

# 15213 Recitation Section C

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## Outline

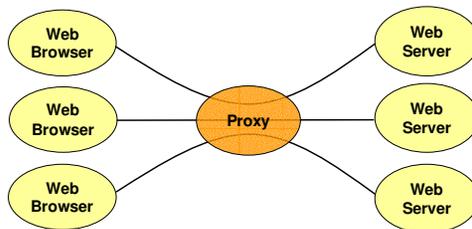
- Threads
- Synchronization
- Thread-safety of Library Functions

## Important Dates

- Lab 7 *Proxy*: due on Thursday, Dec 5
- Final Exam: Tuesday, Dec 17

## Concurrent Servers

- Iterative servers can only serve one client at a time
- Concurrent servers are able to handle multiple requests in parallel
- Required by L7 Part II



## Three Ways for Creating Concurrent Servers

### 1. Processes

- Fork a child process for every incoming client connection
- Difficult to share data among child processes

### 2. Threads

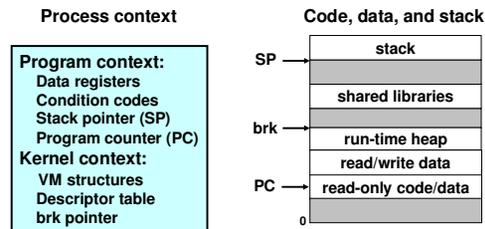
- Create a thread to handle every incoming client connection
- Our focus today

### 3. I/O multiplexing with Unix `select()`

- Use `select()` to notice pending socket activity
- Manually interleave the processing of multiple open connections
- More complex!
  - ~ implementing your own app-specific thread package!

## Traditional View of a Process

- Process = process context + code, data, and stack



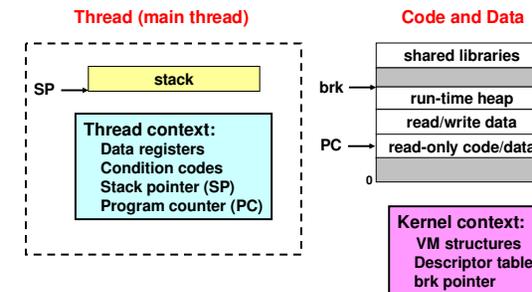
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## Alternate View of a Process

- Process = thread + code, data, and kernel context



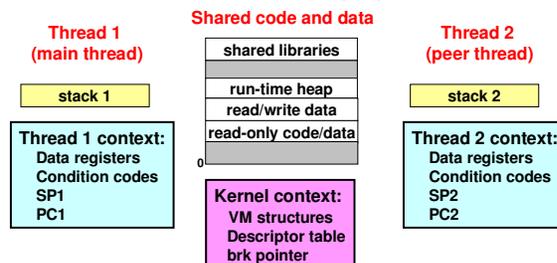
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## A Process With Multiple Threads

- Multiple threads can be associated with a process
  - Each thread has its own logical control flow (instruction flow)
  - Each thread shares the same code, data, and kernel context
  - Each thread has its own thread ID (TID)



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## Threads vs. Processes

- How threads and processes are similar
  - Each has its own logical control flow.
  - Each can run concurrently.
  - Each is context switched.
- How threads and processes are different
  - Threads share code and data, processes (typically) do not.
  - Threads are somewhat less expensive than processes.
    - Process control (creating and reaping) is twice as expensive as thread control.
    - Linux/Pentium III numbers:
      - ~20K cycles to create and reap a process.
      - ~10K cycles to create and reap a thread.

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## Posix Threads (Pthreads) Interface

- Standard interface for ~60 functions
  - Creating and reaping threads.
    - `pthread_create`
    - `pthread_join`
  - Determining your thread ID
    - `pthread_self`
  - Terminating threads
    - `pthread_cancel`
    - `pthread_exit`
    - `exit` [terminates all threads], `return` [terminates current thread]
  - Synchronizing access to shared variables
    - `pthread_mutex_init`
    - `pthread_mutex_[un]lock`
    - `pthread_cond_init`
    - `pthread_cond_[timed]wait`

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## The Pthreads "hello, world" Program

```

/*
 * hello.c - Pthreads "hello, world" program
 */
#include "csapp.h"

void *thread(void *vargp);

int main() {
    pthread_t tid;

    Pthread_create(&tid, NULL, thread, NULL);
    Pthread_join(tid, NULL);
    exit(0);
}

/* thread routine */
void *thread(void *vargp) {
    printf("Hello, world!\n");
    return NULL;
}
    
```

Thread attributes  
(usually NULL)

Thread arguments  
(void \*p)

return value  
(void \*\*p)

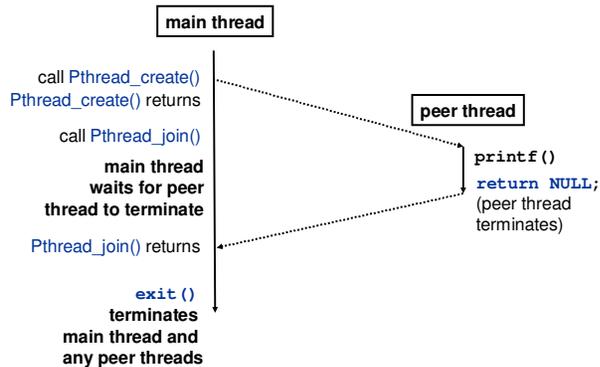
Upper case  
*Pthread\_xxx*  
checks errors

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## Execution of Threaded "hello, world"



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## Thread-Based Concurrent Echo Server

```

int main(int argc, char **argv)
{
    int listenfd, *conndfp, port, clientlen;
    struct sockaddr_in clientaddr;
    pthread_t tid;

    if (argc != 2) {
        fprintf(stderr, "usage: %s <port>\n", argv[0]);
        exit(0);
    }
    port = atoi(argv[1]);

    listenfd = open_listenfd(port);
    while (1) {
        clientlen = sizeof(clientaddr);
        conndfp = Malloc(sizeof(int));
        *conndfp = Accept(listenfd, (SA *)&clientaddr, &clientlen);
        Pthread_create(&tid, NULL, thread, conndfp);
    }
}
    
```

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## Thread-Based Concurrent Server (cont)

```
* thread routine */
void *thread(void *vargp)
{
    int connfd = *((int *)vargp);
    Pthread_detach(pthread_self());
    Free(vargp);

    echo_r(connfd); /* thread-safe version of echo() */
    Close(connfd);
    return NULL;
}
```

## Issue 1: Detached Threads

- At any point in time, a thread is either *joinable* or *detached*.
- *Joinable* thread can be reaped and killed by other threads.
  - must be reaped (with `pthread_join`) to free memory resources.
- *Detached* thread cannot be reaped or killed by other threads.
  - resources are automatically reaped on termination.
- Default state is joinable.
  - use `pthread_detach(pthread_self())` to make detached.
- *Why should we use detached threads?*
  - `pthread_join` blocks the calling thread

## Issue 2: Avoid Unintended Sharing

```
connfdp = Malloc(sizeof(int));
*connfdp = Accept(listenfd, (SA *)&clientaddr, &clientlen);
Pthread_create(&tid, NULL, thread, connfdp);
```

- For example, what happens if we pass the address of `connfd` to the thread routine as in the following code?

```
connfd = Accept(listenfd, (SA *)&clientaddr, &clientlen);
Pthread_create(&tid, NULL, thread, (void *)&connfd);
```

## Issue 3: Thread-safe

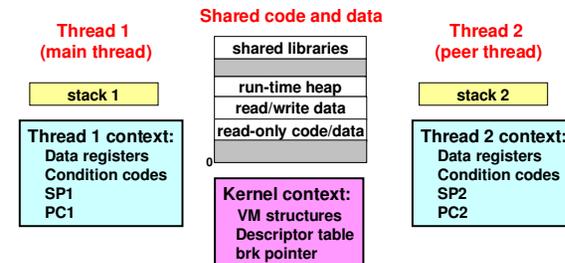
- Easy to share data structures between threads
- But we need to do this correctly!
- Recall the shell lab:
  - Job data structures
  - Shared between main process and signal handler
- Need ways to synchronize multiple control of flows

## Threads Memory Model

- Conceptual model:
  - Each thread runs in the context of a process.
  - Each thread has its own separate thread context.
    - Thread ID, stack, stack pointer, program counter, condition codes, and general purpose registers.
  - All threads share the remaining process context.
    - Code, data, heap, and shared library segments of the process virtual address space.
    - Open files and installed handlers

## Shared Variables in Conceptual Model

- global variables are shared
- stack variables are private



## Caveats of Conceptual Models

- In practice, any thread can read and write the stack of any other thread.
- So one can use a global pointer to point to a stack variable. Then all threads can access the stack variable.
- But this is not a good programming practice.
- More details in this Thursday's lecture

## Synchronization

- If multiple threads want to access a shared global data structure, we need to synchronize their accesses.
- Ways to do synchronization:
  - Semaphores
  - Mutex and conditions
  - Etc.

## Synchronizing With Semaphores

- *Classic solution:* Dijkstra's P and V operations on *semaphores*.
  - *semaphore:* non-negative integer synchronization variable.
    - P(s): [ while (s == 0) wait(); s--; ]
      - Dutch for "Proberen" (test)
    - V(s): [ s++; ]
      - Dutch for "Verhogen" (increment)
  - OS guarantees that operations between brackets [ ] are executed indivisibly.
    - Only one P or V operation at a time can modify s.
    - When while loop in P terminates, only that P can decrements.
- **Semaphore invariant:** ( $s \geq 0$ )

## POSIX Semaphores (in csapp.c)

```
/* initialize semaphore sem to value */
/* pshared=0 if thread, pshared=1 if process */
void Sem_init(sem_t *sem, int pshared, unsigned int value) {
    if (sem_init(sem, pshared, value) < 0)
        unix_error("Sem_init");
}

/* P operation on semaphore sem */
void P(sem_t *sem) {
    if (sem_wait(sem))
        unix_error("P");
}

/* V operation on semaphore sem */
void V(sem_t *sem) {
    if (sem_post(sem))
        unix_error("V");
}
```

## Sharing With POSIX Semaphores

```
#include "csapp.h"
#define NITERS 10000000

unsigned int cnt; /* counter */
sem_t sem; /* semaphore */

int main() {
    pthread_t tid1, tid2;

    Sem_init(&sem, 0, 1);

    /* create 2 threads and wait */
    .....

    exit(0);
}
```

```
/* thread routine */
void *count(void *arg)
{
    int i;

    for (i=0; i<NITERS; i++) {
        P(&sem);
        cnt++;
        V(&sem);
    }
    return NULL;
}
```

## Thread-safety of Library Functions

- All functions in the Standard C Library (at the back of your K&R text) are thread-safe.
  - Examples: **malloc**, **free**, **printf**, **scanf**
- Most Unix system calls are thread-safe, with a few exceptions:

Thread-unsafe function	Class	Reentrant version
asctime	3	asctime_r
ctime	3	ctime_r
gethostbyaddr	3	gethostbyaddr_r
gethostbyname	3	gethostbyname_r
inet_ntoa	3	(none)
localtime	3	localtime_r
rand	2	rand_r

## Thread-Unsafe Functions: Fixes

- Return a ptr to a **static** variable.
- Fixes:
  1. Rewrite code so caller passes pointer to **struct**.
    - Issue: Requires changes in caller and callee.

```
struct hostent
*gethostbyname(char name)
{
    static struct hostent h;
    <contact DNS and fill in h>
    return &h;
}
```

```
hostp = Malloc(...);
gethostbyname_r(name, hostp);
```

## Thread-Unsafe Functions: Fixes

- Return a ptr to a **static** variable.
- Fixes:
  2. *Lock-and-copy*
    - Issue: Requires only simple changes in caller
    - However, caller must free memory.

```
struct hostent
*gethostbyname(char name)
{
    static struct hostent h;
    <contact DNS and fill in h>
    return &h;
}
```

```
struct hostent
*gethostbyname_ts(char *p)
{
    struct hostent *q = Malloc(...);
    P(&mutex); /* lock */
    p = gethostbyname(name);
    *q = *p; /* copy */
    V(&mutex);
    return q;
}
```

## Summary

- Threading is a clean and efficient way to implement concurrent server
- We need to synchronize multiple threads for concurrent accesses to shared variables
  - Semaphore is one way to do this
  - Thread-safety is the difficult part of thread programming