

SAUNG LAB

Classical Predictive Models

- Input and output space: $\mathcal{X} \triangleq \mathbb{R}^{M_x}$ $\mathcal{Y} \triangleq \{-1, +1\}$
- Predictive function $h(\mathbf{x})$: $y^* = h(\mathbf{x}) \triangleq \arg \max_{y \in \mathcal{Y}} F(\mathbf{x}, y; \mathbf{w})$
- $F(\mathbf{x}, y; \mathbf{w}) = g(\mathbf{w}^{\top} \mathbf{f}(\mathbf{x}, y))$ Examples:
- $\hat{\mathbf{w}} = \arg\min_{\mathbf{w} \in \mathcal{W}} \ell(\mathbf{x}, y; \mathbf{w}) + \lambda R(\mathbf{w})$ Learning:

where $\ell(\cdot)$ represents a **convex loss**, and $R(\mathbf{w})$ is a **regularizer** preventing overfitting

- Logistic Regression
 - Max-likelihood (or MAP) estimation

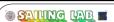
$$\max_{\mathbf{w}} \mathcal{L}(\mathcal{D}; \mathbf{w}) \triangleq \sum_{i=1}^{N} \log p(y^{i} | \mathbf{x}^{i}; \mathbf{w}) + \mathcal{N}(\mathbf{w})$$

$$\ell_{LL}(\mathbf{x}, y; \mathbf{w}) \triangleq \ln \sum_{y' \in \mathcal{Y}} \exp\{\mathbf{w}^{\top} \mathbf{f}(\mathbf{x}, y')\} - \mathbf{w}^{\top} \mathbf{f}(\mathbf{x}, y)$$

Support Vector Machines (SVM)

- Max-margin learning
- $\begin{aligned} \min_{\mathbf{w}, \xi} \quad & \underbrace{\overset{\mathsf{T}}{\mathbf{2}}} \mathbf{w}^{\top} \mathbf{w} + \overset{\mathsf{s}}{C} \sum_{i=1}^{N} \xi_{i}; \\ \text{s.t.} \ \forall i, \forall y' \neq y^{i} : \mathbf{w}^{\top} \Delta \mathbf{f}_{i}(y') \geq 1 \xi_{i}, \ \xi_{i} \geq 0. \end{aligned}$
- $\ell_{MM}(\mathbf{x}, y; \mathbf{w}) \triangleq \max_{y' \in \mathcal{Y}} \mathbf{w}^{\top} \mathbf{f}(\mathbf{x}, y') \mathbf{w}^{\top} \mathbf{f}(\mathbf{x}, y) + \ell'(y', y)$

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From Unstructured to Structured **Prediction**

Binary classification: black-and-white decisions



Multi-class classification: the world of technicolor

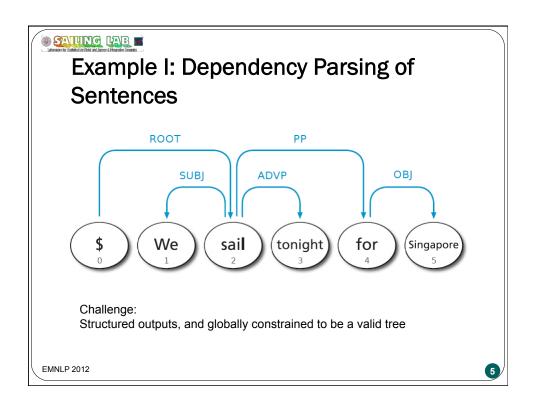


- · can be reduced to several binary decisions, but...
- · often better to handle multiple classes directly
- how many classes? 2? 5? exponentially many?
- Structured prediction: many classes, strongly interdependent
 - Example: image segmentation (number of classes exponential to the # of segments)



$$\mathbf{x} = \begin{pmatrix} x_{11} & x_{12} & \dots \\ x_{21} & x_{22} & \dots \\ \vdots & \vdots & \dots \end{pmatrix} \implies \mathbf{y} = \begin{pmatrix} y_{11} & y_{12} & \dots \\ y_{21} & y_{22} & \dots \\ \vdots & \vdots & \dots \end{pmatrix}$$







Example II: Text Summarization

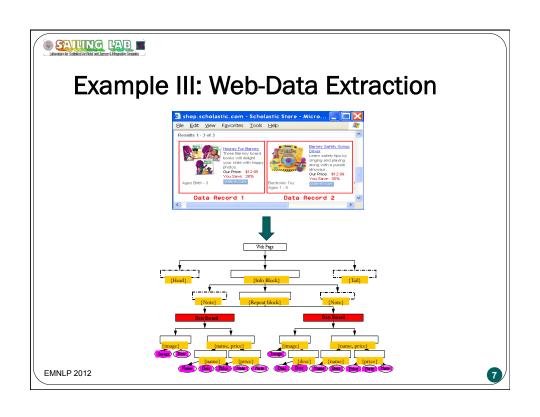
Australian novelist Peter Carey was awarded the coveted Booker Prize for fiction Tuesday night for his love story, "Oscar and Lucinda".

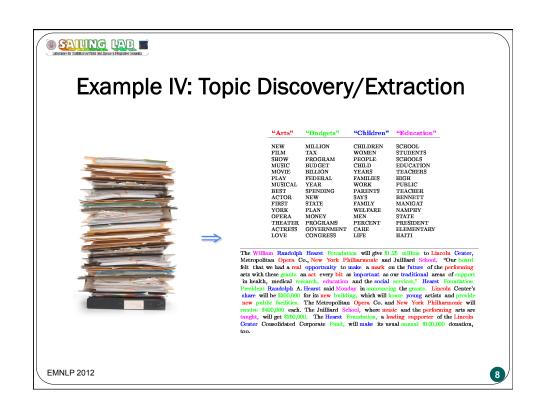
A panel of five judges unanimously announced the award of the \$26,250 prize after an 80-minute deliberation during a banquet at London's ancient Guildhall.

The judges made their selection from 102 books published in Britain in the past 12 months and which they read in their homes.

Carey, who lives in Sydney with his wife and son, said in a brief speech that like the other five finalists he had been asked to attend with a short speech in his pocket in case he won.







SAILING LAB

Structured Prediction Graphical Models

- Input and output space: $\mathcal{X} \triangleq \mathbb{R}_{X_1} \times, \dots, \mathbb{R}_{X_K}$ $\mathcal{Y} \triangleq \mathbb{R}_{Y_1} \times, \dots, \mathbb{R}_{Y_{K'}}$
- · Convex loss function
- Conditional Random Fields (CRFs) (Lafferty et al 2001)
 - Based on a Logistic Loss (LR)
 - Max-likelihood estimation (pointestimate)

$$\mathcal{L}(\mathcal{D}; \mathbf{w}) \triangleq \log \sum_{\mathbf{y}'} \exp(\mathbf{w}^{\top} \mathbf{f}(\mathbf{x}, \mathbf{y}'))$$

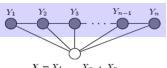
$$-\mathbf{w}^{\top} \mathbf{f}(\mathbf{x}, \mathbf{y})$$

- Max-margin Markov Networks (M³Ns) (Taskar et al 2003)
 - Based on a Hinge Loss (SVM)
 - Max-margin learning (point-estimate)

$$\begin{split} \mathcal{L}(\mathcal{D}; \mathbf{w}) & \triangleq & \log \max_{\mathbf{y}'} \mathbf{w}^{\top} \mathbf{f}(\mathbf{x}, \mathbf{y}') \\ & - \mathbf{w}^{\top} \mathbf{f}(\mathbf{x}, \mathbf{y}) + \ell(\mathbf{y}', \mathbf{y}) \end{split}$$

 Markov properties are encoded in the feature functions f(x, y)

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Structured Prediction Graphical Models

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 - Based on a Logistic Loss (LR)
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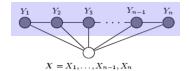
$$\begin{array}{ccc} \mathcal{L}(\mathcal{D}; \mathbf{w}) & \triangleq & \log \sum_{\mathbf{y}'} \exp(\mathbf{w}^{\top} \mathbf{f}(\mathbf{x}, \mathbf{y}')) \\ & - \mathbf{w}^{\top} \mathbf{f}(\mathbf{x}, \mathbf{y}) \end{array}$$

- Max-margin Markov Networks (M³Ns) (Taskar et al 2003)
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$$\begin{split} \mathcal{L}(\mathcal{D}; \mathbf{w}) & \triangleq & \log \max_{\mathbf{y}'} \mathbf{w}^{\top} \mathbf{f}(\mathbf{x}, \mathbf{y}') \\ & - \mathbf{w}^{\top} \mathbf{f}(\mathbf{x}, \mathbf{y}) + \ell(\mathbf{y}', \mathbf{y}) \end{split}$$

Challenges:

- SPARSE "Interpretable" prediction model
- Prior information of structures
- Latent structures/variables
- Time series and non-stationarity
- Scalable to large-scale problems (e.g., 10⁴ or larger input/output dimension)



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Main Claims

- The sparse structures of natural language data (input) and of the NLP tasks (output) can be utilized to improve the quality of the solution and interpretability of the solution
- Over-parameterized models such as conventional NB/LR/ SVM-style classifiers or parsers, topic models, or the related spectrum methods are not benefiting from sparse structures
- It is desirable to explore model spaces with structured sparsity for both predictive models (e.g., classifiers, parsers) and explorative models (e.g., topic models)

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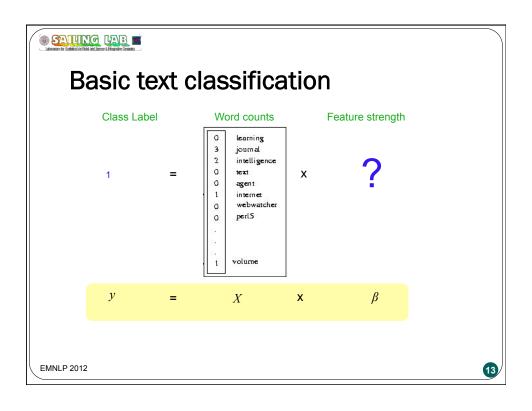


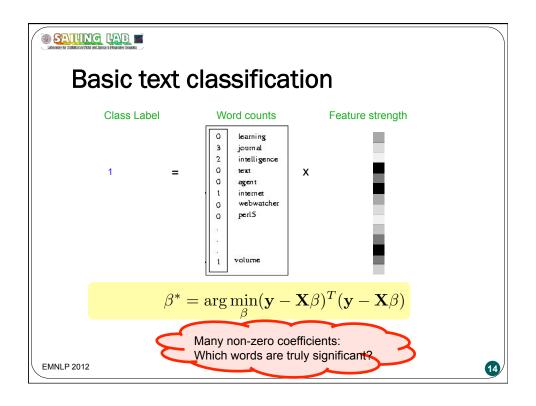


Outline

- Sparse Structured Input-Output Models
 - ... supervised learning
 - ... convex optimization and log loss
 - ... Frequentist-style shrinkage via regularization
- Sparse Topic Models
 - ... unsupervised learning
 - ... non-convex and likelihood-driven
 - ... Bayesian-style posterior inference
- Sparse and Discriminative Topic Models?
 - ... toward jointly explorative and predictive learning







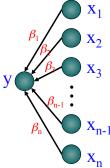


Sparsity: In a mathematical sense

- Consider least squares linear regression problem:
- · Sparsity means most of the beta's are zero.

$$\hat{\boldsymbol{\beta}} = \operatorname{argmin}_{\boldsymbol{\beta}} \|\mathbf{Y} - \mathbf{X}\boldsymbol{\beta}\|^2$$
 subject to:

$$\sum_{j=1}^{p} \mathbb{I}[|\beta_j| > 0] \le C$$



• But this is not convex!!! Many local optima, computationally intractable.

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L1 Regularization (LASSO) (Tibshirani, 1996)

A convex relaxation.

Constrained Form

$$\hat{\boldsymbol{\beta}} = \operatorname{argmin}_{\boldsymbol{\beta}} \|\mathbf{Y} - \mathbf{X}\boldsymbol{\beta}\|^2$$
 subject to:

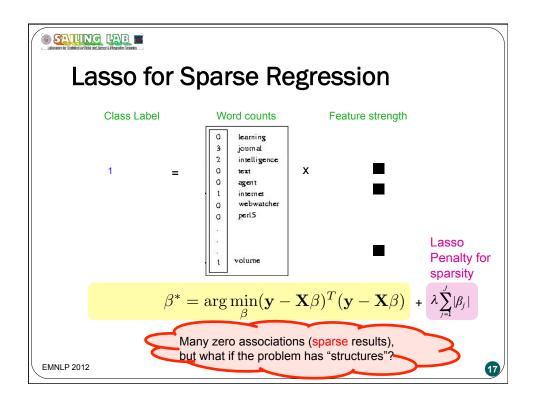
Lagrangian Form

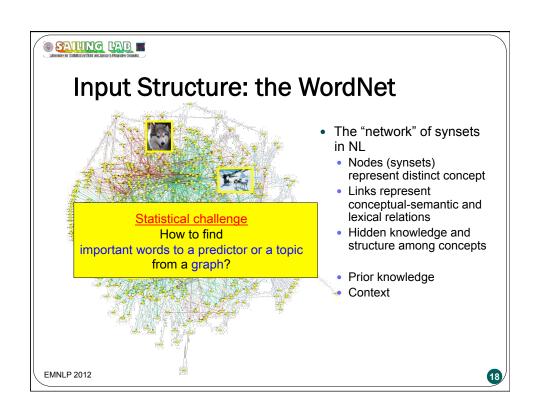
$$\hat{\boldsymbol{\beta}} = \operatorname{argmin}_{\beta} \|\mathbf{Y} - \mathbf{X}\boldsymbol{\beta}\|^2$$
 $\hat{\boldsymbol{\beta}} = \operatorname{argmin}_{\beta} \|\mathbf{Y} - \mathbf{X}\boldsymbol{\beta}\|^2 + \lambda \|\boldsymbol{\beta}\|_1$

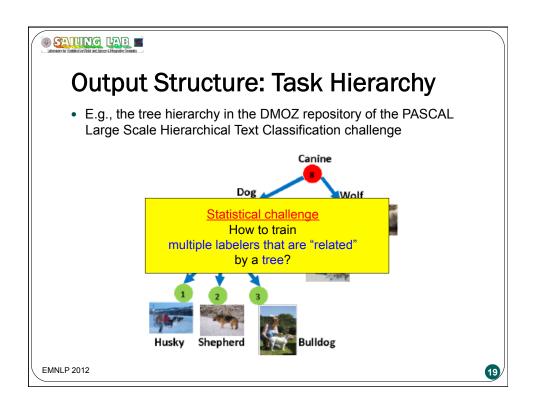
 $\sum_{j=1}^{p} |\beta_j| \le C$

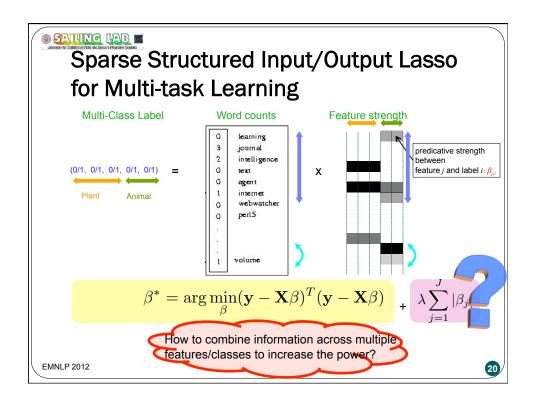
· Still enforces sparsity!

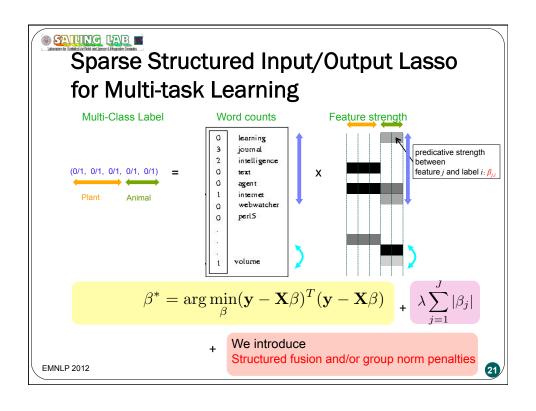


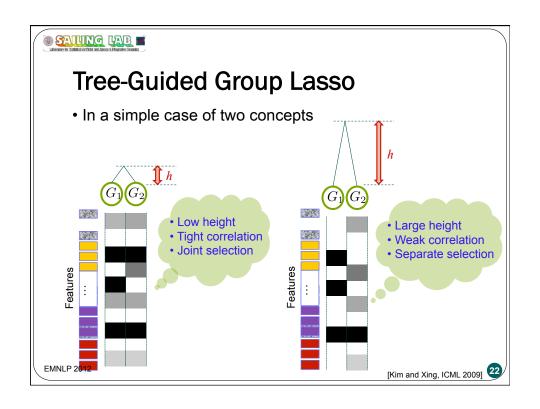


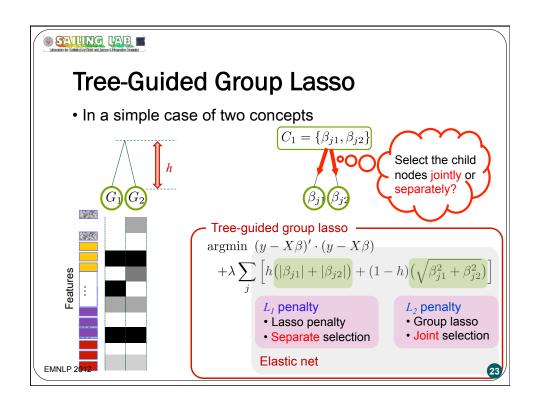


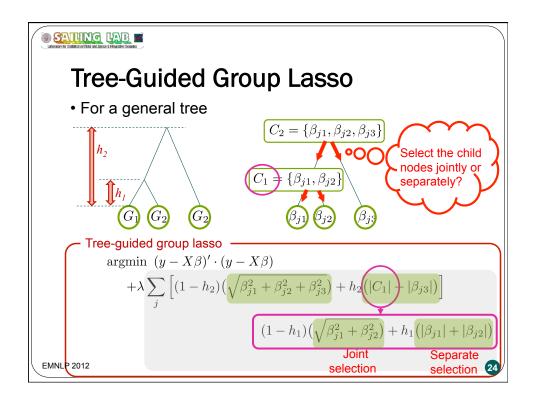






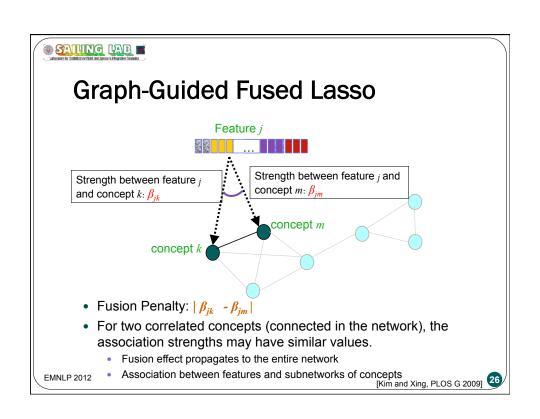






Proposition 1 For each of the k-th output (gene), the sum of the weights
$$w_v$$
 for all nodes $v \in V$ in T whose group G_v contains the k-th output (gene) as a member equals one. In other words, the following holds:
$$\sum_{v:k \in G_v} w_v = \prod_{m \in Ancestors(v_k)} h_m + \sum_{l \in Ancestors(v_k)} (1-h_l) \prod_{m \in Ancestors(v_l)} h_m = 1.$$

$$\beta_{j2} \uparrow \qquad \qquad \beta_{j1}$$
Previously, in Jenatton, Audibert & Bach, 2009
$$\beta_{j2} \uparrow \qquad \qquad \beta_{j1}$$
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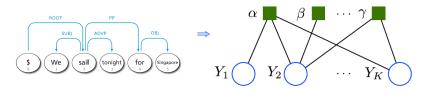




Full GM-based Loss Functions

$$y^* = h(\mathbf{x}) \triangleq \arg \max_{y \in \mathcal{Y}} F(\mathbf{x}, y; \mathbf{w})$$
$$F(\mathbf{x}, y; \mathbf{w}) = g(\mathbf{w}^{\top} \mathbf{f}(\mathbf{x}, y))$$

Represent factorization assumptions: $P(\mathbf{y}|x) = \frac{1}{Z} \prod_{i} \Psi_{i}(y_{i}) \prod_{\alpha} \Psi_{\alpha}(\mathbf{y}_{\alpha})$



Inference: compute the MAP, marginals $\mu_i(y_i)$ and $\mu_{\alpha}(\mathbf{y}_{\alpha})$, Z

 \blacksquare tractable when ${\mathscr G}$ is a tree, often intractable otherwise





Optimization

Original Problem:

$$\arg\max_{\beta} \equiv \mathcal{L}(\{\mathbf{x}_i, \mathbf{y}_i\}; \beta) + \Omega(\beta)$$

Existing Methods:

Interior-point Method (IPM) for Second-order Cone Programming (SOCP) or Quadratic Programming (QP)	2 nd -order, computationally heavy	$\lambda \sum_{g \in \mathcal{G}} w_g \ \boldsymbol{\beta}_g\ _2 \Longrightarrow \lambda \sum_{g \in \mathcal{G}} w_g t_g$ $\text{s.t.} \ \boldsymbol{\beta}_g\ \le t_g$
Block Coordinate Descent	Cannot be easily be applied. Hard to compute the subgradient	Optimize $oldsymbol{eta}_g$ at one time





New Optimization Framework

- Main Difficulties:
 - Complex loss $\mathcal{L}(\{\mathbf{x}_i,\mathbf{y}_i\};\beta)$, (e.g., GMs with intractable factors or loopy graphs)
 - Intractable inference
 - Complex shrinkage Ω(β), (e.g., overlapping group penalties)
 - Non-differentiable, non-separatable

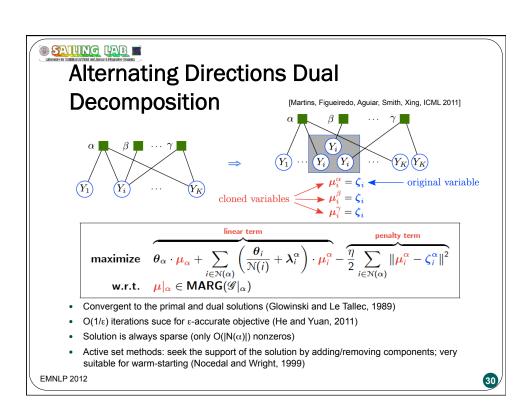
Our approaches:

- Alternating Direction Dual Decomposition (AD3) [Martins et al, ICML 2011]
- Proximal Gradient [Chen et al, AOAS 2012]
- Hierarchical Group Threshholding [Lee and Xing, 2012, submitted]

· Large number of training examples

- · Parallel computation
- · Map-Reduce on computing gradient
 - · Map: calculate gradient on single example
 - Reduce: gather gradients computed by all map procedures, and calculate the sum
- · New multi-core framework ..







Smooth Proximal Gradient Descent [Chen et al and Xing, UAI 2011, AOAS 2012]

Original Problem:

$$\underset{\boldsymbol{\beta} \in \mathbb{R}^J}{\arg \min} f(\boldsymbol{\beta}) \equiv \frac{1}{2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|_2^2 + \Omega(\boldsymbol{\beta})$$

$$\Omega(\boldsymbol{\beta}) = \max_{\boldsymbol{\alpha} \in \mathcal{Q}} \boldsymbol{\alpha}^T C \boldsymbol{\beta}$$

Approximation Problem:

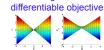
$$\underset{\boldsymbol{\beta} \in \mathbb{R}^J}{\arg\min} \, \widetilde{f}(\boldsymbol{\beta}) \equiv \frac{1}{2} \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|_2^2 + f_{\mu}(\boldsymbol{\beta})$$

Separating overlapping

 $f_{\mu}(\boldsymbol{\beta}) = \max_{\boldsymbol{\alpha} \in \mathcal{Q}} \boldsymbol{\alpha}^T C \boldsymbol{\beta} - \mu d(\boldsymbol{\alpha})$ Smoothing non-

Gradient of the Approximation:

$$\nabla \widetilde{f}(\boldsymbol{\beta}) = \mathbf{X}^T (\mathbf{X} \boldsymbol{\beta} - \mathbf{y}) + C^T \boldsymbol{\alpha}^*$$



$$\alpha^* = \operatorname*{arg\,max}_{\alpha \in \mathcal{Q}} \alpha^T C \beta - \mu d(\alpha)$$

 $\nabla \widetilde{f}(\boldsymbol{\beta})$ is Lipschitz continuous with the Lipschitz constant L

$$L = \lambda_{\max}(\mathbf{X}^T \mathbf{X}) + L_{\mu}$$

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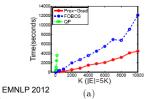
Convergence Rate

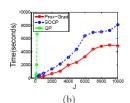
Theorem: If we require $f(\beta^t) - f(\beta^*) \le \epsilon$ and set $\mu = \frac{\epsilon}{2D}$, the number of iterations is upper bounded by:

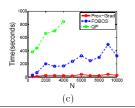
$$t \leq \sqrt{\frac{4\|\boldsymbol{\beta}^*\|_2^2}{\epsilon} \bigg(\lambda_{\max}(\mathbf{X}^T\mathbf{X}) + \frac{2D\|\Gamma\|^2}{\epsilon}\bigg)} = O(\frac{1}{\epsilon})$$

Remarks: state of the art IPM method for for SOCP converges at a rate $O(\frac{1}{\epsilon^2})$

 $\textbf{Time complexity (Per-iteration):} \quad O(J^2K + J\sum_{g \in \mathcal{G}}|g|) \text{ vs. } O\left(J^2(K + |\mathcal{G}|)^2(KN + J(\sum_{g \in \mathcal{G}}|g|))\right)$









What if the structure becomes too complex?

• Too many groups in real problems:

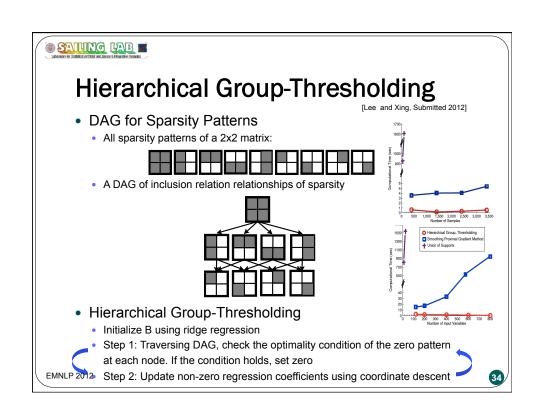
$$\beta_{lo-lasso} = \arg\min_{\beta} \sum_{k=1}^{K} \sum_{i=1}^{N} \left(Y_{i}^{k} - \sum_{j=1}^{p} \beta_{j}^{k} X_{ij} - \sum_{(r,s) \in U} \beta_{r}^{k} Z_{i,rs} \right) + \lambda \sum_{j=1}^{N} \sum_{k=1}^{N} \left| \beta_{j}^{k} \right|$$

$$+ \lambda \sum_{m} \sqrt{\sum_{(r,s) \in S_{m}} \beta_{rs}^{k^{2}}}$$

- Recall that even SPG has a complexity of $O(J^2K + J\sum_{g \in \mathcal{G}}|g|)$
- And an optimization procedure must
 - · minimize our objective function, and
 - · induce correct sparsity patterns
- Hierarchical group-thresholding:
 - an algorithmic approach to directly reduce search space of sparsity, while optimizes the exact loss

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What if the function is non-linear?

Group Sparse Additive Models [Ying, Chen, Xing, ICML 2012]

- Assume G is a partition of {1, · · · , p}, i.e., the groups in G do not overlap
- The optimization problem is

$$\min_{\mathbf{f}} L(\mathbf{f}) + \lambda \Omega_{\text{group}}(\mathbf{f}),$$

where

$$\Omega_{\text{group}}(\mathbf{f}) = \sum_{g \in \mathcal{G}} \sqrt{|g|} \|\mathbf{f}_g\| = \sum_{g \in \mathcal{G}} \sqrt{|g|} \sqrt{\sum_{j \in g} \mathbb{E}\left[f_j^2(X_j)\right]}.$$

- Non-trivial to solve due to
 - correlation structure of component functions within the group
 - non-smoothness of functional group penalty

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Toward Human-Level Intelligence

- Now we have dealt with high feature dimension
 - Sparsity
- and we have know how to leverage structural knowledge
 - Structured shrinkage
- What about massive concept space?





Output Coding

М						K
1	1	1	1	0	0	0
2	-1	0	0	1	1	0
1 2 C	0	-1	0	-1	0	1
С	0	0	-1	0 1 -1 0	-1	-1

- Every class is now represented by a bit-string
 - Coding: a codeword is assigned to each class
 - Decoding: given test data, look for most similar class codeword
- Predict bit by bit through binary or ternary classifier this is much easier than the 1 vs C-1 classifier
- · Decoding the bit-string error correcting

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[Zhao and Xing, 2012, submitted]





Learning the Coding Matrix

- Accuracy of base binary classifiers for bit-prediction
 - · Use category hierarchy for a measure of separability
 - Large intra-partite similarity + small inter-partite similarity
- Strong error-correcting ability
 - Maximize distance between rows of coding matrix
- Fault tolerance
 - Introduction of ignored classes: {-1,0,+1} instead of {-1,+1}

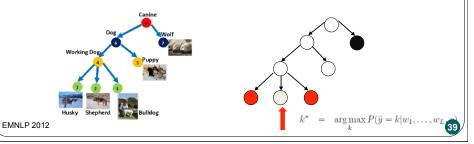
$$\begin{aligned} \max_{\mathbf{B}} \quad & F_b(\mathbf{B}) - \lambda_r F_r(\mathbf{B}) - \lambda_c \sum_{l=1}^L ||\boldsymbol{\beta}_l||_2^2 \\ s.t. \quad & \mathbf{B} \in \{-1,0,+1\}^{K \times L} \quad \sum_{k=1 \atop k=1}^K (|B_{kl}| + B_{kl}) \geq 2, \ \forall l = 1, \dots, L} \\ & \sum_{l=1 \atop l=1}^L ||B_{kl}| \geq 1, \ \forall k = 1, \dots, K \end{aligned}$$





Probabilistic Decoding

- · Output code can have real semantic meaning
 - E.g., encoding a tree path in a label taxonomy
- · Probabilistic decoding:
 - bit i depend on bit j probabilistically
- Define prior $P(y_l|\hat{y} = k)$ using tree hierarchy
 - Graph coloring: all nodes participating in i-th bit prediction are colored (red for positive, black for negative)
 - Task: what is the probability of node k being colored red?



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Multi-Way Classification Accuracy

• DMOZ repository in PASCAL Hierarchical Text Classification challenge

Data set	# classes	# training data	# test data	# features
DMOZ-small	1139	6323	1858	1199848
DMOZ-large	12294	93805	34905	1199856

DMOZ small DMOZ large

		_		
Algorithm	Top 1	Top 5	Top 1	Top 5
OVR	50.91	64.72	37.24	44.87
RDOC	41.77	54.52	5.13	7.99
RSOC	42.30	58.40	5.47	7.23
SpectralOC	44.83	59.10	22.10	23.82
SSOC	56.67	67.33	41.28	46.71

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Zhao and Xing, Submitted 2012]



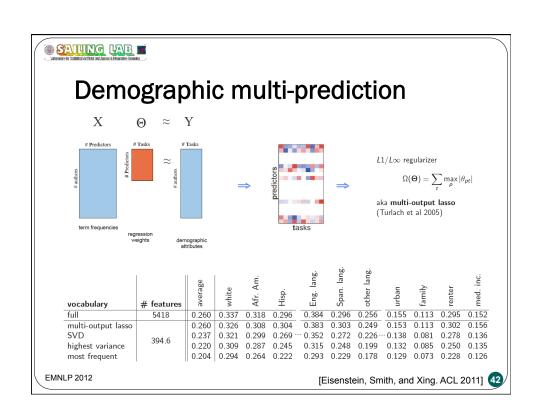
Discovering Sociolinguistic Associations on Twitter

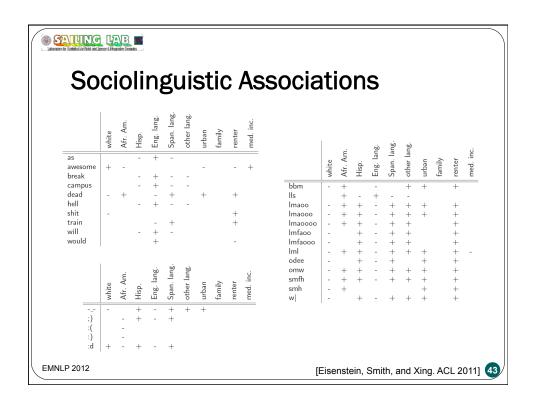
- Twitter Gardenhose feed from March 1-7, 2010
- 9250 authors, 380,000 messages, 4.7 million tokens
- Filters:
 - At least 20 messages (in Gardenhose)
 - Messages must include GPS within a USA zipcode
 - No more than 1000 followers, followees
- ullet GPS o Zipcode o U.S. Census Demographic Statistics
 - Zipcodes commonly proxy for demographics in public health.
 - Careful! Twitter users are not an unbiased sample from a zipcode.

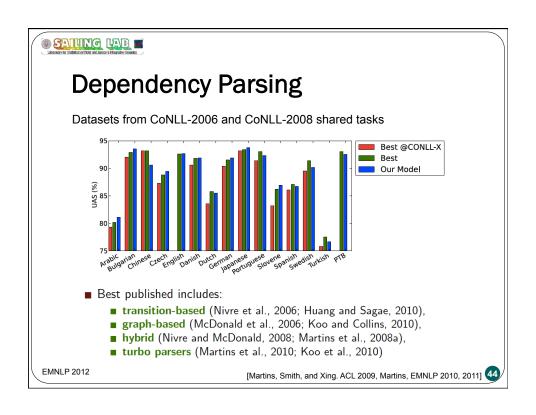


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[Eisenstein, Smith, and Xing. ACL 2011] 41





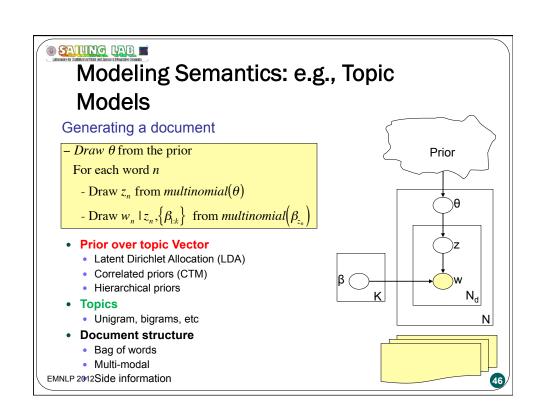


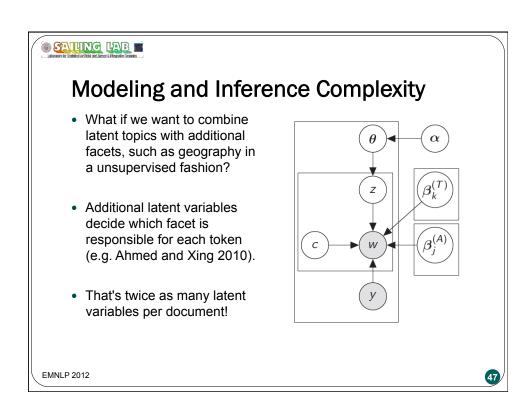


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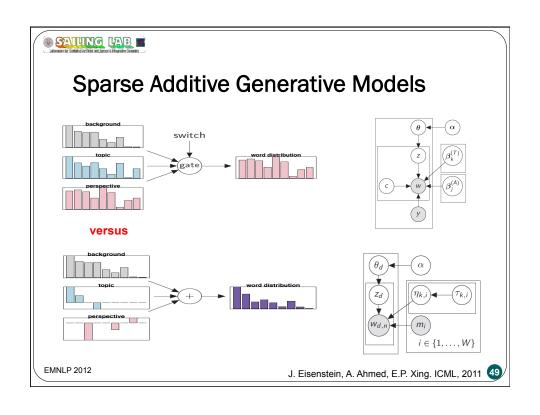
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 - ... convex optimization and log loss
 - ... Frequentist-style shrinkage via regularization
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 - ... Bayesian-style posterior inference
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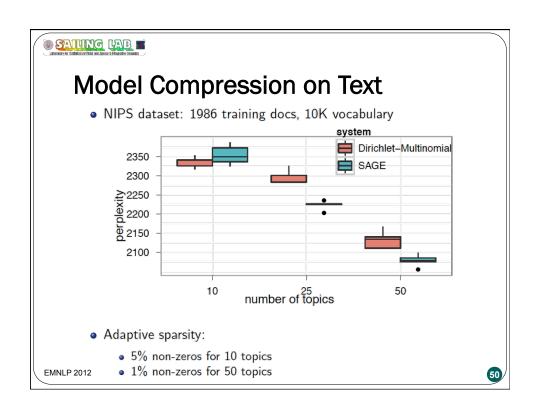


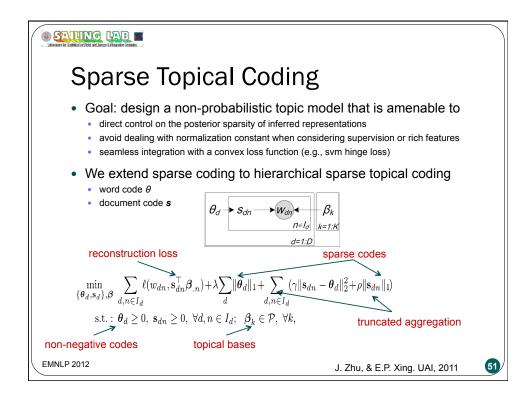


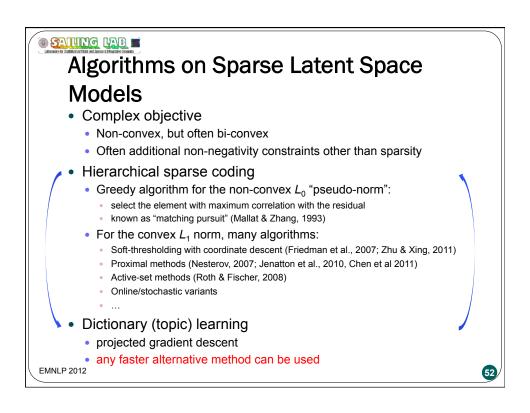


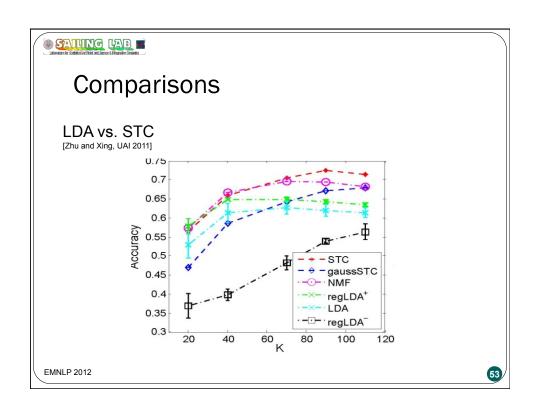


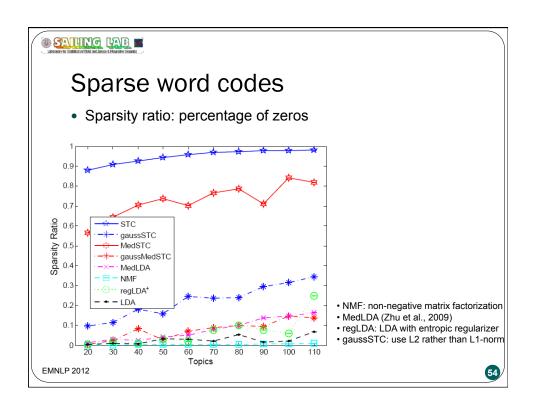














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 - ... non-convex and likelihood-driven
 - ... Bayesian-style posterior inference
- Sparse and Discriminative Topic Models?
 - ... toward jointly explorative and predictive learning

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Predictive Subspace Learning with Supervision

- Unsupervised latent subspace representations are generic but can be sub-optimal for predictions
- Many datasets are available with supervised side information





- Can be noisy, but not random noise (Ames & Naaman, 2007)
 - labels & rating scores are usually assigned based on some intrinsic property of the data
 - helpful to suppress noise and capture the most useful aspects of the data
- Goals:

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Discover latent subspace representations that are both *predictive* and interpretable by exploring weak supervision information.

interpretable by exploring weak supervision information





MLE versus Max-margin Learning

- · Likelihood-based estimation
 - Probabilistic (joint/conditional likelihood model)
 - Easy to perform Bayesian learning, and incorporate prior knowledge, latent structures, missing data
 - Bayesian or direct regularization
 - Hidden structures or generative hierarchy
- Max-margin learning
 - Non-probabilistic (concentrate on inputoutput mapping)
 - Not obvious how to perform Bayesian learning or consider prior, and missing data
 - Support vector property, sound theoretical guarantee with limited samples
 - Kernel tricks
- Maximum Entropy Discrimination (MED) (Jaakkola, et al., 1999)
 - Model averaging

$$\hat{y} = \operatorname{sign} \int p(\mathbf{w}) F(x; \mathbf{w}) \, d\mathbf{w}$$

$$(y \in \{+1, -1\})$$

The optimization problem (binary classification)

$$\min_{p(\Theta)} KL(p(\Theta)||p_0(\Theta))$$

s.t.
$$\int p(\Theta)[y_i F(x; \mathbf{w}) - \xi_i] d\Theta \ge 0, \forall i,$$

where Θ is the parameter \mathbf{w} when ξ are kept fixed or the pair (\mathbf{w}, ξ) when we want to optimize over ξ

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MaxEnt Discrimination Markov Network

(Zhu et al, ICML 2008, Zhu and Xing, JMLR 2009)

Structured MaxEnt Discrimination (SMED):

P1:
$$\min_{p(\mathbf{w}),\xi} KL(p(\mathbf{w})||p_0(\mathbf{w})) + U(\xi)$$

s.t.
$$p(\mathbf{w}) \in \mathcal{F}_1, \ \xi_i \ge 0, \forall i$$
.

generalized maximum entropy or regularized KL-divergence

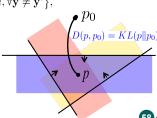
• Feasible subspace of weight distribution:

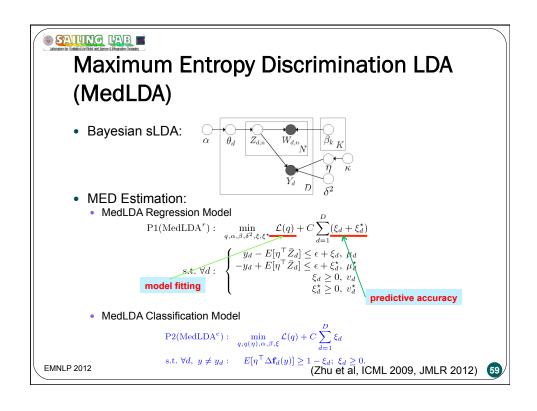
$$\mathcal{F}_1 = \{ p(\mathbf{w}) : \int p(\mathbf{w}) [\Delta F_i(\mathbf{y}; \mathbf{w}) - \Delta \ell_i(\mathbf{y})] \, d\mathbf{w} \ge -\xi_i, \, \forall i, \forall \mathbf{y} \ne \mathbf{y}^i \},$$

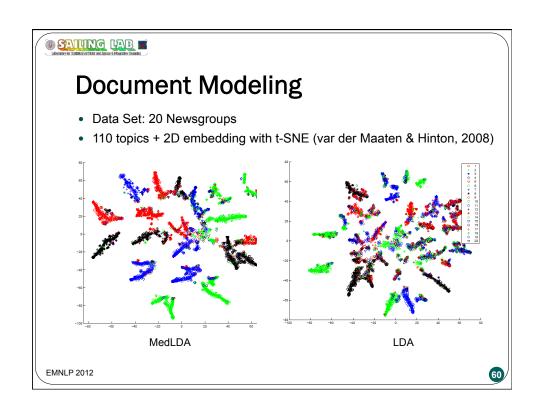
expected margin constraints.

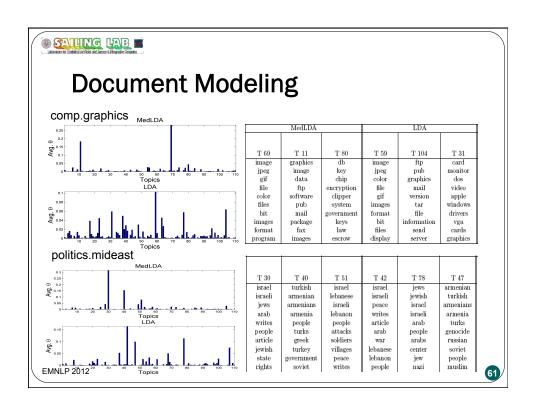


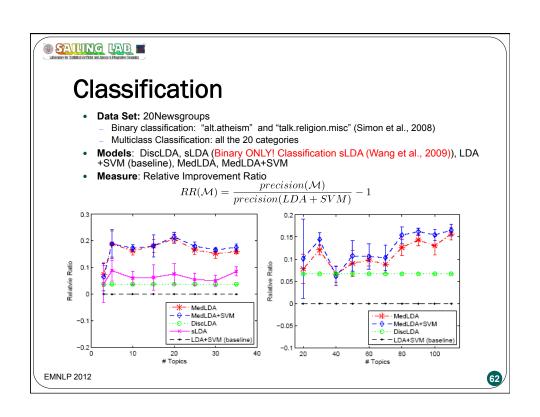
$$h_1(\mathbf{x}; \mathbf{p(w)}) = \arg\max_{\mathbf{y} \in \mathcal{Y}(\mathbf{x})} \int \mathbf{p(w)} F(\mathbf{x}, \mathbf{y}; \mathbf{w}) d\mathbf{w}$$

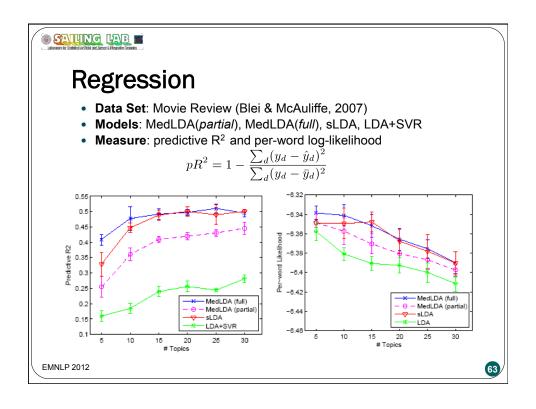


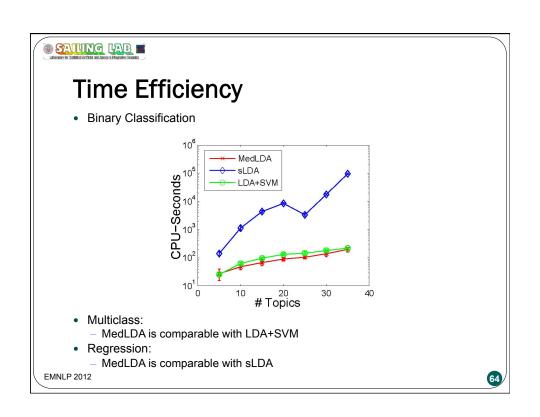






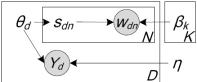








Supervised STC



Joint loss minimization

$$\begin{aligned} \min_{\{\boldsymbol{\theta}_d\}, \{\mathbf{s}_d\}, \boldsymbol{\beta}, \boldsymbol{\eta}} & f(\{\boldsymbol{\theta}_d\}, \{\mathbf{s}_d\}, \boldsymbol{\beta}) + C\mathcal{R}_h(\{\boldsymbol{\theta}_d\}, \boldsymbol{\eta}) + \frac{1}{2} \|\boldsymbol{\eta}\|_2^2 \\ \text{s.t.}: & \boldsymbol{\theta}_d \geq 0, \ \forall d; \ \mathbf{s}_{dn} \geq 0, \ \forall d, n \in I_d; \ \boldsymbol{\beta}_k \in \mathcal{P}, \ \forall k, \end{aligned}$$

- coordinate descent alg. applies with closed-form update rules
- No sum-exp function; seamless integration with nonprobabilistic large-margin principle

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(Zhu and Xing, UAI 2011)



