

Parsimonious Linear Fingerprinting for Time Series

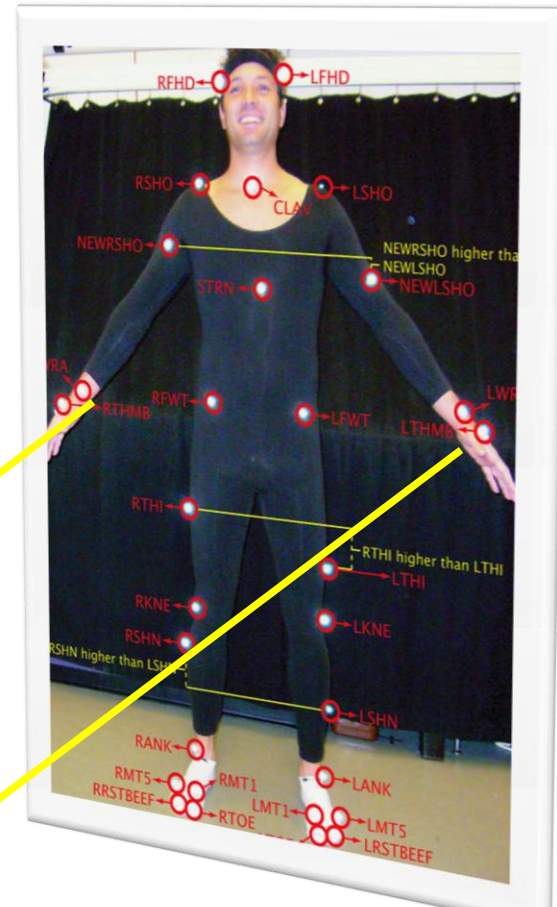
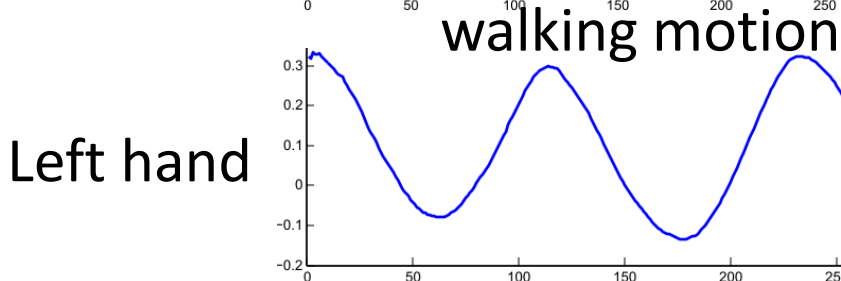
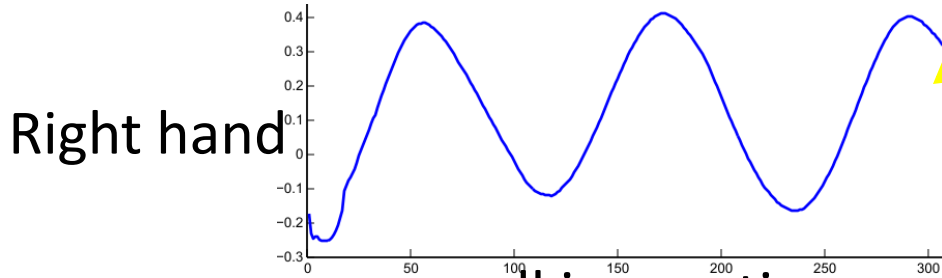
Lei Li

joint work with B. Aditya Prakash, Christos Faloutsos
School of Computer Science
Carnegie Mellon University

Why study time series?

Motion Capture

- Synthesize human motion
- Design robots to assist the disabled



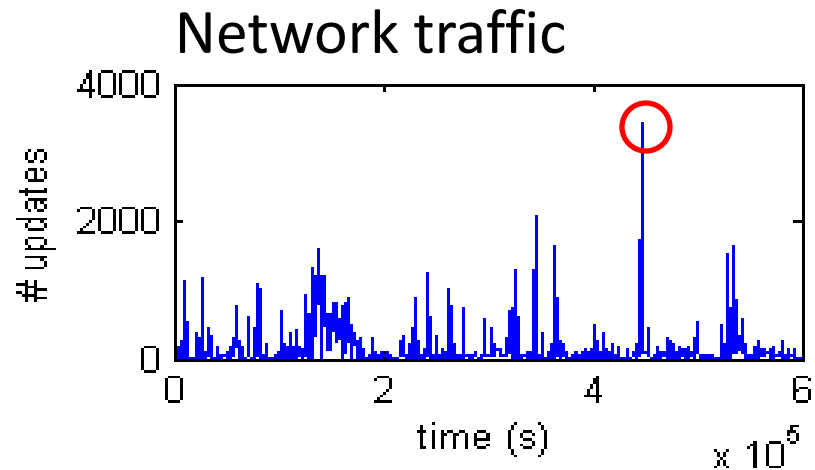
FORD USES HOLLYWOOD MOTION-CAPTURE SOFTWARE BEHIND 'AVATAR' TO IMPROVE VEHICLE DESIGNS



• Ford Motor Company is the only automaker to use the same type of motion-capture software in its virtual

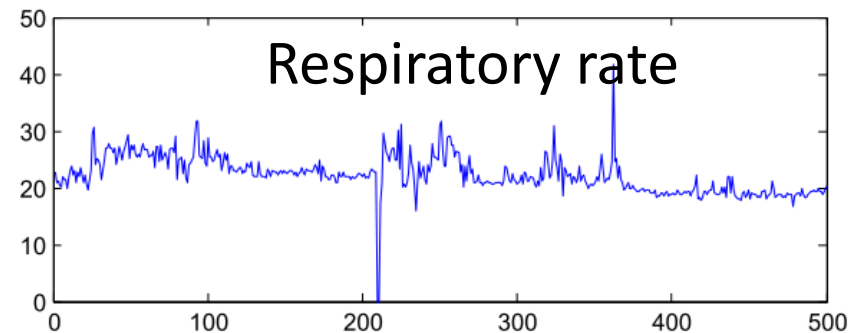
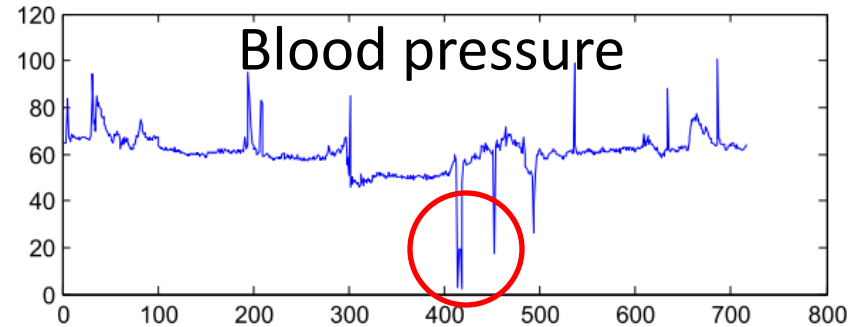
Network Security

- Anomaly detection in computer network



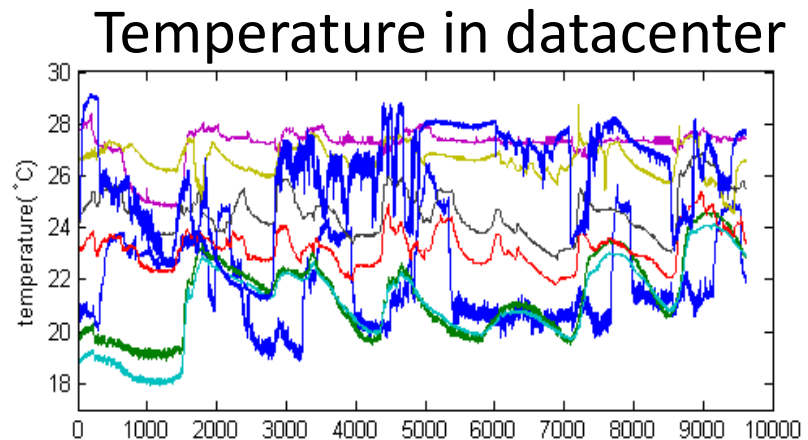
Healthcare

- Monitoring physiologic signals at ICU
- Help early detection of fatal event using forecasting, classification/clustering



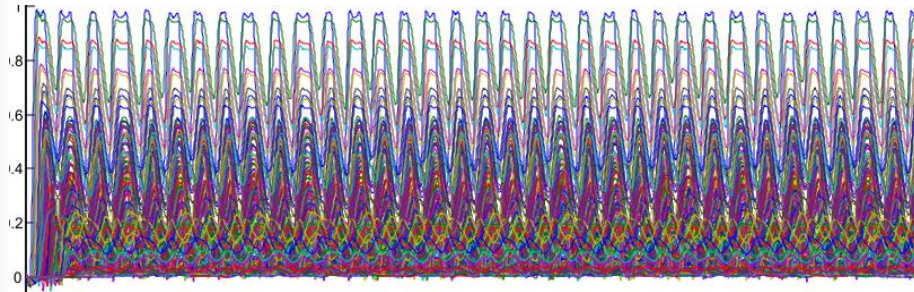
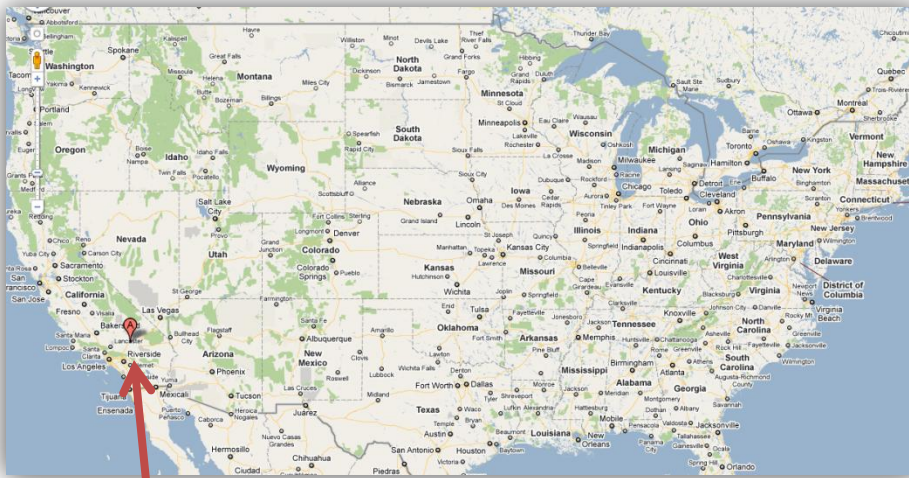
Datacenter Monitoring

- Monitoring a datacenter with 5000 servers: **1TB** data per day, 55 million streams ([Reeves+ 2009])
- Goal: save energy in data centers
 - US alone, **\$4.5billion** power consumption (2006)



Environmental Monitoring

- Chlorine sensor in drinking water systems



Barstow residents advised not to drink tap water because of possible contamination

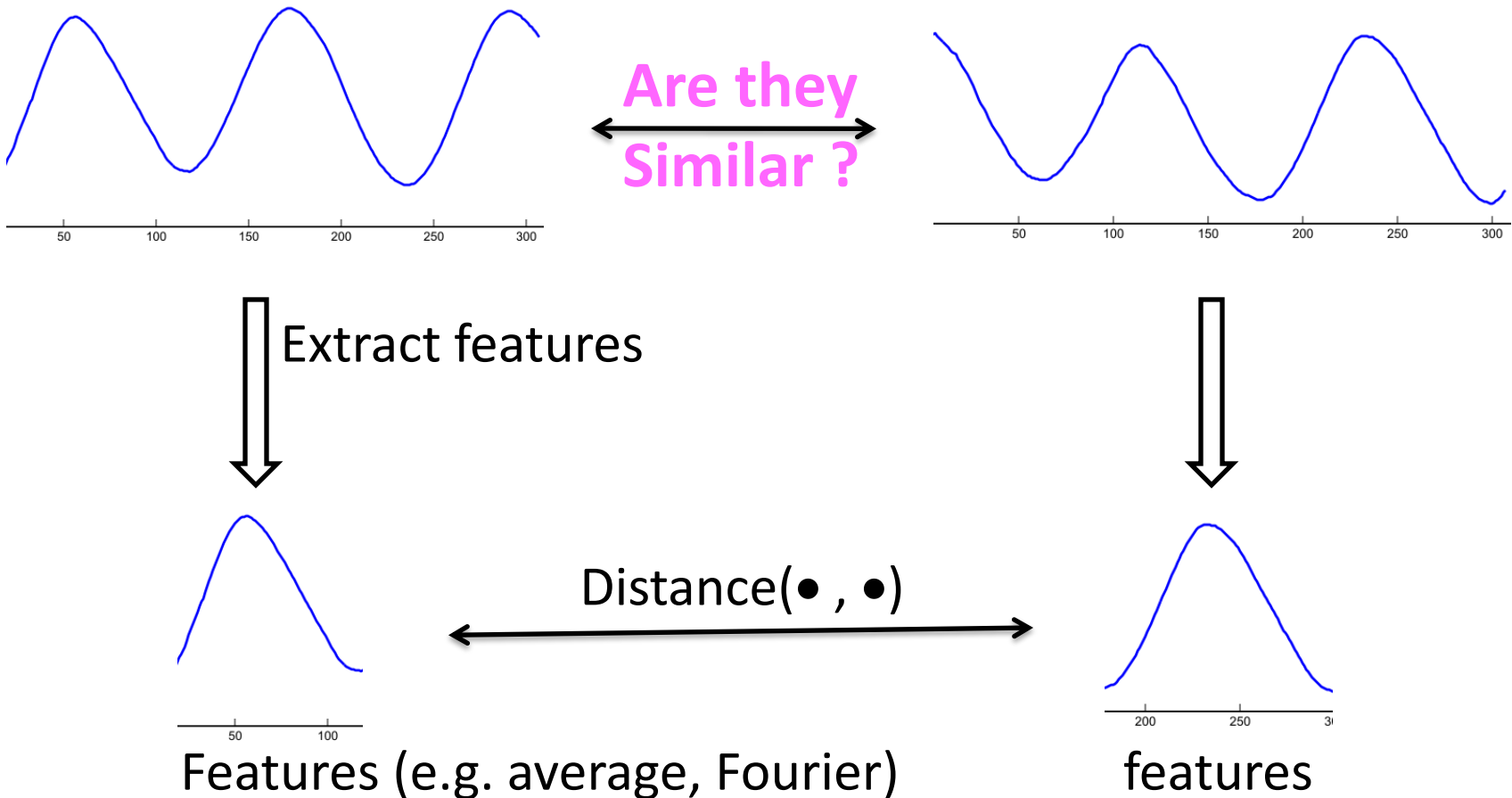
November 19, 2010 | 5:54 pm

Barstow residents were warned Friday not to drink local tap water, which recent tests show may be contaminated.

Golden State Water Co. posted the warning on its website after the agency was notified Thursday that samples contained high levels of perchlorate, an inorganic chemical that interferes with the human thyroid gland, affecting hormones as well as prenatal growth during pregnancies.

Central Problem

- Estimate “Similarity” among time sequences

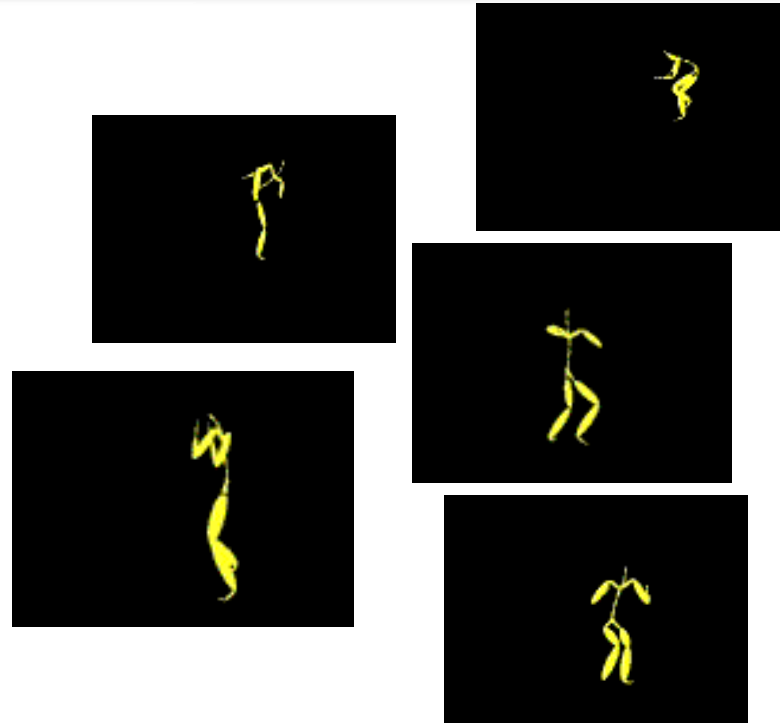
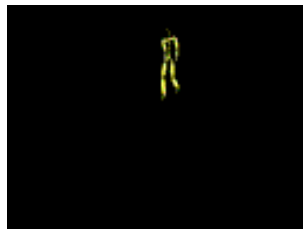


With similarity function: find the most similar motion sequence

SELECT * FROM

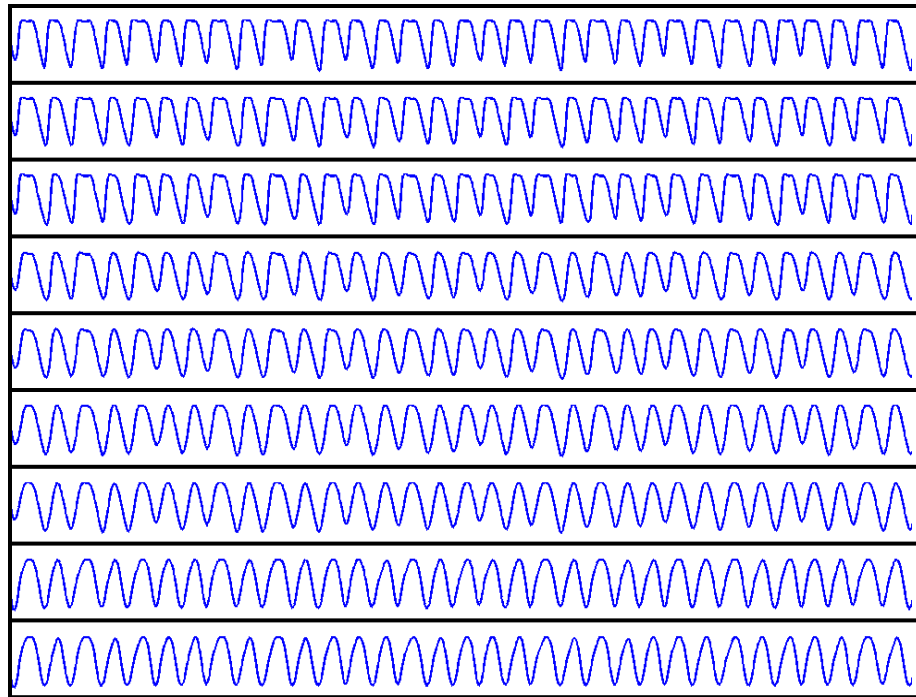
WHERE time_seq.

LIKE

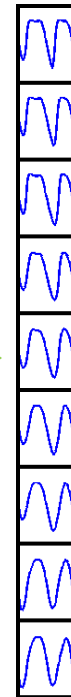


Underlying Question

What are good features / “fingerprints”?



e.g. length=4k,
in Chlorine measurement



Requirements
of good features:

1. Time Shift
2. Frequency
Proximity
3. Grouping
Harmonics

Benefits

Good features / “fingerprints” help with

- Answering similarity queries
- Clustering/Classification
- Compression
- Forecasting

Outline

- Motivation & Problem Definition
- ➔ • An Obvious Solution & Related Work
- Proposed Method: Intuition & Example
- Experiments & Results
- PLiF: High Level Ideas
- PLiF: Low Level Details
- Conclusion

Related Work

- Time series indexing [Keogh et al 02,04, ...]
- Distance function
 - Euclidean distance [Rafiei et al 97, Ogras et al 06, ...]
 - Dynamic time warping [Fu et al 05, Keogh 02, ...]
- Fourier / Wavelets [Gilbert et al 01, Jahangiri et al 01, ...]
- Dimensionality Reduction
 - PCA / SVD [Jolliffe 86]
 - ICA [Hyvarinen et al 01]

An Obvious (but failed) Solution

- Principal Component Analysis (PCA) / SVD
 - Dimensionality reduction
 - Very effective in many cases with high dimensional data
 - “Swiss army knife” in linear algebra

Solved?

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Why PCA fails?

- Properties of Good features / “fingerprints”:
 - (a) Time shift / lag independent
 - (b) frequency proximity
 - (c) grouping harmonics

Example: synthetic signals

Equations

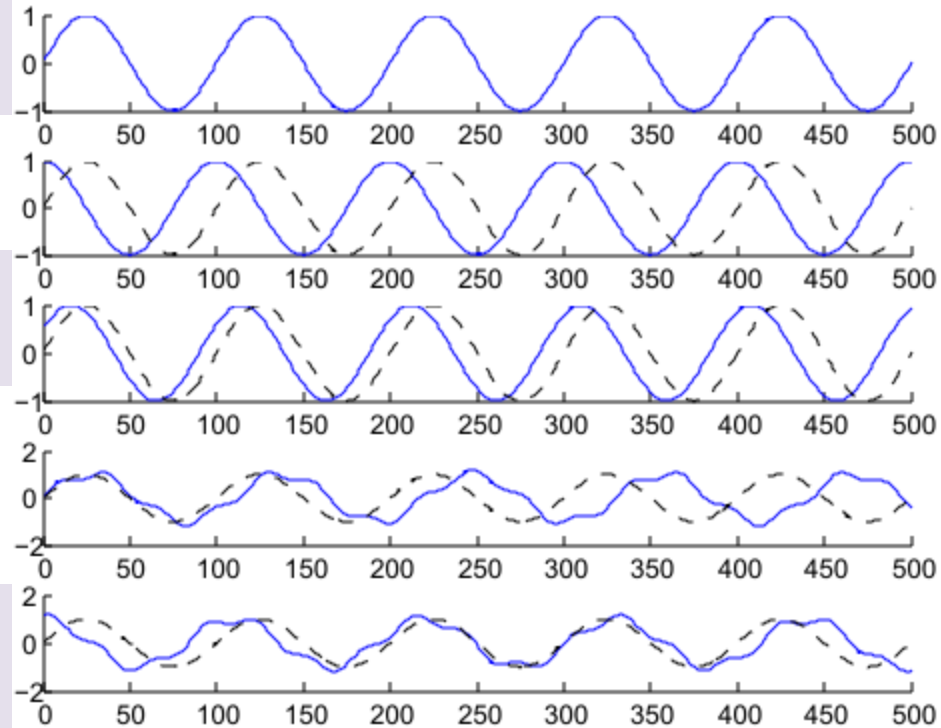
(X1) $\sin(2\pi t/100)$

(X2) $\cos(2\pi t/100)$

(X3) $\sin(2\pi t/98 + \pi/6)$

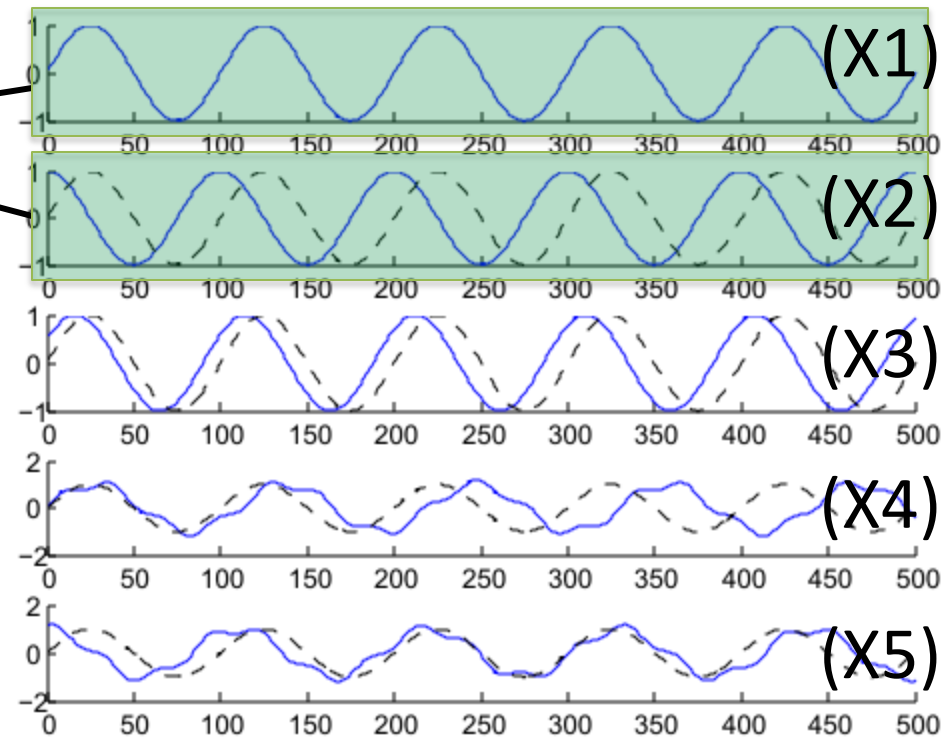
(X4) $\sin(2\pi t/110) +$
 $0.2\sin(2\pi t/30)$

(X5) $\cos(2\pi t/110) +$
 $0.2\sin(2\pi t/30 + \pi/4)$



Intuition of “fingerprints”

(a) Time shift

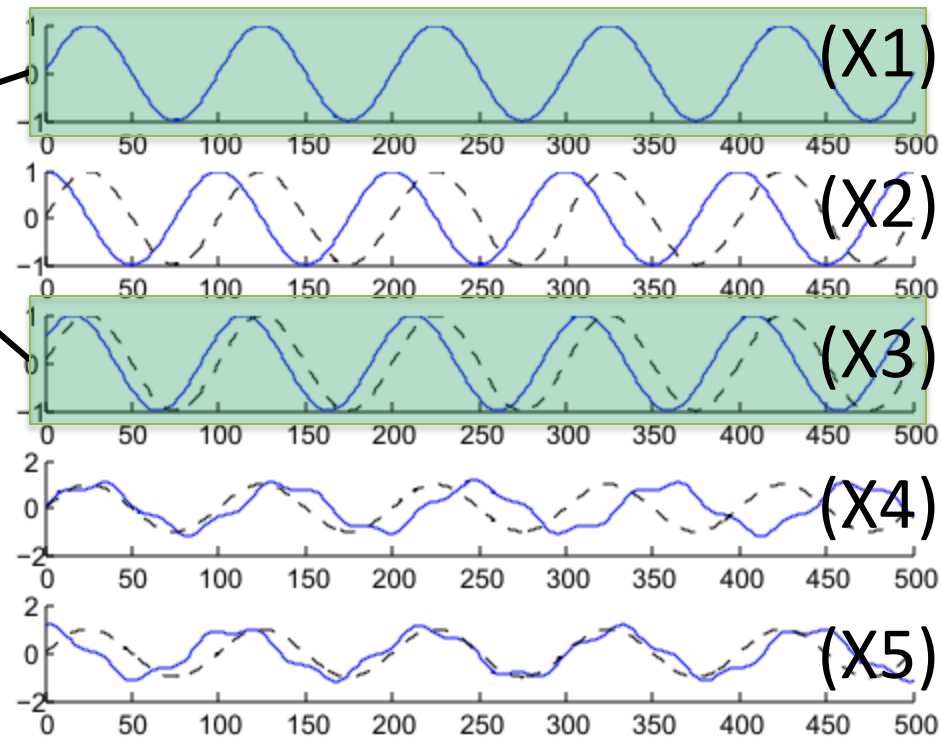


e.g.
left-foot-start walking
v.s.
right-foot-start walking

Intuition of “fingerprints”

(b) nearby frequency

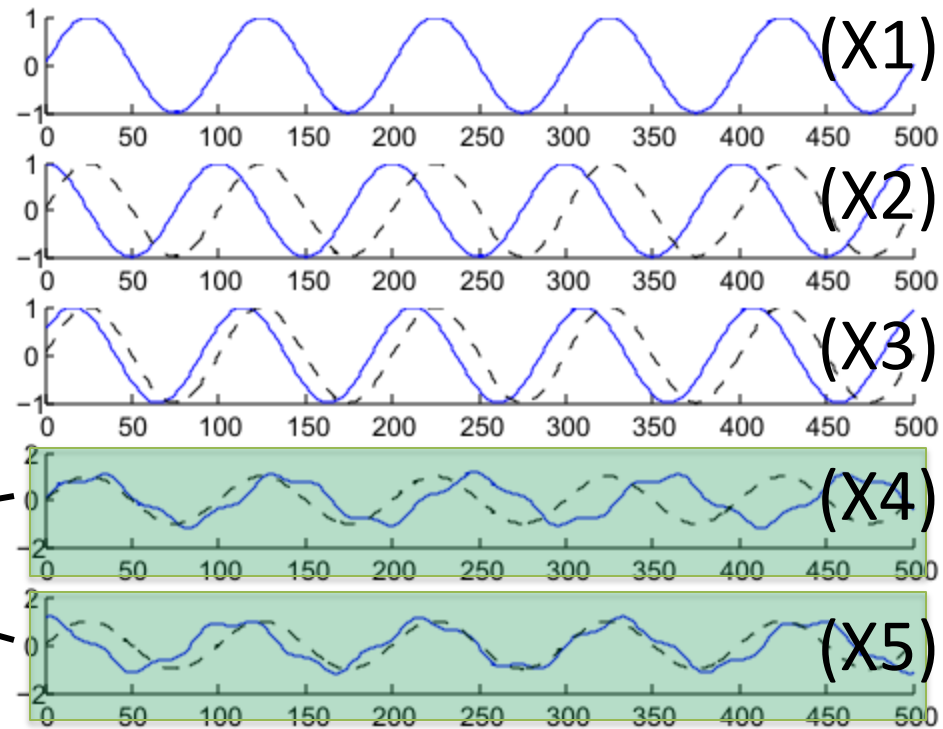
e.g.
running
v.s.
fast running



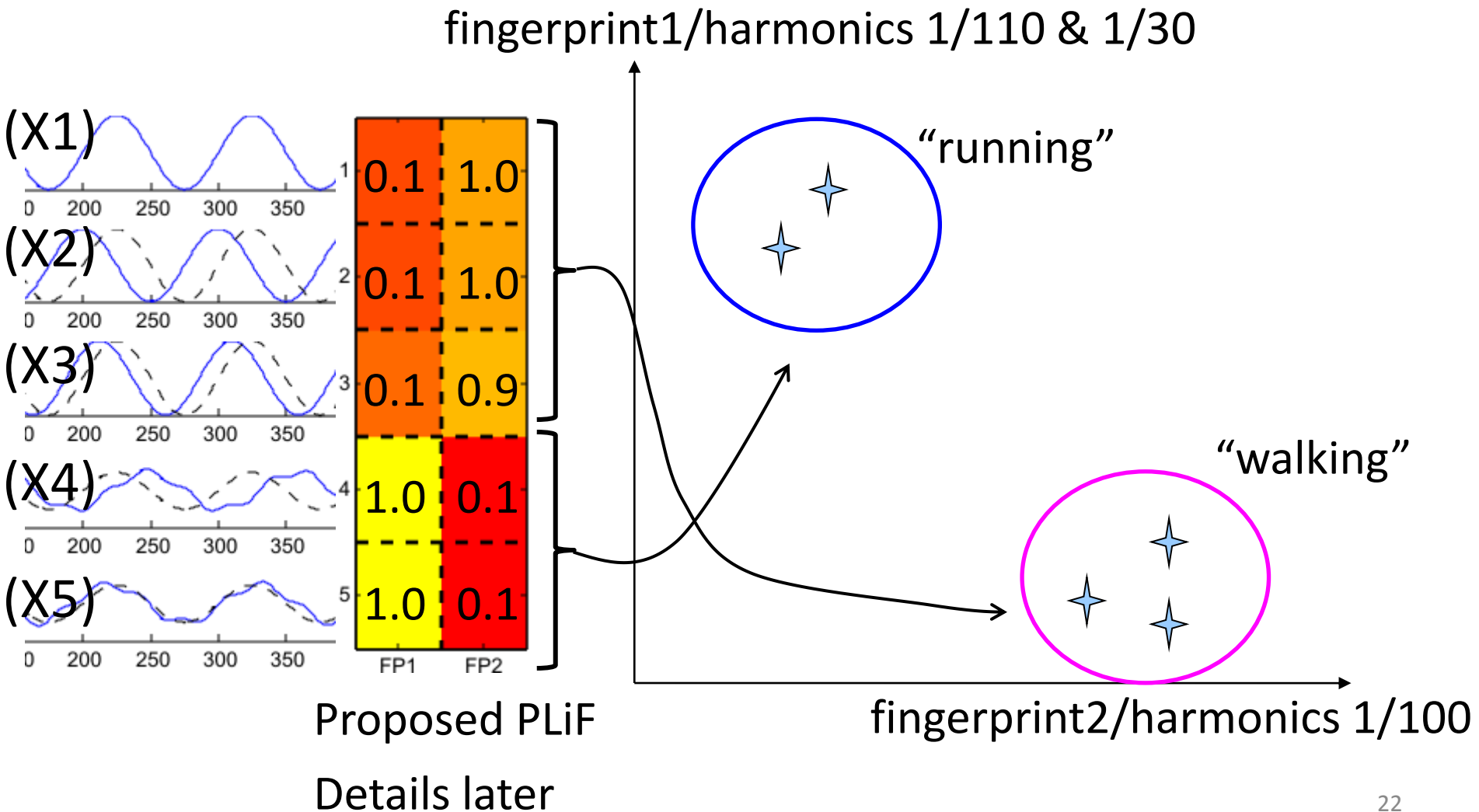
Intuition of “fingerprints”

~ human voices

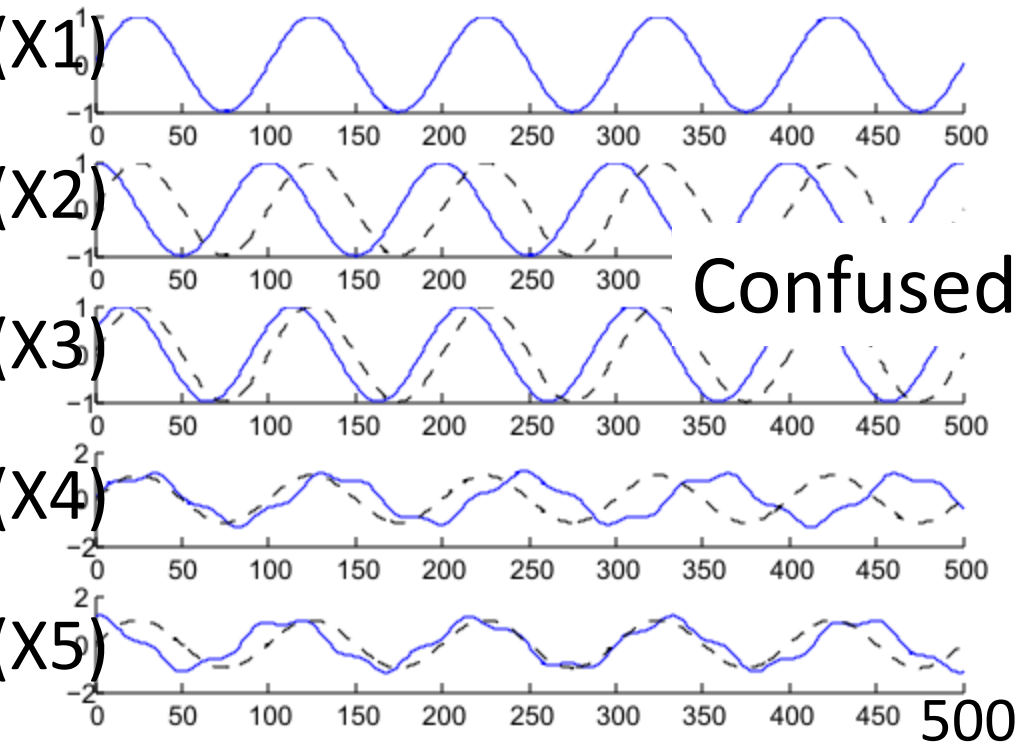
(c) groups of harmonics



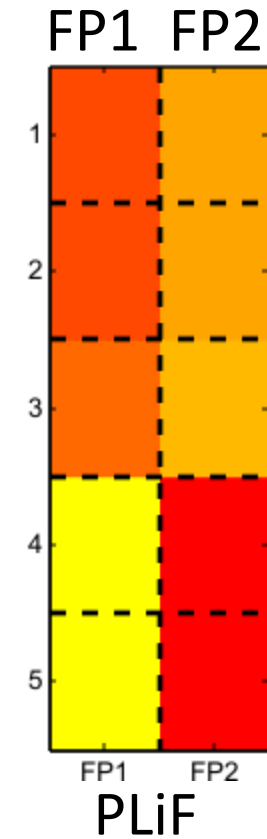
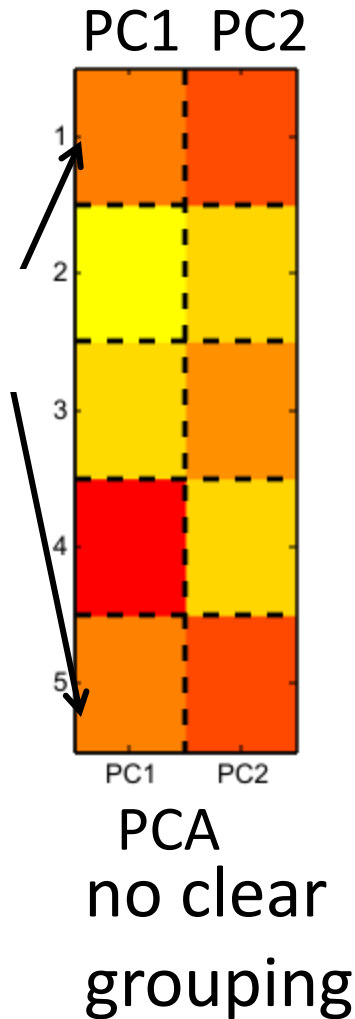
How to extract fingerprints?



For expert: Why not SVD/PCA?



Confused!



Beyond features

Find good/interpretable fingerprints for

requirements

- (a) lag independent
- (b) frequency proximity
- (c) grouping harmonics

functional goals



Good Clustering



Good compression



Ability to forecast

computational goals



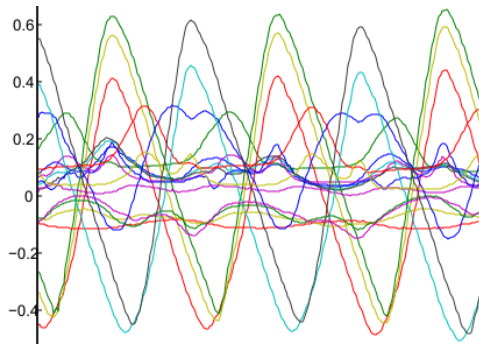
Scalability

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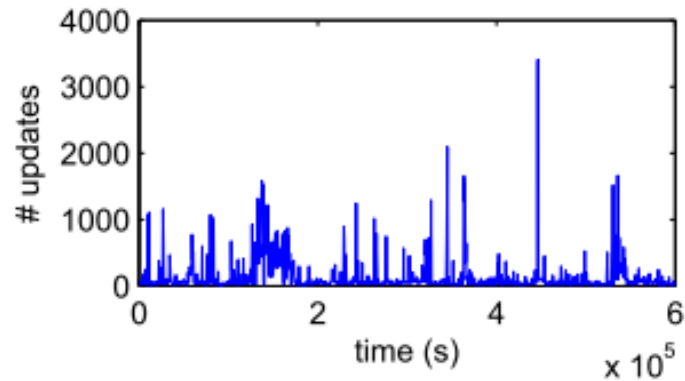
Datasets

Mocap



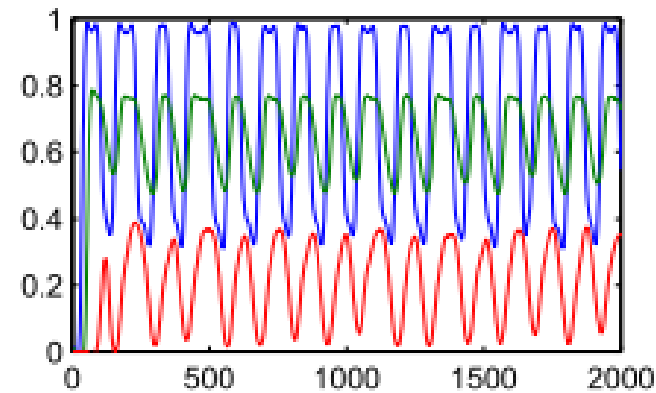
Size: 49×100 -500
mocap.cs.cmu.edu

BGP network traffic



Size: 10×103 k
www.datapositionary.net

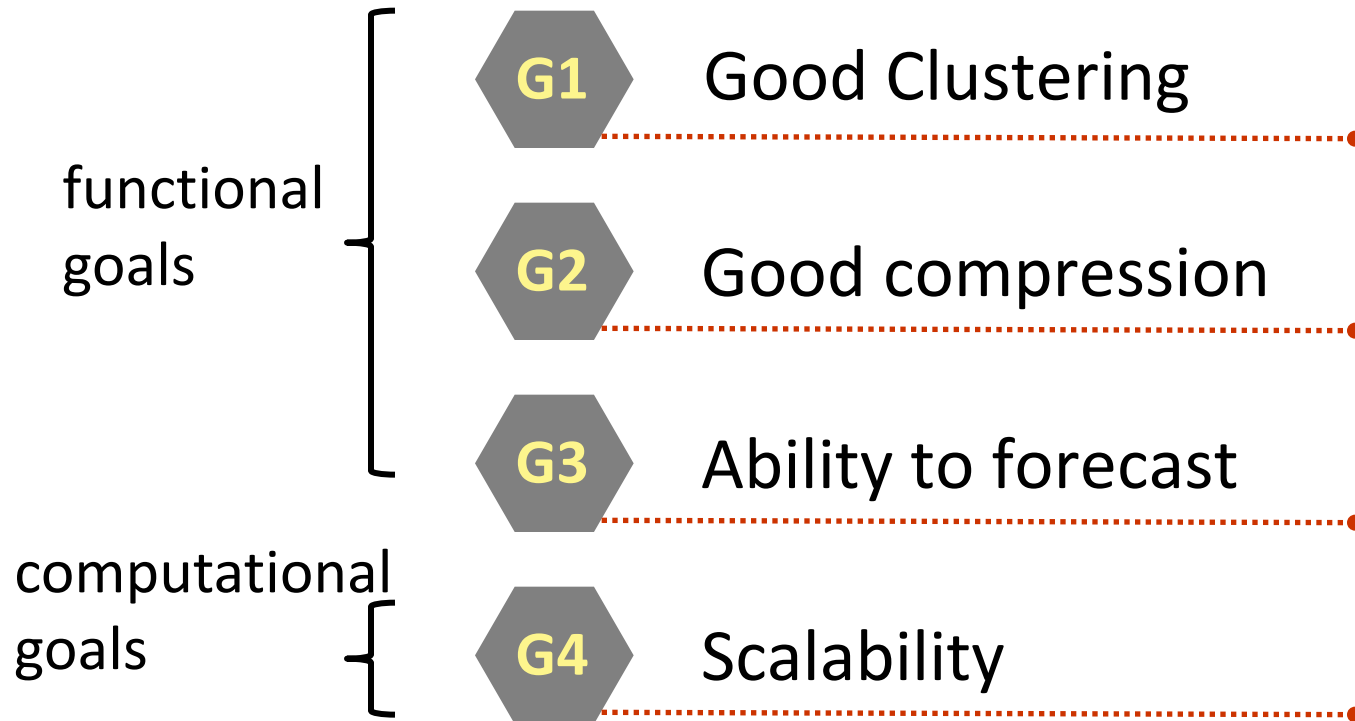
Chlorine



Size: 166×4 k
courtesy of
Prof. J. M. VanBriesen

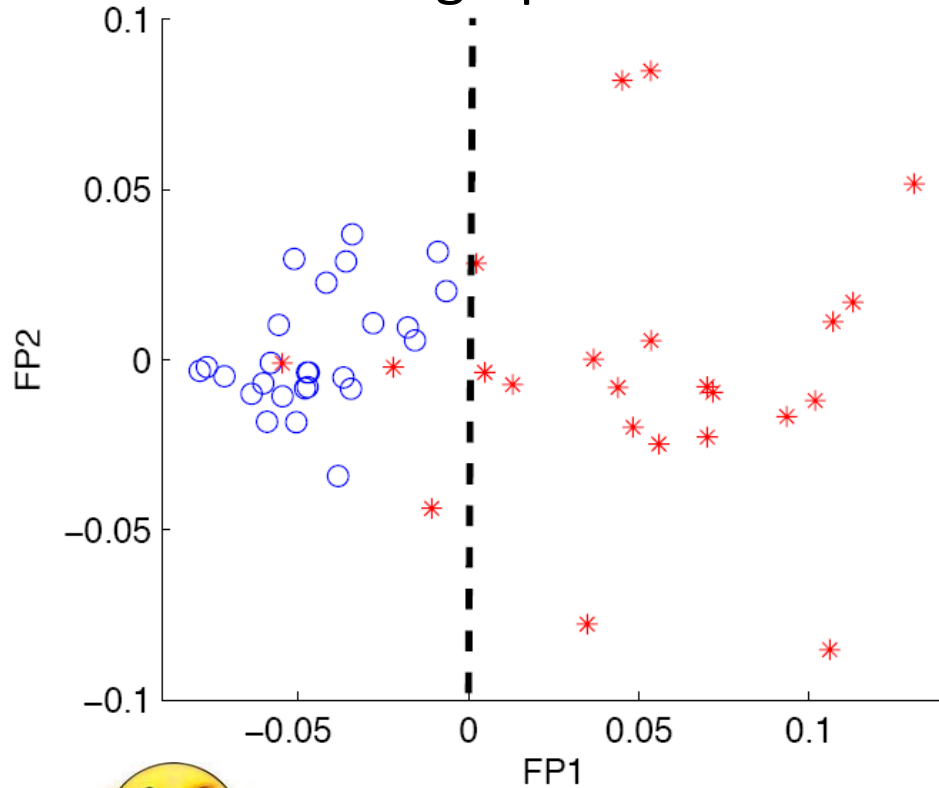
Experiment: Goals to meet

Find good/interpretable fingerprints for



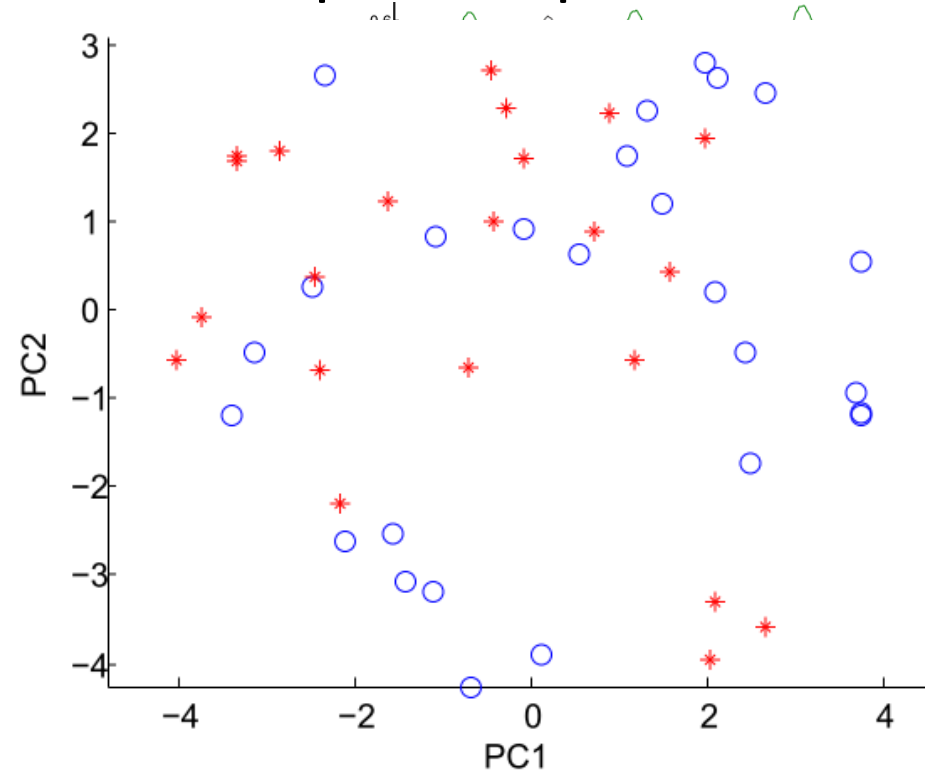
Result – Clustering

PLiF two “fingerprints”



Accuracy = **93.9%**

PCA top 2 components



Accuracy = **51.0%**

○ walking motion * running motion

Result – Clustering

BGP data: PLiF + hierarchical clustering



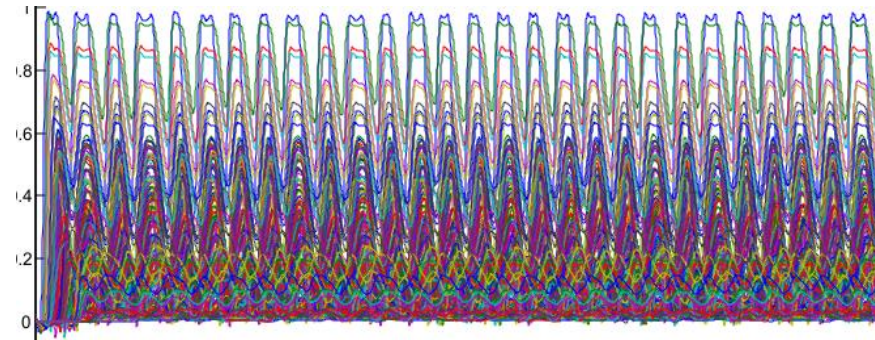
Experiment: Goals

Find good/interpretable fingerprints for

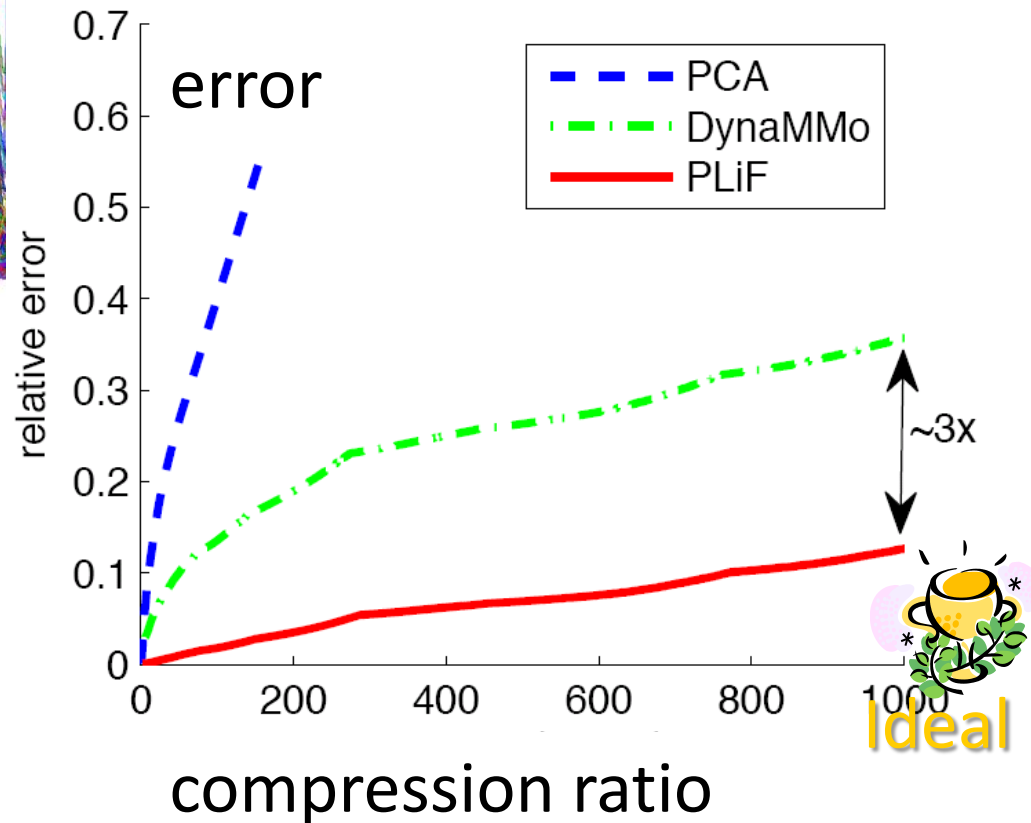
-  **G1** Good Clustering
- G2** Good compression
- G3** Ability to forecast
- G4** Scalability

Result - Compression

Chlorine 166 * 4k

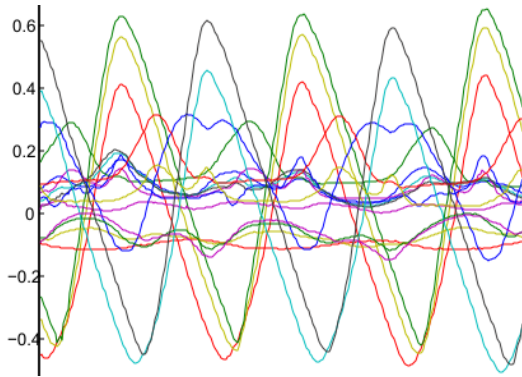


Storing only the PLiF features
& sampling of hidden variables



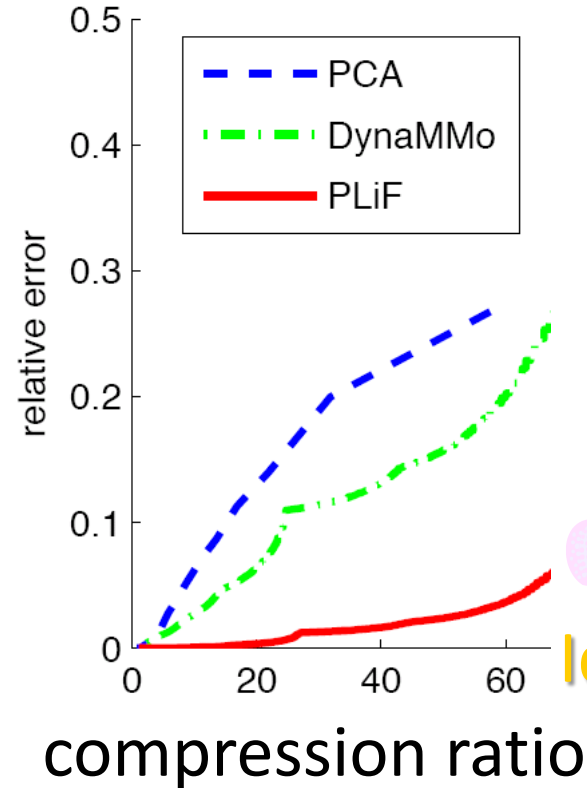
Result - Compression

Mocap: 93 * 300



Storing only the PLiF features
& sampling of hidden variables

error

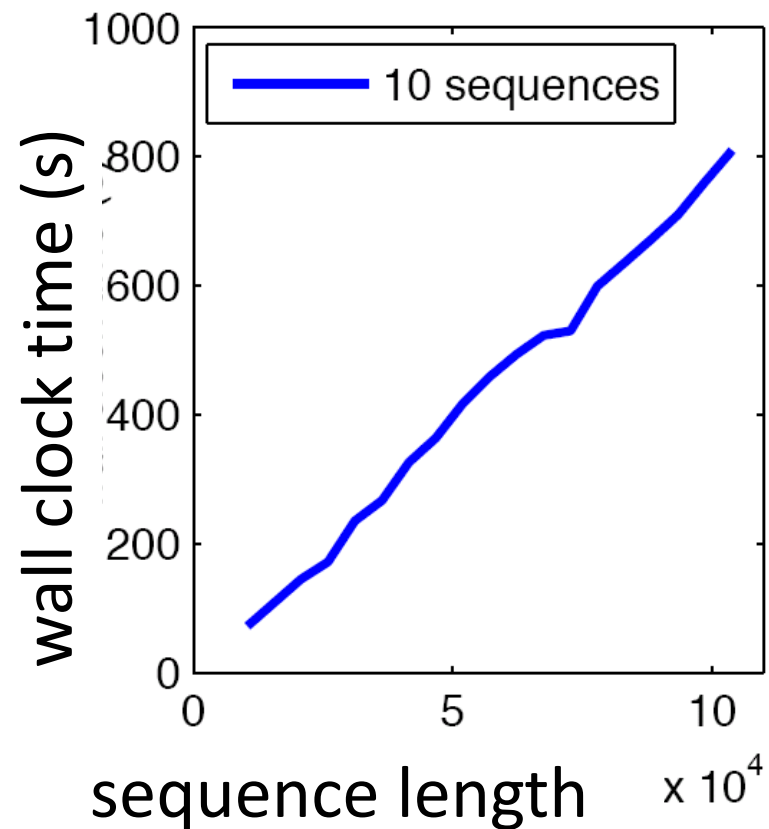
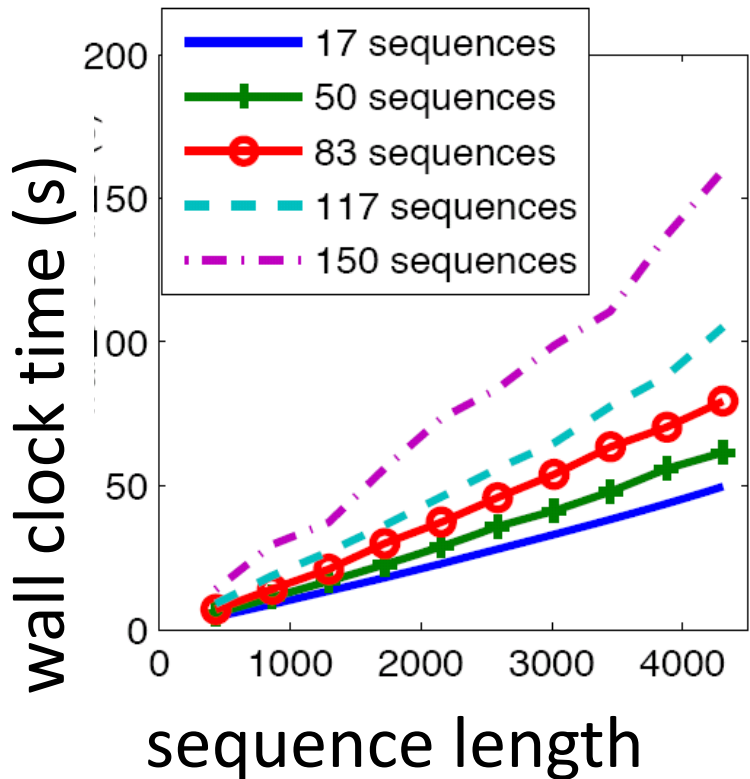


Experiment: Goals

Find good/interpretable fingerprints for

-   **G1** Good Clustering
-   **G2** Good compression
- later  **G3** Ability to forecast
-  **G4** Scalability

Scalability



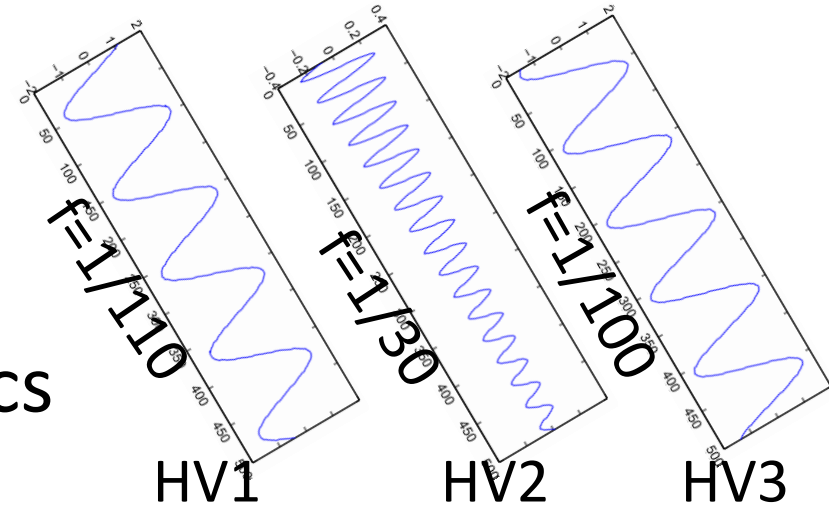
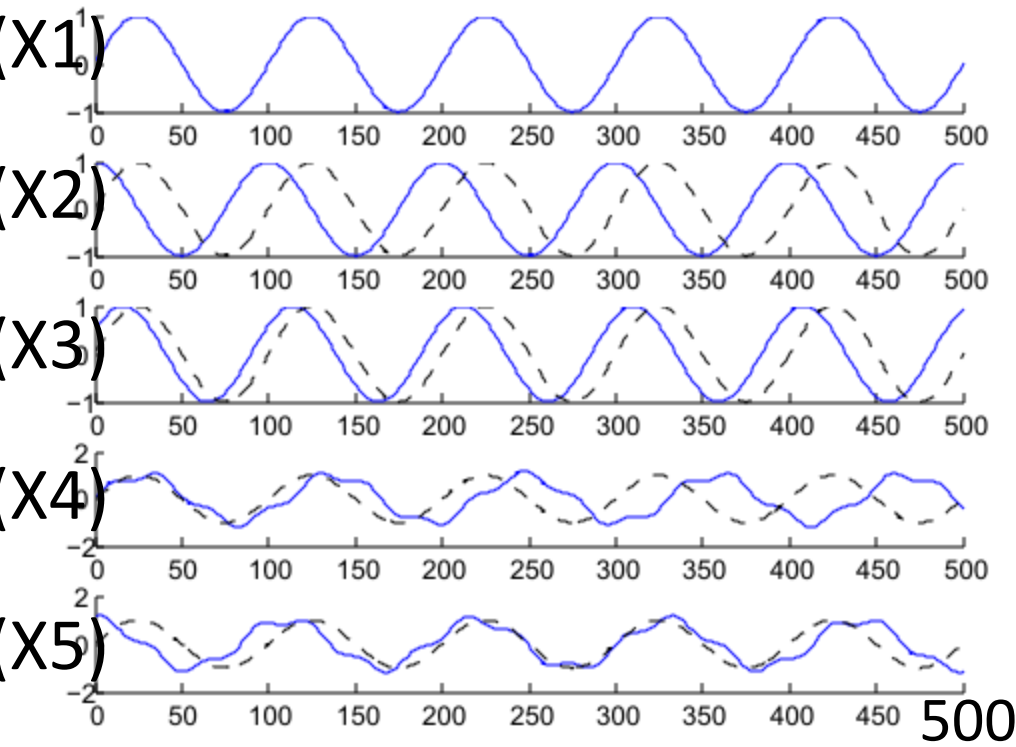
Linear to sequence length!

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how PLiF works?

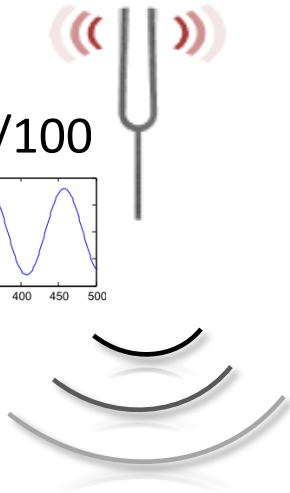
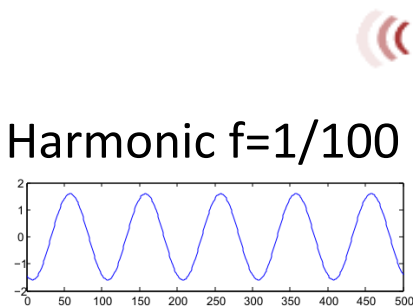
find hidden variable/harmonics



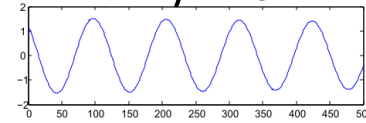
	0	+	1.0	+	0
	0	+	1.0	+	0
	0	+	0.9	+	0
	1.0	+	0	+	1.0
	1.0	+	0	+	1.0

Mixing weights

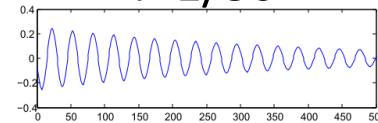
An Analog of Hidden Variables



harmonics
 $f=1/110$



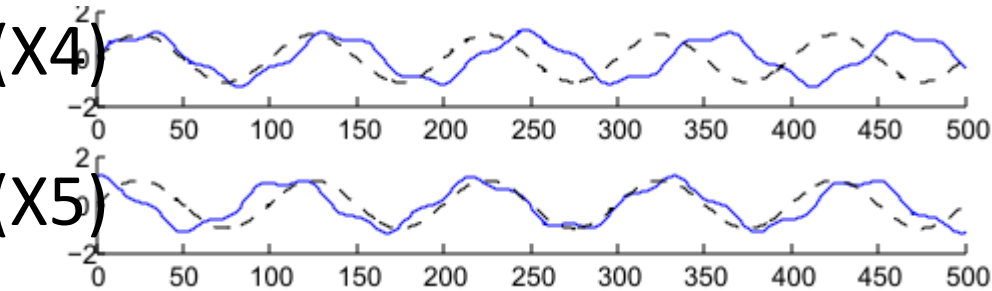
$f=1/30$



Mixing weights = participation strength of sound sources in observation (mic.)

Grouping Correlated Harmonics

$$HV1' = \{HV1, HV2\}$$

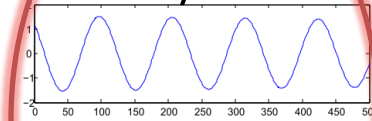


(X4)

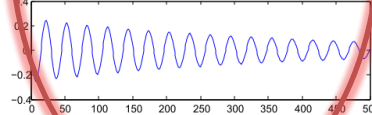


(X5)

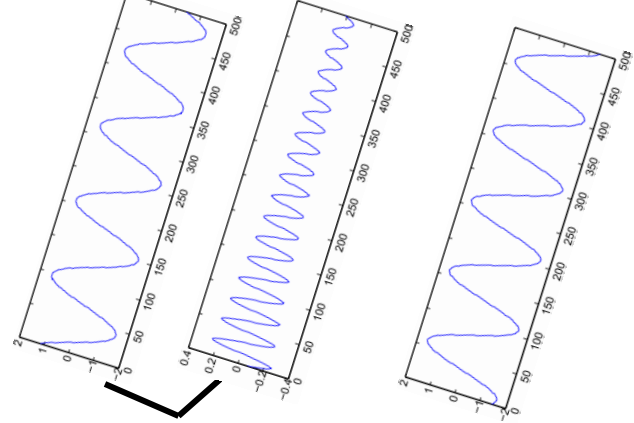
harmonics
 $f=1/110$



$f=1/30$

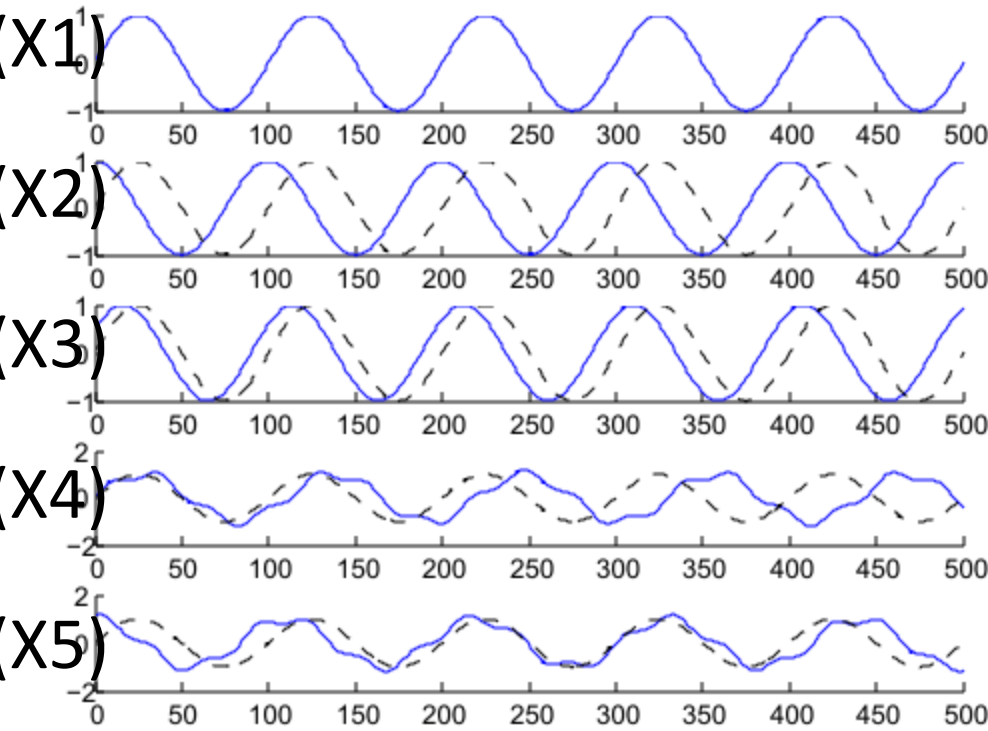


Fingerprints



HV1'

HV2' (=HV3)



0



1.0



0



1.0



0



0.9



1.0



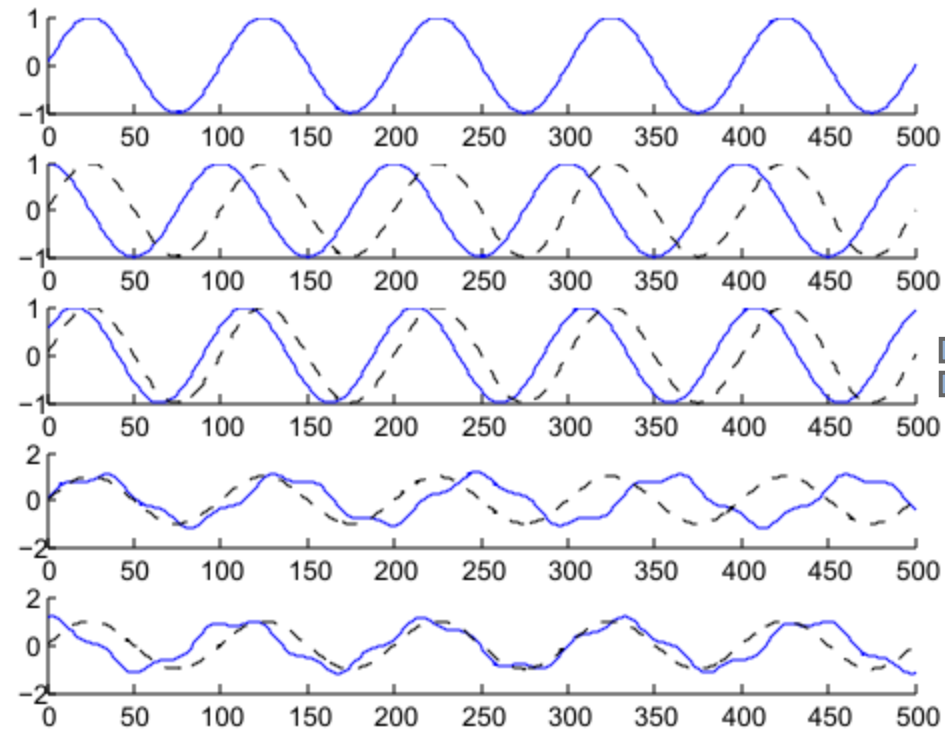
0



1.0



0

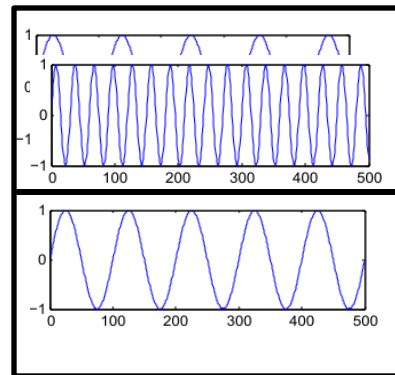


=

1	0	1.0
2	0	1.0
3	0	0.9
4	1.0	0
5	1.0	0
	FP1	FP2

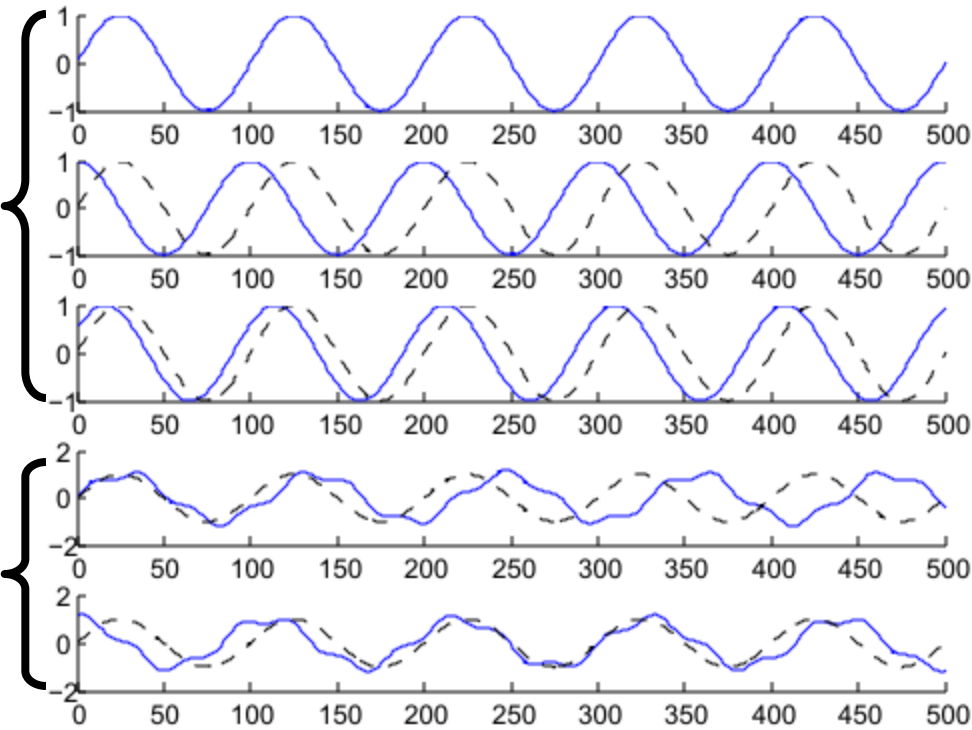
"X"

HV1'



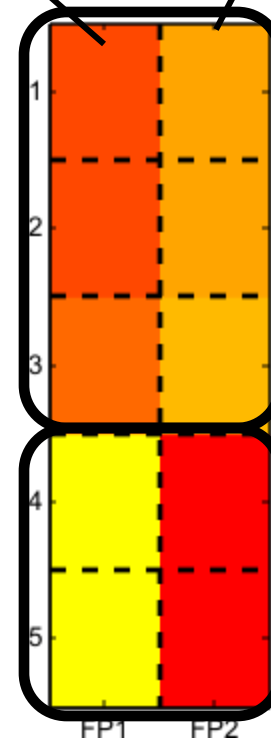
HV2'

How to interpret?

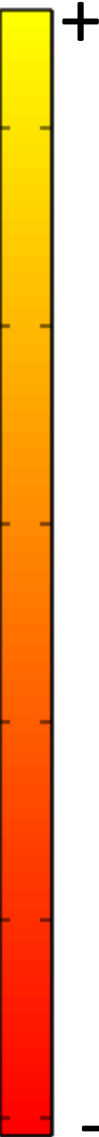


Group of
harmonics
 $1/110$ &
 $1/30$


harmonic.
 $1/100$







Proposed PLiF



Outline

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Steps of PLiFL: Overview

- | | | |
|---|------------------------|--------------------------|
|  S1 | Learning Dynamics | Kalman/LDS |
|  S2 | Finding Canonical Form | Eigenvalue decomposition |
|  S3 | Handling the Lag | |
|  S4 | Grouping Harmonics | SVD |

Why to do ...?

Requirements fingerprints

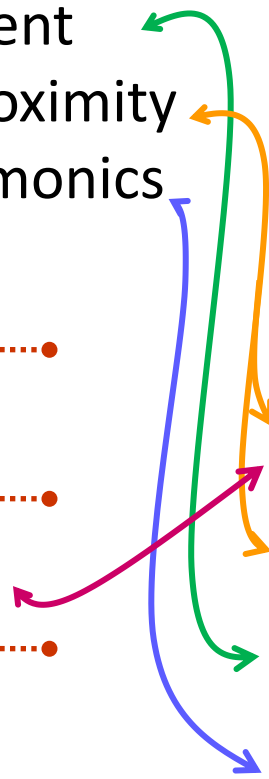
- (a) lag independent
- (b) frequency proximity
- (c) grouping harmonics

PLiF Goals

- G1** Good Clustering
- G2** Good compression
- G3** Ability to forecast
- G4** Scalability

PLiF alg. steps

- S1** Learning Dynamics
- S2** Canonical Form
- S3** Handling Lag
- S4** Grouping Harmonics



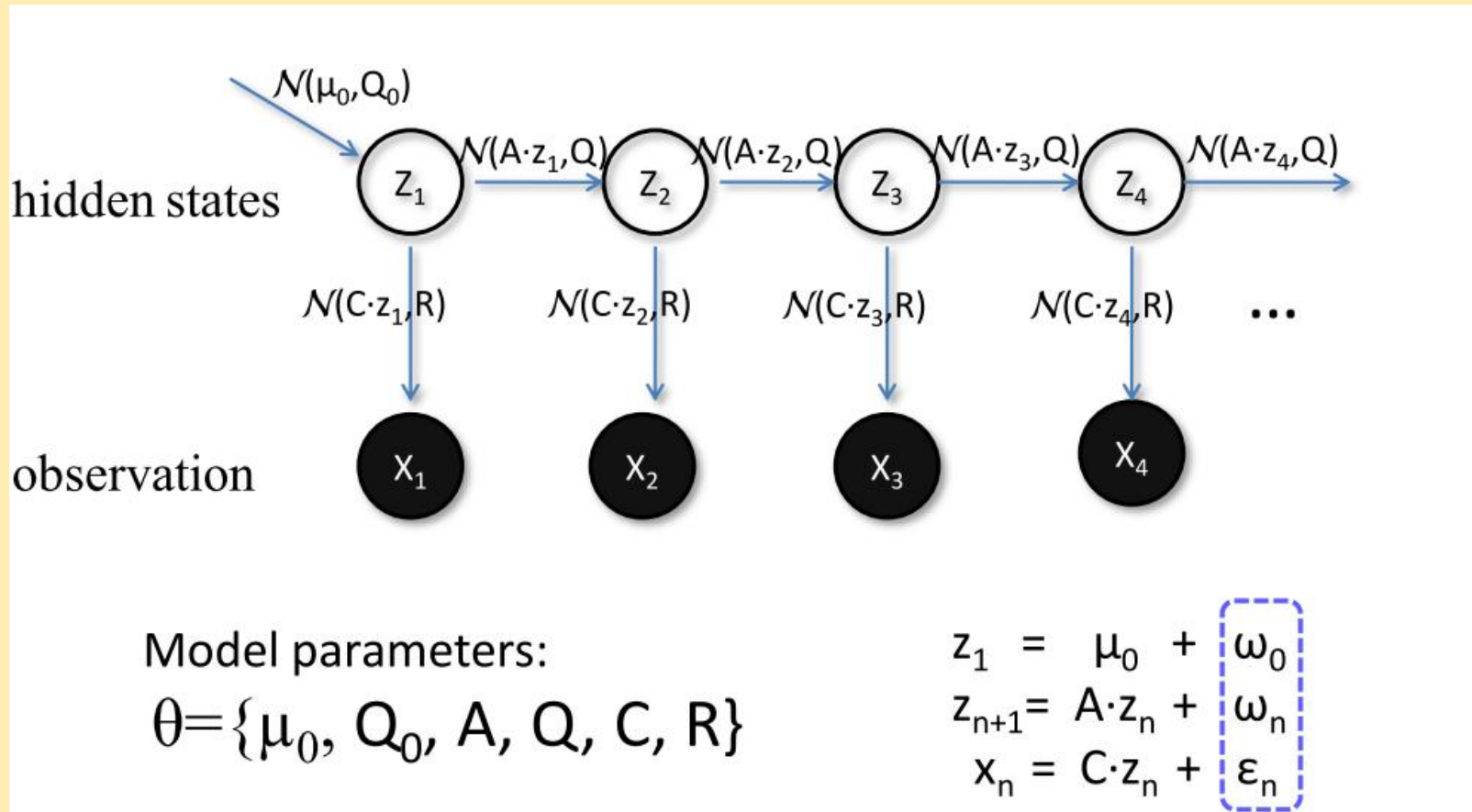
Warning!
A lot math
Only if you want to implement

<http://www.cs.cmu.edu/~leili/>

Step 1. Learning Dynamics

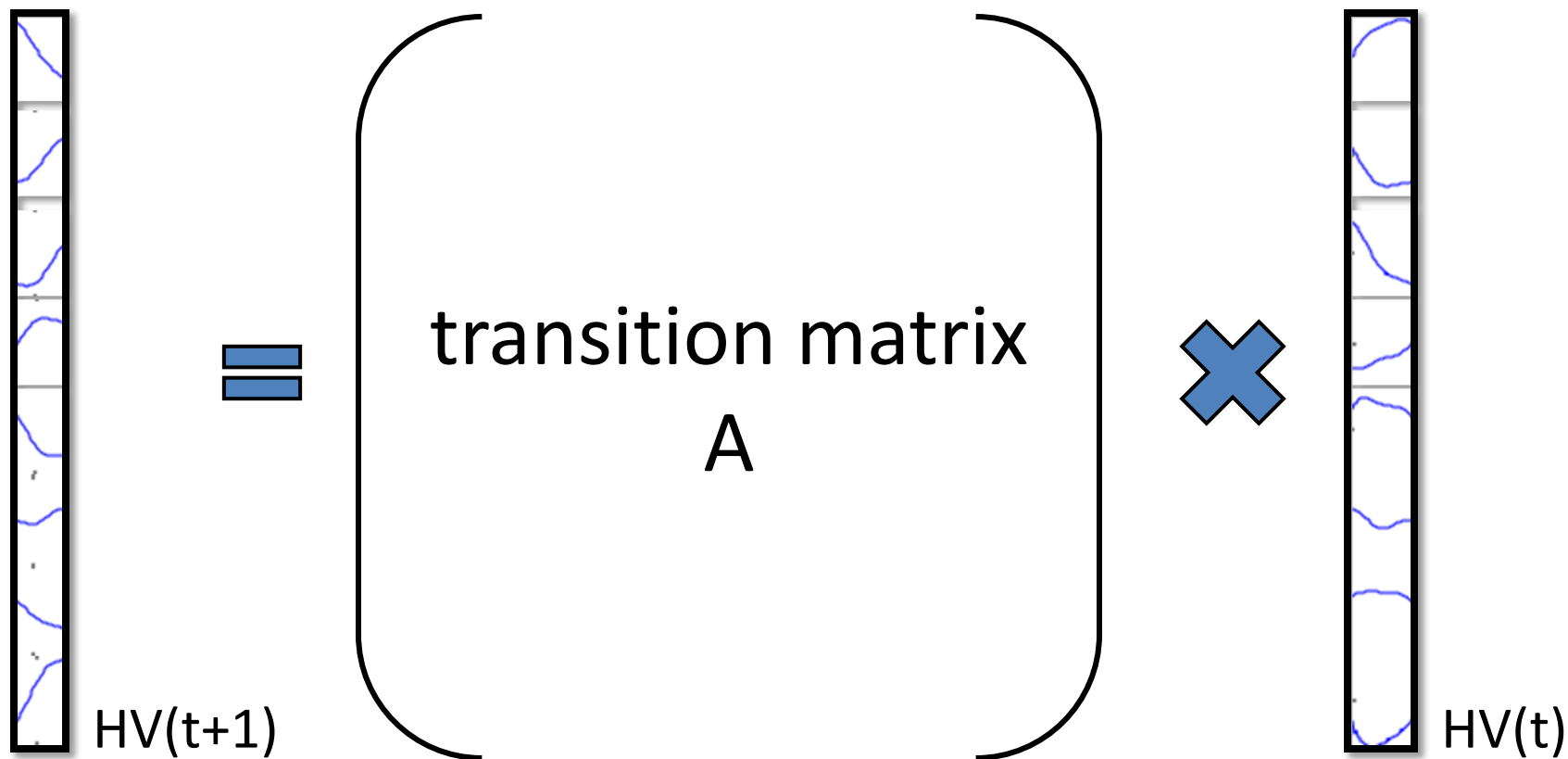
- Use Kalman filters / Linear Dynamical Systems (LDS) to learn the hidden variables

Underlying Model: Linear Dynamical Systems



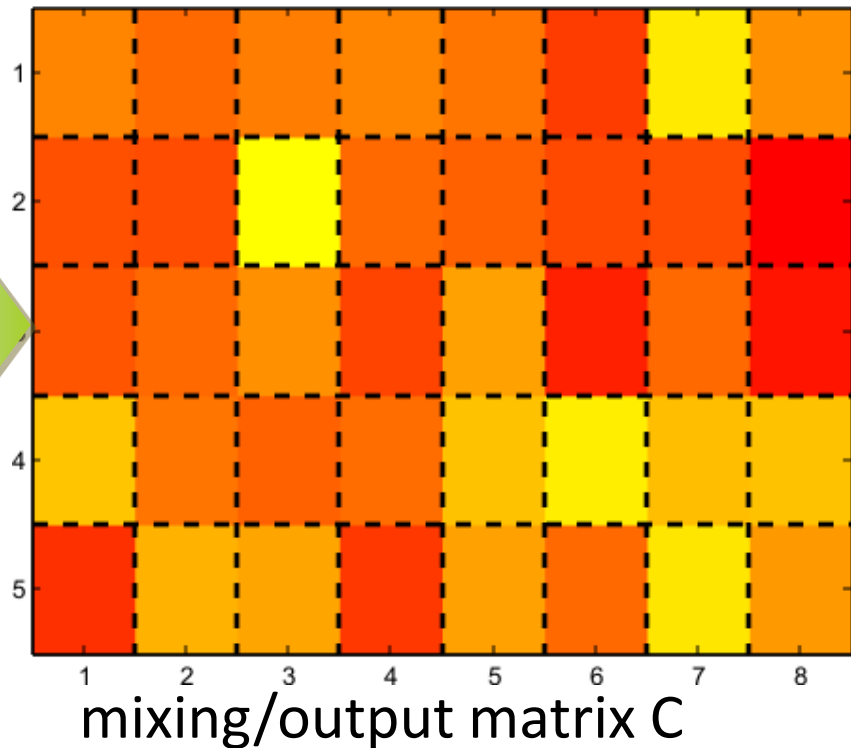
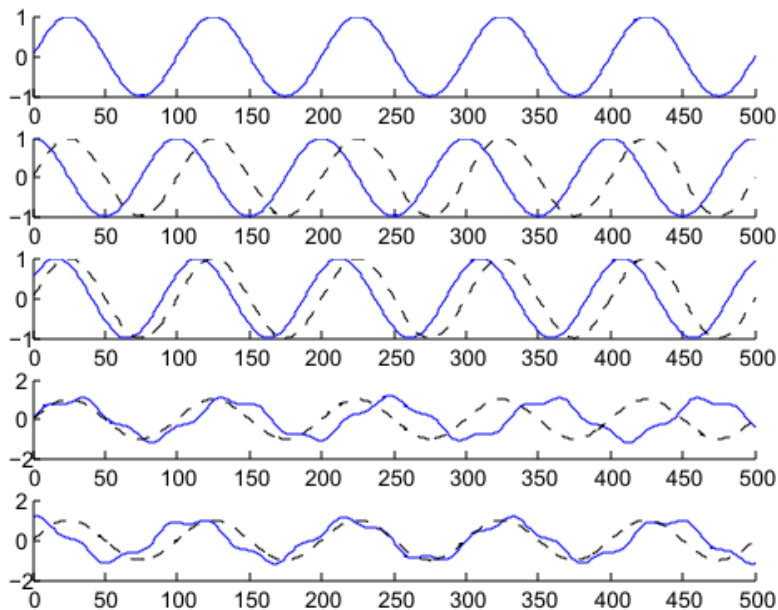
Dynamics/Transition in Hidden Variables

- enables forecasting



Learning Mixing Weights

Expectation-Maximization algorithm [Ghahramani 96]

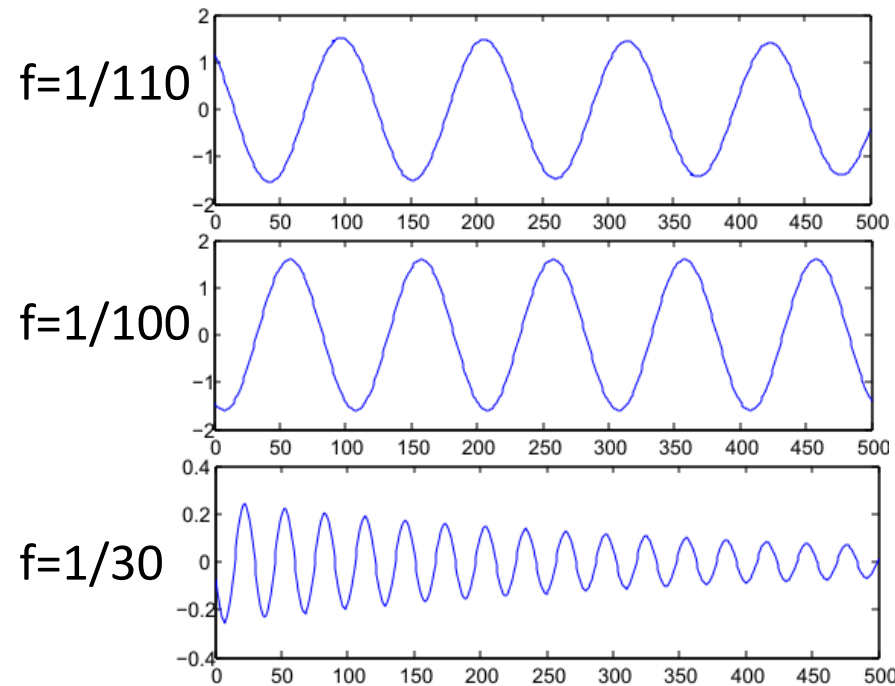
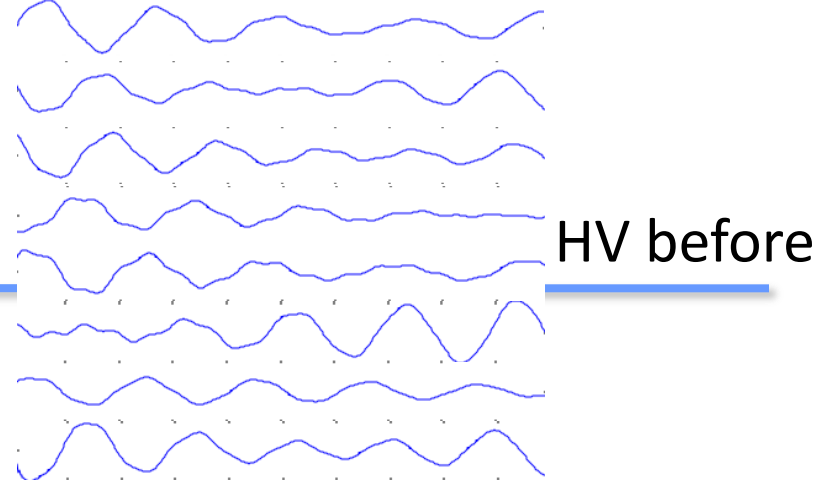


Step 2: Canonicalization

- Use eigen-decomposition on transition matrix A to find “harmonics” and mixing weight of harmonics

$$\text{find } \Lambda \ V$$
$$A \cdot V = \Lambda \cdot V$$

Canonicalization adds Interpretability



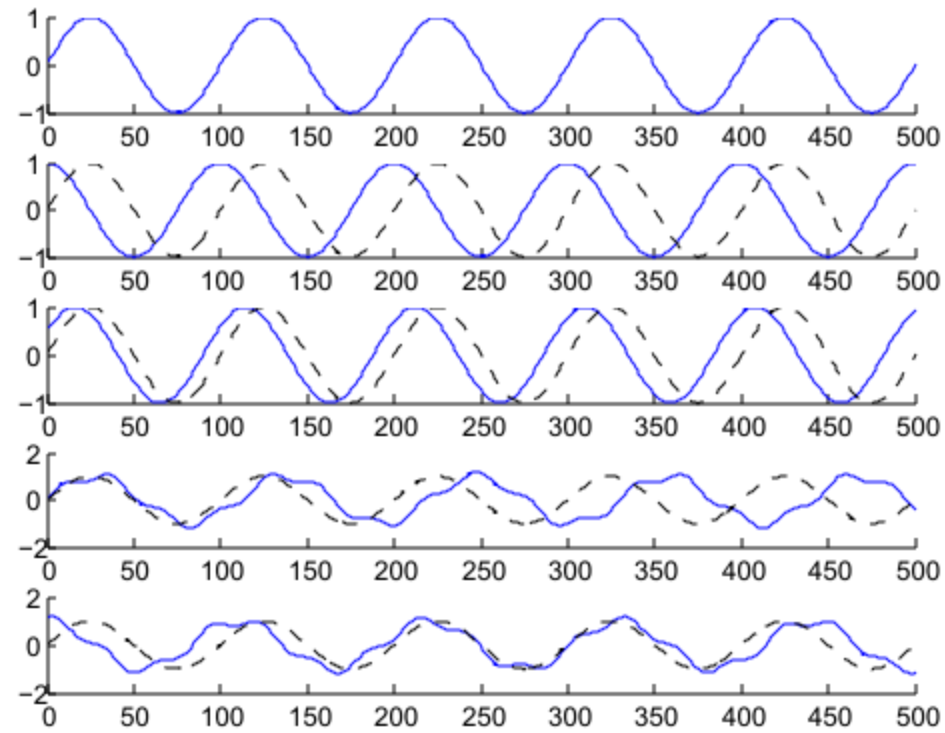
“Harmonics”

frequency

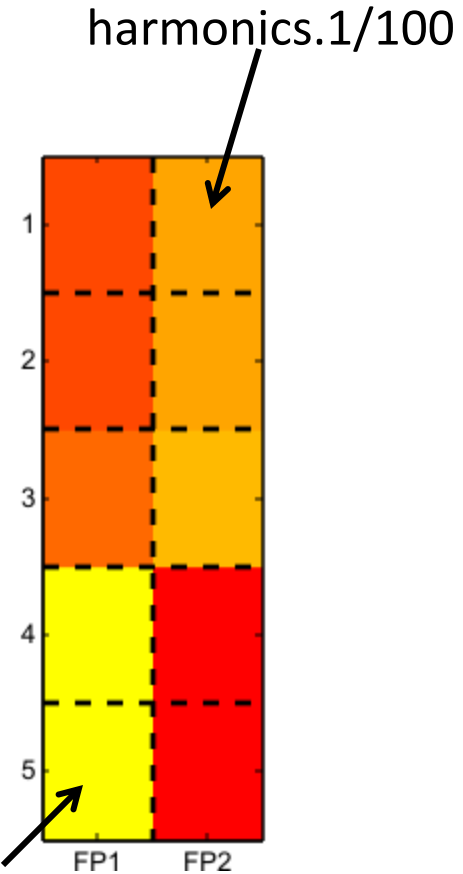
Growing/
shrinking
trend

Time series of HV after canonicalization (real part)

Step 4: Grouping Harmonics



Group of
harmonics
1/110 & 1/30



Conclusion

- Intuition of PLiF
 - three requirements of fingerprints
- How it works
 - Four steps in the algorithm
- What to do with PLiF
 - Similarity, clustering, compression, forecasting, etc.
- Experiments on a diverse set of data
 - It really works
 - It is fast & scalable

Overview

Requirements fingerprints

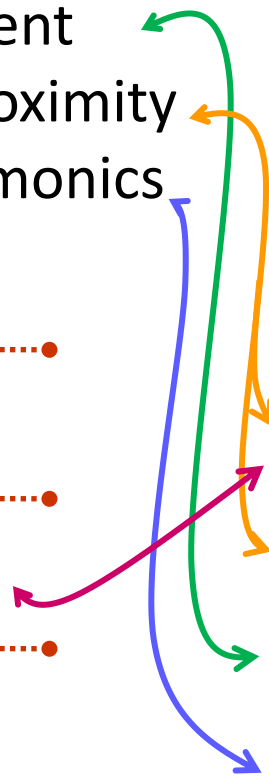
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- S3** Handling Lag
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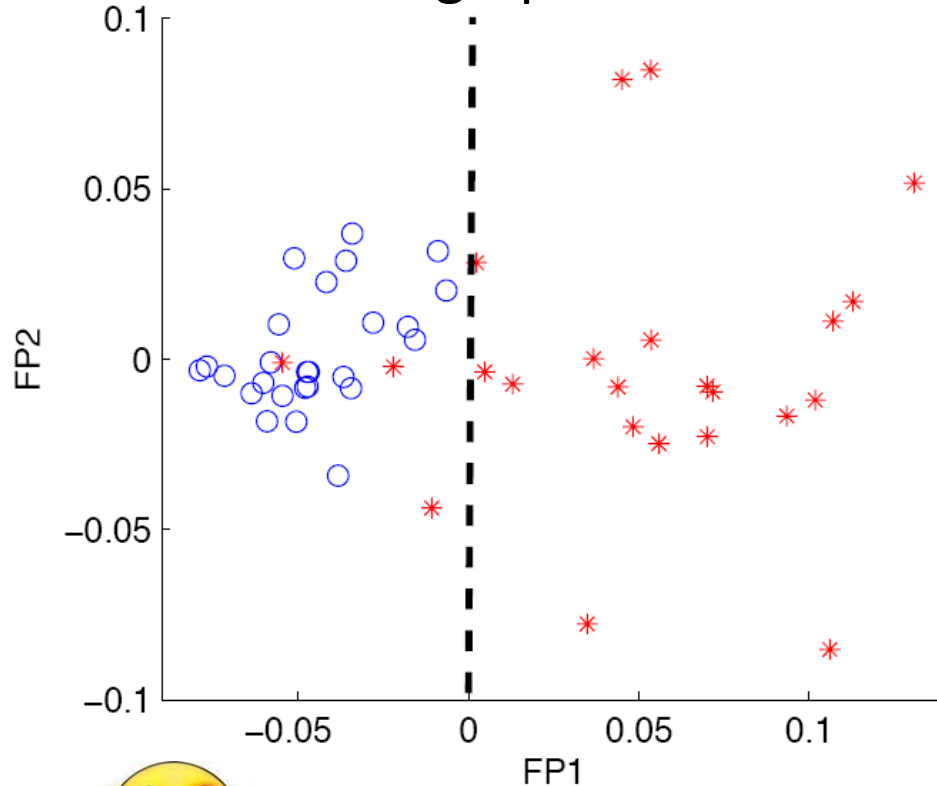


Future Work

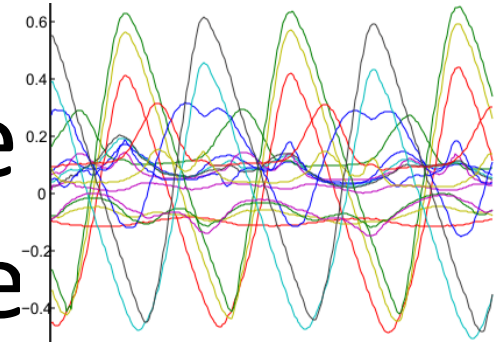
- Non-Gaussian noise
- Nonlinear transition

Thanks!

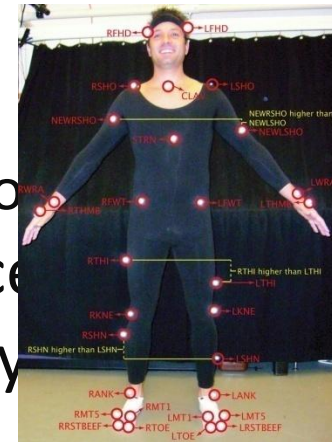
PLiF two "fingerprints"



← Line
or Time



Li
Vishal, Christo
Computer Science
Carnegie Mellon University



Accuracy = 93.9%

○ walking motion * running motion