

★ **SOLUTION:** Yes. In this case, $\alpha_t = +\infty$, and the weights of all the examples are 0. On the other hand, the current weak classifier is perfect on the weighted training data, so it is also perfect on the original data set. There is no need to combine this classifier with other classifiers.

5. [4 points] Given n linearly independent feature vectors in n dimensions, show that for any assignment to the binary labels you can always construct a linear classifier with weight vector w which separates the points. Assume that the classifier has the form $sign(w \cdot x)$. Note that a square matrix composed of linearly independent rows is invertible.

★ **SOLUTION:** Lets define the class labels $y \in \{-1, +1\}$ and the matrix X such that each of the n rows is one of the n dimensional feature vectors. Then we want to find a w such that $sign(Xw) = y$. We know that if $Xw = y$ then $sign(Xw) = y$. Because, X is composed of linearly independent rows we can invert X to obtain $w = X^{-1}y$. Therefore we can construct a linear classifier that separates all n points. Interestingly, if we add an additional constant term to the features we can separate $n + 1$ linearly independent point in n dimensions.

6. [3 points] Construct a one dimensional classification dataset for which the Leave-one-out cross validation error of the One Nearest Neighbors algorithm is always 1. Stated another way, the One Nearest Neighbor algorithm never correctly predicts the held out point.

★ **SOLUTION:** For this question you simply need an alternating configuration of the points $\{+, -, +, -, \ldots\}$ along the real line. In leave-one-out cross validation we compute the predicted class for each point given all the remaining points. Because the neighbors of every point are in the oppositie class, the leave-one-out cross validation predictions will always be wrong.

7. [2 points] Would we expect that running AdaBoost using the ID3 decision tree learning algorithm (without pruning) as the weak learning algorithm would have a better true error rate than running ID3 alone (i.e., without boosting (also without pruning))? Explain.

★ **SOLUTION:** No. Unless two differently labeled examples have the same feature vectors, ID3 will find a consistent classifier every time. In particular, after the first iteration of AdaBoost, $\epsilon_1 = 0$, so the first decision tree learned gets an infinite weight $\alpha_1 = \infty$, and the example weights $D_{t+1}(i)$ would either all become 0, all become ∞, or would remain uniform (depending on the implementation). In any case, we either halt, overflow, or make no progress, none of which helps the true error rate.

8. [1 point] Suppose there is a coin with unknown bias p. Does there exist some value of p for which we would expect the maximum a-posteriori estimate of p, using a $Beta(4, 2)$ prior, to require more coin flips before it is close to the true value of p, compared to the number of flips required of the maximum likelihood estimate of p? Explain.
(The $Beta(4, 2)$ distribution is given in the figure below.)

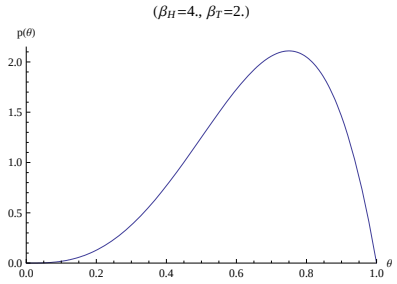


Figure 1: $Beta(4, 2)$ distribution

★ **SOLUTION:** Yes. Consider $p = 0$. Because the prior value there is low, it takes more samples to overcome our prior beliefs and converge to the correct solution, compared to maximum likelihood (which only needs a single observation to find p exactly).

9. [1 point] Suppose there is a coin with unknown bias p. Does there exist some value of p for which we would expect the maximum a-posteriori estimate of p, using a $Uniform([0, 1])$ prior, to require more coin flips before it is close to the true value of p, compared to the number of flips required of the maximum likelihood estimate of p? Explain.

★ **SOLUTION:** No. In this case, the prior's PDF is a constant $f_p(q) = 1$, so the MAP solution $\arg\max_{q\in[0,1]} f_p(q) f_x(\text{Data}; q)$ is always identical to the maximum likelihood solution $\arg\max_{q\in[0,1]} f_x(\text{Data}; q)$.

10. [0.1010 extra credit] Can a linear classifier separate the positive from the negative examples in the dataset below? Justify.

Colbert
for
president

U2
Loosing my religion

The Beatles
There is a season...
Turn! Turn! Turn!

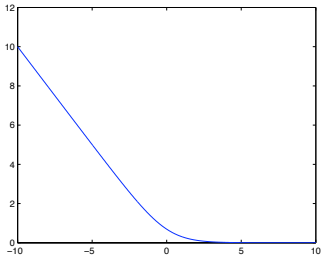
Nirvana
Grunge

★ **SOLUTION:** No. This is an instantiation of XOR.

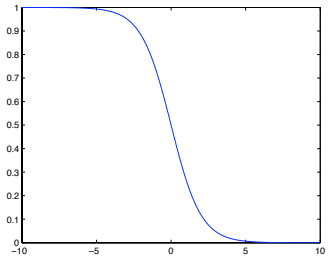
2 [12 points] Loss Function

Generally speaking, a classifier can be written as $H(x) = \text{sign}(F(x))$, where $H(x) : \mathbb{R}^d \rightarrow \{-1, 1\}$ and $F(x) : \mathbb{R}^d \rightarrow \mathbb{R}$. To obtain the parameters in $F(x)$, we need to minimize the loss function averaged over the training set: $\sum_i L(y^i F(x^i))$. Here L is a function of $yF(x)$. For example, for linear classifiers, $F(x) = w_0 + \sum_{j=1}^{d} w_j x_j$, and $yF(x) = y(w_0 + \sum_{j=1}^{d} w_j x_j)$

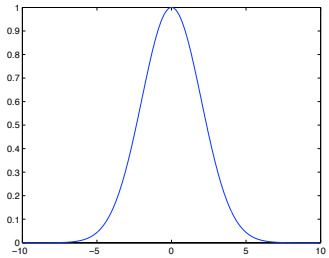
1. [4 points] Which loss functions below are appropriate to use in classification? For the ones that are not appropriate, explain why not. In general, what conditions does L have to satisfy in order to be an appropriate loss function? The x axis is $yF(x)$, and the y axis is $L(yF(x))$.



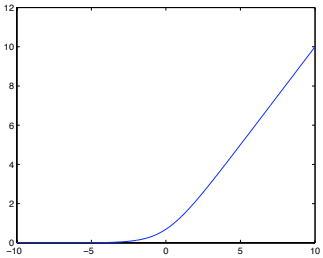
(a)



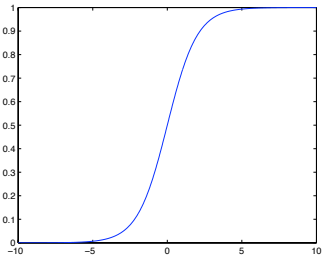
(b)



(c)



(d)



(e)

★ **SOLUTION:** (a) and (b) are appropriate to use in classification. In (c), there is very little penalty for extremely misclassified examples, which correspond to very negative $yF(x)$. In (d) and (e), correctly classified examples are penalized, whereas misclassified examples are not. In general, L should approximate the 0-1 loss, and it should be a non-increasing function of $yF(x)$.

2. [4 points] Of the above loss functions appropriate to use in classification, which one is the most robust to outliers? Justify your answer.

★ **SOLUTION:** (b) is more robust to outliers. For outliers, $yF(x)$ is often very negative. In (a), outliers are heavily penalized. So the resulting classifier is largely affected by the outliers. On the other hand, in (b), the loss of outliers is bounded. So the resulting classifier is less affected by the outliers, and thus more robust.

3. [4 points] Let $F(x) = w_0 + \sum_{j=1}^{d} w_j x_j$ and $L(yF(x)) = \frac{1}{1+\exp(yF(x))}$. Suppose you use gradient descent to obtain the optimal parameters w_0 and w_j. Give the update rules for these parameters.

★ **SOLUTION:** To obtain the parameters in $F(x)$, we need to minimize $\sum_i L(y^i F(x^i)) = \sum_i \frac{1}{1+\exp(y^i F(x^i))} = \sum_i \frac{1}{1+\exp(y^i(w_0+\sum_{j=1}^{d} w_j x_j^i))}$.

$$\frac{\partial}{\partial w_0} \sum_i L(y^i F(x^i)) = \sum_i \frac{\partial}{\partial w_0} \left(\frac{1}{1+\exp(y^i(w_0+\sum_{j=1}^{d} w_j x_j^i))}\right) = -\sum_i \frac{y^i \exp(y^i F(x^i))}{(1+\exp(y^i F(x^i)))^2}$$

$\forall k = 1, \ldots, d,$

$$\frac{\partial}{\partial w_k} \sum_i L(y^i F(x^i)) = \sum_i \frac{\partial}{\partial w_k} \left(\frac{1}{1+\exp(y^i(w_0+\sum_{j=1}^{d} w_j x_j^i))}\right) = -\sum_i \frac{y^i x_k^i \exp(y^i F(x^i))}{(1+\exp(y^i F(x^i)))^2}$$

Therefore, the update rules are as follows.

$$w_0^{(t+1)} = w_0^t - \eta \frac{\partial}{\partial w_0} \sum_i L(y^i F(x^i)) = w_0^t + \eta \sum_i \frac{y^i \exp(y^i F(x^i))}{(1+\exp(y^i F(x^i)))^2}$$

$\forall k = 1, \ldots, d,$

$$w_k^{(t+1)} = w_k^t - \eta \frac{\partial}{\partial w_k} \sum_i L(y^i F(x^i)) = w_0^t + \eta \sum_i \frac{y^i x_k^i \exp(y^i F(x^i))}{(1+\exp(y^i F(x^i)))^2}$$

■ **COMMON MISTAKE 1:** Instead of minimizing $\sum_i L(y^i F(x^i))$, some people only minimize $L(yF(x))$.

3 [12 points] Kernel Regression, k-NN

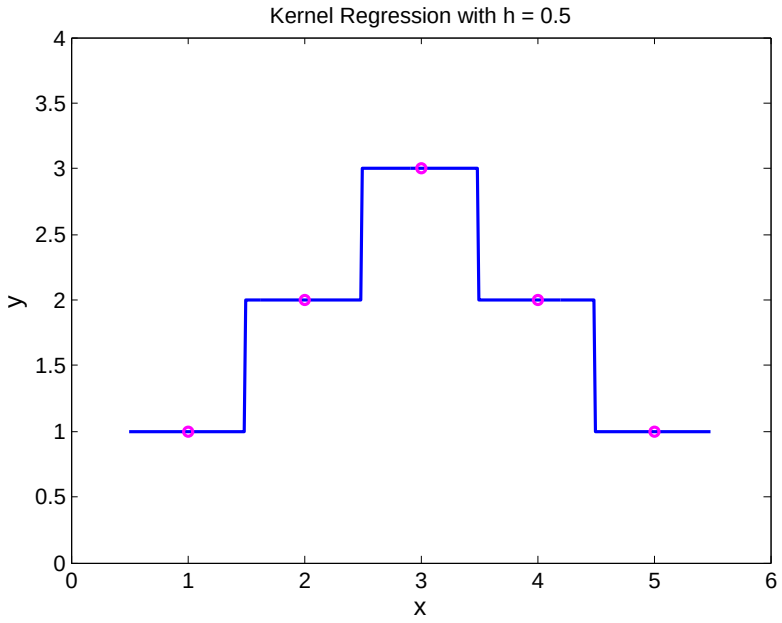
1. [4 points] Sketch the fit Y given X for the dataset given below using kernel regression with a box kernel

$$K(x_i, x_j) = I(-h \leq x_i - x_j < h) = \begin{cases} 1 & if\ -h \leq x_i - x_j < h \\ 0 & otherwise \end{cases}$$

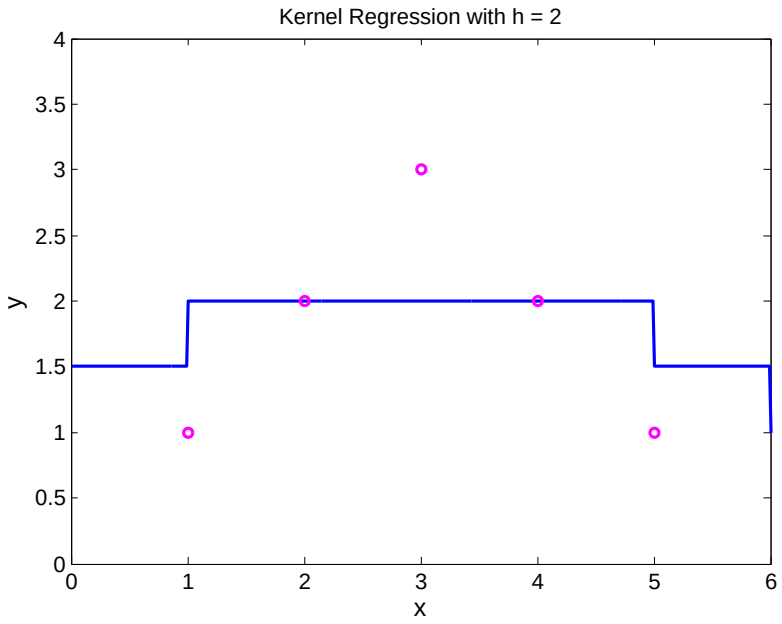
for $h = 0.5, 2$.

★ SOLUTION:

- $h = 0.5$

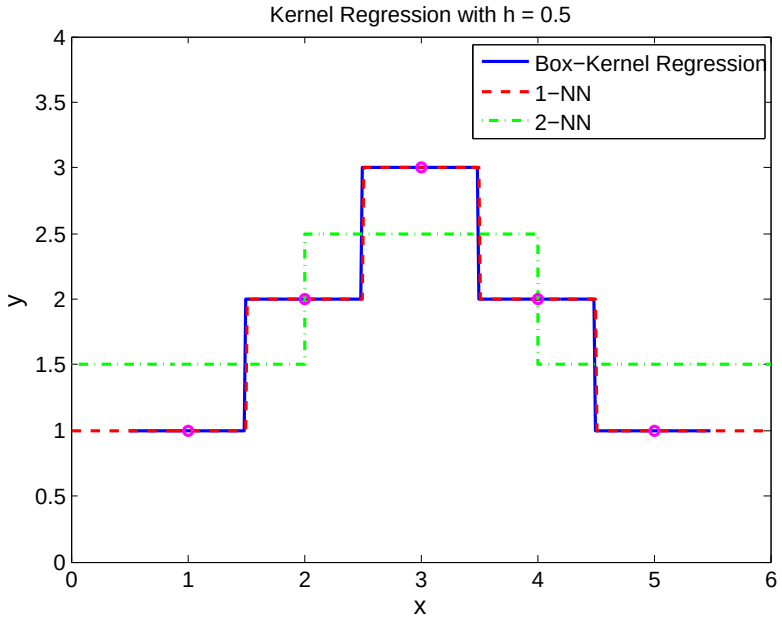


- $h = 2$

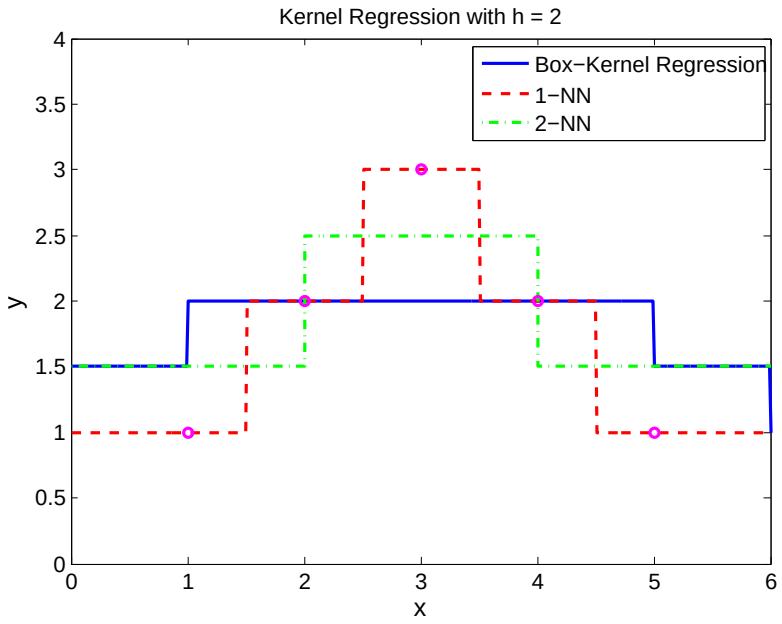


Just for fun, what happens with 1-NN and 2-NN:

- $h = 0.5$



- $h = 2$



■ **COMMON MISTAKE 1:** Some people tried to *classify* the given points using k-NN instead of doing regression.

■ **COMMON MISTAKE 2:** Many people sketched what seemed to be kernel regression or local linear regression with a Gaussian kernel.

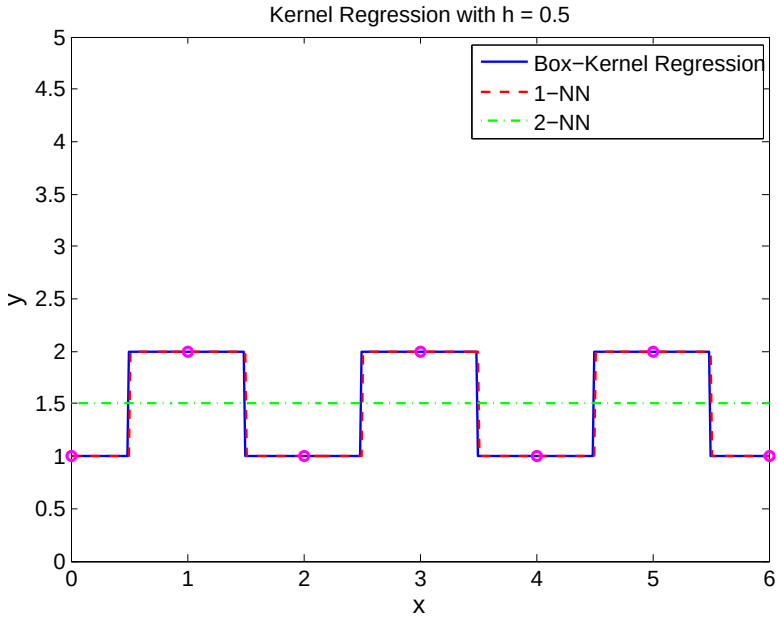
2. [4 points] Sketch or describe a dataset where kernel regression with the box kernel above with $h = 0.5$ gives the same regression values as 1-NN but not as 2-NN in the domain $x \in [0, 6]$ below.

★ **SOLUTION:** Part 1 of the problem with $h = 0.5$ is actually an example where the regression values of kernel regression match 1-NN regression values (in the given domain). The basic idea is to create a dataset where in each inteval of width 1 ($2h$) there is only 1 "training" point and not all given y values are the same (then 1-NN and 2-NN would give the same regression values).

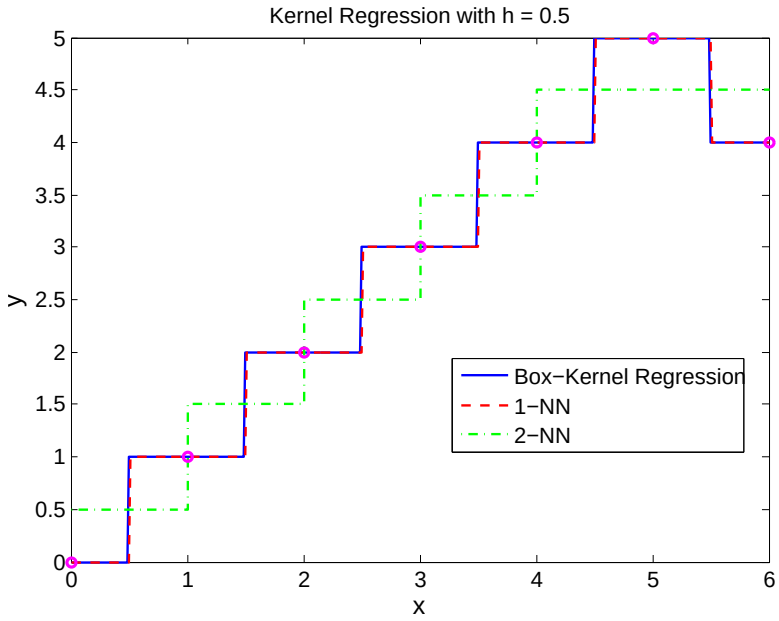
■ **COMMON MISTAKE 1:** Some people tried to come up with examples for k-NN *classification* instead of regression.

Here are some other example solutions. Note that you only had to give the points and here the lines are added just for you to see what happens.

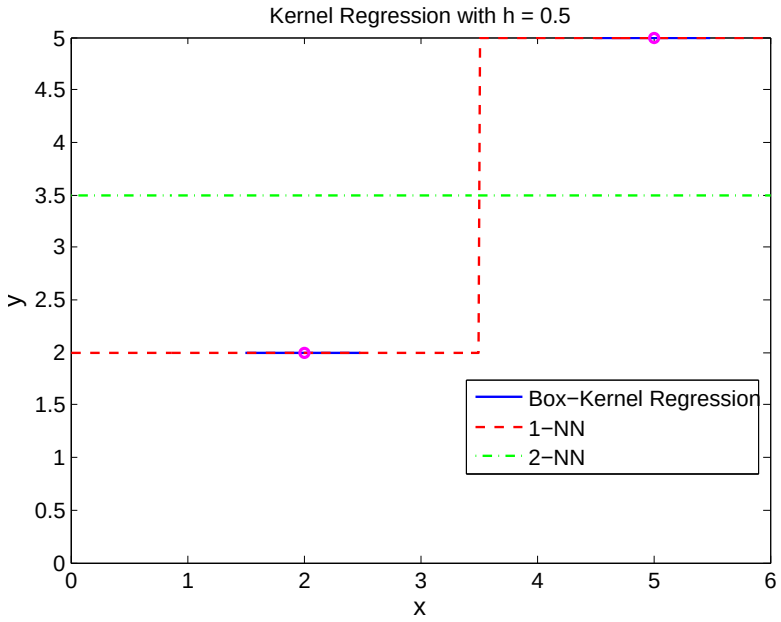
- Example 1



- Example 2



■ **COMMON MISTAKE 2:** Here kernel regression is not defined for some range (e.g. $x \in [0, 1.5]$).

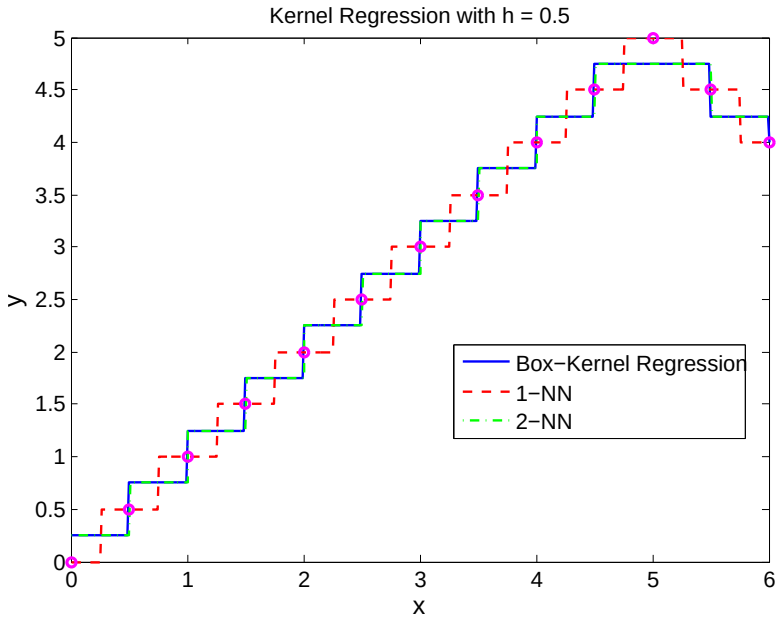


3. [4 points] Sketch or describe a dataset where kernel regression with the box kernel above with $h = 0.5$ gives the same regression values as 2-NN but not as 1-NN in the domain $x \in (0, 6)$ below.

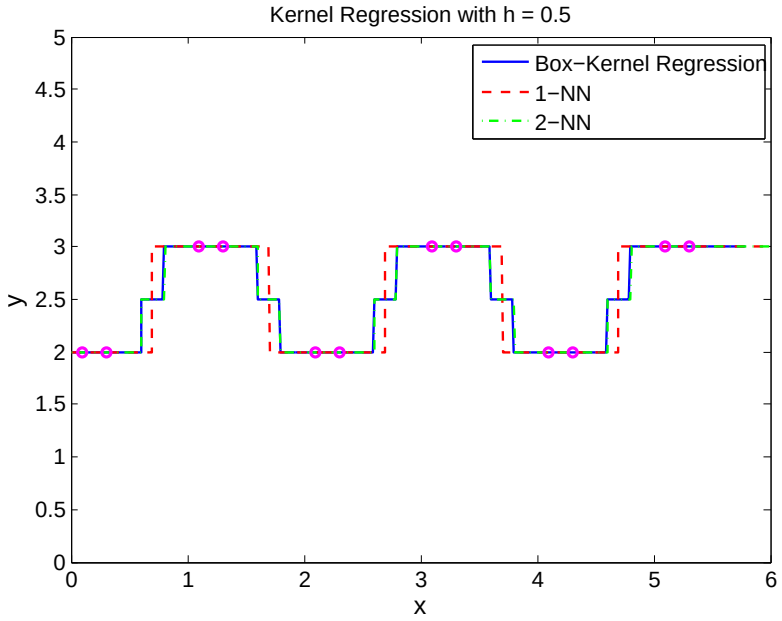
★ **SOLUTION:** As in Part 2, the basic idea is to create a dataset where in each inteval of width 1 ($2h$) there are 2 "training" points.

Here are some example solutions.

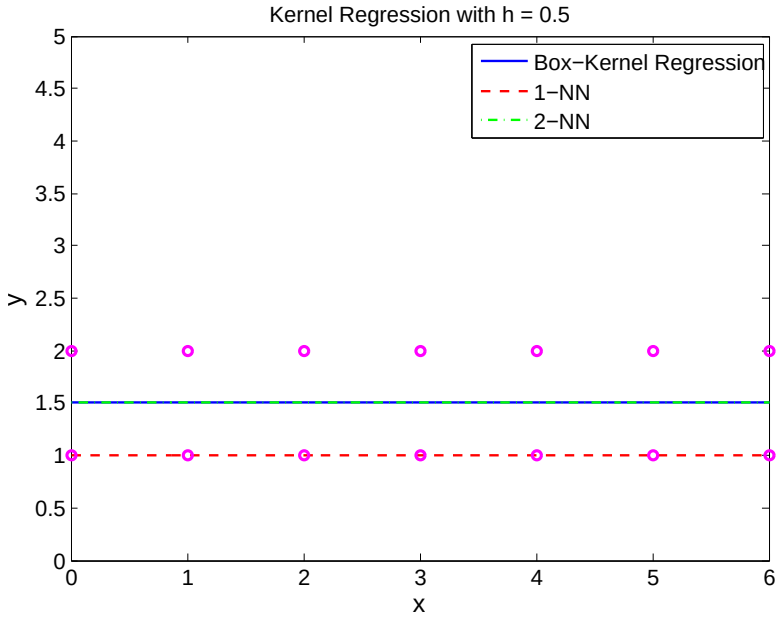
- Example 1



- Example 2



- Example 3: This example works if given a rule for 1-NN to break ties between two neighbors at the same distance from the test point, not average over both their values.



4 [14 Points] Model Selection

A central theme in machine learning is model selection. In this problem you will have the opportunity to demonstrate your understanding of various model selection techniques and their consequences. To make things more concrete we will consider the dataset $\mathcal{D}$ given in Equation 1 consisting of n independent identically distributed observations. The features of $\mathcal{D}$ consist of pairs $(x_1^i, x_2^i) \in \mathbb{R}^2$ and the observations $y^i \in \mathbb{R}$ are continuous valued.

$$\mathcal{D} = \{((x_1^1, x_2^1), y^1), ((x_1^2, x_2^2), y^2), \ldots, ((x_1^n, x_2^n), y^n)\} \tag{1}$$

Consider the abstract model given Equation 2. The function f_{θ_1,θ_2} is a mapping from the features in $\mathbb{R}^2$ to an observation in $\mathbb{R}^1$ which depends on two parameters θ_1 and θ_2. The ϵ^i correspond to the noise. Here we will assume that the $\epsilon^i \sim N(0, \sigma^2)$ are independent Gaussians with zero mean and variance σ^2.

$$y^i = f_{\theta_1,\theta_2}(x_1^i, x_2^i) + \epsilon^i \tag{2}$$

1. [4 Points] Show that the log likelihood of the data given the parameters is equal to Equation 3.

$$l(D; \theta_1, \theta_2) = -\frac{1}{2\sigma^2} \sum_{i=1}^{n} (y^i - f_{\theta_1,\theta_2}(x_1^i, x_2^i))^2 - n \log\left(\sqrt{2\pi}\sigma\right) \tag{3}$$

Recall the probability density function of the $N(\mu, \sigma^2)$ Gaussian distribution is given by Equation 4.

$$p(x) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right) \tag{4}$$

★ **SOLUTION:** The first thing one should think about is the probability of a single data point under this model. We can of coure write this as:

$$y^i - f_{\theta_1,\theta_2}(x_1^i, x_2^i) = \epsilon^i$$

Because we know the distribution of ϵ_i we know that:

$$y^i - f_{\theta_1,\theta_2}(x_1^i, x_2^i) \sim N(0, \sigma^2)$$

We can therefore write the likelihood of the data as:

$$\mathcal{L}(D; \theta_1\theta_2) = \prod_{i=1}^{n} \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(y^i - f_{\theta_1,\theta_2}(x_1^i, x_2^i))^2}{2\sigma^2}\right)$$

To compute the log likelihood we take the log of the likelihood from above to obtain:

$$\begin{aligned} l(D;\theta_1\theta_2) &= \log\left(\mathcal{L}(D;\theta_1\theta_2)\right) \\ &= \log\left(\prod_{i=1}^{n}\frac{1}{\sqrt{2\pi}\sigma}\exp\left(-\frac{\left(y^i - f_{\theta_1,\theta_2}(x_1^i,x_2^i)\right)^2}{2\sigma^2}\right)\right) \\ &= \sum_{i=1}^{n}\log\left(\frac{1}{\sqrt{2\pi}\sigma}\exp\left(-\frac{\left(y^i - f_{\theta_1,\theta_2}(x_1^i,x_2^i)\right)^2}{2\sigma^2}\right)\right) \\ &= \sum_{i=1}^{n}\left(-\log\left(\sqrt{2\pi}\sigma\right) - \frac{\left(y^i - f_{\theta_1,\theta_2}(x_1^i,x_2^i)\right)^2}{2\sigma^2}\right) \\ &= -n\log\left(\sqrt{2\pi}\sigma\right) - \frac{1}{2\sigma^2}\sum_{i=1}^{n}\left(y^i - f_{\theta_1,\theta_2}(x_1^i,x_2^i)\right)^2 \end{aligned}$$

2. [1 Point] If we disregard the parts that do not depend on f_{θ_1,θ_2} and Y the negative of the log-likelihood given in Equation 3 is equivalent to what commonly used loss function?

★ **SOLUTION:** The negative of the log likelihood is the square loss function. This is the loss function used in least squares regression.

3. [2 Points] Many common techniques used to find the maximum likelihood estimates of θ_1 and θ_2 rely on our ability to compute the gradient of the log-likelihood. Compute the gradient of the log likelihood with respect to θ_1 and θ_2. Express you answer in terms of:

$$y^i, \quad f_{\theta_1,\theta_2}(x_1^i,x_2^i), \quad \frac{\partial}{\partial\theta_1}f_{\theta_1,\theta_2}(x_1^i,x_2^i), \quad \frac{\partial}{\partial\theta_2}f_{\theta_1,\theta_2}(x_1^i,x_2^i)$$

★ **SOLUTION:** The important technique we use here is the chain rule. To save space I will take the gradient with respect to θ_j.

$$\begin{aligned} \frac{\partial}{\partial\theta_j}l(D;\theta_1,\theta_2) &= -\frac{1}{2\sigma^2}\sum_{i=1}^{n}\frac{\partial}{\partial\theta_j}(y^i - f_{\theta_1,\theta_2}(x_1^i,x_2^i))^2 \\ &= -\frac{1}{2\sigma^2}\sum_{i=1}^{n}2(y^i - f_{\theta_1,\theta_2}(x_1^i,x_2^i))\frac{\partial}{\partial\theta_j}\left(-f_{\theta_1,\theta_2}(x_1^i,x_2^i)\right) \\ &= \frac{1}{\sigma^2}\sum_{i=1}^{n}(y^i - f_{\theta_1,\theta_2}(x_1^i,x_2^i))\frac{\partial}{\partial\theta_j}f_{\theta_1,\theta_2}(x_1^i,x_2^i) \end{aligned}$$

■ **COMMON MISTAKE 1:** Many people forgot about the negative inside $(\cdot)^2$. This is very important as it would result in an algorithm that finds the minimal likelihood.

4. [2 Points] Given the learning rate η, what update rule would you use in gradient descent to *maximize* the likelihood.

★ **SOLUTION:** The tricky part about this problem is deciding whether to add or subtract the gradient. The easiest way to think about this is consider a simple line. If the slope is positive then adding the slope to the x value will result in a larger y value. Because we are trying to maximize the likelihood we will add the gradient:

$$\theta_j^{(t+1)} = \theta_j^{(t)} + \eta \frac{\partial}{\partial \theta_j} l(D; \theta_1, \theta_2) \tag{5}$$

■ **COMMON MISTAKE 1:** Many people had the sign backwards which is what we normally use when we are trying to *minimize* some loss function.

5. [3 Points] Suppose you are given some function h such that $h(\theta_1, \theta_2) \in \mathbb{R}$ is large when f_{θ_1,θ_2} is complicated and small when f_{θ_1,θ_2} is simple. Use the function h along with the negative log-likelihood to write down an expression for the regularized loss with parameter λ.

★ **SOLUTION:** For this problem we simply write the regularized loss as the negative log likelihood plus the regularization term:

$$loss_{reg}(D; \theta_1, \theta_2) = -l(D; \theta_1, \theta_2) + \lambda h(\theta_1, \theta_2) \tag{6}$$

Based on this equation we see that to minimize the loss we want to maximize the likelihood and minimize the model complexity.

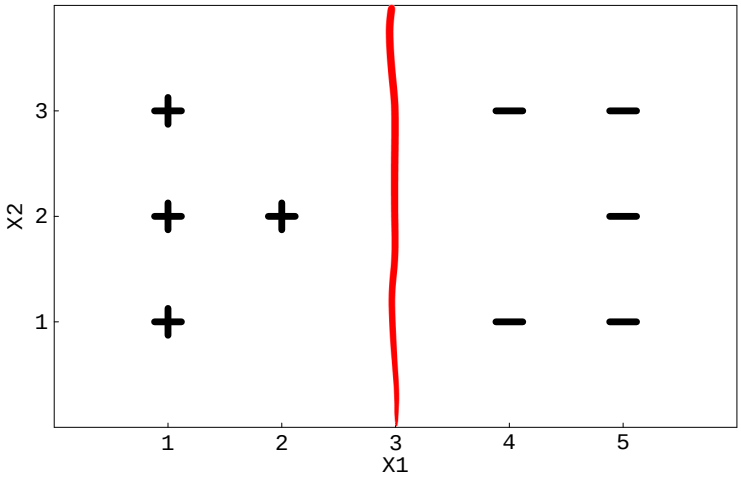
■ **COMMON MISTAKE 1:** Again, the signs are important here. Conceptually we want to minimize model complexity and maximize model fit (or likelihood). Since we always try to minimize the regularized loss we know that we want a negative sign on the likelihood and positive sign on the regularization term $h(\theta_1, \theta_2)$.

6. [2 Points] For small and large values of λ describe the bias variance trade off with respect to the regularized loss provided in the previous part.

★ **SOLUTION:** As we increase the value of λ we place a greater penalty on model complexity resulting in simpler models, more model bias, and less model variance. Alternatively, if we decrease the value of λ then we permit more complex models resulting in less model bias and greater model variance.

5 [12 points] Support Vector Machine

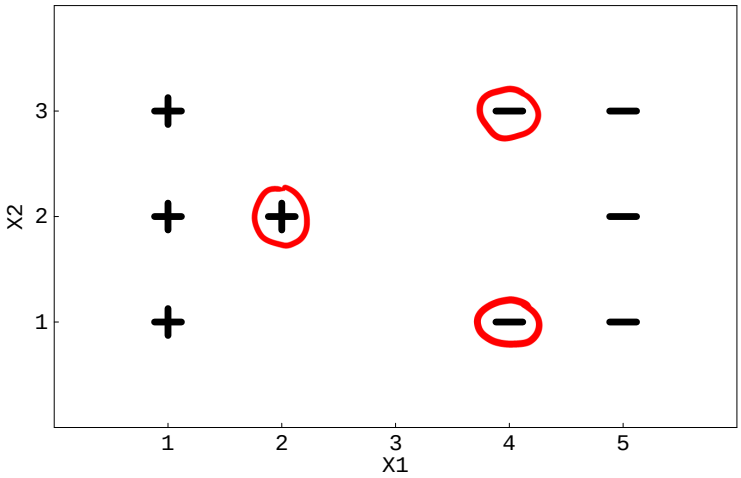
1. [2 points] Suppose we are using a linear SVM (i.e., no kernel), with some large C value, and are given the following data set.



Draw the decision boundary of linear SVM. Give a brief explanation.

★ **SOLUTION:** Because of the large C value, the decision boundary will classify all of the examples correctly. Furthermore, among separators that classify the examples correctly, it will have the largest margin (distance to closest point).

2. [3 points] In the following image, circle the points such that removing that example from the training set and retraining SVM, we would get a different decision boundary than training on the full sample.



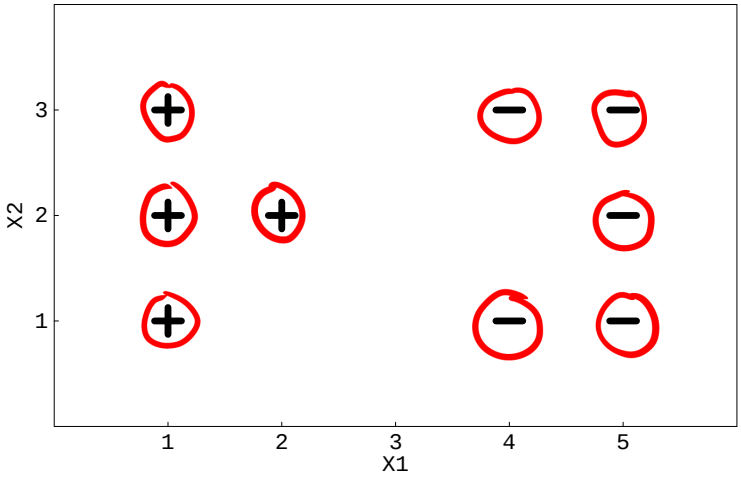
You do not need to provide a formal proof, but give a one or two sentence explanation.

★ **SOLUTION:** These examples are the support vectors; all of the other examples are such that their corresponding constraints are not tight in the optimization problem, so removing them will not create a solution with smaller objective function value (norm of w). These three examples are positioned such that removing any one of them introduces slack in the constraints, allowing for a solution with a smaller objective function value and with a different third support vector; in this case, because each of these new (replacement) support vectors is not close to the old separator, the decision boundary shifts to make its distance to that example equal to the others.

3. [3 points] Suppose instead of SVM, we use regularized logistic regression to learn the classifier. That is,

$$(w, b) = \arg \min_{w \in \mathbb{R}^2, b \in \mathbb{R}} \frac{\|w\|^2}{2} - \sum_i \mathbb{1}[y^{(i)} = 0] \ln \frac{1}{1 + e^{(w \cdot x^{(i)} + b)}} + \mathbb{1}[y^{(i)} = 1] \ln \frac{e^{(w \cdot x^{(i)} + b)}}{1 + e^{(w \cdot x^{(i)} + b)}}.$$

In the following image, circle the points such that removing that example from the training set and running regularized logistic regression, we would get a different decision boundary than training with regularized logistic regression on the full sample.



You do not need to provide a formal proof, but give a one or two sentence explanation.

★ **SOLUTION:** Because of the regularization, the weights will not diverge to infinity, and thus the probabilities at the solution are not at 0 and 1. Because of this, *every* example contributes to the loss function, and thus has an influence on the solution.

4. [4 points] Suppose we have a kernel $K(\cdot, \cdot)$, such that there is an implicit high-dimensional feature map $\phi : \mathbb{R}^d \to \mathbb{R}^D$ that satisfies $\forall x, z \in \mathbb{R}^d,\ K(x, z) = \phi(x) \cdot \phi(z)$, where $\phi(x) \cdot \phi(z) = \sum_{i=1}^{D} \phi(x)_i \phi(z)_i$ is the dot product in the D-dimensional space.

   Show how to calculate the Euclidean distance in the D-dimensional space

$$\|\phi(x) - \phi(z)\| = \sqrt{\sum_{i=1}^{D} (\phi(x)_i - \phi(z)_i)^2}$$

   without explicitly calculating the values in the D-dimensional vectors. For this question, you should provide a formal proof.

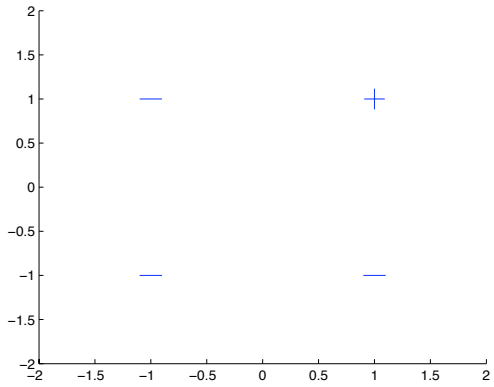
★ SOLUTION:

$$\begin{aligned}
\|\phi(x) - \phi(z)\| &= \sqrt{\sum_{i=1}^{D} (\phi(x)_i - \phi(z)_i)^2} \\
&= \sqrt{\sum_{i=1}^{D} \phi(x)_i^2 + \phi(z)_i^2 - 2\phi(x)_i \phi(z)_i} \\
&= \sqrt{\left(\sum_{i=1}^{D} \phi(x)_i^2\right) + \left(\sum_{i=1}^{D} \phi(z)_i^2\right) - \left(\sum_{i=1}^{D} 2\phi(x)_i \phi(z)_i\right)} \\
&= \sqrt{\phi(x) \cdot \phi(x) + \phi(z) \cdot \phi(z) - 2\phi(x) \cdot \phi(z)} \\
&= \sqrt{K(x, x) + K(z, z) - 2K(x, z)}.
\end{aligned}$$

6 [30 points] Decision Tree and Ensemble Methods

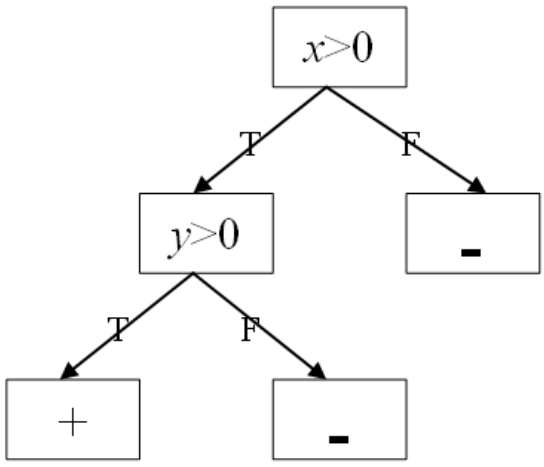
An ensemble classifier $H_T(x)$ is a collection of T weak classifiers $h_t(x)$, each with some weight α_t, $t = 1, \ldots, T$. Given a data point $x \in \mathbb{R}^d$, $H_T(x)$ predicts its label based on the weighted majority vote of the ensemble. In the binary case where the class label is either 1 or -1, $H_T(x) = \text{sgn}(\sum_{t=1}^{T} \alpha_t h_t(x))$, where $h_t(x) : \mathbb{R}^d \to \{-1, 1\}$, and $\text{sgn}(z) = 1$ if $z > 0$ and $\text{sgn}(z) = -1$ if $z \leq 0$. Boosting is an example of ensemble classifiers where the weights are calculated based on the training error of the weak classifier on the weighted training set.

1. [10 points] For the following data set,



- Describe a binary decision tree with the minimum depth and consistent with the data;

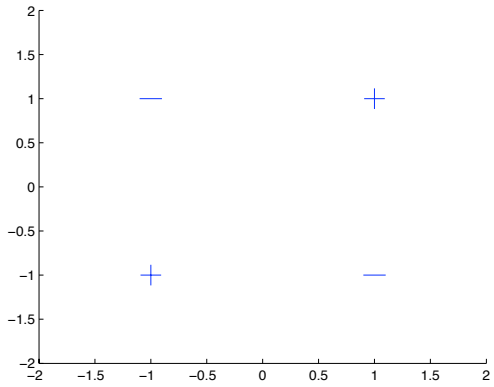
  ★ **SOLUTION:** The decision tree is as follows.



- Describe an ensemble classifier $H_2(x)$ with 2 weak classifiers that is consistent with the data. The weak classifiers should be simple decision stumps. Specify the weak classifiers and their weights.

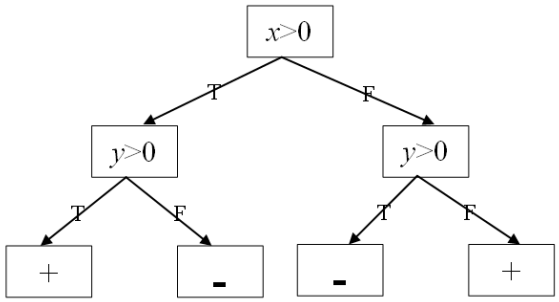
  ★ **SOLUTION:** $h_1(x) = \text{sgn}(x), \alpha_1 = 1, h_2(x) = \text{sgn}(y), \alpha_2 = 1.$

2. [10 points] For the following XOR data set,

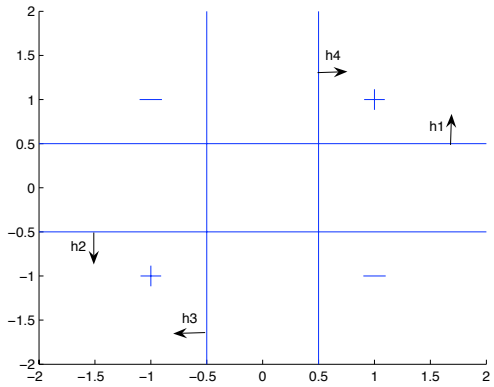


- Describe a binary decision tree with the minimum depth and consistent with the data;

  ★ **SOLUTION:** The decision tree is as follows.



- Let the ensemble classifier consist of the four binary classifiers shown below (the arrow means that the corresponding classifier classifies every data point in that direction as +), prove that there are no weights $\alpha_1, \ldots, \alpha_4$, that make the ensemble classifier consistent with the data.



★ **SOLUTION:** Based on the binary classifiers, we have the following inequalities.

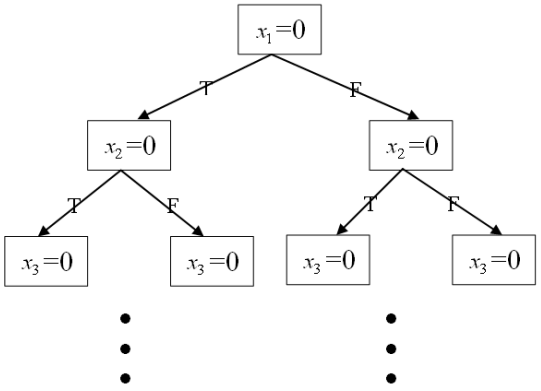
$$\alpha_1 - \alpha_2 - \alpha_3 + \alpha_4 > 0$$
$$-\alpha_1 + \alpha_2 - \alpha_3 + \alpha_4 \leq 0$$
$$-\alpha_1 + \alpha_2 + \alpha_3 - \alpha_4 > 0$$
$$\alpha_1 - \alpha_2 + \alpha_3 - \alpha_4 \leq 0$$

Apparently, the first and third equations can not be satisfied at the same time. Therefore, there are no weights $\alpha_1, \ldots, \alpha_4$, that make the ensemble classifier consistent with the data.

3. [10 points] Suppose that for each data point, the feature vector $x \in \{0,1\}^m$, i.e., x consists of m binary valued features, the class label $y \in \{-1,1\}$, and the true classifier is a majority vote over the features, i.e. $y = \text{sgn}(\sum_{i=1}^{m}(2x_i - 1))$, where x_i is the i^{th} component of the feature vector.

- Describe a binary decision tree with the minimum depth and consistent with the data. How many leaves does it have?

  ★ **SOLUTION:** The decision tree looks as follows.



  Any answers between $2^{\frac{m}{2}}$ and 2^m will get full points.

- Describe an ensemble classifier with the minimum number of weak classifiers. Specify the weak classifiers and their weights.

  ★ **SOLUTION:** The ensemble classifier has m weak classifiers. $h_i(x) = 2x_i - 1, \alpha_i = 1, i = 1, \ldots, m$