Introduction



http://www.cs.cmu.edu/~16385/

16-385 Computer Vision Spring 2019, Lecture 1

Overview of today's lecture

- Teaching staff introductions
- What is computer vision?
- Course fast-forward and logistics

Teaching staff introductions

Instructor: Ioannis (Yannis) Gkioulekas

I won't hold it against you if you mispronounce my last name



Originally from Greece



National Technical University of Athens (2004-09)



Harvard University (2009-17)



Carnegie Mellon University (2017-now)

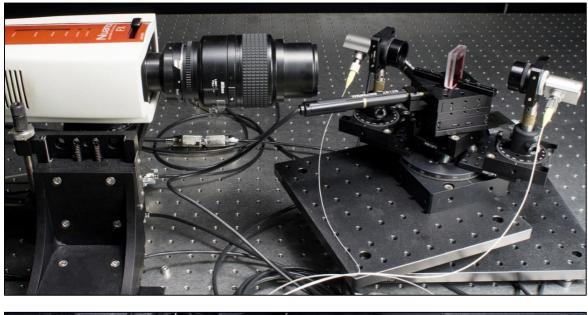
My website: http://www.cs.cmu.edu/~igkioule



me at Harvard in 2011 (obviously need new photo)

Building a scatterometer

Camera for measuring parameters of scattering materials



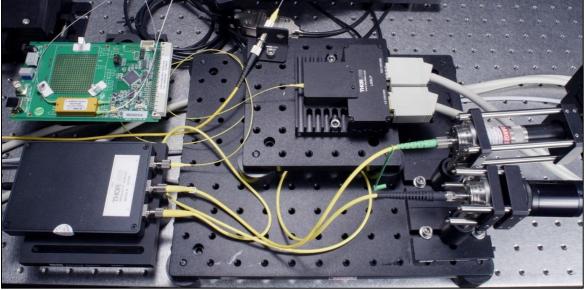
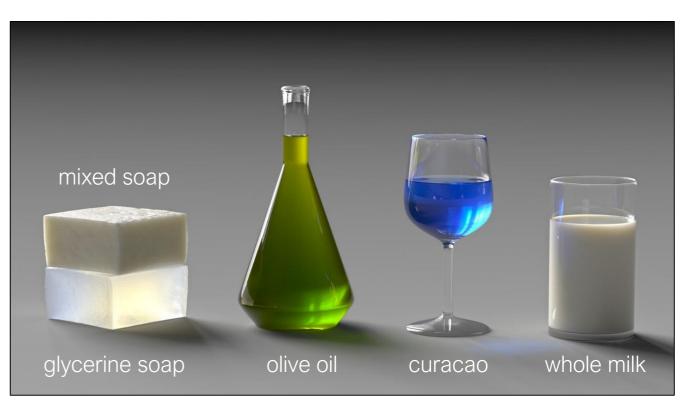
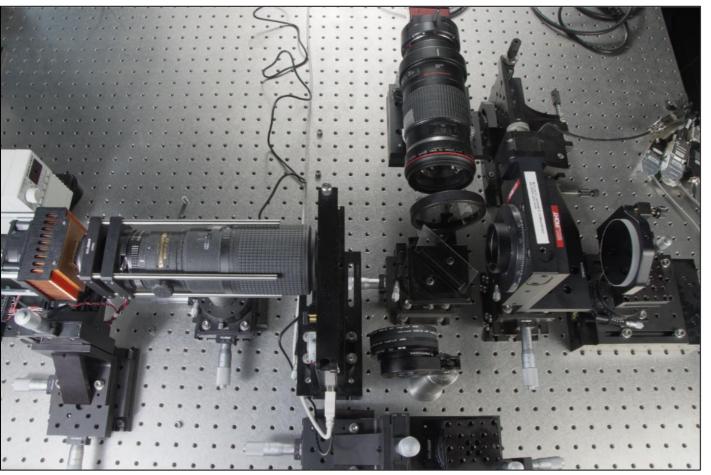


image synthesized from measurements



Quadrillion FPS video

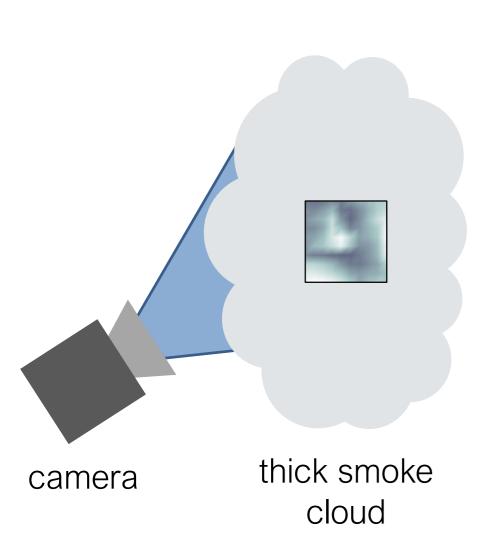




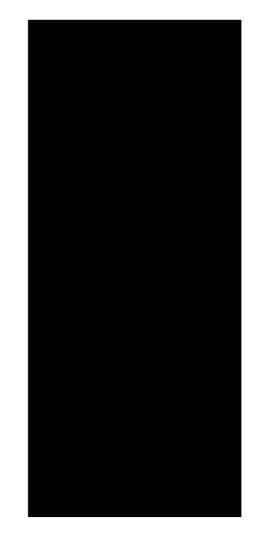




Seeing inside objects





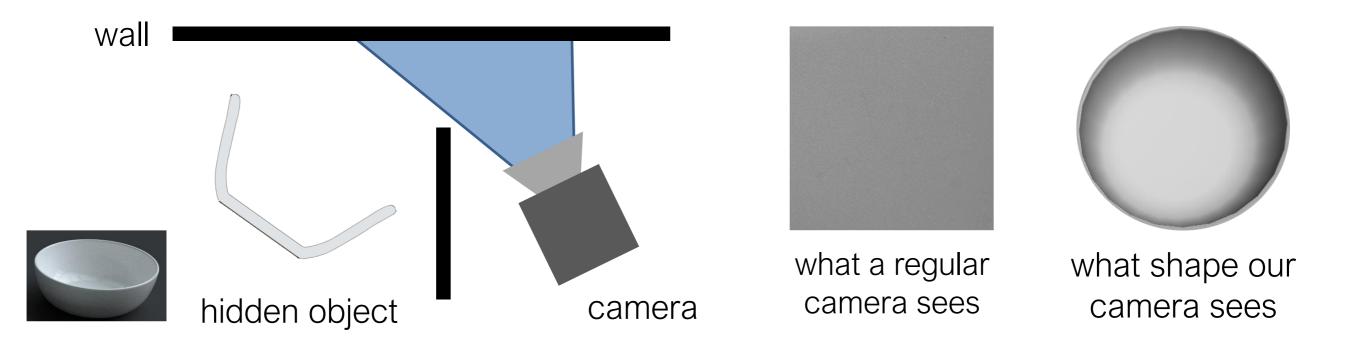


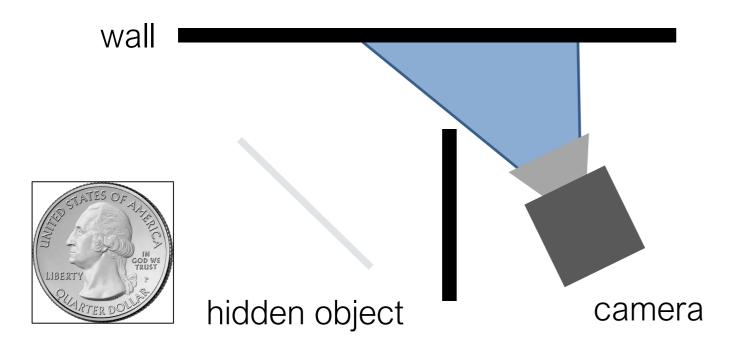


what a regular camera sees

what our camera a slice through the sees cloud

Seeing around walls







what a regular camera sees



what depth our camera sees

TA: Sharvani Chandu

Master of Science in Computer Vision (MSCV)

Research Interests Multimodal machine learning, Deep Learning, Medical Image Processing

Current Area of Research Sony Chef – Learning a Simulator for Cooking (under Prof. Katerina)



Past Research

- Micro Aneurysm detection using deep learning
- Automatic target extraction from satellite images
- Text summarization and intent extraction from documents

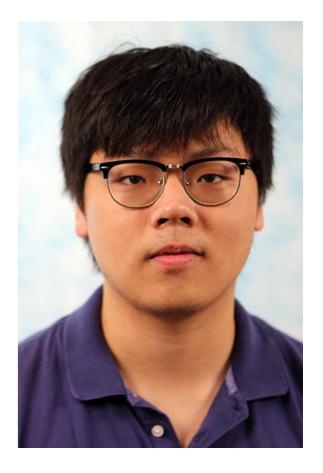
TA: Chengqian Che(Bruce)

Ph.D in Robotics

Research Interests Physics-based Vision; Computer graphics; Deep learning

Current Research area Inverse rendering/ Differentiable rendering; Material inference

Past Research Medical imaging analysis; Ultrasound imaging segmentation/registration



TA: Abhay Gupta

- Master of Science in Computer Vision (MSCV)
- Research Interests:
 - Multi-View Stereo, Video Context Understanding, Visual Reinforcement Learning
- Current Areas of Research:
 - Trajectory Prediction for Self-Driving Cars
- Past Research:
 - Partial Face Segmentation and Recognition
 - Action Recognition in Videos
 - Emotion Recognition in Videos



TA: Anshuman Majumdar

Master of Science in Computer Vision

Research Interests

Object Detection, Tracking and Pose Estimation SLAM and Tracking for AD/AR/VR OCR and Analysis of Handwritten Document Images

Current Area of Research

Visual Inspection for Aircraft and Power Lines

Past Research

- Robust 6-DoF Positional Tracking in presence of Motion Blur for AR/VR
- Monocular Reconstruction of Vehicles on Graded Roads in Dynamic Scenes
- Roadsign Detection, Tracking and Classification
- Visual Aesthetic Analysis for Handwritten Document Images



TA: Neeraj Sajjan

Master of Science in Computer Vision[MSCV]

Research Interests:

3D Vision, Deep Learning, Object Detection and Tracking

Current Area of Research:

Deep 3D Mesh Reconstruction

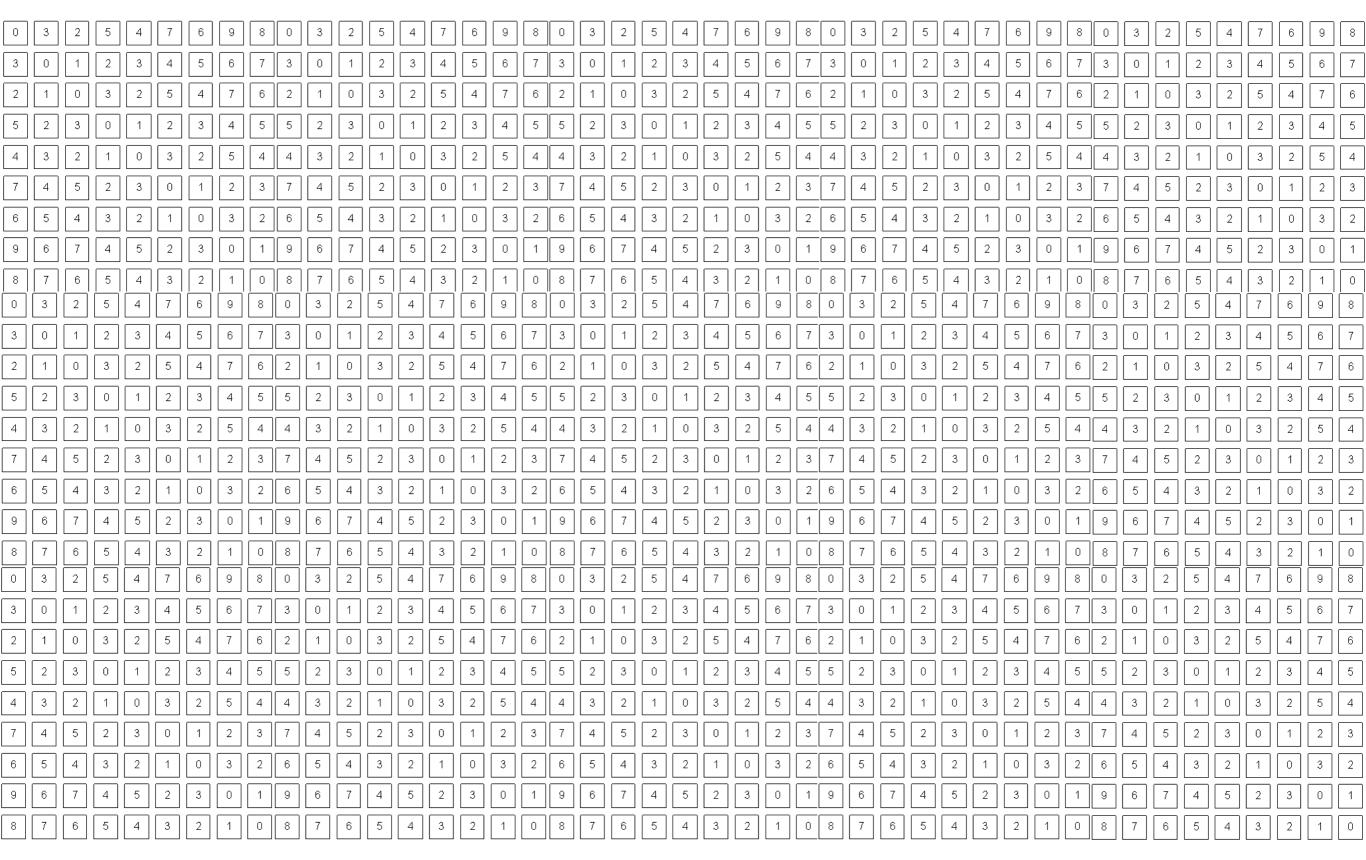
Past Research:

- 3D Object Detection and Tracking
- Crowd Counting
- Overlapped Speech Detection



What is computer vision?

What a person sees



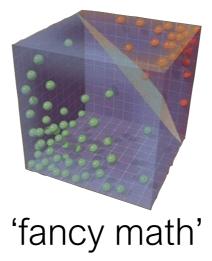
What a computer sees

Why are we able to interpret this image?

The goal of computer vision is to give computers (super) human-level perception

representation







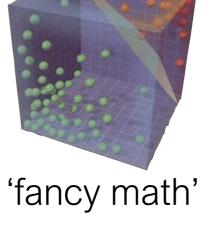
output

representation





what should we look at? (image features)

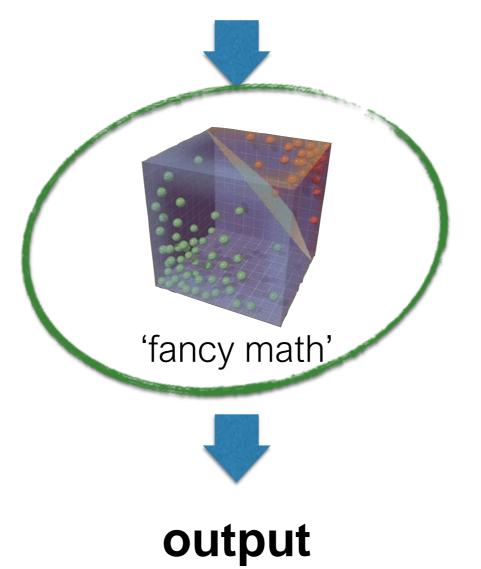




output

what can we understand? (semantic segmentation)

representation

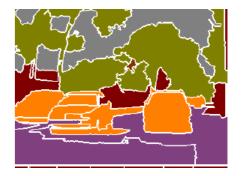


easy to get lost in

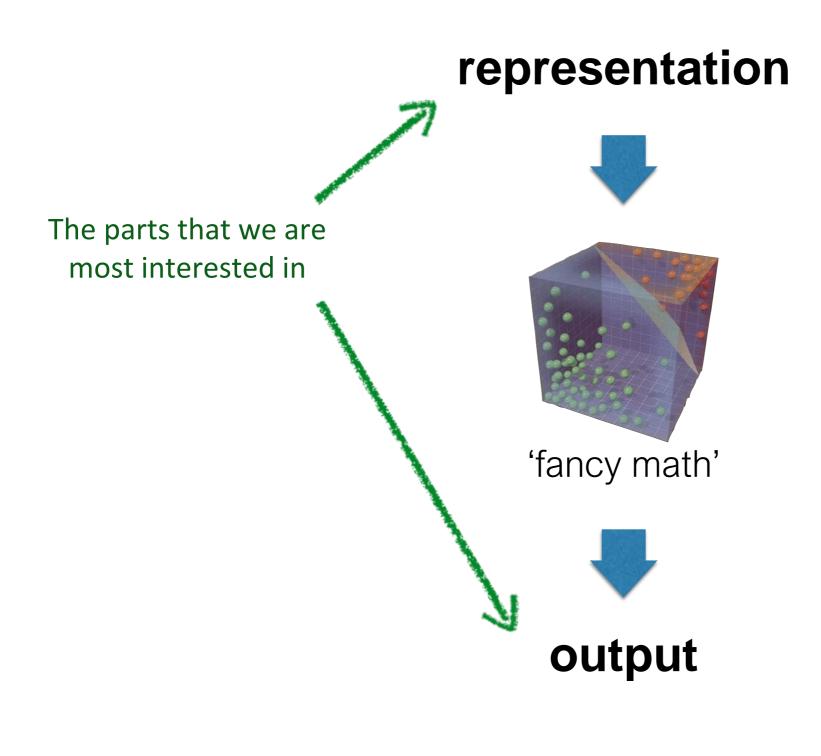
the techniques



what should we look at? (image features)

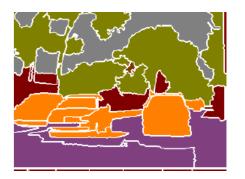


what can we understand? (semantic segmentation)





what should we look at? (image features)



what can we understand? (semantic segmentation)

Important note:

In general, computer vision does not work

Important note:

In general, computer vision does not work

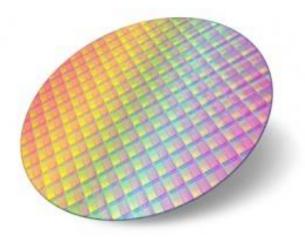
(except in certain situations/conditions)

Applications of computer vision

Machine vision

Automated visual inspection





Object Recognition



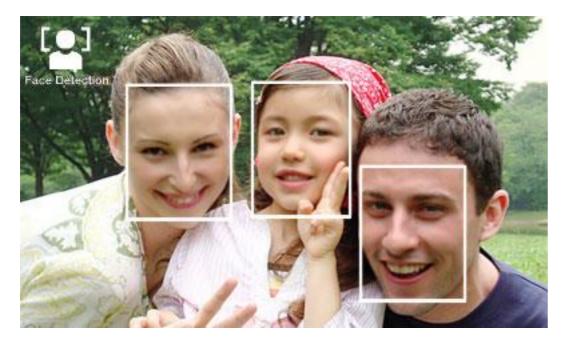
2013

Toshiba Tech IS-910T

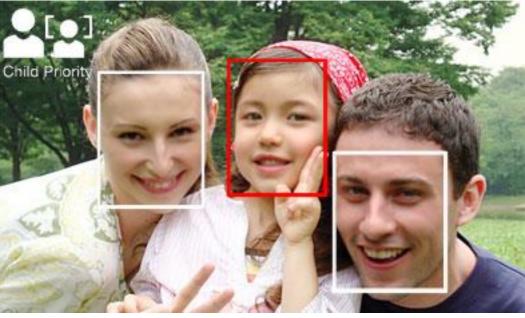


DataLogic LaneHawk LH4000 ²⁰¹²

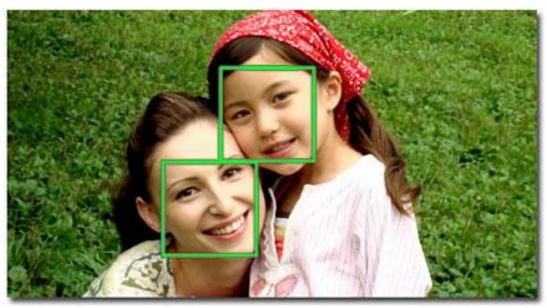
Face detection



Sony Cyber-shot

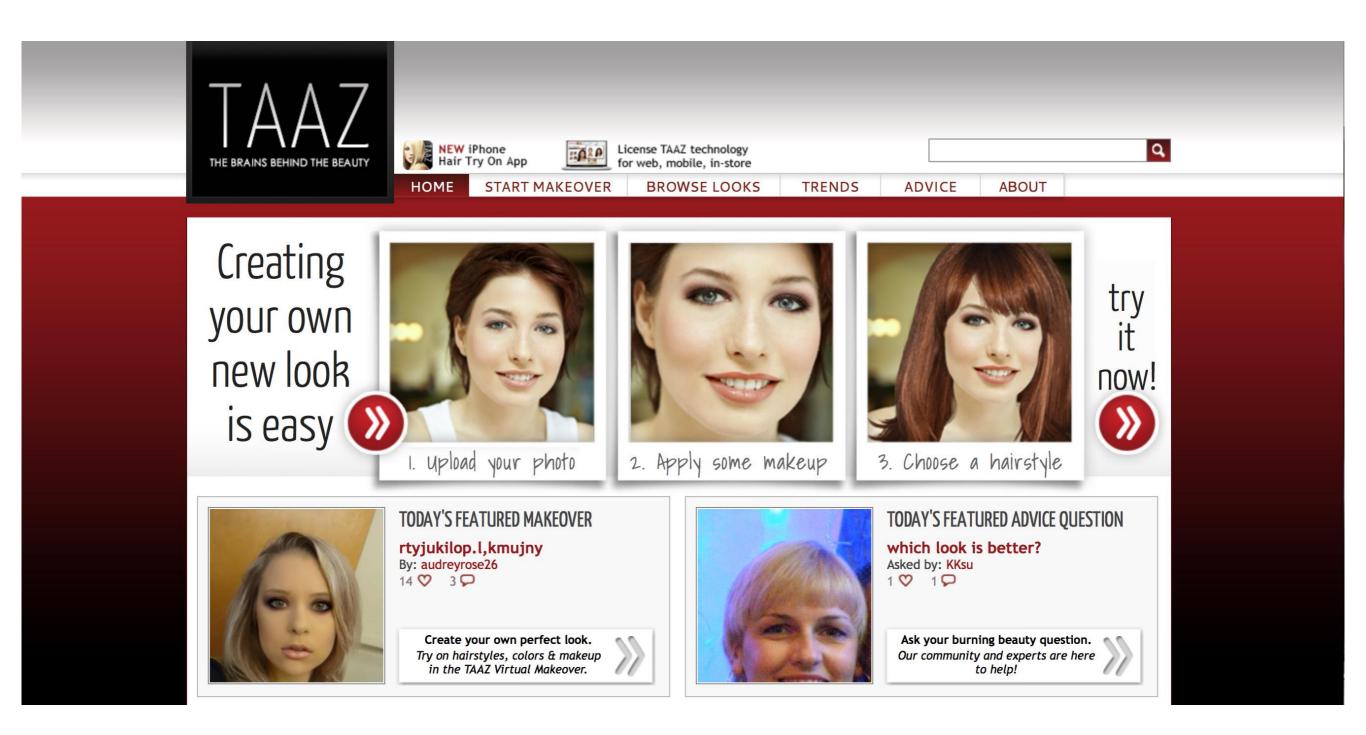


Age recognition



Smile recognition

Face makeovers









Word Lens



Word Lens

www.QuestVisual.com

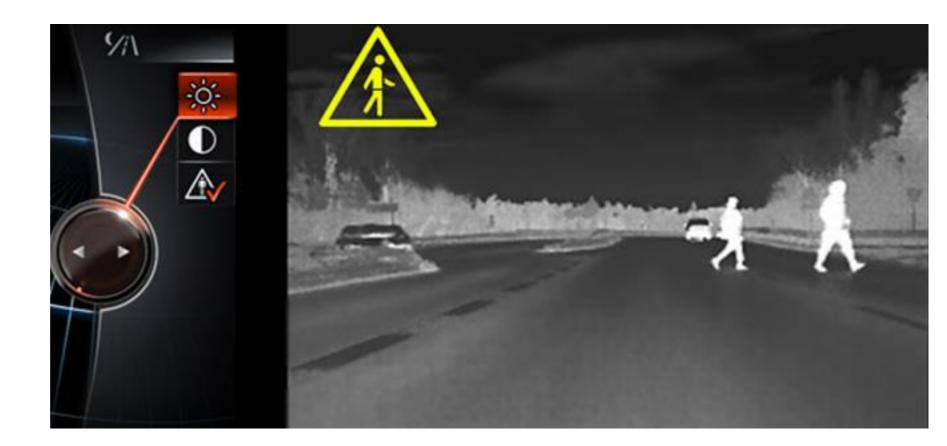
First-down line





BMW 5 series

BMW night vision

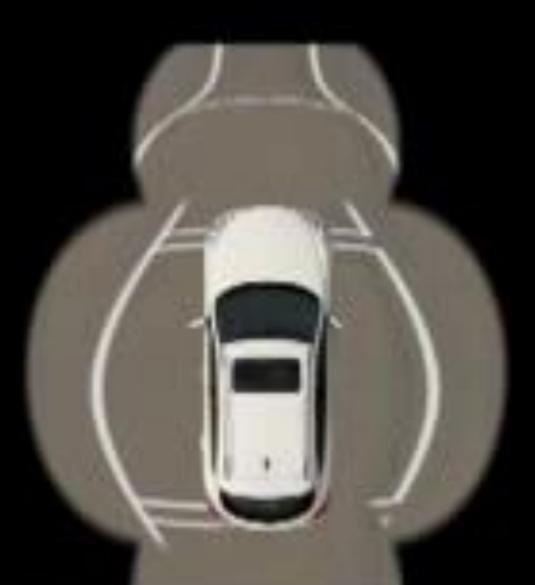




"Around view" camera

Infinity EX





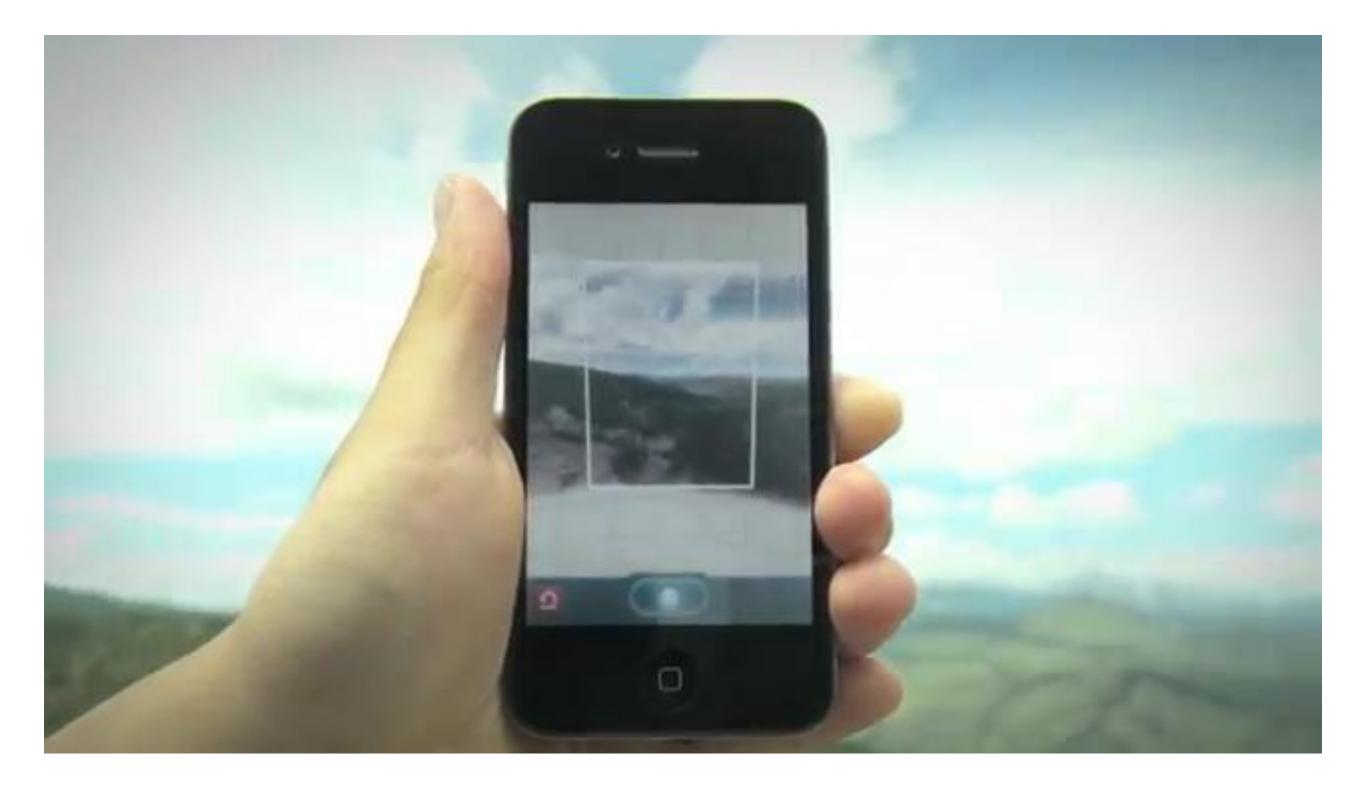
The system converts image data taken by 4 super-wide angle cameras, to display a virtual image of the vehicle from above.

2015

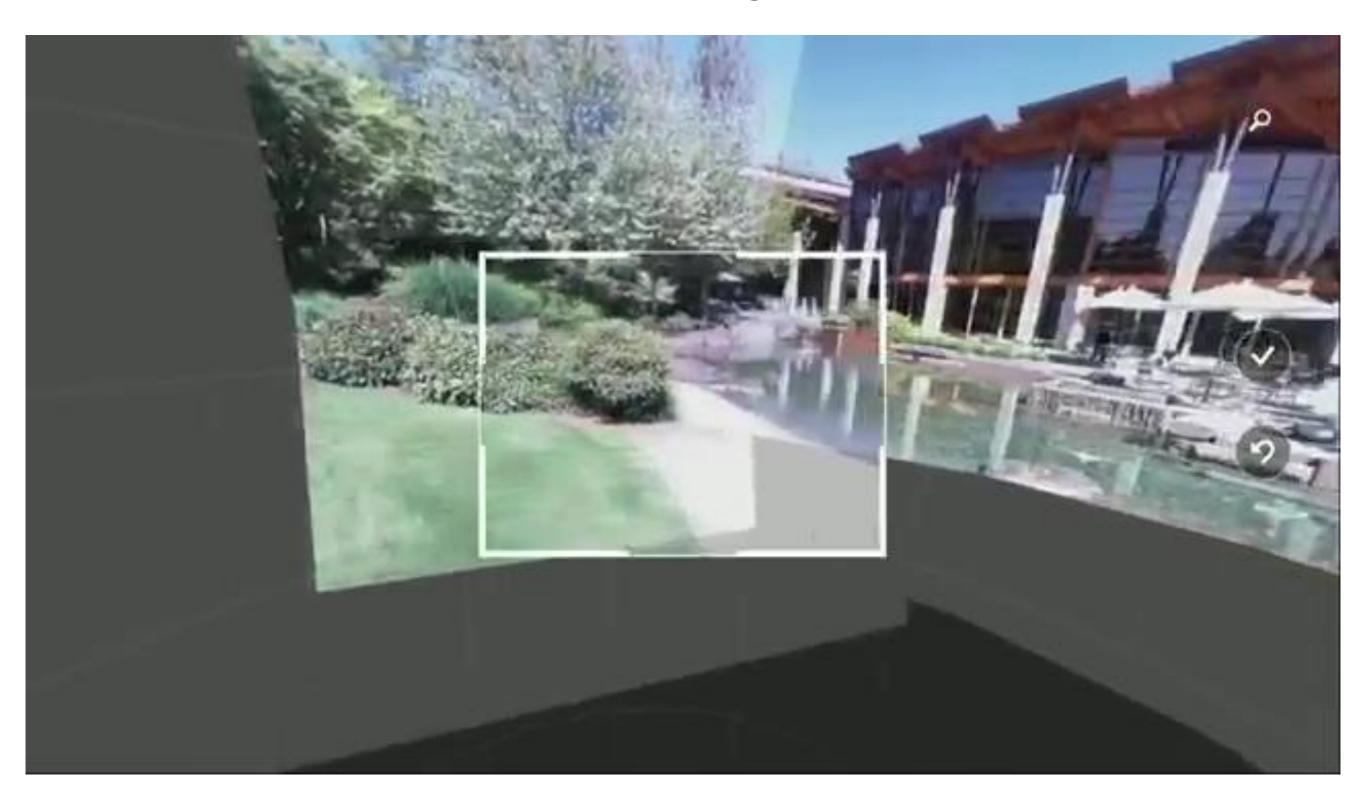
Vision in Cars



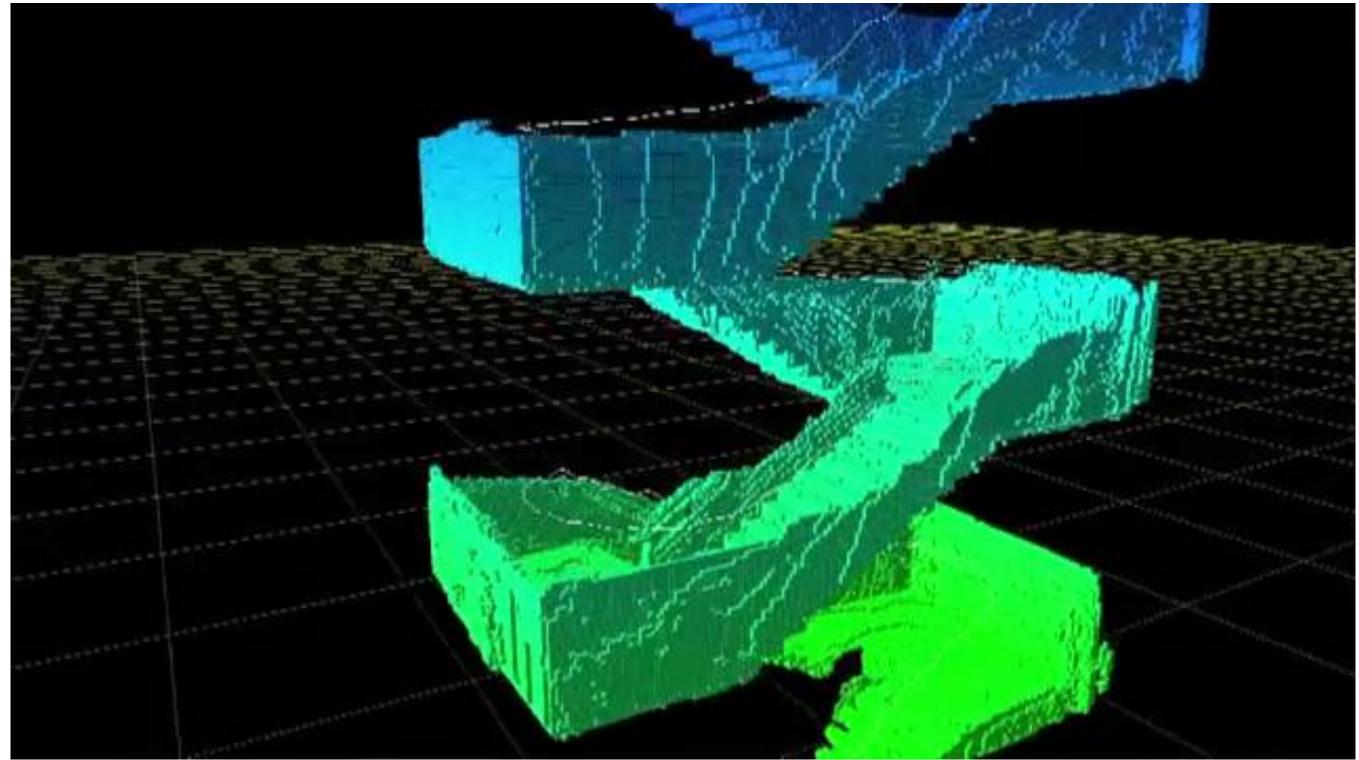
Image stitching



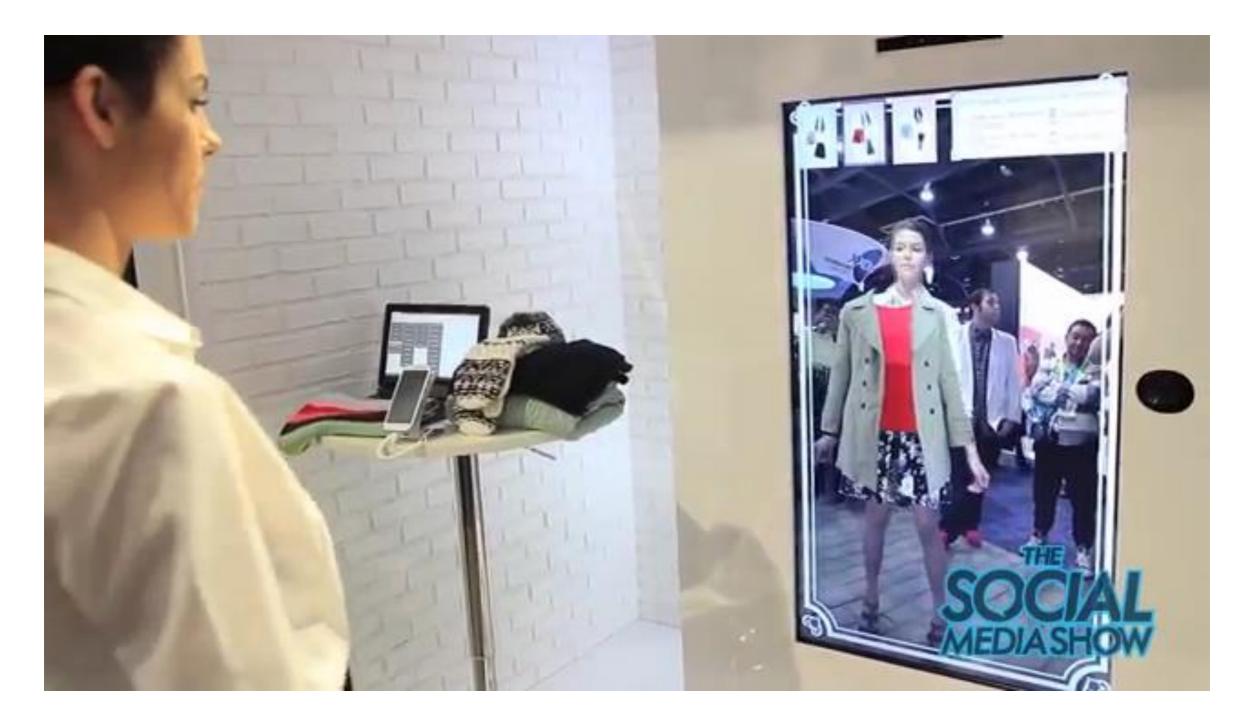
Photosynth



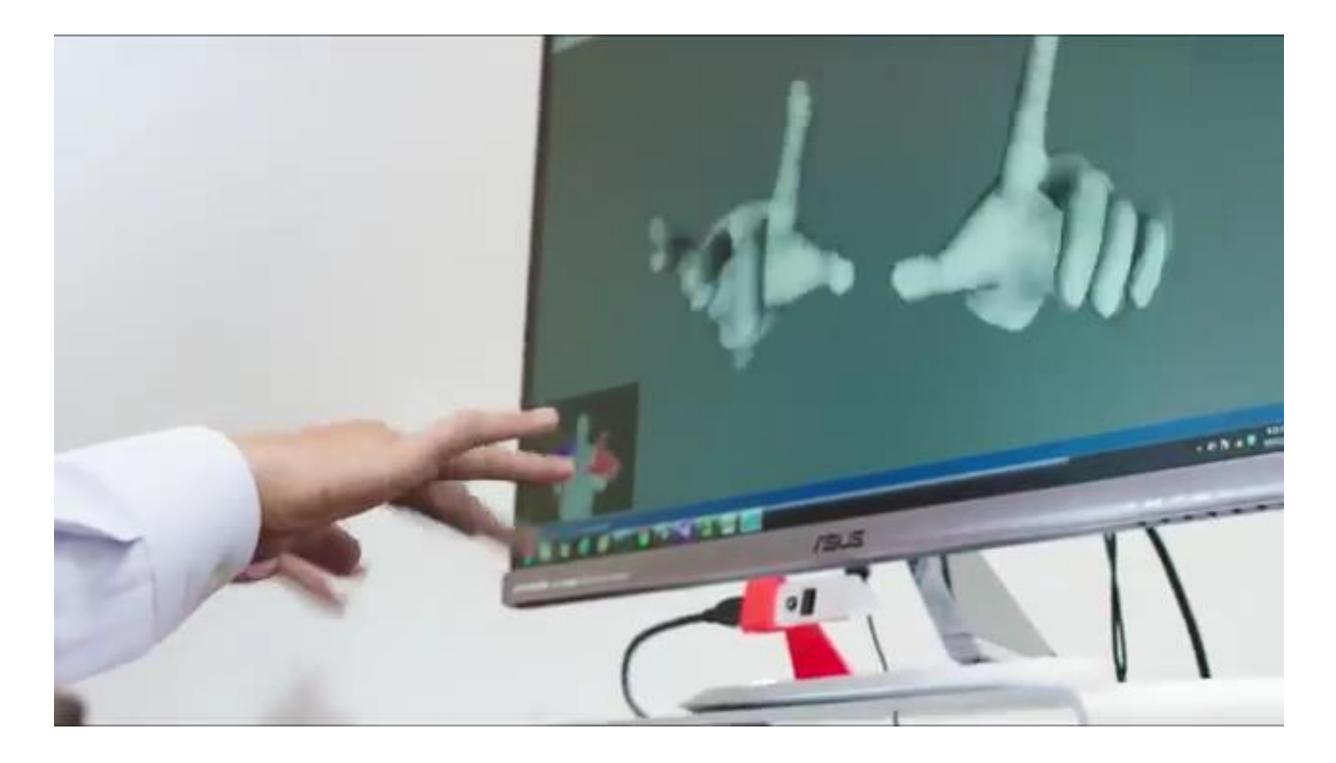
Tango



Virtual Fitting



Computer Vision for VR

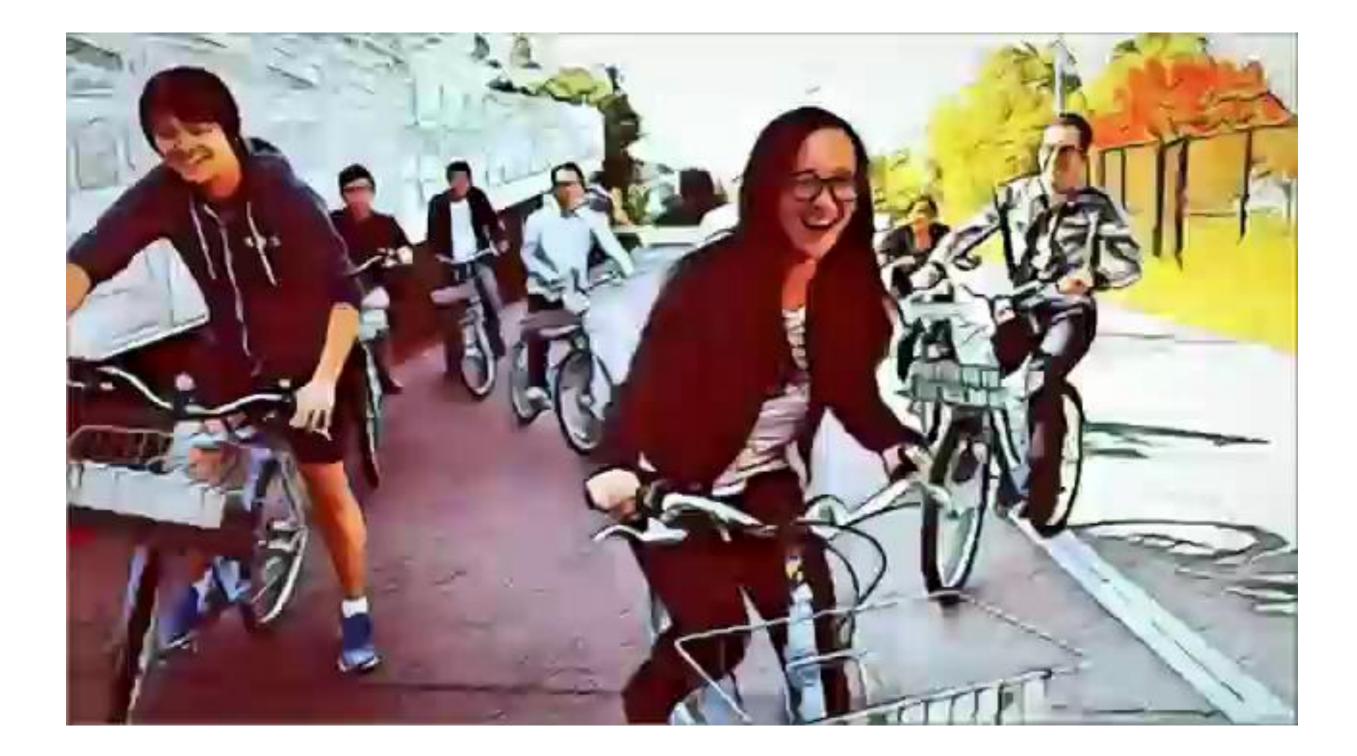


Deep Face



Deep Dream





Facebook video style transfer 2016

Face2Face: Real-time Face Capture and Reenactment of RGB Videos

Justus Thies¹, Michael Zollhöfer², Marc Stamminger¹, Christian Theobalt², Matthias Nießner³

> ¹University of Erlangen-Nuremberg ²Max-Planck-Institute for Informatics ³Stanford University

> > CVPR 2016 (Oral)

It's a good time to do computer vision

Industry aggressively hiring CV faculty from universities (this slide is already out of date by at least 3 CMU faculty)



Platinum Donors facebook amazon Microsoft Google **NVIDIA Tencent** 腾讯 (intel) Nervana DiDi NAVER LINE E2 Alibaba Group
国里巴里第団 **MOMENTA Gold Donors** THISCENE I Mighty Ai Robot CVTE 视源股份 😚 MALONG 码隆 😭 Sighthound SENSETIME SAY BOSCH 图森 tu Simple MonuTonomy A MIRLER METSLENSPE ELECTRIC RESEARCH LABORATORIES, INC meitu MMTLAS COGNEX 350 Snap Inc. Silver Donors Kitware UBER ATG Dissiege Research VionVision TOYOTA AIMATTER & XILINX **Bronze Donors** MathWorks Randterport A Mapillary Spectrum & Lunit omron Spring SPORTLOG VCC A CloudSight Horizon Robotic LINKFACE VIEW Panasonic SEGWAY TOUTIAO 3dMD ROBOTICS Cruise Zillow DAiCure gumgum" [] Synaptics A NIO objectivideo NetP@sa Yandex 👤 playground 😪 Cro Startup Donors MORPX PERCEPTIVE wrnch iniLabs Autox MUMOO CY TURING FEATURE & ANANTAK T Spotscale Muke Shopogon speechacean / 水漏科技 Muke ISEE Non-Profit Donors S PYPIS EYENUK ARKABLE MACH OFFICE

Industry aggressively hiring CV graduates, or even students!

(strong dominant industrial presence at conferences for recruitment)

Advancing computer vision technologies
By: Facebook Research

Google at CVPR 2017 Friday, July 21, 2017



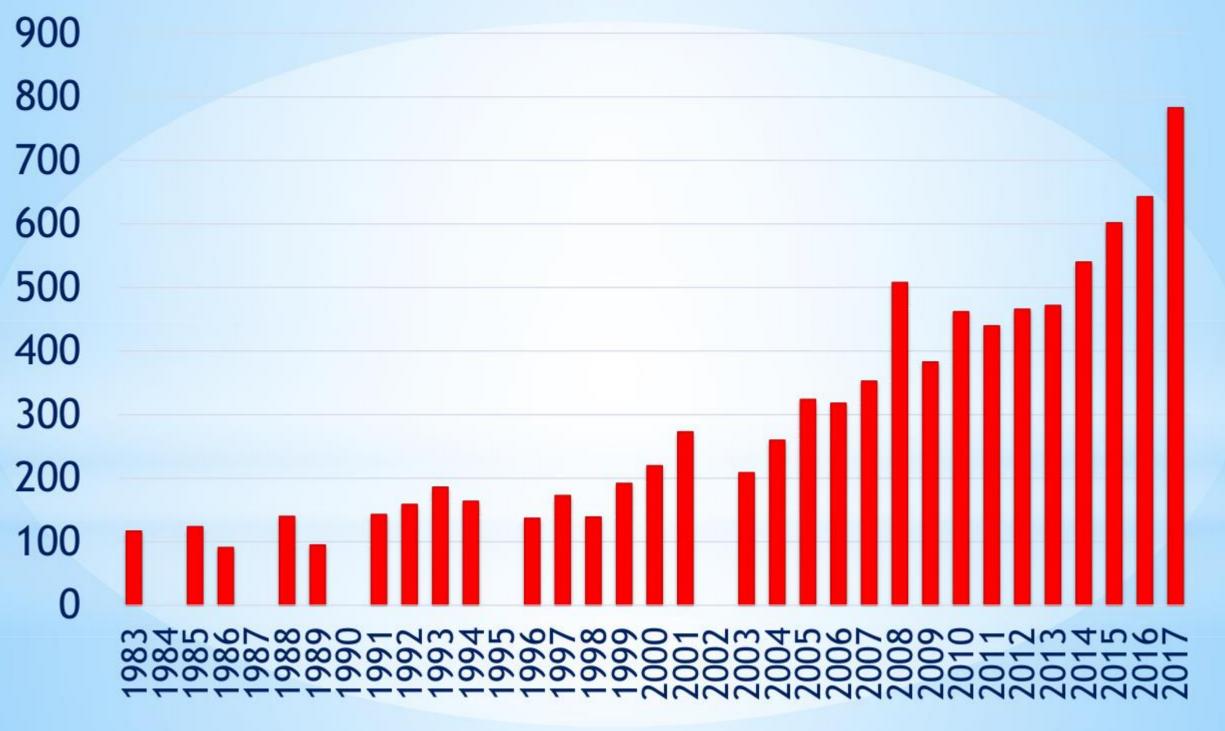
CVPR GROWTH Number of attendees at CVPR

Original slide courtesy of CVPR 2016

6000	
5000	
4000	
3000	
2000	
1000	
0 -	
~98 ³ ,98 ⁶ ,98 ⁹ ,99 ¹ ,99 ⁴ ,99 ¹ ,99 ⁹ ,99 ² ,00 ² ,00 ⁶ ,20 ⁸ ,20 ¹ ,20 ¹ ,20 ¹ ,20 ⁴ ,01 ⁶	

CVPR GROWTH Number of papers at CVPR

Original slide courtesy of CVPR 2016



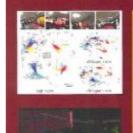
Computer vision at CMU

Dedicated courses for each subject we cover in this class:

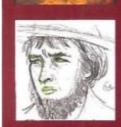
- Physics-based Methods in Vision
- Geometry-based Methods in Computer Vision
- Computational Photography
- Visual Learning and Recognition
- Statistical Techniques in Robotics
- Sensors and sensing
- ... plus an entire department's worth of ML courses.

ICCV 2017: CMU was the second most common <u>academic</u> affiliation among authors (can you guess the first?)

Master in **Computer Vision** at CMU





















Carnegie Mellon

Master of Science - Computer Vision



August 2016 - December 2017 (16-month program)

Computer vision is the study of acquiring and interpreting visual imagery. As computer vision shifts from research to development, there is a critical need for developers with expertise in this field.

GOALS

 Offer a comprehensive set of courses Facilitate hands-on research and development projects Expose students to current and emerging state-of-the-art Computer Vision applications Prepare students for careers in Computer Vision

COURSES

Intoduction to Computer Vision Introduction to Machine Learning Mathematical Fundamentals for Robotics Visual Learning and Recognition Geometry-based Methods in Computer Vision

Electives (choose 2)

Human Communication and Multimodal Machine Learning The Visual World as seen by Neurons and Machines **Comprehensive Sensing and Sparse Optimization** Large Scale Learning using Images and Text **Big Data approaches in Computer Vision** Human Motion Modeling and Analysis Statistical Techniques in Robotics Physics-based Methods in Vision **Probabilistic Graphical Models** Statistical Machine Learning **Convex Optimization** Vision Sensors Project and Seminar Courses

MSCV Seminar MSCV Project I MSCV Project II

ADMISSION AND APPLICATION Requirements: Undergraduate (B.S. or equivalent) in engineering, computer science or applied mathematics

> Application Materials Résumé
> General GRE TOEFL / IELTS (Foreign Students only) Statement of Purpose (1 to 2 pages) Letters of Recommendation (3 Required) Undergraduate/Graduate (as applicable) Transcripts

Only online applications will be accepted. Early application deadline: December 3, 2015 Final application deadline: December 15, 2015

FOR INDUSTRY SPONSORSHIPS PLEASE CONTACT JULIE GOLDSTEIN (JGOLDS@CS.CMU.EDU), 412-268-4017

Carnegie Mellon University 5000 Forbes Avenue, Pittsburgh, PA 15232 ms-cv@ri.cmu.edu www.ri.cmu.edu/MSCV

MSCV Faculty



Srinivasa Narasimhan MSCV Program Director



Martial Hebert **MSCV Spiritual Guru**



J. Andrew (Drew) Bagnell



Fernando De la Torre Frade



Abhinav Gupta



Kris M. Kitani



Simon Lucey



Deva Kannan Ramanan



Yaser Ajmal Sheikh



Course logistics

Website



http://www.cs.cmu.edu/~16385/

Assignments Canvas

https://canvas.cmu.edu/courses/8880

Discussion¬es plazza

https://piazza.com/class/jqmfa1yz38v2oc

(you should sign up here on your own)

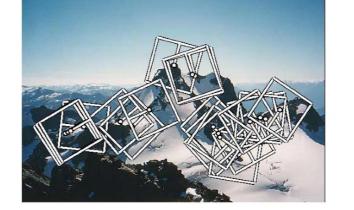
Image processing:

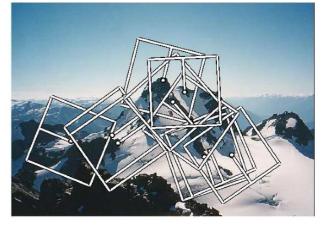
- Basics of filtering.
- Image pyramids.
- Gradients and lines.
- Hough transforms.



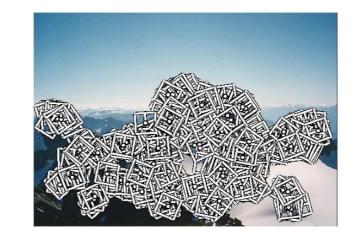
Feature detection and correspondences:

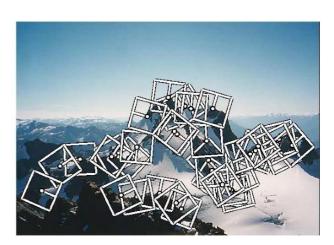
- Corner detection.
- SIFT et al.





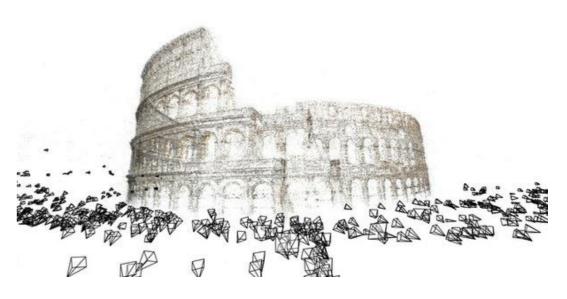
- Feature descriptors.
- RANSAC.





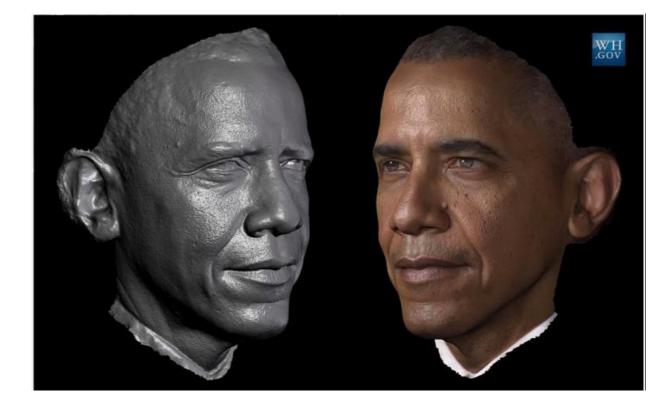
Transformations and geometry:

- Homographies and image alignment.
- Camera models.
- Fundamental matrix.
- Epipolar geometry and stereo.
- Structure from motion.



Physics-based vision:

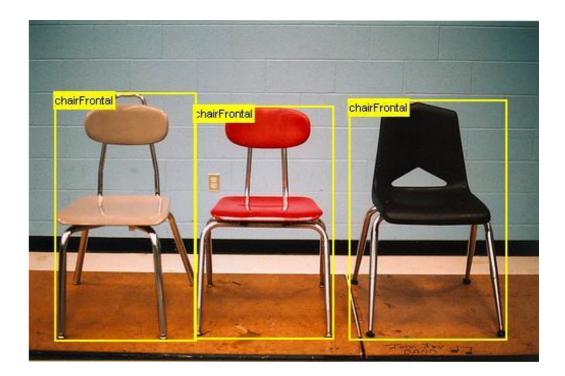
- Reflectance and image formation.
- Radiometry.
- Shape from shading.
- Photometric stereo.



Color.

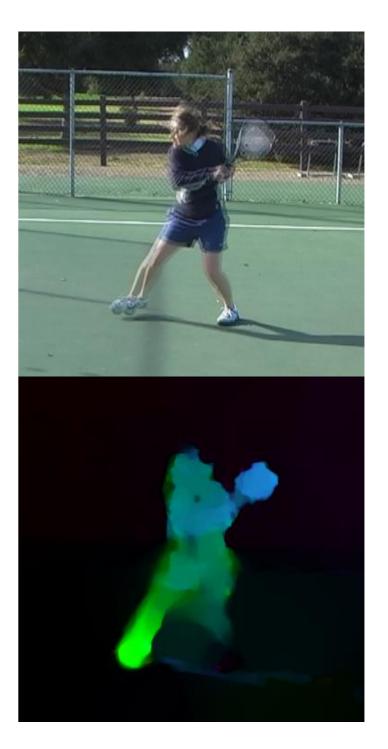
Objects, faces, and learning:

- Basics of probability.
- K-means, KNN, PCA, SVM.
- Bag of words.
- Viola-Jones face detection.
- Perceptron, backpropagation.
- Convolutional neural networks.



Dealing with motion:

- Optical flow (LK, HS).
- Image registration.
- Kalman Filtering.
- Tracking (KLT, Mean-Shift).



Special topics:

- Computational photography.
- ???



Grading: Project-based

- Seven two-week projects: 95%
- Class and Piazza participation: 5%

Projects:

- a lot of programming in Matlab.
- hours and hours of programming.
- days and days of debugging.

Participation:

- Be around for lectures.
- Post on Piazza discussions.
- Ask and answer questions.

Tentative project schedule

Projects

Project 0 Matlab (optional, no credit) Project 1 Hough Transform Project 2 Homography Project 3 Stereo Project 4 Photometric Stereo Project 5 Bag of Words Project 5 Bag of Words Project 6 Convolutional Neural Nets Project 7 Lucas-Kanade Tracking

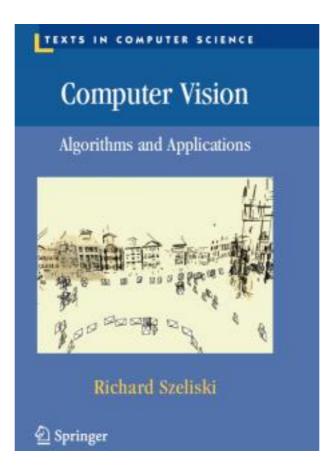
- . Generous grading policy (like grad school)
- . Getting an A vs. mastering the material
- . Build your CV
- . Take advantage of extra credit

Late days

- 10% reduction of points per late day
- 5 free late days total (not per project)
- use them wisely...

Book

We will be posting readings after each lecture



PDF online http://szeliski.org/Book/

Prerequisites

We assume familiarity with calculus, linear algebra, basic probability, and programming.

Formal prerequisites:

 "Mathematical Foundations of Electrical Engineering" (18-202) and "Principles of Imperative Computation" (15-122)

OR

 "Matrix Algebra with Applications" (21-240) and "Matrices and Linear Transformations" (21-241) and "Calculus in Three Dimensions" (21-259) and "Principles of Imperative Computation" (15-122)

If you are missing a prerequisite but still want to enroll, let me know and we'll discuss it.

Contact information and office hours

- Feel free to email us about administrative questions.
 o please use [16385] in email title!
- Technical questions should be asked on Piazza.
 - we won't answer technical questions through email.
 - you can post anonymously if you prefer.
- Office hours will be determined by poll.
 - o feel free to email Yannis about additional office hours.
 - o you can also just drop by Yannis' office (Smith Hall (EDSH) Rm 225).

Yannis will announce office hours for this week.

Please take the course survey before the next lecture!

(posted on Piazza)