

# 15-213

*“The course that gives CMU its Zip!”*

## Synchronization

### November 19, 2008

#### Topics

- Synchronizing with semaphores
- Races and deadlocks
- Thread safety and reentrancy

# badcnt.c: An Improperly Synchronized Threaded Program

```
/* shared */
volatile unsigned int cnt = 0;
#define NITERS 100000000

int main() {
    pthread_t tid1, tid2;
    Pthread_create(&tid1, NULL,
                  count, NULL);
    Pthread_create(&tid2, NULL,
                  count, NULL);

    Pthread_join(tid1, NULL);
    Pthread_join(tid2, NULL);

    if (cnt != (unsigned)NITERS*2)
        printf("BOOM! cnt=%d\n",
              cnt);
    else
        printf("OK cnt=%d\n",
              cnt);
}
```

```
/* thread routine */
void *count(void *arg) {
    int i;
    for (i=0; i<NITERS; i++)
        cnt++;
    return NULL;
}
```

```
linux> ./badcnt
BOOM! cnt=198841183

linux> ./badcnt
BOOM! cnt=198261801

linux> ./badcnt
BOOM! cnt=198269672
```

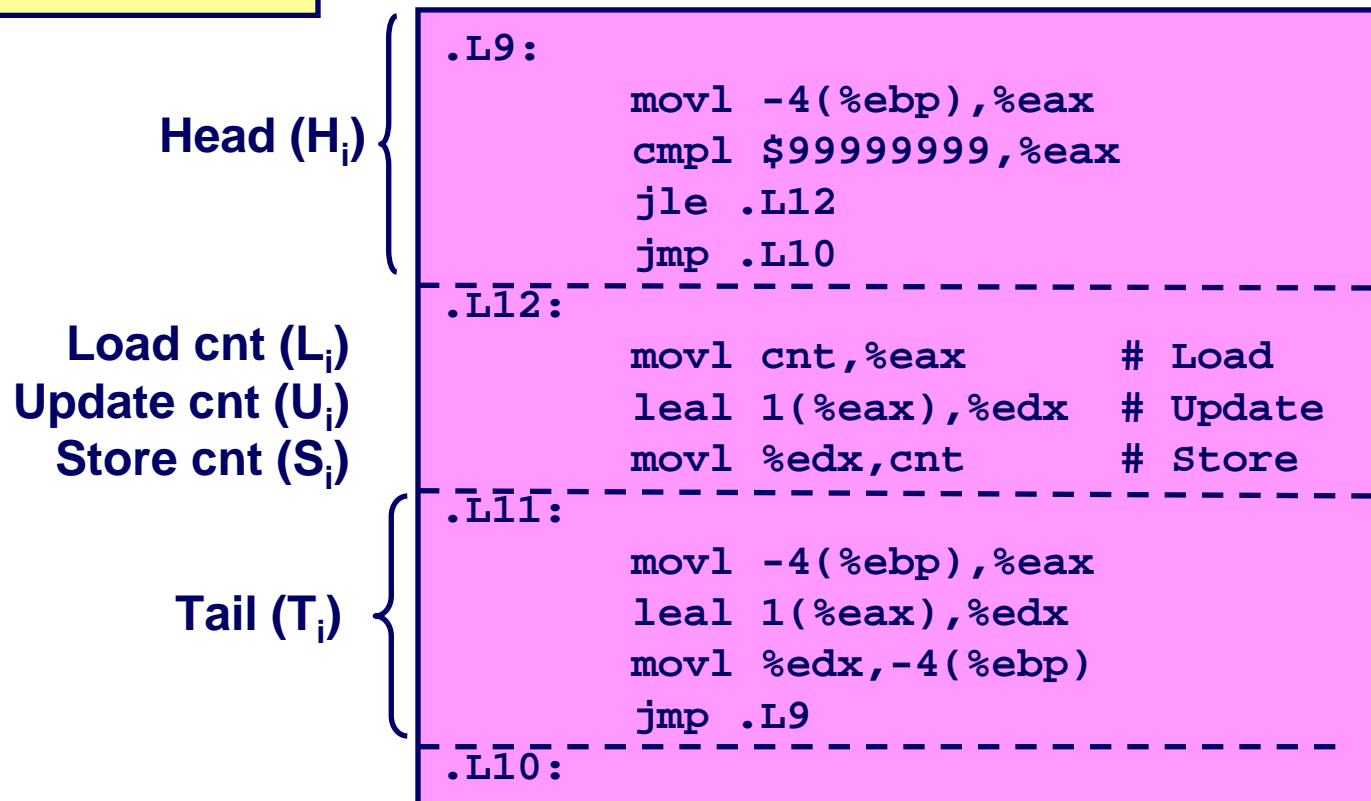
**cnt should be  
equal to 200,000,000.  
What went wrong?!**

# Assembly Code for Counter Loop

## C code for counter loop

```
for (i=0; i<NITERS; i++)  
    cnt++;
```

## Corresponding asm code



# Concurrent Execution

**Key idea: In general, any sequentially consistent interleaving is possible, but some are incorrect!**

- $I_i$  denotes that thread  $i$  executes instruction  $I$
- $\%eax_i$  is the contents of  $\%eax$  in thread  $i$ 's context

$i$ (thread)	$instr_i$	$\%eax_1$	$\%eax_2$	cnt
1	$H_1$	-	-	0
1	$L_1$	0	-	0
1	$U_1$	1	-	0
1	$S_1$	1	-	1
2	$H_2$	-	-	1
2	$L_2$	-	1	1
2	$U_2$	-	2	1
2	$S_2$	-	2	2
2	$T_2$	-	2	2
1	$T_1$	1	-	2

OK

# Concurrent Execution (cont)

**Incorrect ordering: two threads increment the counter, but the result is 1 instead of 2.**

i (thread)	instr <sub>i</sub>	%eax <sub>1</sub>	%eax <sub>2</sub>	cnt
1	H <sub>1</sub>	-	-	0
1	L <sub>1</sub>	0	-	0
1	U <sub>1</sub>	1	-	0
2	H <sub>2</sub>	-	-	0
2	L <sub>2</sub>	-	0	0
1	S <sub>1</sub>	1	-	1
1	T <sub>1</sub>	1	-	1
2	U <sub>2</sub>	-	1	1
2	S <sub>2</sub>	-	1	1
2	T <sub>2</sub>	-	1	1

**Oops!**

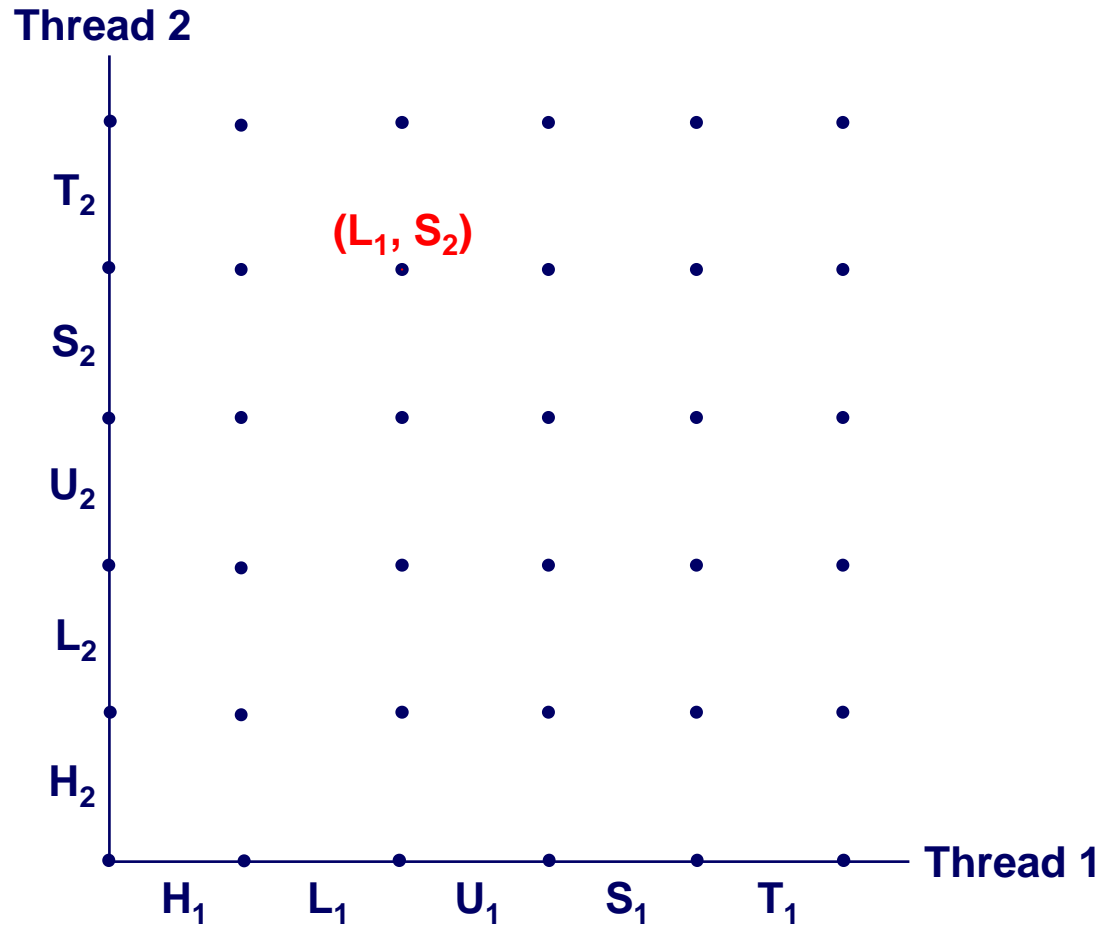
# Concurrent Execution (cont)

How about this ordering?

i (thread)	instr <sub>i</sub>	%eax <sub>1</sub>	%eax <sub>2</sub>	cnt
1	H <sub>1</sub>			
1	L <sub>1</sub>			
2	H <sub>2</sub>			
2	L <sub>2</sub>			
2	U <sub>2</sub>			
2	S <sub>2</sub>			
1	U <sub>1</sub>			
1	S <sub>1</sub>			
1	T <sub>1</sub>			
2	T <sub>2</sub>			

We can clarify our understanding of concurrent execution with the help of the *progress graph*

# Progress Graphs



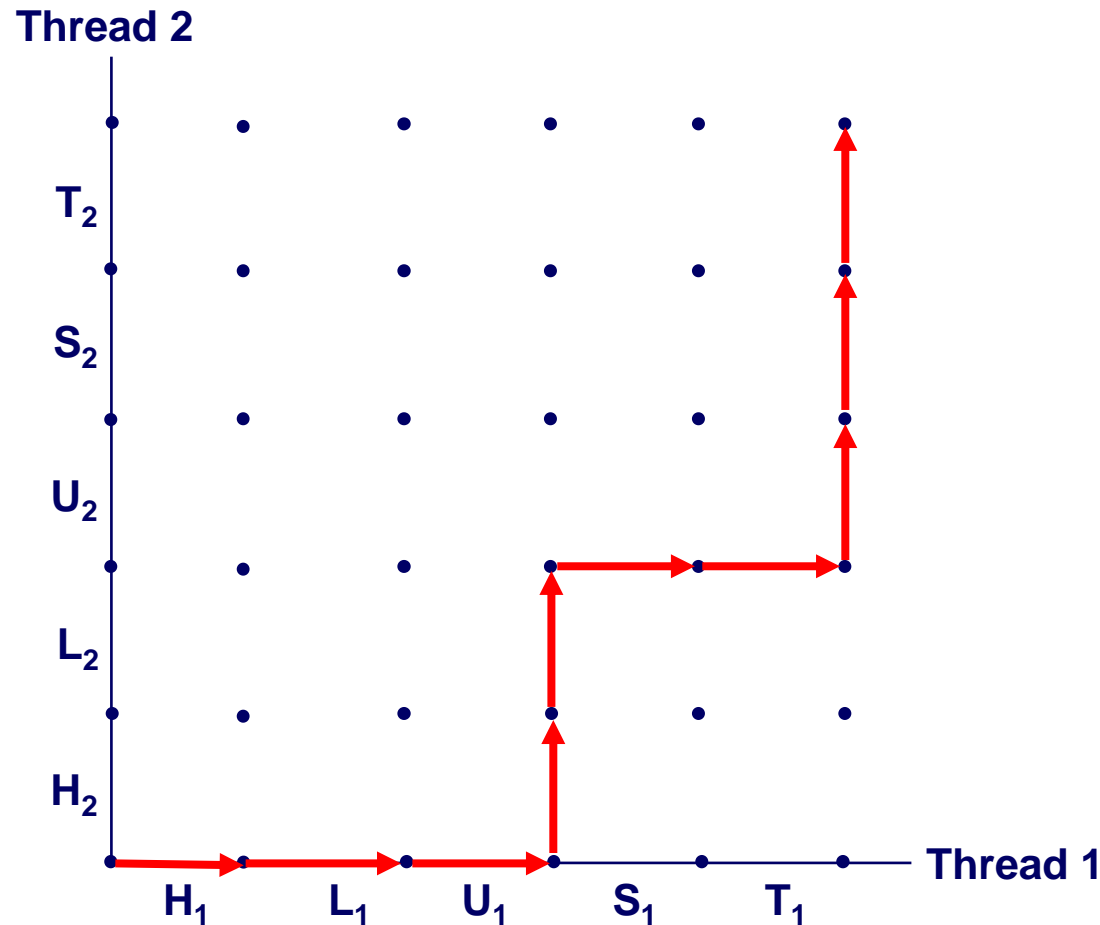
A **progress graph** depicts the discrete **execution state space** of concurrent threads.

Each axis corresponds to the sequential order of instructions in a thread.

Each point corresponds to a possible **execution state** (Inst<sub>1</sub>, Inst<sub>2</sub>).

E.g., (L<sub>1</sub>, S<sub>2</sub>) denotes state where thread 1 has completed L<sub>1</sub> and thread 2 has completed S<sub>2</sub>.

# Trajectories in Progress Graphs



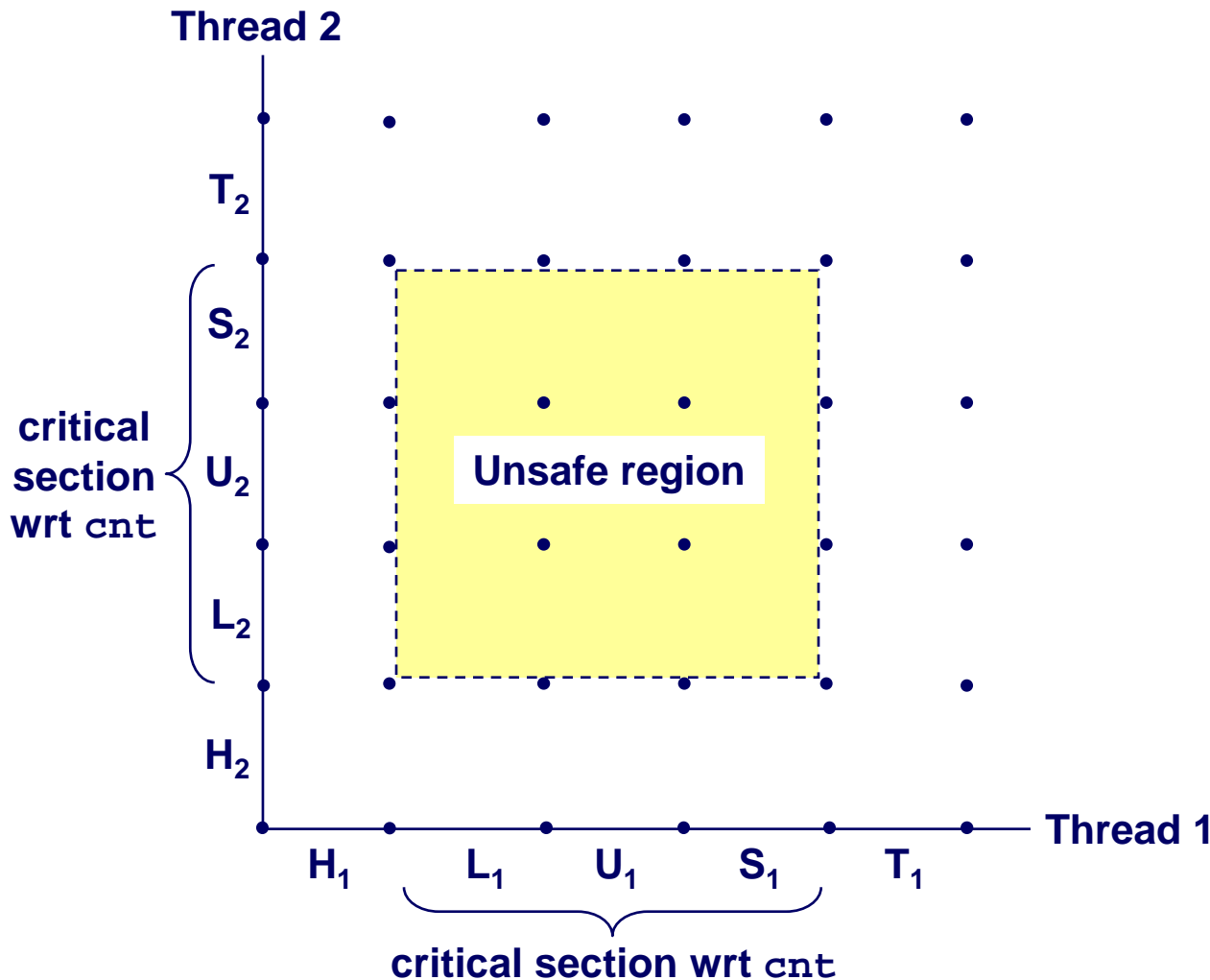
A *trajectory* is a sequence of legal state transitions that describes one possible concurrent execution of the threads.

Example:

H<sub>1</sub>, L<sub>1</sub>, U<sub>1</sub>, H<sub>2</sub>, L<sub>2</sub>,  
S<sub>1</sub>, T<sub>1</sub>, U<sub>2</sub>, S<sub>2</sub>, T<sub>2</sub>



# Critical Sections and Unsafe Regions

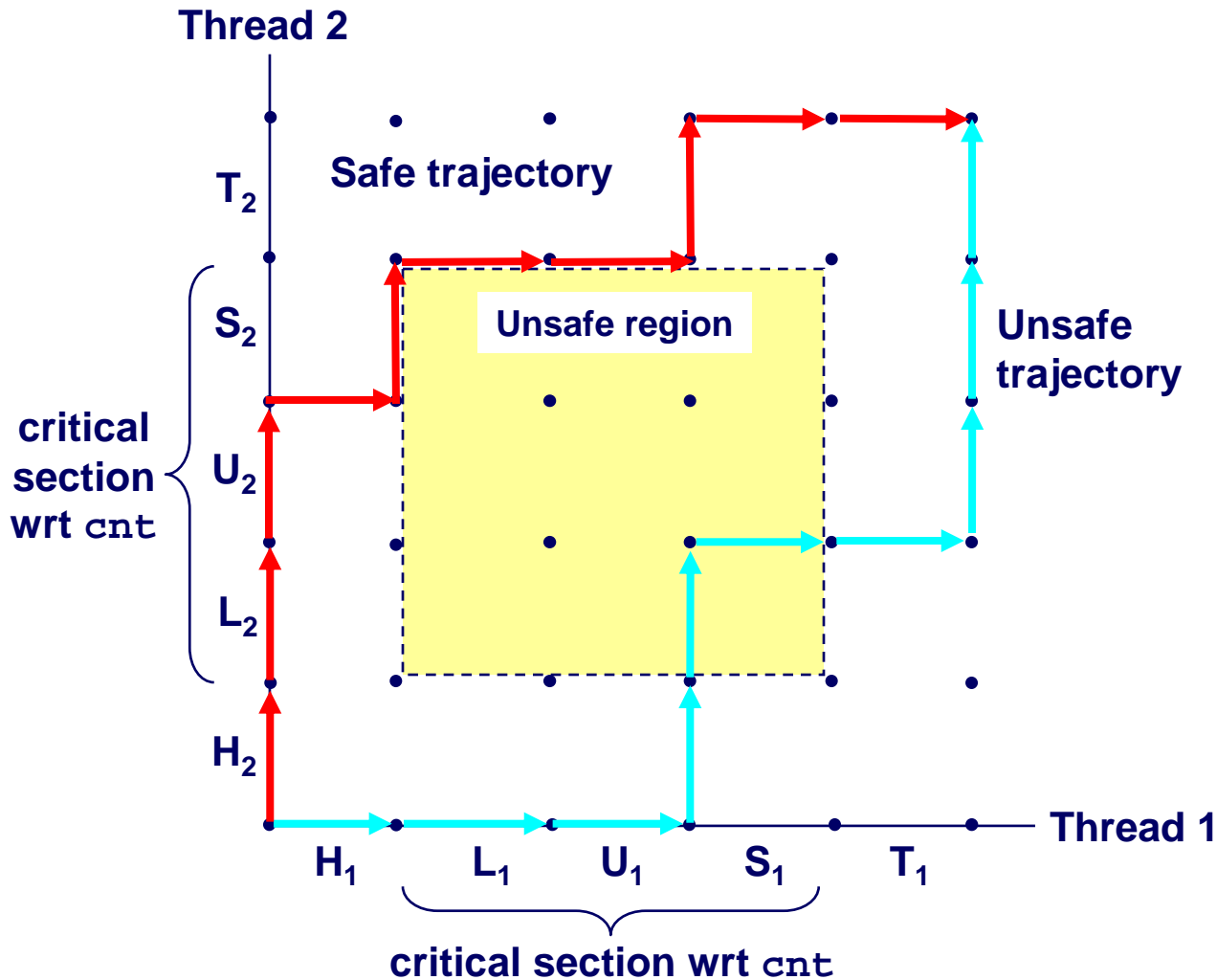


L, U, and S form a **critical section** with respect to the shared variable `cnt`.

Instructions in critical sections (wrt to some shared variable) should not be interleaved.

Sets of states where such interleaving occurs form **unsafe regions**.

# Safe and Unsafe Trajectories



**Def:** A trajectory is **safe** iff it doesn't touch any part of an unsafe region.

**Claim:** A trajectory is correct (wrt cnt) iff it is safe.

# Semaphores

**Question:** How can we guarantee a safe trajectory?

- We must **synchronize** the threads so that they never enter an unsafe state.

**Classic solution:** Dijkstra's P and V operations on semaphores.

- **semaphore:** non-negative integer synchronization variable
  - P(s): [ while (s == 0) wait(); s--; ]
    - » Dutch for "Proberen" (test)
  - V(s): [ s++; ]
    - » Dutch for "Verhogen" (increment)
- OS guarantees that operations between brackets [ ] are executed indivisibly
  - Only one P or V operation at a time can modify s
  - When while loop in P terminates, only that P can decrement s

**Semaphore invariant:  $(s \geq 0)$**

# Locking with Semaphores

Here is one way we could use P and V operations to synchronize the threads that update cnt

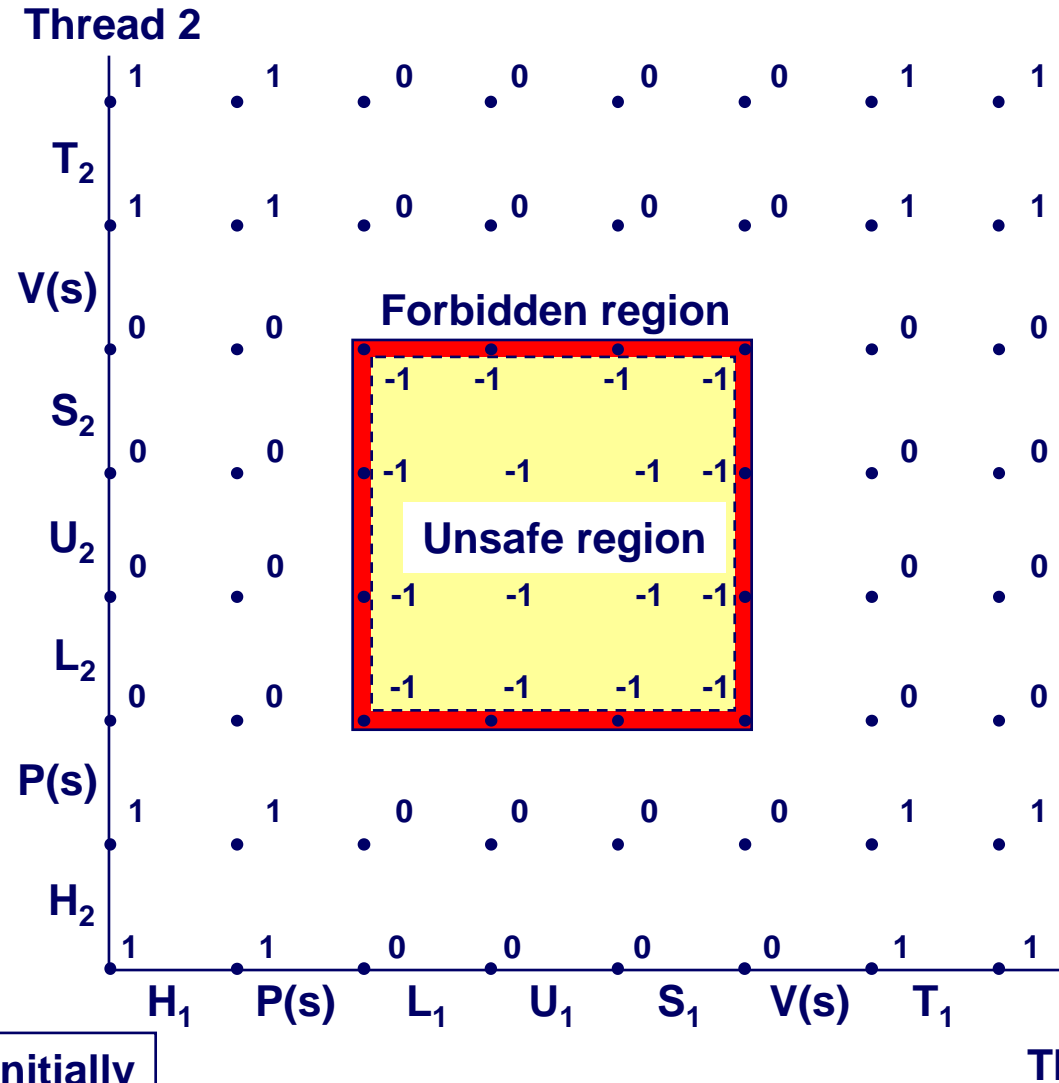
- Semaphore used like this referred to as a “lock”

```
/* Semaphore s is initially 1 */

/* Thread routine */
void *count(void *arg)
{
    int i;

    for (i=0; i<NITERS; i++) {
        P(s);
        cnt++;
        V(s);
    }
    return NULL;
}
```

# Safe Sharing With Locks



Provide mutually exclusive access to shared variable by surrounding critical section with P and V operations on semaphore  $s$  (initially set to 1).

Semaphore invariant creates a *forbidden region* that encloses unsafe region and is never touched by any trajectory.

# Wrappers on POSIX Semaphores

```
/* Initialize semaphore sem to value */
/* pshared=0 if thread, pshared=1 if process */
void Sem_init(sem_t *sem, int pshared, unsigned int value) {
    if (sem_init(sem, pshared, value) < 0)
        unix_error("Sem_init");
}

/* P operation on semaphore sem */
void P(sem_t *sem) {
    if (sem_wait(sem))
        unix_error("P");
}

/* V operation on semaphore sem */
void V(sem_t *sem) {
    if (sem_post(sem))
        unix_error("V");
}
```

# Sharing With POSIX Semaphores

```
/* properly sync'd counter program */
#include "csapp.h"
#define NITERS 10000000

volatile unsigned int cnt;
sem_t sem;          /* semaphore */

int main() {
    pthread_t tid1, tid2;

    Sem_init(&sem, 0, 1); /* sem=1 */

    /* create 2 threads and wait */
    ...

    if (cnt != (unsigned)NITERS*2)
        printf("BOOM! cnt=%d\n", cnt);
    else
        printf("OK cnt=%d\n", cnt);
    exit(0);
}
```

```
/* thread routine */
void *count(void *arg)
{
    int i;

    for (i=0; i<NITERS; i++) {
        P(&sem);
        cnt++;
        V(&sem);
    }
    return NULL;
}
```

**Warning:**

**It's really slow!**

# One worry: races

A **race** occurs when the correctness of the program depends on one thread reaching point x before another thread reaches point y

```
/* a threaded program with a race */
int main() {
    pthread_t tid[N];
    int i;
    for (i = 0; i < N; i++)
        Pthread_create(&tid[i], NULL, thread, &i);
    for (i = 0; i < N; i++)
        Pthread_join(tid[i], NULL);
    exit(0);
}

/* thread routine */
void *thread(void *vargp) {
    int myid = *((int *)vargp);
    printf("Hello from thread %d\n", myid);
    return NULL;
}
```



# Race Elimination

Make sure don't have unintended sharing of state

```
/* a threaded program with a race */
int main() {
    pthread_t tid[N];
    int i;
    for (i = 0; i < N; i++) {
        int *valp = malloc(sizeof(int));
        *valp = i;
        Pthread_create(&tid[i], NULL, thread, valp);
    }
    for (i = 0; i < N; i++)
        Pthread_join(tid[i], NULL);
    exit(0);
}

/* thread routine */
void *thread(void *vargp) {
    int myid = *((int *)vargp);
    free(vargp);
    printf("Hello from thread %d\n", myid);
    return NULL;
}
```

# Another worry: Deadlock

- Processes wait for condition that will never be true

## Typical Scenario

- Processes 1 and 2 needs two resources (A and B) to proceed
- Process 1 acquires A, waits for B
- Process 2 acquires B, waits for A
- Both will wait forever!

# Deadlocking With POSIX Semaphores

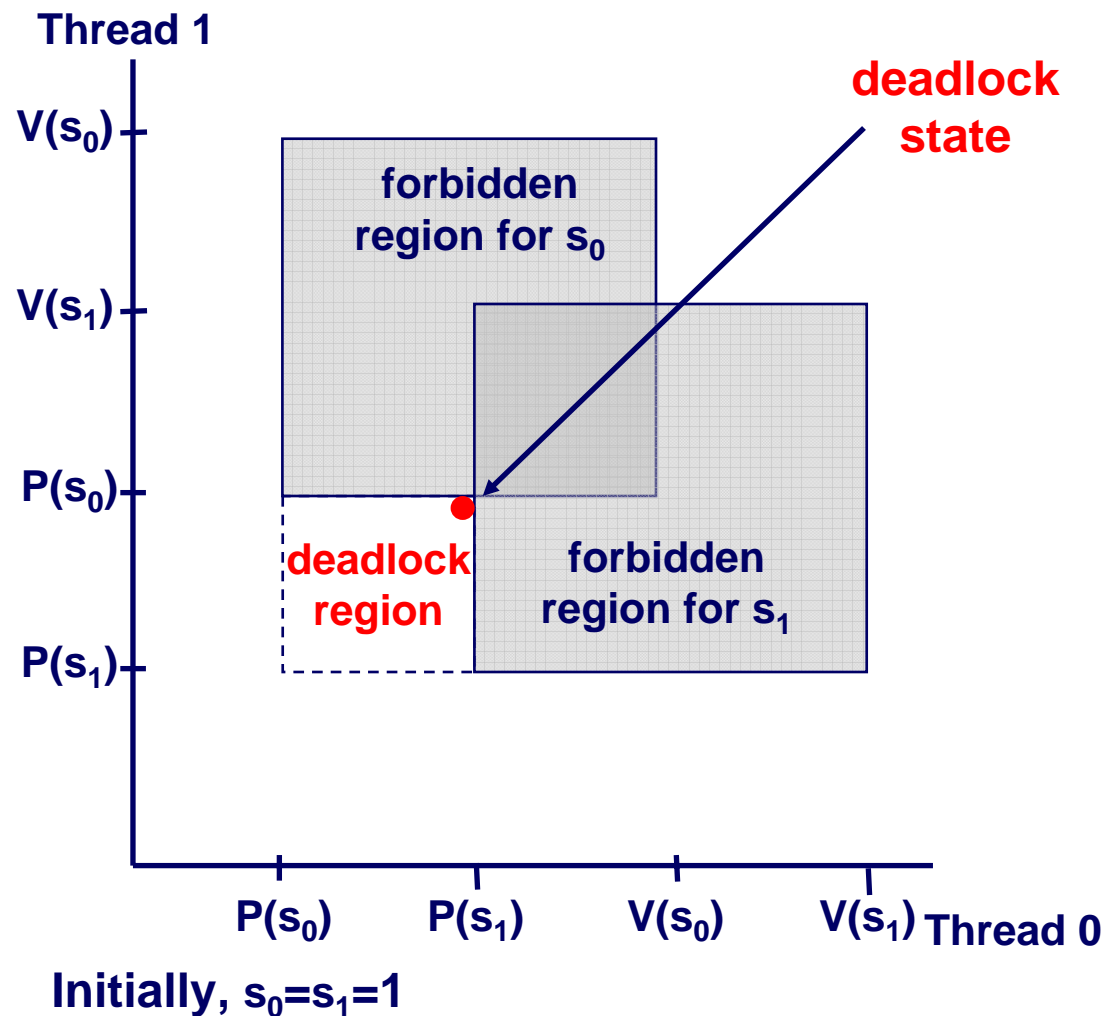
```
int main()
{
    pthread_t tid[2];
    Sem_init(&mutex[0], 0, 1); /* mutex[0] = 1 */
    Sem_init(&mutex[1], 0, 1); /* mutex[1] = 1 */
    Pthread_create(&tid[0], NULL, count, (void*) 0);
    Pthread_create(&tid[1], NULL, count, (void*) 1);
    Pthread_join(tid[0], NULL);
    Pthread_join(tid[1], NULL);
    printf("cnt=%d\n", cnt);
    exit(0);
}
```

```
void *count(void *vargp)
{
    int i;
    int id = (int) vargp;
    for (i = 0; i < NITERS; i++) {
        P(&mutex[id]); P(&mutex[1-id]);
        cnt++;
        V(&mutex[id]); V(&mutex[1-id]);
    }
    return NULL;
}
```

Tid[0]:  
P(s<sub>0</sub>);  
P(s<sub>1</sub>);  
cnt++;  
V(s<sub>0</sub>);  
V(s<sub>1</sub>);

Tid[1]:  
P(s<sub>1</sub>);  
P(s<sub>0</sub>);  
cnt++;  
V(s<sub>1</sub>);  
V(s<sub>0</sub>);

# Deadlock



Locking introduces the potential for **deadlock**: waiting for a condition that will never be true.

Any trajectory that enters the **deadlock region** will eventually reach the **deadlock state**, waiting for either  $s_0$  or  $s_1$  to become nonzero.

Other trajectories luck out and skirt the deadlock region.

Unfortunate fact: deadlock is often non-deterministic.

# Avoiding Deadlock

```
int main()
{
    pthread_t tid[2];
    Sem_init(&mutex[0], 0, 1); /* mutex[0] = 1 */
    Sem_init(&mutex[1], 0, 1); /* mutex[1] = 1 */
    Pthread_create(&tid[0], NULL, count, (void*) 0);
    Pthread_create(&tid[1], NULL, count, (void*) 1);
    Pthread_join(tid[0], NULL);
    Pthread_join(tid[1], NULL);
    printf("cnt=%d\n", cnt);
    exit(0);
}
```

```
void *count(void *vargp)
{
    int i;
    int id = (int) vargp;
    for (i = 0; i < NITERS; i++) {
        P(&mutex[0]); P(&mutex[1]);
        cnt++;
        V(&mutex[id]); V(&mutex[1-id]);
    }
    return NULL;
}
```

Tid[0]:  
P(s<sub>0</sub>);  
P(s<sub>1</sub>);  
cnt++;  
V(s<sub>0</sub>);  
V(s<sub>1</sub>);

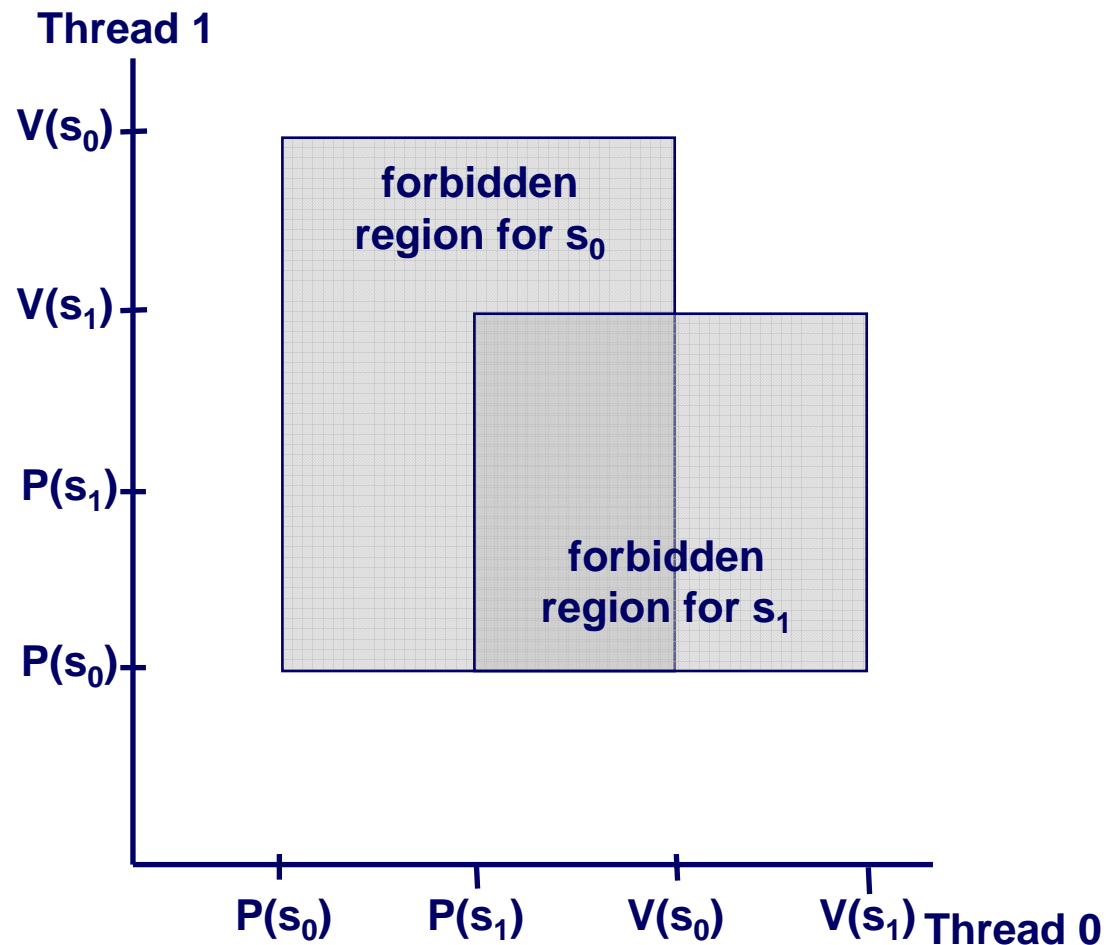
Tid[1]:  
P(s<sub>0</sub>);  
P(s<sub>1</sub>);  
cnt++;  
V(s<sub>1</sub>);  
V(s<sub>0</sub>);

# Removed Deadlock

No way for trajectory to get stuck

Processes acquire locks in same order

Order in which locks released immaterial



Initially,  $s_0=s_1=1$

# Crucial concept: Thread Safety

Functions called from a thread (without external synchronization) must be *thread-safe*

- i.e., it must be safe for multiple threads to be calling it concurrently

Some examples of thread-unsafe functions:

- Failing to protect shared variables
- Relying on persistent state across invocations
- Returning a pointer to a static variable
- Calling thread-unsafe functions

# Thread-Unsafe Functions (1)

## Failing to protect shared variables

- **Fix: Use P and V semaphore operations**
- **Example: `goodcnt.c`**
- **Issue: Synchronization operations will slow down code**
  - e.g., `badcnt` requires 0.5s, `goodcnt` requires 7.9s



# Thread-Unsafe Functions (2)

## Relying on persistent state across multiple function invocations

- Example: Random number generator that relies on static state

```
/* rand - return pseudo-random integer on 0..32767 */
static unsigned int next = 1;
int rand(void)
{
    next = next*1103515245 + 12345;
    return (unsigned int)(next/65536) % 32768;
}

/* srand - set seed for rand() */
void srand(unsigned int seed)
{
    next = seed;
}
```

# Making Thread-Safe RNG

## Pass state as part of argument

- and, thereby, eliminate static state

```
/* rand - return pseudo-random integer on 0..32767 */  
  
int rand_r(int *nextp)  
{  
    *nextp = *nextp*1103515245 + 12345;  
    return (unsigned int)(*nextp/65536) % 32768;  
}
```

- Consequence: programmer using rand must maintain seed

# Thread-Unsafe Functions (cont)

Returning a ptr to a static variable

Fixes:

- 1. Rewrite code so caller passes pointer to struct

- » Issue: Requires changes in caller and callee

```
struct hostent
*gethostbyname(char name)
{
    static struct hostent h;
    <contact DNS and fill in h>
    return &h;
}
```

```
hostp = Malloc(...);
gethostbyname_r(name, hostp);
```

- 2. *Lock-and-copy*

- » Issue: Requires only simple changes in caller (and none in callee)
- » However, caller must free memory

```
struct hostent
*gethostbyname_ts(char *name)
{
    struct hostent *q = Malloc(...);
    struct hostent *p;
    P(&mutex); /* lock */
    p = gethostbyname(name);
    *q = *p; /* copy */
    V(&mutex);
    return q;
}
```

# Thread-Unsafe Functions

## Calling thread-unsafe functions

- Calling one thread-unsafe function makes the entire function that calls it thread-unsafe
- Fix: Modify the function so it calls only thread-safe functions 😊

# Thread-Safe Library Functions

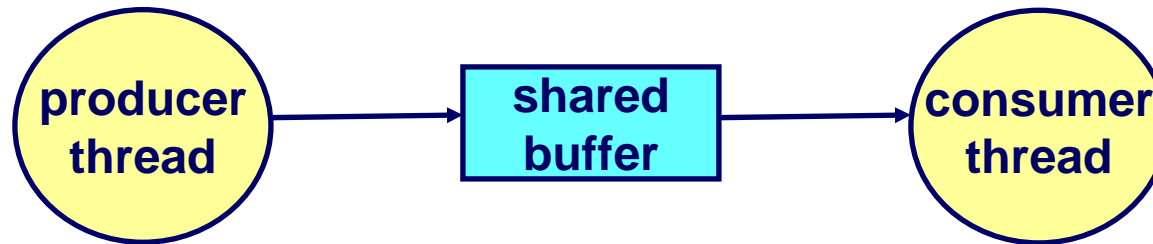
All functions in the Standard C Library (at the back of your K&R text) are thread-safe

- Examples: `malloc`, `free`, `printf`, `scanf`

Most Unix system calls are thread-safe, with a few exceptions:

Thread-unsafe function	Class	Reentrant version
<code>asctime</code>	3	<code>asctime_r</code>
<code>ctime</code>	3	<code>ctime_r</code>
<code>gethostbyaddr</code>	3	<code>gethostbyaddr_r</code>
<code>gethostbyname</code>	3	<code>gethostbyname_r</code>
<code>inet_ntoa</code>	3	(none)
<code>localtime</code>	3	<code>localtime_r</code>
<code>rand</code>	2	<code>rand_r</code>

# Notifying With Semaphores



## Common synchronization pattern:

- Producer waits for slot, inserts item in buffer, and notifies consumer
- Consumer waits for item, removes it from buffer, and notifies producer

## Examples

- Multimedia processing:
  - Producer creates MPEG video frames, consumer renders them
- Event-driven graphical user interfaces
  - Producer detects mouse clicks, mouse movements, and keyboard hits and inserts corresponding events in buffer
  - Consumer retrieves events from buffer and paints the display

# Producer-Consumer on a Buffer That Holds One Item

```
/* buf1.c - producer-consumer
on 1-element buffer */
#include "csapp.h"

#define NITERS 5

void *producer(void *arg);
void *consumer(void *arg);

struct {
    int buf; /* shared var */
    sem_t full; /* sems */
    sem_t empty;
} shared;
```

```
int main() {
    pthread_t tid_producer;
    pthread_t tid_consumer;

    /* initialize the semaphores */
    Sem_init(&shared.empty, 0, 1);
    Sem_init(&shared.full, 0, 0);

    /* create threads and wait */
    Pthread_create(&tid_producer, NULL,
                  producer, NULL);
    Pthread_create(&tid_consumer, NULL,
                  consumer, NULL);
    Pthread_join(tid_producer, NULL);
    Pthread_join(tid_consumer, NULL);

    exit(0);
}
```

# Producer-Consumer (cont)

Initially: empty = 1, full = 0.

```
/* producer thread */
void *producer(void *arg) {
    int i, item;

    for (i=0; i<NITERS; i++) {
        /* produce item */
        item = i;
        printf("produced %d\n",
              item);

        /* write item to buf */
        P(&shared.empty);
        shared.buf = item;
        V(&shared.full);
    }
    return NULL;
}
```

```
/* consumer thread */
void *consumer(void *arg) {
    int i, item;

    for (i=0; i<NITERS; i++) {
        /* read item from buf */
        P(&shared.full);
        item = shared.buf;
        V(&shared.empty);

        /* consume item */
        printf("consumed %d\n",
              item);
    }
    return NULL;
}
```



# Counting with Semaphores

Remember, it's a non-negative integer

- So, values greater than 1 are legal

Lets repeat thing\_5() 5 times for every 3 of thing\_3()

```
/* thing_5 and thing_3 */
#include "csapp.h"

sem_t five;
sem_t three;

void *five_times(void *arg);
void *three_times(void *arg);
```

```
int main() {
    pthread_t tid_five, tid_three;

    /* initialize the semaphores */
    Sem_init(&five, 0, 5);
    Sem_init(&three, 0, 3);

    /* create threads and wait */
    Pthread_create(&tid_five, NULL,
                  five_times, NULL);
    Pthread_create(&tid_three, NULL,
                  three_times, NULL);

    .
    .
    .
}
```

# Counting with semaphores (cont)

Initially: five = 5, three = 3

```
/* thing_5() thread */
void *five_times(void *arg) {
    int i;

    while (1) {
        for (i=0; i<5; i++) {
            /* wait & thing_5() */
            P(&five);
            thing_5();
        }
        V(&three);
        V(&three);
        V(&three);
    }
    return NULL;
}
```

```
/* thing_3() thread */
void *three_times(void *arg) {
    int i;

    while (1) {
        for (i=0; i<3; i++) {
            /* wait & thing_3() */
            P(&three);
            thing_3();
        }
        V(&five);
        V(&five);
        V(&five);
        V(&five);
        V(&five);
    }
    return NULL;
}
```

# Threads Summary

**Threads provide another mechanism for writing concurrent programs**

**Threads are growing in popularity**

- Somewhat cheaper than processes
- Easy to share data between threads

**However, the ease of sharing has a cost:**

- Easy to introduce subtle synchronization errors
- Tread carefully with threads!

**For more info:**

- D. Butenhof, “Programming with Posix Threads”, Addison-Wesley, 1997.

# Beware of Optimizing Compilers!

## Code From Book

```
#define NITERS 100000000

/* shared counter variable */
unsigned int cnt = 0;

/* thread routine */
void *count(void *arg)
{
    int i;
    for (i = 0; i < NITERS; i++)
        cnt++;
    return NULL;
}
```

- Global variable `cnt` shared between threads
- Multiple threads could be trying to update within their iterations

## Generated Code

```
movl    cnt, %ecx
movl    $99999999, %eax
.L6:
    leal  1(%ecx), %edx
    decl  %eax
    movl  %edx, %ecx
    jns   .L6
    movl  %edx, cnt
```

- Compiler moved access to `cnt` out of loop
- Only shared accesses to `cnt` occur before loop (read) or after (write)
- What are possible program outcomes?