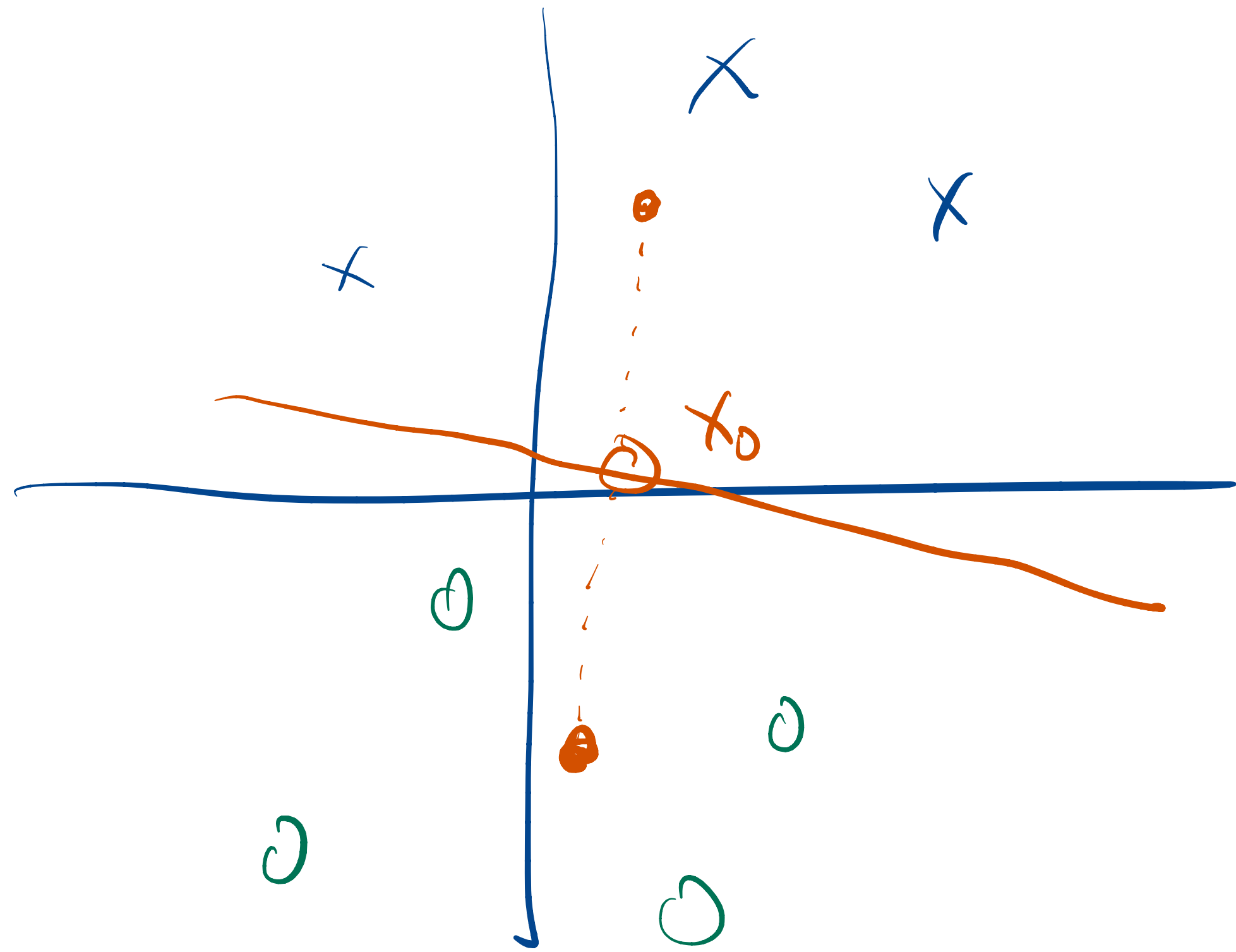


# **Math Foundations for ML**

**10-606**

**Geoff Gordon**



$$\begin{pmatrix} 0 \\ -4.5 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 0.25 \end{pmatrix} = b$$

$= -1.125$

$-1, 2$	$\rightarrow$	$-1$	$\rightarrow$	$\mu_x$
$-1, -1$	$\rightarrow$	$+1$	$\rightarrow$	$0, 2.5$
$+1, 3$	$\rightarrow$	$-1$	$\rightarrow$	$0, -2$
$+1, -3$	$\rightarrow$	$+1$	$\rightarrow$	$\mu_0$

~~$w \cdot x_0 = b$~~

$(\mu_+ + \mu_-) / 2$

~~$x_0 = \frac{\mu_x + \mu_0}{2}$~~

$= (0, 0.25)$

$\mu_+ - \mu_-$

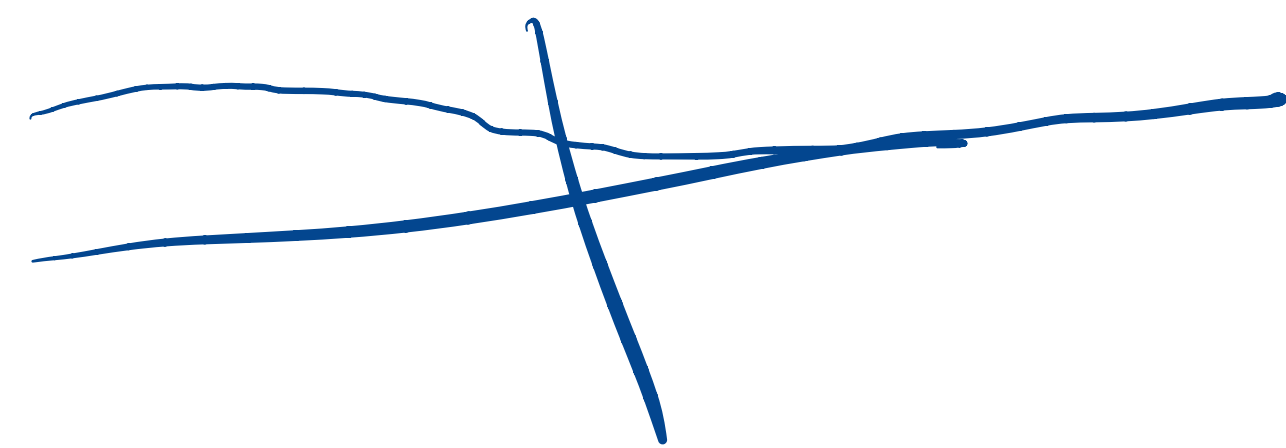
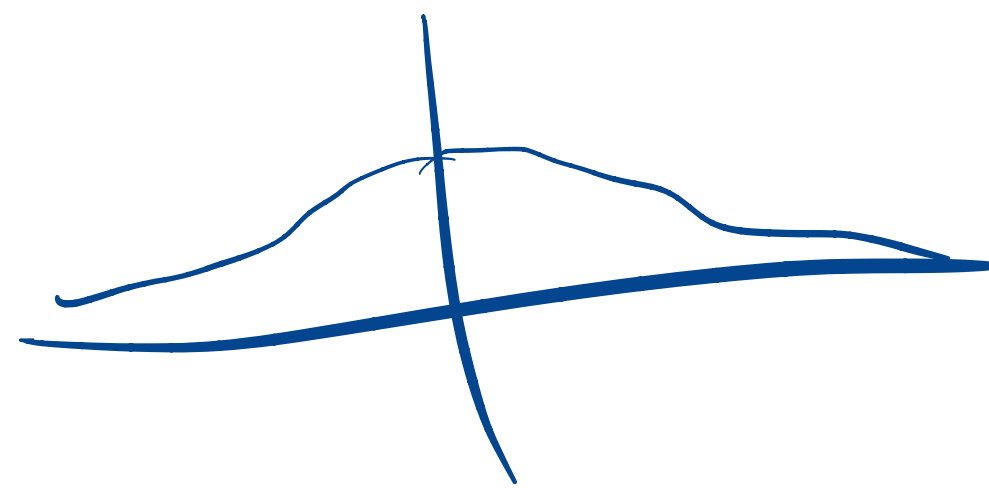
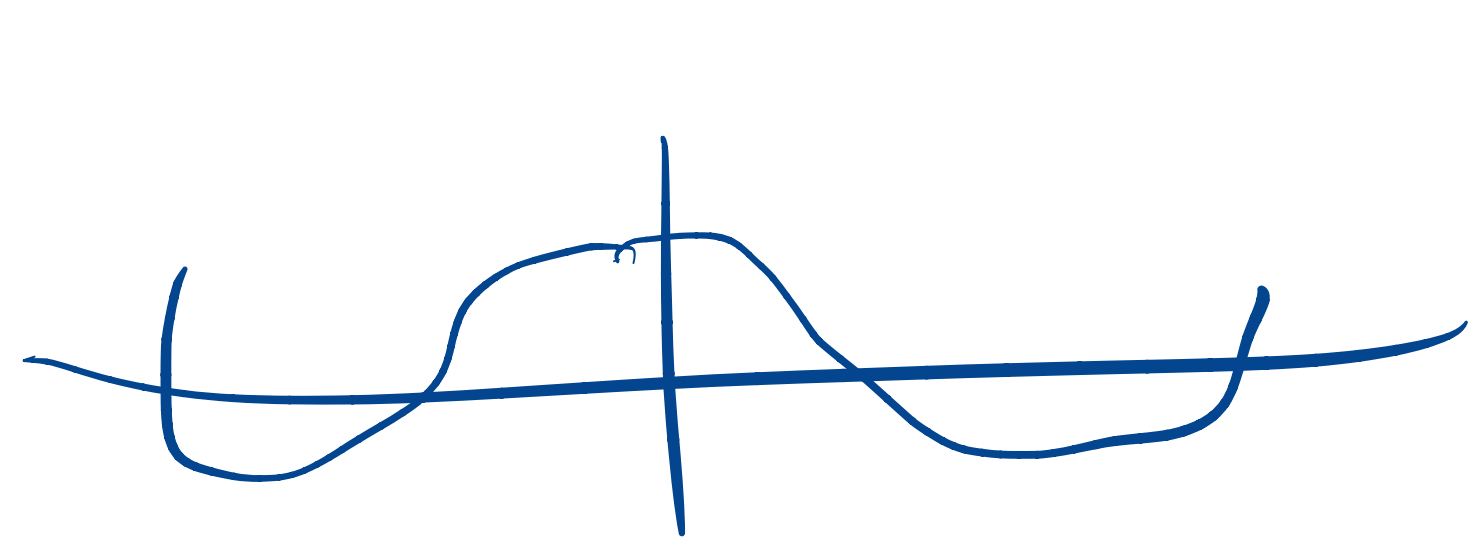
~~$w = \mu_0 - \mu_x$~~

$= (0, -4.5)$

$$\begin{pmatrix} 1 & & 0 \\ & 1 & \\ \alpha_{ij} & & 1 \end{pmatrix}$$

take  $\alpha_{ij}$  times row  $j$   
add to row  $i$

$$\text{Span}(\cos(x), e^{-x^2}, \frac{1}{1+e^x}) = V$$



$$f \in V$$

$$f(0) = 3$$

$$f(1) = 2$$

$$f(2) = 5$$

$$a \cos(0) + b e^{-0^2} + c \frac{1}{1+e^0} = 3$$

$$a + b + \frac{1}{2}c = 3$$

$$A = \begin{pmatrix} 3 & 1 & 7 \\ 2 & 4 & -1 \\ -1 & 0 & 3 \end{pmatrix} \rightarrow \begin{pmatrix} 3 & 1 & 7 \\ 2 & 4 & -1 \\ 0 & \frac{1}{3} & \frac{5}{3} \end{pmatrix} = R_1 A$$

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -\frac{1}{3} & 0 & 1 \end{pmatrix} \quad \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \frac{1}{3} & 0 & 1 \end{pmatrix} \quad \begin{pmatrix} 3 & 1 & 7 \\ 0 & 3\frac{1}{3} & -5\frac{2}{3} \\ 0 & \frac{1}{3} & \frac{5}{3} \end{pmatrix} = R_2 R_1 A$$

$R_1^{-1}$

$R_1$

$R_2$

$$\tilde{u} = R_2 R_1 A$$

$R_2^{-1}$

$$\begin{pmatrix} 1 & 0 & 0 \\ +\frac{2}{3} & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 0 & 0 \\ -\frac{2}{3} & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

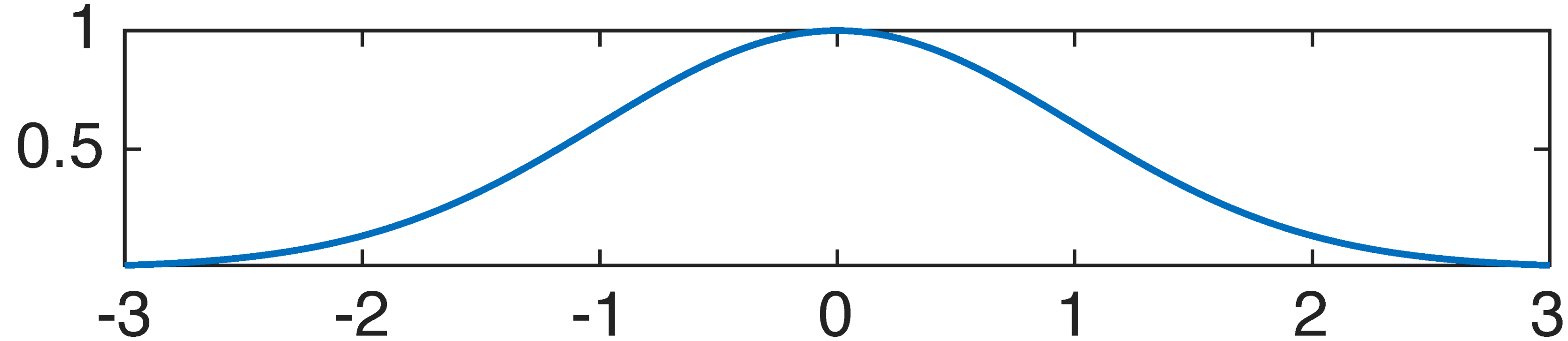
$$R_2^{-1} \tilde{u} = R_1 A$$

$$(R_1^{-1} R_2^{-1}) \tilde{u} = A$$

# Gaussian radial basis function

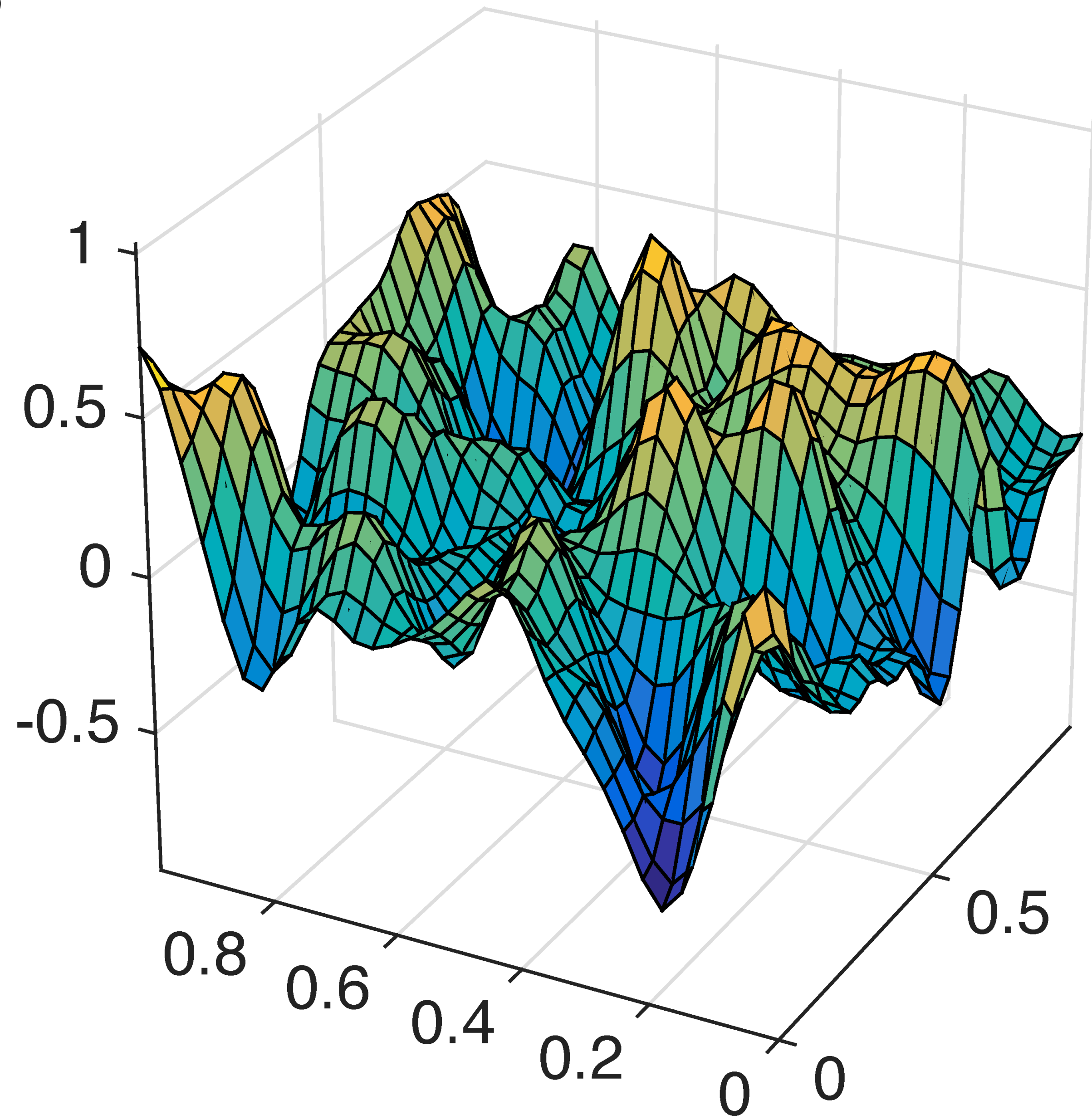
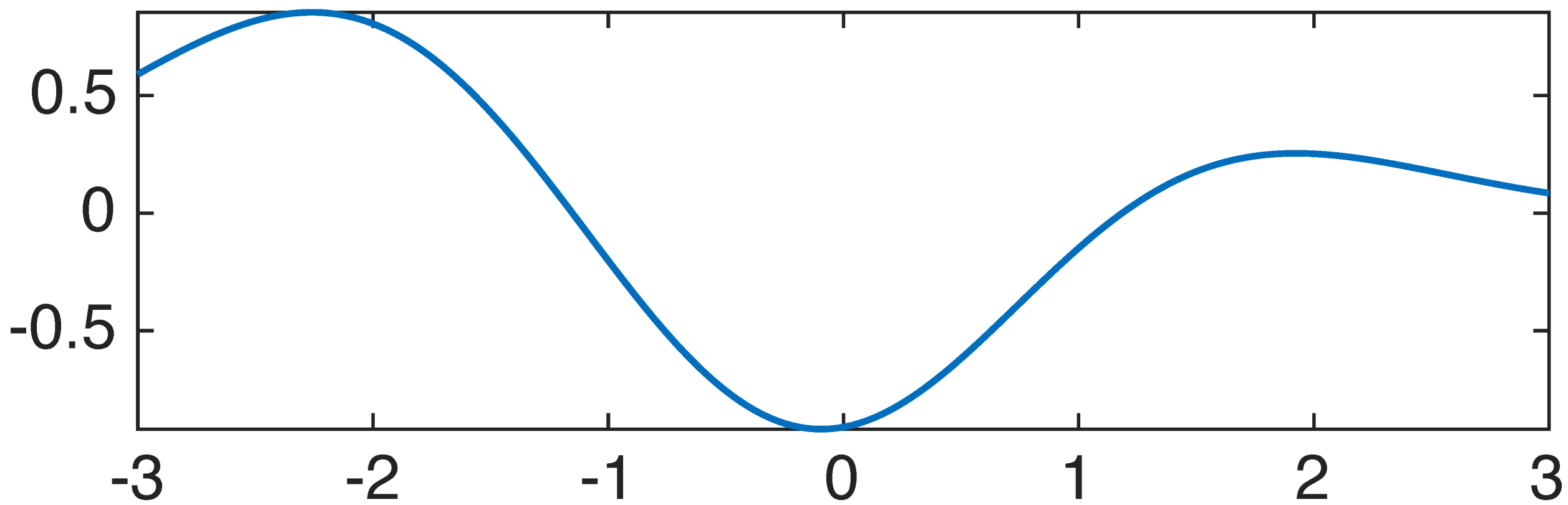
also called squared exponential function

$$e^{-\frac{1}{2}(x-x_0)^2}$$
$$e^{-\frac{1}{2}\|x-x_0\|^2}$$

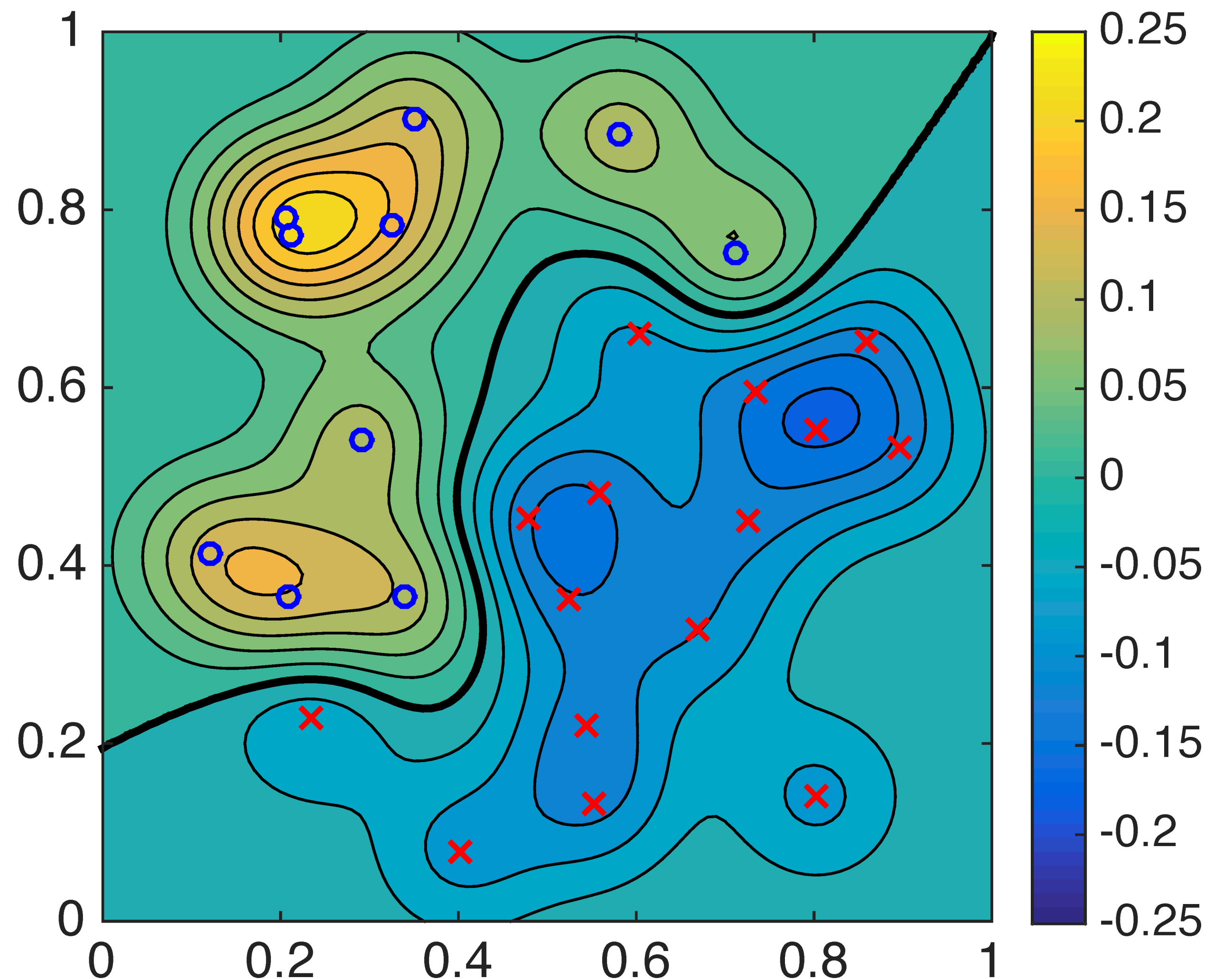
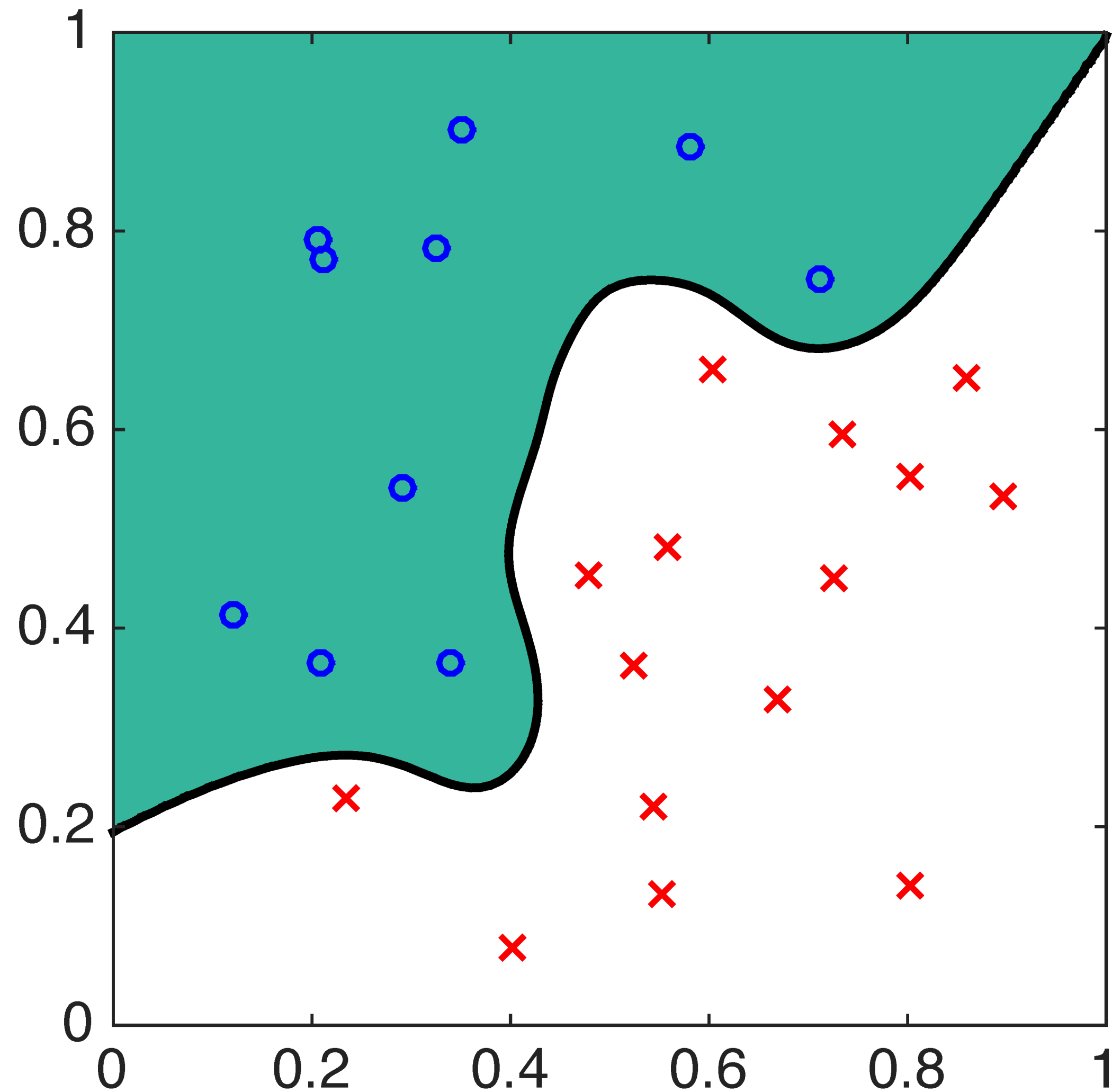


$x_0 = 0$

# GRBF vector examples

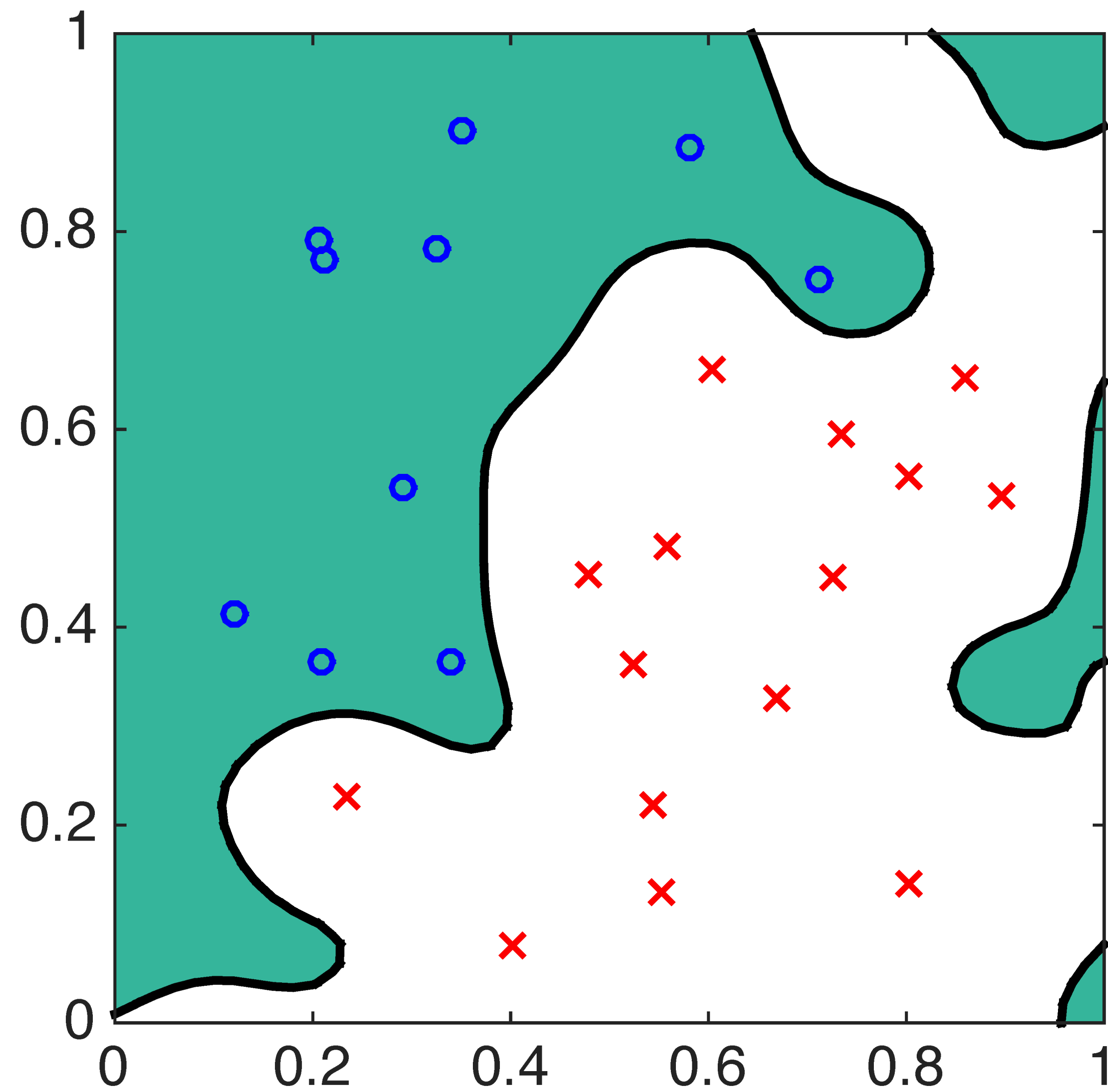


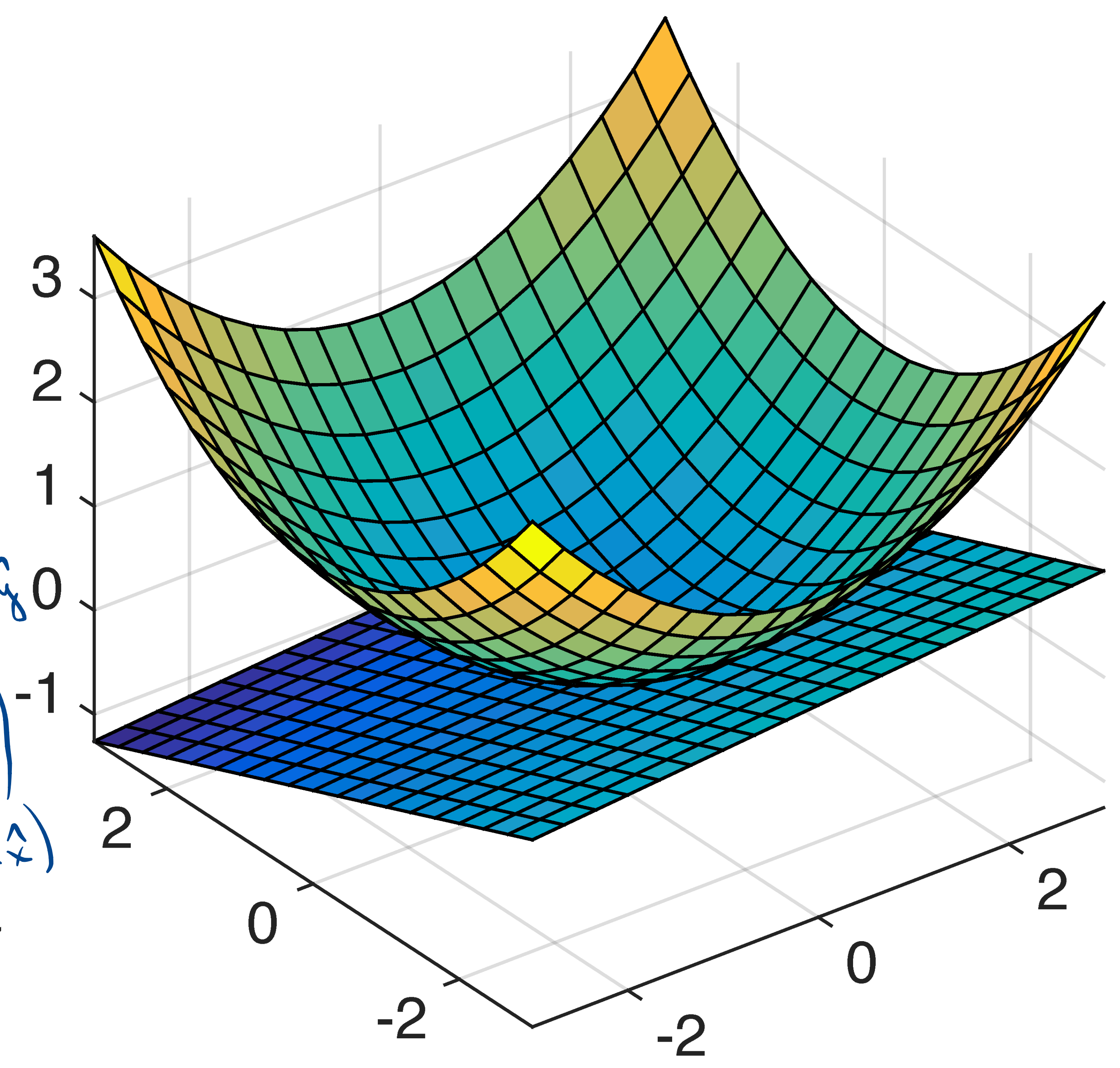
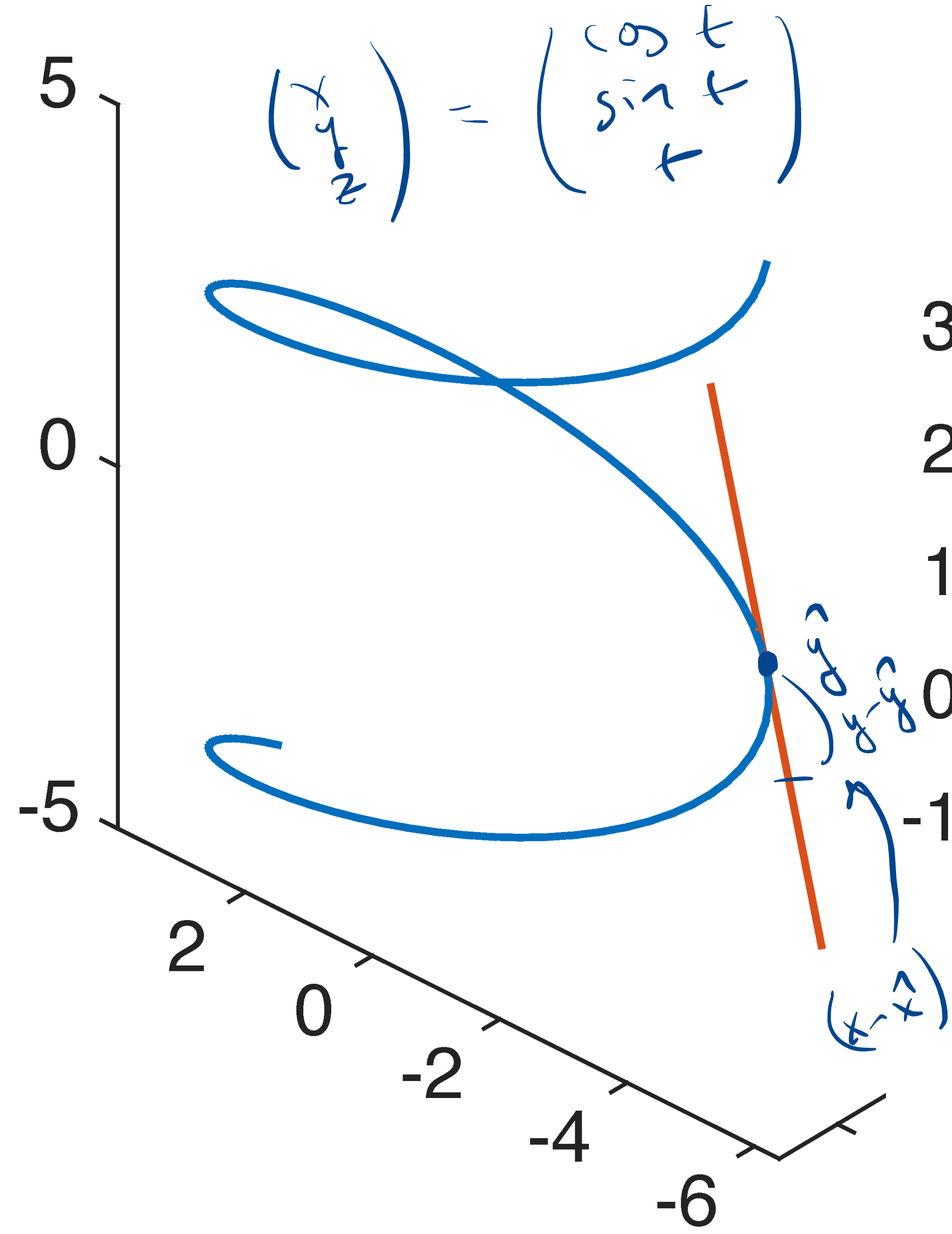
# Linear discriminant in function space





# Narrower RBFs





$$f: \mathbb{R}^1 \rightarrow \mathbb{R}^m$$

$$(y - \hat{y}) = A(x - \hat{x})$$

$\uparrow$  point where tangent

$\uparrow$  Jacobian

$$A_{ij} = \frac{\partial y_i}{\partial x_j}$$

$\uparrow$   
 $f(\hat{x})$

$$dy = A dx$$

$$\frac{dy}{dx}$$
$$df(x) = f'(x) dx$$
$$d(x^2 + 2x + 3) = (2x + 2) dx$$

$$d \ln \det A = \langle A^{-1}, dA \rangle$$

$$d \|x\| = \frac{x}{\|x\|} dx \quad x \neq 0$$

$$d(a f + b g) = a df + b dg$$

$$d(A^T X + 3Y) = A^T dX + 3dY$$

$$d(fg) = (df)g + f(dg)$$

if  $f$  const,  $= f dg$

$$d(fgh) = (df)gh + f(dg)h + fg(dh)$$

$$f = [ \dots x \dots ]$$

$$df = [ \dots x \dots dx \dots ]$$

↑ linear index

$$df = f'(x)dx$$

$$\downarrow$$

$$\frac{df}{dx} = f'(x)$$

$$df = \underbrace{[ \dots x \dots ]}_{\text{linear function}} dx$$

$$\hookrightarrow f'(x)$$

$$f(x) = u^3 + v^3$$

$$x = \begin{pmatrix} u \\ v \end{pmatrix}$$

$$\begin{aligned} df(x) &= 3u^2 du + 3v^2 dv \\ &= \underbrace{(3u^2 \quad 3v^2)}_{\hookrightarrow f'(x)} \begin{pmatrix} du \\ dv \end{pmatrix} \end{aligned}$$

$$\hookrightarrow \frac{df(x)}{dx}$$