

Advanced Component Analysis Methods for Signal Processing

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Outline

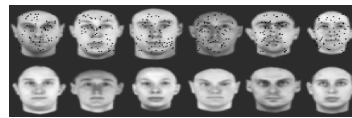
- Introduction
- Principal Component Analysis (PCA)
 - Robust Principal CA
 - PCA missing data
 - Parameterized Principal CA
- Linear Discriminant Analysis
 - Multimodal Oriented Discriminant Analysis
- Canonical Correlation Analysis
 - Canonical Time Warping
- K-means
 - Aligned Cluster Analysis (ACA)
 - Discriminative Cluster Analysis (DCA)

Robust PCA

•Two types of outliers:

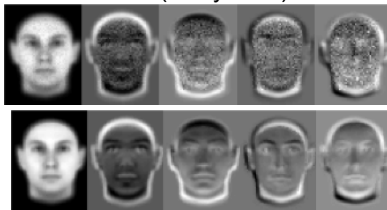


Sample outliers
(Xu & Yuille., 1995)



Intra-sample outliers
(de la Torre & Black, 2001b; Skočaj & Leonardis, 2003)

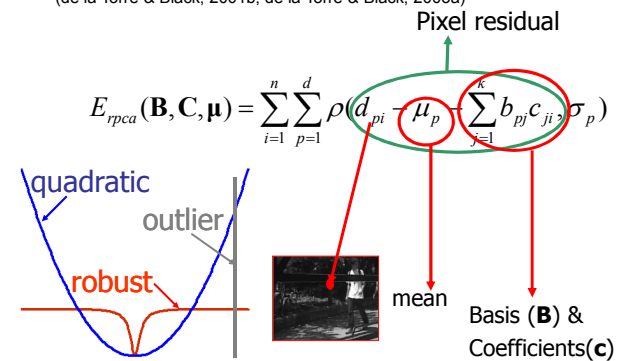
•Standard PCA solution (noisy data):



Robust PCA

• Using robust statistics:

(de la Torre & Black, 2001b; de la Torre & Black, 2003a)



Numerical Problems

- No closed form solution in terms of an eigen-equation.
- Deflation approaches do not hold.

$$\mathbf{A}' = \mathbf{A} - \lambda_1 \mathbf{u}_1 \mathbf{u}_1^T \rightarrow \text{First eigenvector with highest eigenvalue.}$$

$$\mathbf{A}'' = \mathbf{A}' - \lambda_2 \mathbf{u}_2 \mathbf{u}_2^T \rightarrow \text{Second eigenvector with highest eigenvalue.}$$

...

- In the robust case all the basis have to be computed simultaneously (including the mean).

How to Optimize it?

$$E_{rpca}(\mathbf{B}, \mathbf{C}, \boldsymbol{\mu}) = \sum_{i=1}^n \sum_{p=1}^d \rho(d_{pi} - \mu_p - \sum_{j=1}^k b_{pj} c_{ji}, \sigma_p)$$

- Normalized Gradient descent

$$\mathbf{B}^{n+1} = \mathbf{B}^n - [\mathbf{H}_b]^{-1} \circ \frac{\partial E_{rpca}}{\partial \mathbf{B}} \quad \mathbf{H}_b = \max \text{diag} \left(\frac{\partial^2 E_{rpca}}{\partial \mathbf{b}_i \partial \mathbf{b}_i^T} \right)$$

$$\mathbf{C}^{n+1} = \mathbf{C}^n - [\mathbf{H}_c]^{-1} \circ \frac{\partial E_{rpca}}{\partial \mathbf{C}} \quad \mathbf{H}_c = \max \text{diag} \left(\frac{\partial^2 E_{rpca}}{\partial \mathbf{c}_i \partial \mathbf{c}_i^T} \right)$$

- Deterministic annealing methods to avoid local minima. (Blake & Zisserman, 1987)

Example



Statistical outlier

- Small region
- Short amount of time

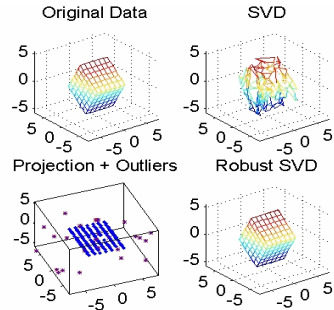


Robust PCA

Original PCA RPCA Outliers



Structure from Motion



More work on Robust PCA

- Robust estimation of coefficients (Black & Jepson, 1998; Leonardis & Bischof, 2000; Ke & Kanade, 2004)
- Robust estimation of basis and coefficients (Gabriel & Odoro, 1984; Croux & Filzmoser, 1981; Skocaj et al., 2002; Skocaj & Leonardis, 2003; de la Torre & Black, 2001b; de la Torre & Black, 2003a)
- Other Robust PCA techniques (sample outliers) (Campbell, 1980; Ruymagaart, 1981; Xu & Yuille, 1995)

PCA with Uncertainty and Missing Data

- Adding uncertainty $E_2(\mathbf{B}, \mathbf{C}) = \|\mathbf{W} \circ (\mathbf{D} - \mathbf{BC})\|_F = \sum_{i=1}^d \sum_{j=1}^n w_{ij} (d_{ij} - \sum_{s=1}^k b_{is} c_{sj})^2$



- If weights are separable $\mathbf{W} = \mathbf{w}_r \mathbf{w}_c^T$ closed-form solution.

$$\mathbf{w}^c = \begin{pmatrix} w_1^c & w_2^c & \dots & w_n^c \end{pmatrix}$$

$$\mathbf{w}^r = \begin{pmatrix} w_1^r \\ w_2^r \\ \dots \\ w_d^r \end{pmatrix}$$

$$\mathbf{D} = \begin{pmatrix} d_{11} & \dots & d_{1n} \\ \vdots & \ddots & \vdots \\ d_{d1} & \dots & d_{dn} \end{pmatrix} = \mathbf{D}$$

$$\mathbf{W} \in \mathfrak{R}^{d \times n}$$

$$w_{ij} \geq 0$$

◦ Hadamard product



- Generalized SVD (Greenacre, 1984; Irani & Anandan, 2000;)

General Case

- For arbitrary weights no closed-form solution.

$$E_2(\mathbf{B}, \mathbf{C}) = \|\mathbf{W} \circ (\mathbf{D} - \mathbf{BC})\|_F = \sum_{i=1}^d (\mathbf{d}_i - \mathbf{Bc}_i)^T \text{diag}(\mathbf{w}_i) (\mathbf{d}_i - \mathbf{Bc}_i) =$$

$$\sum_{p=1}^d (\mathbf{d}^p - \mathbf{C}^T \mathbf{b}^p)^T \text{diag}(\mathbf{w}^p) (\mathbf{d}^p - \mathbf{C}^T \mathbf{b}^p) \quad (\text{Torre \& Black, 2003a})$$

- Alternated least squares algorithms
 - Slow convergence, easy implementation.

- Damped Newton Algorithm
 - Fast convergence. (Buchanan & Fitzgibbon, 2005)

$$E_2(\mathbf{B}, \mathbf{C}) = \|\mathbf{W} \circ (\mathbf{D} - \mathbf{BC})\|_F + \lambda_1 \|\mathbf{B}\|_F + \lambda_2 \|\mathbf{C}\|_F$$

$$\mathbf{v} = \begin{bmatrix} \text{vec}(\mathbf{B}) \\ \text{vec}(\mathbf{C}) \end{bmatrix} \quad \mathbf{v}^{(n+1)} = \mathbf{v}^n - \left[\frac{\partial^2 E_2}{\partial^2 \mathbf{v}} \right]^{-1} \frac{\partial E_2}{\partial \mathbf{v}}$$

$$\text{– H definite positive: } \mathbf{H} = \frac{\partial^2 E_2}{\partial^2 \mathbf{v}} + \lambda \mathbf{I}$$

repeat

$$\mathbf{H} = \frac{\partial^2 E_2}{\partial^2 \mathbf{v}} \quad \mathbf{g} = \frac{\partial E_2}{\partial \mathbf{v}}$$

repeat

$$\lambda = 10\lambda$$

$$\mathbf{y} = \mathbf{x} - (\mathbf{H} + \lambda \mathbf{I})^{-1} \mathbf{g}$$

$$\text{until } F(\mathbf{y}) < F(\mathbf{x})$$

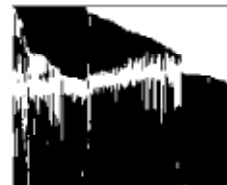
$$\mathbf{x} = \mathbf{y}; \lambda = \frac{\lambda}{10}$$

until convergence

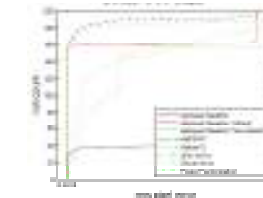
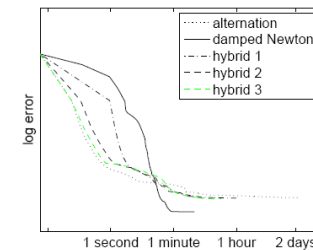
Experiments



240 x 167; 70% known



Total: 500 runs



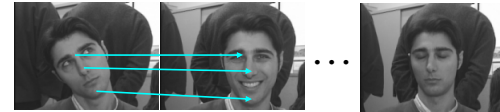
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Parameterized Component Analysis (PaCA)

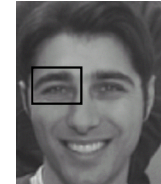
(de la Torre & Black, 2003b)

- Learn a subspace invariant to geometric transformations?



- Data has to be **geometrically** normalized

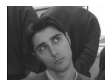
- Tedious manual cropping.
- Inaccuracies due to matching ambiguities.
- Hard to achieve sub-pixel accuracy.



Error function for PaCA



$$E(\mathbf{B}, \mathbf{C}, \mathbf{a}) = \sum_{t=1}^T \left\| \mathbf{d}(\mathbf{f}(\mathbf{x}, \mathbf{a}_t)) - \mathbf{B}\mathbf{c}_t \right\|_{\mathbf{W}_1}^2 + p_1(\mathbf{a}) + p_2(\mathbf{c})$$



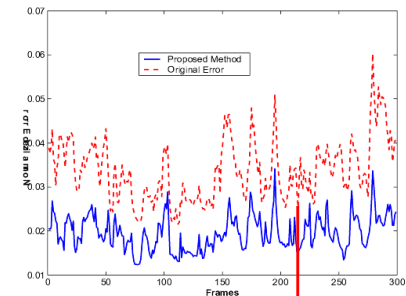
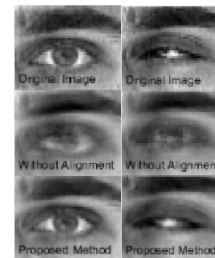
Motion
(warping)

Basis (\mathbf{B}) &
coefficients (\mathbf{c})

Regularization

$$\sum_{t=1}^T \sum_{l=1}^L \lambda_1 \left\| \mathbf{c}_t - \Gamma_c \mathbf{c}_{t-1} \right\|_{\mathbf{W}_2}^2 + \lambda_2 \left\| \mathbf{a}_t - \Gamma_a \mathbf{a}_{t-1} \right\|_{\mathbf{W}_3}^2$$

EigenEye Learning



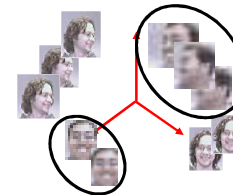
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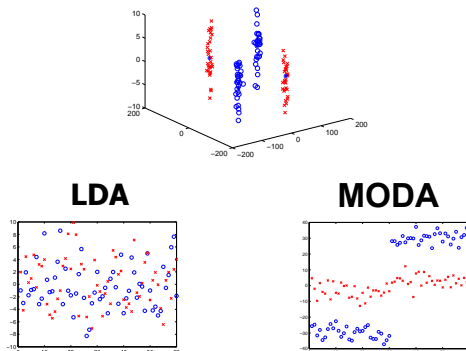
Multimodal Oriented Component Analysis (MODA)

(de la Torre & Kanade, 2005a)

- How to extend LDA to deal with:
 - Model class covariances.
 - Multimodal classes.
 - Deal efficiently with huge covariance matrices (e.g. 100*100).

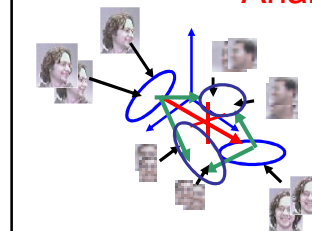


Multimodality



Multimodal Oriented Discriminant Analysis (MODA)

▪ **B** that MAXIMIZES the Kullback-Leibler divergence between clusters among classes.



$$\sum_{i=1}^{\text{classes}} \sum_{j \neq i} \sum_{r_1 \in C_i} \sum_{r_2 \in C_j} t \left(\mathbf{B}^T \left(\Sigma_j^{r_2} \Sigma_i^{r_1^{-1}} + \Sigma_j^{r_2^{-1}} \Sigma_i^{r_1} + (\boldsymbol{\mu}_i^{r_1} - \boldsymbol{\mu}_j^{r_2})(\Sigma_j^{r_1^{-1}} + \Sigma_i^{r_2^{-1}})(\boldsymbol{\mu}_i^{r_1} - \boldsymbol{\mu}_j^{r_2})^T \right) \mathbf{B} \right)$$

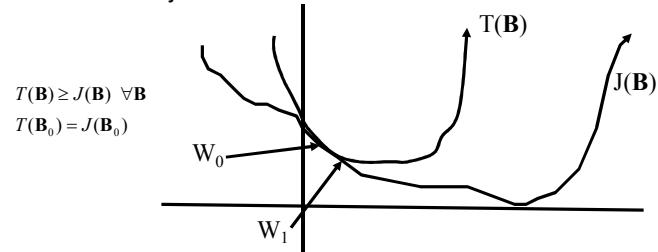
- 1 mode per class and equal covariances equivalent to LDA.

Optimization

- Hard optimization problem

$$J(\mathbf{B}) = -\sum_{i=1} \text{tr}((\mathbf{B}^T \Sigma_i \mathbf{B})^{-1} (\mathbf{B}^T \mathbf{A}_i \mathbf{B}))$$

- Iterative Majorization (Kiers, 1995; Leeuw, 1994)



Majorization

$$T(\mathbf{B}) = \sum_{i=1}^{\text{classes}} \left\| (\mathbf{B}^T \Sigma_i \mathbf{B})^{-\frac{1}{2}} \mathbf{B}^T \mathbf{A}_i^{-\frac{1}{2}} - (\mathbf{B}^T \Sigma_i \mathbf{B})^{-\frac{1}{2}} (\mathbf{B}_0^T \Sigma_i \mathbf{B}_0)^{-\frac{1}{2}} \mathbf{B}_0^T \mathbf{A}_i^{-\frac{1}{2}} \right\|^2$$

$$\geq -\sum_{i=1}^{\text{classes}} \text{tr}((\mathbf{B}^T \Sigma_i \mathbf{B})^{-1} (\mathbf{B}^T \mathbf{A}_i \mathbf{B}))$$

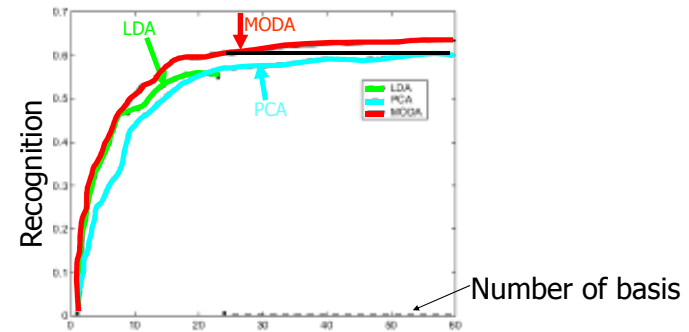
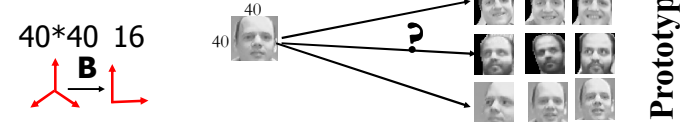
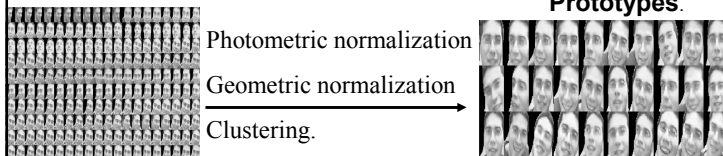
- Slow convergence...

Face recognition from video



- Challenges

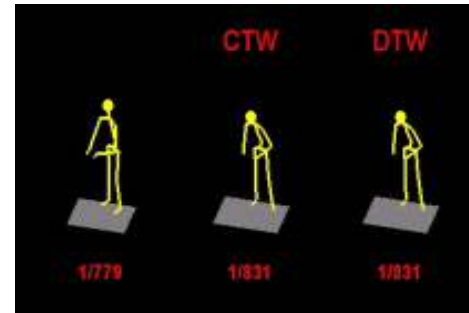
- Low quality small images (40-50 pixels).
- Changes in expression/pose/occlusion/illumination.
- Real time and scalable to several users.



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Problem



Canonical Correlation Analysis (CCA)

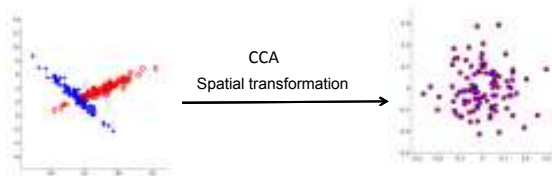
(Hotelling 1936)

- CCA minimizes:

different #rows, same #columns

$$X \in \mathbb{R}^{d_x \times n}, Y \in \mathbb{R}^{d_y \times n}$$

$$J_{cca}(V_x, V_y) = \|V_x^T X - V_y^T Y\|_F^2 \quad s.t. \begin{cases} V_x^T X X^T V_x \\ V_y^T Y Y^T V_y \end{cases} = I_b$$

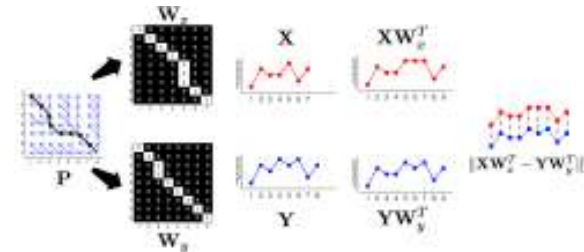


A least-square formulation for DTW

same #rows, different #columns

$$X \in \mathbb{R}^{d \times n_x}, Y \in \mathbb{R}^{d \times n_y}$$

$$J_{dtw}(W_x, W_y) = \|XW_x^T - YW_y^T\|_F^2$$



Canonical Time Warping (CTW)

Reminder

$$J_{cca}(\mathbf{V}_x, \mathbf{V}_y) = \|\mathbf{V}_x^T \mathbf{X} - \mathbf{V}_y^T \mathbf{Y}\|_F^2$$

$$J_{dnc}(\mathbf{W}_x, \mathbf{W}_y) = \|\mathbf{X}\mathbf{W}_x^T - \mathbf{Y}\mathbf{W}_y^T\|_F^2$$

different #rows, different #columns
 $\mathbf{X} \in \mathbb{R}^{d_x \times n_x}, \mathbf{Y} \in \mathbb{R}^{d_y \times n_y}$

spatial transformation

$$J_{ctw}(\mathbf{W}_x, \mathbf{W}_y, \mathbf{V}_x, \mathbf{V}_y) = \|\mathbf{V}_x^T \mathbf{X} \mathbf{W}_x^T - \mathbf{V}_y^T \mathbf{Y} \mathbf{W}_y^T\|_F^2$$

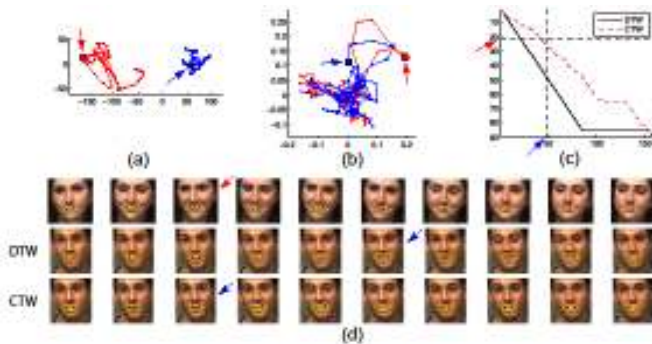
temporal alignment

$$s.t. \left. \begin{array}{l} \mathbf{V}_x^T \mathbf{X} \mathbf{W}_x^T \mathbf{W}_x \mathbf{X}^T \mathbf{V}_x \\ \mathbf{V}_y^T \mathbf{Y} \mathbf{W}_y^T \mathbf{W}_y \mathbf{Y}^T \mathbf{V}_y \end{array} \right\} = \mathbf{I}_b$$

Facial expression alignment



Facial expression alignment



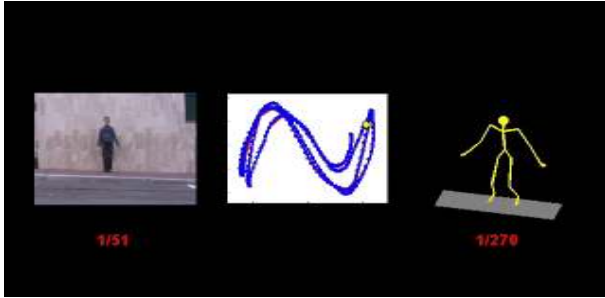
Aligning human motion



Boxing

Opening a cabinet

Aligning motion capture and video



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Problem

- Mining facial expression



Problem

- Mining facial expression for one subject



- Summarization

Problem

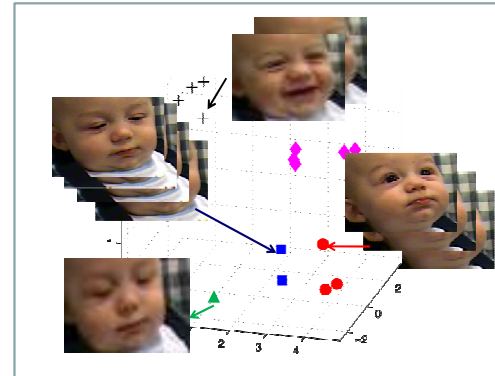
- Mining facial expression for one subject



- Summarization

Problem

- Mining facial expression of one subject

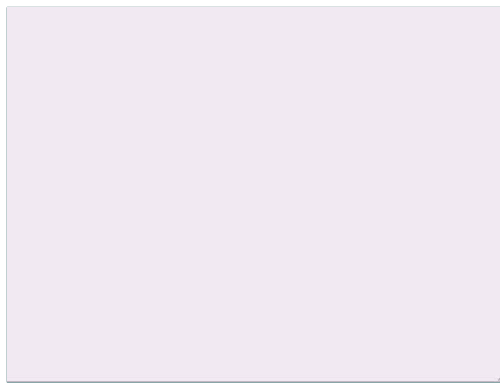


- Summarization

- Embedding

Problem

- Mining facial expression for one subject



- Summarization

- Embedding

- Indexing

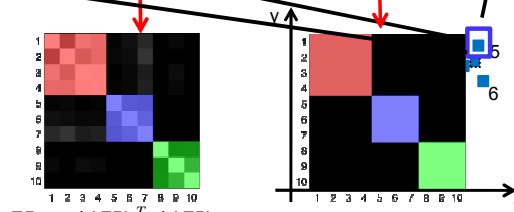
k-means and kernel k-means

(MacQueen 67, Ding et al. 02, Dhillon et al. 04, Zass and Shashua 05, De la Torre 06)

$$J(\mathbf{M}, \mathbf{G}) = \|\phi(\mathbf{X}) - \mathbf{MG}\|_F^2$$

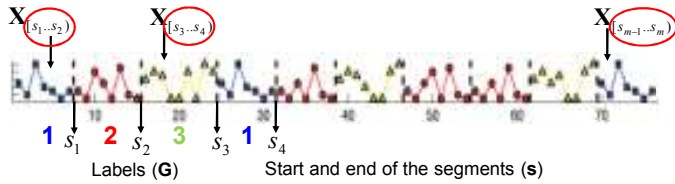
$$\mathbf{G} = \begin{bmatrix} 1 & 1 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 \end{bmatrix}$$

$$\mathbf{M} \mathcal{F}(\mathbf{X}) \in \mathcal{H} \quad \mathbf{G} \# \begin{bmatrix} 1 & 1 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 \end{bmatrix} \quad \left(\mathbf{MG}^T \mathbf{X} - \mathbf{1} \right) \mathbf{G}$$



$$\mathbf{K} = \phi(\mathbf{X})^T \phi(\mathbf{X})$$

Problem formulation for ACA (I)



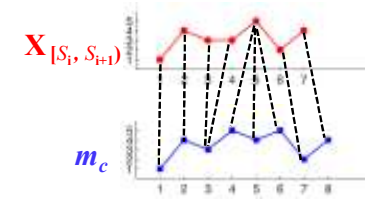
$$J_{aca}(\mathbf{M}, \mathbf{G}, \mathbf{S}) = \left\| \varphi(\mathbf{X}_{[s_1..s_2]}, \mathbf{X}_{[s_2..s_3]}, \dots, \mathbf{X}_{[s_{m-1}..s_m]}) - \mathbf{M}\mathbf{G} \right\|_F^2$$

Problem formulation for ACA (II)

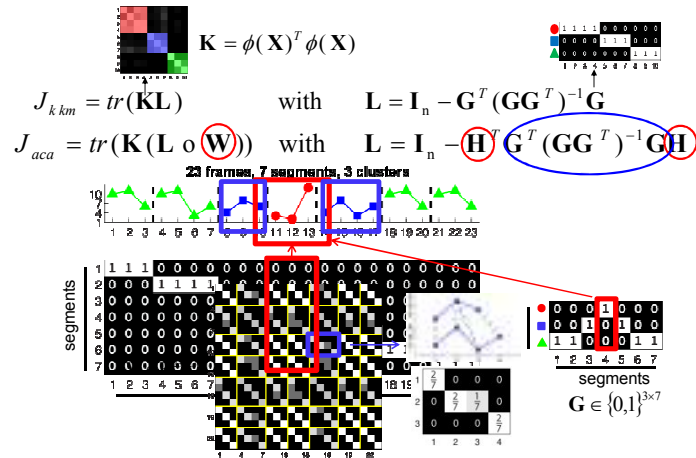
$$J_{aca}(\mathbf{M}, \mathbf{G}, \mathbf{S}) = \left\| \varphi(\mathbf{X}_{[s_1..s_2]}, \mathbf{X}_{[s_2..s_3]}, \dots, \mathbf{X}_{[s_{m-1}..s_m]}) - \mathbf{M}\mathbf{G} \right\|_F^2$$

$$= \sum_{c=1}^k \sum_{i=1}^m g_{ci} \left\| \varphi(\mathbf{X}_{[s_i, s_{i+1})}) - m_c \right\|_2^2$$

Dynamic Time Alignment Kernel (Shimodaira et al. 01)

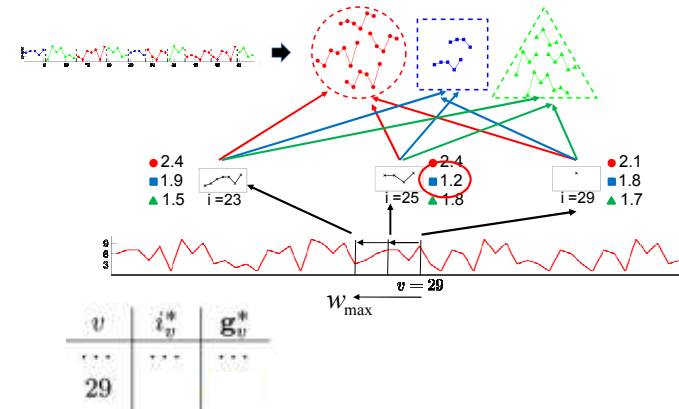


Matrix formulation for ACA

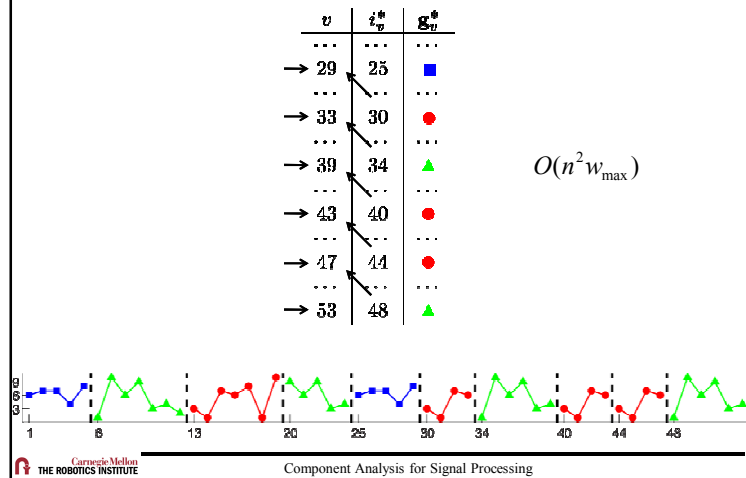


Optimizing ACA (forward step)

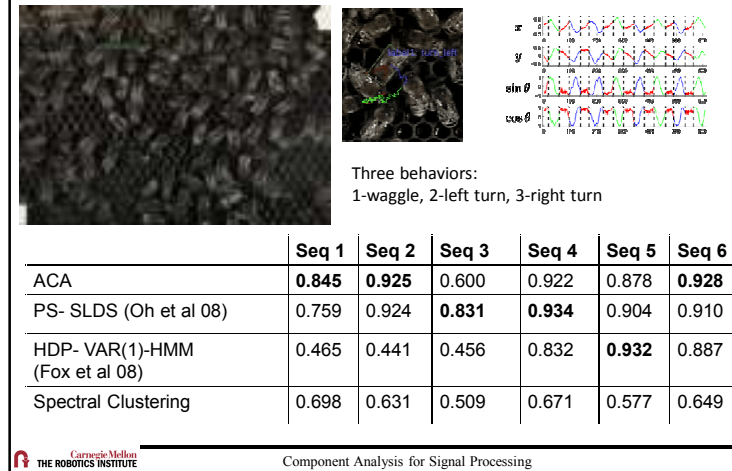
- Efficient Dynamic Programming



Optimizing ACA (backward step)



Honey bee dance data (Oh et al. 08)

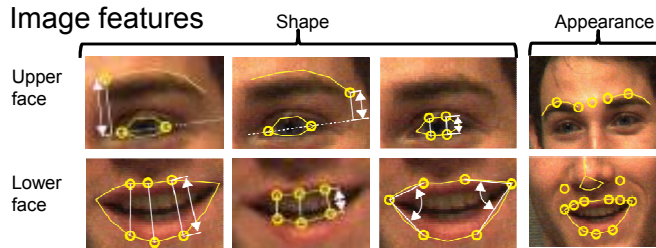


Facial image features

- Active Appearance Models (Baker and Matthews '04)

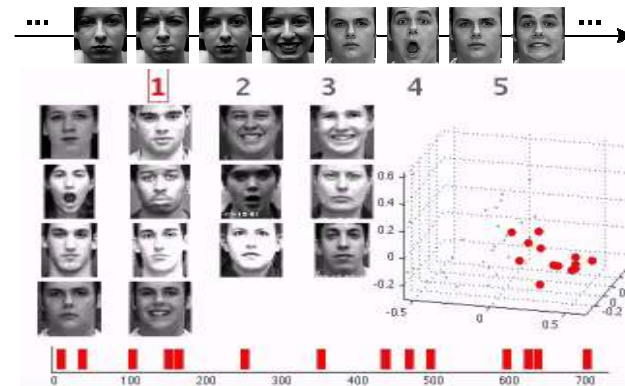


- Image features



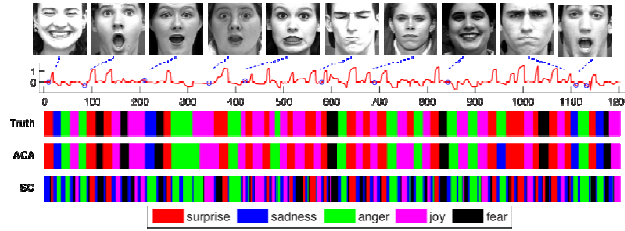
Facial event discovery across subjects

- Cohn-Kanade: 30 people and five different expressions (surprise, joy, sadness, fear, anger)



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- Cohn-Kanade: 30 people and five different expressions (surprise, joy, sadness, fear, anger)



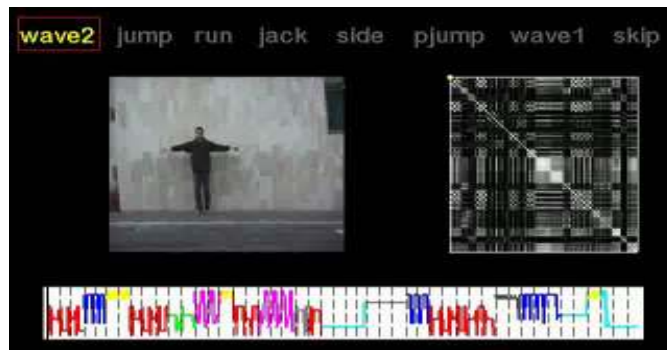
- 10 sets of 30 people

	ACA	Spectral Clustering (SC)
	0.87(.05)	0.56(.04)

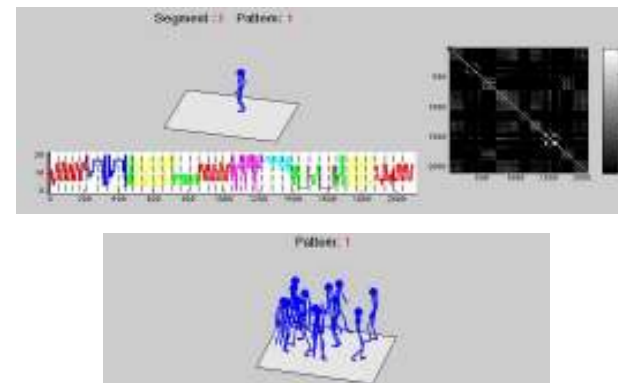
Unsupervised facial event discovery



Clustering human motion



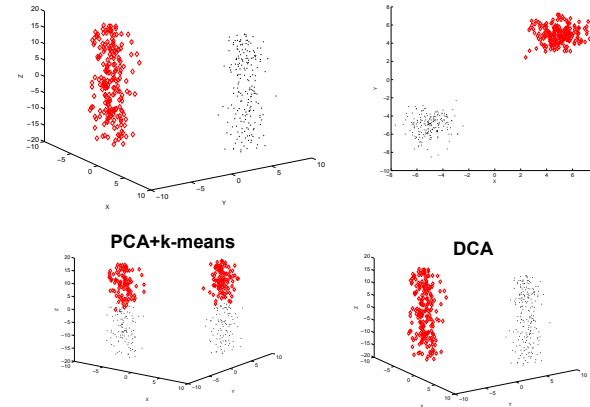
clustering of human motion II



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Problem



Discriminative Cluster Analysis (DCA)

(de la Torre & Kanade, 2006)

- Generative clustering (e.g. k-means):

$$E(\mathbf{G}, \mathbf{B}) = \|\mathbf{D} - \mathbf{B}\mathbf{G}^T\|_F = \sum_{i=1}^c \sum_{j \in C_i} \|\mathbf{d}_j - \mathbf{b}_i\|$$

$$g_{ij} \in \{0,1\} \quad \mathbf{G}\mathbf{1}_k = \mathbf{1}_n$$

- Not efficient for high dimensional data.
- Multiple local minima.

- Discriminative clustering (de la Torre & Kanade, 2006):

$$E(\mathbf{V}, \mathbf{B}, \mathbf{G}) = \|\mathbf{G}^T \mathbf{G}\|^{-\frac{1}{2}} \|\mathbf{G}^T - \mathbf{V}\mathbf{B}^T \mathbf{D}\|_F$$

- Simultaneous dimensionality reduction and clustering.

Optimization

- Eliminate \mathbf{V}

$$E(\mathbf{B}, \mathbf{G}) \propto \text{tr}((\mathbf{B}^T \mathbf{D} \mathbf{D}^T \mathbf{B})^{-1} (\mathbf{B}^T \mathbf{D} \mathbf{G} (\mathbf{G}^T \mathbf{G})^{-1} \mathbf{G}^T \mathbf{D}^T \mathbf{B}))$$

- Optimize for \mathbf{B}

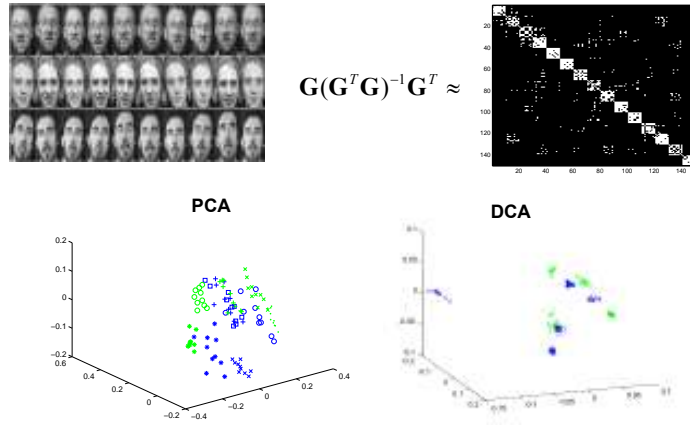
$$\mathbf{D}\mathbf{G}(\mathbf{G}^T \mathbf{G})^{-1} \mathbf{G}^T \mathbf{D}^T \mathbf{B} = \mathbf{D}\mathbf{D}^T \mathbf{B}\mathbf{A}$$

- Optimize for \mathbf{G} $\mathbf{A} = \mathbf{C}^T (\mathbf{C}^T \mathbf{C})^{-1} \mathbf{C}$ $\mathbf{C} = \mathbf{B}^T \mathbf{D}$

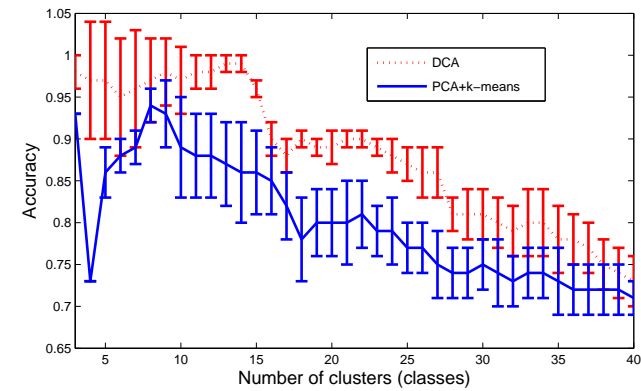
$$\mathbf{G} = \mathbf{V} \circ \mathbf{V} \quad \mathbf{V}^{(n+1)} = \mathbf{V}^{(n)} - \eta \frac{\partial E}{\partial \mathbf{V}}$$

$$\frac{\partial E}{\partial \mathbf{V}} = (\mathbf{I}_c - \mathbf{G}(\mathbf{G}^T \mathbf{G})^{-1} \mathbf{G}^T) \mathbf{A} \mathbf{G} (\mathbf{G}^T \mathbf{G})^{-1}$$

Experiments



DCA vs. PCA+k-means



What's next?



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