11-755 Machine Learning for Signal Processing

Expectation Maximization Mixture Models HMMs

Class 9. 21 Sep 2010

21 Sep 2010

11755/18797

Learning Distributions for Data

- Problem: Given a collection of examples from some data, estimate its distribution
 - Basic ideas of Maximum Likelihood and MAP estimation can be found in Aarti/Paris' slides
 - Pointed to in a previous class
- Solution: Assign a model to the distribution
- Learn parameters of model from data
- Models can be arbitrarily complex
- Mixture densities, Hierarchical models.
- Learning must be done using Expectation Maximization
- Following slides: An intuitive explanation using a simple example of multinomials

p 2010 11755/18797

A Thought Experiment



63154124..

- A person shoots a loaded dice repeatedly
- You observe the series of outcomes
- You can form a good idea of how the dice is loaded
- Figure out what the probabilities of the various numbers are for dice
- P(number) = count(number)/sum(rolls)
- This is a maximum likelihood estimate
 - Estimate that makes the observed sequence of numbers most probable

21 Sep 2010

11755/18797

The Multinomial Distribution

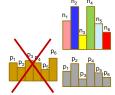
 A probability distribution over a discrete collection of items is a Multinomial

P(X : X belongs to a discrete set) = P(X)

- E.g. the roll of dice
- □ X : X in (1,2,3,4,5,6)
- Or the toss of a coin
 - □ X : X in (head, tails)

Sep 2010

Maximum Likelihood Estimation





- Basic principle: Assign a form to the distribution
 - □ E.g. a multinomial
 - Or a Gaussian
- Find the distribution that best fits the histogram of the data

21 Sep 2010

11755/18797

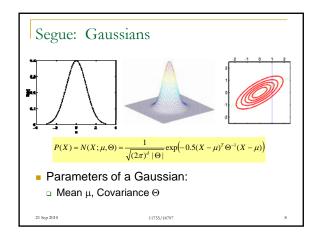
Defining "Best Fit"

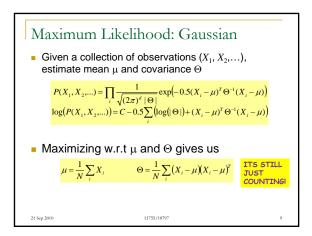
- The data are generated by draws from the distribution
 - I.e. the generating process draws from the distribution
- Assumption: The distribution has a high probability of generating the observed data
 - Not necessarily true
- Select the distribution that has the highest probability of generating the data
 - Should assign lower probability to less frequent observations and vice versa

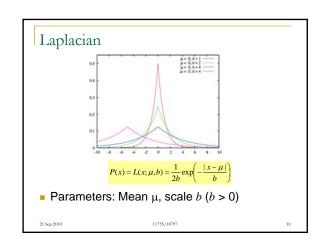
21 Sep 2010

11755/18797

Maximum Likelihood Estimation: Multinomial Probability of generating $(n_1, n_2, n_3, n_4, n_5, n_6)$ $P(n_1, n_2, n_3, n_4, n_5, n_6) = Const \prod_i p_i^{n_i}$ Find $p_1, p_2, p_3, p_4, p_5, p_6$ so that the above is maximized Alternately maximize $\log(P(n_1, n_2, n_3, n_4, n_5, n_6)) = \log(Const) + \sum_i n_i \log(p_i)$ $\log(P(n_1, n_2, n_3, n_4, n_5, n_6)) = \log(Const) + \sum_i n_i \log(p_i)$ $\log(P(n_1, n_2, n_3, n_4, n_5, n_6)) = \log(Const) + \sum_i n_i \log(p_i)$ $\log(P(n_1, n_2, n_3, n_4, n_5, n_6)) = \log(Const) + \sum_i n_i \log(p_i)$ $\log(P(n_1, n_2, n_3, n_4, n_5, n_6)) = \log(Const) + \sum_i n_i \log(p_i)$ $\log(P(n_1, n_2, n_3, n_4, n_5, n_6)) = \log(Const) + \sum_i n_i \log(p_i)$ $\log(P(n_1, n_2, n_3, n_4, n_5, n_6)) = \log(Const) + \sum_i n_i \log(p_i)$ $\log(P(n_1, n_2, n_3, n_4, n_5, n_6)) = \log(Const) + \sum_i n_i \log(p_i)$ $\log(P(n_1, n_2, n_3, n_4, n_5, n_6)) = \log(Const) + \sum_i n_i \log(p_i)$ $\log(P(n_1, n_2, n_3, n_4, n_5, n_6)) = \log(Const) + \sum_i n_i \log(p_i)$ $\log(P(n_1, n_2, n_3, n_4, n_5, n_6)) = \log(Const) + \sum_i n_i \log(p_i)$ $\log(P(n_1, n_2, n_3, n_4, n_5, n_6)) = \log(Const) + \sum_i n_i \log(p_i)$ $\log(P(n_1, n_2, n_3, n_4, n_5, n_6)) = \log(Const) + \sum_i n_i \log(p_i)$ $\log(P(n_1, n_2, n_3, n_4, n_5, n_6)) = \log(Const) + \sum_i n_i \log(p_i)$ $\log(P(n_1, n_2, n_3, n_4, n_5, n_6)) = \log(Const) + \sum_i n_i \log(p_i)$ $\log(P(n_1, n_2, n_3, n_4, n_5, n_6)) = \log(Const) + \sum_i n_i \log(p_i)$ $\log(P(n_1, n_2, n_3, n_4, n_5, n_6)) = \log(Const) + \sum_i n_i \log(p_i)$ $\log(P(n_1, n_2, n_3, n_4, n_5, n_6)) = \log(Const) + \sum_i n_i \log(p_i)$ $\log(P(n_1, n_2, n_3, n_4, n_5, n_6)) = \log(Const) + \sum_i n_i \log(p_i)$ $\log(P(n_1, n_2, n_3, n_4, n_5, n_6)) = \log(Const) + \sum_i n_i \log(p_i)$ $\log(P(n_1, n_2, n_3, n_4, n_5, n_6)) = \log(Const)$ $\log(P(n_1, n_2, n_3, n_4, n_5, n_6)) = \log(Const)$ $\log(P(n_1, n_2, n_3, n_4, n_5, n_6)$ $\log(P(n_1, n_2, n_3, n_4, n_5, n_6)) = \log(Const)$ $\log(P(n_1, n_2, n_5, n_6)) = \log(Const)$ $\log(P(n_1, n_$

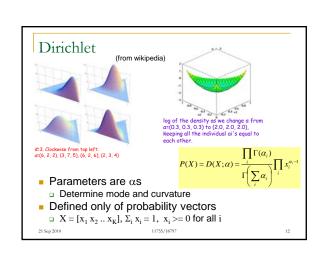






Maximum Likelihood: Laplacian

• Given a collection of observations $(x_1, x_2,...)$, estimate mean μ and scale b $\log(P(x_1, x_2,...)) = C - N\log(b) - \sum_i \frac{|x_i - \mu|}{b}$ • Maximizing w.r.t μ and b gives us $\mu = \frac{1}{N} \sum_i x_i \qquad b = \frac{1}{N} \sum_i |x_i - \mu|$



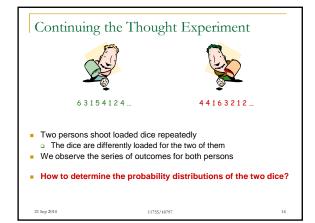
Maximum Likelihood: Dirichlet

• Given a collection of observations $(X_1, X_2,...)$, estimate α

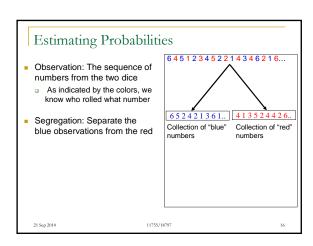
 $\log(P(X_1, X_2,...)) = \sum_{i} \sum_{i} (\alpha_i - 1) \log(X_{j,i}) + N \sum_{i} \log(\Gamma(\alpha_i)) - N \log\left(\Gamma\left(\sum_{i} \alpha_i\right)\right)$

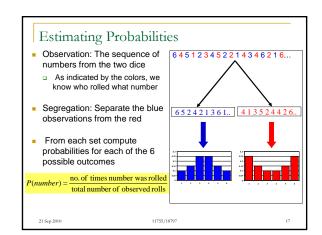
- No closed form solution for αs .
 - Needs gradient ascent
- Several distributions have this property: the ML estimate of their parameters have no closed form solution

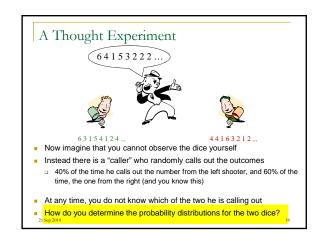
21 Sep 2010 11755/18797 13

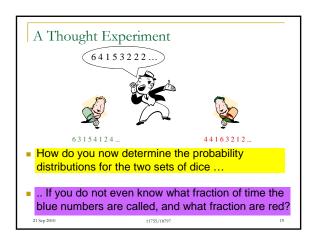


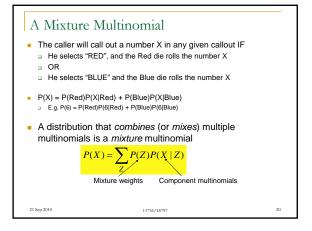
Estimating Probabilities Observation: The sequence of numbers from the two dice As indicated by the colors, we know who rolled what number

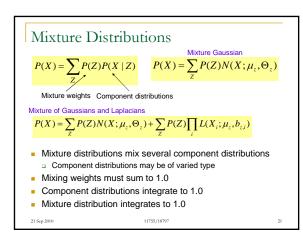


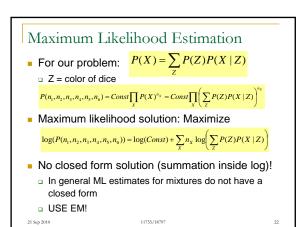












Expectation Maximization

- It is possible to estimate all parameters in this setup using the Expectation Maximization (or EM) algorithm
- First described in a landmark paper by Dempster, Laird and Rubin
 - Maximum Likelihood Estimation from incomplete data, via the EM Algorithm, Journal of the Royal Statistical Society, Series B, 1977
- Much work on the algorithm since then
- The principles behind the algorithm existed for several years prior to the landmark paper, however.

21 Sep 2010 11755/18797 21

Expectation Maximization

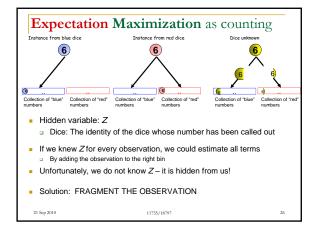
- Iterative solution
- Get some initial estimates for all parameters
 - Dice shooter example: This includes probability distributions for dice AND the probability with which the caller selects the dice
- Two steps that are iterated:
 - Expectation Step: Estimate statistically, the values of unseen variables
 - Maximization Step: Using the estimated values of the unseen variables as truth, estimates of the model parameters

Sen 2010 11755/18797 24

EM: The auxiliary function

- EM iteratively optimizes the following auxiliary function
- $Q(\theta, \theta') = \Sigma_Z P(Z|X, \theta') \log(P(Z, X \mid \theta))$
 - Z are the unseen variables
 - □ Assuming Z is discrete (may not be)
- θ' are the parameter estimates from the previous iteration
- θ are the estimates to be obtained in the current iteration

11 Sep 2010 11755/18797



Fragmenting the Observation

- EM is an iterative algorithm
 - At each time there is a *current* estimate of parameters
- The "size" of the fragments is proportional to the a posteriori probability of the component distributions
 - The a posteriori probabilities of the various values of Z are computed using Bayes' rule:

$$P(Z \mid X) = \frac{P(X \mid Z)P(Z)}{P(X)} = CP(X \mid Z)P(Z)$$

Every dice gets a fragment of size P(dice | number)

21 Sep 2010 11/35/18/97

Hypothetical Dice Shooter Example: We obtain an initial estimate for the probability distribution of the two sets of dice (somehow): We obtain an initial estimate for the probability with which the caller calls out the two shooters (somehow) 1.5 0.5 0.5 0.5 0.5 0.5

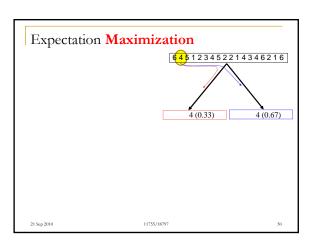
Expectation Maximization

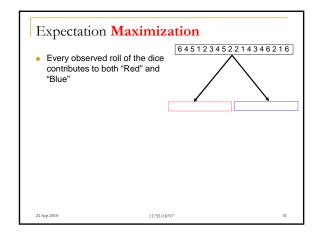
- Hypothetical Dice Shooter Example:
- Initial estimate:
 - □ P(blue) = P(red) = 0.5
 - $P(4 \mid blue) = 0.1, \text{ for } P(4 \mid red) = 0.05$
- Caller has just called out 4
- Posterior probability of colors:

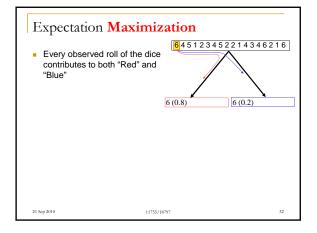
 $P(red \mid X = 4) = CP(X = 4 \mid Z = red)P(Z = red) = C \times 0.05 \times 0.5 = C0.025$ $P(blue \mid X = 4) = CP(X = 4 \mid Z = blue)P(Z = blue) = C \times 0.1 \times 0.5 = C0.05$

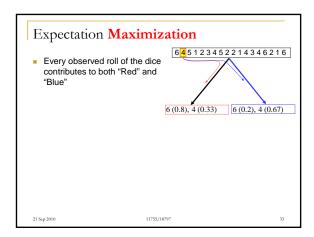
Normalizing : $P(red \mid X = 4) = 0.33$; $P(blue \mid X = 4) = 0.67$

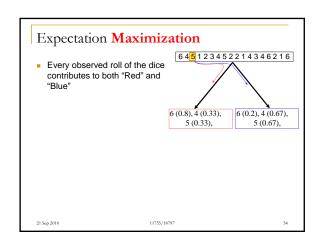
Sep 2010 11755/18797

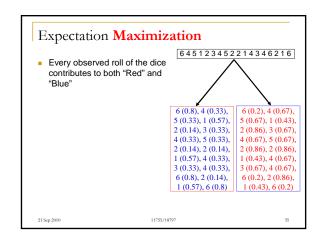


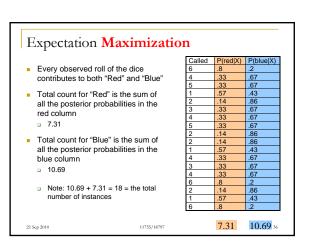


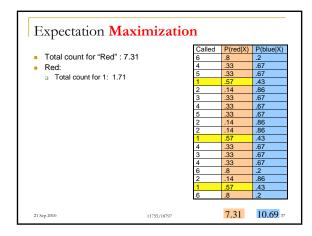


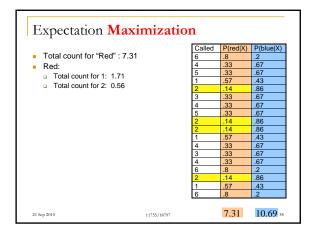


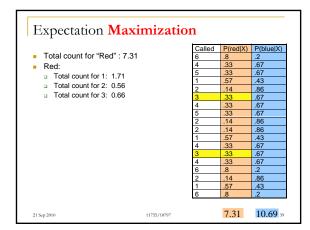


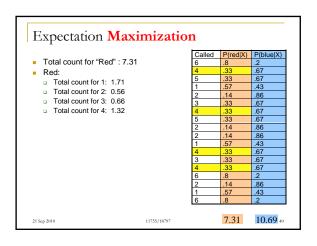


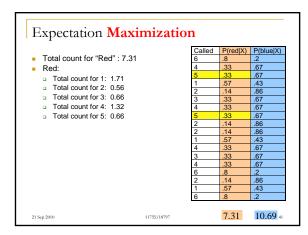


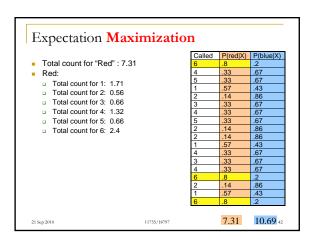


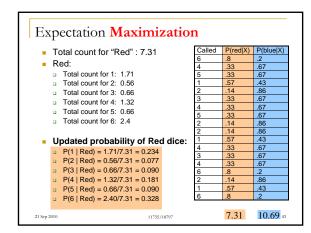


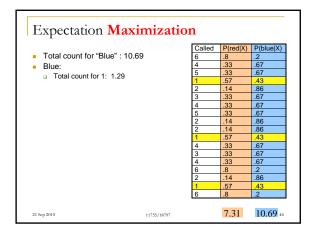


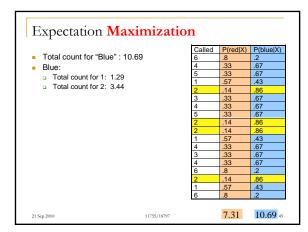


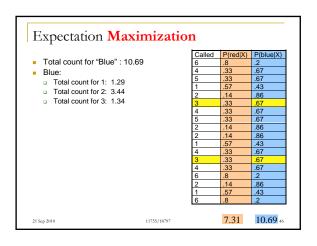


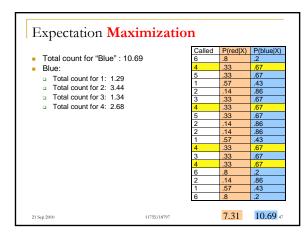


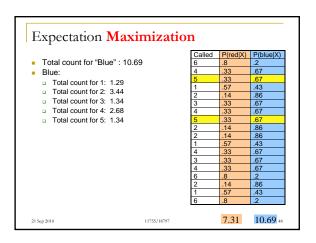


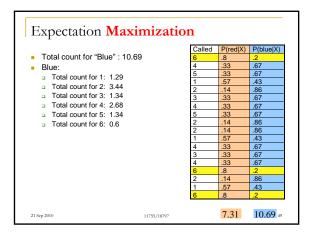


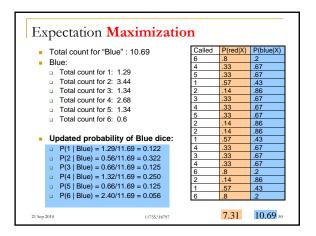


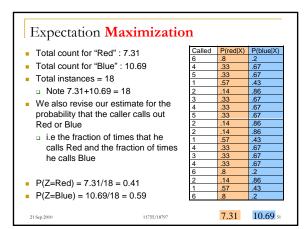


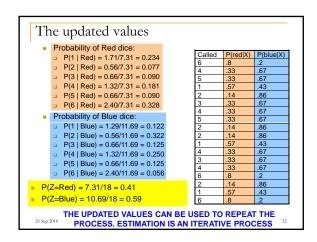


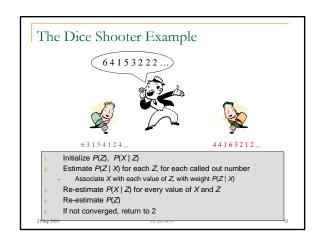


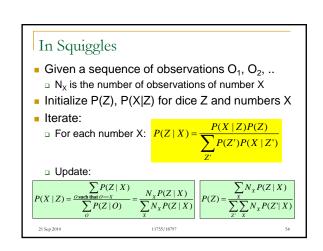




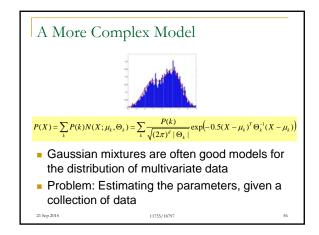


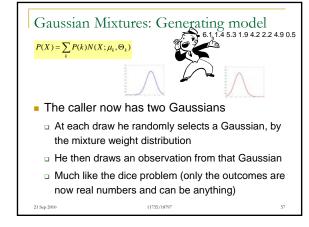


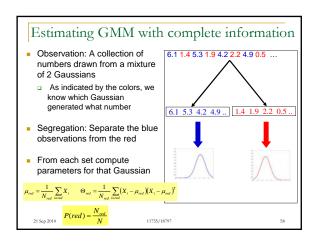


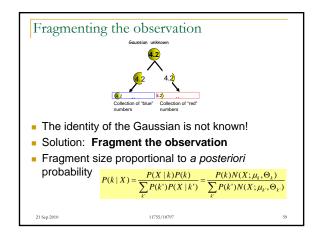


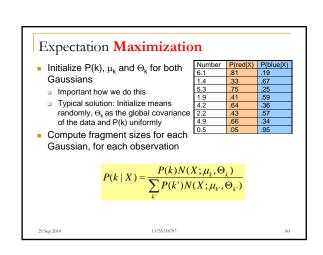
Solutions may not be unique The EM algorithm will give us one of many solutions, all equally valid! The probability of 6 being called out: $P(6) = \alpha P(6 \mid red) + \beta P(6 \mid blue) = \alpha P_r + \beta P_b$ Assigns P, as the probability of 6 for the red die Assigns P_b as the probability of 6 for the blue die The following too is a valid solution [FIX] $P(6) = 1.0(\alpha P_r + \beta P_b) + 0.0 anything$ Assigns 1.0 as the a priori probability of the red die Assigns 0.0 as the probability of the blue die The solution is NOT unique

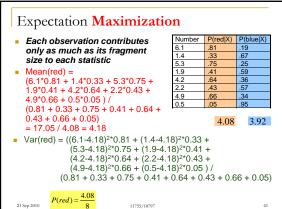




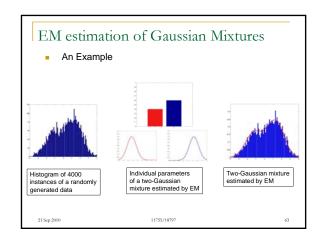


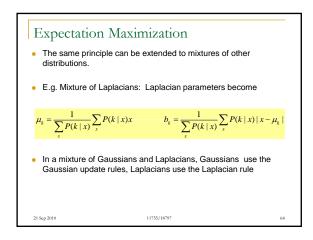






EM for Gaussian Mixtures 1. Initialize P(k), μ_k and Θ_k for all Gaussians 2. For each observation X compute a posteriori probabilities for all Gaussian $P(k \mid X) = \frac{P(k)N(X; \mu_k, \Theta_k)}{\sum_{k'} P(k')N(X; \mu_k, \Theta_{k'})}$ 3. Update mixture weights, means and variances for all Gaussians $\frac{\sum_{k'} P(k \mid X)}{N} \qquad \mu_k = \frac{\sum_{k'} P(k \mid X)}{\sum_{k'} P(k \mid X)} \qquad \Theta_k = \frac{\sum_{k'} P(k \mid X)(X - \mu_k)^2}{\sum_{k'} P(k \mid X)}$ 4. If not converged, return to 2





Expectation Maximization The EM algorithm is used whenever proper statistical analysis of a phenomenon requires the knowledge of a hidden or missing variable (or a set of hidden/missing variables) The hidden variable is often called a "latent" variable Some examples: Estimating mixtures of distributions Only data are observed. The individual distributions and mixing proportions must both be learnt. Estimating the distribution of data, when some attributes are missing Estimating the dynamics of a system, based only on observations that may be a complex function of system state

Solve this problem:

Caller rolls a dice and flips a coin
He calls out the number rolled if the coin shows head
Otherwise he calls the number+1
Determine p(heads) and p(number) for the dice from a collection of ouputs

Caller rolls two dice
He calls out the sum
Determine P(dice) from a collection of ouputs

