Representing Images and Sounds

Class 4. 2 Sep 2010

Instructor: Bhiksha Raj

Administrivia

- Homework up

- Basics of probability: Will not be covered
- Very nice lecture by Aarthi Singh
  - http://www.cs.cmu.edu/~epxing/Class/10701/Lecture/lecture2.pdf
- Another nice lecture by Paris Smaragdis
  - http://www.cs.illinois.edu/~paris/cs598-f10/cs598-f10/Lectures.html
    - Look for Lecture 2
- Amazing number of resources on the web
- Things to know:
  - Basic probability, Bayes rule
  - Probability distributions over discrete variables
  - Probability density and Cumulative density over continuous variables
    - Particularly Gaussian densities
  - Moments of a distribution
  - What is independence
  - Nice to know
    - What is maximum likelihood estimation
    - MAP estimation

Representing an Elephant

- It was six men of Indostan,
  To learning much inclined,
  Who went to see the elephant,
  (Though all of them were blind),
  That each by observation
  Might satisfy his mind.

- The first approached the elephant,
  And happening to fall
  Against his broad and sturdy side,
  At once began to bawl:
  "God bless me! But the elephant
  Is very like a wall!“

- The second, feeling of the tusk,
  Cried: "Ho! What have we here,
  So very round and smooth and sharp?
  To me 'tis very clear,
  This wonder of an elephant
  Is very like a spear!“

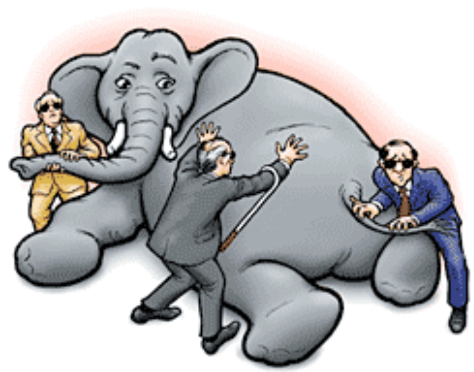
- The third approached the animal,
  And happening to take
  The squirming trunk within his hands,
  Thus boldly up and spake:
  "I see," quoth he, "the elephant
  Is very like a snake!“

- The fourth reached out an eager hand,
  And felt about the knee.
  "What most this wondrous beast is like
  Is might plain," quoth he;
  "Tis clear enough the elephant
  Is very like a tree."

- The fifth, who chanced to touch the ear,
  Said: "E'en the blindest man
  Can tell what this resembles most:
  Deny the fact who can,
  This marvel of an elephant
  Is very like a fan.“

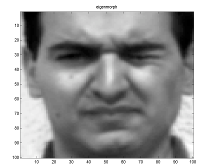
- The sixth no sooner had begun
  About the beast to grope,
  Than seizing on the swinging tail
  That fell within his scope,
  "I see," quoth he, "the elephant
  Is very like a rope.“

- And so these men of Indostan
  Disputed loud and long,
  Each in his own opinion
  Exceeding stiff and strong.
  Though each was partly right,
  All were in the wrong.



Representation

- Describe these images
  - Such that a listener can visualize what you are describing




- More images



Still more images


aboard Apollo space capsule.
1038 x 1280 - 142k
LIFE


Apollo Xi
1280 x 1255 - 226k
LIFE


aboard **Apollo space** capsule.
1029 x 1280 - 128k
LIFE


Building **Apollo space** ship.
1280 x 1257 - 114k
LIFE


aboard **Apollo space** capsule.
1017 x 1280 - 130k
LIFE


Apollo Xi
1228 x 1280 - 181k
LIFE


Apollo 10 **space** ship, w.
1280 x 853 - 72k
LIFE


Splashdown of **Apollo** XI mission.
1280 x 866 - 184k
LIFE


Earth seen from **space** during the
1280 x 839 - 60k
LIFE


Apollo Xi
844 x 1280 - 123k
LIFE


Apollo 8
1278 x 1280 - 74k
LIFE


working on **Apollo space** project.
1280 x 956 - 117k
LIFE

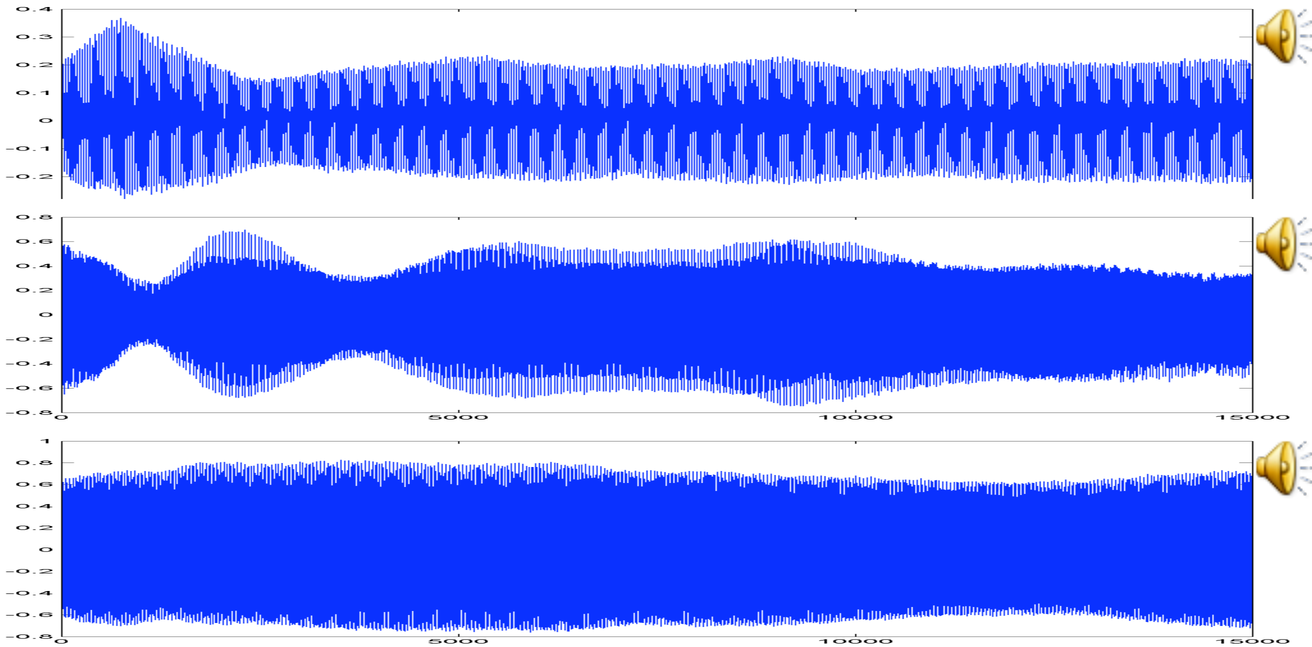

the moon as seen from **Apollo** 8
1223 x 1280 - 214k
LIFE


Apollo 11
1280 x 1277 - 142k
LIFE


Apollo 8 Crew
968 x 1280 - 125k
LIFE

How do you describe them?

Sounds

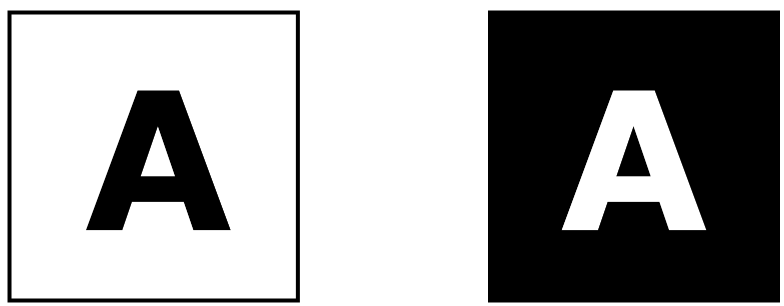


- Sounds are just sequences of numbers

- When plotted, they just look like blobs
  - Which leads to the natural “sounds are blobs”
    - Or more precisely, “sounds are sequences of numbers that, when plotted, look like blobs”
  - Which wont get us anywhere

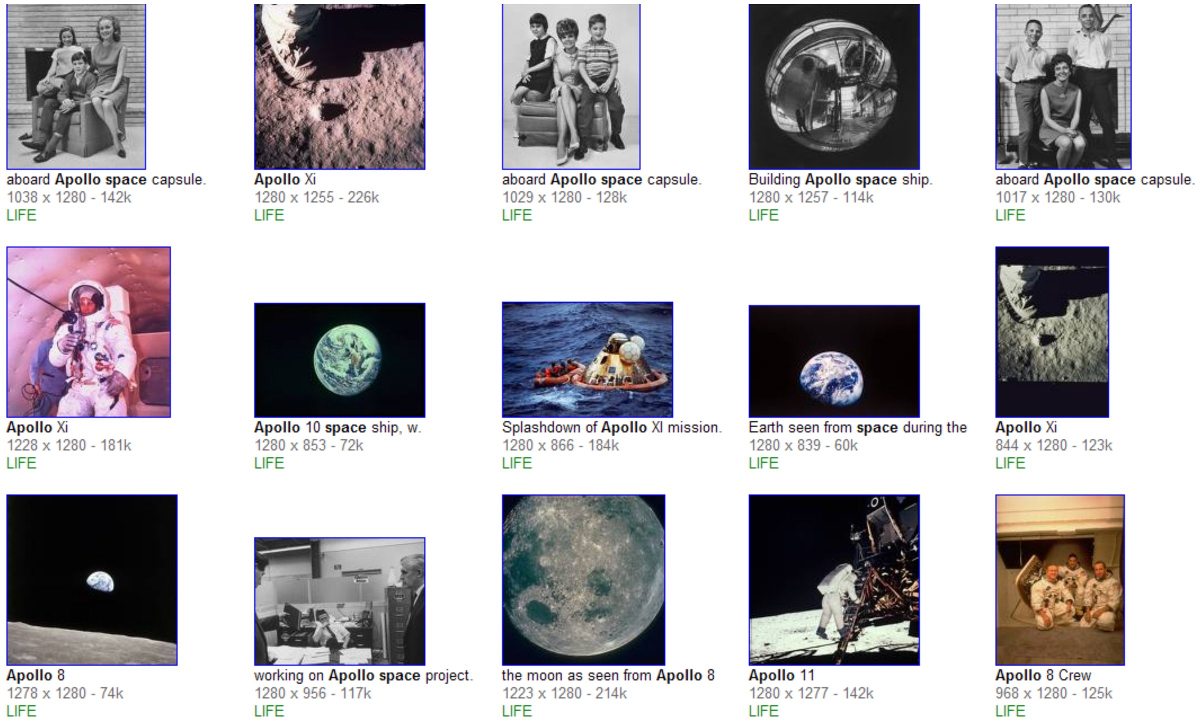
Representation

- Representation is description
- But in compact form
- Must describe the salient characteristics of the data
  - E.g. a pixel-wise description of the two images here will be completely different



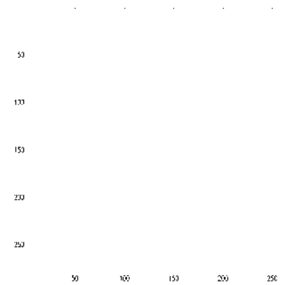
- Must allow identification, comparison, storage..

Representing images



- The most common element in the image: background
  - Or rather large regions of relatively featureless shading
  - Uniform sequences of numbers

Representing images using a "plain" image



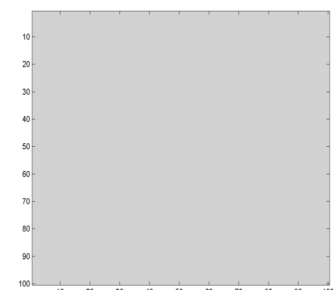
$$B = \begin{bmatrix} 1 \\ 1 \\ . \\ 1 \end{bmatrix} \qquad \text{Image} = \begin{bmatrix} pixel1 \\ pixel2 \\ . \\ pixelN \end{bmatrix}$$

- Most of the figure is a more-or-less uniform shade
  - Dumb approximation – a image is a block of uniform shade
    - Will be mostly right!
  - How much of the figure is uniform?
- How? Projection
  - Represent the images as vectors and compute the projection of the image on the "basis"

$$BW \approx \text{Image}$$

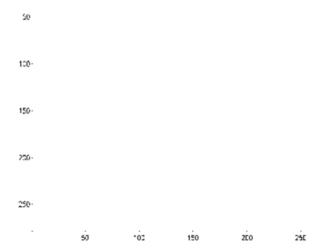
$$W = pinv(B)\,\text{Image}$$

$$PROJECTION = BW = B(B^T B)^{-1} B^T.\text{Image}$$

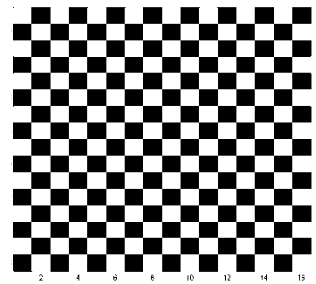


Adding more bases

B1



B2



$$B = \begin{array}{c} \begin{array}{cc} B_1 & B_2 \end{array} \\ \begin{bmatrix} 1 & 1 \\ 1 & -1 \\ 1 & 1 \\ 1 & -1 \\ 1 & 1 \end{bmatrix} \end{array}$$

- Lets improve the approximation
- Images have some fast varying regions
  - Dramatic changes
  - Add a second picture that has very fast changes
    - A checkerboard where every other pixel is black and the rest are white

$$\text{Image} \approx w_1 B_1 + w_2 B_2$$

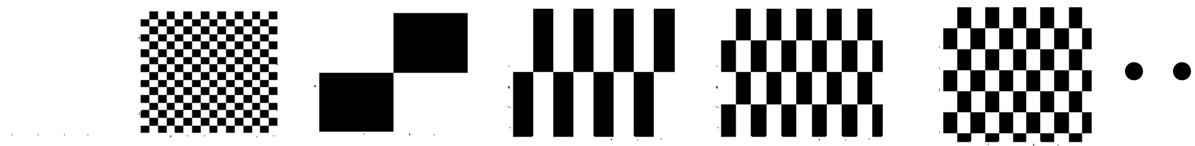
$$W = \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} \qquad B = [B_1 \ \ B_2]$$

$$BW \approx \text{Image}$$

$$W = pinv(B)\text{Image}$$

$$PROJECTION = BW = B(B^T B)^{-1} B^T.\text{Image}$$

Adding still more bases



B_1 B_2 B_3 B_4 B_5 B_6

- Regions that change with different speeds

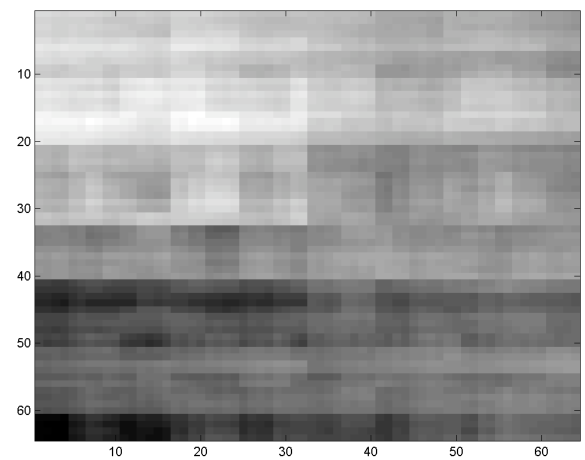
$$\mathrm{Image} \approx w_1 B_1 + w_2 B_2 + w_3 B_3 + \ldots$$

$$W = \begin{bmatrix} w_1 \\ w_2 \\ w_3 \\ . \\ . \end{bmatrix} \qquad B = [B_1 \;\; B_2 \;\; B_3]$$

$$BW \approx \mathrm{Image}$$

$$W = pinv(B)\,\mathrm{Image}$$

$$PROJECTION = BW = B(B^T B)^{-1} B^T.\mathrm{Image}$$



Getting closer at 625 bases!

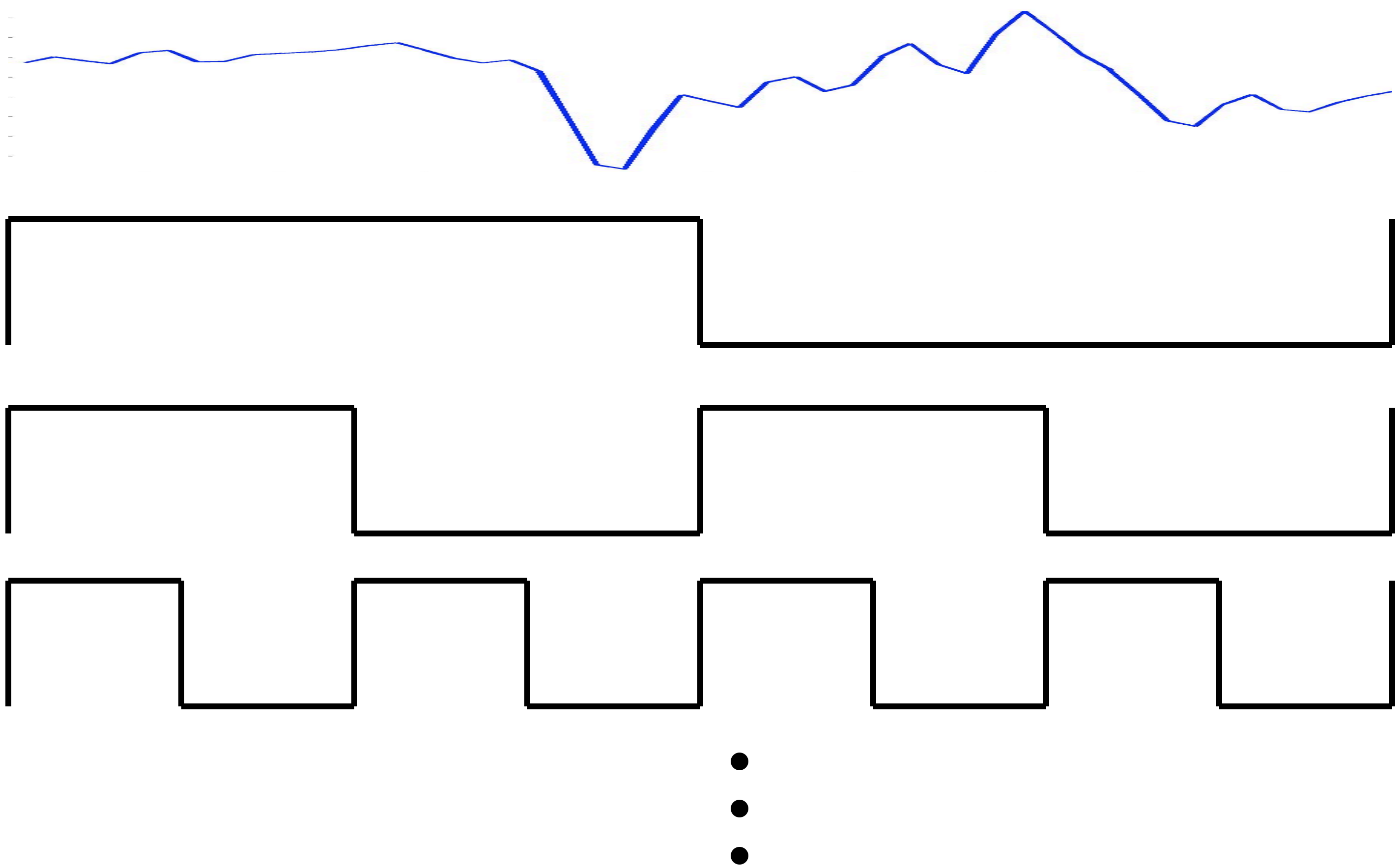
Representation using checkerboards

- A “standard” representation
  - Checker boards are the same regardless of what picture you’re trying to describe
    - As opposed to using “nose shape” to describe faces and “leaf colour” to describe trees.

- Any image can be specified as (for example) 0.8*checkerboard(0) + 0.2*checkerboard(1) + 0.3*checkerboard(2) ..

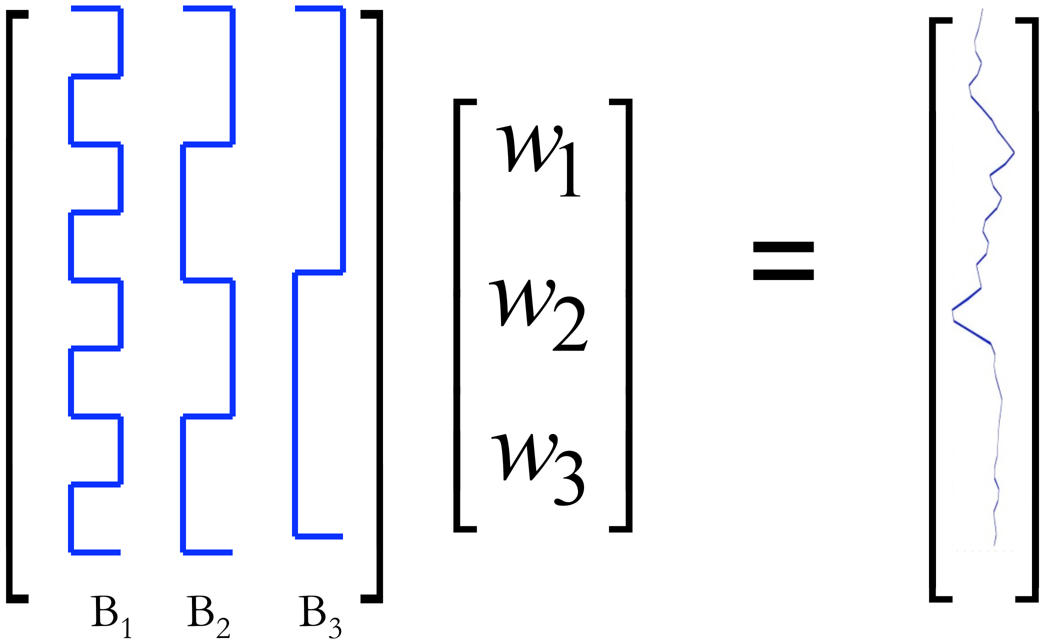
- The definition is sufficient to reconstruct the image to some degree
  - Not perfectly though

What about sounds?



- Square wave equivalents of checker boards

Projecting sounds



$$Signal \approx w_1 B_1 + w_2 B_2 + w_3 B_3$$

$$W = \begin{bmatrix} w_1 \\ w_2 \\ w_3 \end{bmatrix} \qquad B = [B_1 \;\; B_2 \;\; B_3]$$

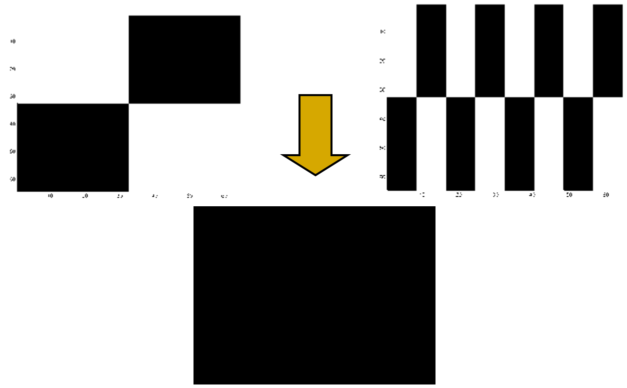
$$BW \approx Signal$$

$$W = pinv(B) Signal$$

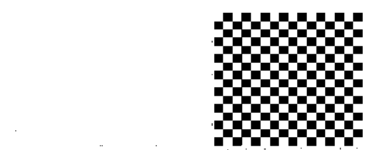
$$PROJECTION = BW = B(B^T B)^{-1} B.Signal$$

Why checkerboards are great bases

- We cannot explain one checkerboard in terms of another
  - The two are orthogonal to one another!



- This means that we can find out the contributions of individual bases separately
  - Joint decompostion with multiple bases with give us the same result as separate decomposition with each of them
  - This never holds true if one basis can explain another



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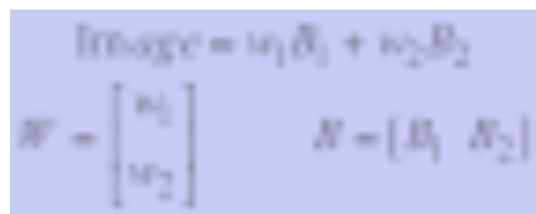
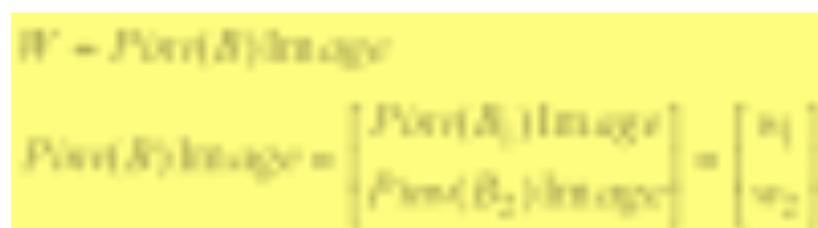
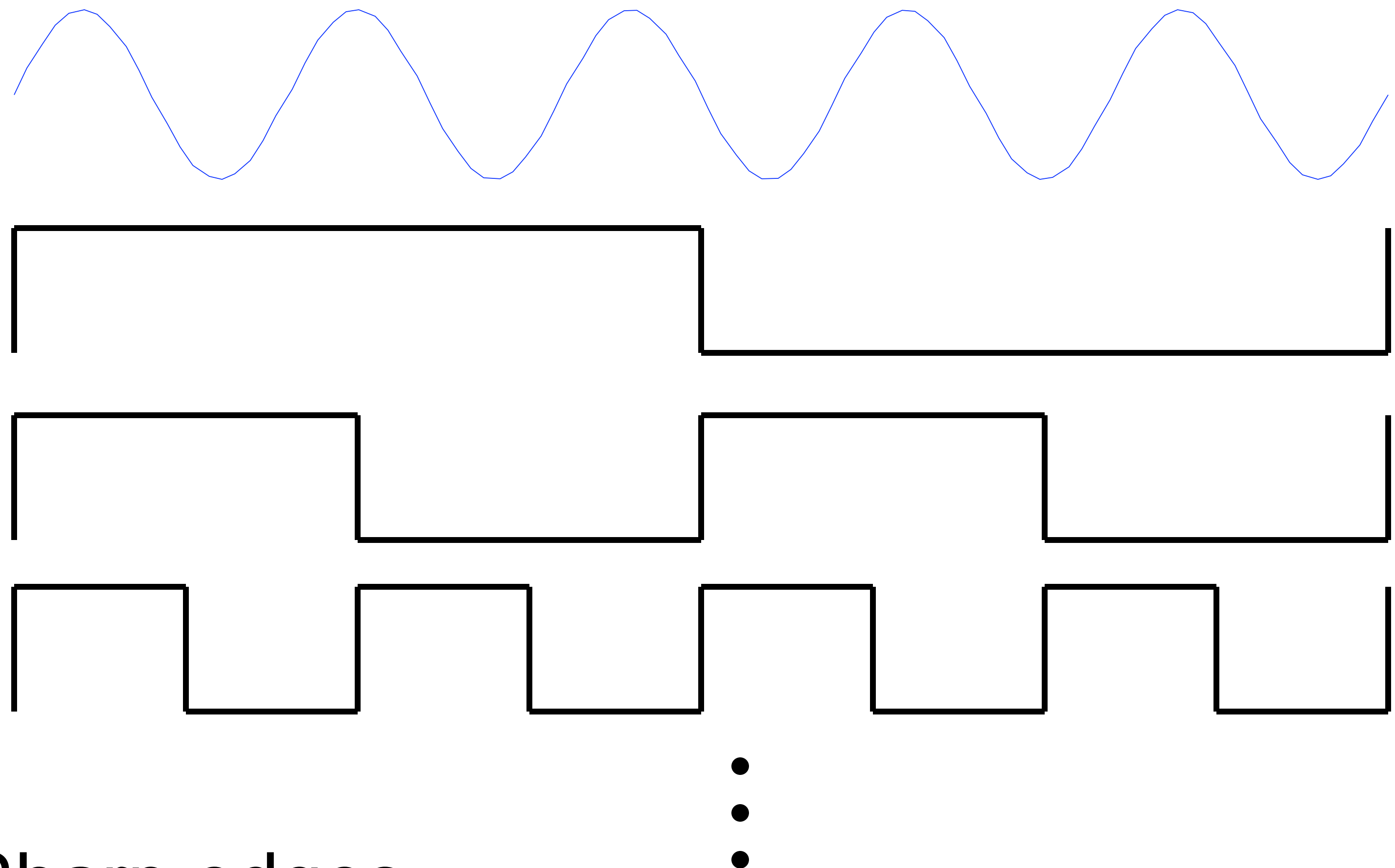
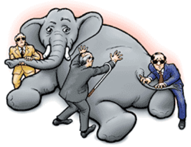




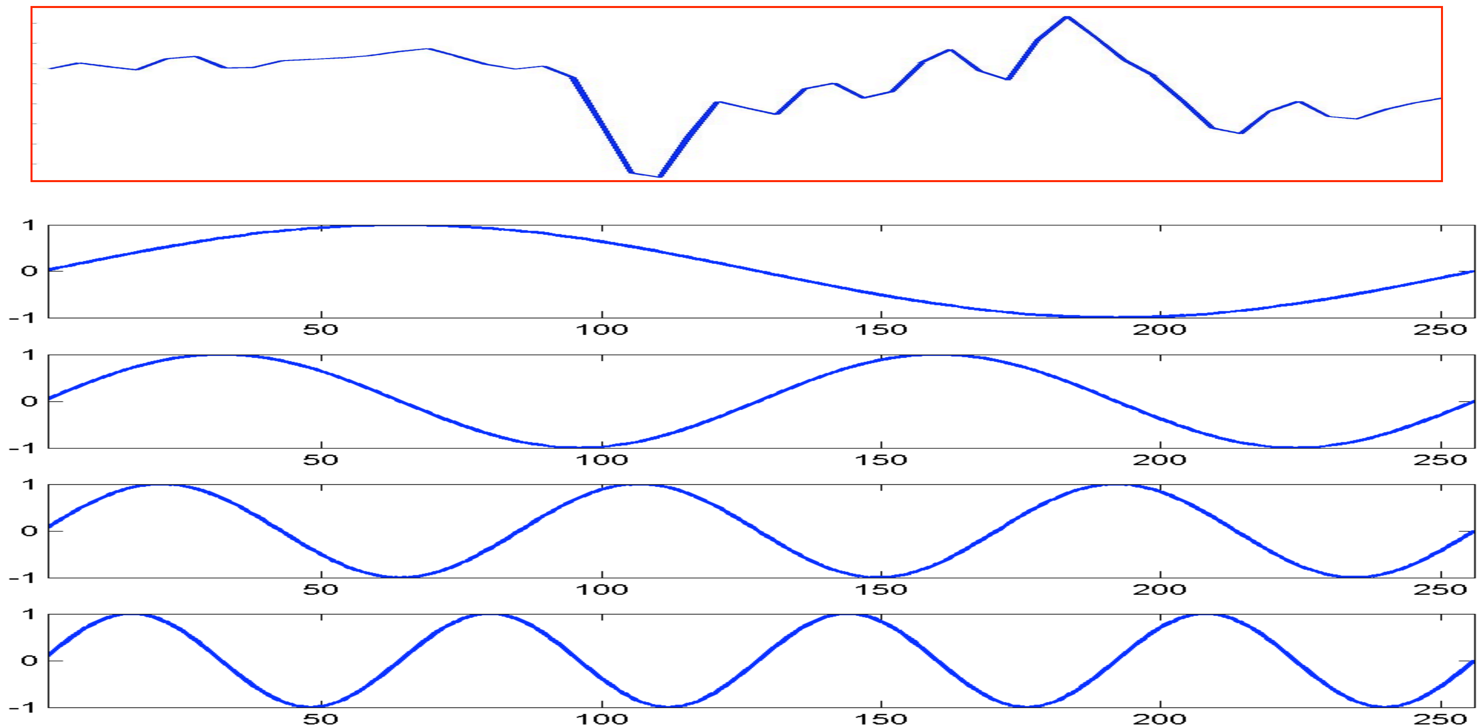
Checker boards are not good bases



- Sharp edges
  - Can *never* be used to explain rounded curves



Sinusoids ARE good bases

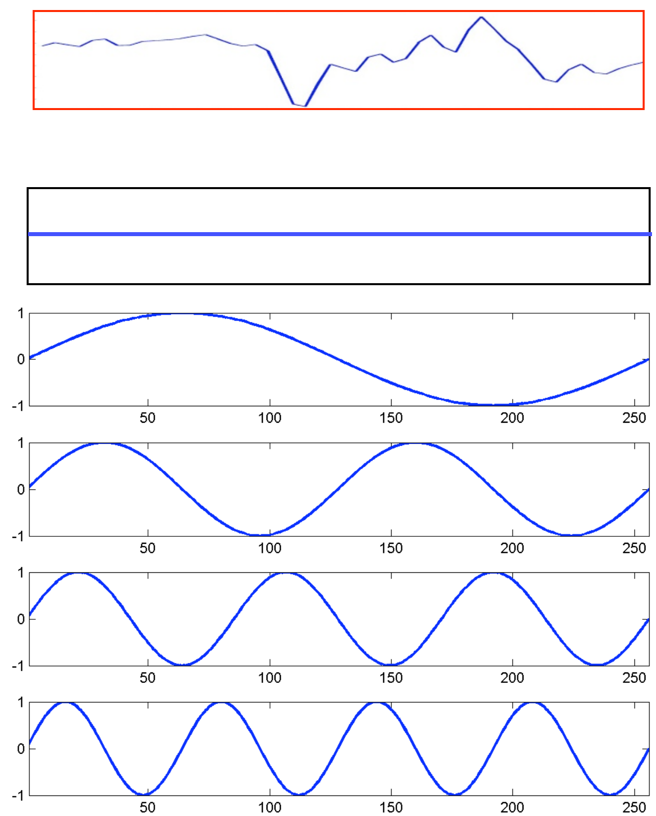


- They are orthogonal
- They can represent rounded shapes nicely
  - Unfortunately, they cannot represent sharp corners

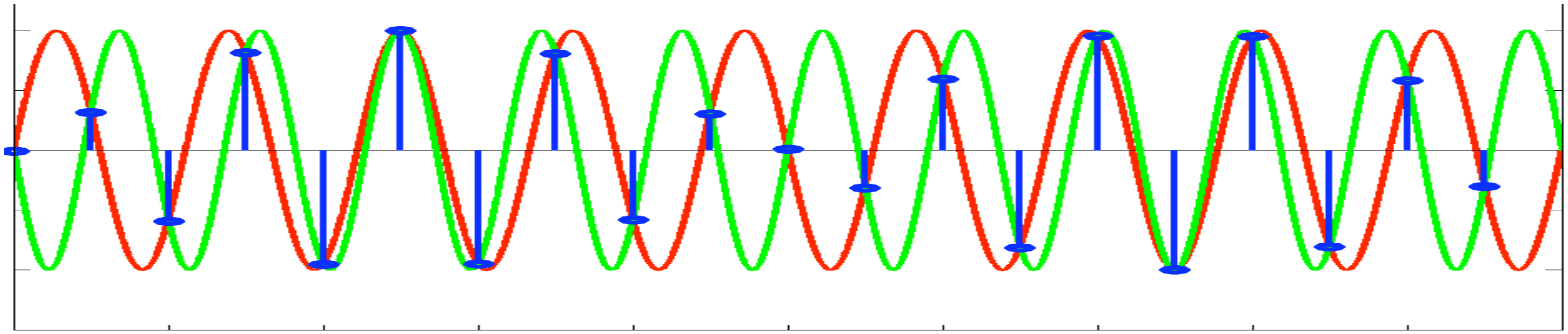
What are the frequencies of the sinusoids

- Follow the same format as the checkerboard:
  - DC
  - The entire length of the signal is one period
  - The entire length of the signal is two periods.
- And so on..

- The k-th sinusoid:
  - $F(n) = \sin(2\pi kn/N)$
    - N is the length of the signal
    - k is the number of periods in N samples



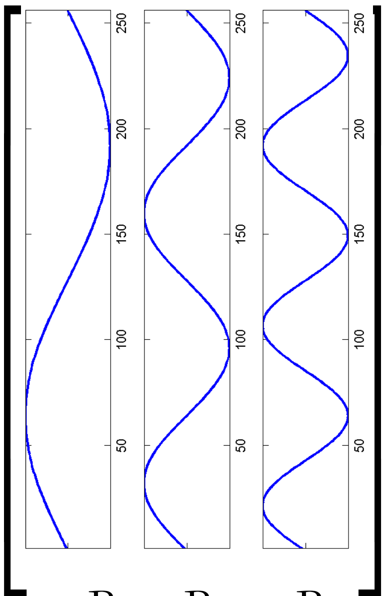
How many frequencies in all?



- A max of L/2 periods are possible
- If we try to go to (L/2 + X) periods, it ends up being identical to having (L/2 – X) periods
  - With sign inversion

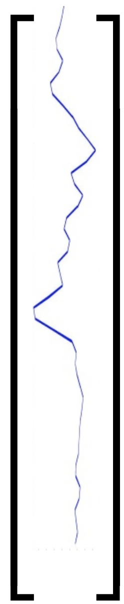
- Example for L = 20
  - Red curve = sine with 9 cycles (in a 20 point sequence)
    - $Y(n) = \sin(2\pi 9n/20)$
  - Green curve = sine with 11 cycles in 20 points
    - $Y(n) = -\sin(2\pi 11n/20)$
  - The blue lines show the actual samples obtained
    - These are the only numbers stored on the computer
    - This set is the same for both sinusoids

How to compose the signal from sinusoids



B$_1$ B$_2$ B$_3$

$$\begin{bmatrix} w_1 \\ w_2 \\ w_3 \end{bmatrix} =$$



$$Signal \approx w_1 B_1 + w_2 B_2 + w_3 B_3$$

$$W = \begin{bmatrix} w_1 \\ w_2 \\ w_3 \end{bmatrix} \qquad B = [B_1 \;\; B_2 \;\; B_3]$$

$$BW \approx Signal$$

$$W = pinv(B)Signal$$

$$PROJECTION = BW = B(B^T B)^{-1} B.Signal$$

- The sines form the vectors of the projection matrix
  - Pinv() will do the trick as usual

How to compose the signal from sinusoids

$$\begin{bmatrix} \sin(2\pi.0.0/L) & \sin(2\pi.1.0/L) & . & . & \sin(2\pi.(L/2).0/L) \\ \sin(2\pi.0.1/L) & \sin(2\pi.1.1/L) & . & . & \sin(2\pi.(L/2).1/L) \\ . & . & . & . & . \\ . & . & . & . & . \\ \sin(2\pi.0.(L-1)/L) & \sin(2\pi.1.(L-1)/L) & . & . & \sin(2\pi.(L/2).(L-1)/L) \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \\ . \\ . \\ w_{L/2} \end{bmatrix} = \begin{bmatrix} s[0] \\ s[1] \\ . \\ . \\ s[L-1] \end{bmatrix}$$

L/2 columns only

$$Signal \approx w_1 B_1 + w_2 B_2 + w_3 B_3$$

$$W = \begin{bmatrix} w_1 \\ w_2 \\ w_3 \end{bmatrix} \qquad B = [B_1 \;\; B_2 \;\; B_3]$$

$$Signal = \begin{bmatrix} s[0] \\ s[1] \\ . \\ s[L-1] \end{bmatrix}$$

$$BW \approx Signal$$

$$W = pinv(B)Signal$$

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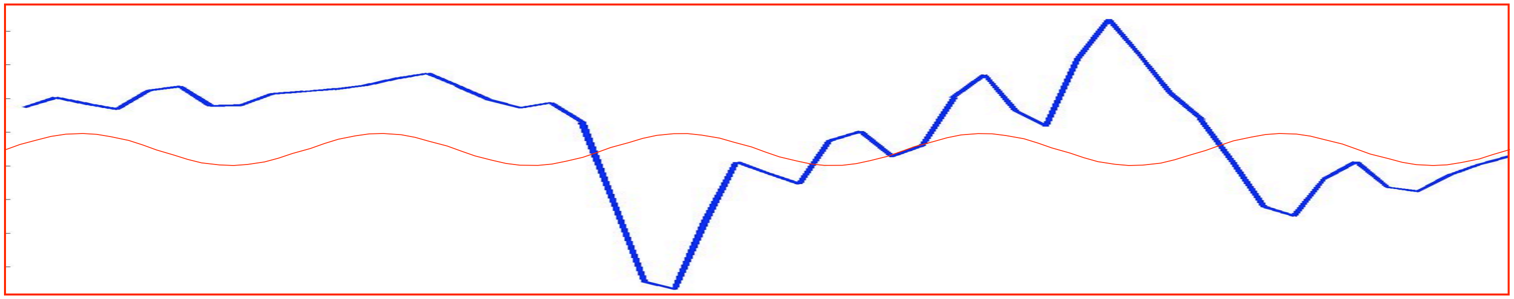
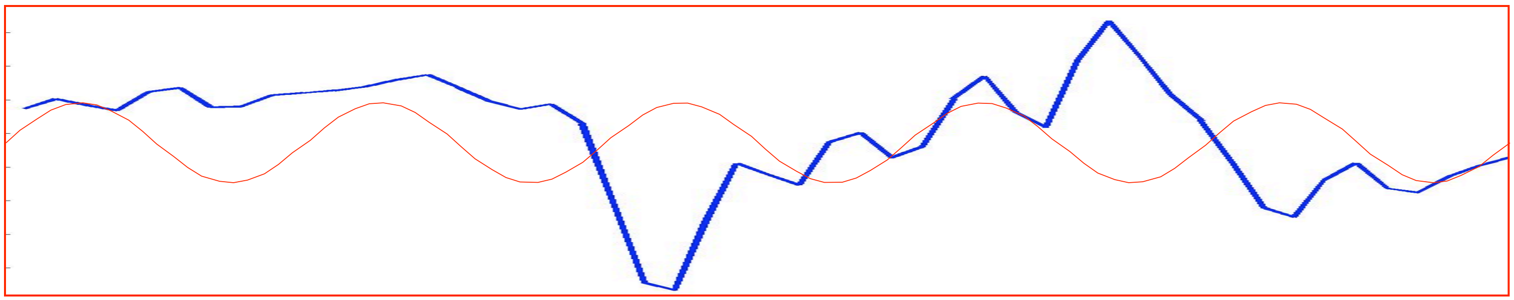
Interpretation..



- Each sinusoid’s amplitude is adjusted until it gives us the least squared error
  - The amplitude is the weight of the sinusoid
- This can be done independently for each sinusoid

Interpretation..



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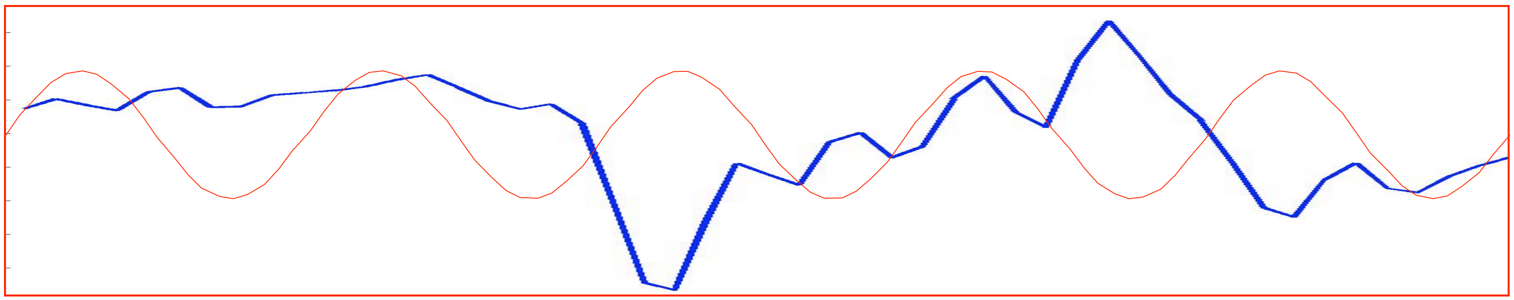

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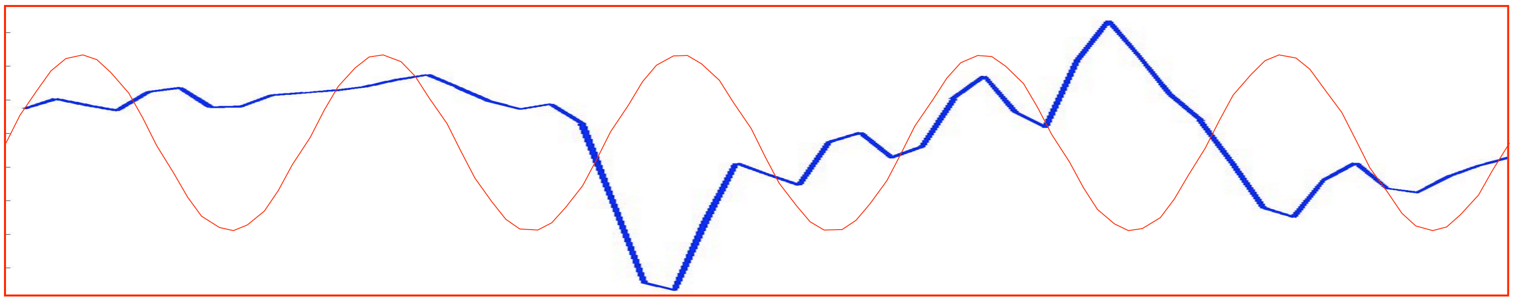

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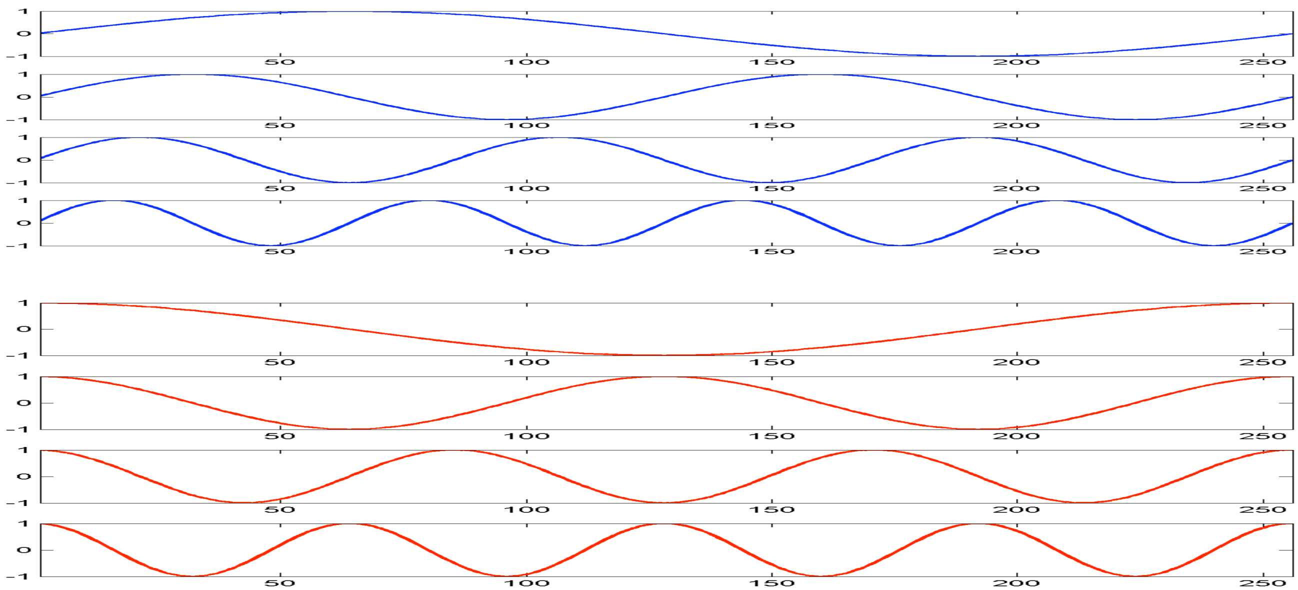
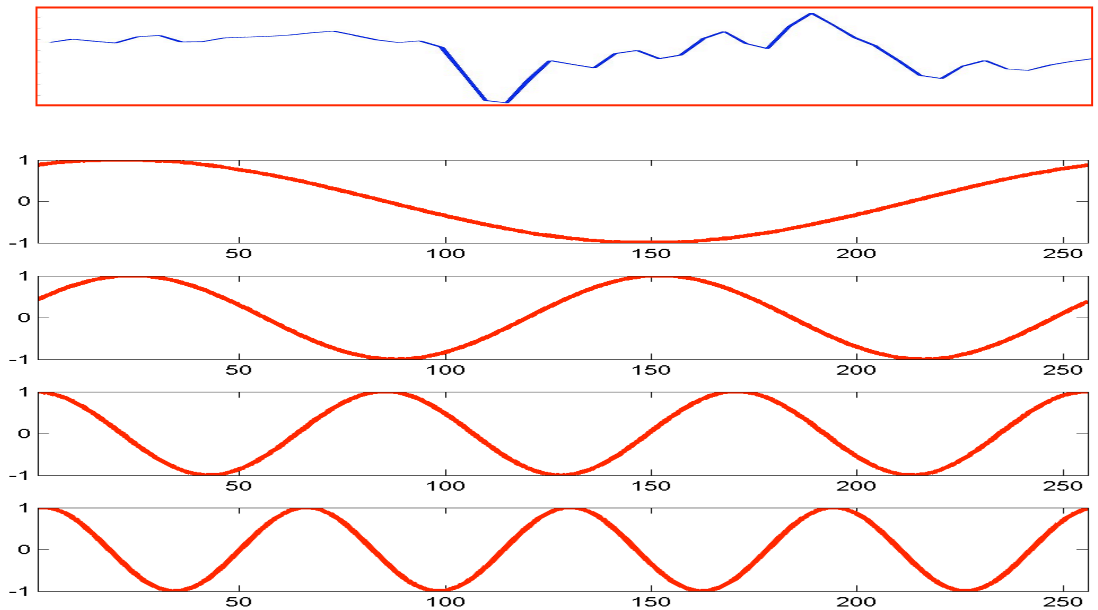
Sines by themselves are not enough



- Every sine starts at zero
  - Can never represent a signal that is non-zero in the first sample!
- Every cosine starts at 1
  - If the first sample is zero, the signal cannot be represented!

The need for phase



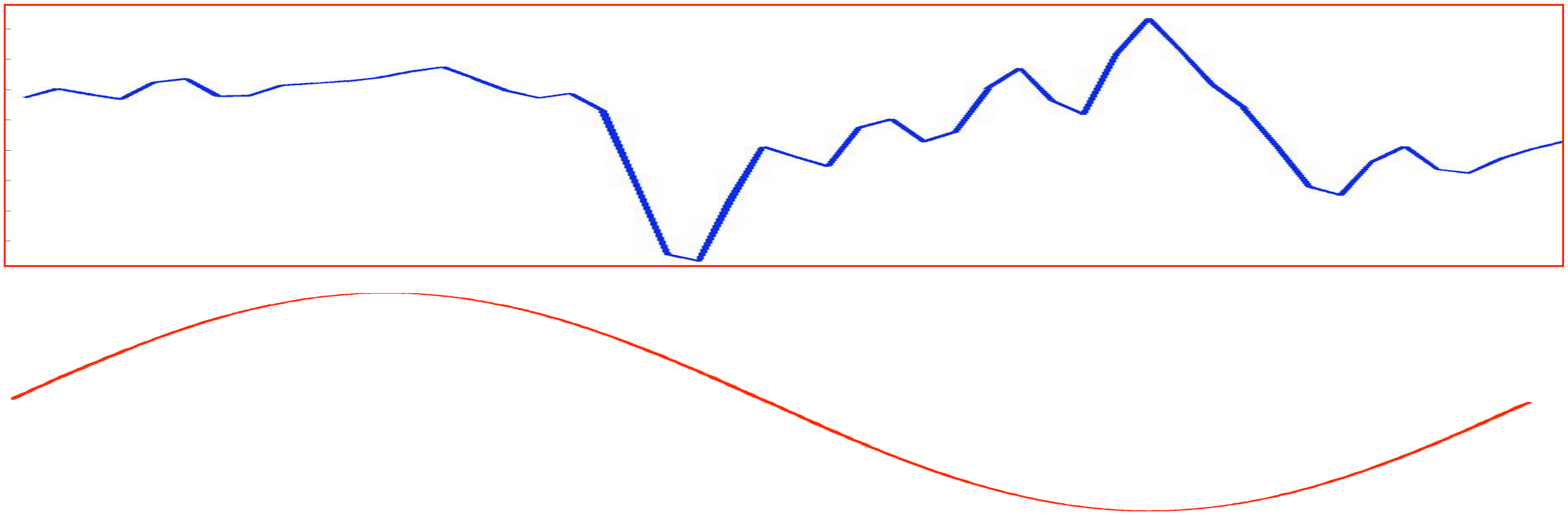
Sines are shifted: do not start with value = 0

- Allow the sinusoids to move!

$$signal = w_1 \sin(2\pi kn / N + \phi_1) + w_2 \sin(2\pi kn / N + \phi_2) + w_3 \sin(2\pi kn / N + \phi_3) + \ldots.$$

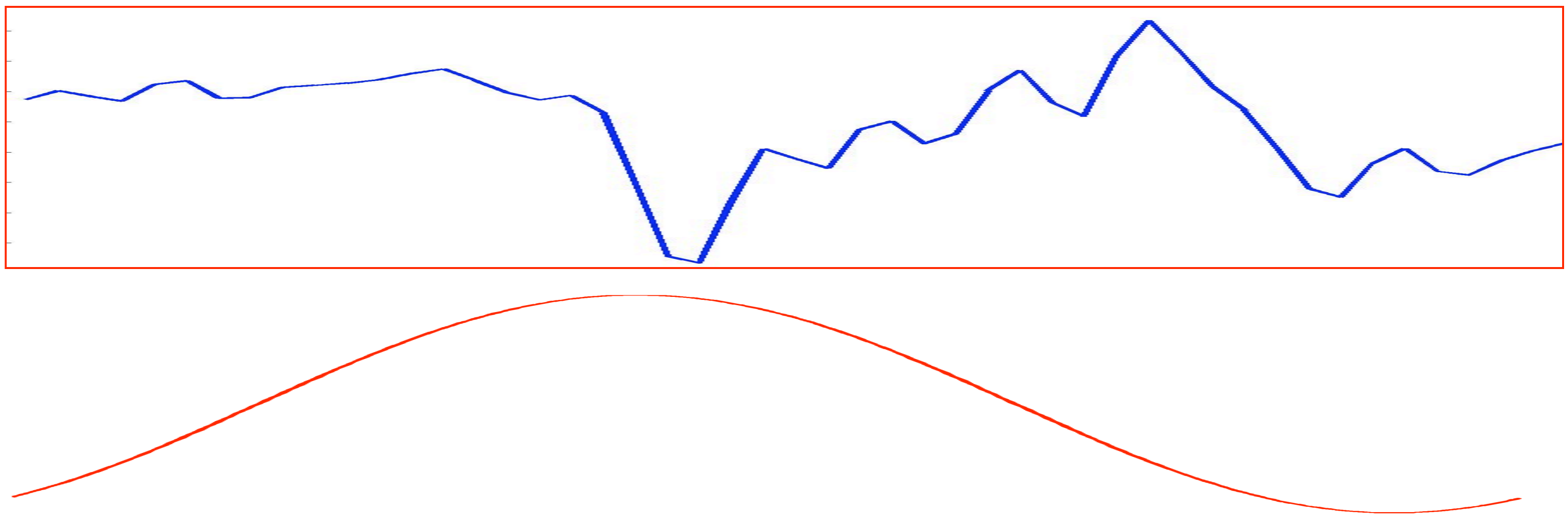
- How much do the sines shift?

Determining phase



- Least squares fitting: move the sinusoid left / right, and at each shift, try all amplitudes
  - Find the combination of amplitude and phase that results in the lowest squared error
- We can still do this separately for each sinusoid
  - The sinusoids are still orthogonal to one another

Determining phase



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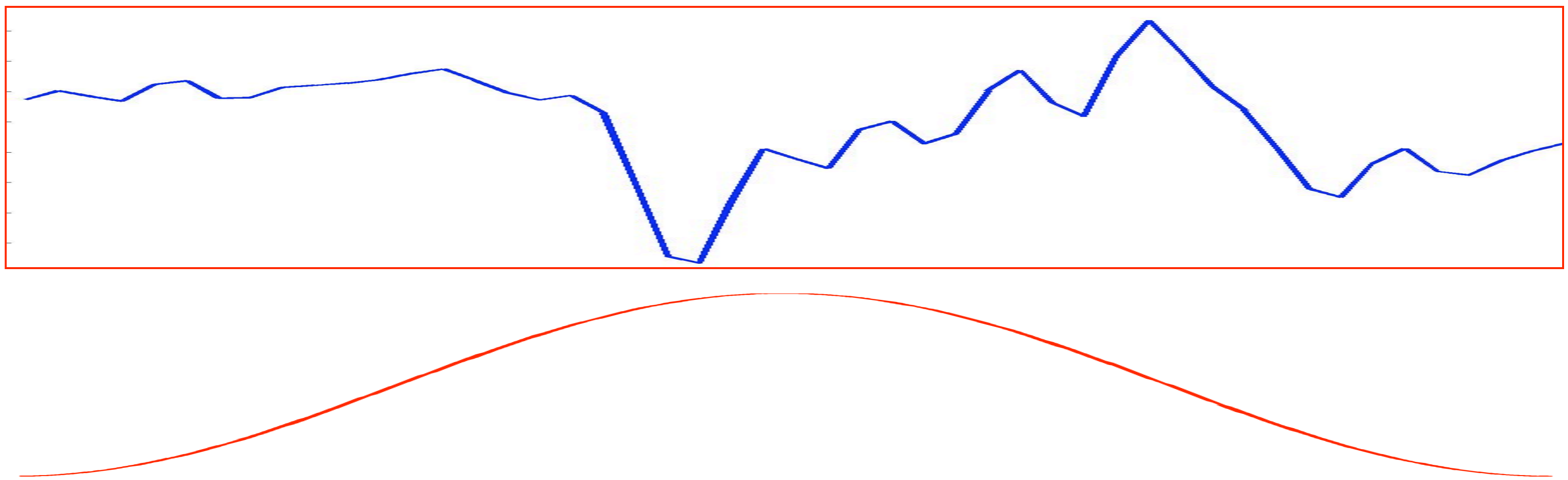

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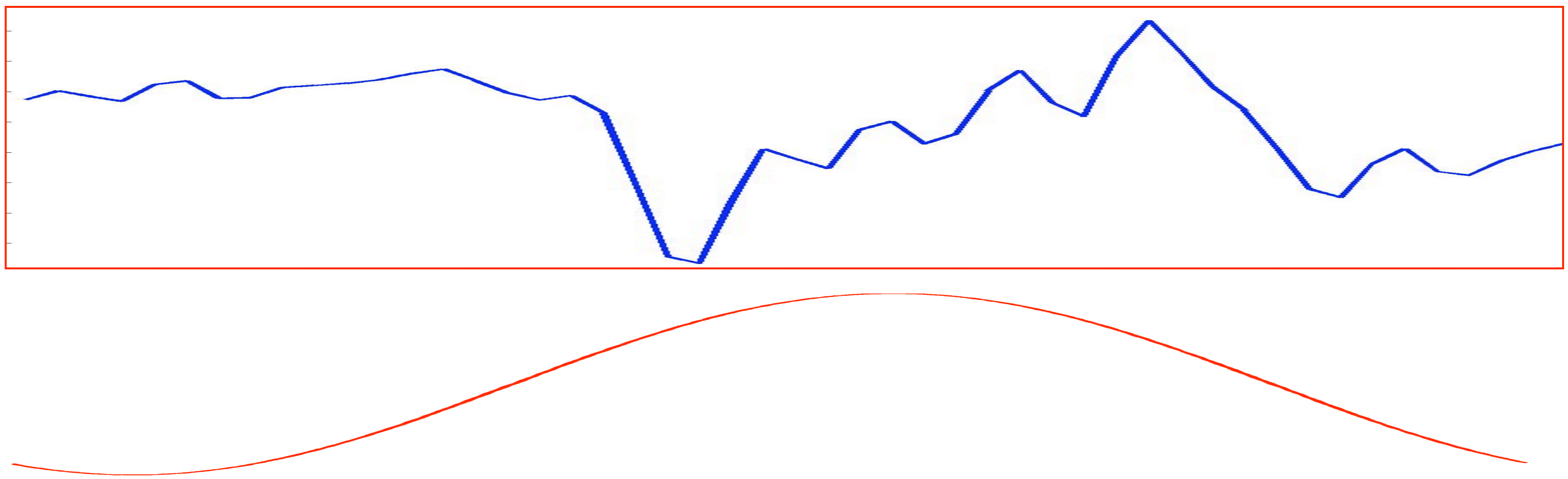

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The problem with phase

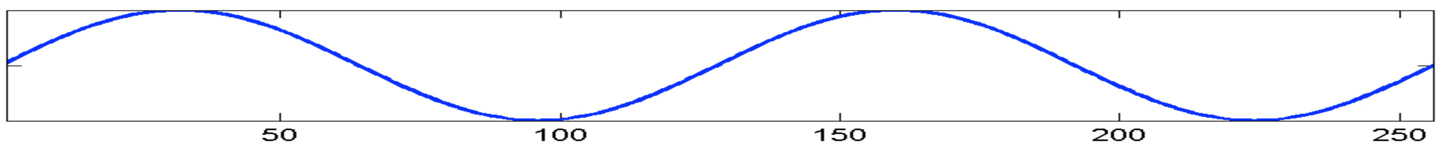
$$\begin{bmatrix} \sin(2\pi.0.0/\mathrm{L}+\phi_0) & \sin(2\pi.1.0/\mathrm{L}+\phi_1) & . & . & \sin(2\pi.(L/2).0/\mathrm{L}+\phi_{\mathrm{L}/2}) \\ \sin(2\pi.0.1/\mathrm{L}+\phi_0) & \sin(2\pi.1.1/\mathrm{L}+\phi_1) & . & . & \sin(2\pi.(L/2).1/\mathrm{L}+\phi_{\mathrm{L}/2}) \\ . & . & . & . & . \\ . & . & . & . & . \\ \sin(2\pi.0.(L-1)/\mathrm{L}+\phi_0) & \sin(2\pi.1.(L-1)/\mathrm{L}+\phi_1) & . & . & \sin(2\pi.(L/2).(L-1)/\mathrm{L}+\phi_{\mathrm{L}/2}) \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \\ . \\ . \\ w_{L/2} \end{bmatrix} = \begin{bmatrix} s[0] \\ s[1] \\ . \\ . \\ s[L-1] \end{bmatrix}$$

L/2 columns only

- This can no longer be expressed as a simple linear algebraic equation
  - The phase is integral to the bases
    - I.e. there's a component of the basis itself that must be estimated!
- Linear algebraic notation can only be used if the bases are *fully* known
  - *We can only (pseudo) invert a known matrix*

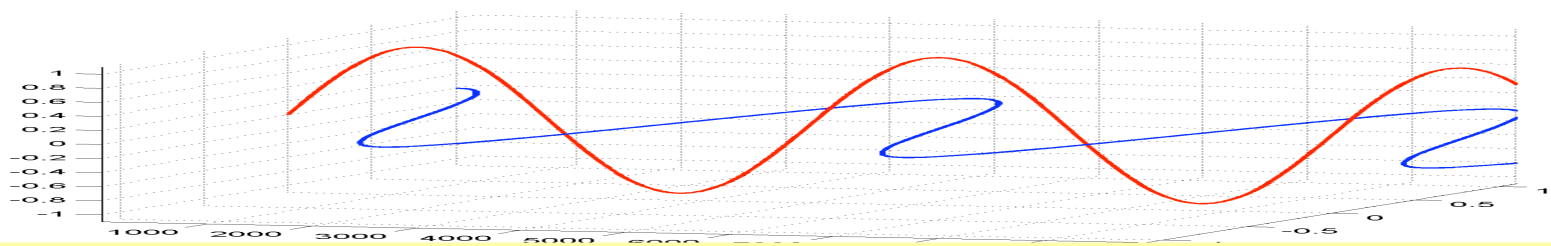
Complex Exponential to the rescue

$$b[n] = \sin(freq * n)$$



$$b[n] = \exp(j * freq * n) = \cos(freq * n) + j\sin(freq * n)$$

$$j = \sqrt{-1}$$

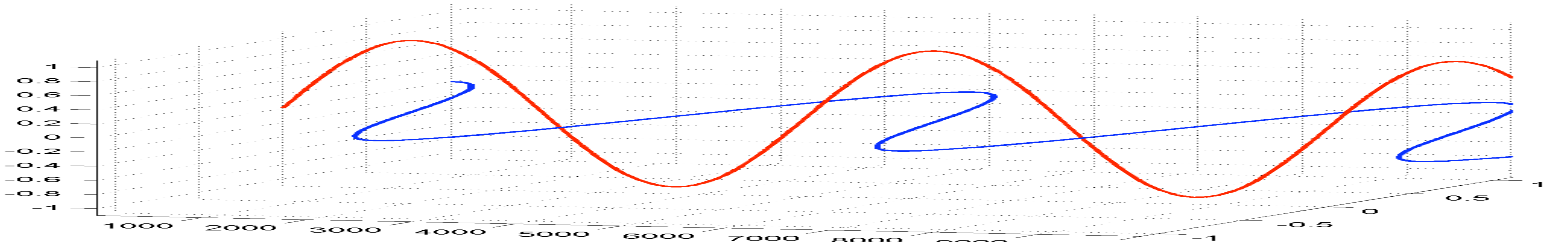


$$\exp(j * freq * n + \phi) = \exp(j * freq * n)\exp(\phi) = \cos(freq * n + \phi) + j\sin(freq * n + \phi)$$

- The cosine is the real part of a complex exponential
  - The sine is the imaginary part
- A phase term for the sinusoid becomes a multiplicative term for the complex exponential!!

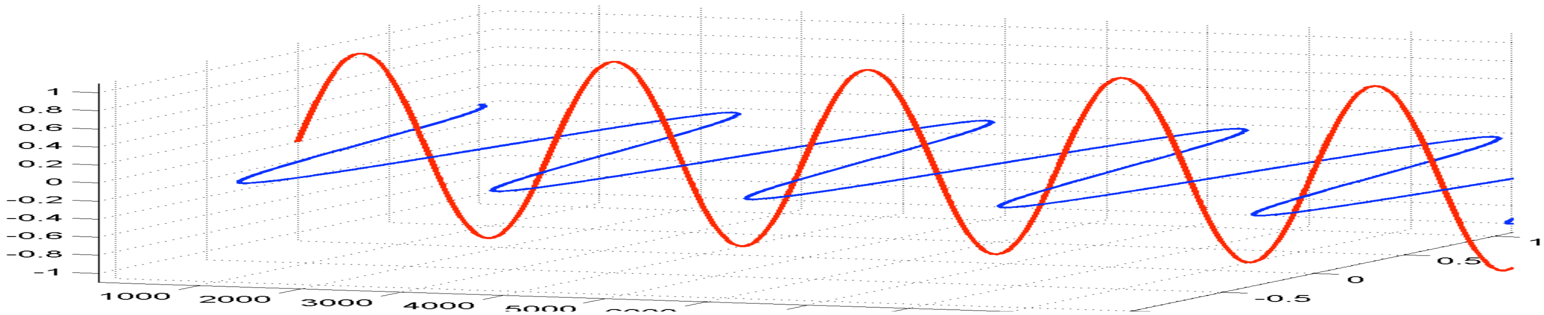
Explaining with Complex Exponentials

A x



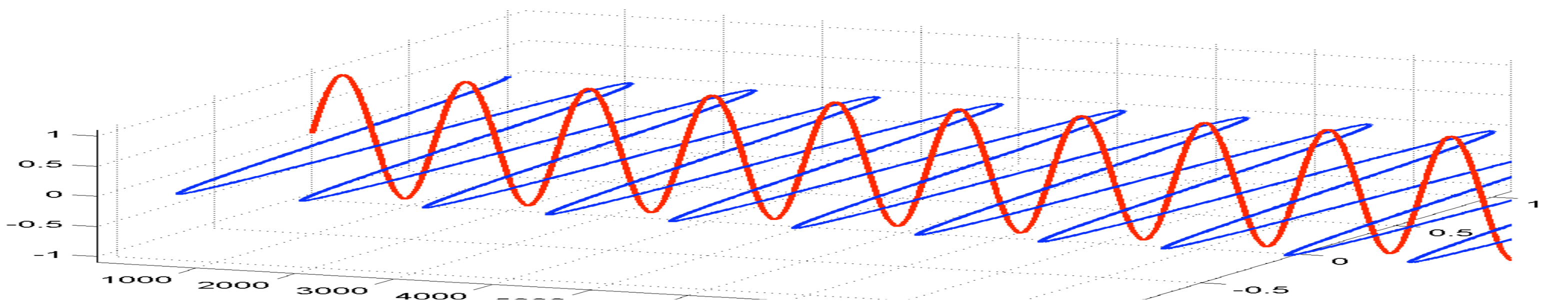
+

B x

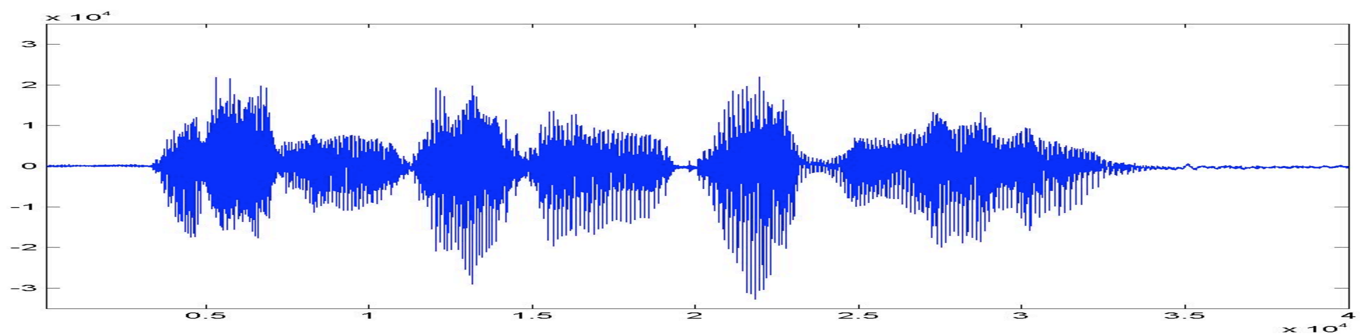


+

C x



=



Complex exponentials are well behaved

- Like sinusoids, a complex exponential of one frequency can never explain one of another
  - They are orthogonal
- They represent smooth transitions
- Bonus: They are *complex*
  - Can even model complex data!
- They can also model real data
  - exp(j x) + exp(-j x) is real
    - cos(x) + j sin(x) + cos(x) – j sin(x) = 2cos(x)
- More importantly
  - $\exp\left(j2\pi\frac{(L/2-x)n}{L}\right)+\exp\left(j2\pi\frac{(L/2+x)n}{L}\right)$ is real
    - The complex exponentials with frequencies equally spaced from L/2 are complex conjugates

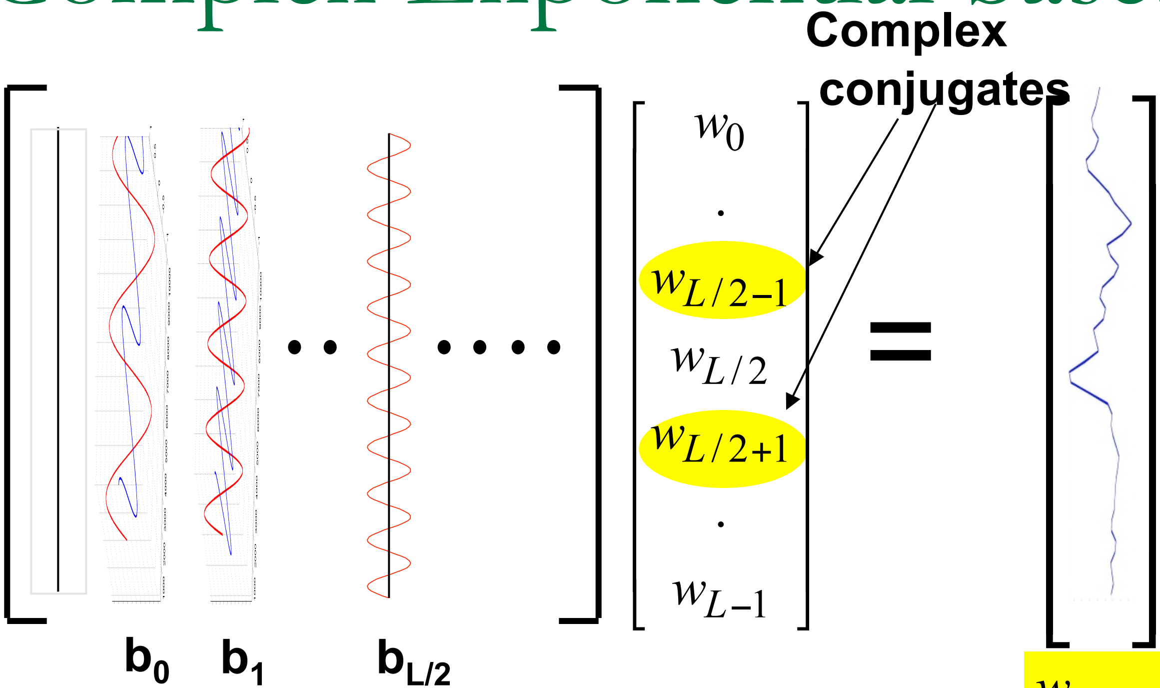
Complex exponentials are well behaved

- $$\exp\left(j2\pi\frac{(L/2-x)n}{L}\right)+\exp\left(j2\pi\frac{(L/2+x)n}{L}\right)$$ is real
  - The complex exponentials with frequencies equally spaced from L/2 are complex conjugates
    - "Frequency = k" ➔ k periods in L samples

$$a\exp\left(j2\pi\frac{(L/2-x)n}{L}\right)+conjugate(a)\exp\left(j2\pi\frac{(L/2+x)n}{L}\right)$$

  - Is also real
  - If the two exponentials are multiplied by numbers that are conjugates of one another the result is real

Complex Exponential bases



$$w_{L/2+k} = conjugate(w_{L/2-k})$$

- Explain the data using L complex exponential bases
- The weights given to the (L/2 + k)th basis and the (L/2 – k)th basis should be complex conjugates, to make the result real
  - Because we are dealing with real data
- Fortunately, a least squares fit will give us identical weights to both bases automatically; there is no need to impose the constraint externally

Complex Exponential Bases: Algebraic Formulation

$$\begin{bmatrix} \exp(j2\pi.0.0/\mathrm{L}) & . & \exp(j2\pi.(L/2).0/\mathrm{L}). & . & \exp(j2\pi.(L-1).0/\mathrm{L}) \\ \exp(j2\pi.0.1/\mathrm{L}) & . & \exp(j2\pi.(L/2).1/\mathrm{L}). & . & \exp(j2\pi.(L-1).1/\mathrm{L}) \\ . & . & . & . & . \\ . & . & . & . & . \\ \exp(j2\pi.0.(L-1)/\mathrm{L}) & . & \exp(j2\pi.(L/2).(L-1)/\mathrm{L}) & . & \exp(j2\pi.(L-1).(L-1)/\mathrm{L}) \end{bmatrix} \begin{bmatrix} S_0 \\ . \\ S_{L/2} \\ . \\ S_{L-1} \end{bmatrix} = \begin{bmatrix} s[0] \\ s[1] \\ . \\ . \\ s[L-1] \end{bmatrix}$$

- Note that $S_{L/2+x} = \text{conjugate}(S_{L/2-x})$

Shorthand Notation

$$W_L^{k,n} = \frac{1}{\sqrt{L}}\exp(j2\pi kn/L) = \frac{1}{\sqrt{L}}\left(\cos(2\pi kn/L) + j\sin(2\pi kn/L)\right)$$

$$\begin{bmatrix} W_L^{0,0} & . & W_L^{L/2,0} & . & W_L^{L-1,0} \\ W_L^{0,1} & . & W_L^{L/2,1} & . & W_L^{L-1,1} \\ . & . & . & . & . \\ . & . & . & . & . \\ W_L^{0,L-1} & . & W_L^{L/2,L-1} & . & W_L^{L-1,L-1} \end{bmatrix} \begin{bmatrix} S_0 \\ . \\ S_{L/2} \\ . \\ S_{L-1} \end{bmatrix} = \begin{bmatrix} s[0] \\ s[1] \\ . \\ . \\ s[L-1] \end{bmatrix}$$

- Note that $S_{L/2+x}$ = conjugate($S_{L/2-x}$)

A quick detour

- Real Orthonormal matrix:
  - $XX^T = X X^T = I$
    - But only if all entries are real
  - The inverse of X is its own transpose
- Definition: Hermitian
  - X^H = Complex conjugate of X^T
    - Conjugate of a number $a + ib = a - ib$
    - Conjugate of $\exp(ix) = \exp(-ix)$
- Complex Orthonormal matrix
  - $XX^H = X^H X = I$
  - The inverse of a complex orthonormal matrix is its own Hermitian

$W^{-1} = W^H$

$$W = \begin{bmatrix} W_L^{0,0} & . & W_L^{L/2,0}. & . & W_L^{L-1,0} \\ W_L^{0,1} & . & W_L^{L/2,1}. & . & W_L^{L-1,1} \\ . & . & . & . & . \\ . & . & . & . & . \\ W_L^{0,L-1} & . & W_L^{L/2,L-1} & . & W_L^{L-1,L-1} \end{bmatrix} \qquad W_L^{k,n} = \frac{1}{\sqrt{L}} \exp(j2\pi kn/L)$$

$$W_L^{-k,n} = \frac{1}{\sqrt{L}} \exp(-j2\pi kn/L) \qquad W^H = \begin{bmatrix} W_L^{0,0} & . & W_L^{-0,L/2}. & . & W_L^{-0,L-1} \\ W_L^{-1,0,} & . & W_L^{-1,L/2}. & . & W_L^{-1,L-1} \\ . & . & . & . & . \\ . & . & . & . & . \\ W_L^{-(L-1),0} & . & W_L^{-(L-1),L/2} & . & W_L^{-(L-1),(L-1)} \end{bmatrix}$$

- The complex exponential basis is orthonormal
  - Its inverse is its own Hermitian
  - $W^{-1} = W^H$

Doing it in matrix form

$$\begin{bmatrix} W_L^{0,0} & . & W_L^{L/2,0}. & . & W_L^{L-1,0} \\ W_L^{0,1} & . & W_L^{L/2,1}. & . & W_L^{L-1,1} \\ . & . & . & . & . \\ . & . & . & . & . \\ W_L^{0,L-1} & . & W_L^{L/2,L-1} & . & W_L^{L-1,L-1} \end{bmatrix} \begin{bmatrix} S_0 \\ . \\ S_{L/2} \\ . \\ S_{L-1} \end{bmatrix} = \begin{bmatrix} s[0] \\ s[1] \\ . \\ . \\ s[L-1] \end{bmatrix}$$

$$\begin{bmatrix} S_0 \\ . \\ S_{L/2} \\ . \\ S_{L-1} \end{bmatrix} = \begin{bmatrix} W_L^{0,0} & . & W_L^{-0,L/2}. & . & W_L^{-0,L-1} \\ W_L^{-1,0,} & . & W_L^{-1,L/2}. & . & W_L^{-1,L-1} \\ . & . & . & . & . \\ . & . & . & . & . \\ W_L^{-(L-1),0} & . & W_L^{-(L-1),L/2} & . & W_L^{-(L-1),(L-1)} \end{bmatrix} \begin{bmatrix} s[0] \\ s[1] \\ . \\ . \\ s[L-1] \end{bmatrix}$$

- Because $W^{-1} = W^H$

The Discrete Fourier Transform

$$\begin{bmatrix} S_0 \\ . \\ S_{L/2} \\ . \\ S_{L-1} \end{bmatrix} = \begin{bmatrix} W_L^{0,0} & . & W_L^{-0,L/2} & . & W_L^{-0,L-1} \\ W_L^{-1,0,} & . & W_L^{-1,L/2} & . & W_L^{-1,L-1} \\ . & . & . & . & . \\ . & . & . & . & . \\ W_L^{-(L-1),0} & . & W_L^{-(L-1),L/2} & . & W_L^{-(L-1),(L-1)} \end{bmatrix} \begin{bmatrix} s[0] \\ s[1] \\ . \\ . \\ s[L-1] \end{bmatrix}$$

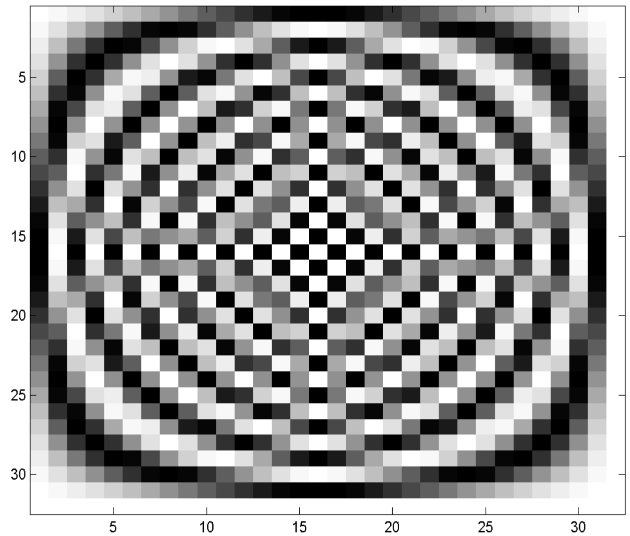
- The matrix to the right is called the “Fourier Matrix”
- The weights (S_0, S_1. . Etc.) are called the Fourier transform

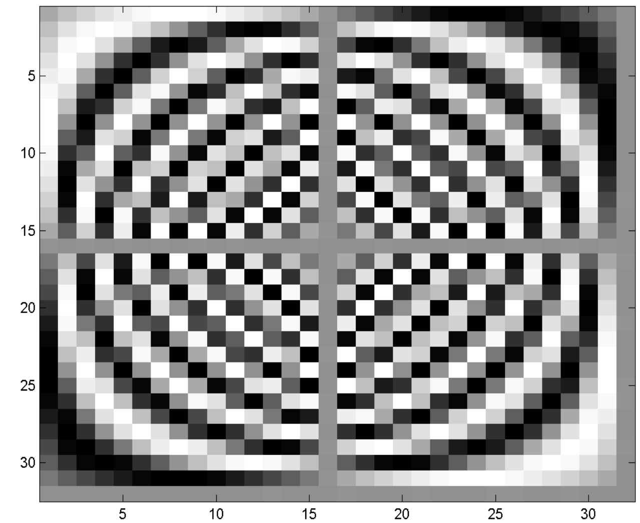
The Inverse Discrete Fourier Transform

$$
\begin{bmatrix}
W_L^{0,0} & . & W_L^{L/2,0} . & . & W_L^{L-1,0} \\
W_L^{0,1} & . & W_L^{L/2,1} . & . & W_L^{L-1,1} \\
. & . & . & . & . \\
. & . & . & . & . \\
W_L^{0,L-1} & . & W_L^{L/2,L-1} & . & W_L^{L-1,L-1}
\end{bmatrix}
\begin{bmatrix}
S_0 \\ . \\ S_{L/2} \\ . \\ S_{L-1}
\end{bmatrix}
=
\begin{bmatrix}
s[0] \\ s[1] \\ . \\ . \\ s[L-1]
\end{bmatrix}
$$

- The matrix to the left is the inverse Fourier matrix
- Multiplying the Fourier transform by this matrix gives us the signal right back from its Fourier transform

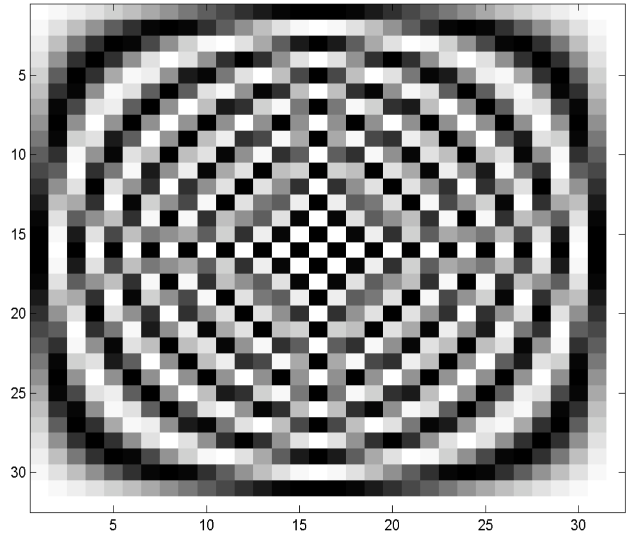
The Fourier Matrix

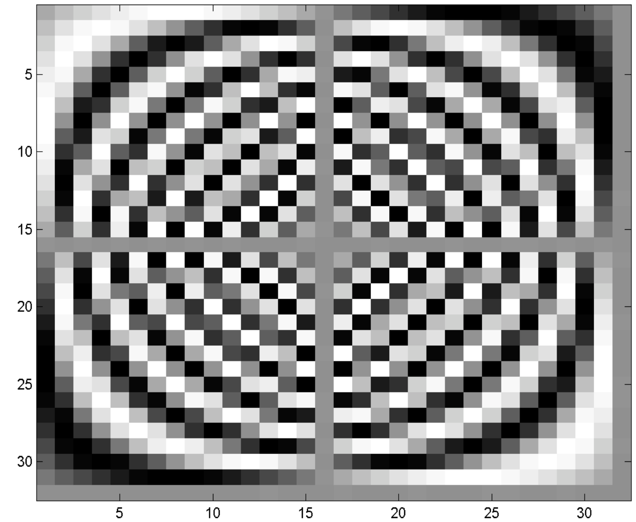




- Left panel: The real part of the Fourier matrix
  - For a 32-point signal
- Right panel: The imaginary part of the Fourier matrix

The FAST Fourier Transform



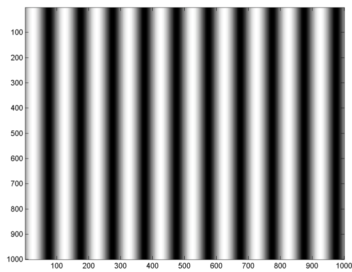


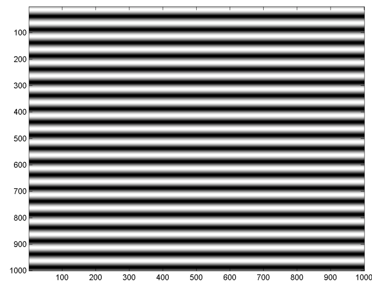
- The outcome of the transformation with the Fourier matrix is the **DISCRETE FOURIER TRANSFORM** (DFT)
- The **FAST Fourier transform** is an algorithm that takes advantage of the symmetry of the matrix to perform the matrix multiplication really fast
- The FFT computes the DFT
  - Is much faster if the length of the signal can be expressed as 2^N

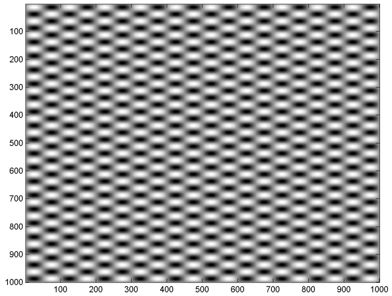
Images

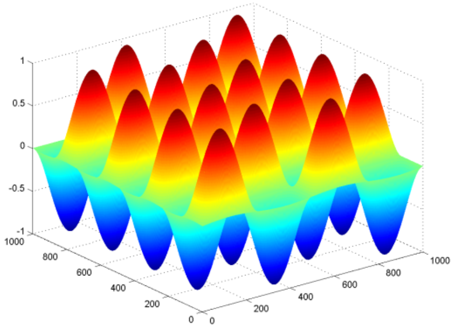
- The complex exponential is two dimensional
  - Has a separate X frequency and Y frequency
    - Would be true even for checker boards!
  - The 2-D complex exponential must be unravelled to form one component of the Fourier matrix
    - For a KxL image, we'd have K*L bases in the matrix

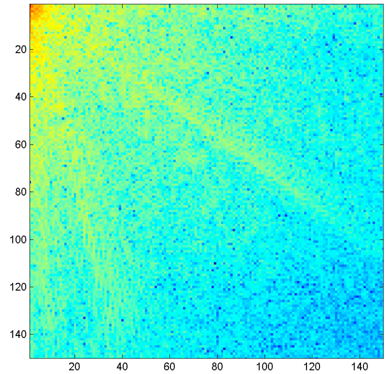
Typical Image Bases











- Only real components of bases shown

DFT: Properties

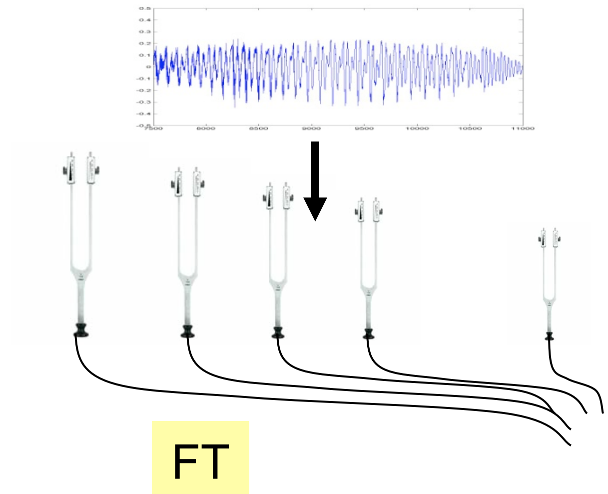
- The DFT coefficients are complex
  - Have both a magnitude and a phase

$$S_k = |S_k| \exp(-j\angle S_k)$$

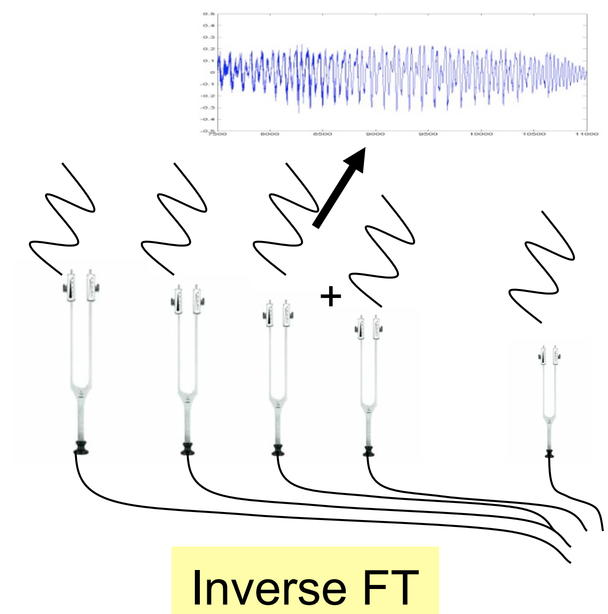
- Simple linear algebra tells us that
  - DFT(A + B) = DFT(A) + DFT(B)
  - The DFT of the sum of two signals is the DFT of their sum
- A horribly common approximation in sound processing
  - Magnitude(DFT(A+B)) = Magnitude(DFT(A)) + Magnitude(DFT(B))
  - Utterly wrong
  - Absurdly useful

The Fourier Transform and Perception: Sound

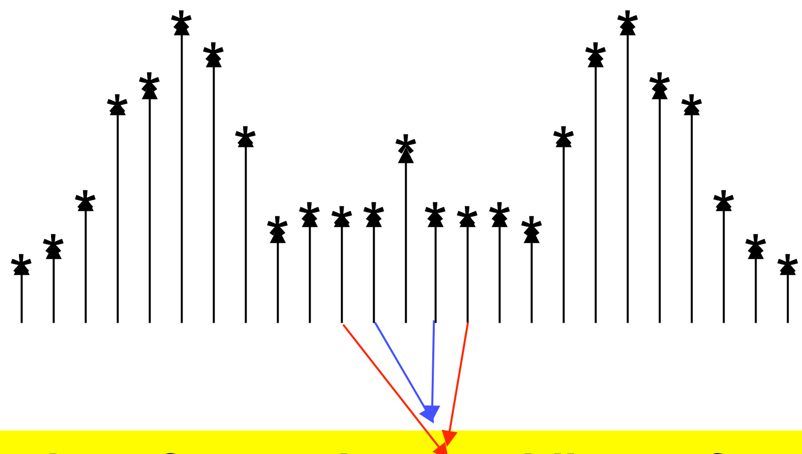
- The Fourier transforms represents the signal analogously to a bank of tuning forks



- Our ear *has* a bank of tuning forks
- The output of the Fourier transform is perceptually very meaningful



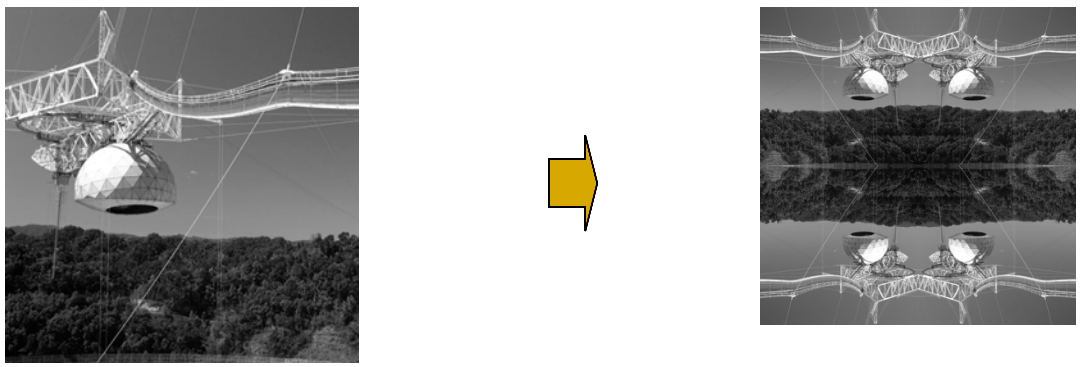
Symmetric signals



Contributions from points equidistant from L/2 combine to cancel out imaginary terms

- If a signal is symmetric around L/2, the Fourier coefficients are real!
  - $A(L/2-k) * \exp(-j * f * (L/2-k)) + A(L/2+k) * \exp(-j * f * (L/2+k))$ is always real if **$A(L/2-k) = A(L/2+k)$**
  - We can pair up samples around the center all the way; the final summation term is always real
- Overall symmetry properties
  - If the *signal* is real, the FT is symmetric
  - If the signal is symmetric, the FT is real
  - If the signal is real and symmetric, the FT is real and symmetric

The Discrete Cosine Transform



- Compose a symmetric signal or image
  - Images would be symmetric in two dimensions

- Compute the Fourier transform
  - Since the FT is symmetric, sufficient to store only half the coefficients (quarter for an image)
    - Or as many coefficients as were originally in the signal / image

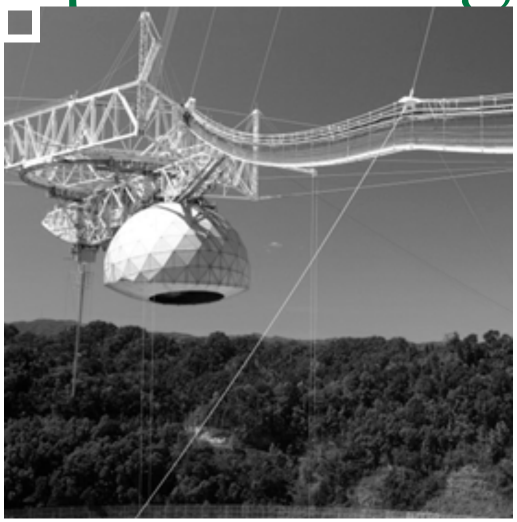
DCT

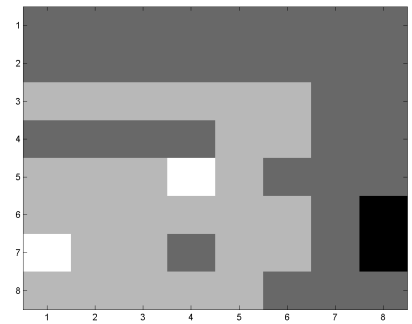
$$
\begin{bmatrix}
\cos(2\pi(0.5).0/2\mathrm{L}) & \cos(2\pi.(1+0.5).0/2\mathrm{L}) & . & . & \cos(2\pi.(L-0.5).0/2\mathrm{L}) \\
\cos(2\pi.(0.5).1/2\mathrm{L}) & \cos(2\pi.(1+0.5).1/2\mathrm{L}) & . & . & \cos(2\pi.(L-0.5).1/2\mathrm{L}) \\
. & . & . & . & . \\
. & . & . & . & . \\
\cos(2\pi.(0.5).(L-1)/2\mathrm{L}) & \cos(2\pi.(1+0.5).(L-1)/2\mathrm{L}) & . & . & \cos(2\pi.(L-0.5).(L-1)/2\mathrm{L})
\end{bmatrix}
\begin{bmatrix} w_0 \\ w_1 \\ . \\ . \\ w_{L-1} \end{bmatrix}
=
\begin{bmatrix} s[0] \\ s[1] \\ . \\ . \\ s[L-1] \end{bmatrix}
$$

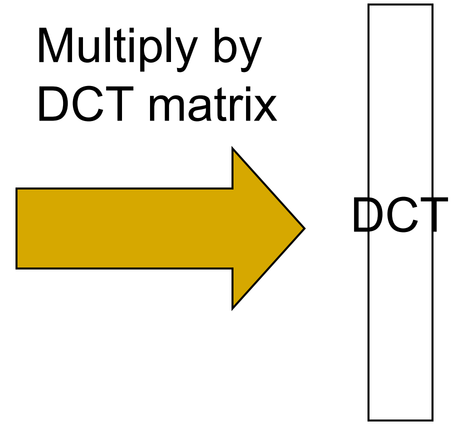
L columns

- Not necessary to compute a 2xL sized FFT
  - Enough to compute an L-sized *cosine* transform
  - Taking advantage of the symmetry of the problem
- This is the Discrete Cosine Transform

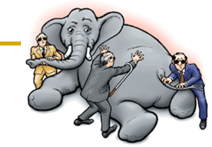
Representing images







- Most common coding is the DCT
- JPEG: Each 8x8 element of the picture is converted using a DCT
- The DCT coefficients are quantized and stored
  - Degree of quantization = degree of compression
- Also used to represent textures etc for pattern recognition and other forms of analysis



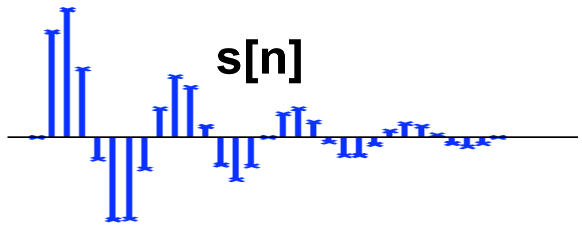
What does the DFT represent

$$\begin{bmatrix} \exp(j2\pi.0.0/\mathrm{L}) & . & \exp(j2\pi.(L/2).0/\mathrm{L}). & . & \exp(j2\pi.(L-1).0/\mathrm{L}) \\ \exp(j2\pi.0.1/\mathrm{L}) & . & \exp(j2\pi.(L/2).1/\mathrm{L}). & . & \exp(j2\pi.(L-1).1/\mathrm{L}) \\ . & . & . & . & . \\ . & . & . & . & . \\ \exp(j2\pi.0.(L-1)/\mathrm{L}) & . & \exp(j2\pi.(L/2).(L-1)/\mathrm{L}) & . & \exp(j2\pi.(L-1).(L-1)/\mathrm{L}) \end{bmatrix} \begin{bmatrix} S_0 \\ . \\ S_{L/2} \\ . \\ S_{L-1} \end{bmatrix} = \begin{bmatrix} s[0] \\ s[1] \\ . \\ . \\ s[L-1] \end{bmatrix}$$

$$s[n] = \sum_{k=0}^{L-1} S_k \exp(j2\pi kn/L)$$

- The DFT can be written formulaically as above
- There is no restriction on computing the formula for n < 0 or n > L-1
  - Its just a formula
  - But computing these terms behind 0 or beyond L-1 tells us what the signal composed by the DFT looks like outside our narrow window

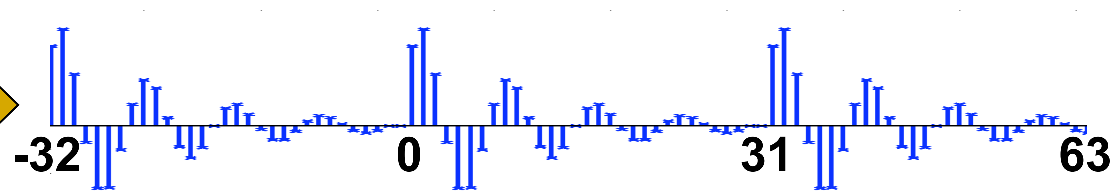
What does the DFT represent



DFT

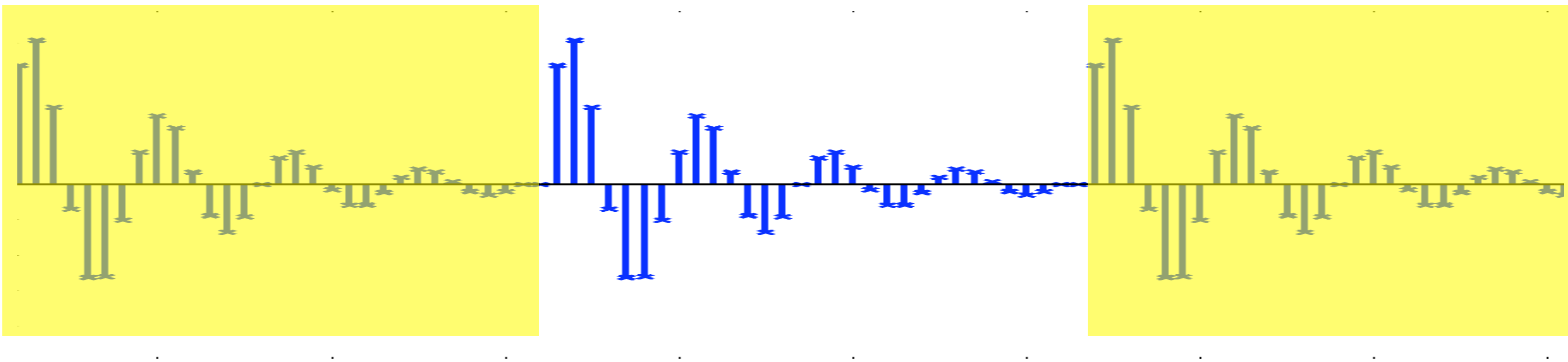
$[S_0\ S_1\ ..\ S_{31}]$

$$s[n] = \sum_{k=0}^{L-1} S_k \exp(j2\pi kn / L)$$



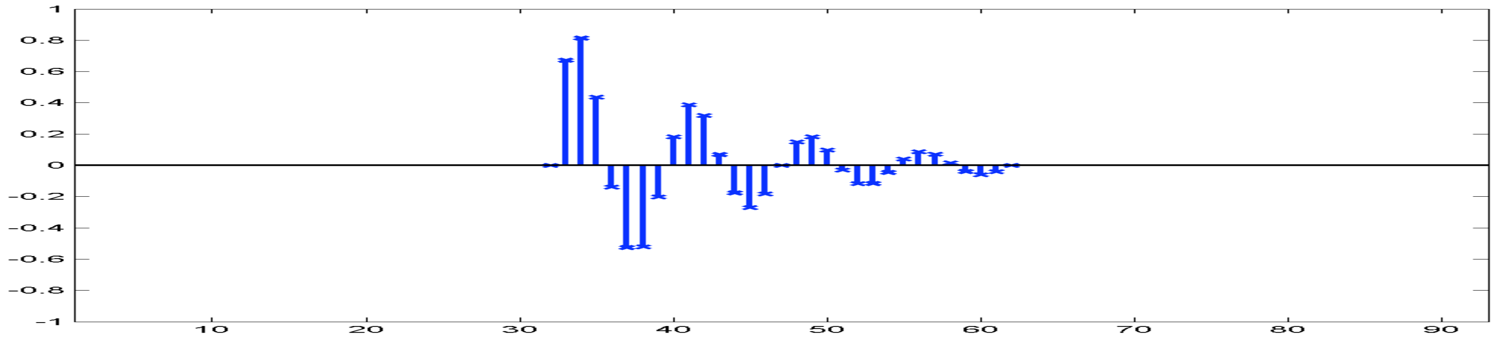
- If you extend the DFT-based representation beyond 0 (on the left) or L (on the right) it repeats the signal!
- So what does the DFT really mean

What does the DFT represent

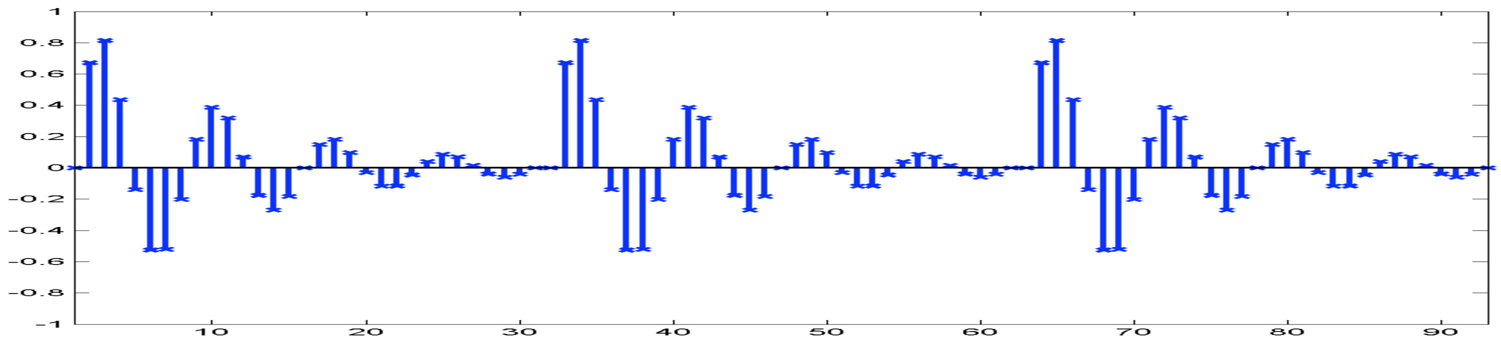


- **The DFT represents the properties of the infinitely long repeating signal that you can generate with it**
  - Of which the observed signal is ONE period
- This gives rise to some odd effects

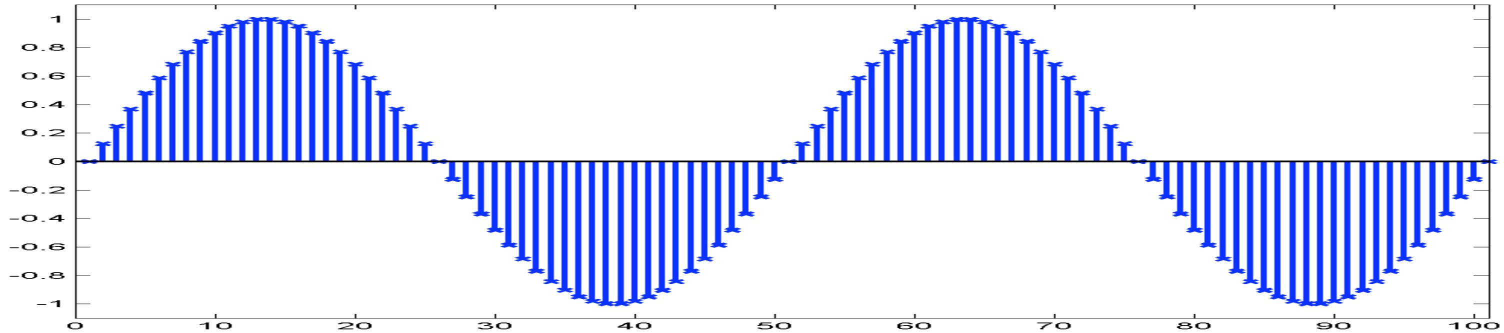
The discrete Fourier transform



- The discrete Fourier transform of the above signal actually computes the properties of the periodic signal shown below
  - Which extends from –infinity to +infinity
  - The period of this signal is 32 samples in this example

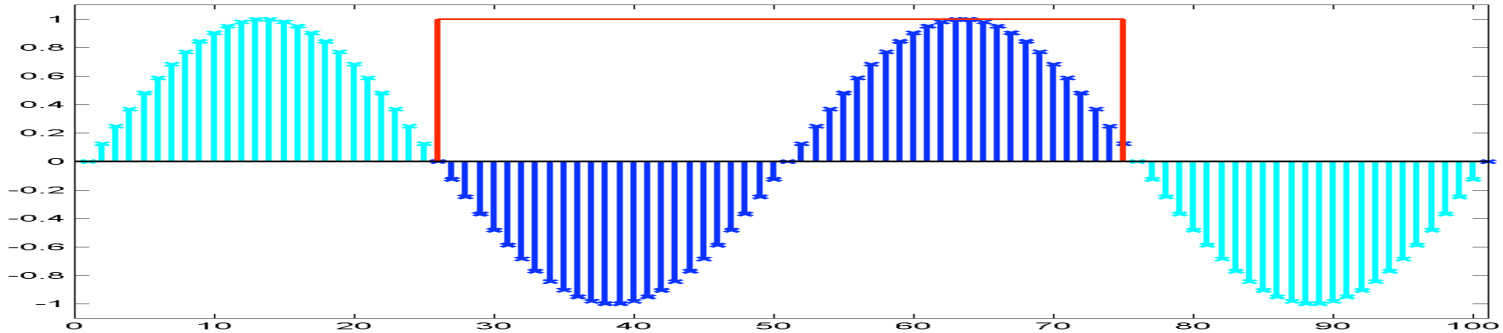


Windowing



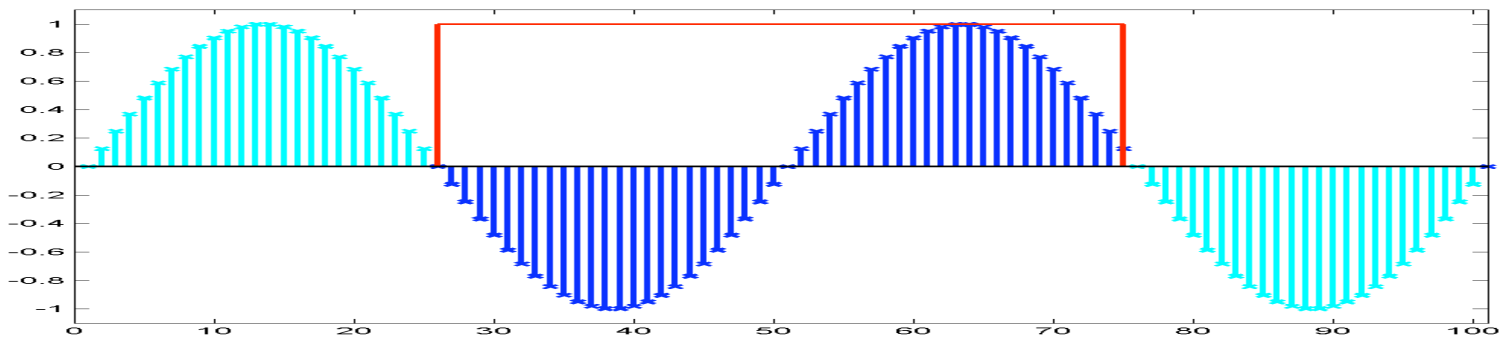
- The DFT of one period of the sinusoid shown in the figure computes the spectrum of the entire sinusoid from –infinity to +infinity

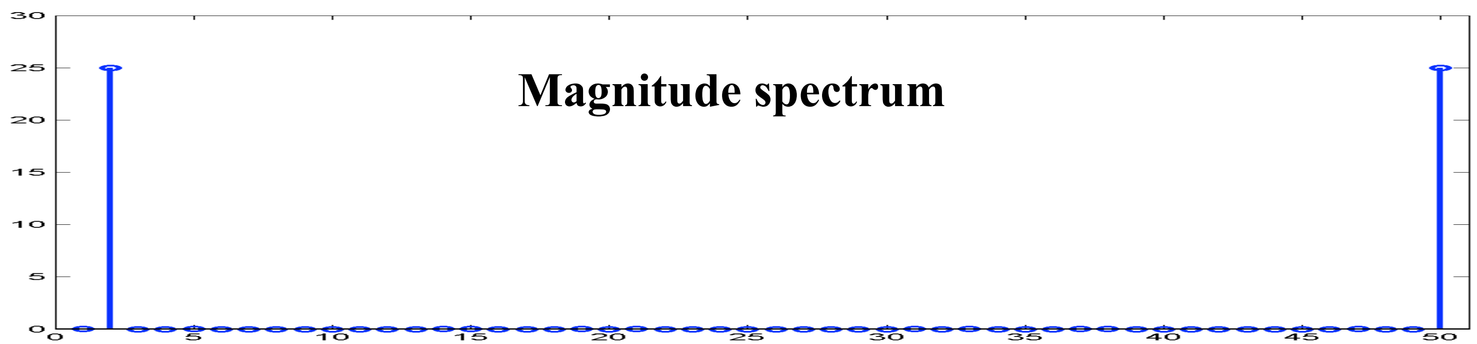
Windowing



- The DFT of one period of the sinusoid shown in the figure computes the spectrum of the entire sinusoid from –infinity to +infinity

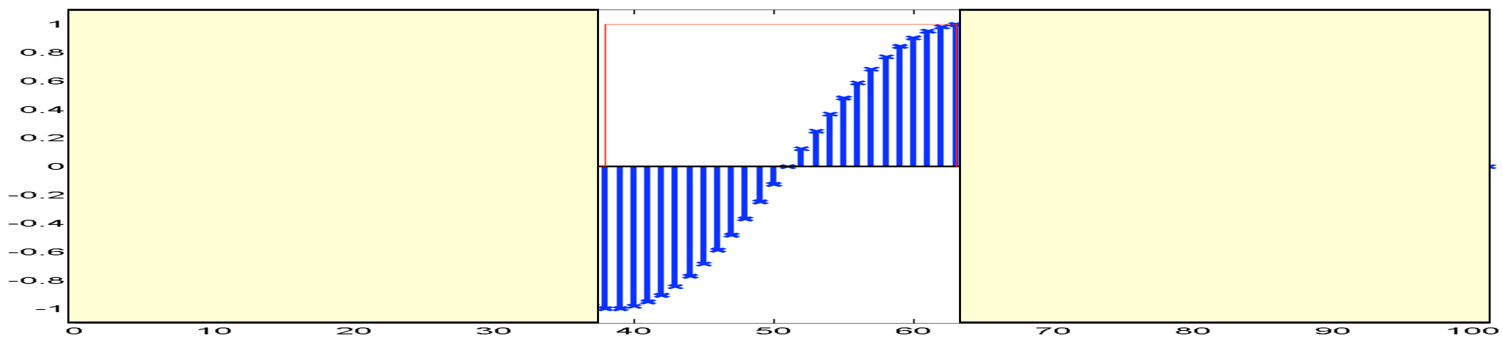
Windowing





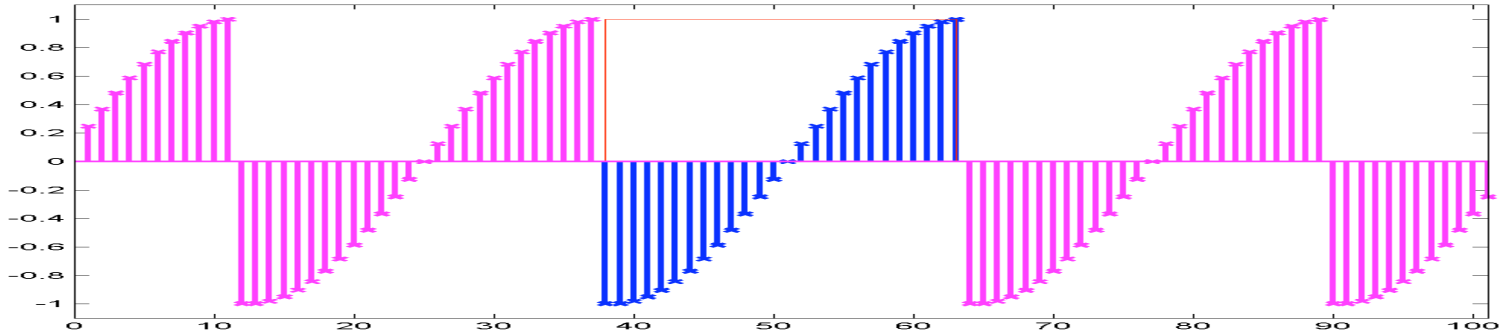
- The DFT of one period of the sinusoid shown in the figure computes the spectrum of the entire sinusoid from –infinity to +infinity
- The DFT of a real sinusoid has only one non zero frequency
  - The second peak in the figure is the "reflection" around L/2 (for real signals)

Windowing



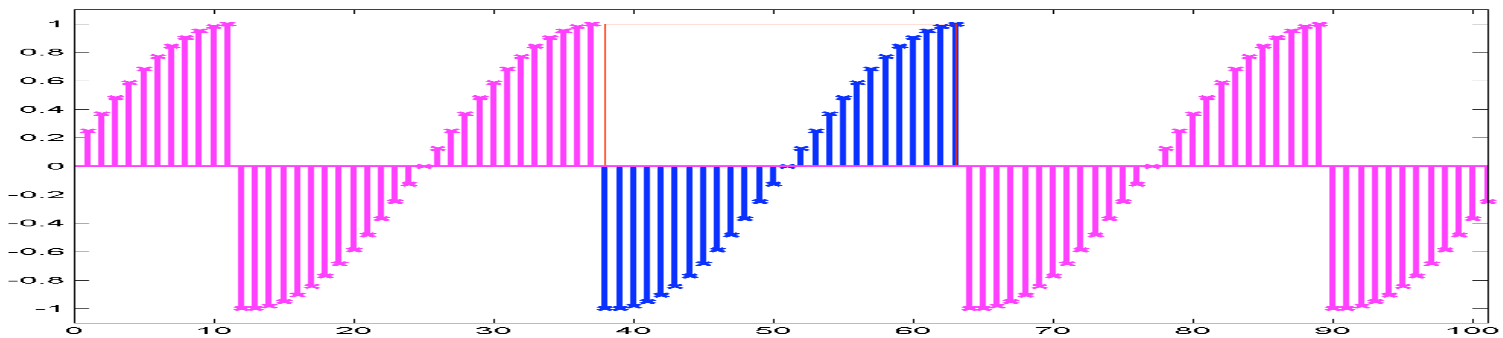
- The DFT of *any* sequence computes the spectrum for an infinite repetition of that sequence

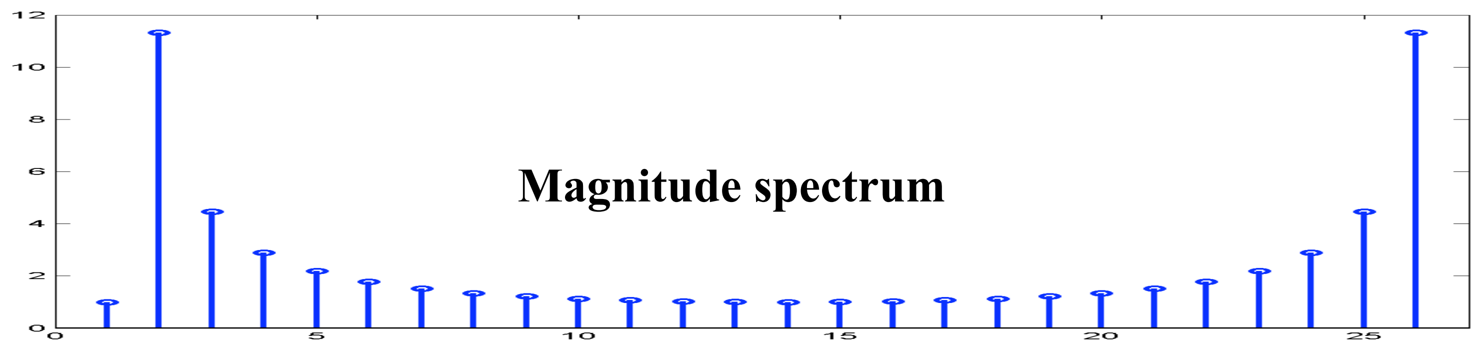
Windowing



- The DFT of *any* sequence computes the spectrum for an infinite repetition of that sequence
- The DFT of a partial segment of a sinusoid computes the spectrum of an infinite repetition of that segment, and not of the entire sinusoid

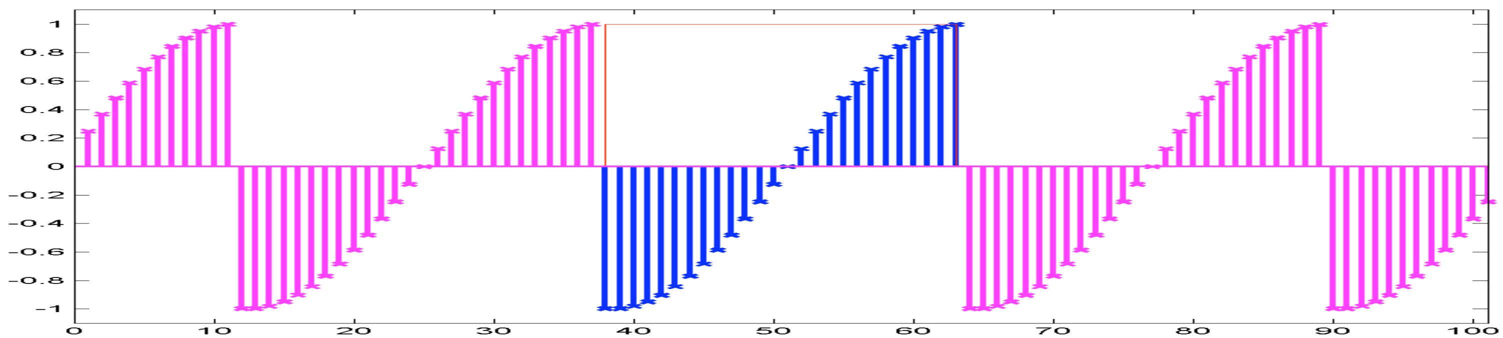
Windowing

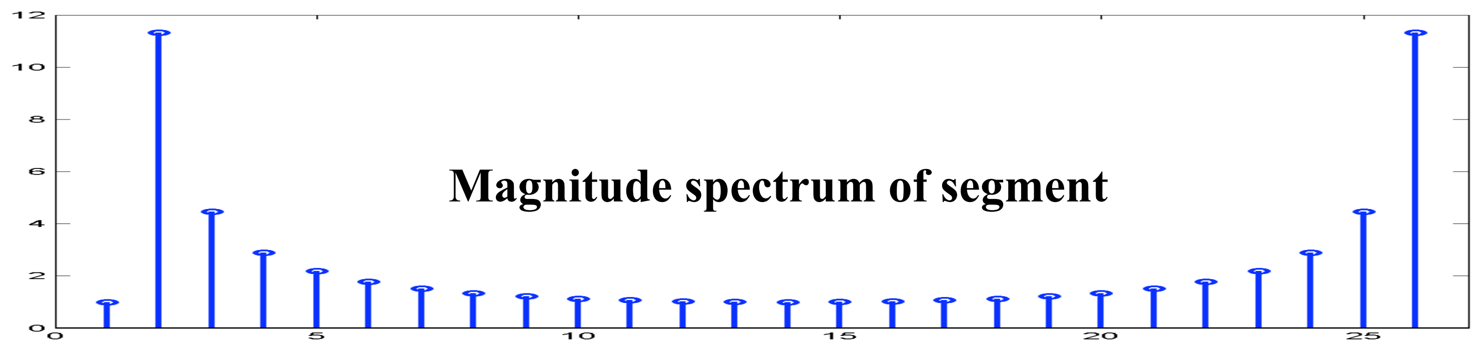


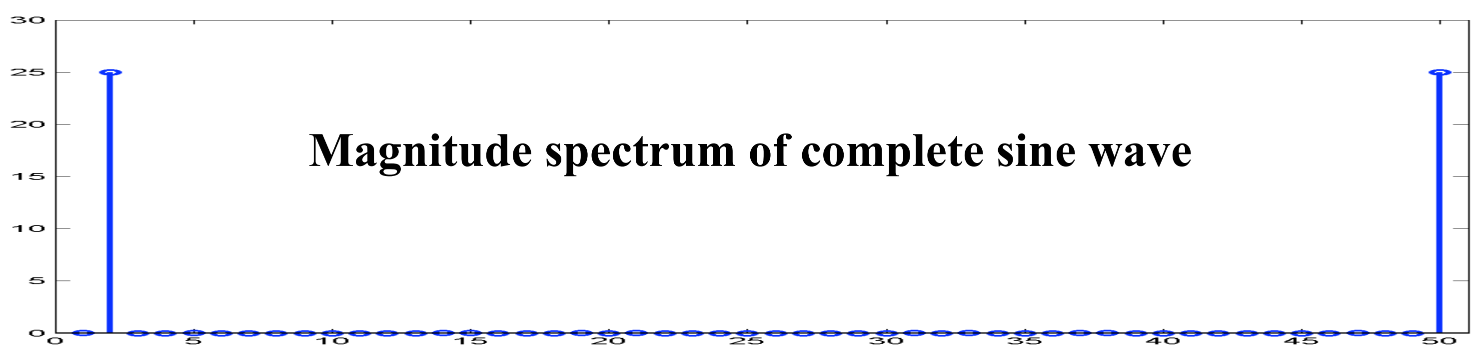


- The DFT of *any* sequence computes the spectrum for an infinite repetition of that sequence
- The DFT of a partial segment of a sinusoid computes the spectrum of an infinite repetition of that segment, and not of the entire sinusoid
- This will not give us the DFT of the sinusoid itself!

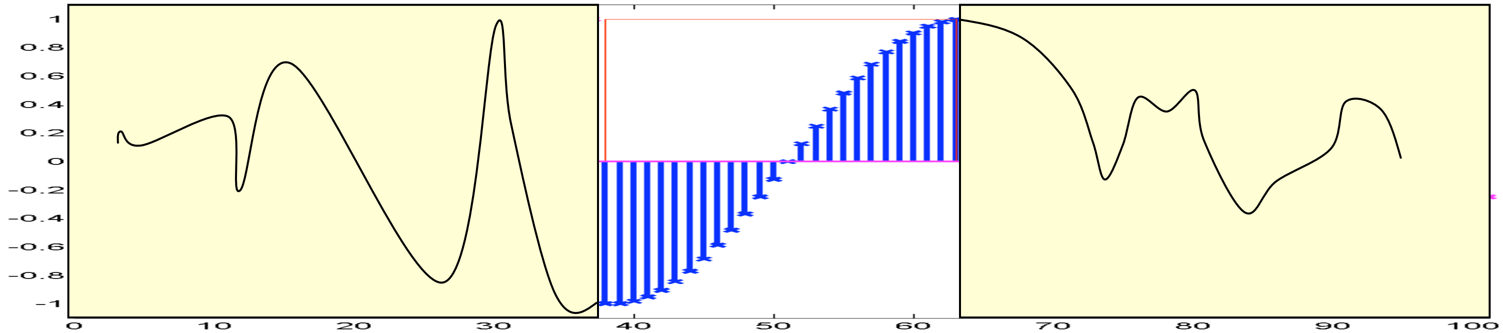
Windowing




Magnitude spectrum of segment

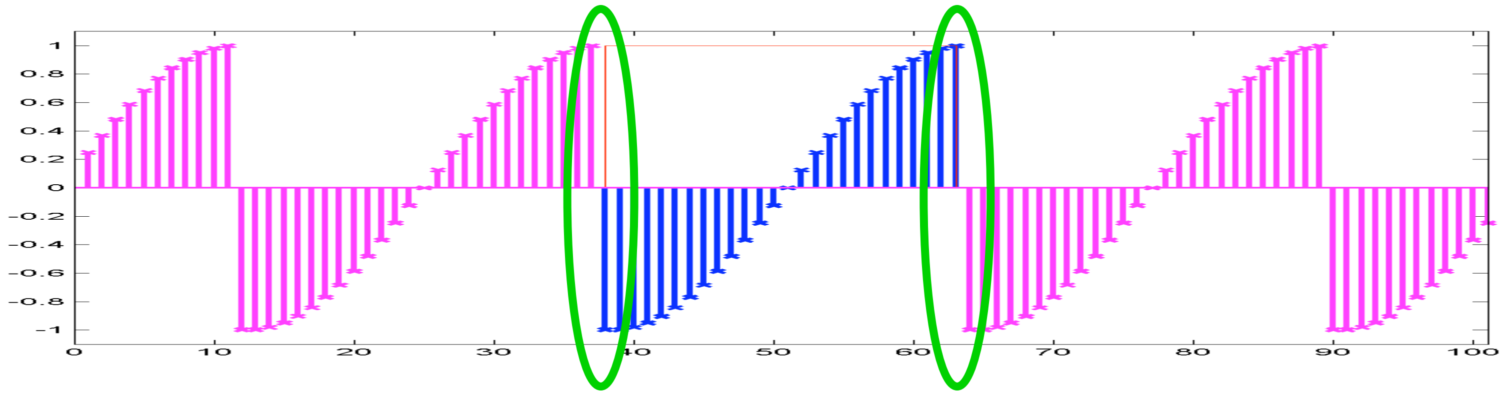

Magnitude spectrum of complete sine wave

Windowing



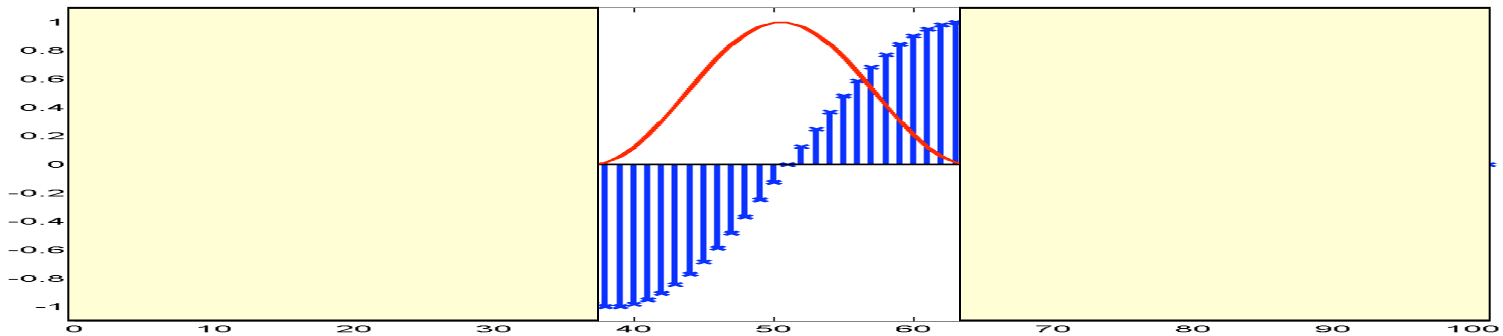
- The difference occurs due to two reasons:
- The transform cannot know what the signal actually looks like outside the observed window

Windowing



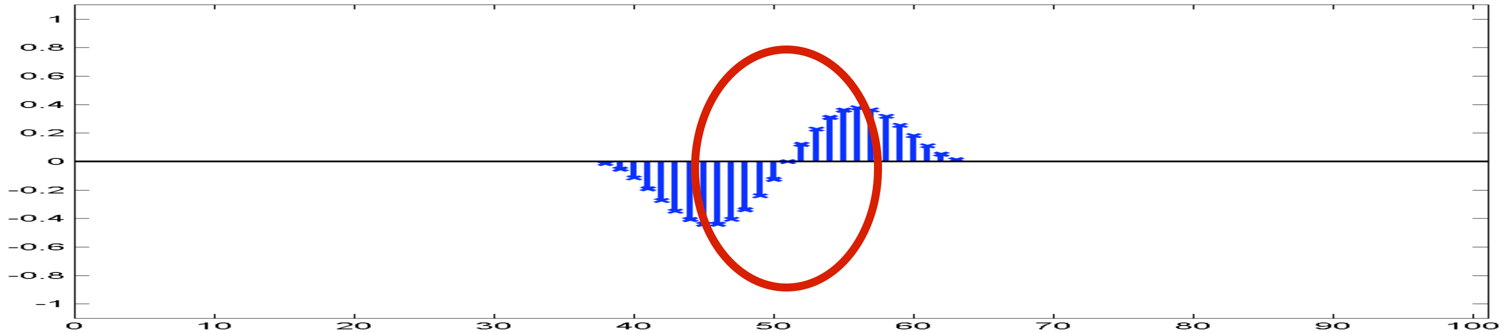
- The difference occurs due to two reasons:
- The transform cannot know what the signal actually looks like outside the observed window
- The implicit repetition of the observed signal introduces large discontinuities at the points of repetition
  - These are not part of the underlying signal
    - We only want to characterize the underlying signal
      - The discontinuity is an irrelevant detail

Windowing



- While we can never know what the signal looks like outside the window, we can try to minimize the discontinuities at the boundaries
- We do this by multiplying the signal with a *window* function
  - We call this procedure windowing
  - We refer to the resulting signal as a "windowed" signal

Windowing



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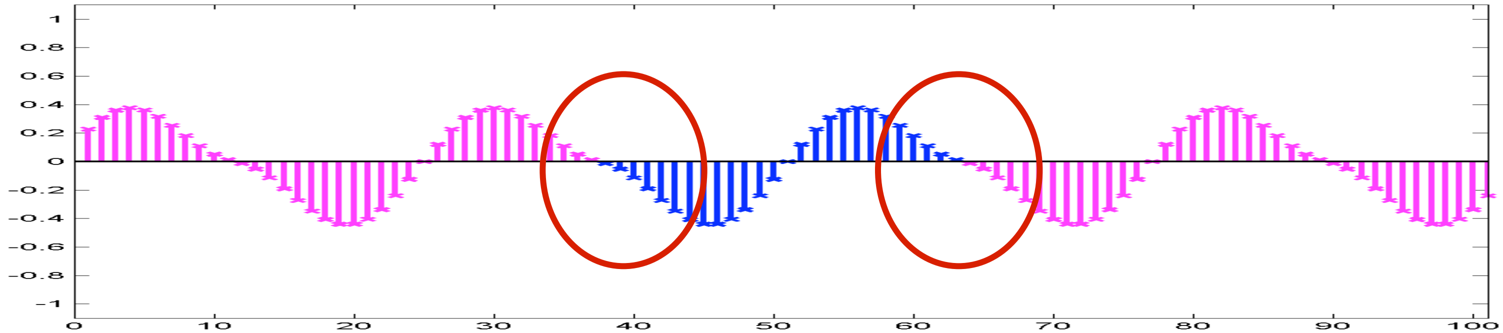
  - We refer to the resulting signal as a "windowed" signal
- Windowing attempts to do the following:
  - Keep the windowed signal similar to the original in the central regions

Windowing



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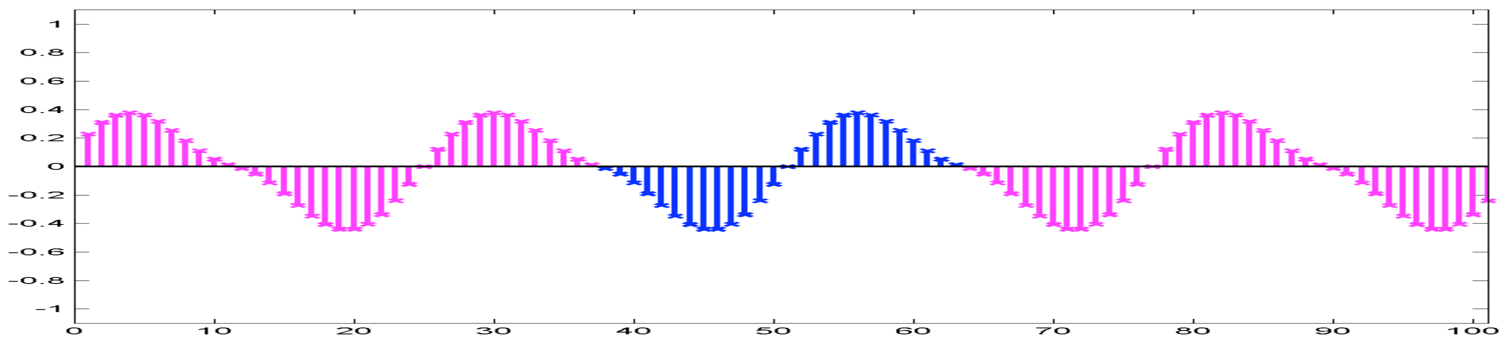
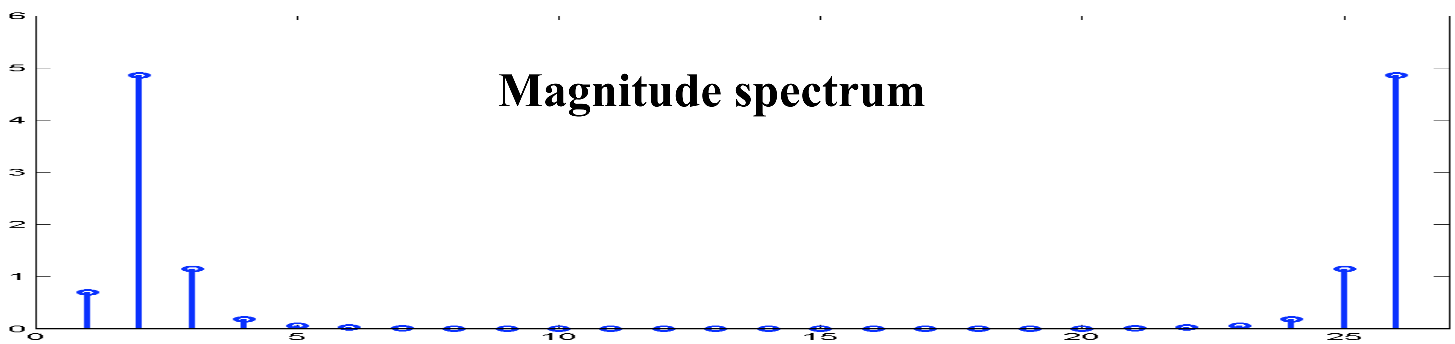
- We do this by multiplying the signal with a *window* function
  - We call this procedure windowing
  - We refer to the resulting signal as a "windowed" signal
- Windowing attempts to do the following:
  - Keep the windowed signal similar to the original in the central regions
  - Reduce or eliminate the discontinuities in the implicit periodic signal

Windowing

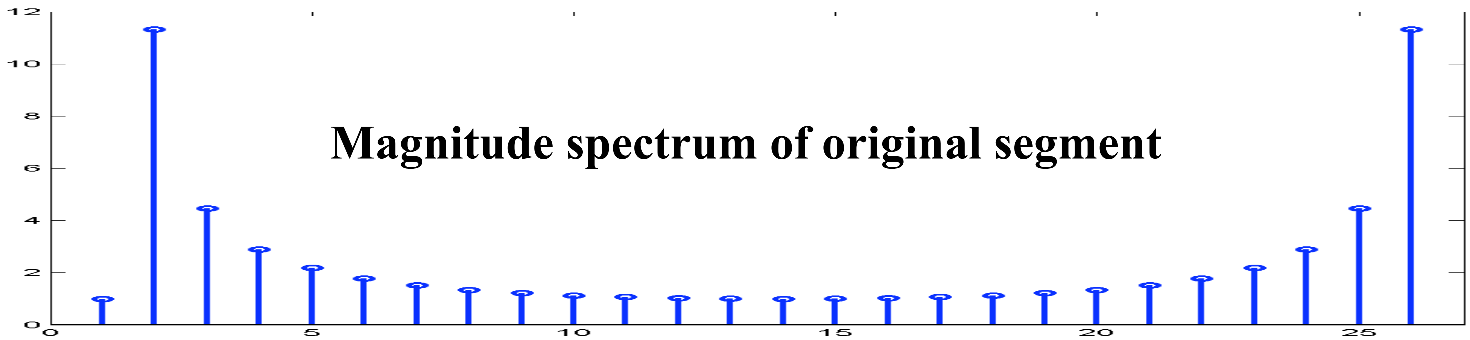


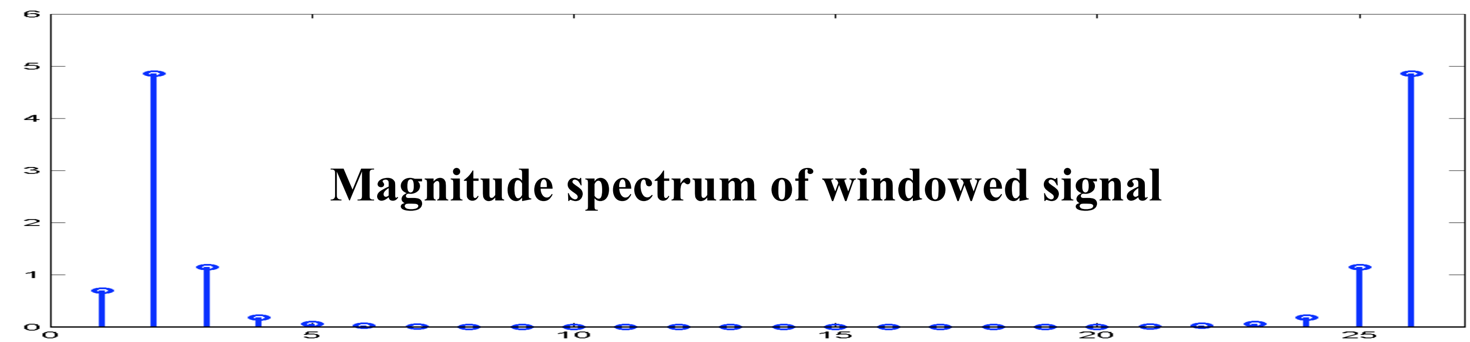
1
0.8
0.6
0.4
0.2
0
-0.2
-0.4
-0.6
-0.8
-1
0
10
20
30
40
50
60
70
80
90
100

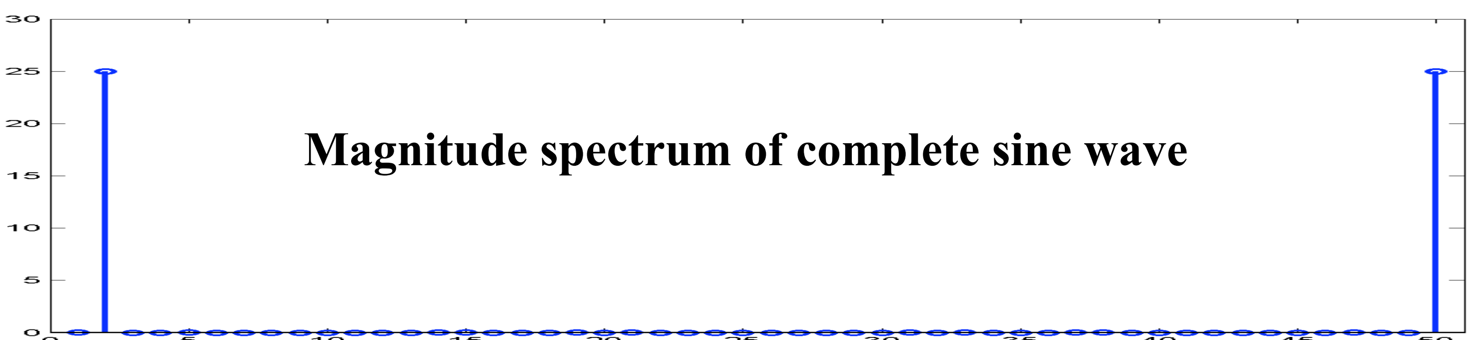


Magnitude spectrum
6
5
4
3
2
1
0
0
5
10
15
20
25

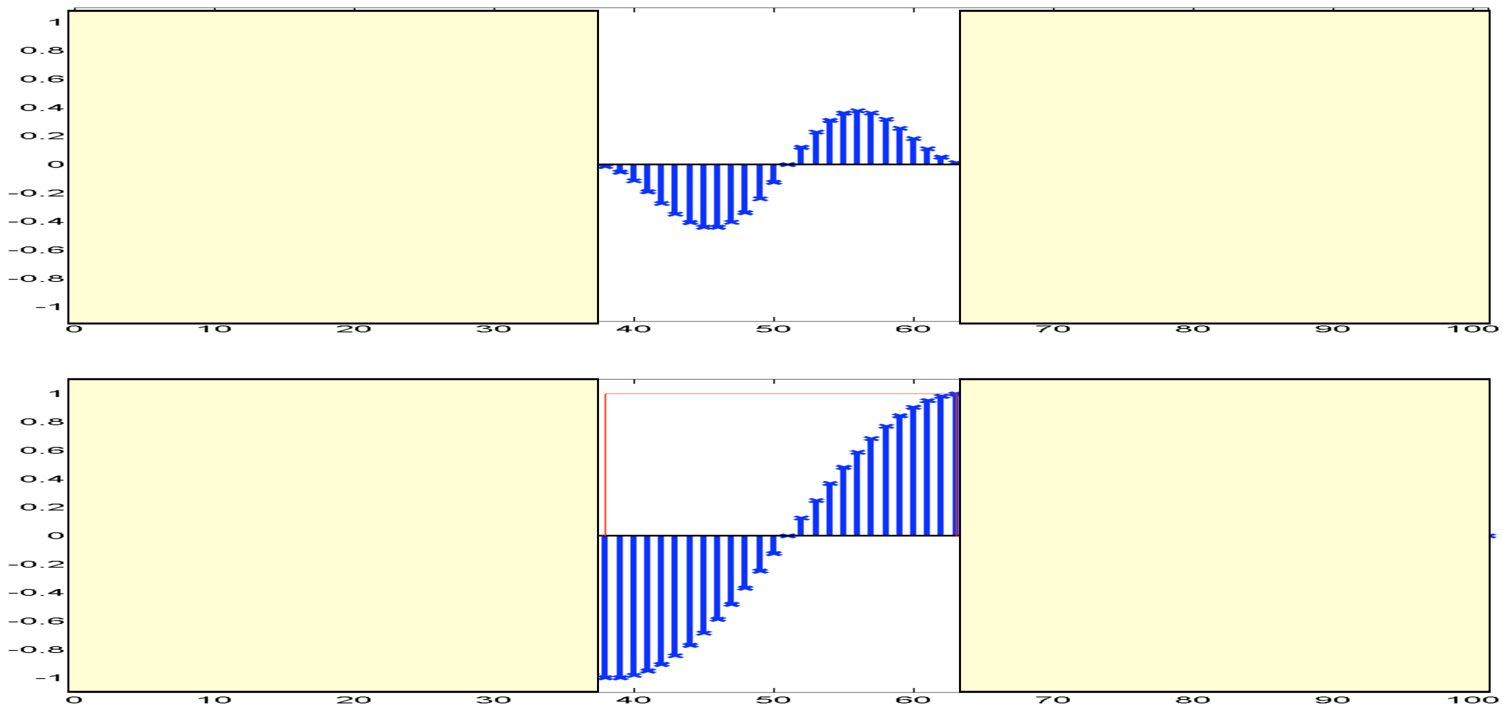
Windowing


Magnitude spectrum of original segment
0 2 4 6 8 10 12
0 5 10 15 20 25


Magnitude spectrum of windowed signal
0 1 2 3 4 5 6
0 5 10 15 20 25

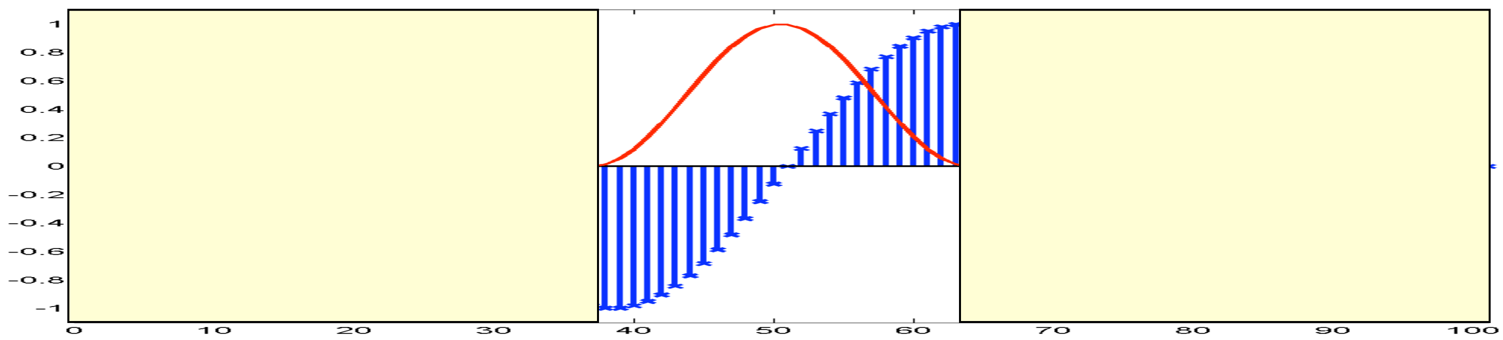

Magnitude spectrum of complete sine wave
0 5 10 15 20 25 30
0 5 10 15 20 25 30 35 40 45 50

Windowing



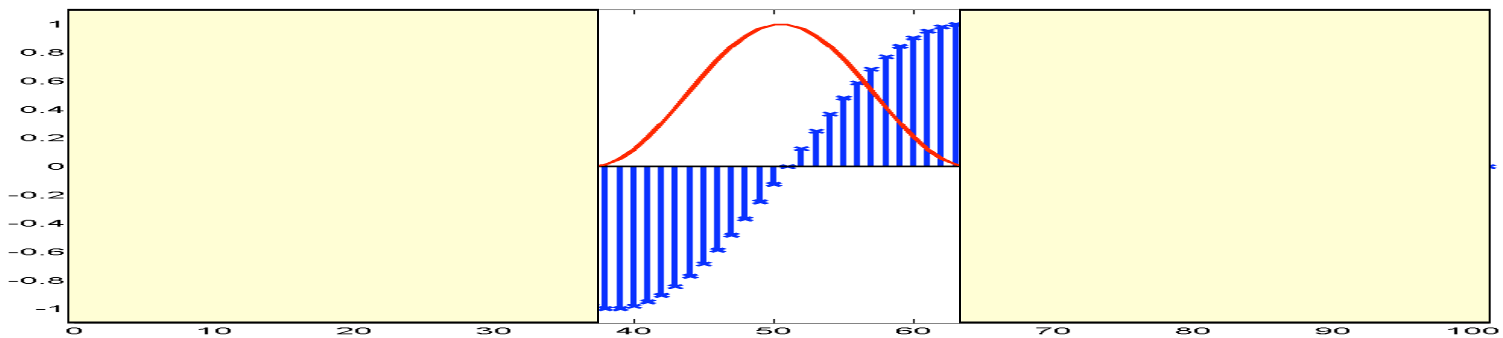
- Windowing is not a perfect solution
  - The original (unwindowed) segment is identical to the original (complete) signal within the segment
  - The windowed segment is often not identical to the complete signal anywhere
- Several windowing functions have been proposed that strike different tradeoffs between the fidelity in the central regions and the smoothing at the boundaries

Windowing

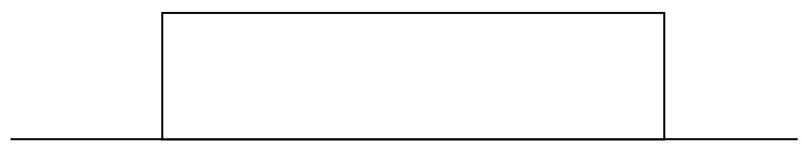


- Cosine windows:
  - Window length is M
  - Index begins at 0
- Hamming: $w[n] = 0.54 – 0.46 \cos(2\pi n/M)$
- Hanning: $w[n] = 0.5 – 0.5 \cos(2\pi n/M)$
- Blackman: $0.42 – 0.5 \cos(2\pi n/M) + 0.08 \cos(4\pi n/M)$

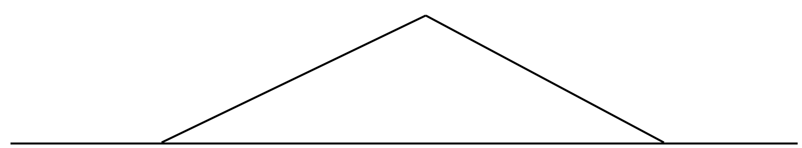
Windowing



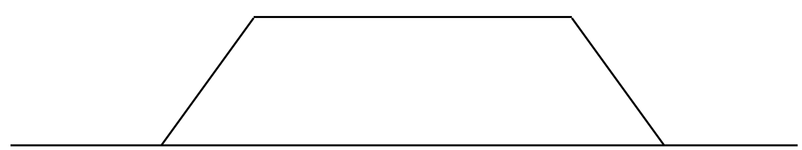
- Geometric windows:
  - Rectangular (boxcar):



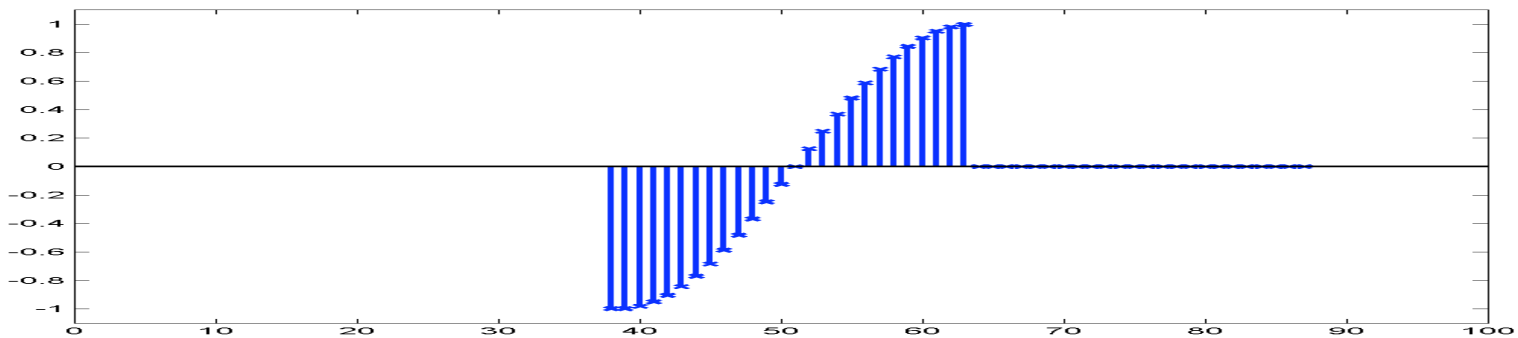
  - Triangular (Bartlett):



  - Trapezoid:

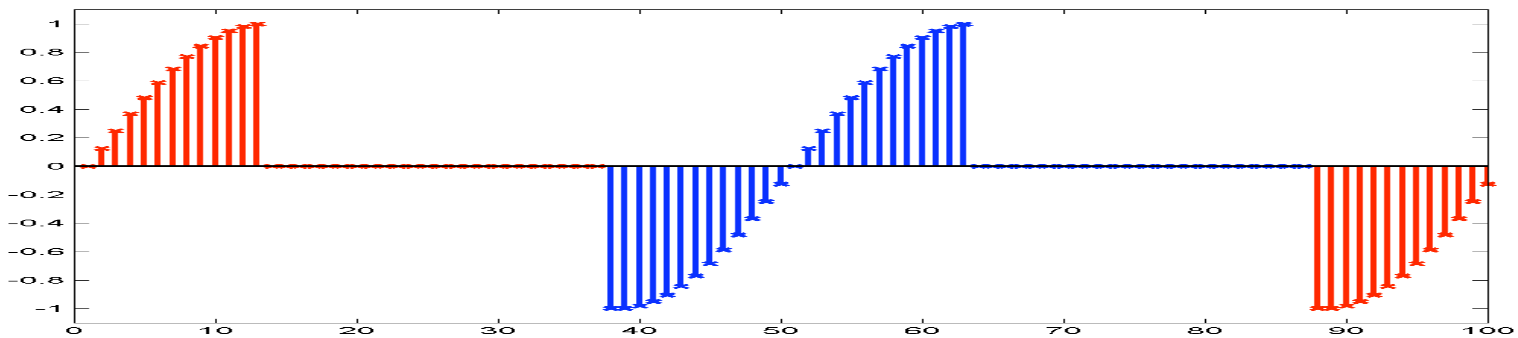


Zero Padding



- We can pad zeros to the end of a signal to make it a desired length
  - Useful if the FFT (or any other algorithm we use) requires signals of a specified length
  - E.g. Radix 2 FFTs require signals of length 2^n i.e., some power of 2. We must zero pad the signal to increase its length to the appropriate number

Zero Padding



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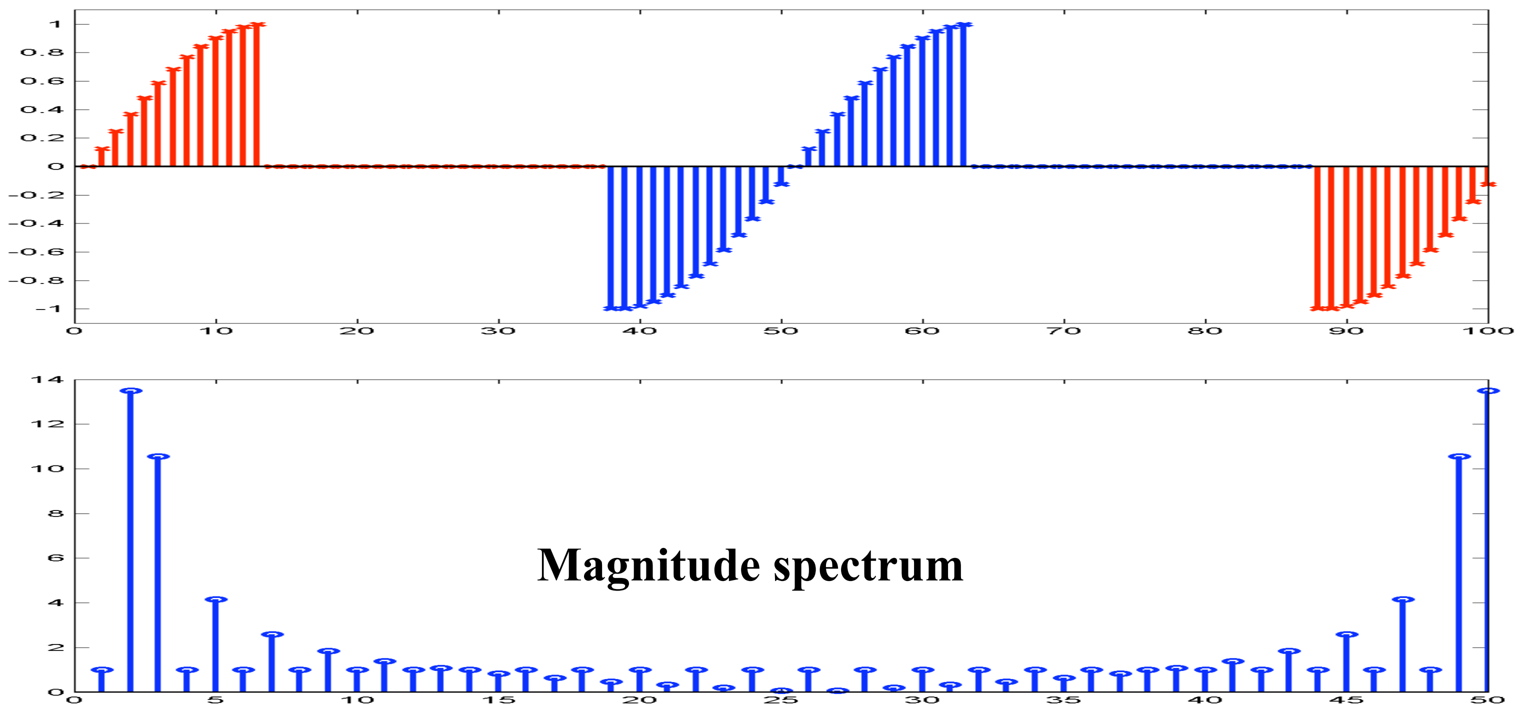
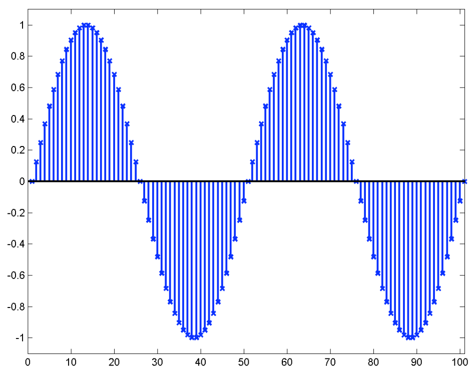
- The consequence of zero padding is to change the periodic signal whose Fourier spectrum is being computed by the DFT

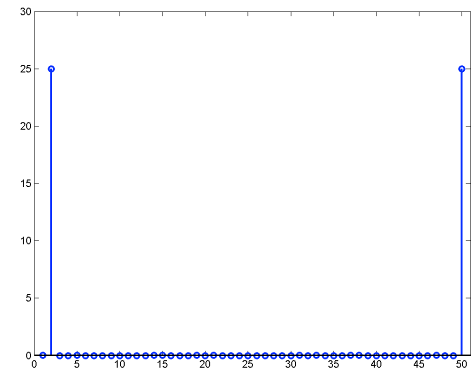
Zero Padding

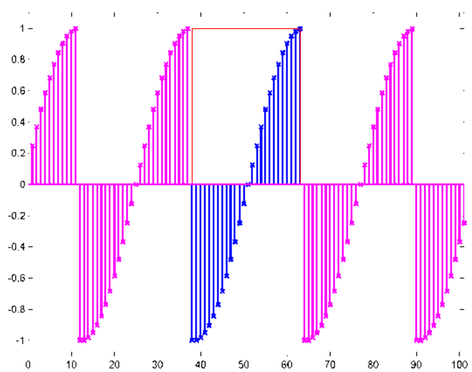


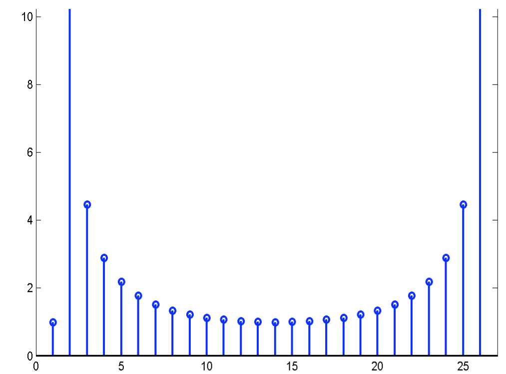
- The DFT of the zero padded signal is essentially the same as the DFT of the unpadded signal, with additional spectral samples inserted in between
  - It does not contain any additional information over the original DFT
  - It also does not contain less information

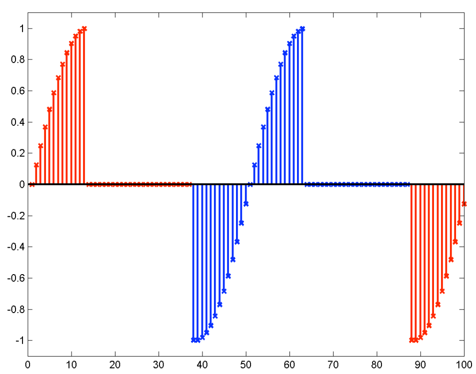
Magnitude spectra

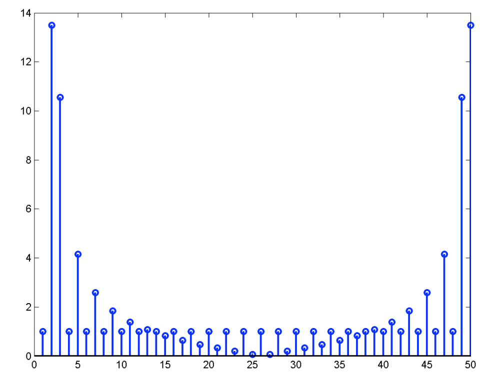




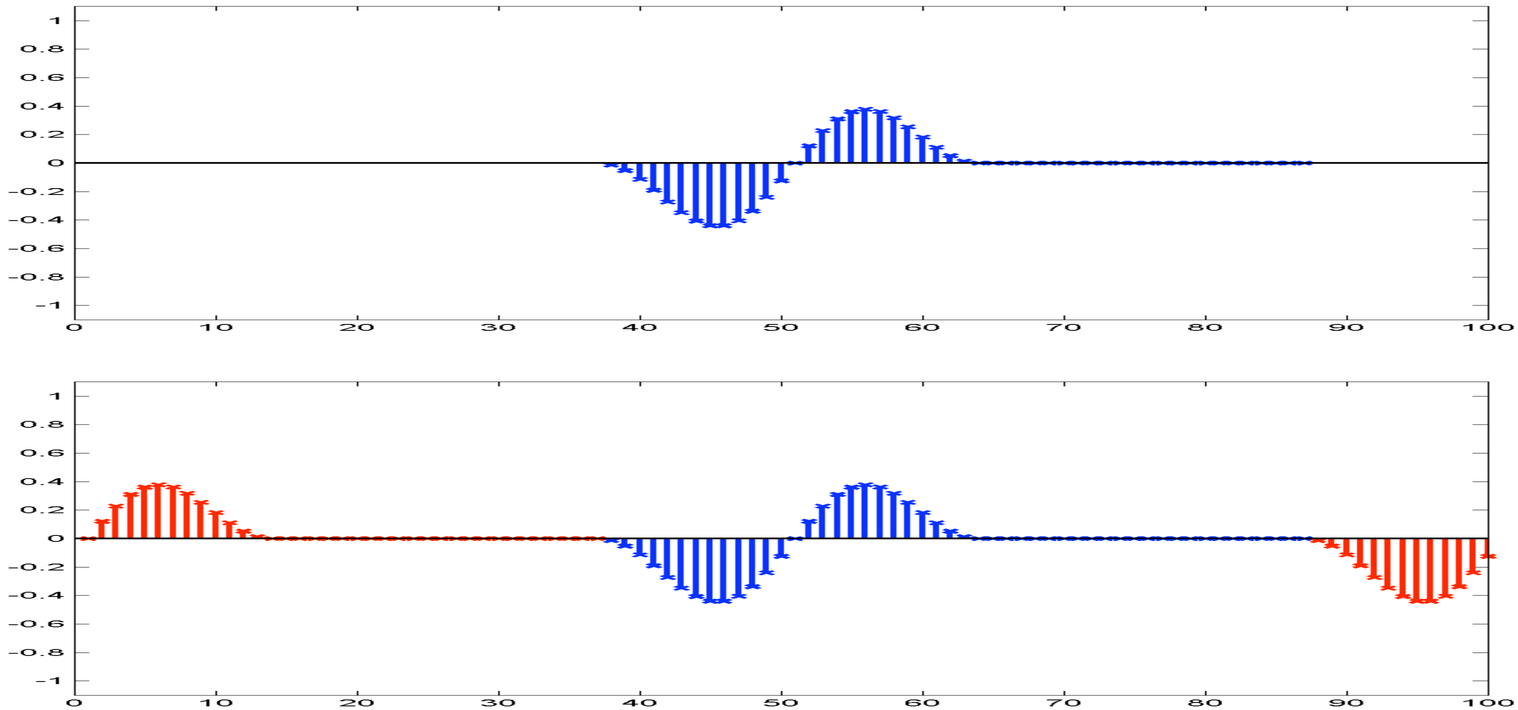






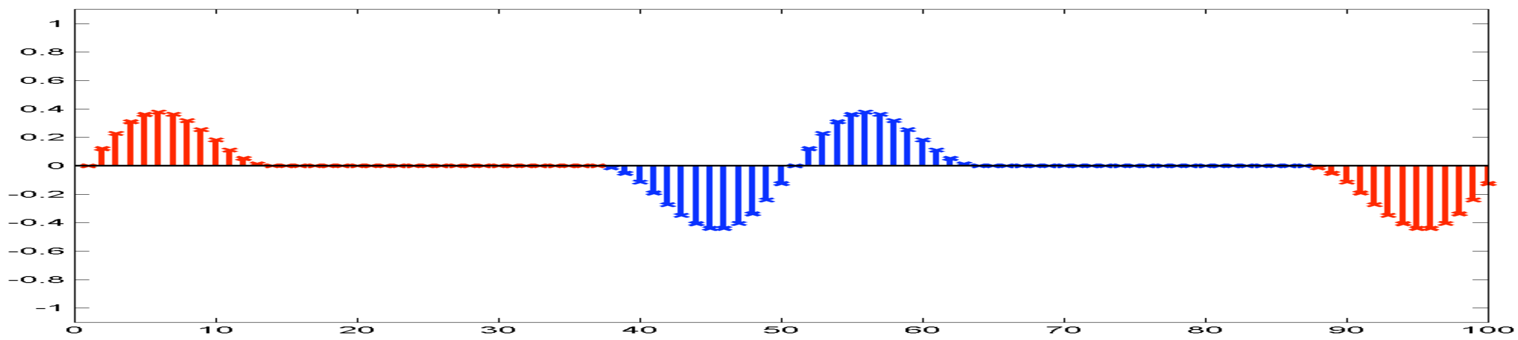


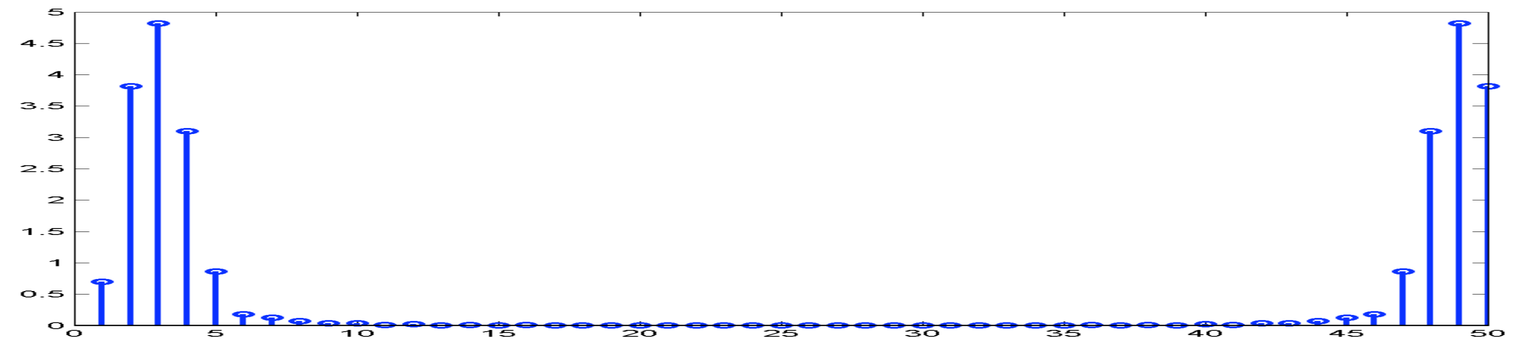
Zero Padding



- Zero padding windowed signals results in signals that appear to be less discontinuous at the edges
  - This is only illusory
  - Again, we do not introduce any new information into the signal by merely padding it with zeros

Zero Padding





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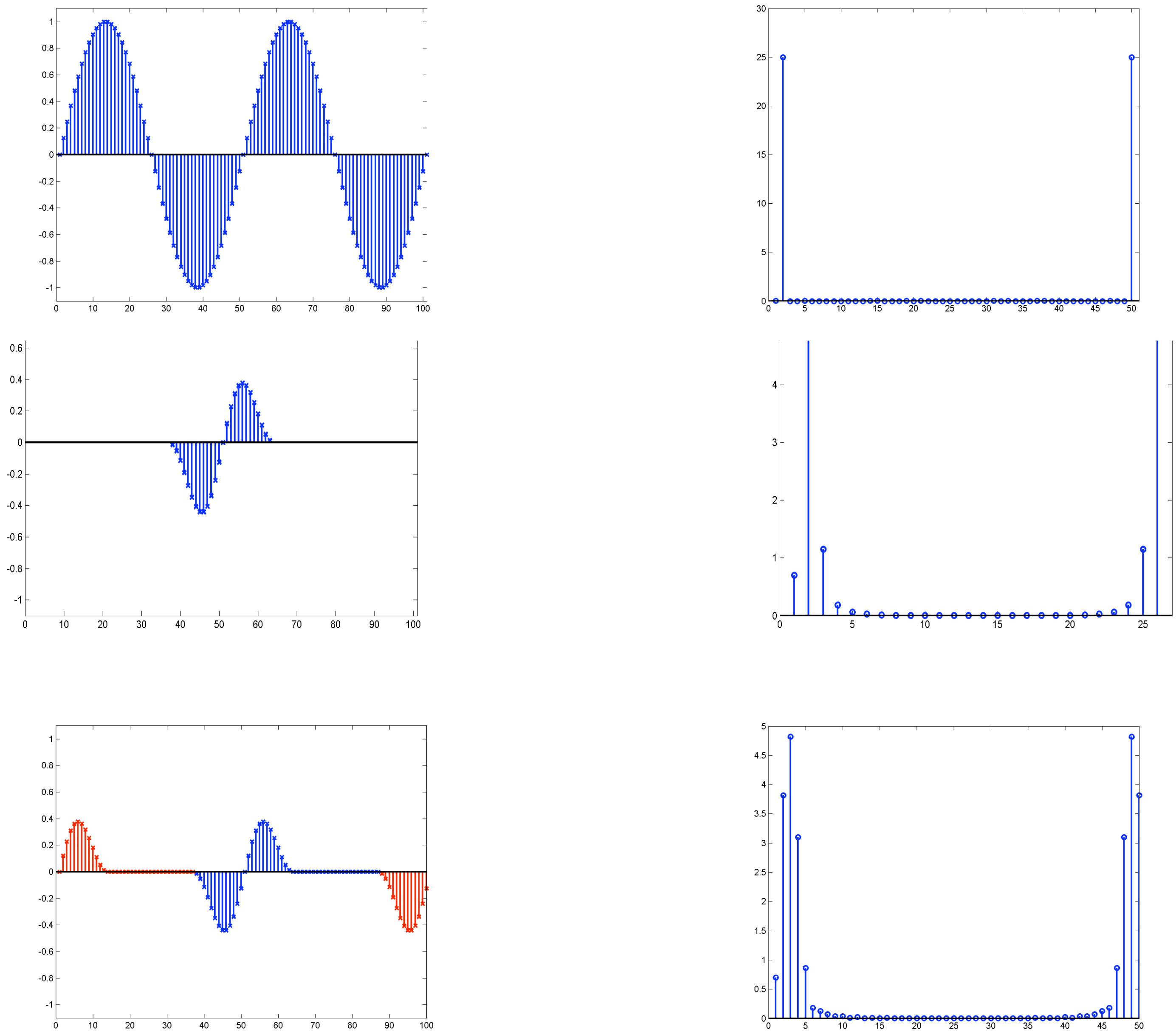
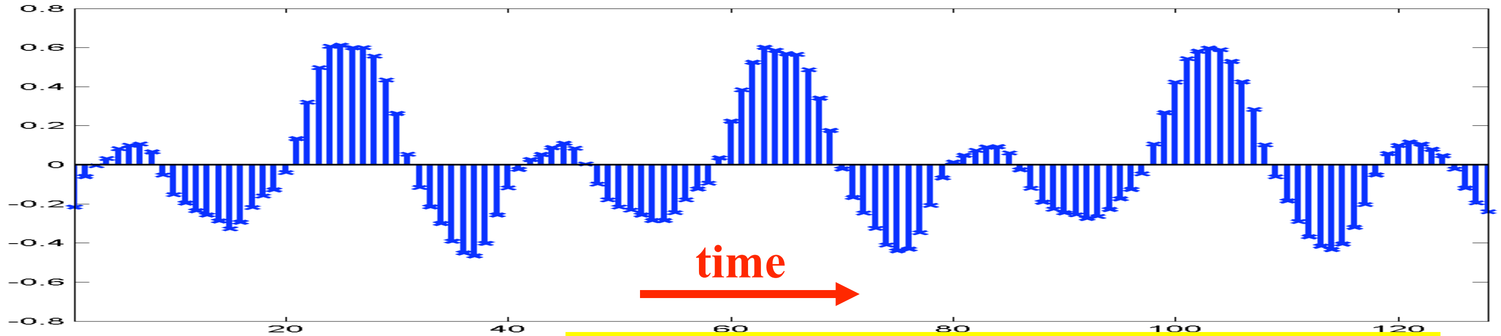
Magnitude spectra

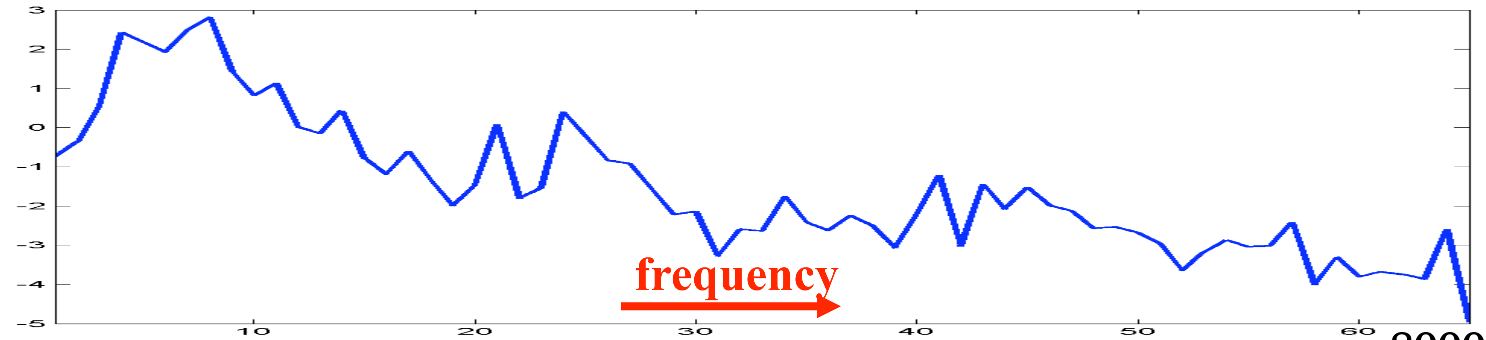


Zero padding a speech signal

128 samples from a speech signal sampled at 16000 Hz

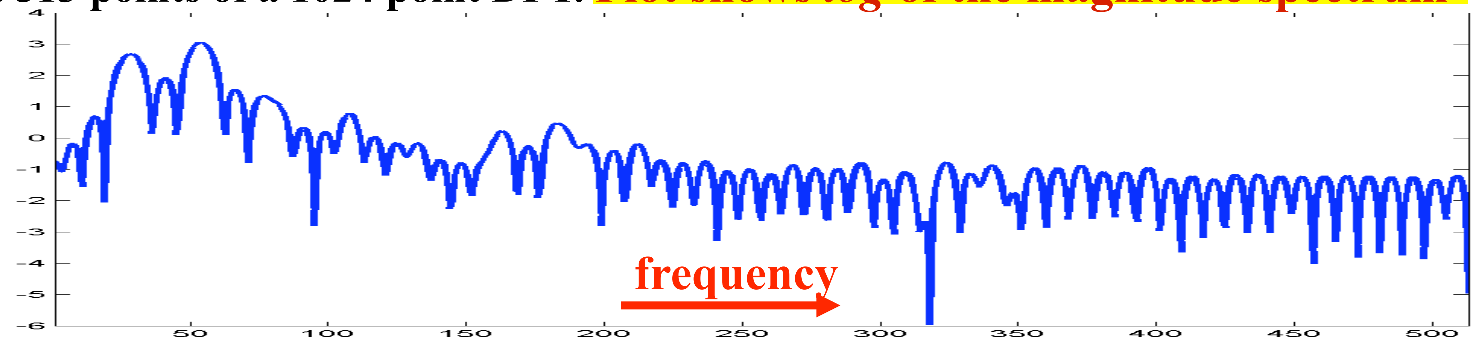


The first 65 points of a 128 point DFT. **Plot shows *log* of the magnitude spectrum**



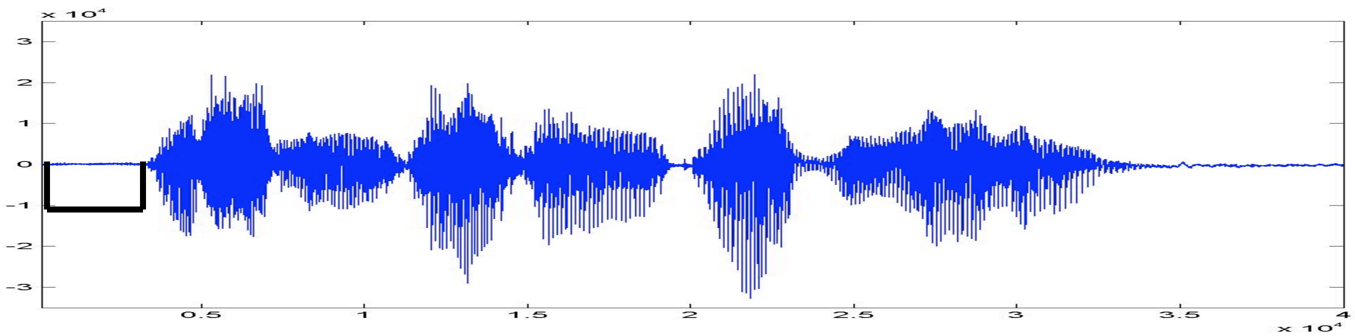
8000Hz

The first 513 points of a 1024 point DFT. **Plot shows *log* of the magnitude spectrum**



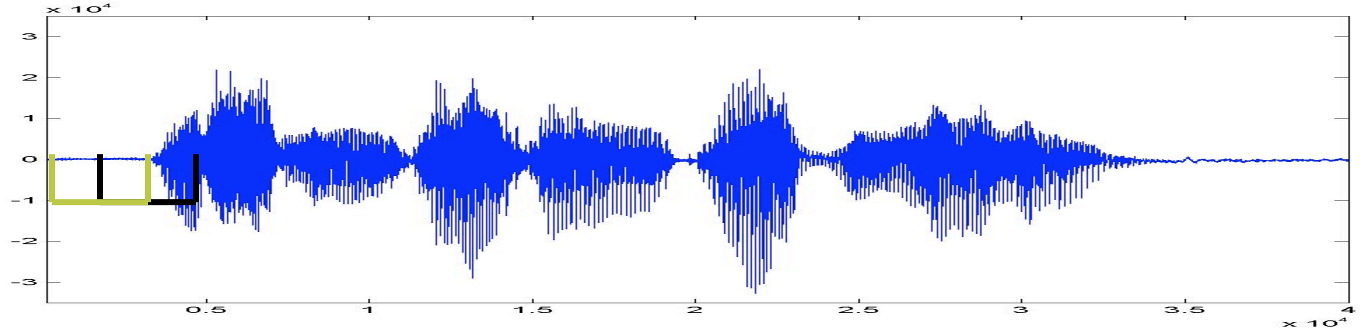
8000Hz

The process of parameterization



- The signal is processed in segments of 25-64 ms
  - Because the properties of audio signals change quickly
  - They are "stationary" only very briefly

The process of parameterization



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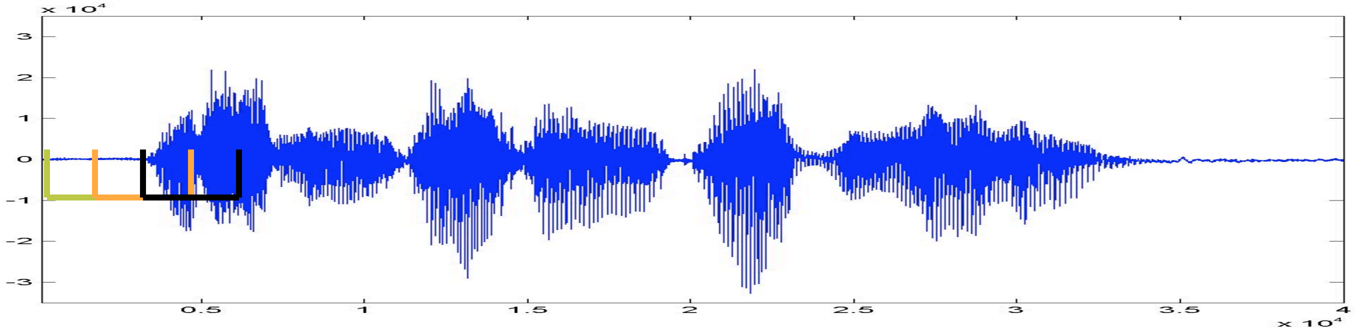
- Adjacent segments overlap by 15-48 ms

The process of parameterization



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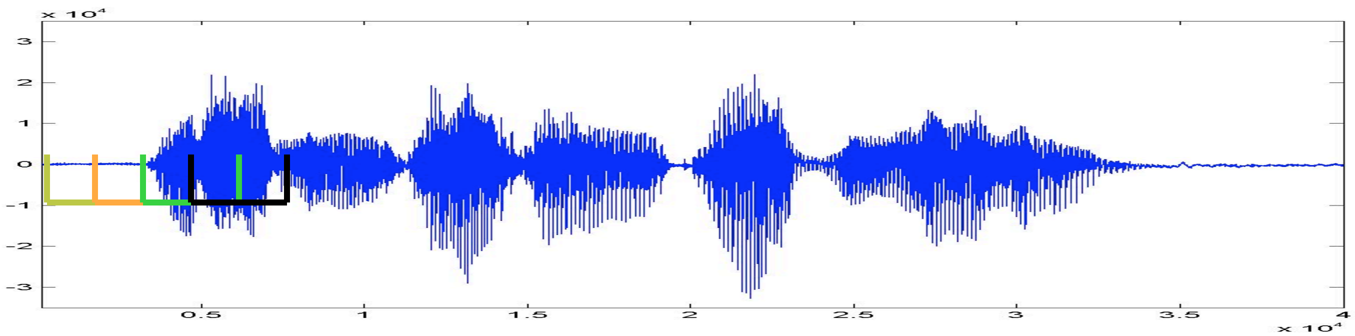

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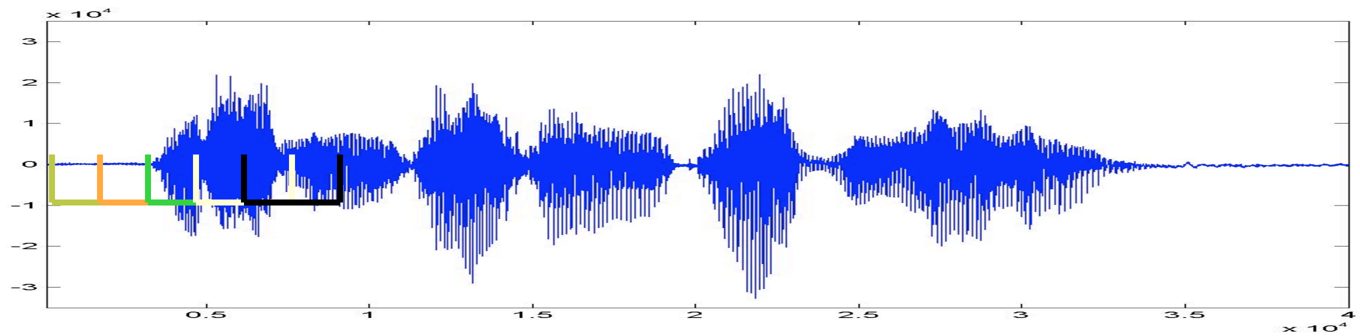

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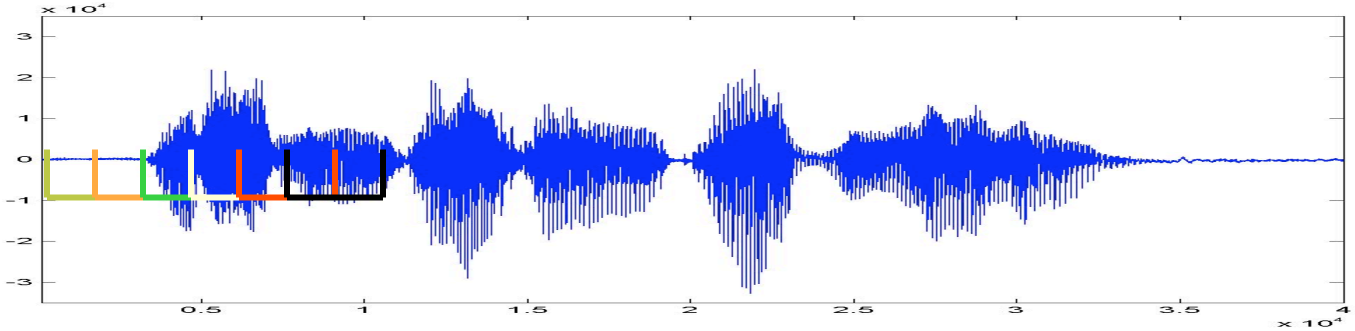

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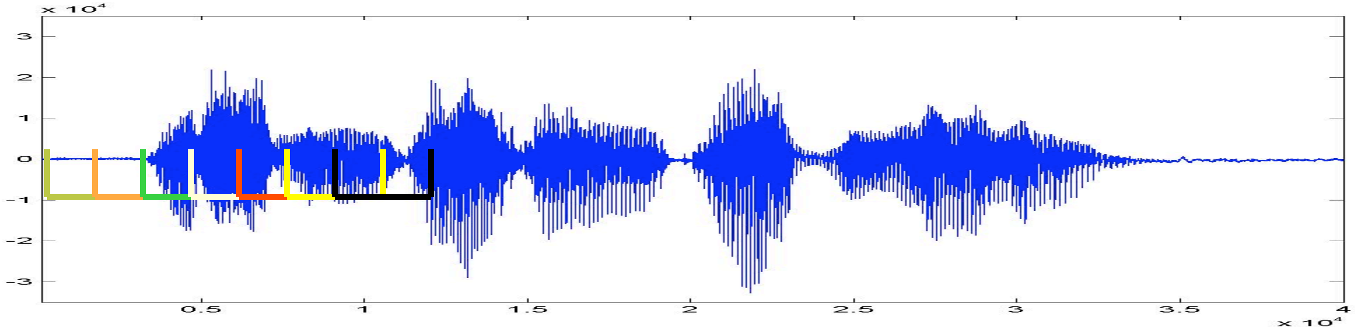

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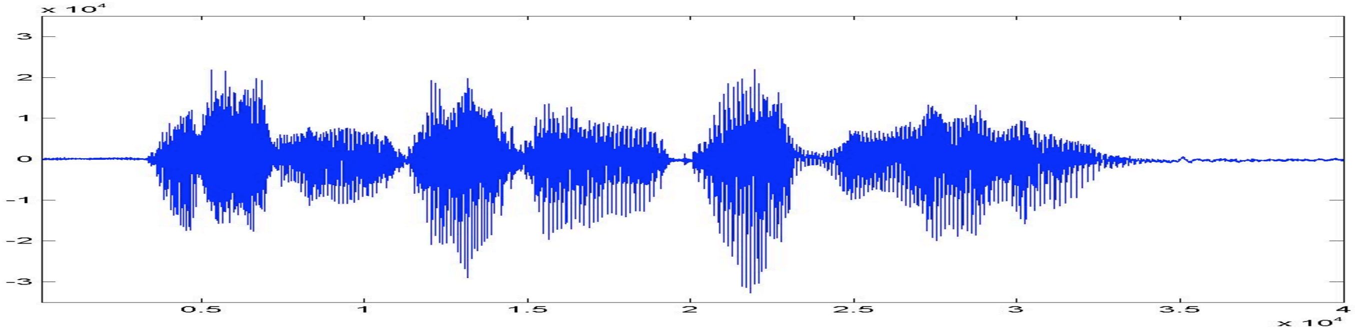
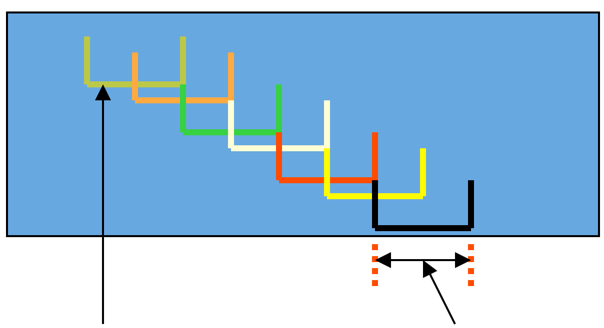


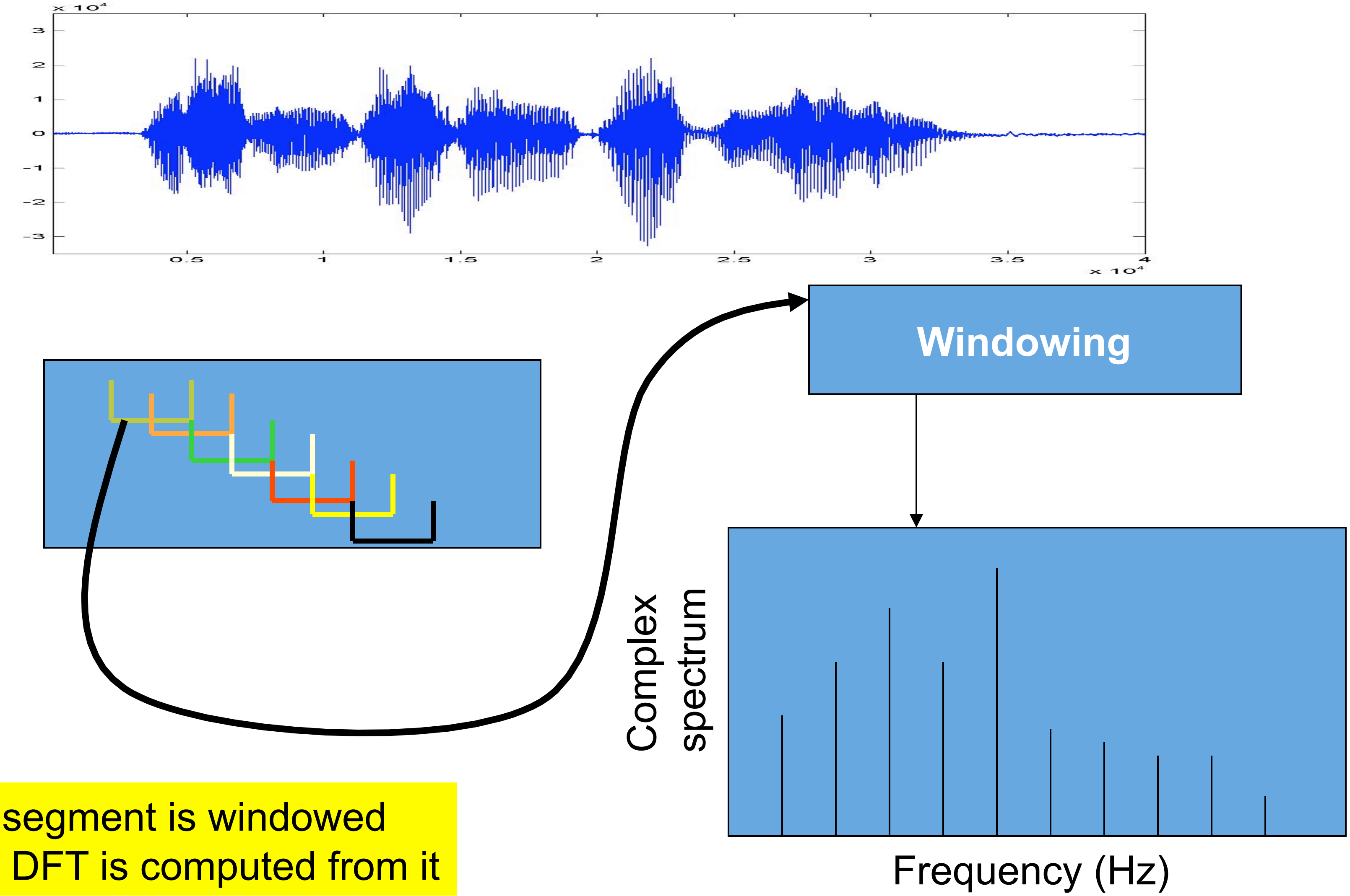


Segments shift every 10-16 milliseconds

Each segment is typically 25-64 milliseconds wide

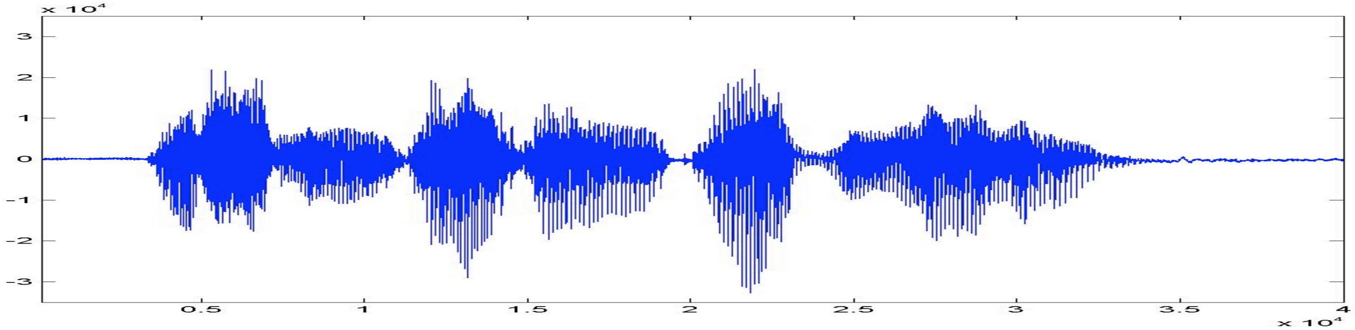
Audio signals typically do not change significantly within this short time interval

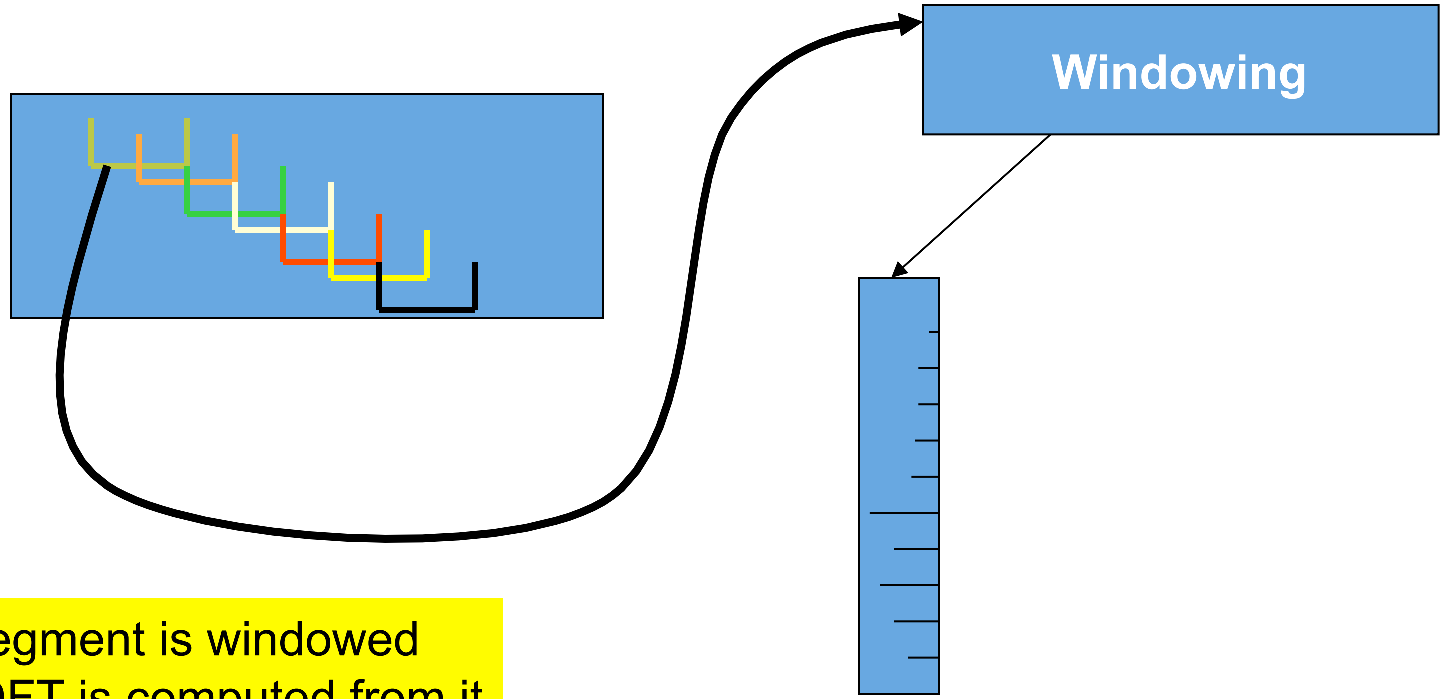
The process of parameterization



Each segment is windowed and a DFT is computed from it

The process of parameterization





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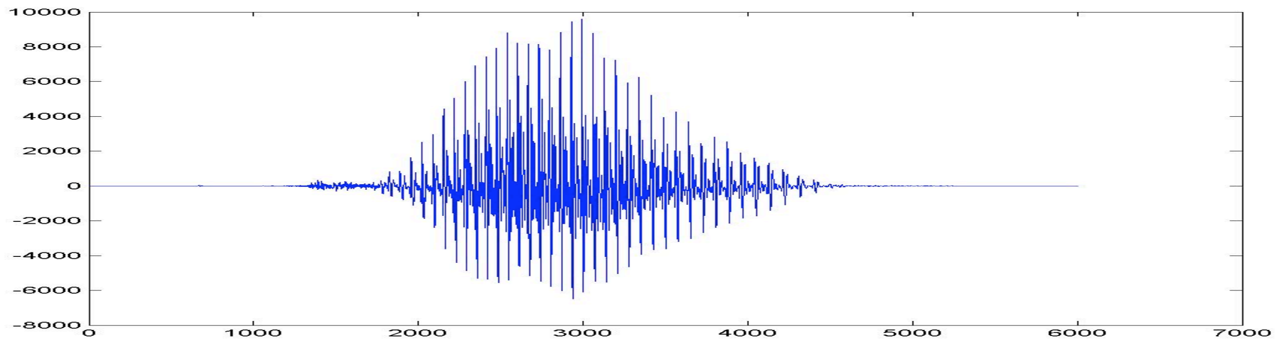
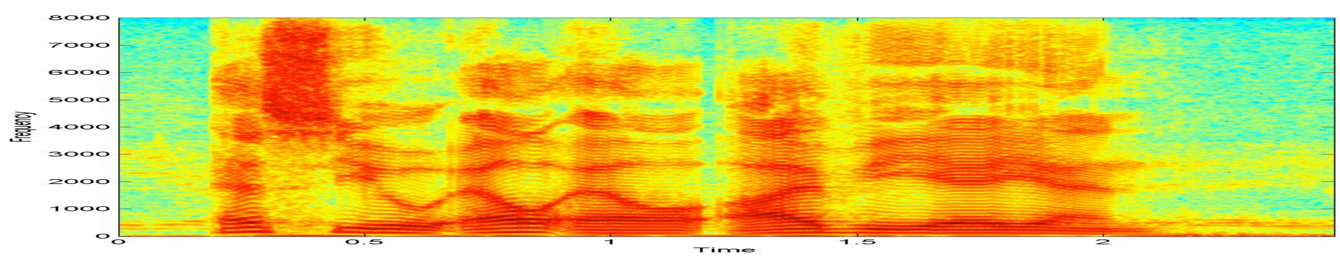
Computing a Spectrogram





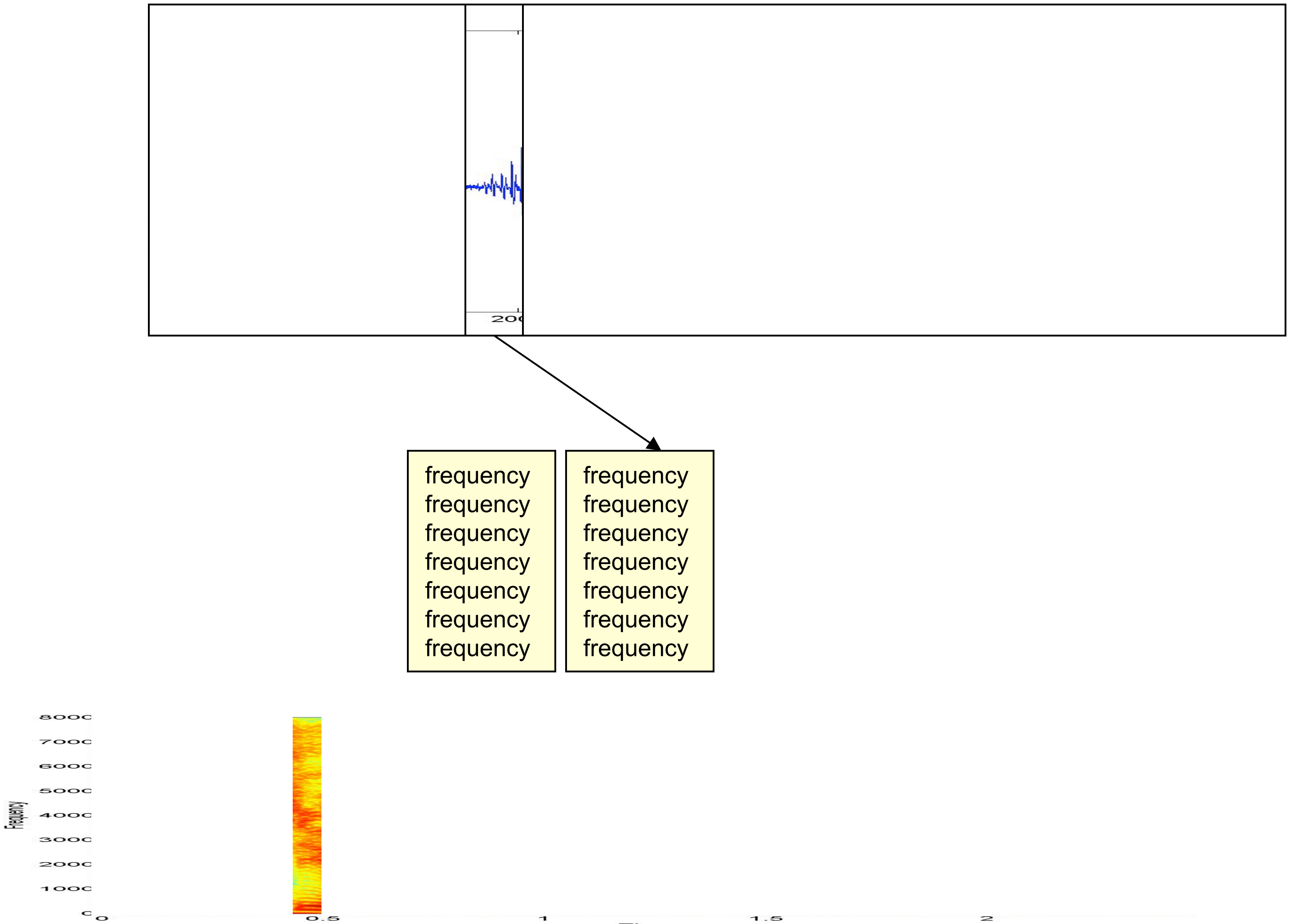
Compute Fourier Spectra of segments of audio and stack them side-by-side

Computing a Spectrogram

frequency
frequency
frequency
frequency
frequency
frequency
frequency

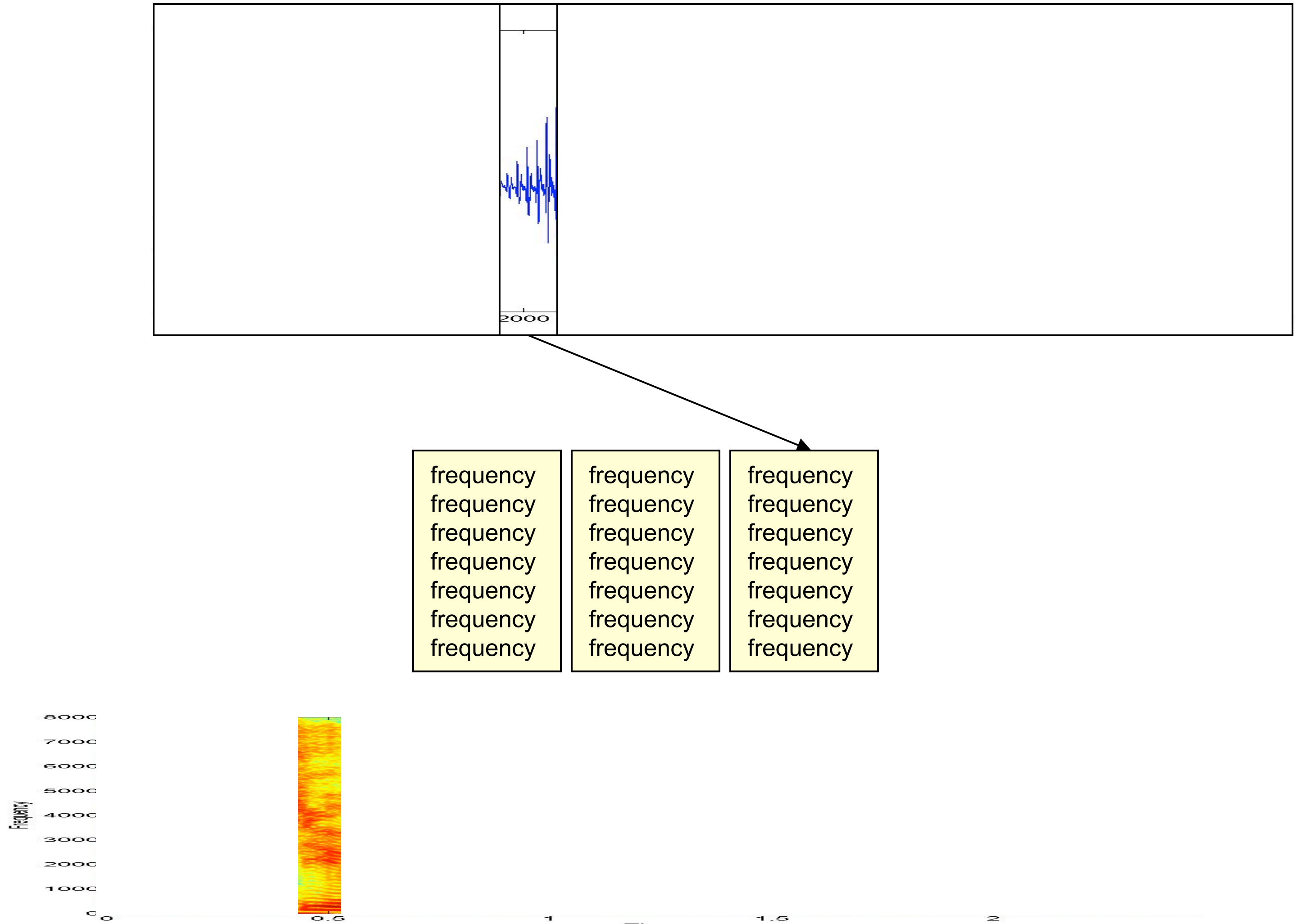
Compute Fourier Spectra of segments of audio and stack them side-by-side

Computing a Spectrogram



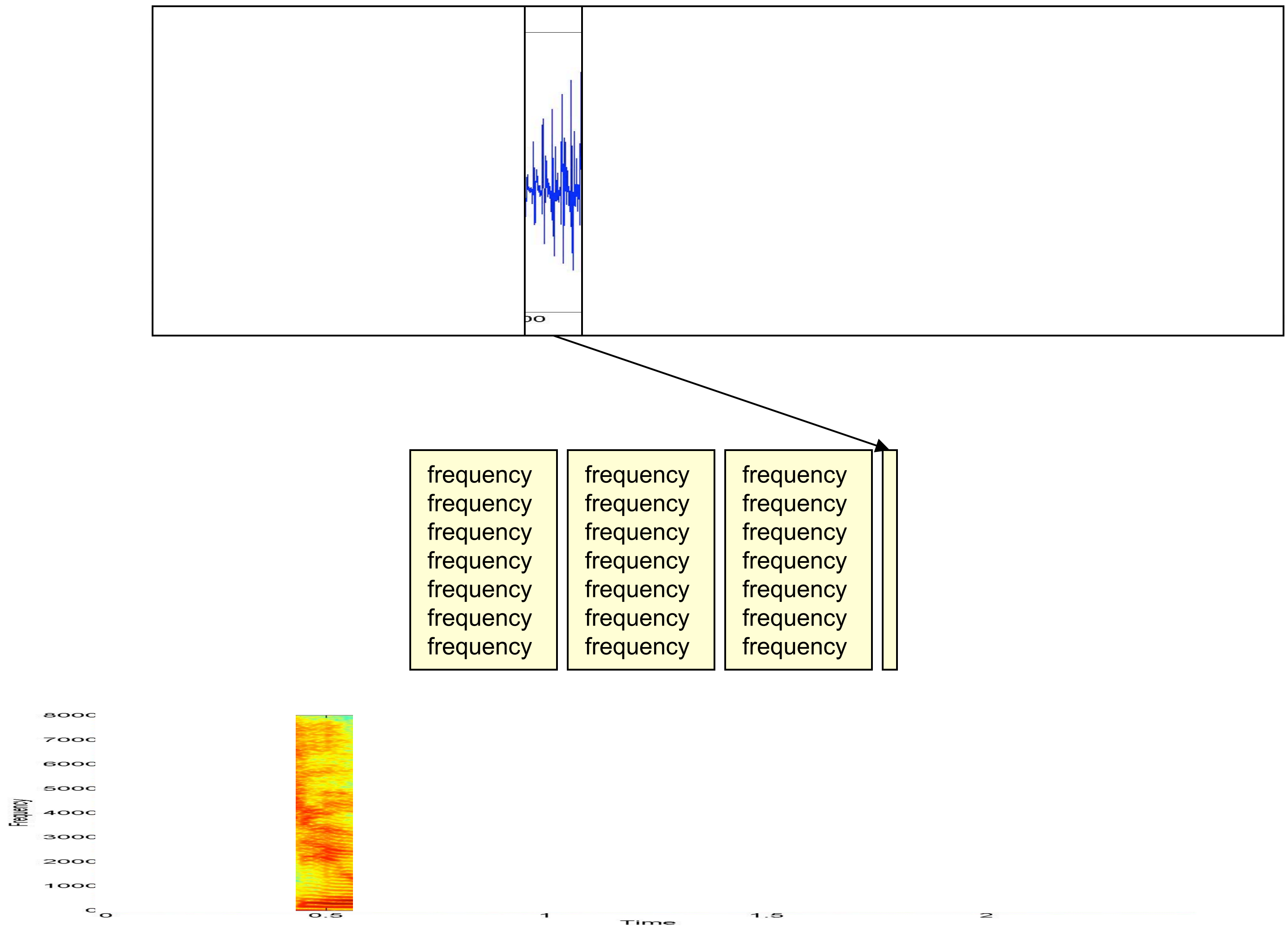
Compute Fourier Spectra of segments of audio and stack them side-by-side

Computing a Spectrogram



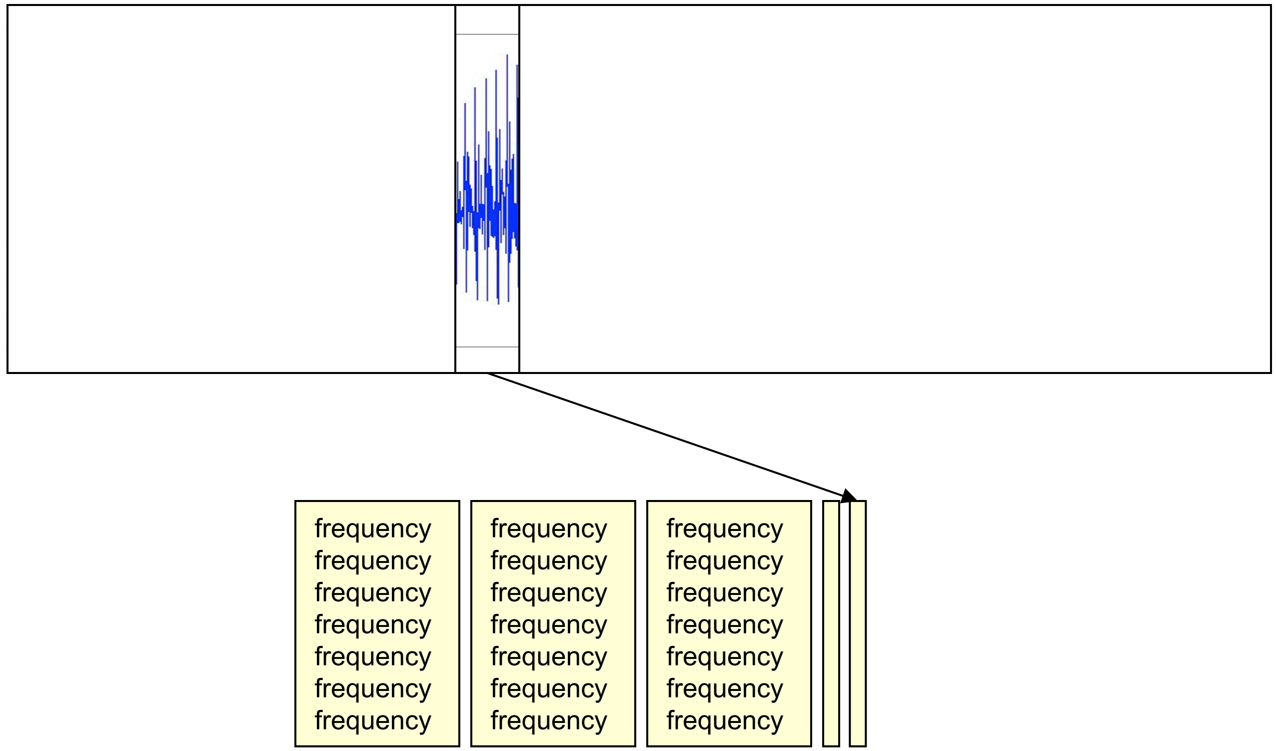
Compute Fourier Spectra of segments of audio and stack them side-by-side

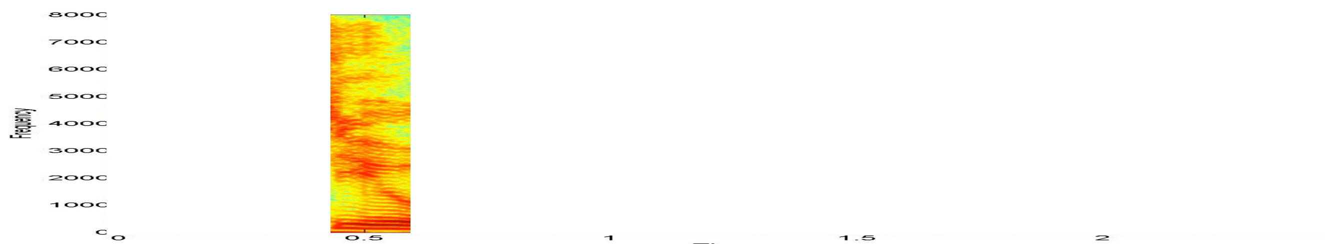
Computing a Spectrogram



Compute Fourier Spectra of segments of audio and stack them side-by-side

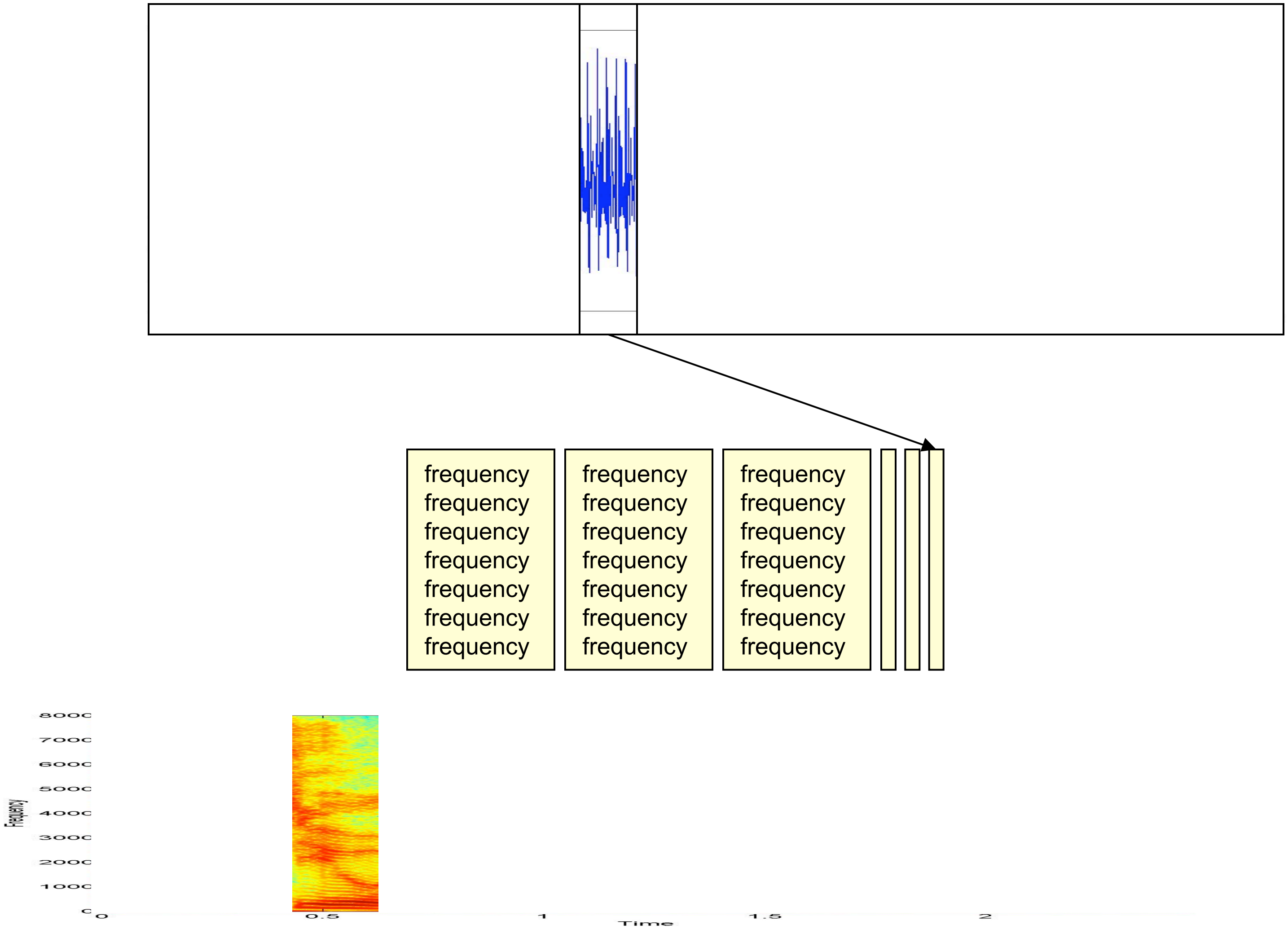
Computing a Spectrogram





Compute Fourier Spectra of segments of audio and stack them side-by-side

Computing a Spectrogram



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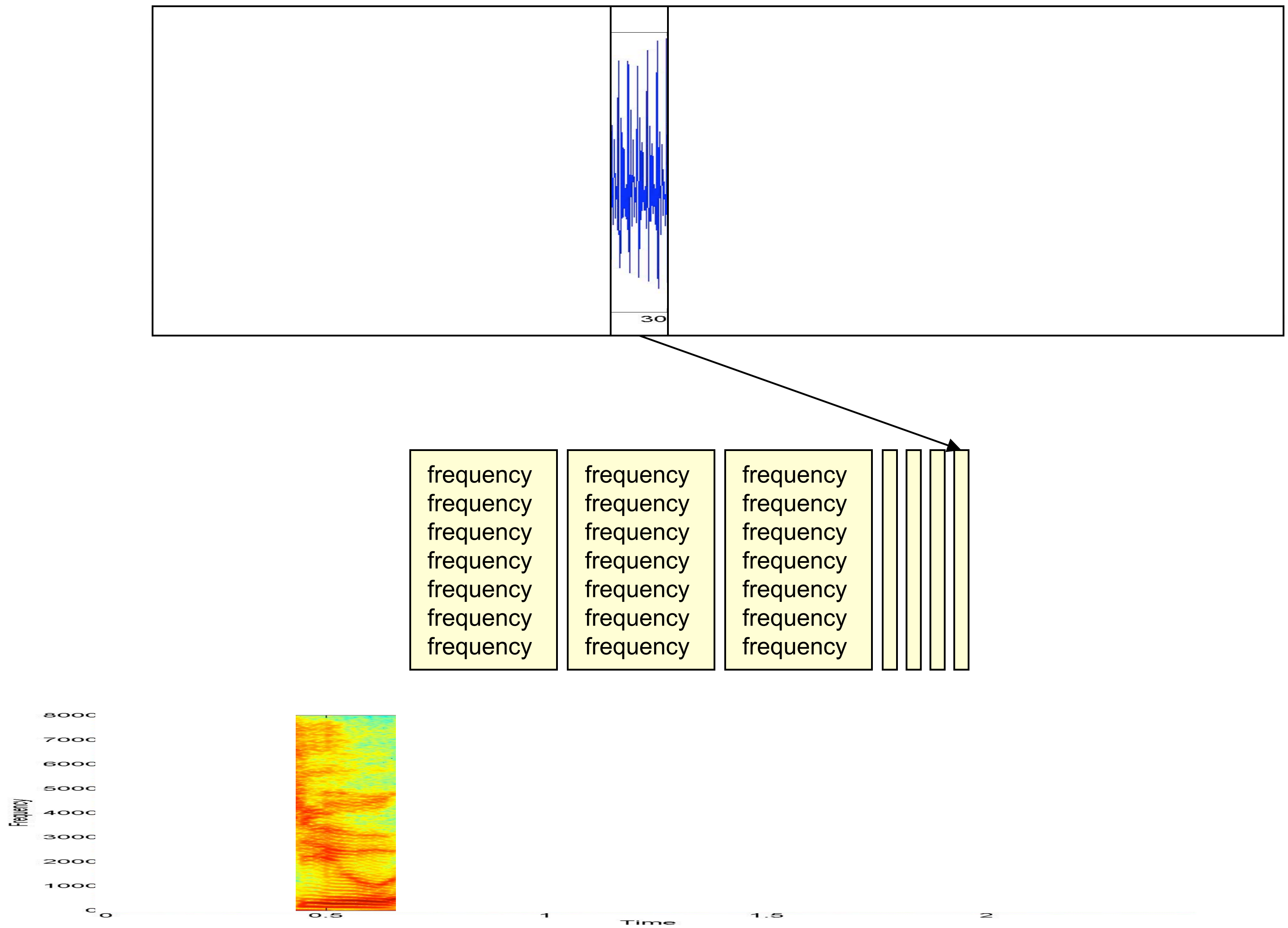

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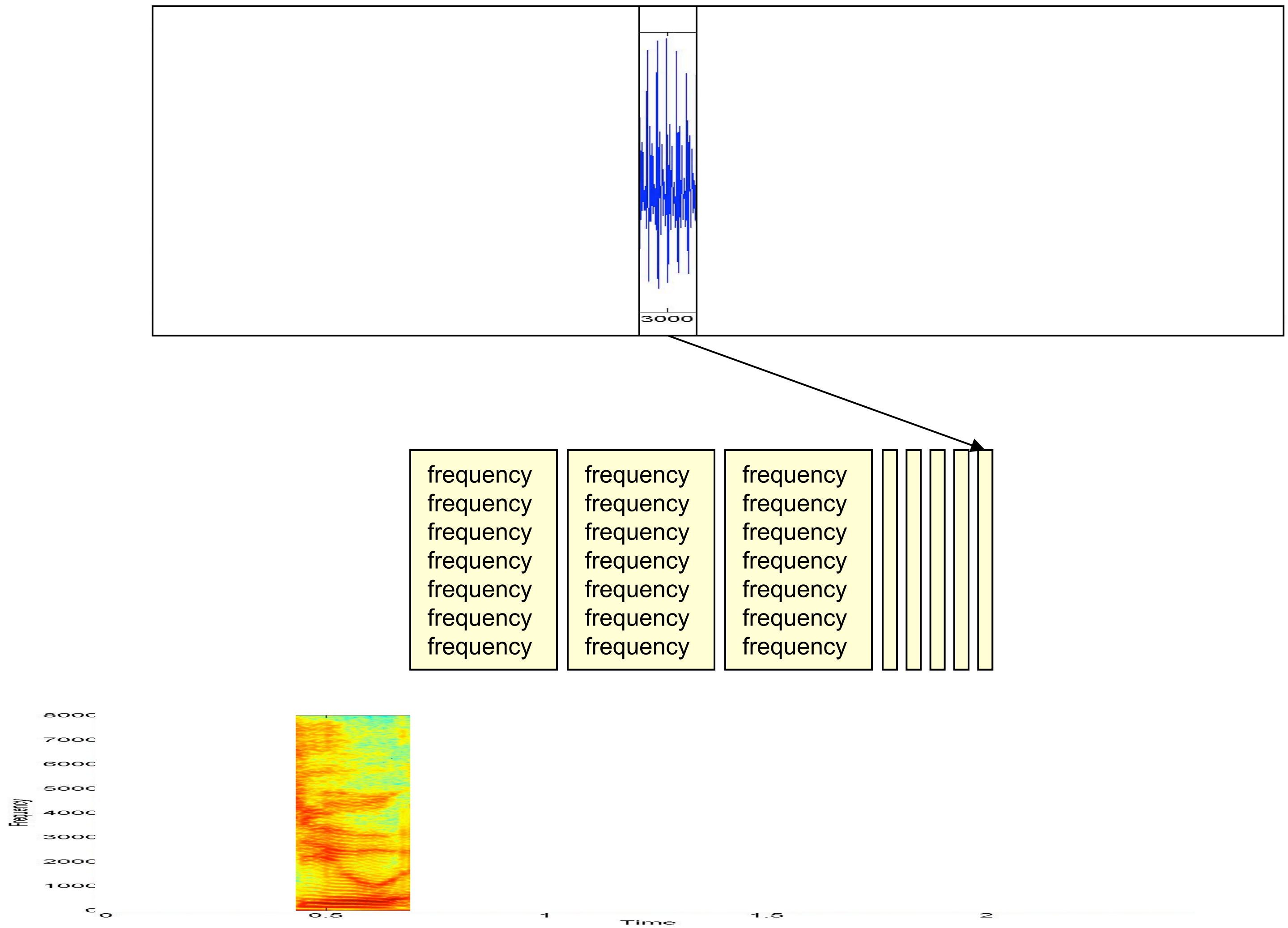

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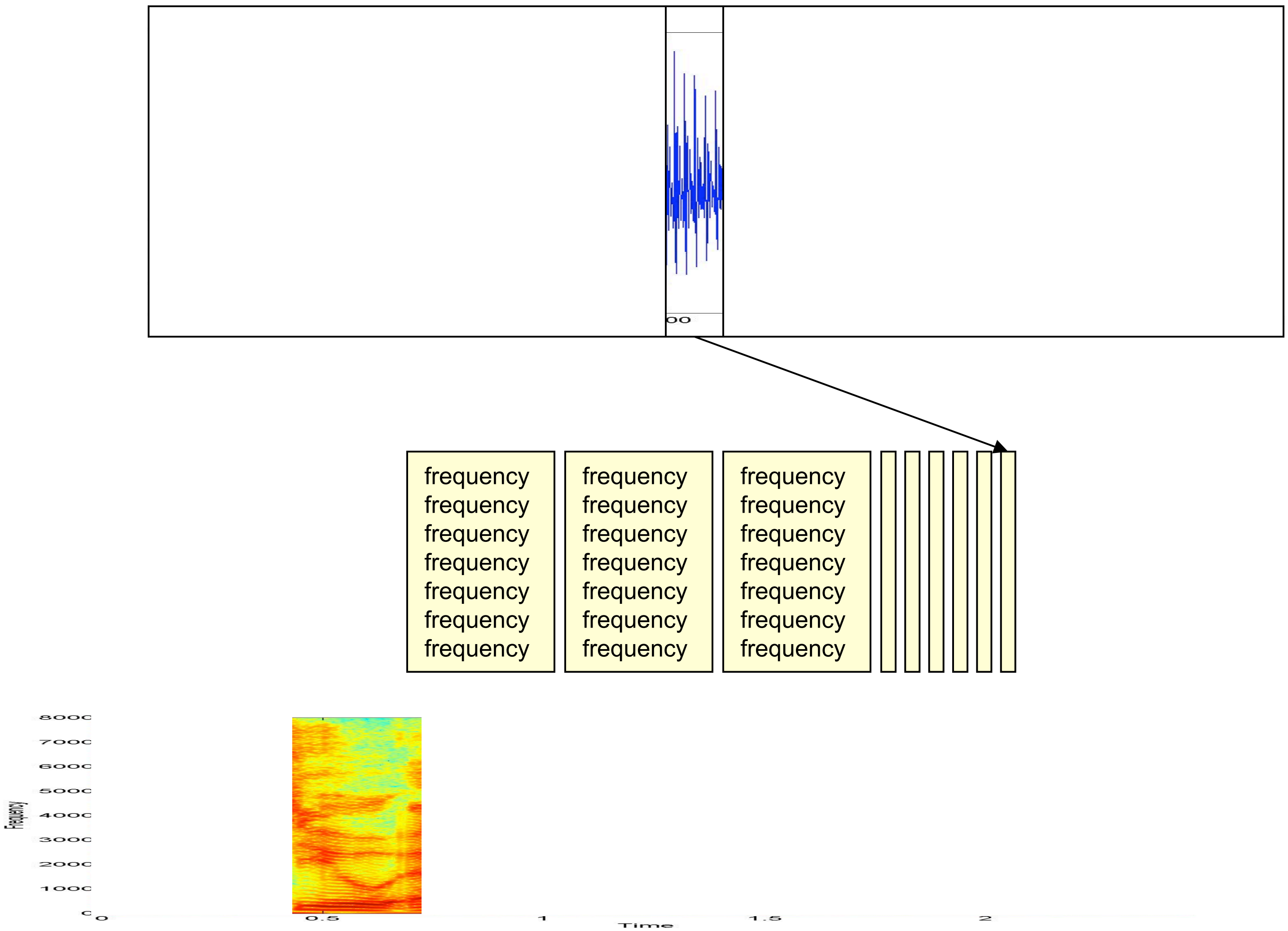

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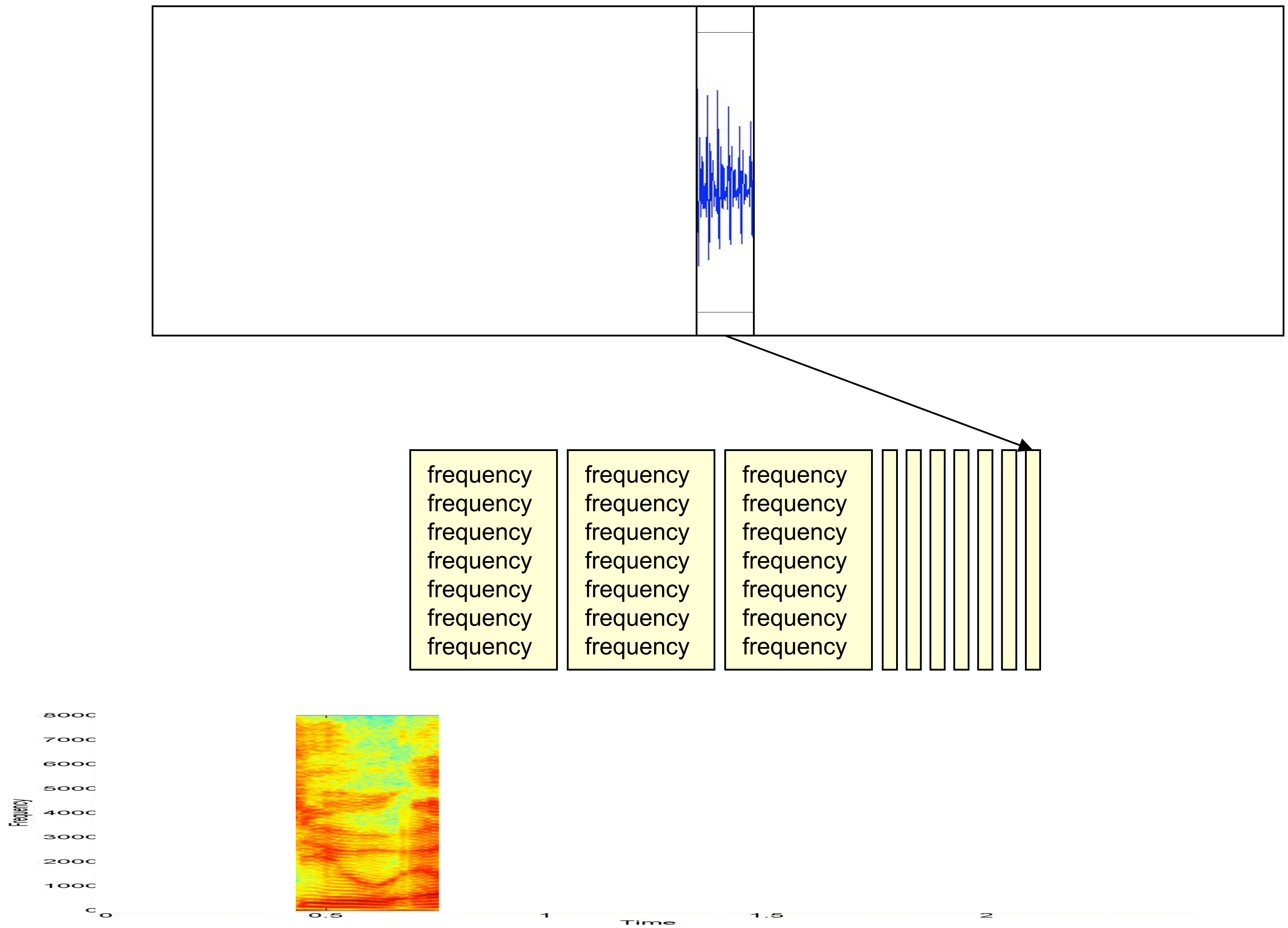

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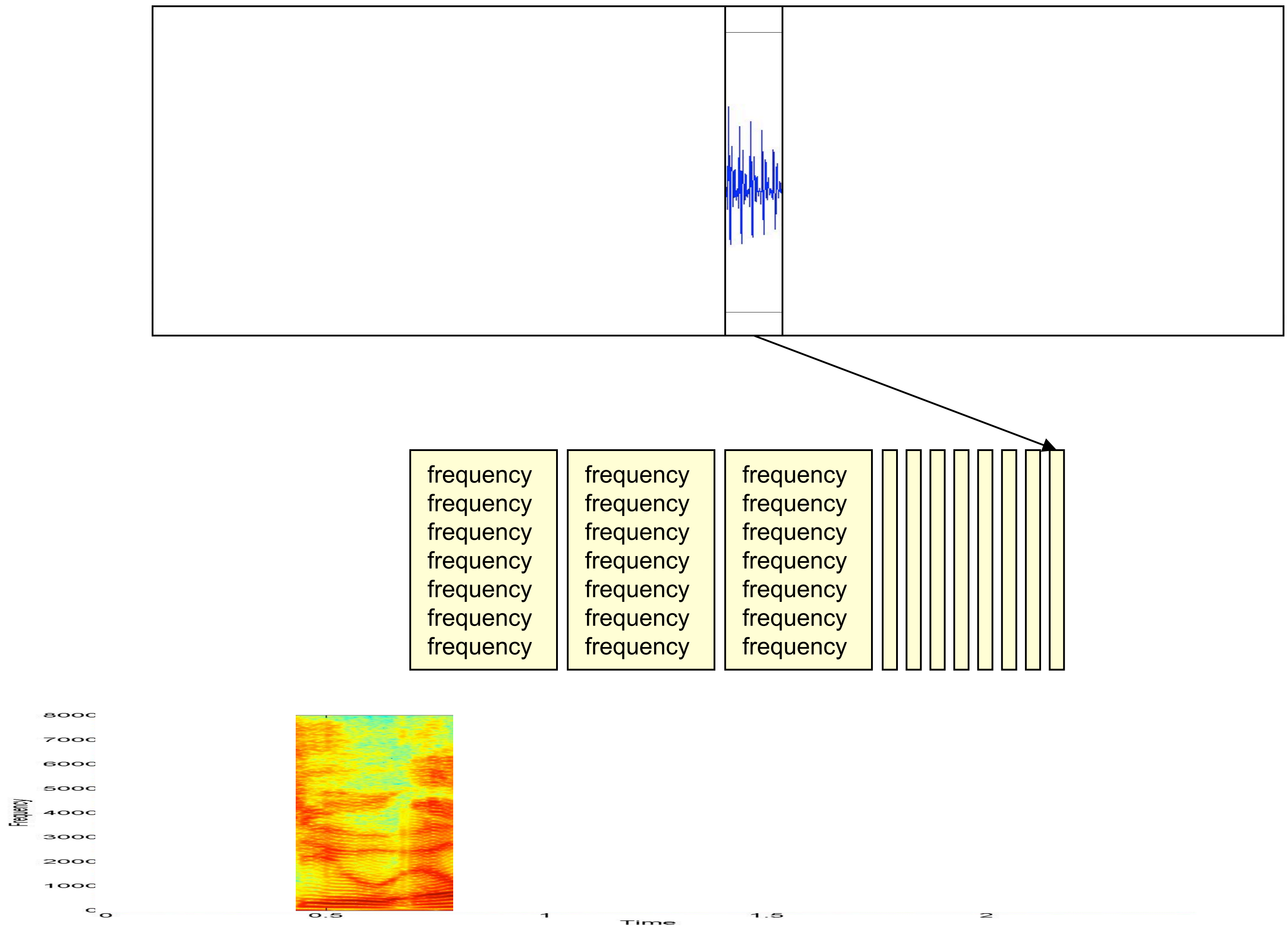

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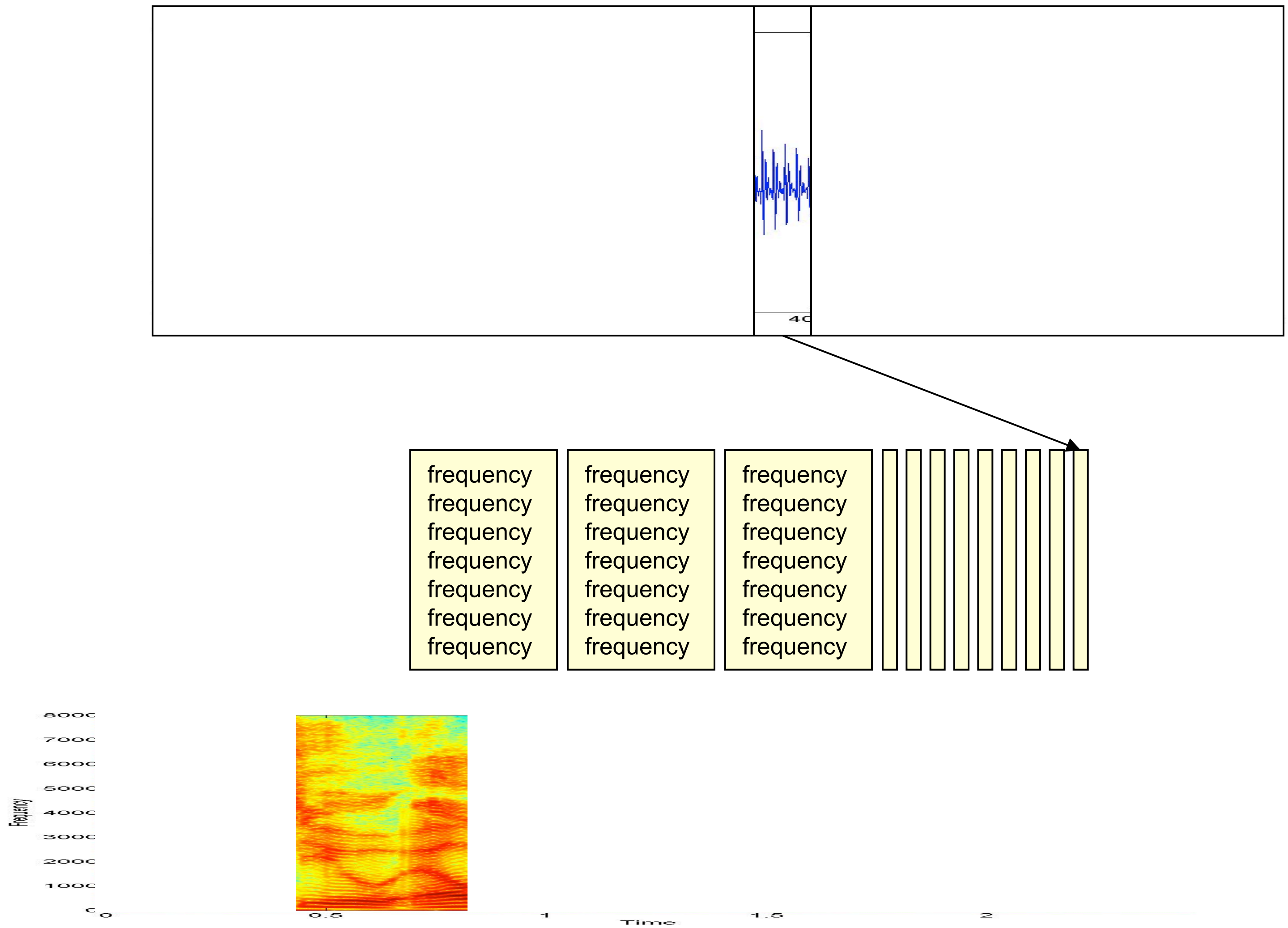

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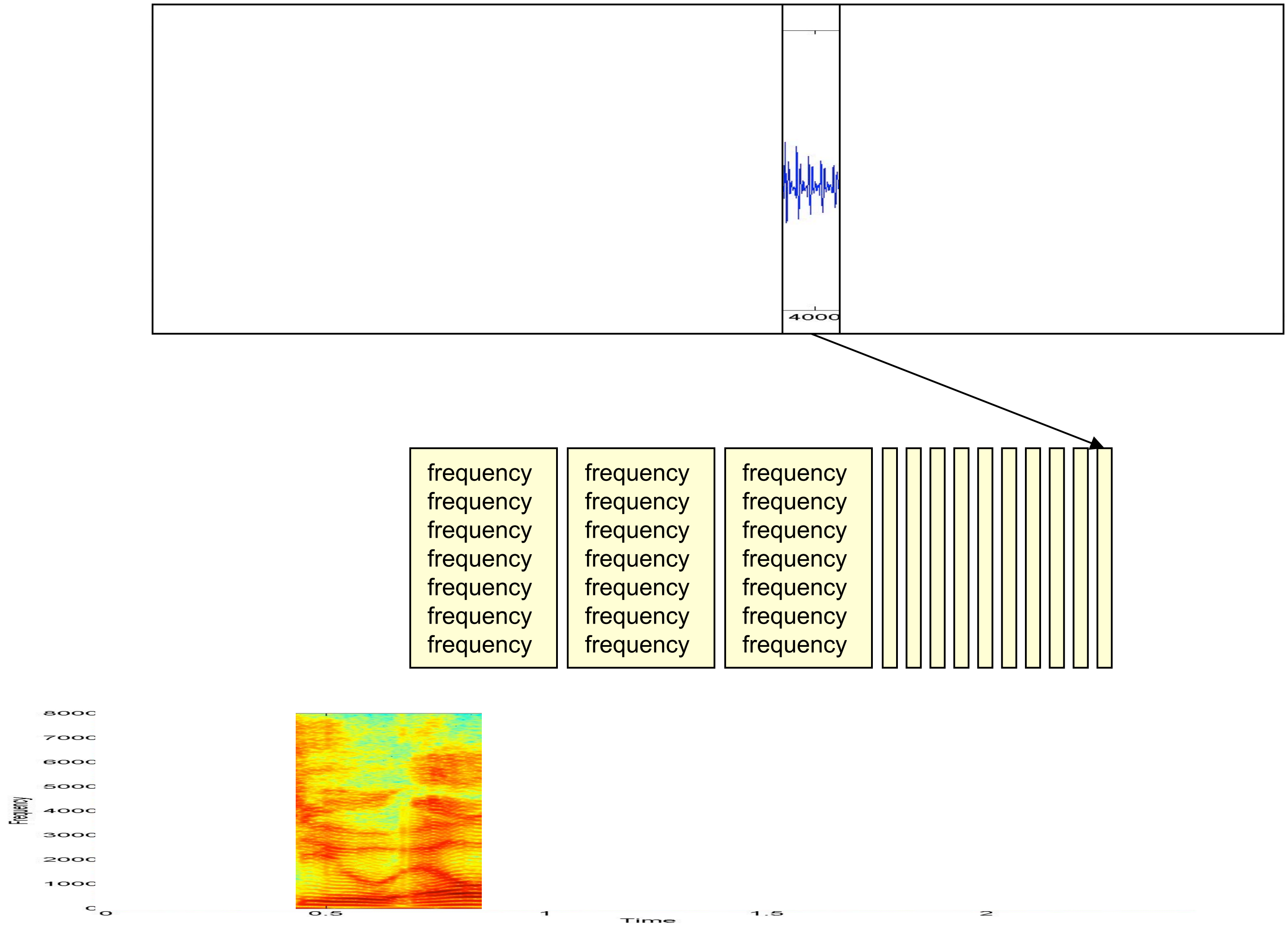

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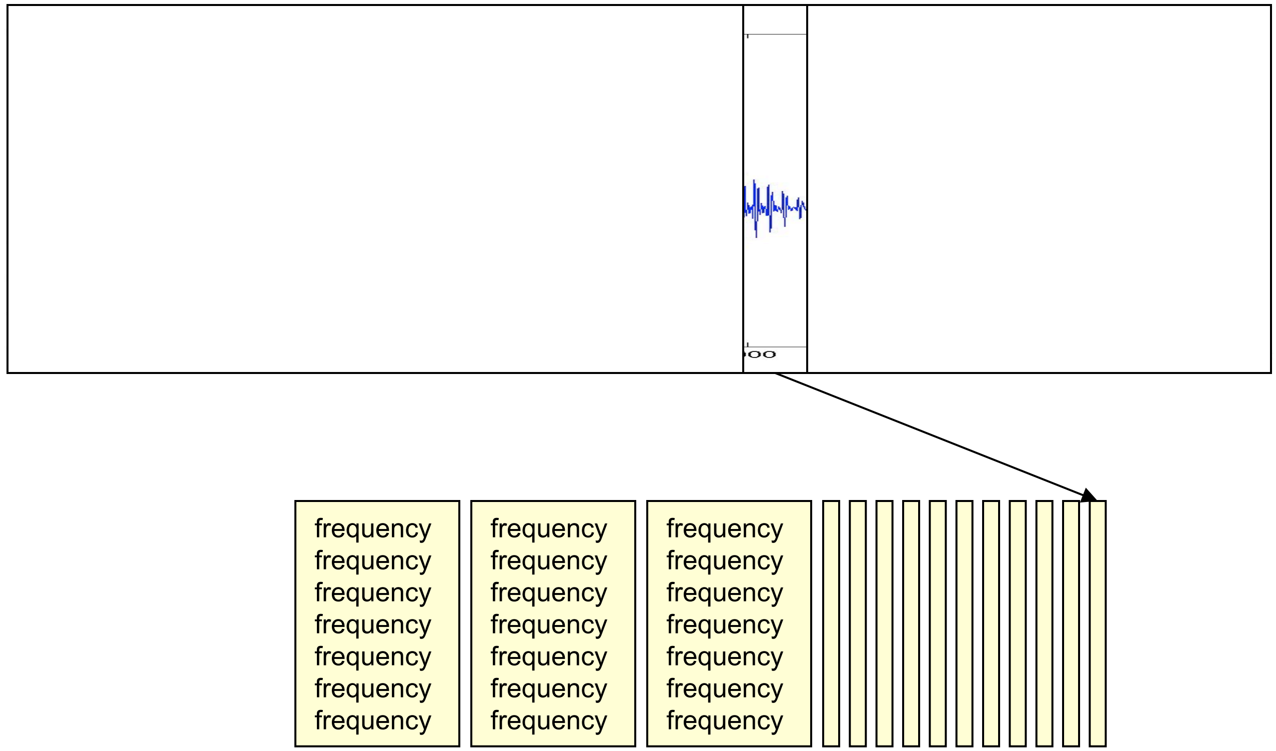

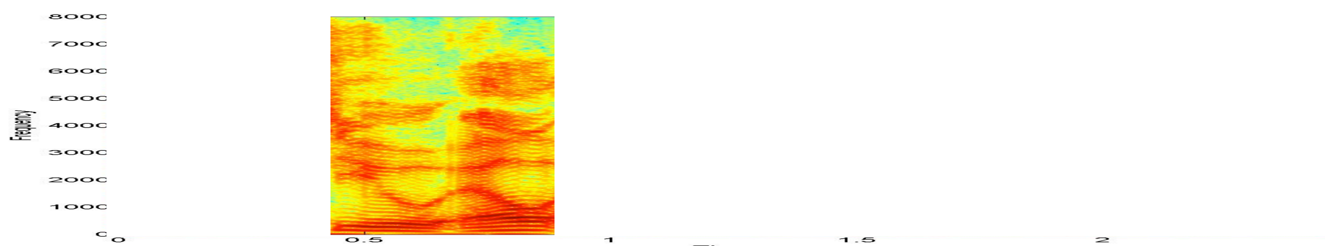

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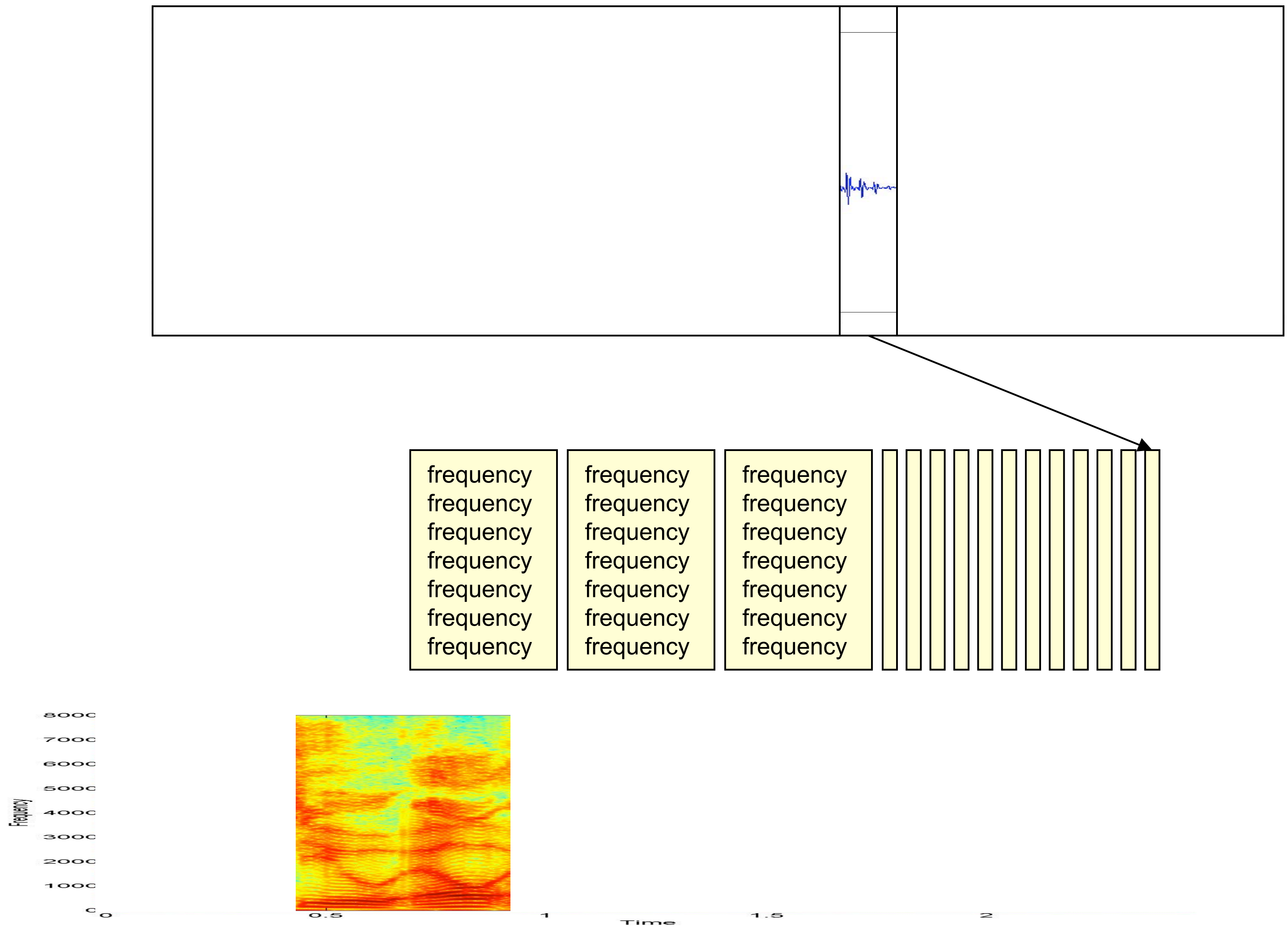

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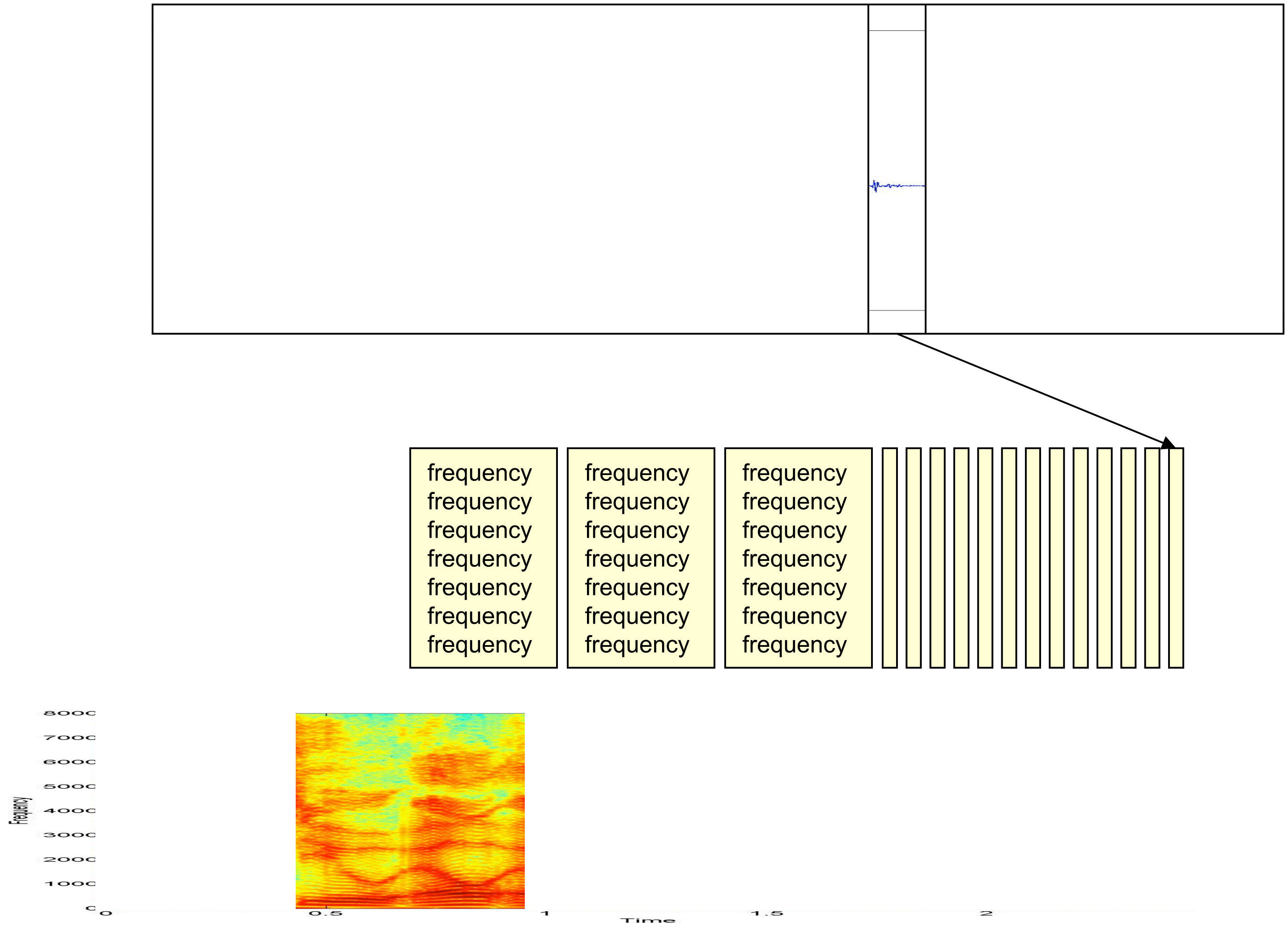

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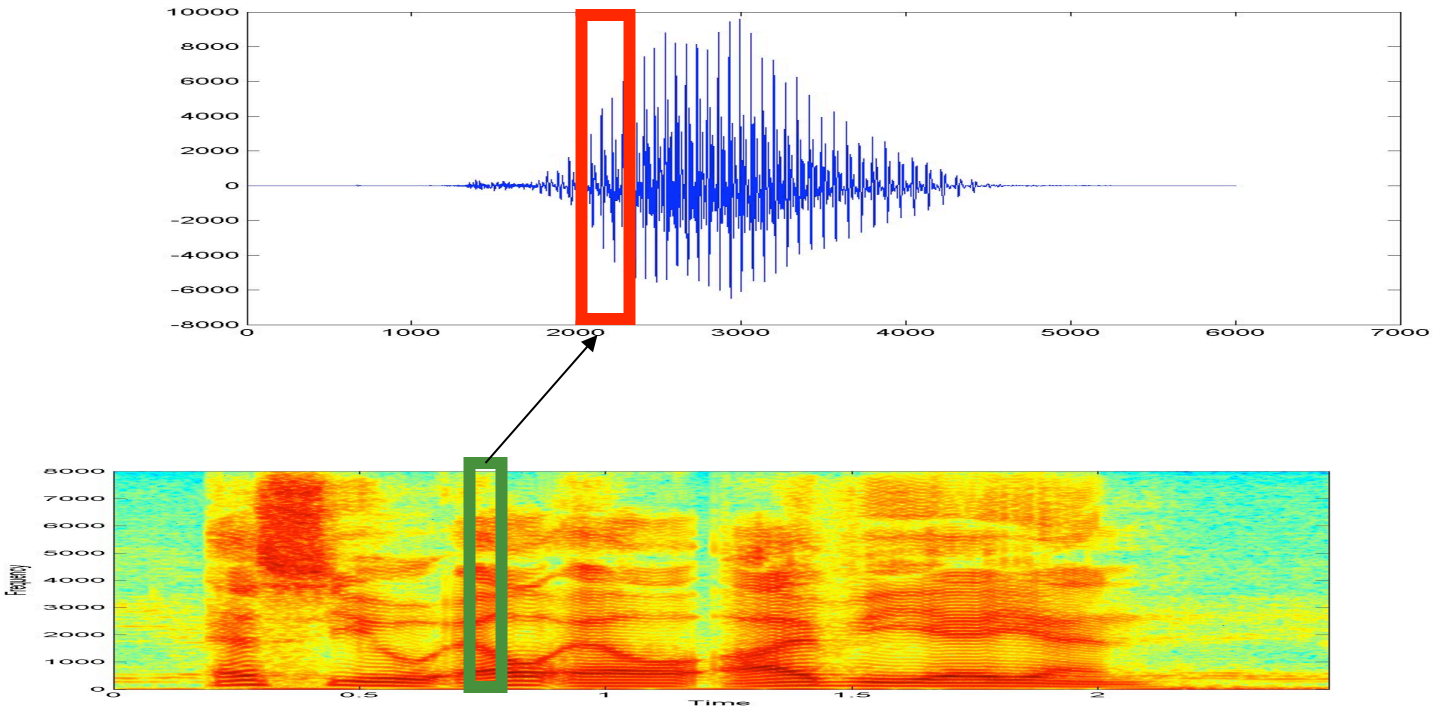
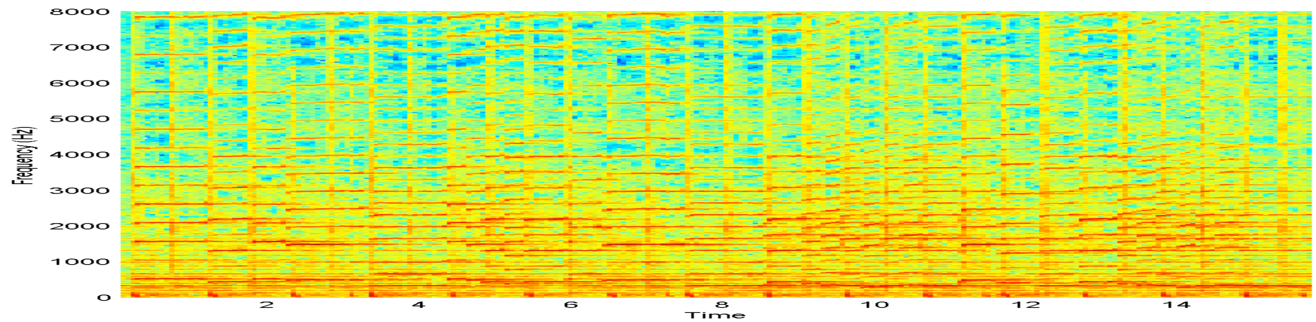


Compute Fourier Spectra of segments of audio and stack them side-by-side
The Fourier spectrum of each window can be inverted to get back the signal.
Hence the spectrogram can be inverted to obtain a time-domain signal

In this example each segment was 25 ms long and adjacent segments overlapped by 15 ms

The result of parameterization



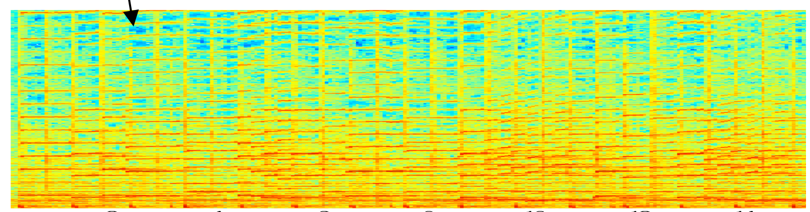
- Each column here represents the FT of a single segment of signal 64ms wide.
  - Adjacent segments overlap by 48 ms.
- DFT details
  - 1024 points (16000 samples a second).
  - 2048 point DFT – 1024 points of zero padding.
  - Only 1025 points of each DFT are shown
    - The rest are “reflections”
- The value shown is actually the magnitude of the complex spectral values
  - Most of our analysis / operations are performed on the magnitude

Magnitude and phase

?

$$S_k = |S_k| \exp(j.phase(S_k))$$

$$\begin{bmatrix} W_L^{0,0} & . & W_L^{L/2,0} & . & W_L^{L-1,0} \\ W_L^{0,1} & . & W_L^{L/2,1} & . & W_L^{L-1,1} \\ . & . & . & . & . \\ . & . & . & . & . \\ W_L^{0,L-1} & . & W_L^{L/2,L-1} & . & W_L^{L-1,L-1} \end{bmatrix} \begin{bmatrix} S_0 \\ . \\ S_k \\ . \\ S_{L-1} \end{bmatrix} = \begin{bmatrix} s[0] \\ s[1] \\ . \\ . \\ s[L-1] \end{bmatrix}$$



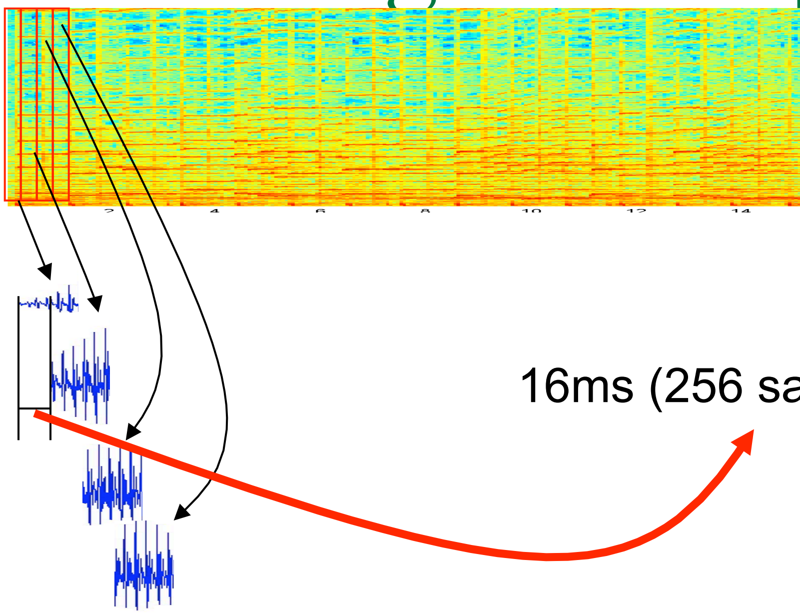
- All the operations (e.g. the examples shown in the previous class) are performed on the magnitude
- The phase of the complex spectrum is needed to invert a DFT to a signal
  - Where does that come from?
- Deriving phase is a serious, not-quite solved problem.

Phase

- Common tricks: Obtain the phase from the original signal
  - Sft = DFT(signal)
  - Phase1 = phase(Sft)
    - Each term is of the form real + j imag
    - For each element, compute arctan(imag/real)
  - Smagnitude = magnitude(Sft)
    - For each element compute Sqrt(real*real + imag*imag)
  - ProcessedSpectrum = Process(Smagnitude)
  - New SFT = ProcessedSpectrum*exp(j*Phase)
  - Recover signal from SFT

- Some other tricks:
  - Compute the FT of a different signal of the same length
  - Use the phase from that signal

Returning to the speech signal



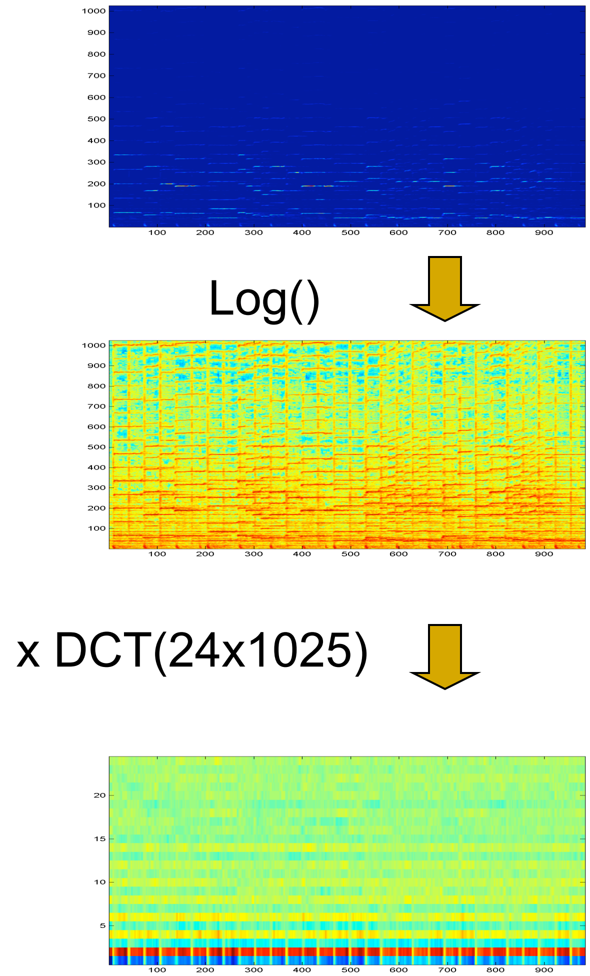
Actually a matrix of complex numbers

16ms (256 samples)

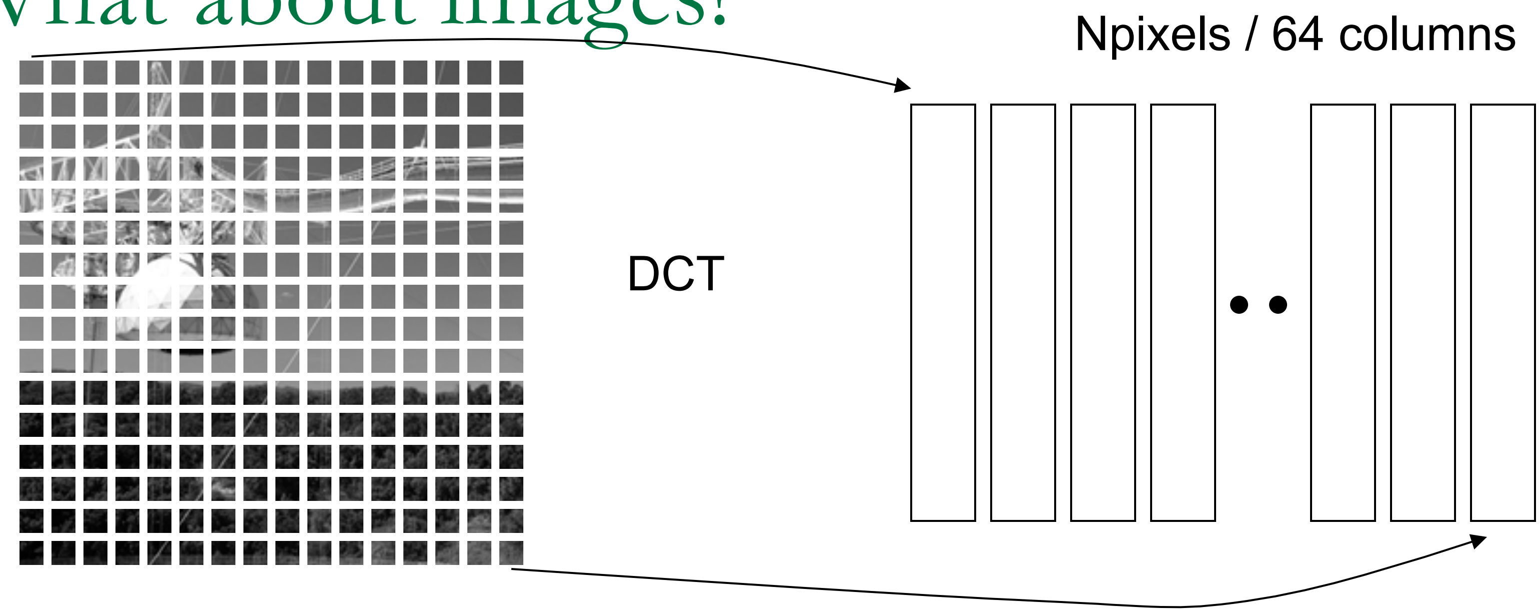
- For each complex spectral vector, compute a signal from the inverse DFT
  - Make sure to have the complete FT (including the reflected portion)
- If need be window the retrieved signal
- Overlap signals from adjacent vectors in exactly the same manner as during analysis
  - E.g. If a 48ms (768 sample) overlap was used during analysis, overlap adjacent segments by 768 samples

Additional tricks

- The basic representation is the magnitude spectrogram
- Often it is transformed to a *log* spectrum
  - By computing the log of each entry in the spectrogram matrix
  - After processing, the entry is exponentiated to get back the magnitude spectrum
    - To which phase may be factored in to get a signal
- The log spectrum may be "compressed" by a dimensionality reducing matrix
  - Usually a DCT matrix



What about images?



- DCT of small segments
  - 8x8
  - Each image becomes a matrix of DCT vectors
- DCT of the image
- Haar transform (checkerboard)
- Various wavelet representations
  - Gabor wavelets
- ***Or data-driven representations***
  - **Eigen faces**