

15-745

SSA

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Def-Use chains are expensive

```
foo(int i, int j) {
  ...
  switch (i) {
    case 0: x=3; break;
    case 1: x=1; break;
    case 2: x=6; break;
    case 3: x=7; break;
    default: x = 11;
  }
  switch (j) {
    case 0: y=x+7; break;
    case 1: y=x+4; break;
    case 2: y=x-2; break;
    case 3: y=x+1; break;
    default: y=x+9;
  }
  ...
}
```

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Def-Use chains are expensive

```
foo(int i, int j) {
  ...
  switch (i) {
    case 0: x=3;
    case 1: x=1;
    case 2: x=6;
    case 3: x=7;
    default: x = 11;
  }
  switch (j) {
    case 0: y=x+7;
    case 1: y=x+4;
    case 2: y=x-2;
    case 3: y=x+1;
    default: y=x+9;
  }
  ...
}
```

In general,
N defs
M uses
⇒ $O(NM)$ space and time

A solution is to limit each
var to ONE def site

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Def-Use chains are expensive

```
foo(int i, int j) {
  ...
  switch (i) {
    case 0: x=3; break;
    case 1: x=1; break;
    case 2: x=6;
    case 3: x=7;
    default: x = 11;
  }
  switch (j) {
    case 0: y=x1+7;
    case 1: y=x1+4;
    case 2: y=x1-2;
    case 3: y=x1+1;
    default: y=x1+9;
  }
  ...
}
```

A solution is to limit each
var to ONE def site

x1 is one of the above x's

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Def-Use chains are expensive

```
foo(int i, int j) {
  ...
  switch (i) {
    case 0: x=3; break;
    case 1: x=1; break;
    case 2: x=6;
    case 3: x=7;
    default: x = 11;
  }
  x1 = x;
  switch (j) {
    case 0: y=x1+7;
    case 1: y=x1+4;
    case 2: y=x1-2;
    case 3: y=x1+1;
    default: y=x1+9;
  }
}
```

A solution is to limit each var to ONE def site

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5

Advantages of SSA

- Makes du-chains explicit (and what of ud-chains?)
- Makes dataflow analysis easier
- Improves register allocation
 - Automatically builds Webs
 - Makes building interference graphs easier
- For most programs, reduces space/time requirements

Muchnick: "Thus, it is valuable to be able to translate a given representation of a procedure into SSA form, to operate on it and, when appropriate, to translate it back into the original form." Hmm....?

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6

SSA

- Static single assignment is an IR where every variable is assigned a value at most once in the program text
- Easy for a basic block:
 - assign to a fresh variable at each stmt.
 - Each use uses the most recently defined var.
 - (Similar to Value Numbering)

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7

Straight-line SSA

```
a ← x + y
b ← a + x
a ← b + 2
c ← y + 1
a ← c + a
```



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8

Straight-line SSA

$a \leftarrow x + y$	\rightarrow	$a_1 \leftarrow x + y$
$b \leftarrow a + x$		$b_1 \leftarrow a_1 + x$
$a \leftarrow b + 2$		$a_2 \leftarrow b_1 + 2$
$c \leftarrow y + 1$		$c_1 \leftarrow y + 1$
$a \leftarrow c + a$		$a_3 \leftarrow c_1 + a_2$

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9

SSA

- Static single assignment is an IR where every variable is assigned a value at most once in the program text
- Easy for a basic block:
 - assign to a fresh variable at each stmt.
 - Each use uses the most recently defined var.
 - (Similar to Value Numbering)
- **What about at joins in the CFG?**

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10

Merging at Joins

$c \leftarrow 12$		$c_1 \leftarrow 12$
$\text{if } (i) \{$		$\text{if } (i)$
$a \leftarrow x + y$		$a_1 \leftarrow x + y$
$b \leftarrow a + x$		$a_2 \leftarrow b + 2$
$\} \text{ else } \{$		$b_1 \leftarrow a_1 + x$
$a \leftarrow b + 2$		$c_2 \leftarrow y + 1$
$c \leftarrow y + 1$		
$\}$		
$a \leftarrow c + a$		$a_4 \leftarrow c_2 + a_2$

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11

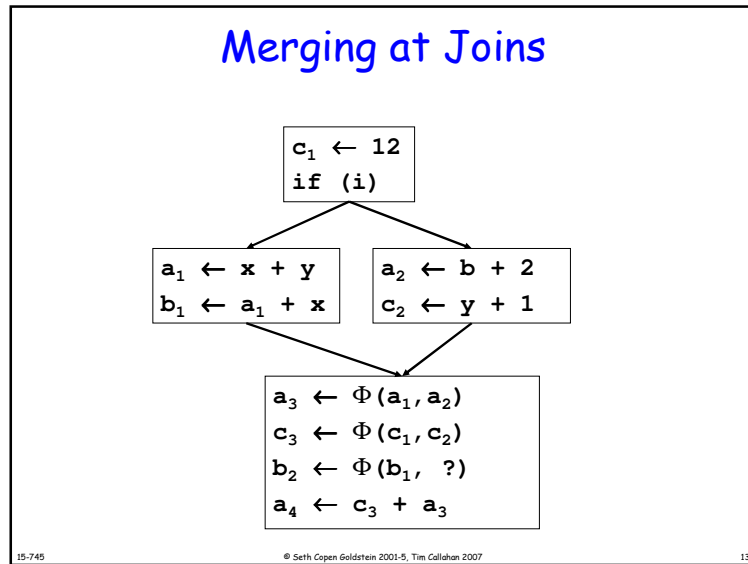
SSA

- Static single assignment is an IR where every variable is assigned a value at most once in the program text
- Easy for a basic block:
 - assign to a fresh variable at each stmt.
 - Each use uses the most recently defined var.
 - (Similar to Value Numbering)
- **What about at joins in the CFG?**
 - Use a notional fiction: A Φ function

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12

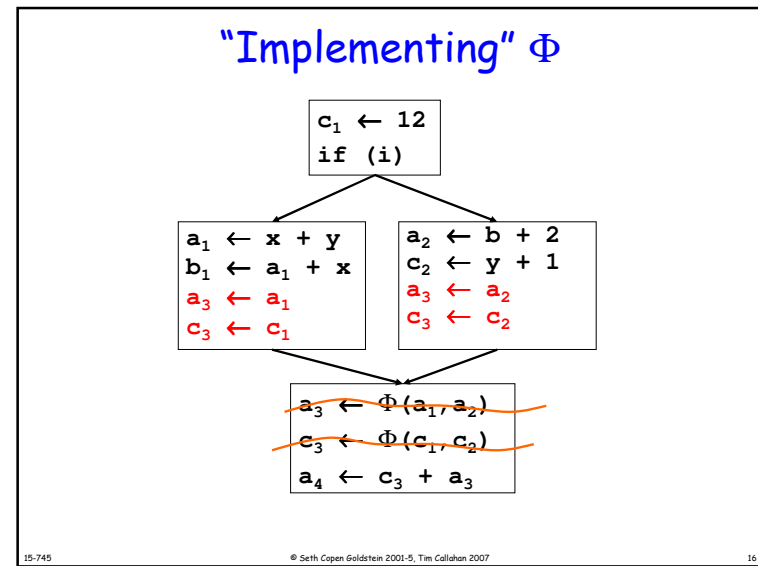
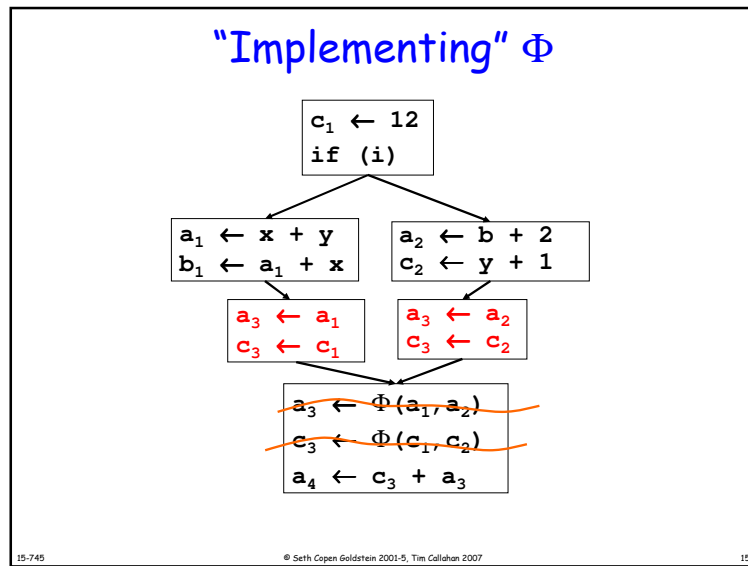


The Φ function

- Φ merges multiple definitions along multiple control paths into a single definition.
- At a BB with p predecessors, there are p arguments to the Φ function.

$$x_{new} \leftarrow \Phi(x_1, x_2, x_3, \dots, x_p)$$
- How do we choose which x_i to use?
 - We don't really care!
 - If we care, use moves on each incoming edge

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"Implementing" Φ : Example 2

```

    graph TD
      N1["c1 ← 12  
a1 ← 3  
if (i)"]
      N2["a2 ← b + 2  
c2 ← c1 + 1"]
      N3["a3 ← Φ(a1, a2)  
c3 ← Φ(c1, c2)  
a4 ← c3 + a3"]
      N1 --> N2
      N1 --> N3
      N2 --> N3
    
```

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"Implementing" Φ : Example 2

```

    graph TD
      N1["c1 ← 12  
a1 ← 3  
if (i)"]
      N2["a3 ← a1  
c3 ← c1"]
      N3["a2 ← b + 2  
c2 ← c1 + 1  
a3 ← a2  
c3 ← c2"]
      N4["a3 ← Φ(a1, a2)  
c3 ← Φ(c1, c2)  
a4 ← c3 + a3"]
      N1 --> N2
      N1 --> N3
      N2 --> N4
      N3 --> N4
    
```

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"Implementing" Φ : Example 2

```

    graph TD
      N1["c1 ← 12  
a1 ← 3  
if (i)"]
      N2["a3 ← a1  
c3 ← c1"]
      N3["a2 ← b + 2  
c2 ← c1 + 1  
a3 ← a2  
c3 ← c2"]
      N4["a3 ← Φ(a1, a2)  
c3 ← Φ(c1, c2)  
a4 ← c3 + a3"]
      N1 --> N2
      N1 --> N3
      N2 --> N4
      N3 --> N4
    
```

• Sometimes keep moves on edges
• ...we'll come back to this later

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Trivial SSA

- Each assignment generates a fresh variable.
- At each join point insert Φ functions for all live variables.

```

    graph TD
      subgraph Left
        L1["x ← 1"]
        L2["y ← x"]
        L3["y ← 2"]
        L4["z ← y + x"]
        L1 --> L2
        L1 --> L3
        L2 --> L4
        L3 --> L4
      end
      subgraph Right
        R1["x1 ← 1"]
        R2["y1 ← x1"]
        R3["y2 ← 2"]
        R4["x2 ← Φ(x1, x1)"]
        R5["y3 ← Φ(y1, y2)"]
        R6["z1 ← y3 + x2"]
        R1 --> R2
        R1 --> R3
        R2 --> R4
        R3 --> R4
        R2 --> R5
        R3 --> R5
        R4 --> R6
        R5 --> R6
      end
      L1 --> R1
      L2 --> R2
      L3 --> R3
      L4 --> R6
    
```

Way too many Φ functions inserted.

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Minimal SSA

- Each assignment generates a fresh variable.
- At each join point insert Φ functions for all variables with **multiple outstanding defs.**

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Another Example

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Another Example

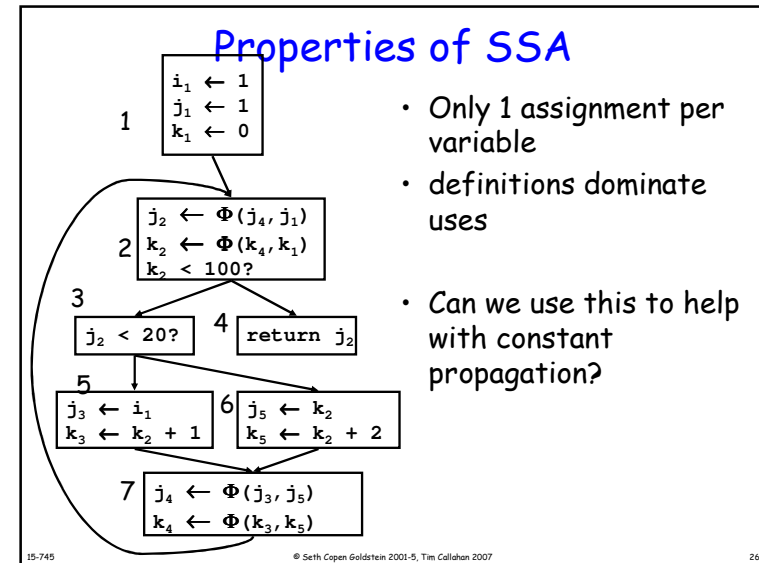
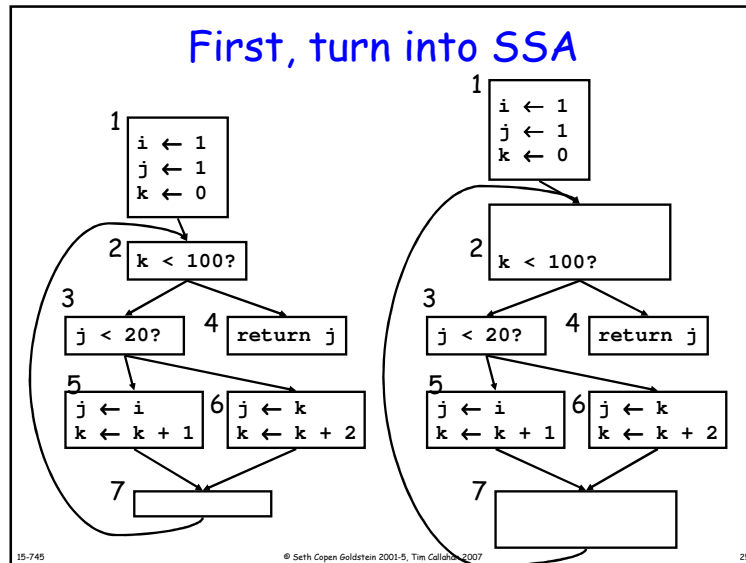
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Let's optimize the following:

```

i=1;
j=1;
k=0;
while (k<100) {
  if (j<20) {
    j=i;
    k++;
  } else {
    j=k;
    k+=2;
  }
}
return j;
    
```

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Constant Propagation

- If " $v \leftarrow c$ ", replace all uses of v with c
- If " $v \leftarrow \Phi(c, c, c)$ " replace all uses of v with c

```

W ← list of all defs
while !W.isEmpty {
  Stmt S ← W.removeOne
  if S has form " $v \leftarrow \Phi(c, \dots, c)$ "
    replace S with  $V \leftarrow c$ 
  if S has form " $v \leftarrow c$ " then
    delete S
  foreach stmt U that uses v,
    replace v with c in U
  W.add(U)
}

```

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27

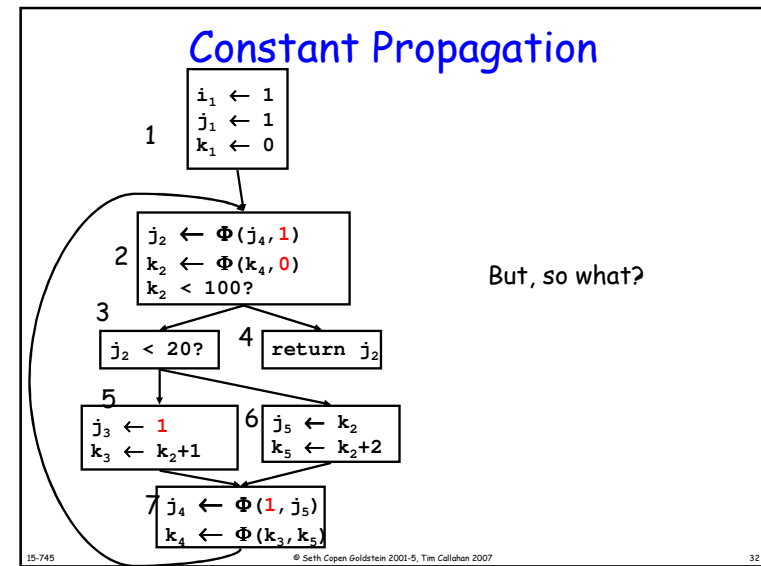
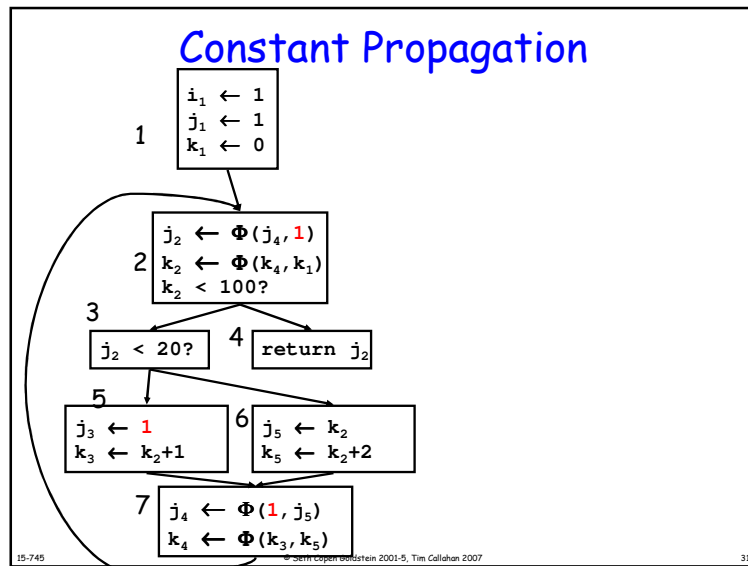
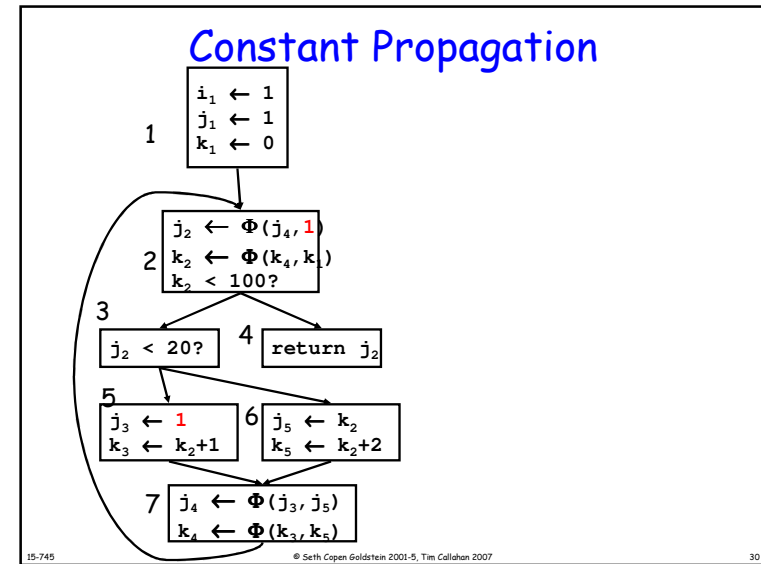
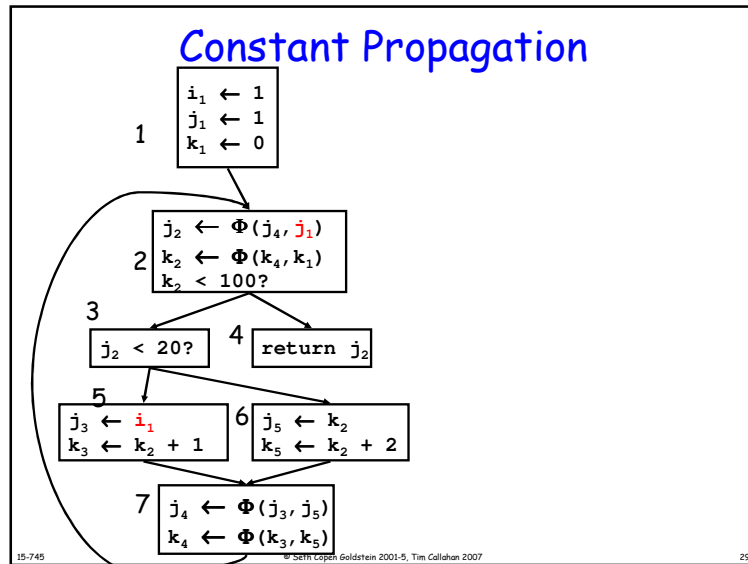
Other stuff we can do?

- Copy propagation
 - delete " $x \leftarrow \Phi(y)$ " and replace all x with y
 - delete " $x \leftarrow y$ " and replace all x with y
- Constant Folding
 - (Also, constant conditions too!)
- Unreachable Code
 - Remember to delete all edges from unreachable block

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28



Conditional Constant Propagation

```

    graph TD
      1["1  
i1 ← 1  
j1 ← 1  
k1 ← 0"] --> 2["2  
j2 ← Φ(j4, 1)  
k2 ← Φ(k4, 0)  
k2 < 100?"]
      2 --> 3["3  
j2 < 20?"]
      2 --> 4["4  
return j2"]
      3 --> 5["5  
j3 ← 1  
k3 ← k2 + 1"]
      3 --> 6["6  
j5 ← k2  
k5 ← k2 + 2"]
      5 --> 7["7  
j4 ← Φ(1, j5)  
k4 ← Φ(k3, k5)"]
      6 --> 7
      7 --> 2
  
```

- Does block 6 ever execute?
- Simple CP can't tell
- CCP can tell:
 - Assumes blocks don't execute until proven otherwise
 - Assumes Values are constants until proven otherwise

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Tracks:

- Blocks (assume unexecuted until proven otherwise)
- Variables (assume not executed, only with proof of assignments of a non-constant value do we assume not constant)

Use a lattice for variables:

BOT = we have evidence that variable can hold different values at different times

integers = we have seen evidence that the var has been assigned a constant with the value

TOP = not known to be executed

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Conditional Constant Propagation

```

    graph TD
      1["1  
i1 ← 1  
j1 ← 1  
k1 ← 0"] --> 2["2  
j2 ← Φ(j4, 1)  
k2 ← Φ(k4, 0)  
k2 < 100?"]
      2 --> 3["3  
j2 < 20?"]
      2 --> 4["4  
return j2"]
      3 --> 5["5  
j3 ← 1  
k3 ← k2 + 1"]
      3 --> 6["6  
j5 ← k2  
k5 ← k2 + 2"]
      5 --> 7["7  
j4 ← Φ(1, j5)  
k4 ← Φ(k3, k5)"]
      6 --> 7
      7 --> 2
  
```

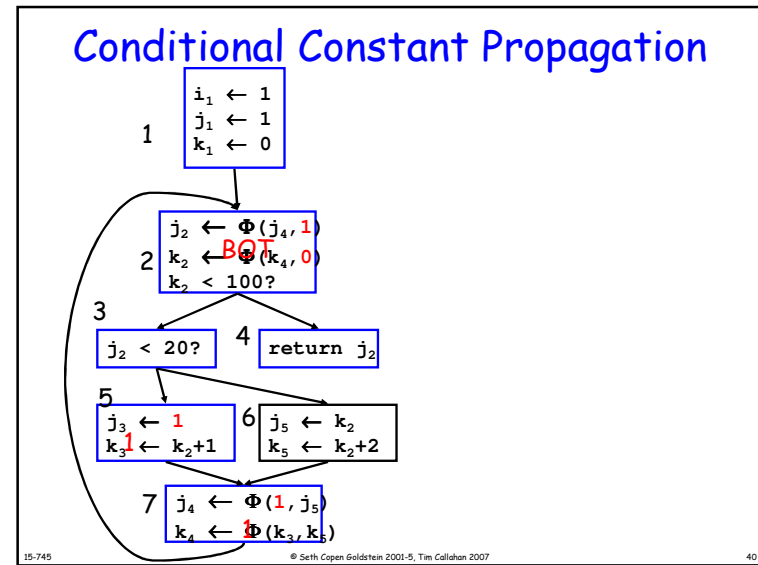
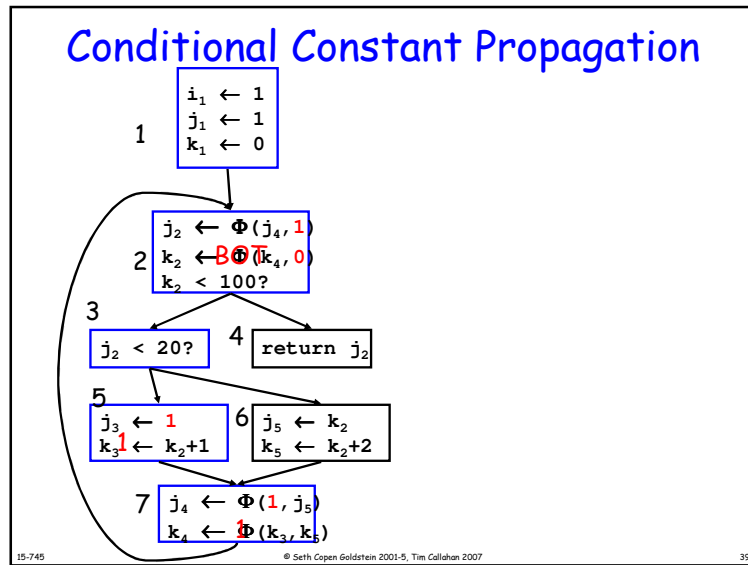
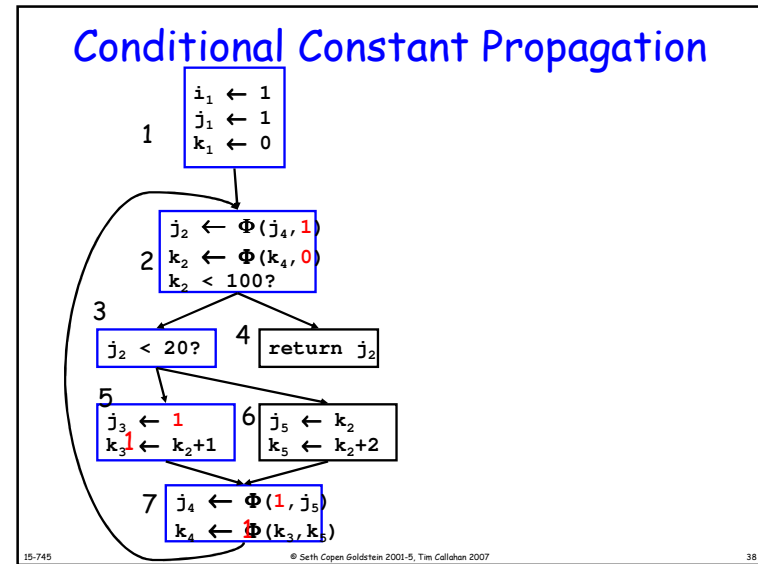
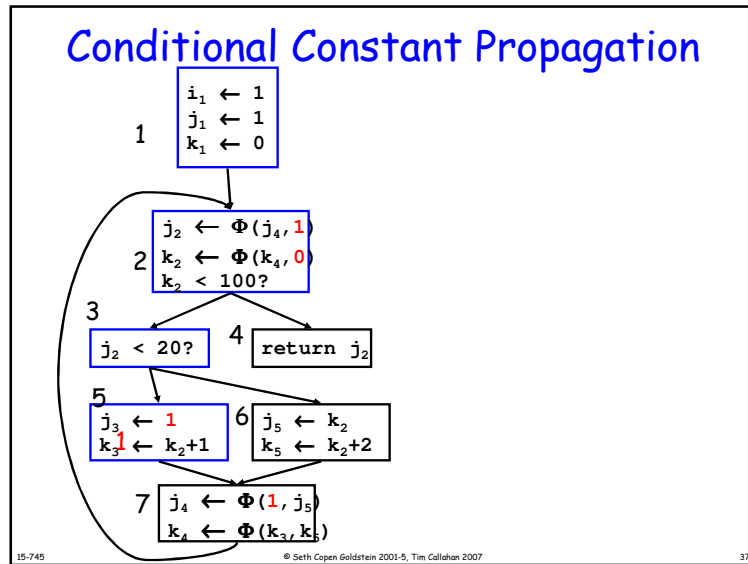
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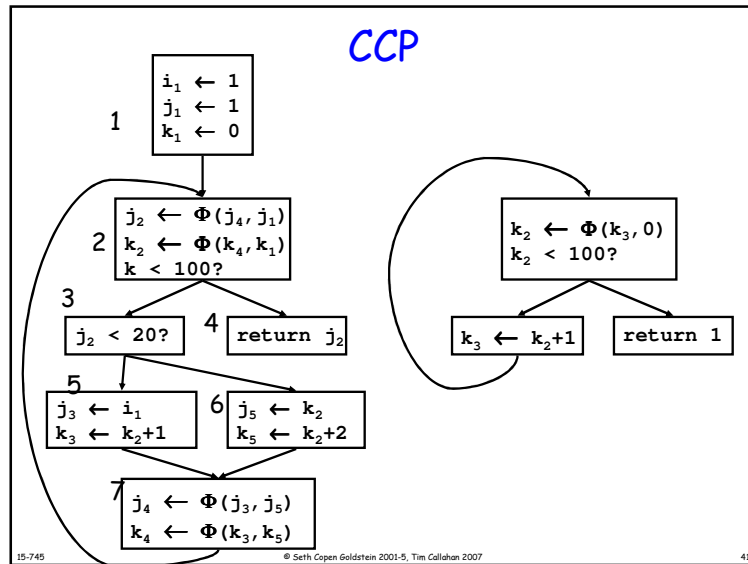
Conditional Constant Propagation

```

    graph TD
      1["1  
i1 ← 1  
j1 ← 1  
k1 ← 0"] --> 2["2  
j2 ← Φ(j4, 1)  
k2 ← Φ(k4, 0)  
k2 < 100?"]
      2 --> 3["3  
j2 < 20?"]
      2 --> 4["4  
return j2"]
      3 --> 5["5  
j3 ← 1  
k3 ← k2 + 1"]
      3 --> 6["6  
j5 ← k2  
k5 ← k2 + 2"]
      5 --> 7["7  
j4 ← Φ(1, j5)  
k4 ← Φ(k3, k5)"]
      6 --> 7
      7 --> 2
  
```

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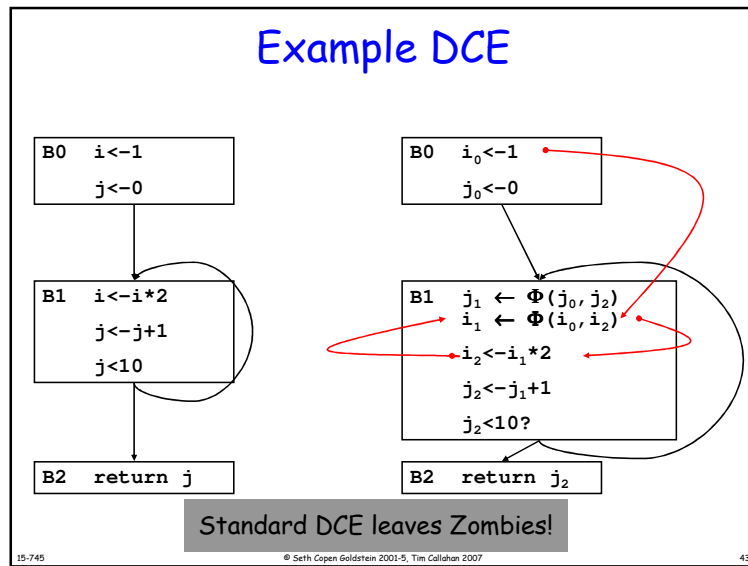
Dead Code Elimination

Since we are using SSA, this is just a list of all variable assignments.

```

W ← list of all defs
while !W.isEmpty {
  Stmt S ← W.removeOne
  if |S.users| != 0 then continue
  if S.hasSideEffects() then continue
  foreach def in S.definers {
    def.users ← def.users - {S}
    if |def.users| == 0 then
      W ← W UNION {def}
  }
  delete S
}
    
```

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Aggressive Dead Code Elimination

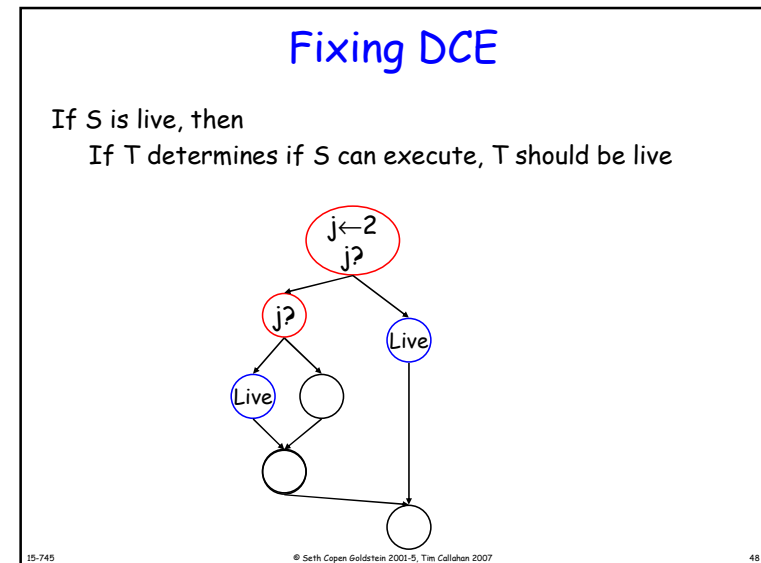
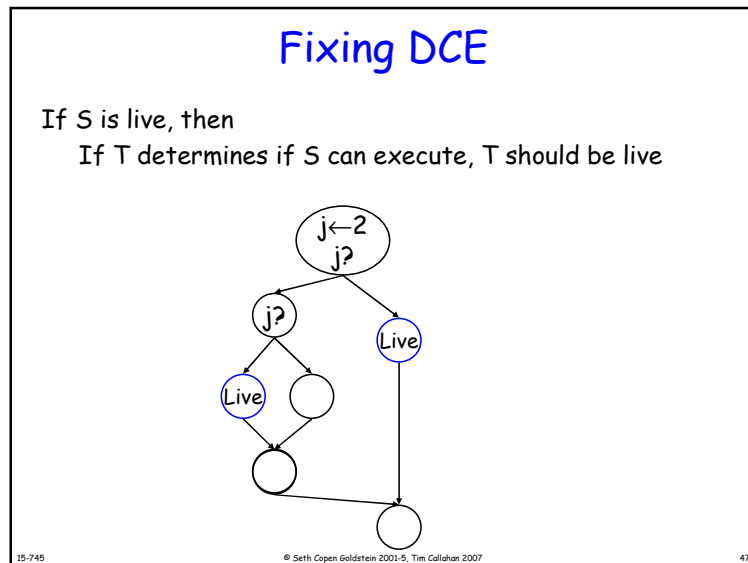
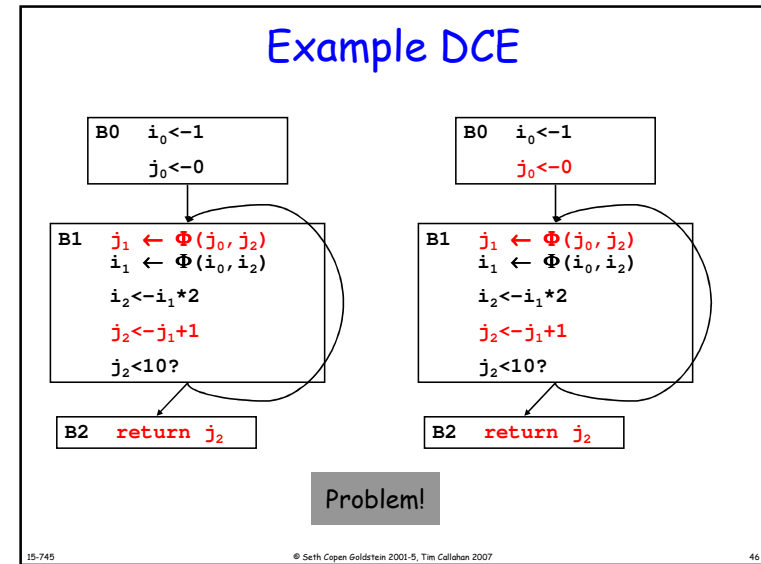
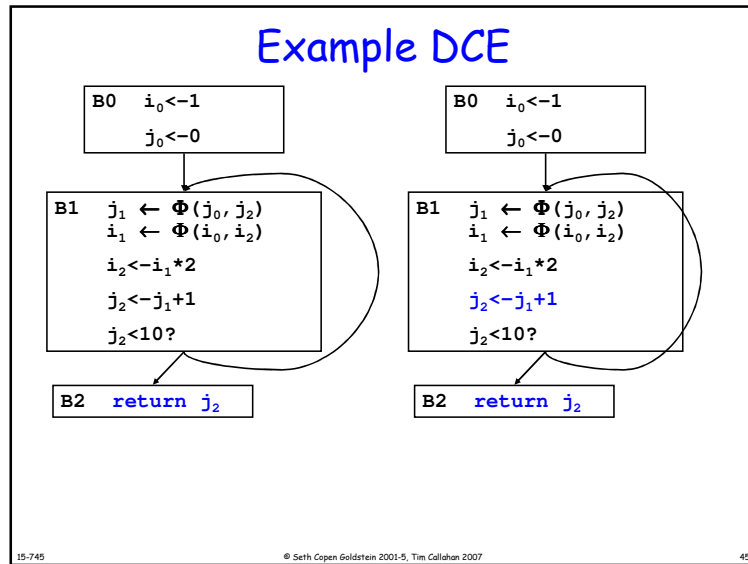
Assume a stmt is dead until proven otherwise.

```

init:
  mark as live all stmts that have side-effects:
    - I/O
    - stores into memory
    - returns
    - calls a function that MIGHT have side-effects
  As we mark S live, insert S.defs into W

while (|W| > 0) {
  S ← W.removeOne()
  if (S is live) continue;
  mark S live, insert S.defs into W
}
    
```

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Aggressive Dead Code Elimination

Assume a stmt is dead until proven otherwise.

```

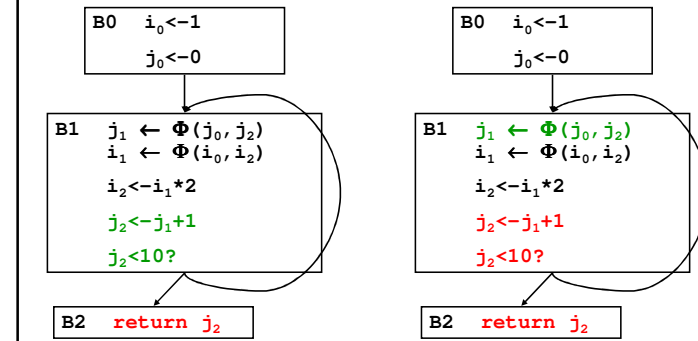
while (|W| > 0) {
  S ← W.removeOne()
  if (S is live) continue;
  mark S live, insert
  - forall operands, S.operand.definers into W
  - S.CD-1 into W
}
    
```

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49

Example DCE

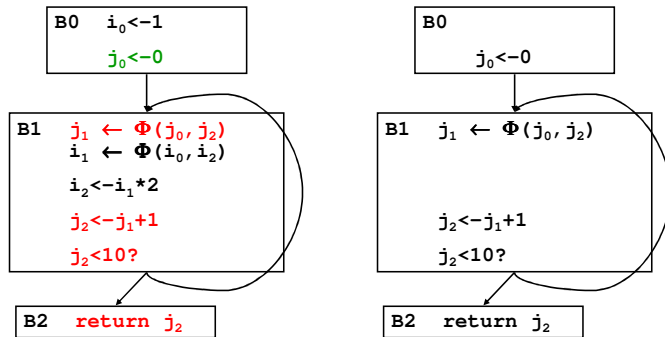


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50

Example DCE

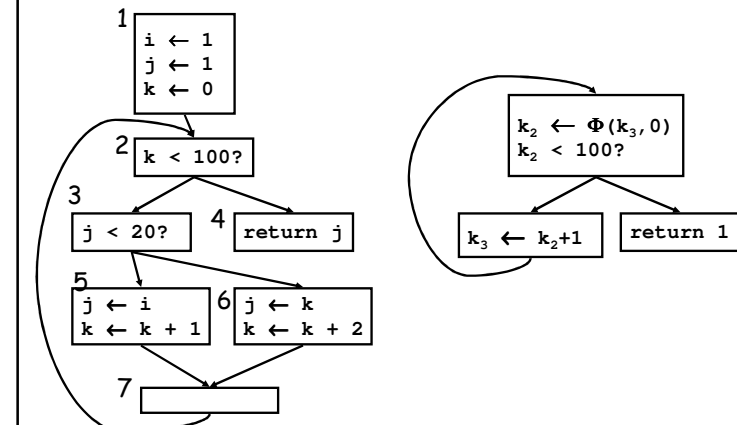


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51

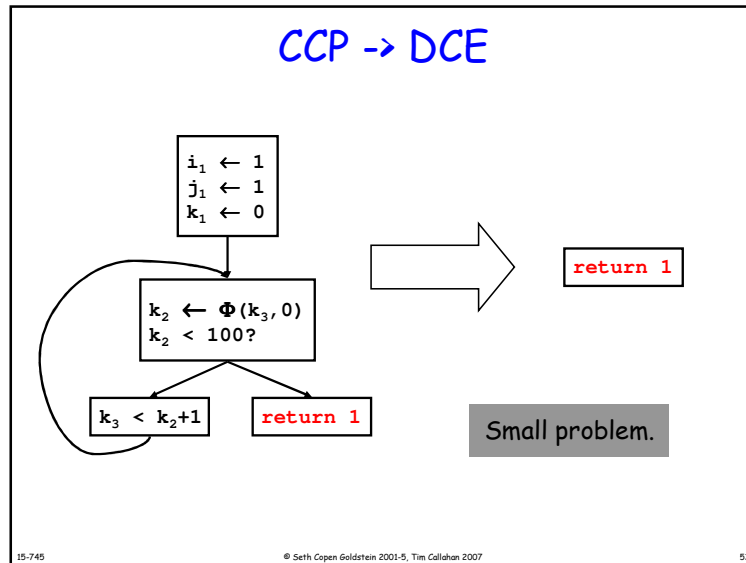
CCP Example



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52



Extending SSA → Pegasus

- SUIF is the front-end
 - standard transformation
 - some optimizations
 - Then, to graph-based SSA
 - Once in SSA form, why leave?
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Straight-line SSA

a ← x + y	→	a ₁ ← x + y
b ← a + x		b ₁ ← a ₁ + x
a ← b + 2		a ₂ ← b ₁ + 2
c ← y + 1		c ₁ ← y + 1
a ← c + a		a ₃ ← c ₁ + a ₂

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Straight-line SSA to Pegasus

```

a1 ← x + y
b1 ← a1 + x
a2 ← b1 + 2
c1 ← y + 1
a3 ← c1 + a2

```

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Straight-line SSA to Pegasus

$$a_1 \leftarrow x + y$$

$$b_1 \leftarrow a_1 + x$$

$$a_2 \leftarrow b_1 + 2$$

$$c_1 \leftarrow y + 1$$

$$a_3 \leftarrow c_1 + a_2$$

Put a circly-box around each statement

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Straight-line SSA to Pegasus

$$a_1 \leftarrow x + y$$

$$b_1 \leftarrow a_1 + x$$

$$a_2 \leftarrow b_1 + 2$$

$$c_1 \leftarrow y + 1$$

$$a_3 \leftarrow c_1 + a_2$$

Draw the explicit def-use edges

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Straight-line SSA to Pegasus

$$\textcircled{x} \quad \textcircled{y}$$

$$a_1 \leftarrow x + y$$

$$b_1 \leftarrow a_1 + x$$

$$a_2 \leftarrow b_1 + 2$$

$$c_1 \leftarrow y + 1$$

$$a_3 \leftarrow c_1 + a_2$$

Make placeholders for input vars

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Straight-line SSA to Pegasus

$$\textcircled{x} \quad \textcircled{y}$$

$$a_1 \leftarrow x + y$$

$$b_1 \leftarrow a_1 + x$$

$$a_2 \leftarrow b_1 + 2$$

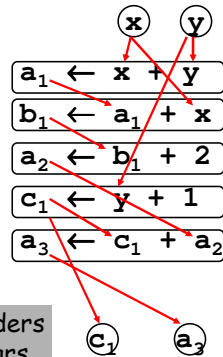
$$c_1 \leftarrow y + 1$$

$$a_3 \leftarrow c_1 + a_2$$

Make placeholders for input vars... and connect them

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Straight-line SSA to Pegasus



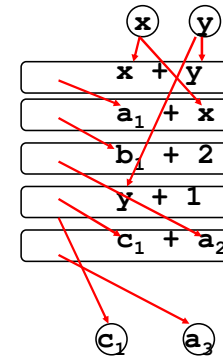
Make placeholders for live-out vars, and connect

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61

Straight-line SSA to Pegasus



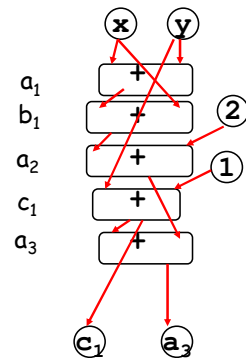
Don't need destinations any more...

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62

Straight-line SSA to Pegasus



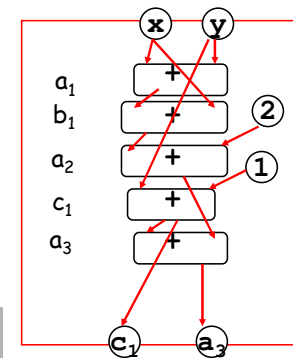
Actually, only need the operation

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63

Straight-line SSA to Pegasus



So that's our basic block... but how do they connect?

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64

"Implementing" Φ : Example 2

$$c_1 \leftarrow 12$$

$$a_1 \leftarrow 3$$

$$\text{if } (i)$$

$$a_2 \leftarrow b + 2$$

$$c_2 \leftarrow c_1 + 1$$

$$a_3 \leftarrow \Phi(a_1, a_2)$$

$$c_3 \leftarrow \Phi(c_1, c_2)$$

$$a_4 \leftarrow c_3 + a_3$$

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"Implementing" Φ : Example 2

▽ = eta = gate

△ = mu = merge

$$a_3 \leftarrow \Phi(a_1, a_2)$$

$$c_3 \leftarrow \Phi(c_1, c_2)$$

$$a_4 \leftarrow c_3 + a_3$$

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"Implementing" Φ : Example 2

▽ = eta = gate

△ = mu = merge

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"Implementing" Φ : Example 2

▽ = eta = gate

△ = mu = merge

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"Implementing" Φ : Example 2

∇ = eta = gate

Δ = mu = merge

The diagram shows a control flow graph with nodes represented by triangles. A top block contains nodes with labels 0, 1, 2, 3, 12, and 'eq'. Below it are two blocks, each containing nodes with labels 1 and 2, and a '+' operator. A bottom block contains a '+' operator and a gate node. Arrows indicate control flow between these blocks. Red dots are placed on some edges.

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"Implementing" Φ : Example 2

∇ = eta = gate

Δ = mu = merge

The diagram shows a control flow graph similar to the previous one, but with red dots on different edges.

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"Implementing" Φ : Example 2

∇ = eta = gate

Δ = mu = merge

Note 1: the set of etas targeting the same successor correspond to one edge in the control flow graph.

The diagram shows a control flow graph similar to the previous ones, but with a red circle around a specific gate node.

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"Implementing" Φ : Example 2

∇ = eta = gate

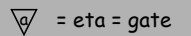
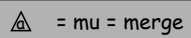
Δ = mu = merge

Note 2: for a dataflow analysis problem, where do the facts go? how are the facts different?

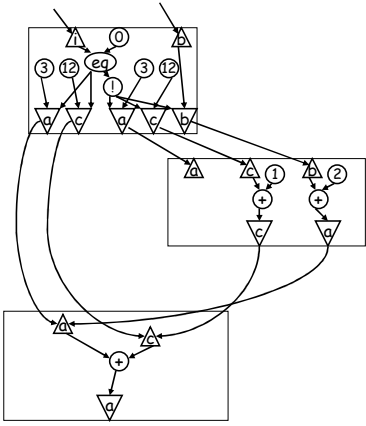
The diagram shows a control flow graph similar to the previous ones, with a red dot on an edge.

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"Implementing" Φ : Example 2


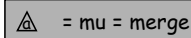
 = eta = gate
 = mu = merge

Note 3: the etas are like the "implemented Φ " moves on the edges..



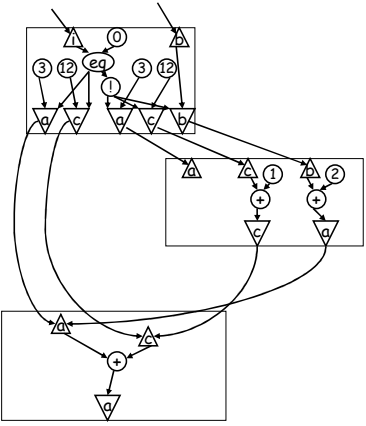
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"Implementing" Φ : Example 2

 = eta = gate
 = mu = merge

Note 4: WHY?

- can be mapped to spatial dataflow hardware directly
- allows detailed, per-data-edge dataflow analysis



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Currently

- Pegasus used to convert C into hardware
- Several orders of magnitude improvement in energy-delay!
- 15-745: Use Pegasus to target advanced architecture, e.g., Itanium
 - VLIW (requires compiler to schedule)
 - Predicated (supports predicated ops)
 - Speculation (explicit speculation in ISA)