Hardware Overview

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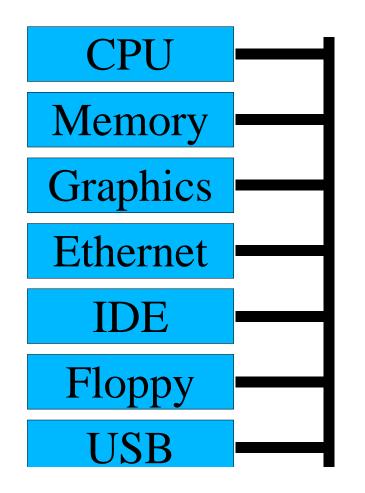
Synchronization

- Today's class
 - Not exactly Chapter 2 or 13
- Friday's class
 - Project 1 talk (probably relevant to you)
- Being registered is good
 - Disk space, access control lists, etc.

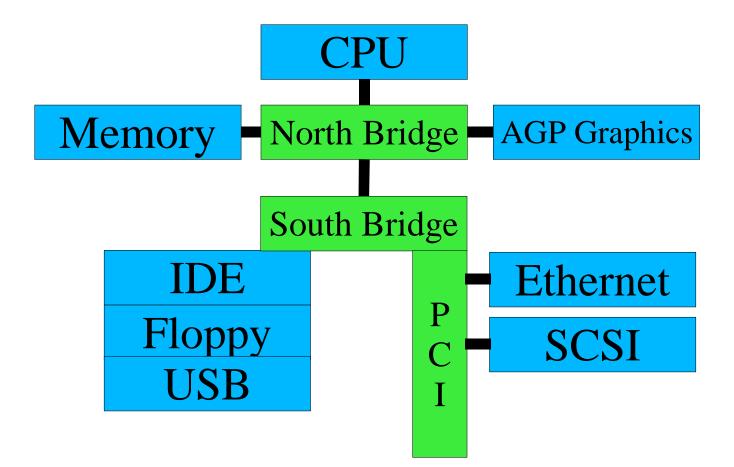
Outline

- Computer parts
- CPU State
- Fairy tales about system calls
- CPU context switch (intro)
- Interrupt handlers
- Interrupt masking

Inside The Box - Historical/Logical







CPU State

- User registers (on Planet Intel)
 - General purpose %eax, %ebx, %ecx, %edx
 - Stack Pointer %esp
 - Frame Pointer %ebp
 - Mysterious String Registers %esi, %edi

CPU State

- *Non-user* registers, aka...
- Processor status register(s)
 - User process / Kernel process
 - Interrupts on / off
 - Virtual memory on / off
 - Memory model
 - small, medium, large, purple, dinosaur

CPU State

- Floating Point Number registers
 - Logically part of "User registers"
 - Sometimes special instead
 - Some machines don't have floating point
 - Some processes don't use floating point

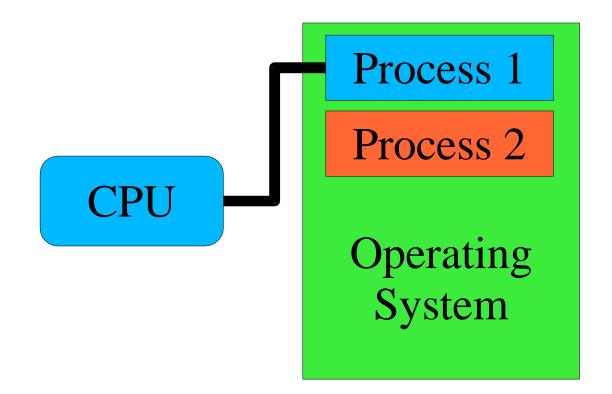
Story time!

- Time for some fairy tales
 - The getpid() story (shortest legal fairy tale)
 - The read() story (toddler version)
 - The read() story (grade-school version)

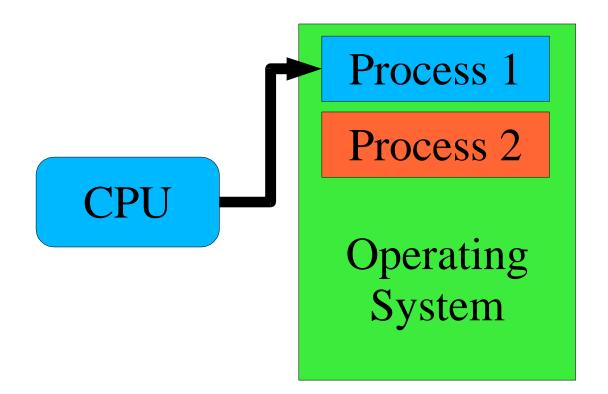
The Story of getpid()

- User process is computing
 - User process calls getpid() library routine
 - Library routine executes TRAP(314159)
- The world changes
 - Some registers dumped into memory somewhere
 - Some registers loaded from memory somewhere
 - (else)
- The processor has *entered kernel mode*

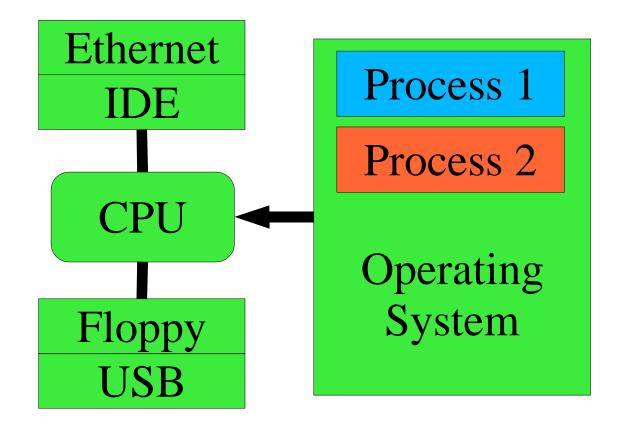
User Mode



Entering Kernel Mode



Entering Kernel Mode



The Kernel Runtime Environment

- Language runtimes differ
 - ML: no stack, "nothing but heap"
 - C: stack-based
- Processor is mostly agnostic
- Trap handler builds kernel runtime environment
 - Switches to correct stack
 - Turns on virtual memory
 - Flushes caches

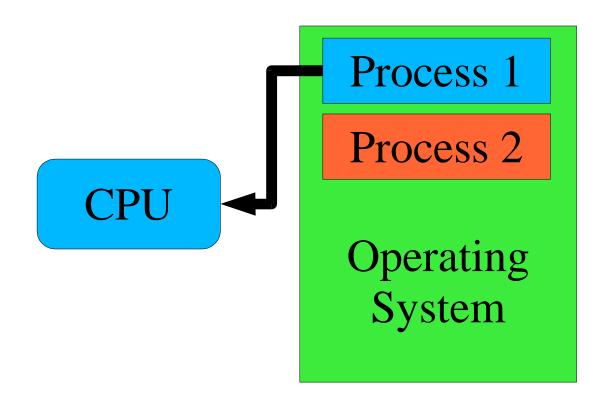
The Story of getpid()

• Process in kernel mode

- u.u_reg[R_EAX] = u.u_pid;

- Return from interrupt
 - Processor state restored to user mode
 - (modulo %eax)
- User process returns to computing
 - Library routine returns %eax as value of getpid()

Returning to User Mode



A Story About read()

- User process is computing
 count = read(0, buf, sizeof (buf));
- User process "goes to sleep"
- Operating system issues disk read
- Time passes
- Operating system copies data
- User process wakes up

Another Story About read()

- P1: read()
 - Trap to kernel mode
- Kernel: issue disk read
- Kernel: switch to P2
 - Return from interrupt but to P2, not P1!
- P2: compute 1/3 of Mandelbrot set

Another Story About read()

- Disk: done!
 - Interrupt to kernel mode
- Kernel: switch to P1
 - Return from interrupt but to P1, not P2!

What do you need for P1?

- Single-process "operating system"
- Only one C runtime environment
 - One memory address space, one stack
- Process based on polling

```
while(1)
  if (time_to_move(paddle))
    move_paddle();
  if ((c = getchar()) != NONE)
    process_char(c);
```

What do you need for P1?

- Keyboard interrupt handler
 - Turns key up/down events into characters
 - Makes characters available to getchar()
 - [not its real name]
- Timer interrupt handler
 - Updates "now" when countdown timer fires
- Console driver
 - Put/scroll characters/strings on screen

Interrupt Vector Table

- How does CPU handle *this* interrupt?
 - Disk interrupt -> disk driver
 - Mouse interrupt -> mouse driver
- Need to know
 - Where to dump registers
 - often: property of current process, not of interrupt
 - New register values to load into CPU
 - key: new program counter, new status register

Interrupt Vector Table

- Table lookup
 - Interrupt controller says: this is interrupt source #3
- CPU knows table base pointer, table entry size
- Spew, slurp, off we go

Race Conditions

if (device_idle)
 start_device(request);
else
 enqueue(request);

Race Conditions

User process	Interrupt handler
if (device_idle)	
	INTERRUPT
	• • •
	<pre>device_idle = 1;</pre>
	RETURN FROM INTERRUPT
enqueue(request)	

Interrupt masking

- Atomic actions
 - Block device interrupt while checking and enqueueing
 - Or use a lock-free data structure
 - [left as an exercise for the reader]
- Avoid blocking *all* interrupts
 - [not a big issue for 15-410]
- Avoid blocking too long
 - Part of Project 3 grading criteria

Timer – Behavior

- Count something
 - CPU cycles, bus cycles, microseconds
- When you hit a limit, generate an interrupt
- Reload counter (don't wait for software to do it)

Timer – Why?

- Why interrupt a perfectly good execution?
- Avoid CPU hogs

for (;;) ;

- Maintain accurate time of day
 - Battery-backed calendar counts only seconds (poorly)
- Dual-purpose interrupt
 - ++ticks_since_boot;
 - force process switch (probably)

Closing

- Welcome to the machine
 - For P1
 - Keyboard
 - Clock
 - Screen
 - Memory (a little)
- Browse Intel document introductions?
- Start choosing a partner for P2