



Overview



- **Spatial Hearing and HRTFs**
- **A Different Approach**
- **An Efficient Representation**
- **Applying Bayesian estimation**
- **Modeling individual differences**
- **Summary of Contributions**

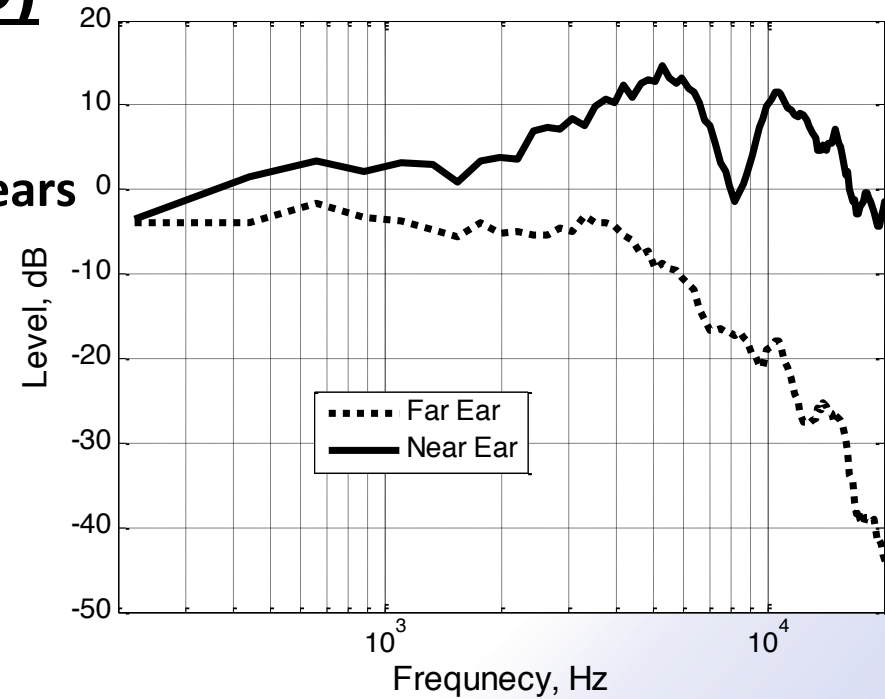
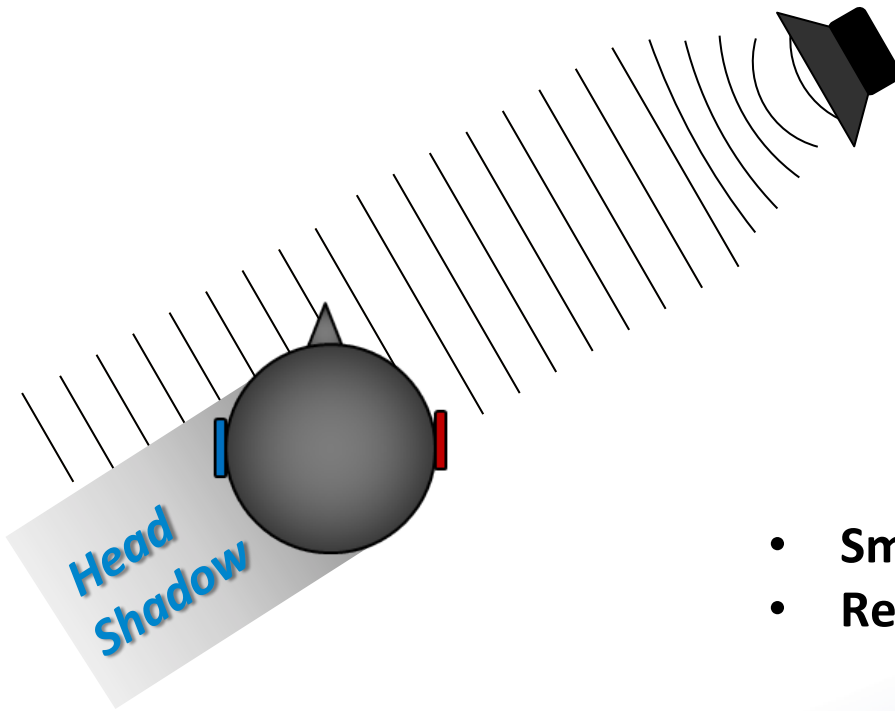


Spatial Hearing



Interaural Level Difference (ILD)

- Sound energy is scattered by the head
- Less energy arrives at the far ear
- Results in a level difference at the two ears



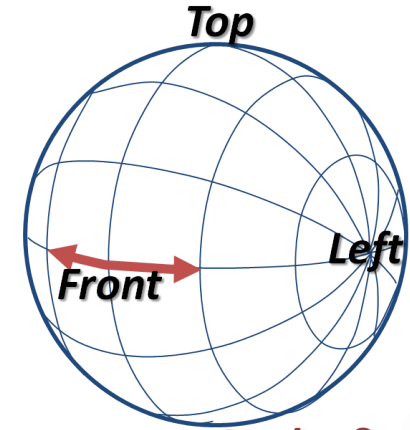
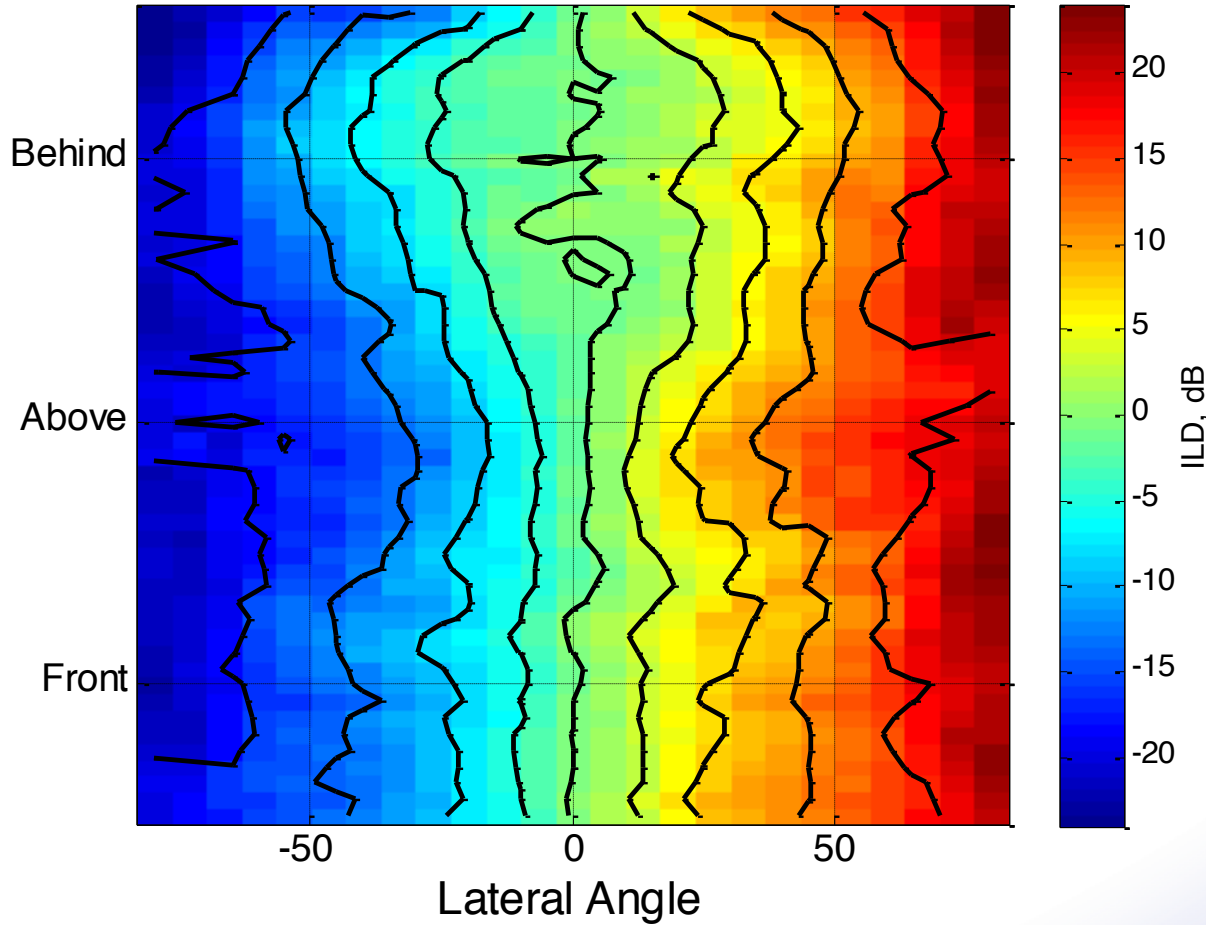
- Smaller wavelengths are attenuated more
- Results in larger ILDs at high frequencies



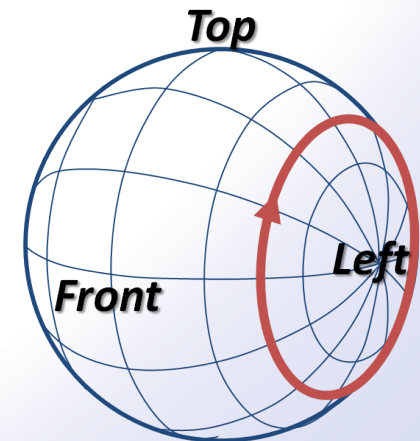
Spatial Hearing



Interaural Level Difference (ILD)



Lateral Angle, θ



Intraconic Angle, ϕ

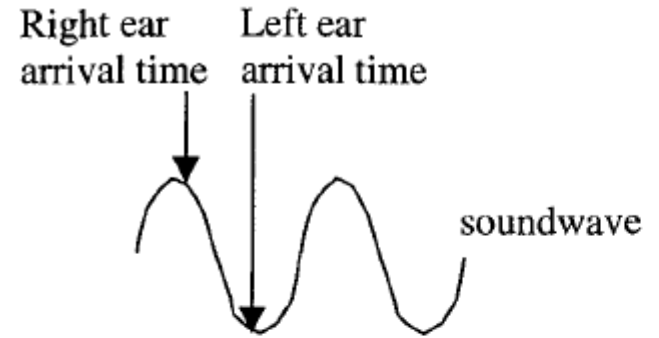
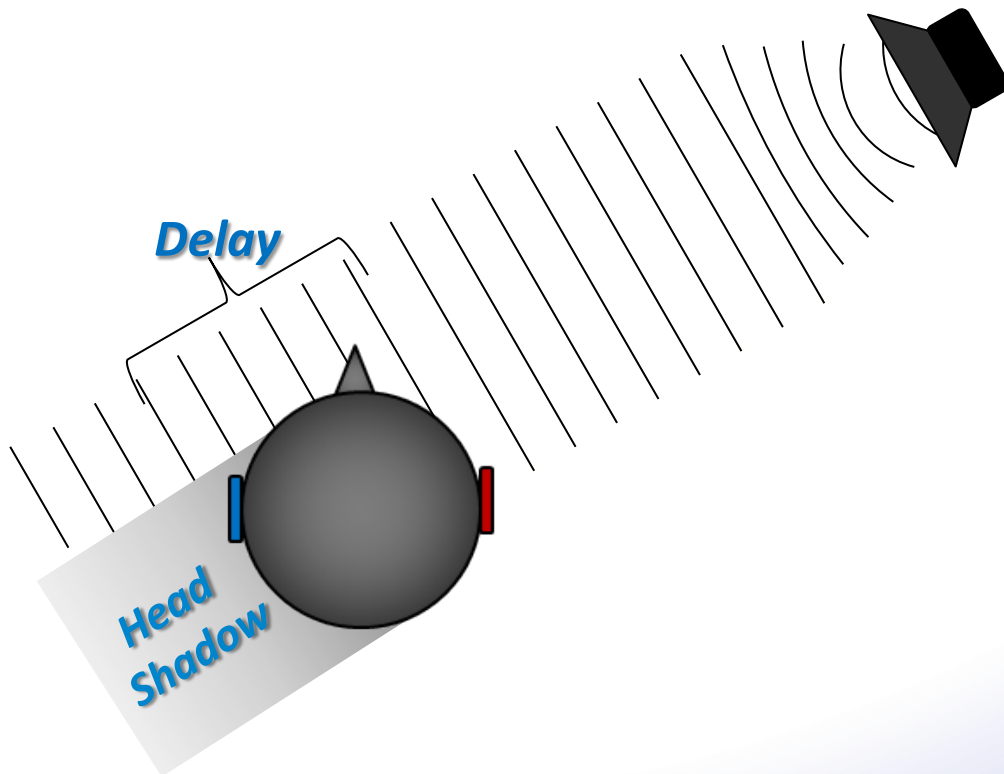


Spatial Hearing

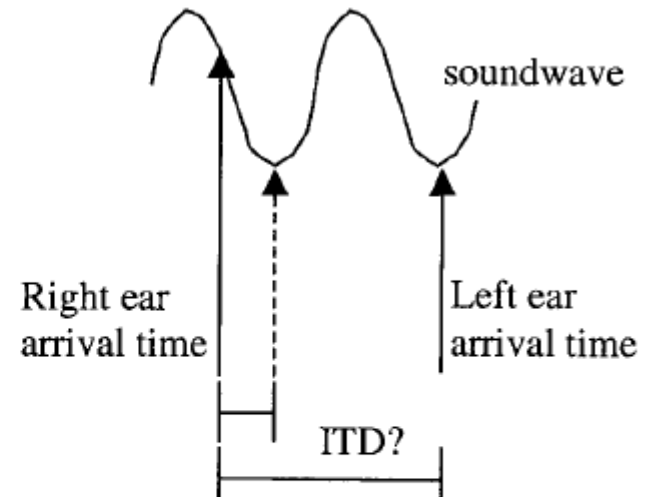


Interaural Time Difference (ITD)

- Sound arrives at near ear before far ear
- Results in a arrival and phase difference
- Becomes ambiguous at high frequencies



ITD

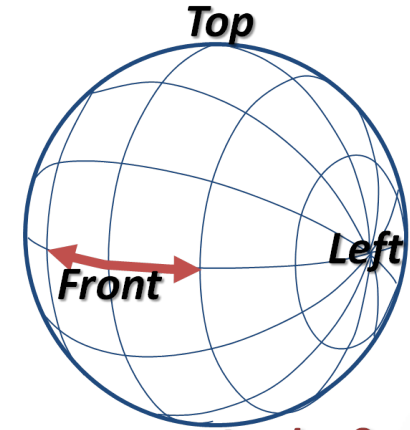
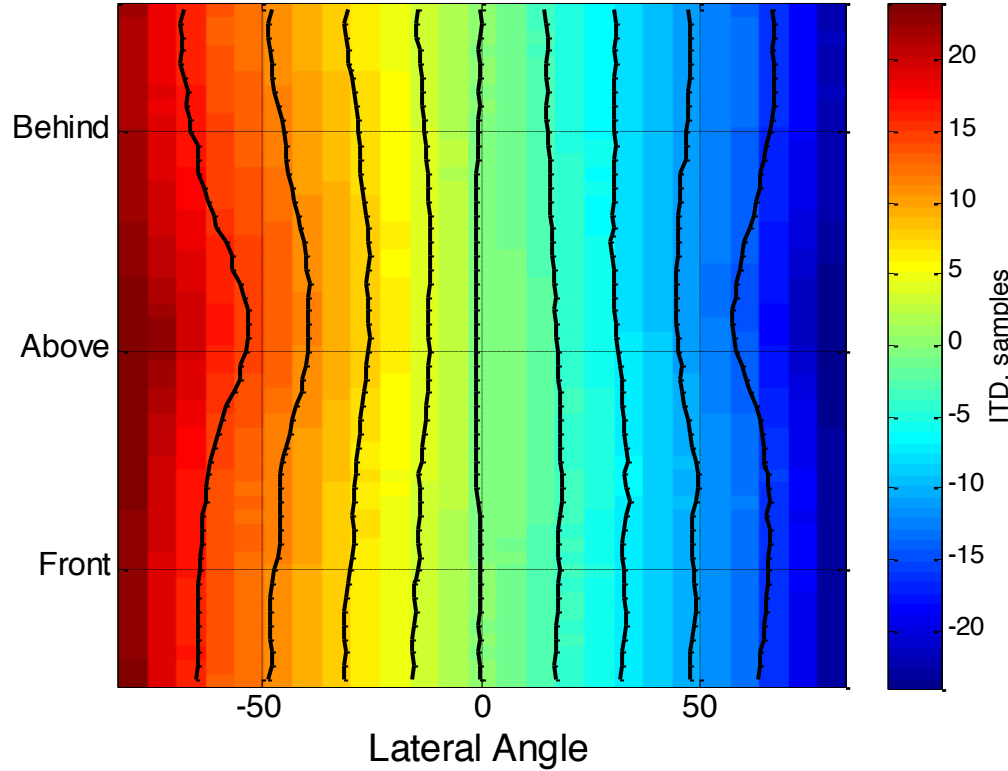




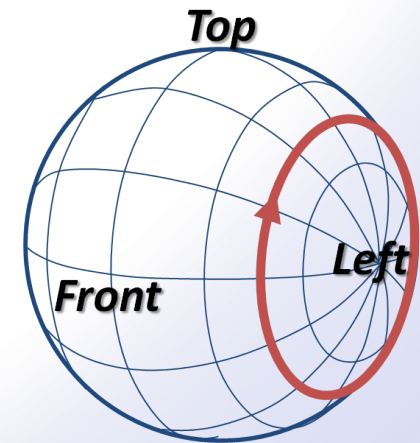
Spatial Hearing



Interaural Time Difference (ITD)



Lateral Angle, θ



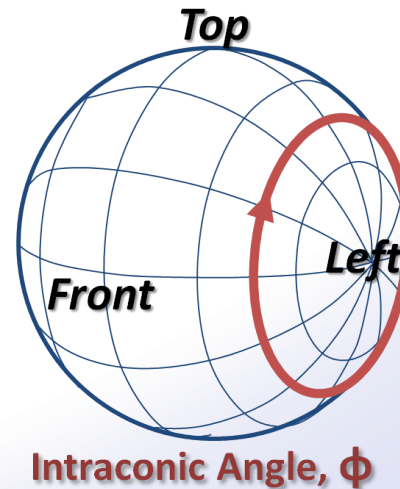
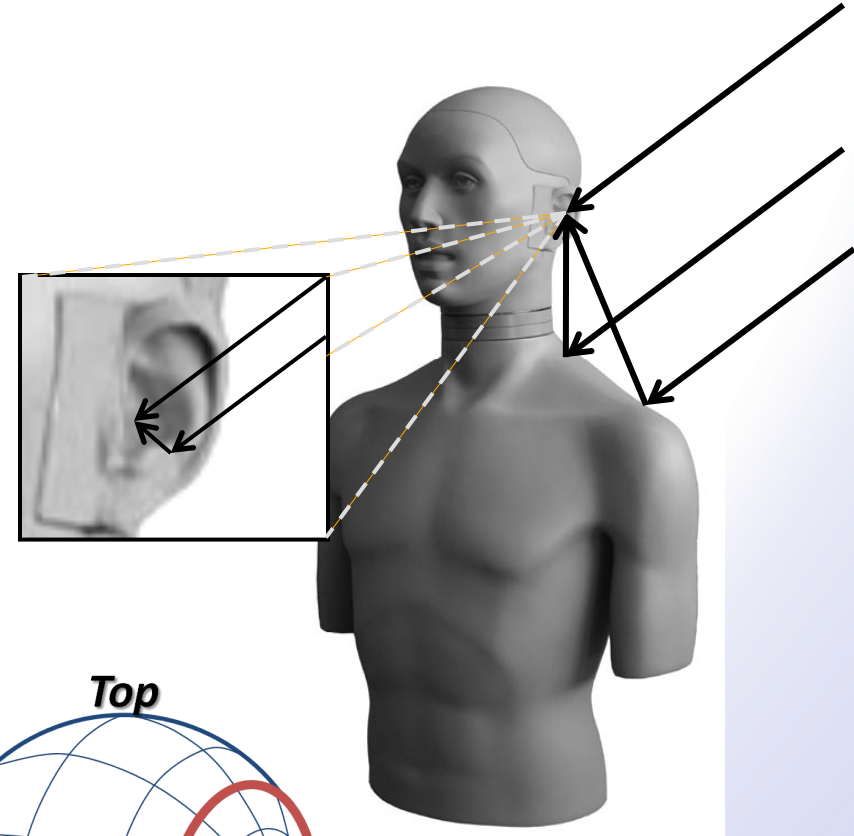
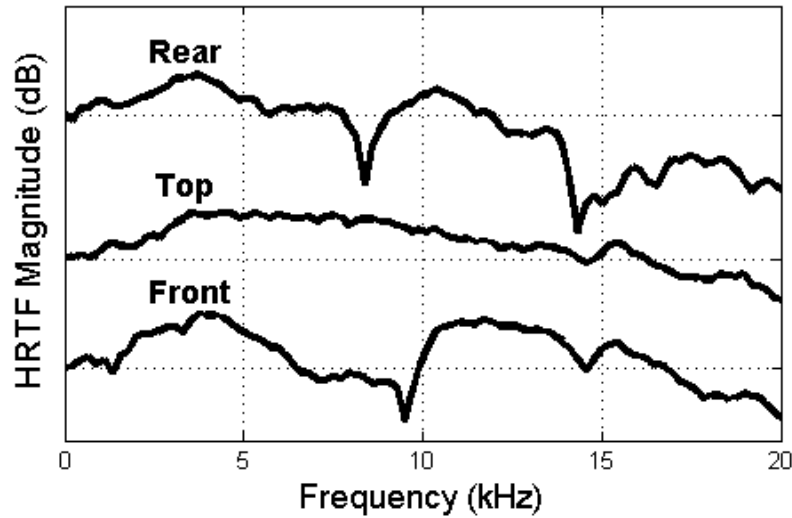
Intraconic Angle, ϕ



Spatial Hearing

Spectral Cues

- High frequency cues due to pinna
- Lower frequency cue due to shoulders
- Perceptually weighted to favor closer ear

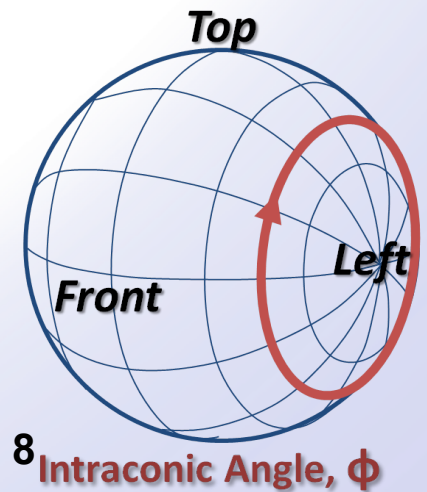
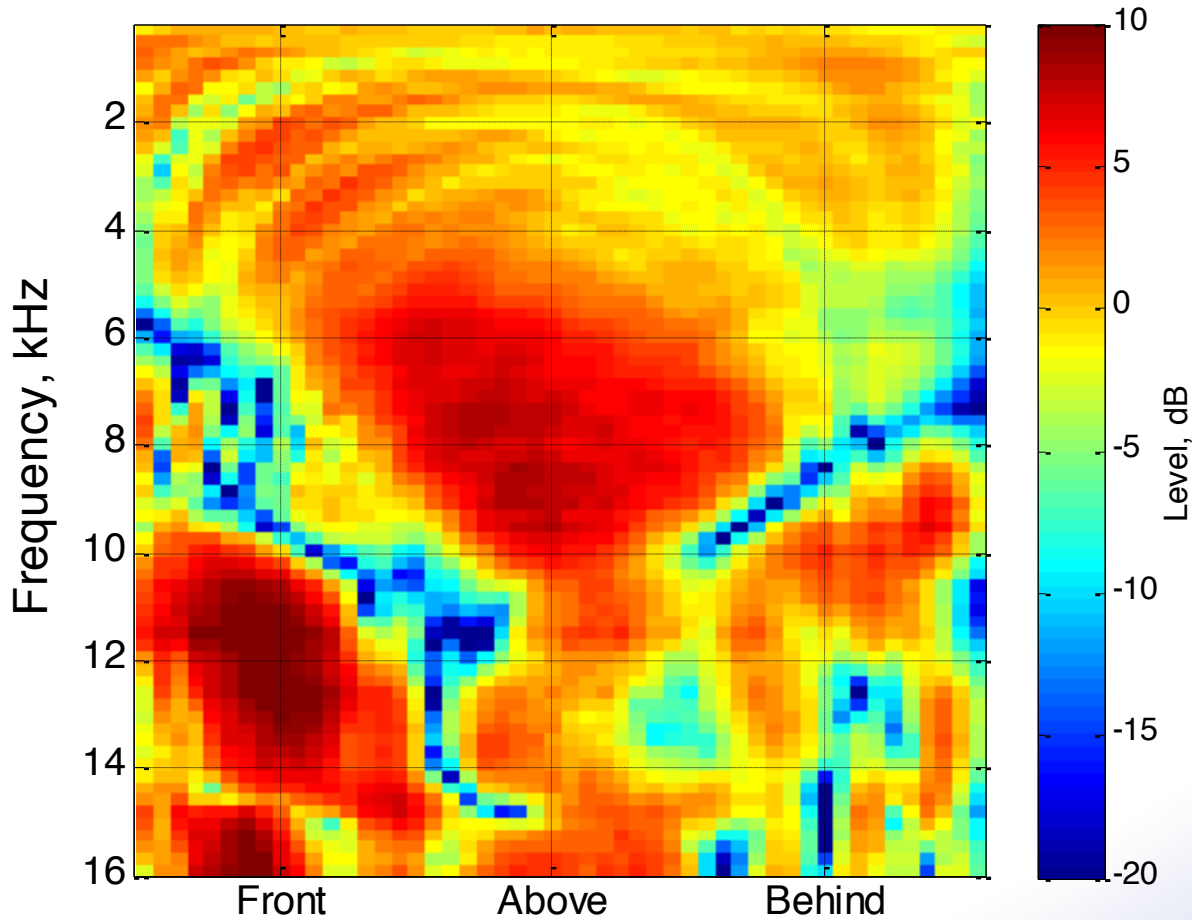




Spatial Hearing

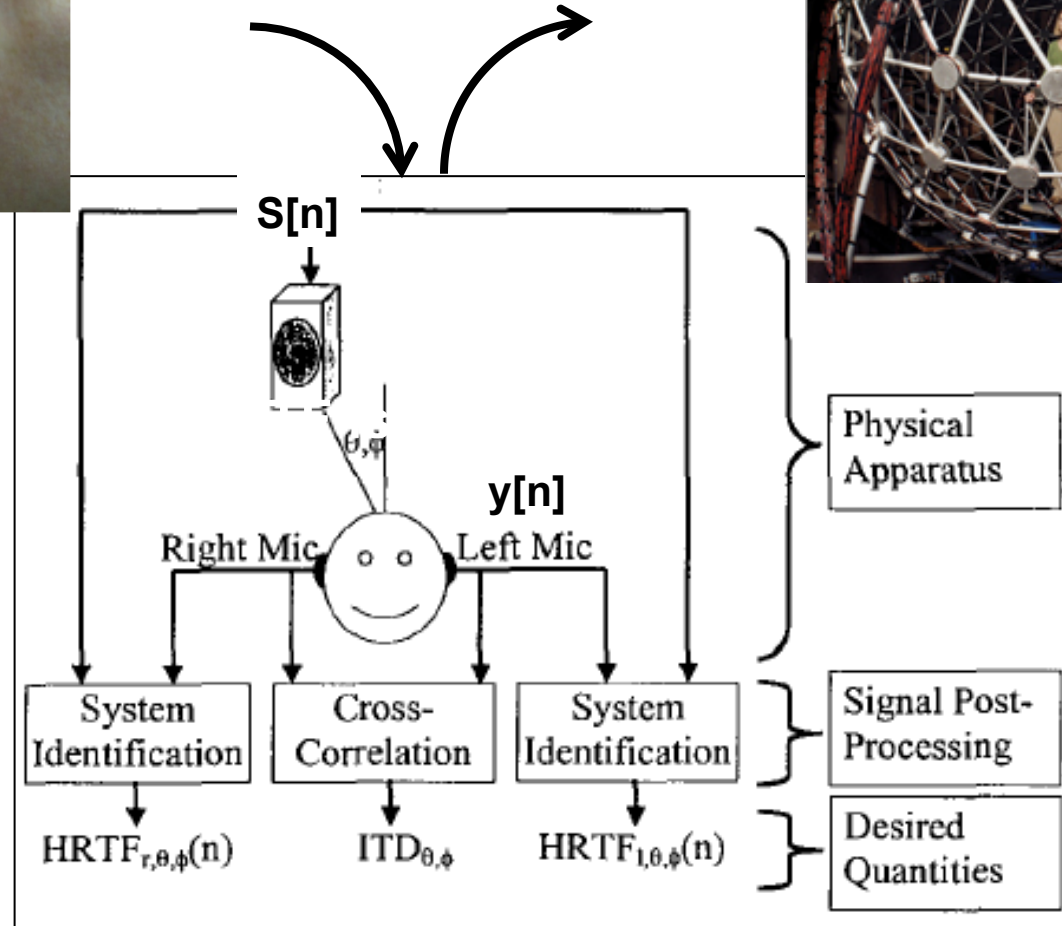
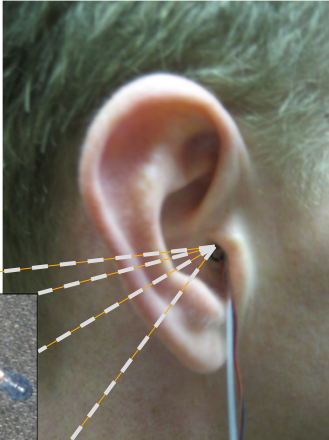


Spectral Cues



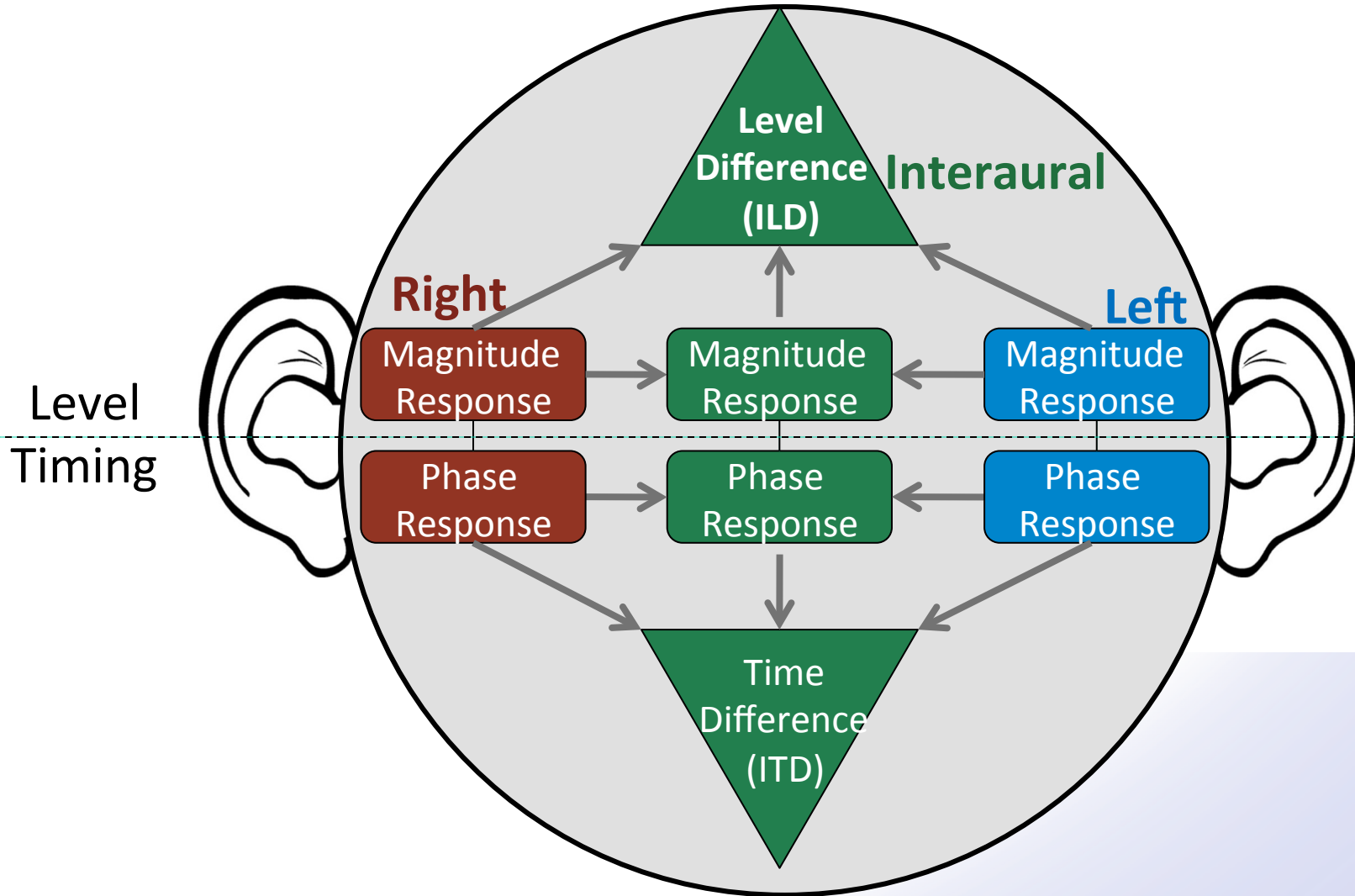


Head-Related Transfer Functions:



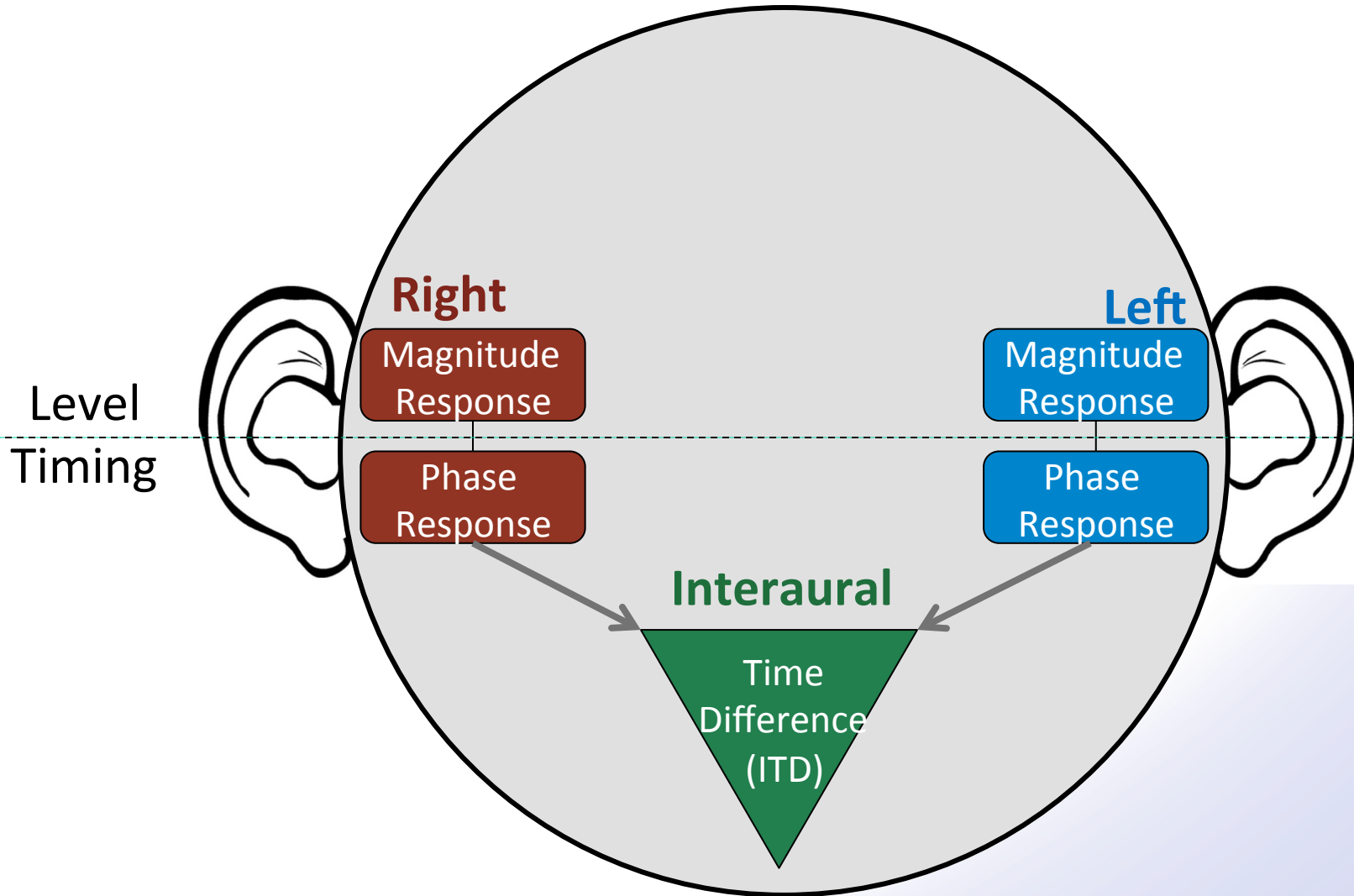


HRTF \leftrightarrow Spatial Hearing Cues



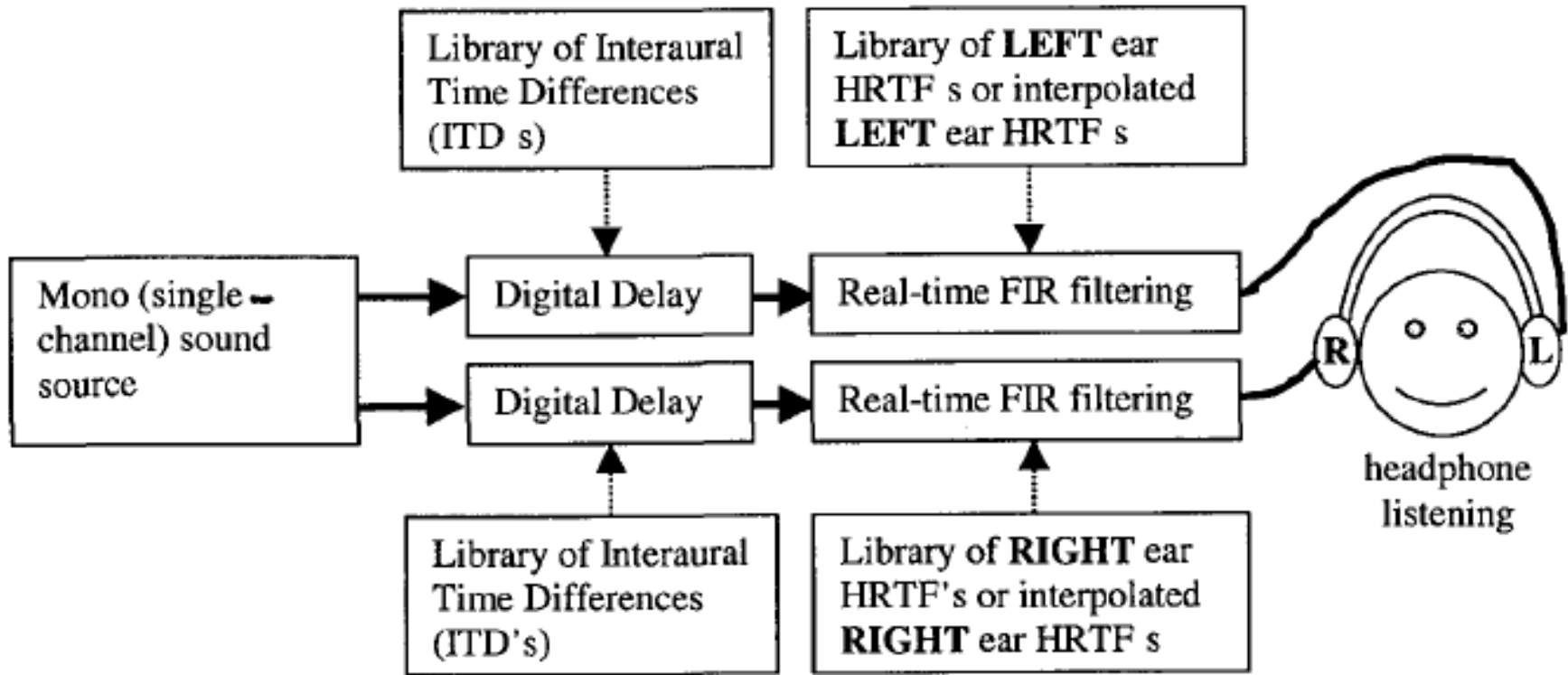


HRTF \leftrightarrow Spatial Hearing Cues





Binaural Synthesis





Spatial Auditory Displays:



Spatial Auditory Displays

- Guidance systems
- Hearing Restoration
- Virtual Reality
- Augmented Reality

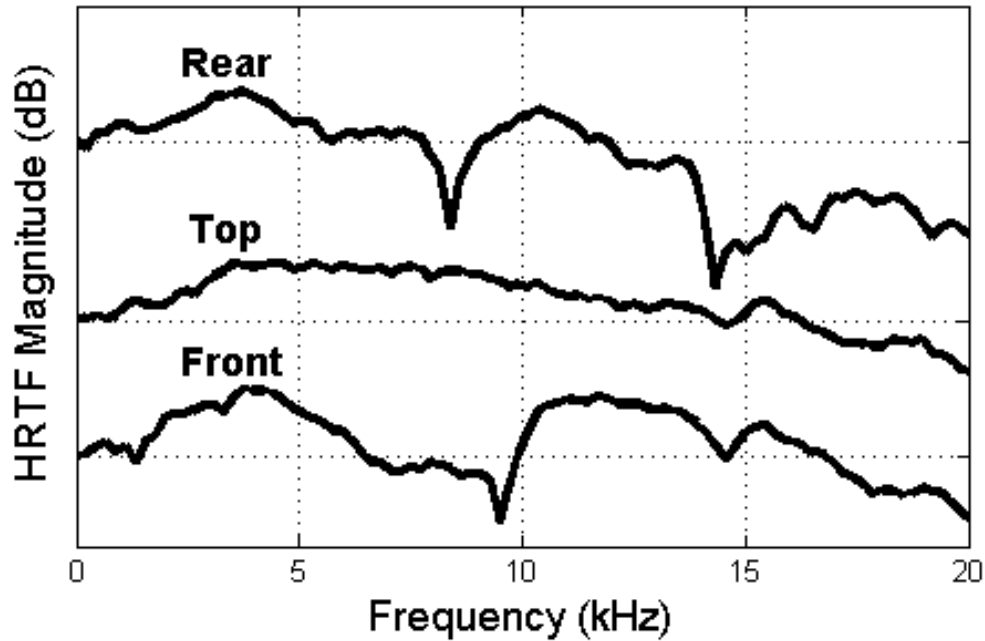




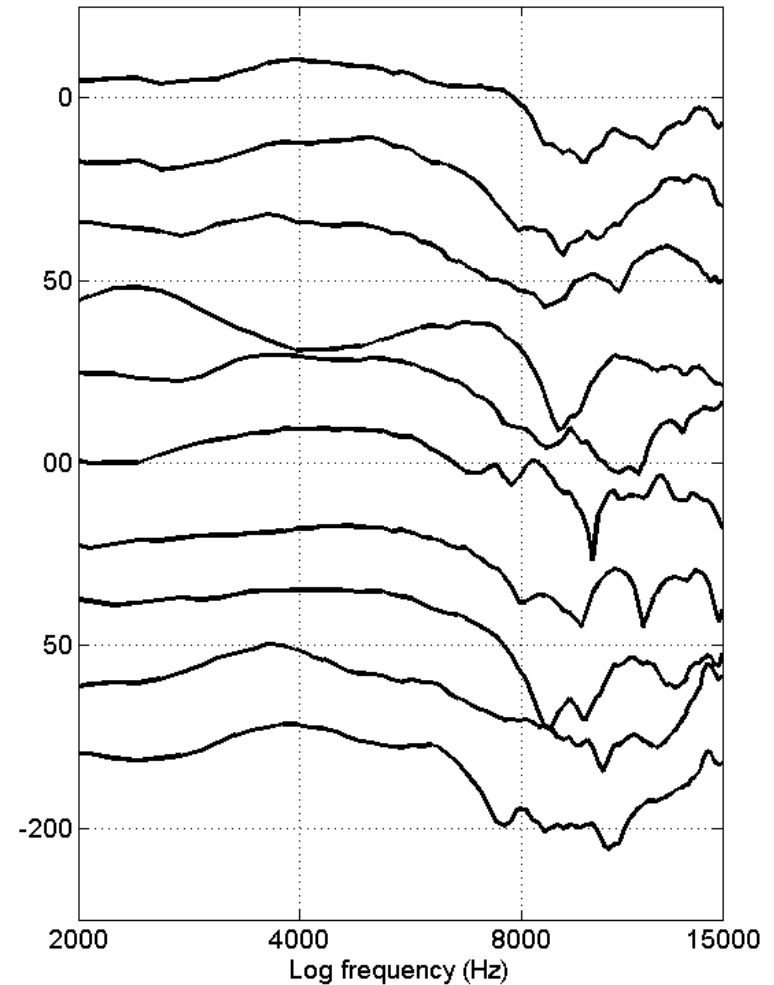
HRTFs: *Idiosyncrasy*



By location



By individual

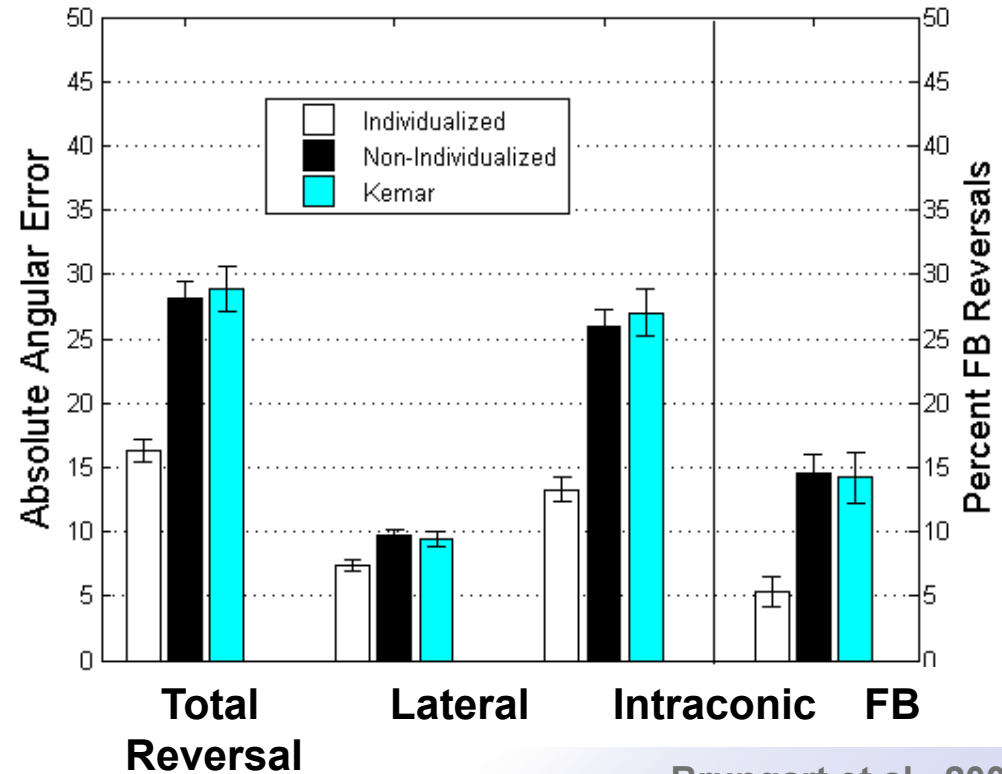
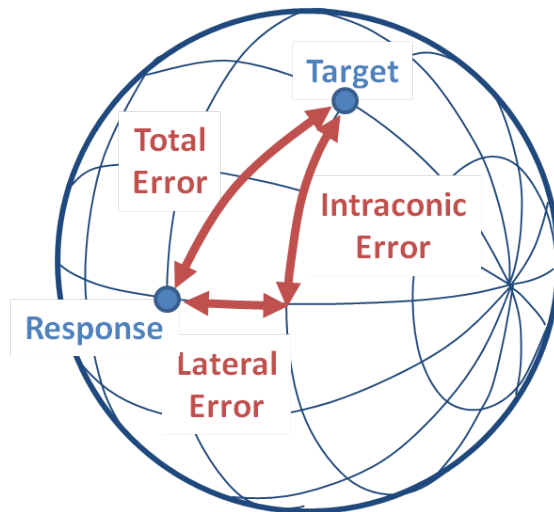




HRTFs: *Idiosyncrasy*



- SADs need Individual HRTFs
- Otherwise:
 1. No sense of elevation
 2. Frequent FB Reversals
 3. Localized “In the Head”



- Brungart et al., 2009



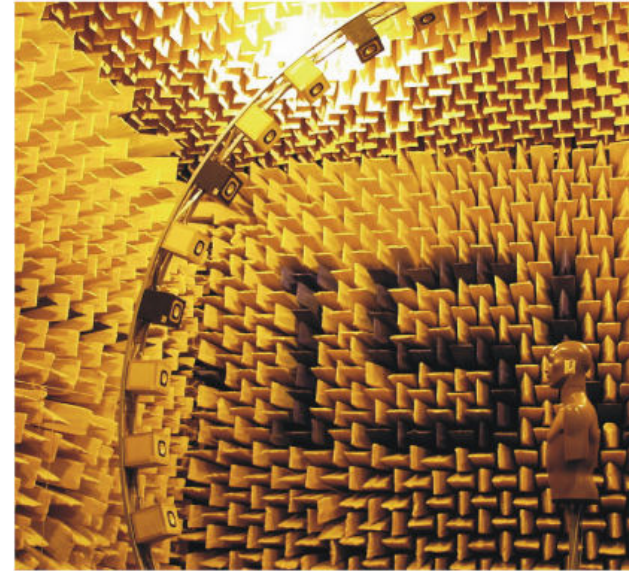
HRTFs: *Spatial Measurement*



Fixed Spherical Array



Rotating Arc Array



Pros: **Fast (5 – 10 min)**

Cheaper, Temporary

Cons: **Expensive, Permanent**

Slow (1 – 2 hours)



The Problem



How can we get an HRTF for every spatial angle with as few physical measurements as possible?



Previous Methods:

Parallel

Measurement

- Reciprocity
- Spectral asynchrony

- Same Equipment**
- Less Time**
- Perceptually Equivalent Performance**

Baseline HRTF

- 277 locations
- 256 taps

Non-Acoustic Interpolation

Naive

- Linear kNN
- Spherical Basis

Statistical

- Pattern Matching
- Neural Net

- Less Equipment**
- Less Time**
- Perceptually Equivalent Performance**

Subjective Selection

- Most Externalized
- Vertical Lift

Structural Models

- “Snowman”
- Anthropometric

Generalization

- Averaging
- Super Subject

- Least Equipment**
- Less Time**
- Poor Performance**

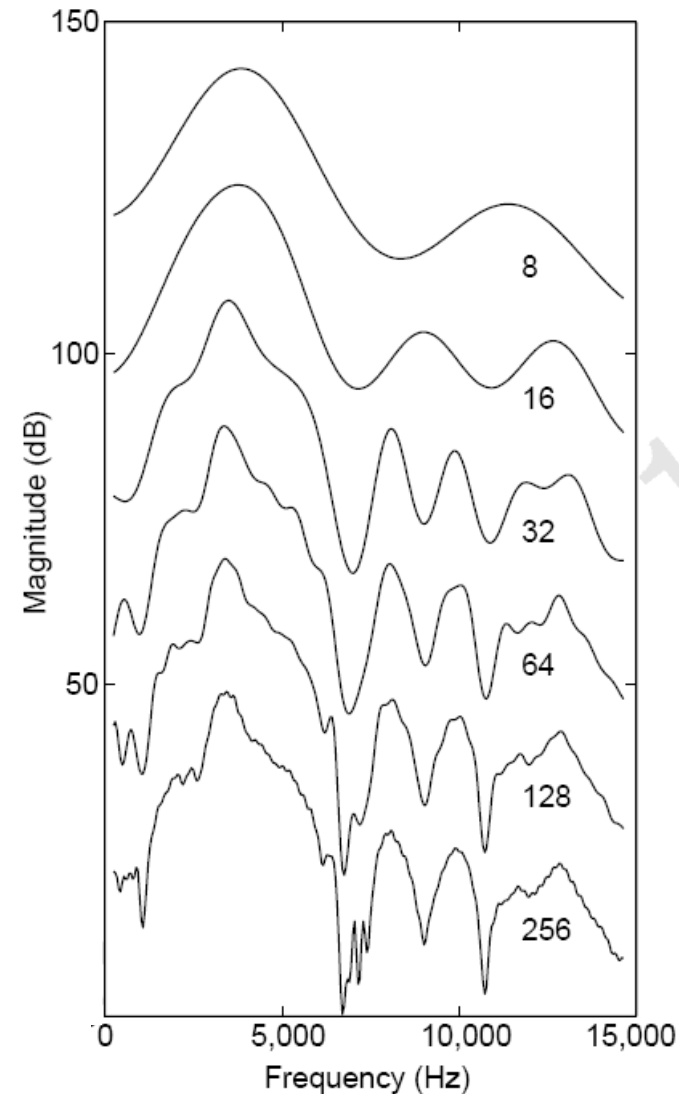


Irrelevant Spectral Details



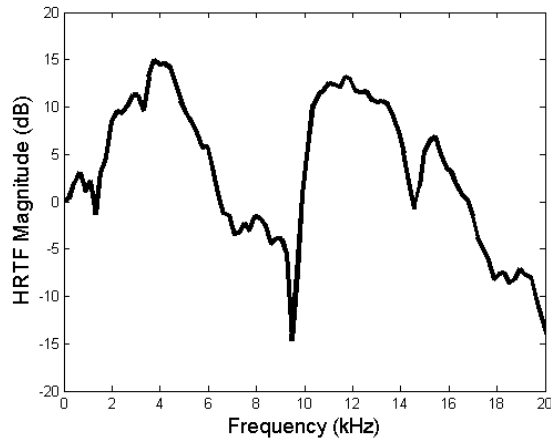
- Auditory system has limited spectral resolution
- This results in fine spectral details being averaged out
- Most impactful at high frequencies

Maybe we can get away with smoothing the spatial detail

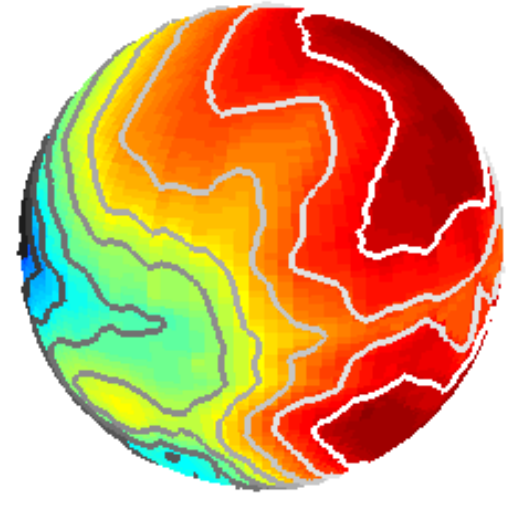




Spatial Representation:



$$|H_{\theta, \phi}(\omega)| \Leftrightarrow |H_{\omega}(\theta, \phi)|$$



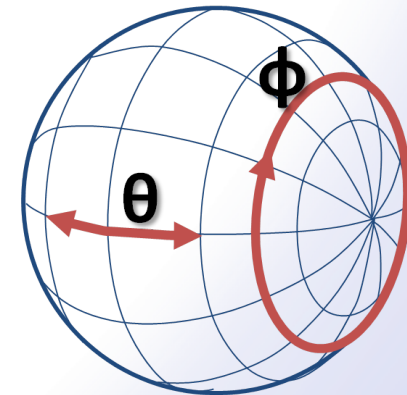
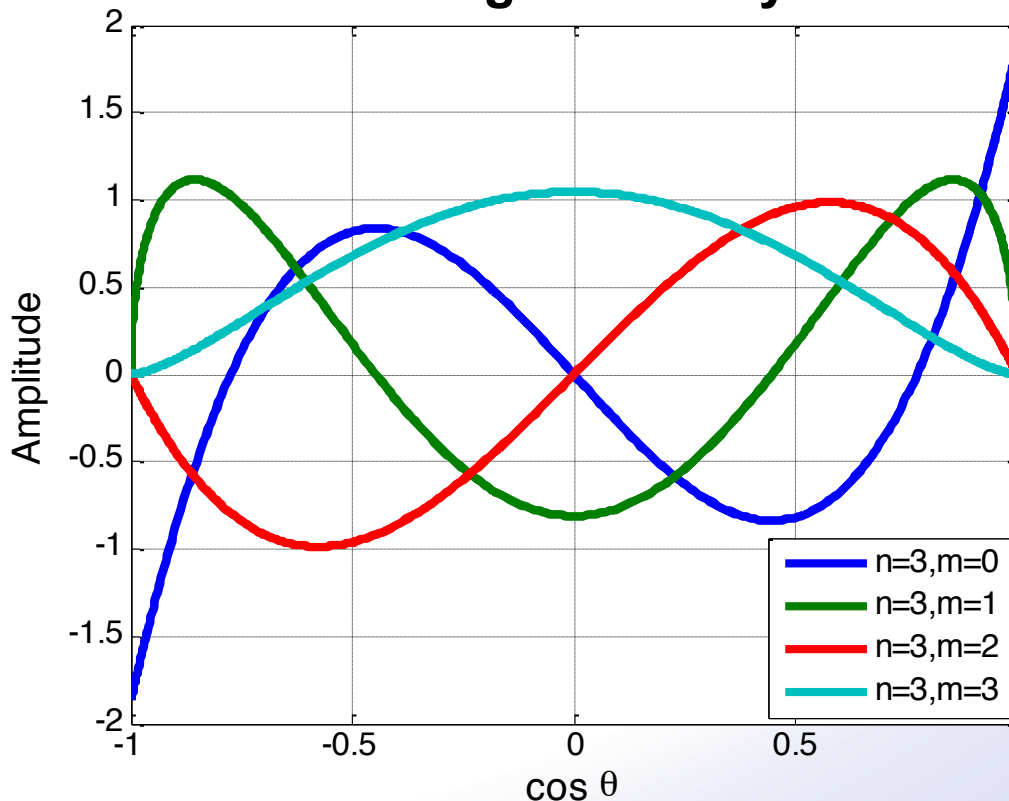


Spherical Harmonics



$$Y_{nm}(\phi, \theta) = \begin{cases} N_n^m P_n^m(\cos \theta) \cos(m\phi) & \text{if } m \geq 0 \\ N_n^m \underbrace{P_n^{|m|}(\cos \theta)} \sin(m\phi) & \text{if } m < 0 \end{cases}$$

Associated Legendre Polynomials



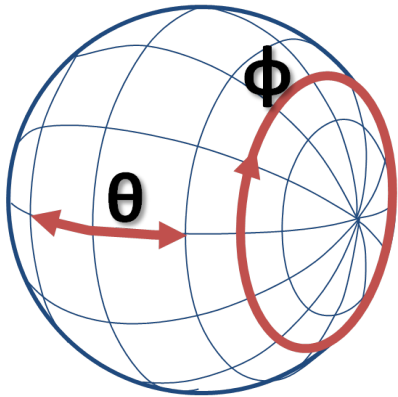
Orthogonal functions
for lateral angle



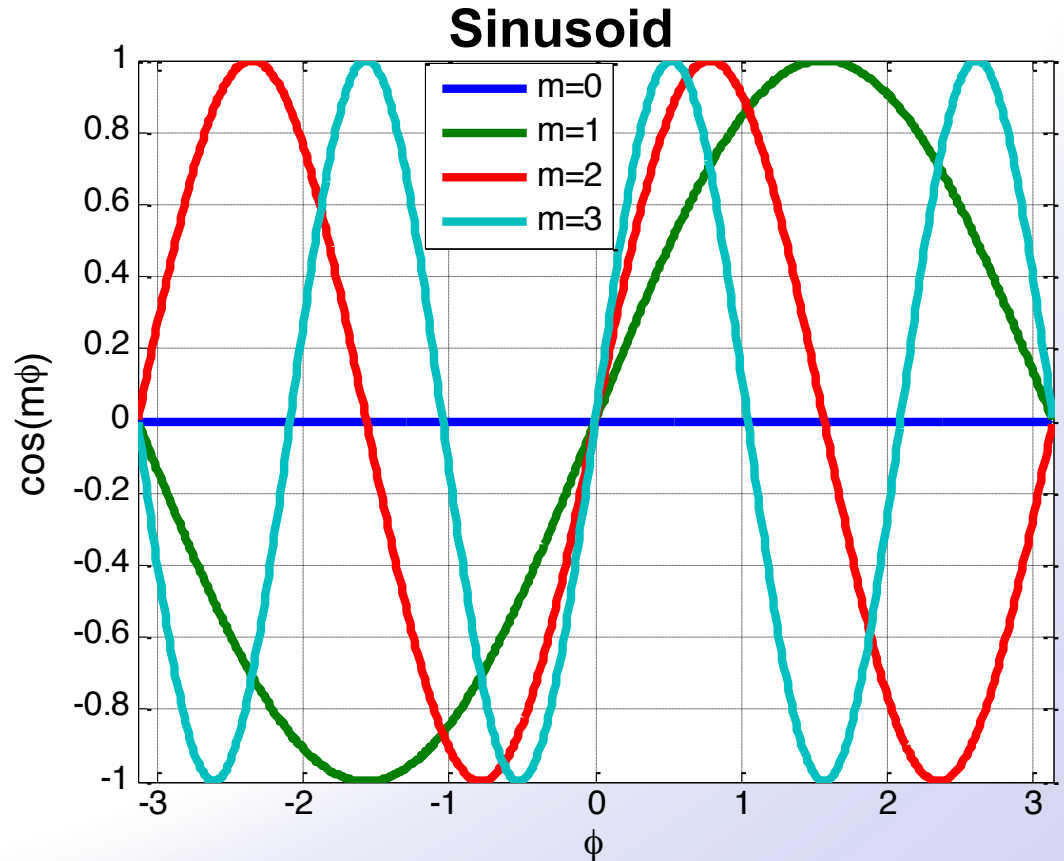
Spherical Harmonics



$$Y_{nm}(\phi, \theta) = \begin{cases} N_n^m P_n^m(\cos \theta) \cos(m\phi) & \text{if } m \geq 0 \\ N_n^m P_n^{|m|}(\cos \theta) \underbrace{\sin(m\phi)}_{\text{Sinusoid}} & \text{if } m < 0 \end{cases}$$



Orthogonal functions
in intraconic angle





Spherical Harmonics



Orthonormal basis over the continuous sphere

$$\int_{\theta=-\pi/2}^{\pi/2} \int_{\phi=-\pi}^{\pi} Y_{lnm}(\phi, \theta) Y_{l'n'm'}(\phi, \theta) d\Omega = \delta_{lnn'} \delta_{lmm'}$$

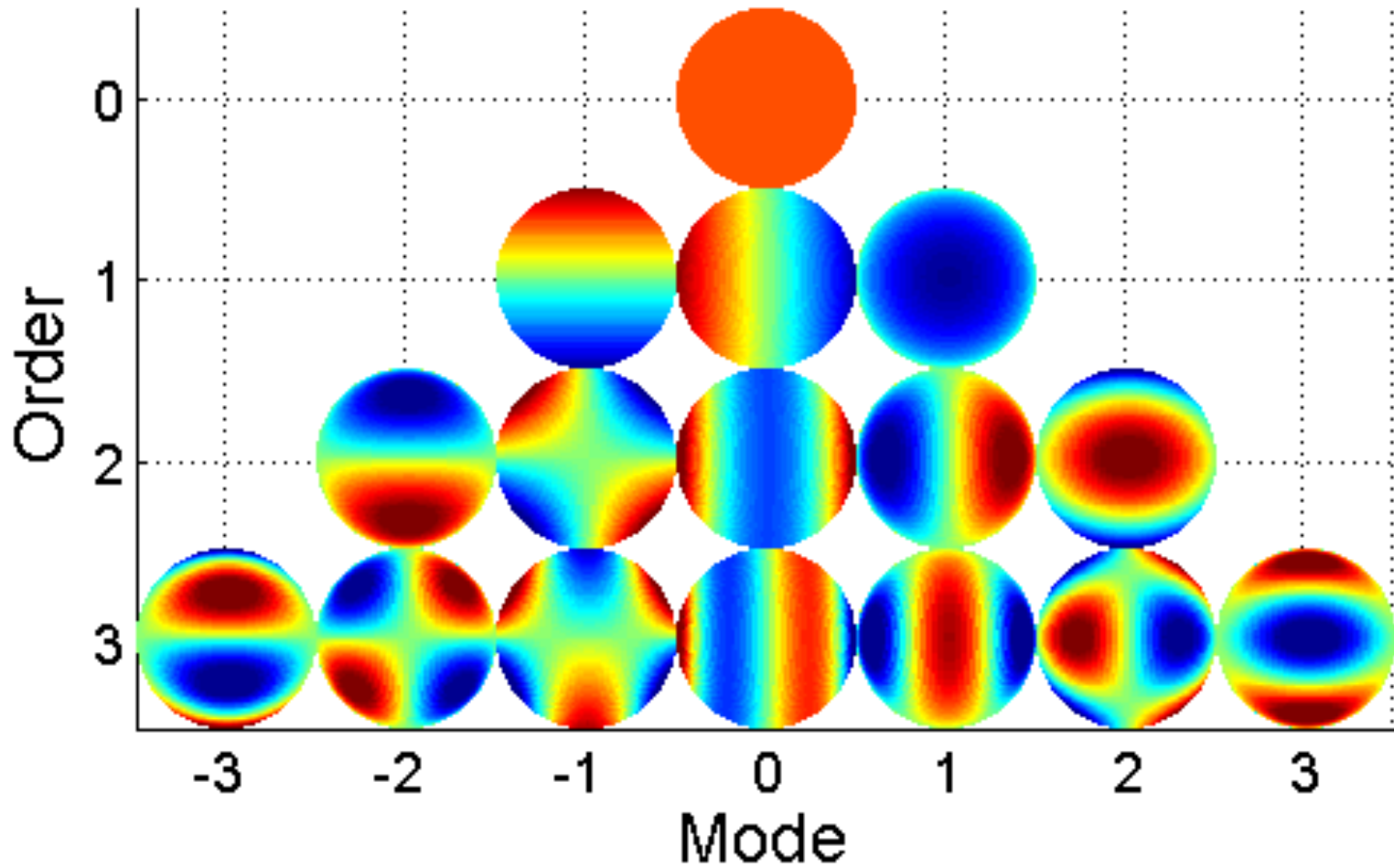
Allow us to represent any square integrable spherical function with a set of SH coefficients

$$f(\phi, \theta) = \sum_{n=0}^{\infty} \sum_{m=-n}^n Y_{nm}(\phi, \theta) C_{nm}$$

****** We can do Fourier analysis on a sphere ******



Spherical Harmonics





Practical SH Expansion



Re-cast problem into system of linear equations

$$\mathbf{f} = \mathbf{Y}\mathbf{c}$$

$$\text{where } \mathbf{f} = [f(\phi_0, \theta_0), f(\phi_1, \theta_1), \dots, f(\phi_S, \theta_S)]^T$$

$$\mathbf{c} = [C_{00}, C_{1-1}, C_{10}, C_{11}, \dots, C_{PP}]^T$$

$$\mathbf{Y} = \begin{bmatrix} Y_{00}(\phi_1, \theta_1) & Y_{-11}(\phi_1, \theta_1) & \cdots & Y_{PP}(\phi_1, \theta_1) \\ Y_{00}(\phi_2, \theta_2) & Y_{-11}(\phi_2, \theta_2) & \cdots & \vdots \\ \vdots & \vdots & \ddots & \vdots \\ Y_{00}(\phi_S, \theta_S) & Y_{-11}(\phi_S, \theta_S) & \cdots & Y_{PP}(\phi_S, \theta_S) \end{bmatrix}$$

Simple least-squares solution

$$\hat{\mathbf{c}} = (\mathbf{Y}^T \mathbf{Y})^{-1} \mathbf{Y}^T \mathbf{f}$$

**Truncation
Order**

**# of
samples**

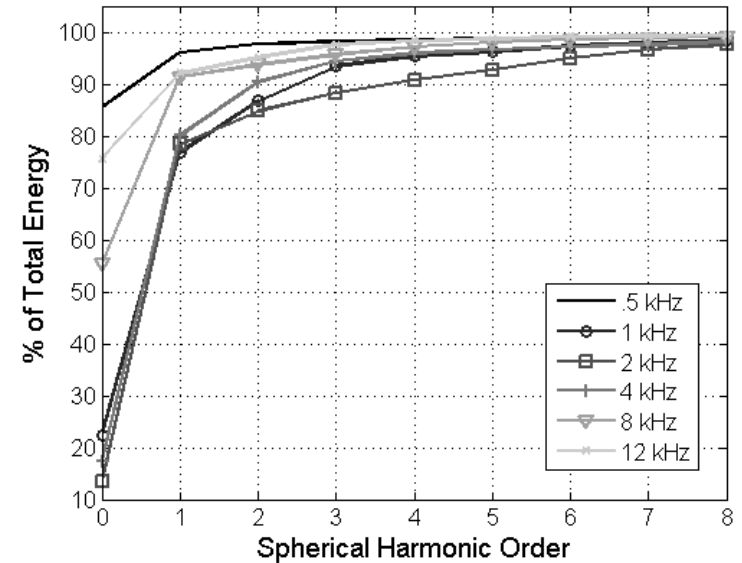


Spatial Smoothing:



Truncating the expansion provides spatial smoothing

$$f(\phi, \theta) = \sum_{n=0}^P \sum_{m=-n}^n Y_{nm}(\phi, \theta) C_{nm}$$



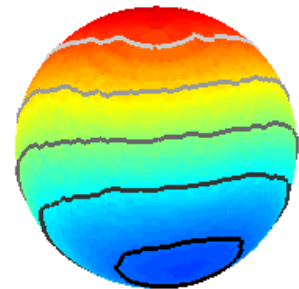
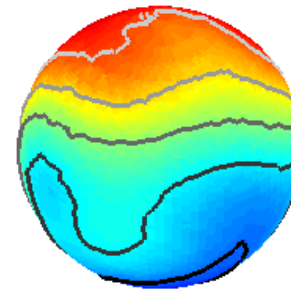
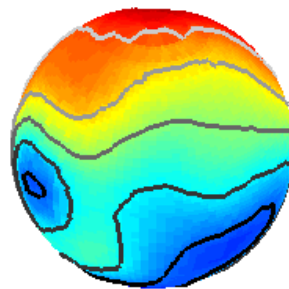
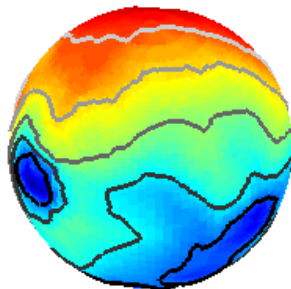
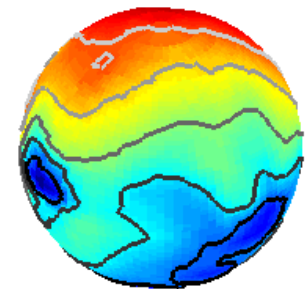
Full

12

6

4

2



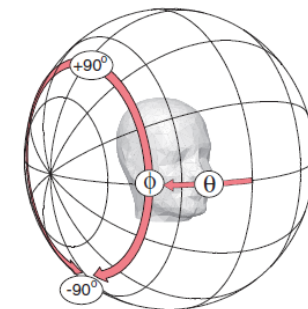
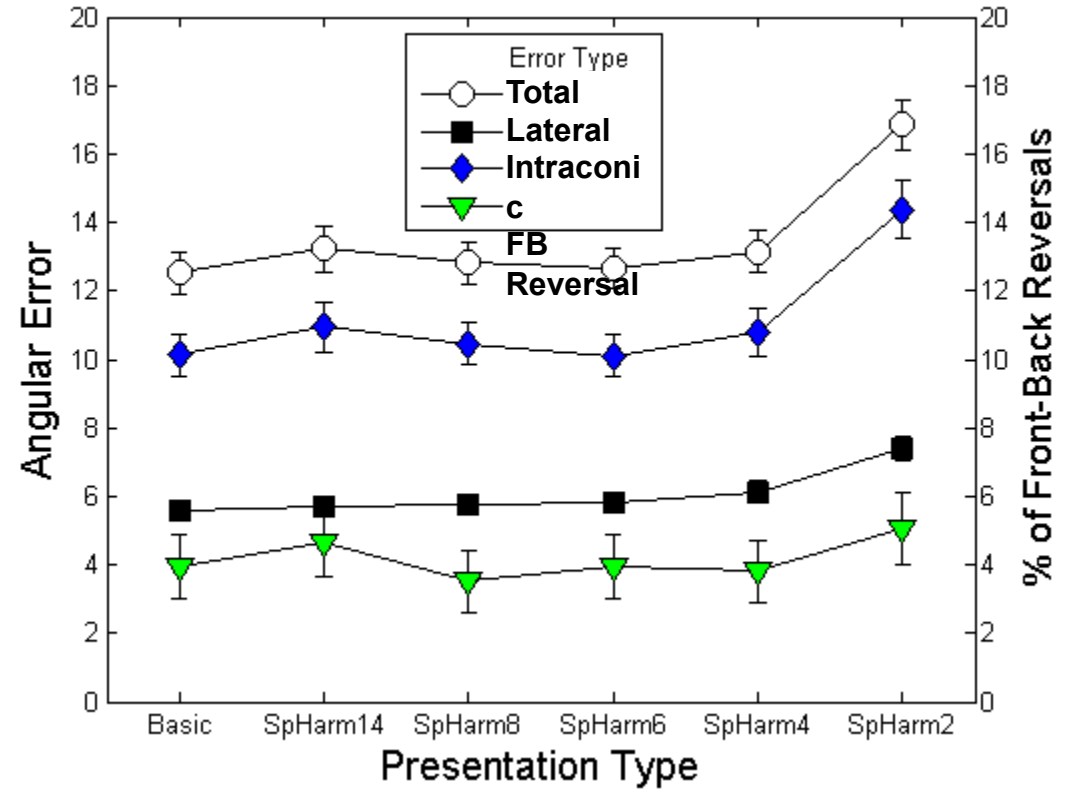


Perceptual Evaluation



Localization task

- 8 Subjects
- 250-ms noise bursts
- 245 locations





Recap...



- **New SH-based HRTF representation**
 - **Spatially continuous**
 - **Reduces irrelevant spatial variation**
 - **Localization equivalent to full HRTF**
 - **Reduces # of parameters by 95% w.r.t. baseline HRTF**

Can non-individualized HRTFs provide information about a new HRTF measurement?



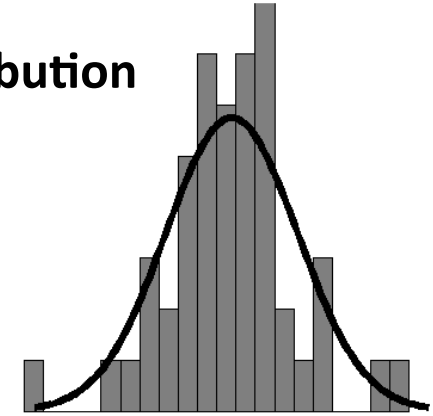
Bayesian HRTF Model



Model all HRTFs as belonging to the same underlying distribution

$$\mathbf{f} = \mathbf{Y}\mathbf{c} + \mathbf{n}$$

$$\left. \begin{array}{l} \mathbf{c} : \mathcal{N}(\mathbf{m}_c, \mathbf{R}_{cc}) \\ \mathbf{n} : \mathcal{N}(\mathbf{0}, \sigma^2 \mathbf{I}) \end{array} \right\} \text{Independent}$$



Non-individual information is incorporated through hyper-parameters

$$\left. \begin{array}{l} \mathbf{R}_{cc} = \begin{bmatrix} \sigma_{00}^2 & 0 & \cdots & 0 \\ 0 & \sigma_{-11}^2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \sigma_{PP}^2 \end{bmatrix} \\ \mathbf{m}_c = \begin{bmatrix} E[C_{00}] \\ E[C_{-11}] \\ \vdots \\ E[C_{PP}] \end{bmatrix} \end{array} \right\}$$



Bayesian Estimation



Estimation via MMSE Estimator

$$\hat{\mathbf{c}} = \mathbf{E}[\mathbf{c}|\mathbf{f}] = \mathbf{m}_c + \mathbf{R}_{cc} \mathbf{Y}^T (\mathbf{Y} \mathbf{R}_{cc} \mathbf{Y}^T + \sigma^2 \mathbf{I})^{-1} (\mathbf{f} - \mathbf{Y} \mathbf{m}_c)$$

↑
**Estimated SH
coefficients
for individual**

**Difference between
individual HRTF and average
HRTF at measurement
locations**

Estimator is based on how the HRTF is different from average...



Bayesian Estimation



Estimation via MMSE Estimator

$$\hat{c} = \mathbf{E}[c|f] = m_c + \underbrace{\mathbf{R}_{cc} \mathbf{Y}^T (\mathbf{Y} \mathbf{R}_{cc} \mathbf{Y}^T + \sigma^2 \mathbf{I})^{-1} (f - \mathbf{Y} m_c)}_{\text{Innovations from individualized measurements (bias)}}$$

Average SH
coefficients

Innovations from
individualized
measurements (bias)

Assuming hyper-parameters are already known...



Estimating Hyper-parameters



We have fixed unknown model parameters....

$$\mathbf{c} : \mathcal{N}(\mathbf{m}_c, \mathbf{R}_{cc})$$

Classical Estimation (MVUB)

$$\hat{\mathbf{m}}_c = \frac{1}{M} \sum_{i=1}^M \mathbf{c}_i$$

$$\hat{\sigma}_j^2 = \frac{1}{M-1} \sum_{i=1}^M (\mathbf{c}_i[j] - \hat{\mathbf{m}}_c[j])^2$$

$$\mathbf{R}_{cc} = \begin{bmatrix} \sigma_{00}^2 & 0 & \cdots & 0 \\ 0 & \sigma_{-11}^2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \sigma_{PP}^2 \end{bmatrix}$$

Assuming we have M individuals SH coefficients...



Estimating Hyper-parameters



We have fixed unknown model parameters....

$$\mathbf{c} : \mathcal{N}(\mathbf{m}_c, \mathbf{R}_{cc})$$

Classical Estimation (MVUB)

$$\hat{\mathbf{m}}_c = \frac{1}{M} \sum_{i=1}^M \mathbf{c}_i$$

$$\hat{\sigma}_j^2 = \frac{1}{M-1} \sum_{i=1}^M (\mathbf{c}_i[j] - \hat{\mathbf{m}}_c[j])^2$$

But we can't measure SH coefficients. We need a way to estimate both simultaneously.

$$\mathbf{R}_{cc} = \begin{bmatrix} \sigma_{00}^2 & 0 & \cdots & 0 \\ 0 & \sigma_{-11}^2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \sigma_{PP}^2 \end{bmatrix}$$

Assuming we have M individuals' SH coefficients...



Expectation-Maximization



Compute parameters and hyper-parameters iteratively

1. Initialize \mathbf{R}_{cc} and \mathbf{m}_c to arbitrary values
2. Calculate Bayesian estimates of SH coefficients

$$\hat{\mathbf{c}} = \mathbf{m}_c + \mathbf{R}_{cc} \mathbf{Y}^T (\mathbf{Y} \mathbf{R}_{cc} \mathbf{Y}^T + \sigma^2 \mathbf{I})^{-1} (\mathbf{f} - \mathbf{Y} \mathbf{m}_c)$$

3. Update estimates of \mathbf{R}_{cc} and \mathbf{m}_c using new coefficient values

$$\hat{\mathbf{m}}_c = \frac{1}{M} \sum_{i=1}^M \mathbf{c}_i \quad \hat{\sigma}_j^2 = \frac{1}{M-1} \sum_{i=1}^M (\mathbf{c}_i[j] - \hat{\mathbf{m}}_c[j])^2$$

4. Repeat 2 and 3 until estimates converge



Computational Performance

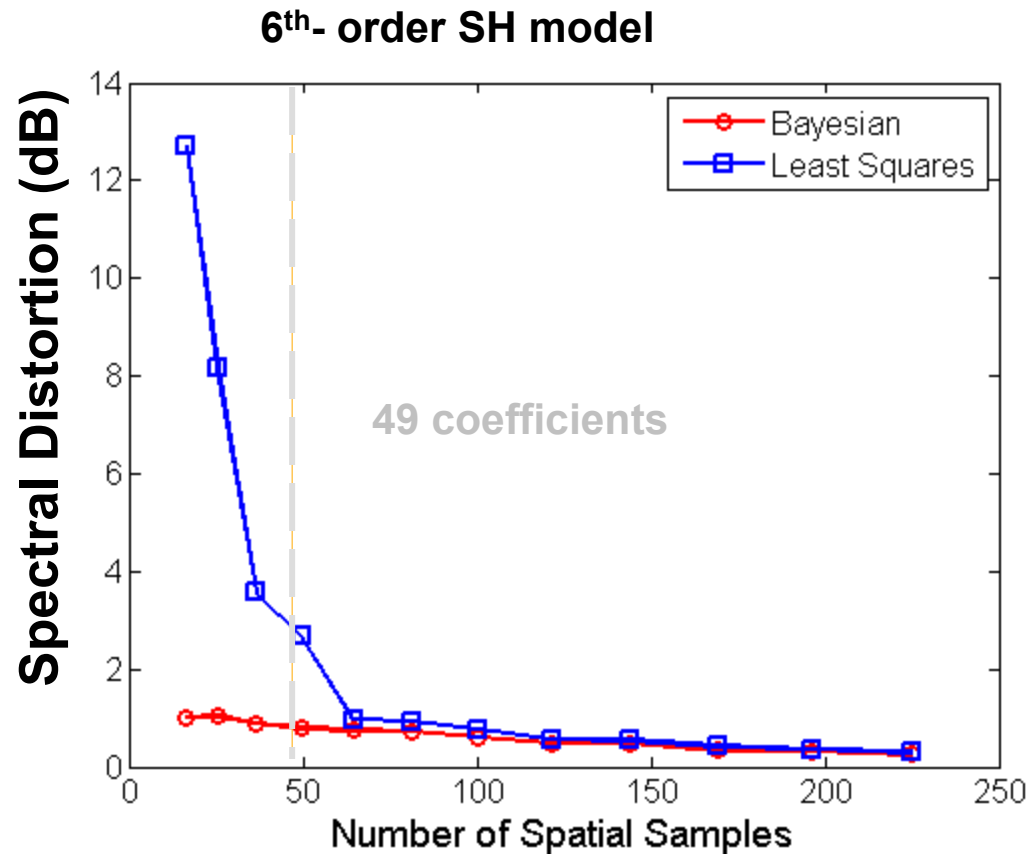


Training the model

- EM based
- 44 subjects
- 274 spatial samples

Testing the model

- Bayesian estimation
- 10 subjects
- varied # of samples



**Better reconstruction
performance with fewer
spatial samples**



Computational Performance



277

100

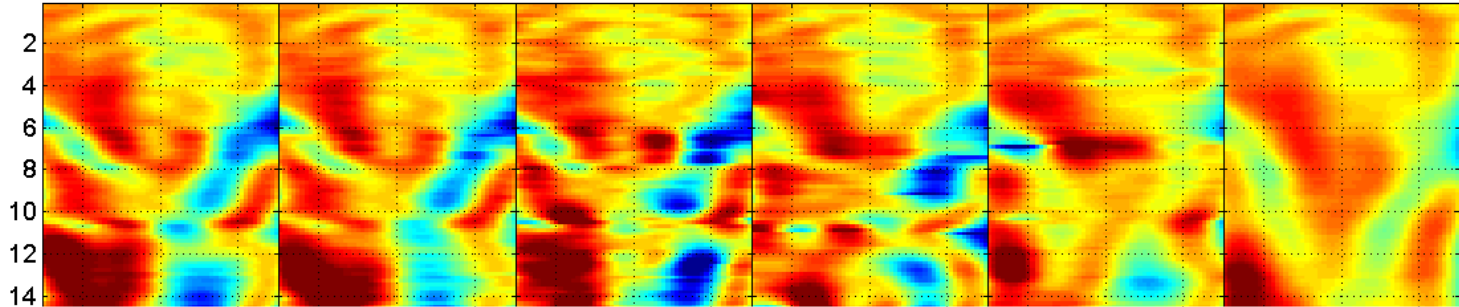
25

12

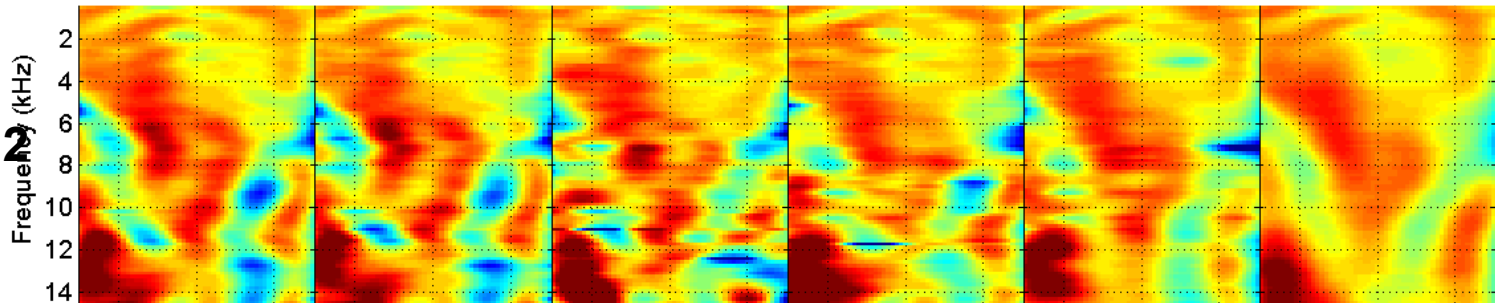
6

0

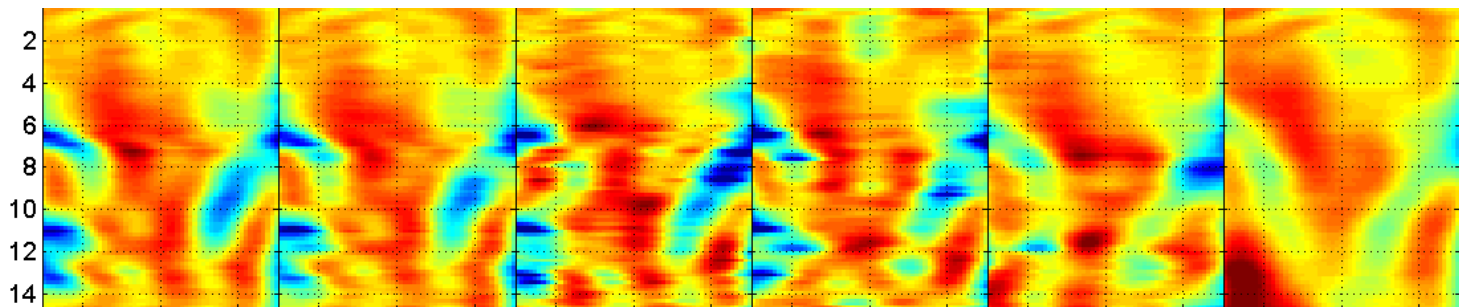
Subject 1



Subject 2



Subject 3



Front AboveBehind Front AboveBehind Front AboveBehind Front AboveBehind Front AboveBehind Front AboveBehind

36

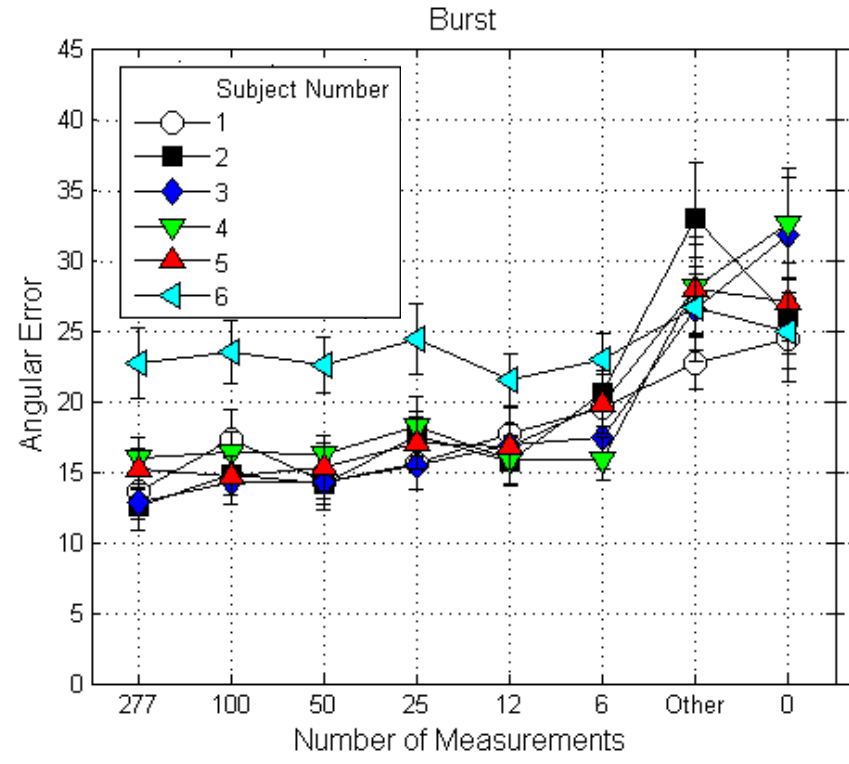


Perceptual Evaluation



Localization Task

- 6 Subjects
- 250-ms noise bursts
- 245 locations



**Equivalent performance with
as few as 12 measurements**



Recap...



- **Bayesian HRTF model**
 - Models general HRTF distribution as MVN
 - Individualized HRTF represents a single sample
- **Bayesian HRTF Estimation**
 - Non-individualized HRTFs provide “template”
 - Individualized measurements personalize the template
 - Much fewer measurements are needed (~ 12 distributed)

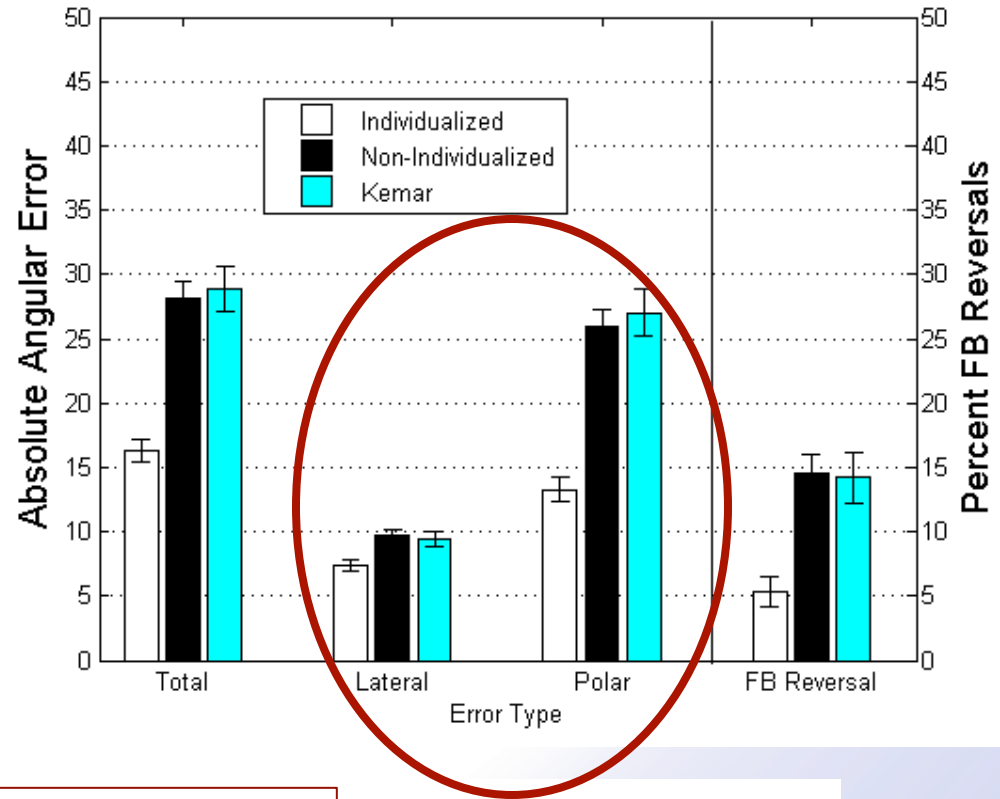
How do HRTFs differ amongst individuals?



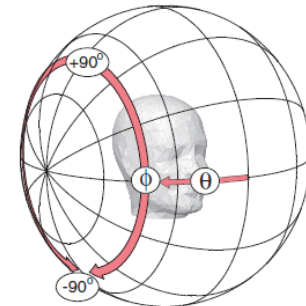
Further Model Reduction



- Non-individual localization is bad mostly in polar dimension
- Implies inter-subject differences in HRTFs account for polar cue difference

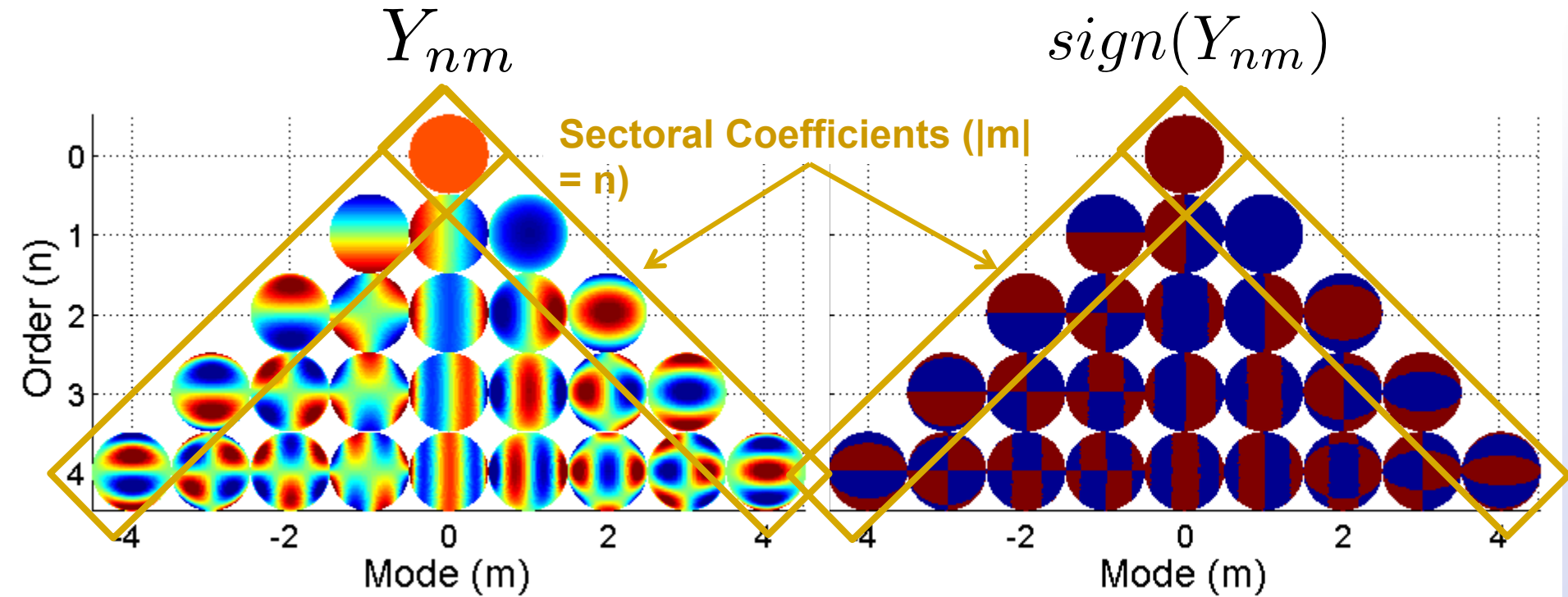


If we can separate out polar cues we might only need to estimate those!





Further Model Reduction



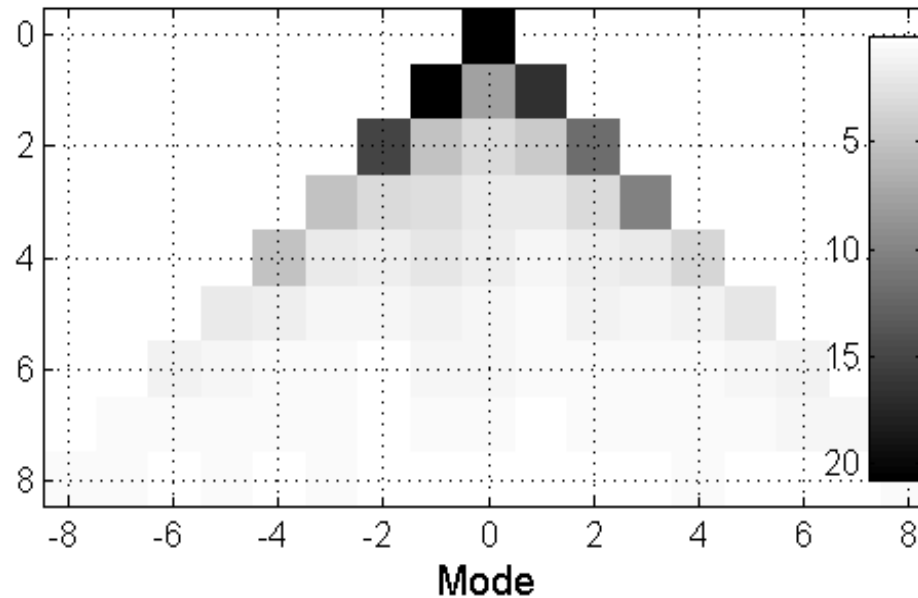
Sectoral coefficients capture mostly intraconic variation



Further Model Reduction



Inter-subject Variance



Sectoral coefficients contain most of the inter-subject variance

These coefficients may be all that need to be individualized

41



Sectoral HRTF Model:



Separate individual (Sectoral) and non-individual (Lateral) features.

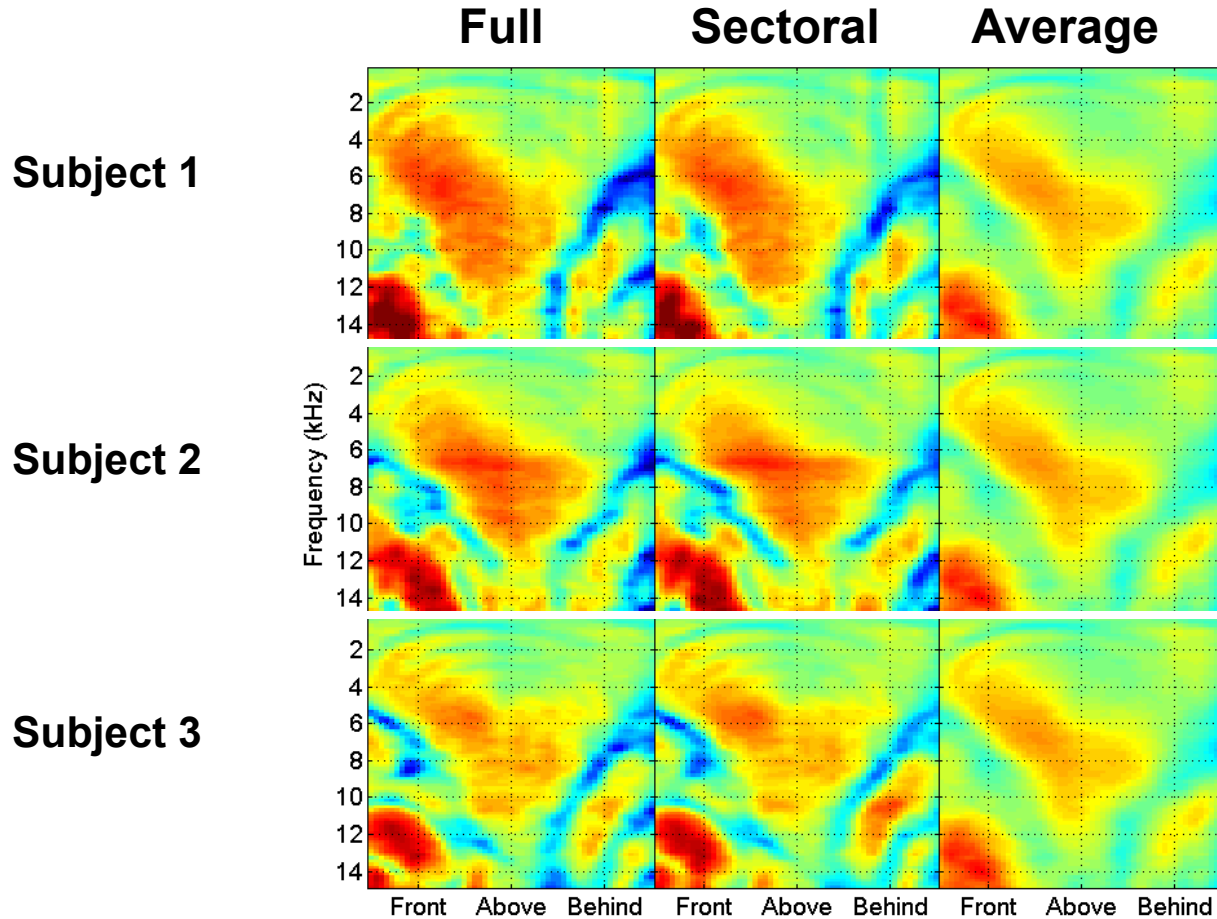
$$\begin{aligned} \mathbf{h} &= \mathbf{h}_{\text{Sec}} + \mathbf{h}_{\text{Lat}} \\ &= \mathbf{Y}_{\text{Sec}} \mathbf{c}_{\text{Sec}} + \mathbf{Y}_{\text{Lat}} \bar{\mathbf{c}}_{\text{Lat}} \end{aligned}$$

Sectoral Basis Functions *Sectoral Coefficients* *Lateral Basis Functions* *Average Lateral Coefficients*

Only sectoral coefficients need to be estimated. The rest can be average values.



Sectoral HRTF Model:



Sectoral model does capture the intraconic HRTF features



Estimating the Sectoral HRTF:



Estimate Sectoral HRTF with average lateral coefficients.

$$\begin{aligned}\hat{\mathbf{h}}_{\text{Sec}} &\approx \mathbf{h} - \mathbf{Y}_{\text{Lat}} \bar{\mathbf{c}}_{\text{Lat}} \\ &\approx \mathbf{Y}_{\text{Sec}} \mathbf{c}_{\text{Sec}}\end{aligned}$$

*Average
Coefficients*

Now use Bayesian technique with Sectoral basis functions.

$$\begin{aligned}\hat{\mathbf{c}}_{\text{Sec}} &= E[\mathbf{c} | \mathbf{h}_{\text{Sec}}] \\ &= \bar{\mathbf{c}}_{\text{Sec}} + \mathbf{R}_{\text{Sec}} \mathbf{Y}_{\text{Sec}}^T (\mathbf{Y}_{\text{Sec}} \mathbf{R}_{\text{Sec}} \mathbf{Y}_{\text{Sec}}^T + \sigma^2 \mathbf{I})^{-1} (\hat{\mathbf{h}}_{\text{Sec}} - \mathbf{Y}_{\text{Sec}} \bar{\mathbf{c}}_{\text{Sec}})\end{aligned}$$

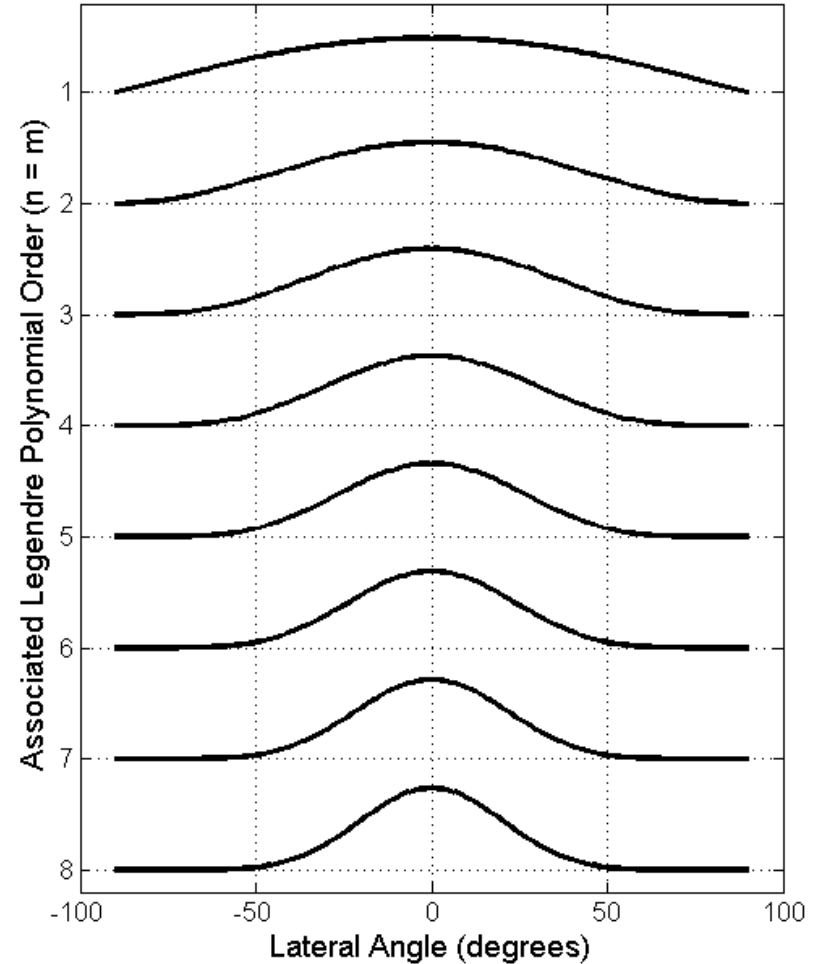
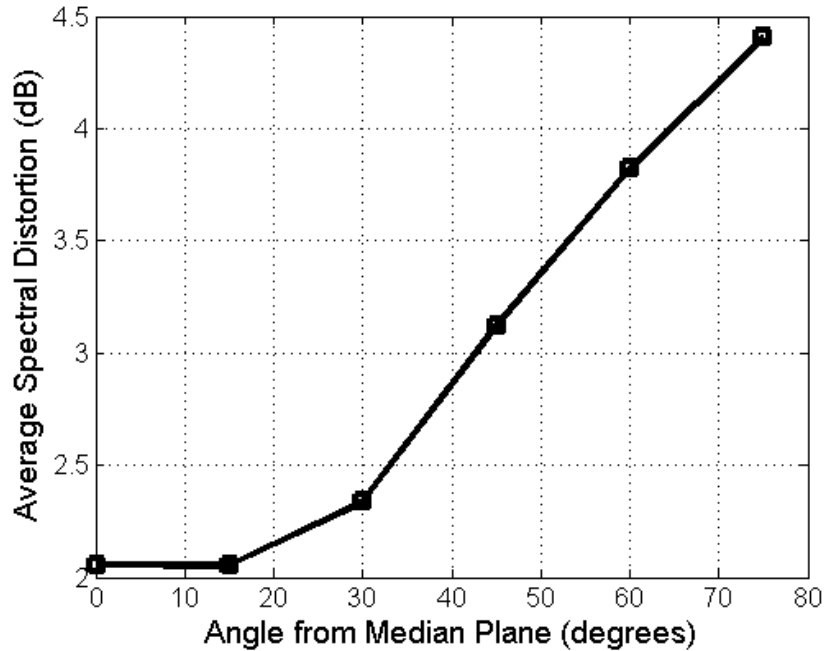
Estimated Sectoral HRTF



Why the median plane?



- Bad DC estimate off midline
- Sectoral harmonics contain no energy off the midline at high orders



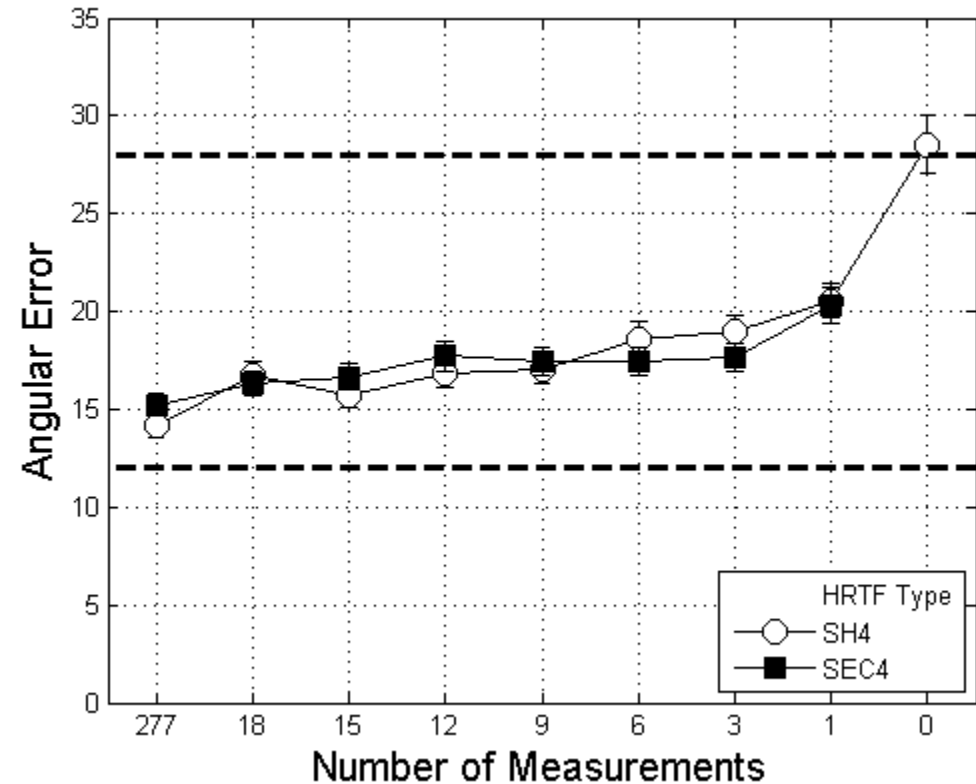


Perceptual Evaluation



Localization Task

- 6 Subjects
- 250-ms noise bursts
- 245 locations
- HRTFs
 - Full 4th-Order (SH4)
 - 4th-Order Sectoral (SEC4)

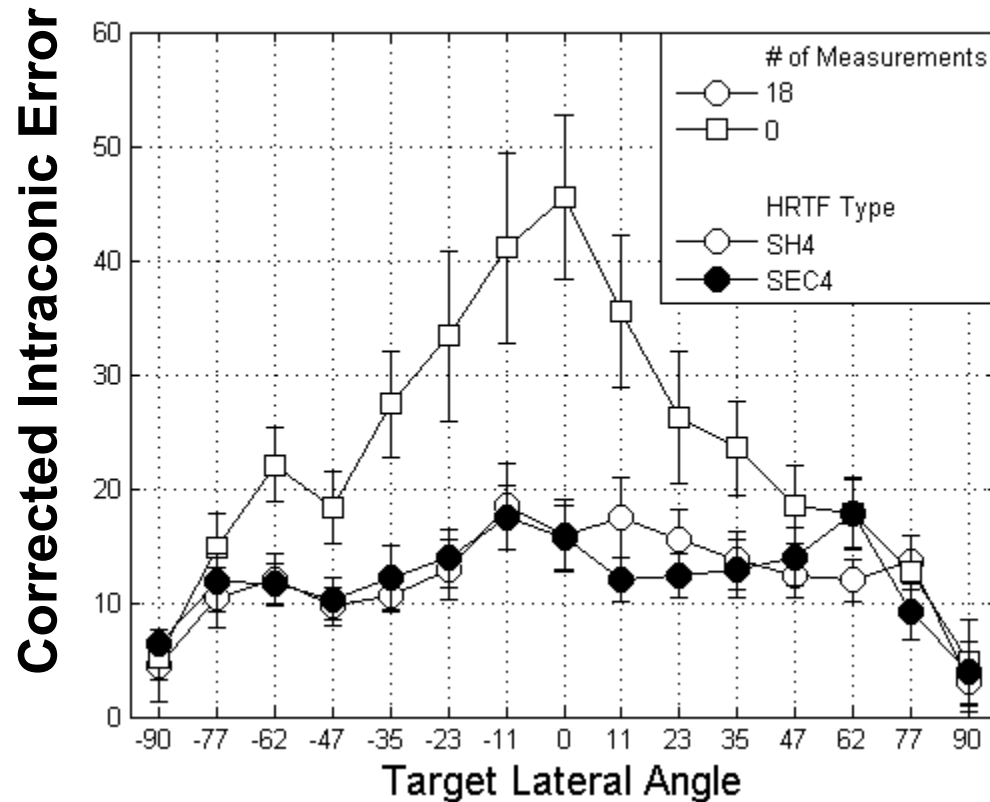
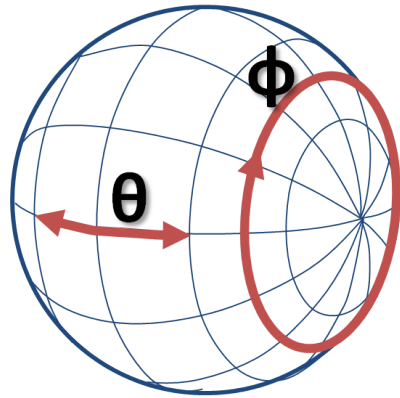


• Statistically similar performance with as few as 12 measurements

• No performance difference from Full SH model



Perceptual Evaluation



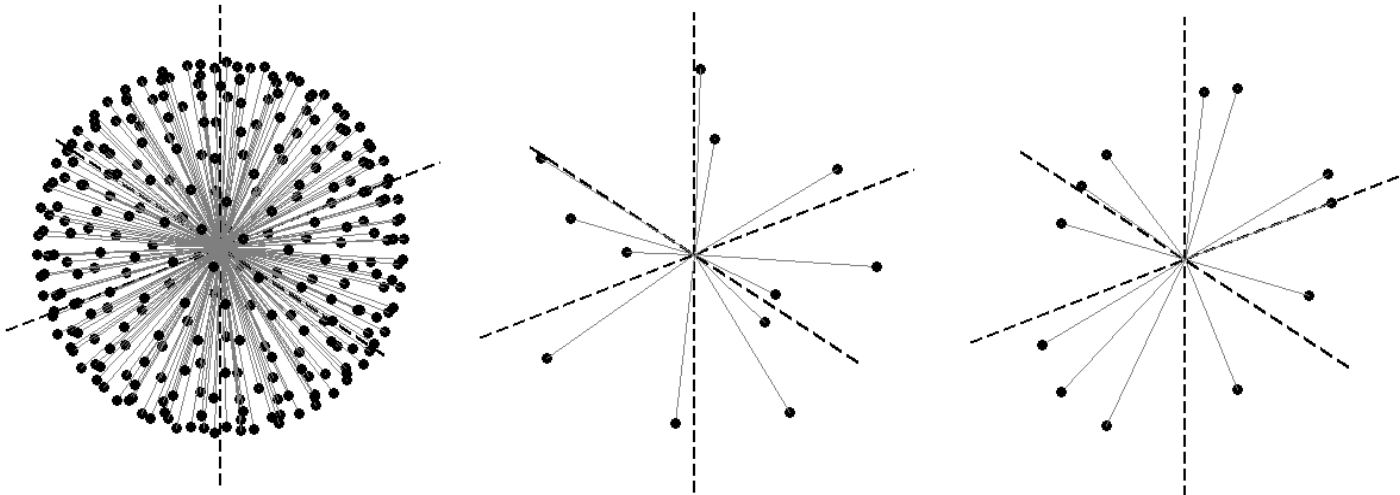
Maintains good performance off the midline



Recap...



- **Sectoral HRTF Model**
 - Sectoral coefficients contain large inter-subject variance
 - Only sectoral coefficients need to be individualized
 - The rest of the coefficients can be replaced with average
 - 98% fewer parameters w.r.t. baseline HRTF
- **Median-Plane Estimation**
 - Sectoral harmonics vary mainly in intraconic dimension
 - **Values can be estimated from median plane measurements**



Thank You

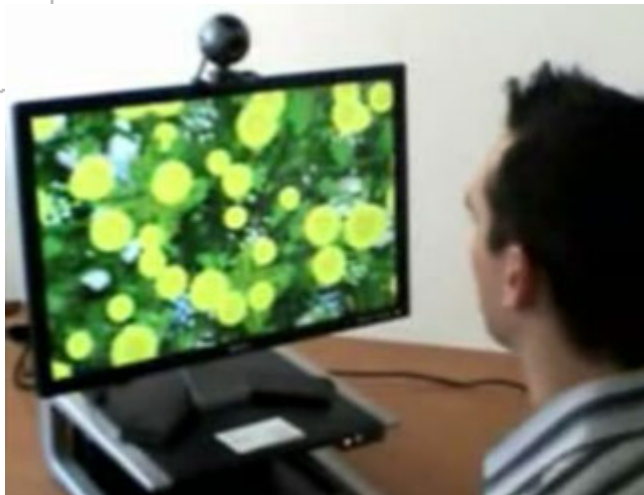
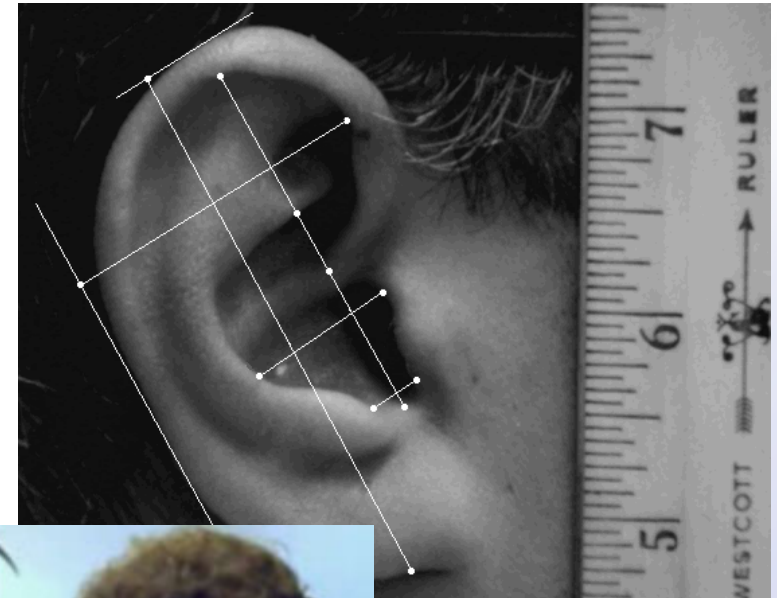
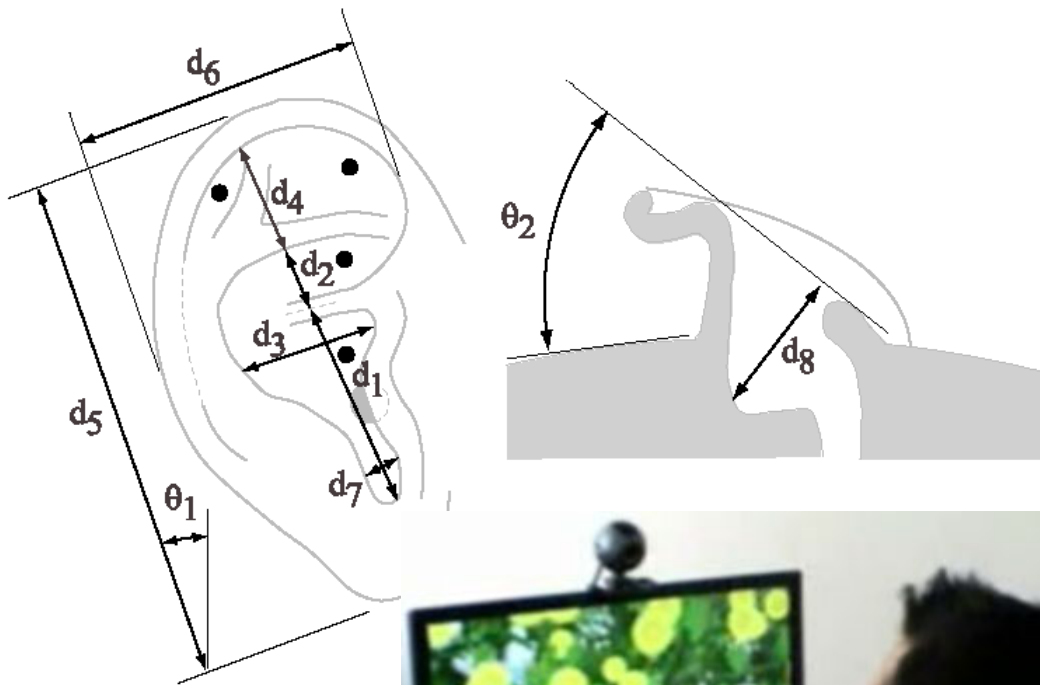




Project Ideas



Head-tracking and/or prediction of anthropometric parameters via webcam





Project Ideas



HRTF measurement using a single speaker and a head tracker





Project Ideas



HRTF-based sound source localization/segregation from a binaural recording (many recordings available)