

Math Foundations for ML

10-606

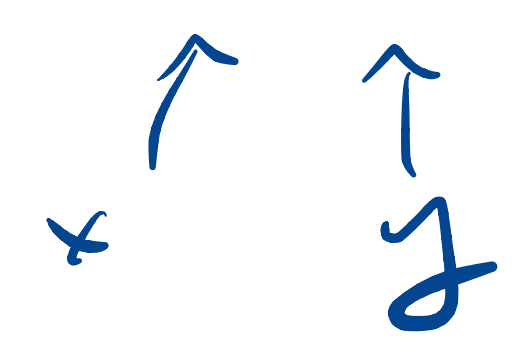
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Notes and reminders

- HW1 and Quiz1 are graded and viewable on Gradescope
- Further reading: Magnus & Neudecker
 - ▶ <https://onlinelibrary.wiley.com/doi/book/10.1002/9781119541219>
 - ▶ note their notation differs slightly from class; e.g., they define a function $df(x; dx)$ which takes the place of our $f'(x) dx$

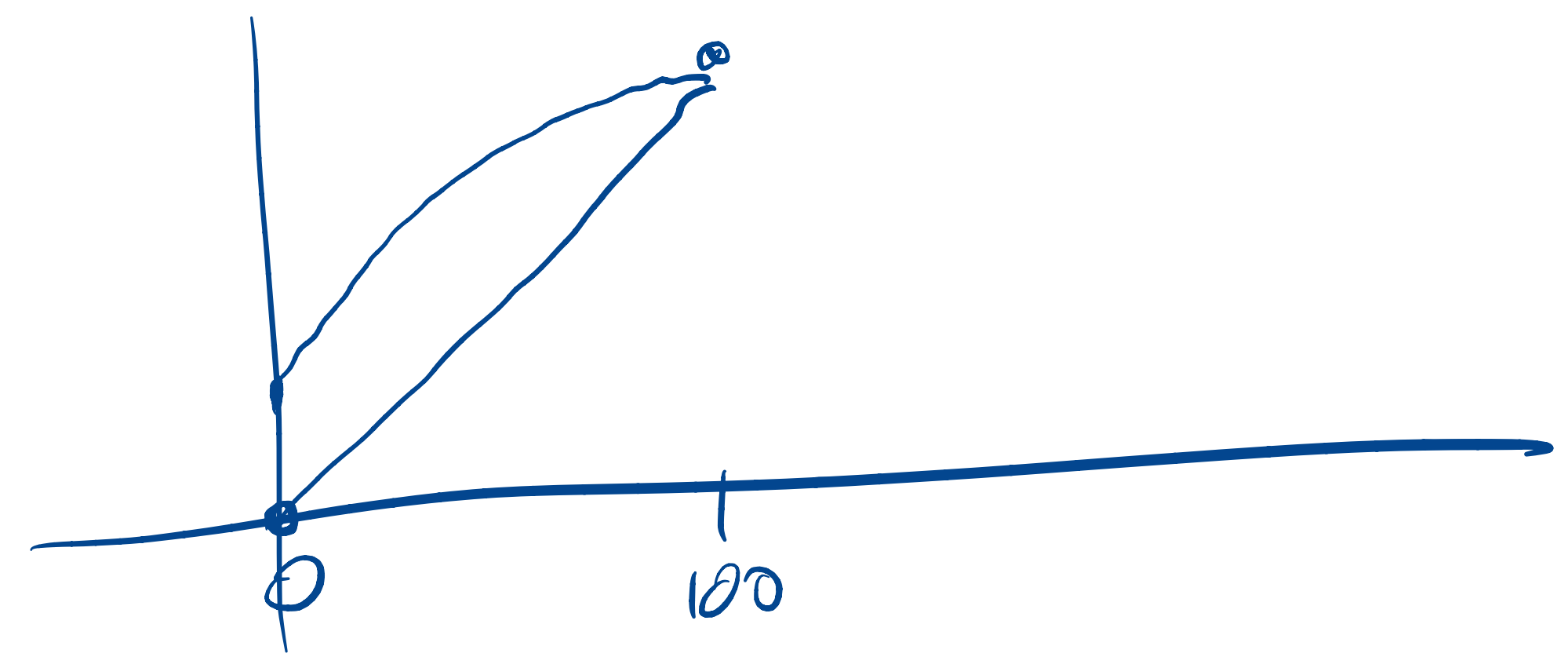
$$L(x) = ax + b$$

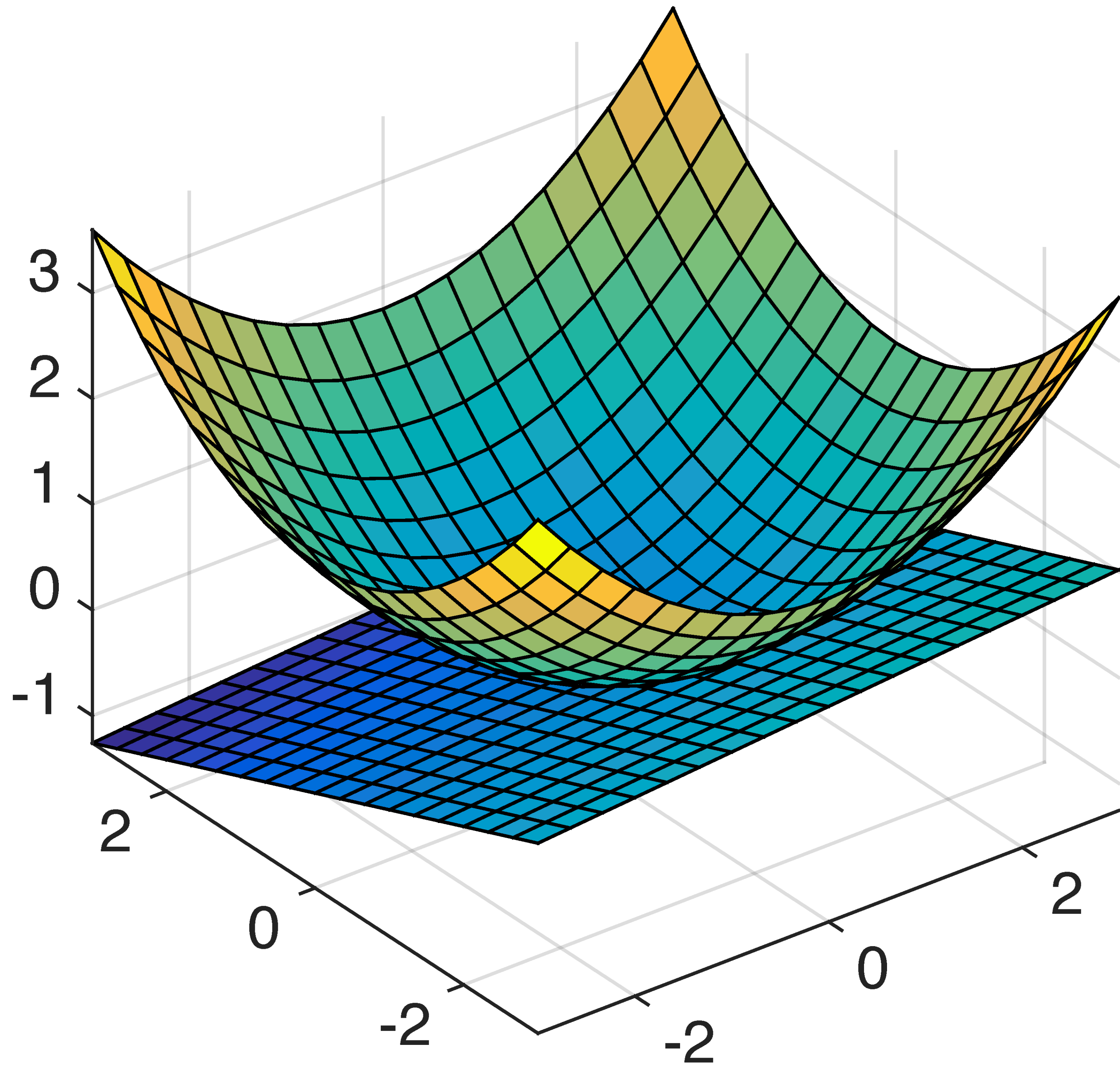
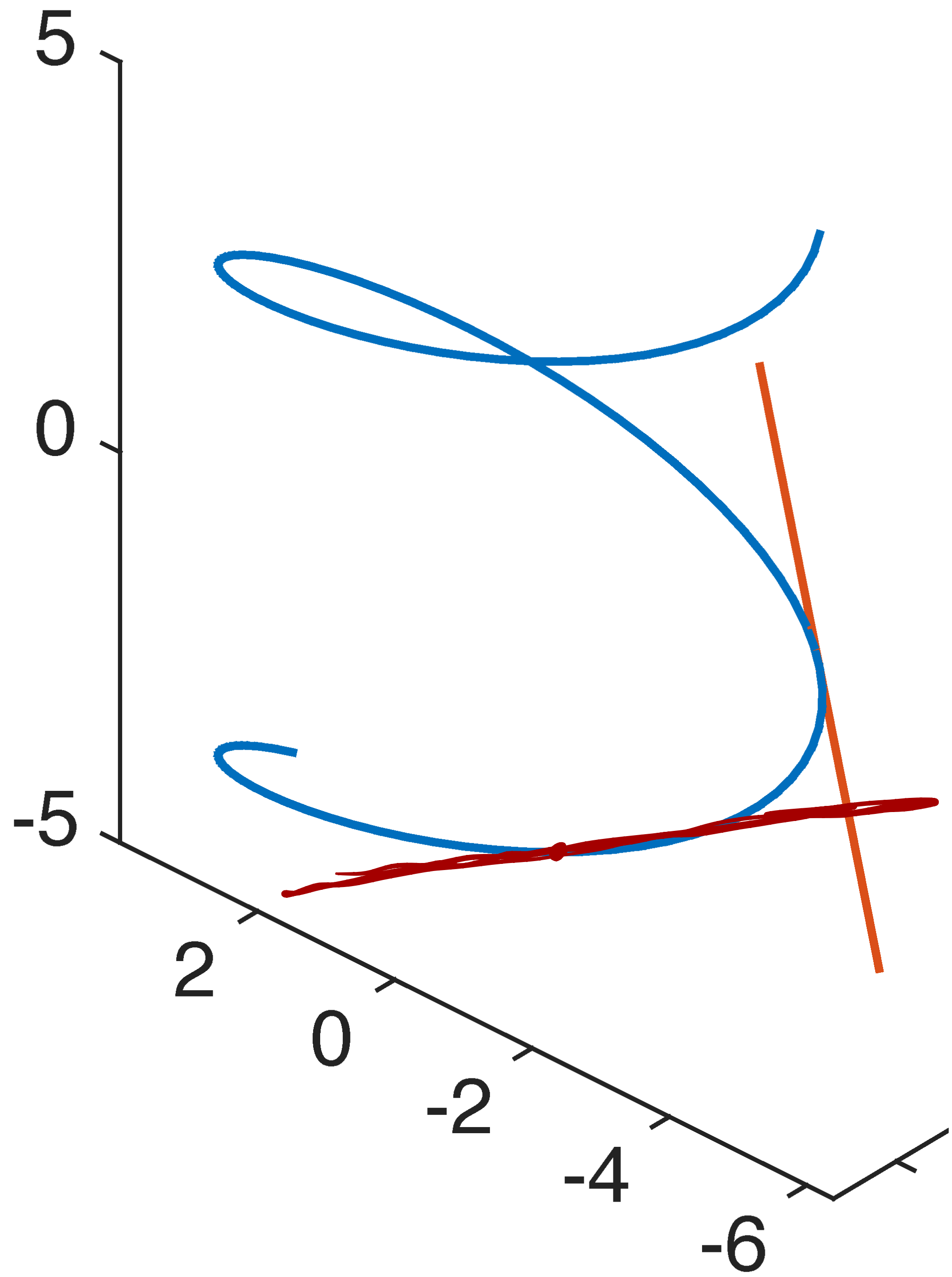
$$D = \{ (-2, 0), (0, -1), (1, 1) \}$$



$$\begin{aligned}
 & \left(a(-2) + b - 0 \right)^2 \rightarrow 4a^2 - 4ab + b^2 \\
 + & \left(a(0) + b - (-1) \right)^2 \rightarrow b^2 + 2b + 1 \\
 + & \left(a(1) + b - 1 \right)^2 \rightarrow a^2 + 2ab - 2a - 2b + 1
 \end{aligned}$$

$$5a^2 \rightarrow 10a$$





$$y = \ln \det A = f(A) \quad \begin{matrix} \mathbb{R}^{n \times n} \\ \downarrow \end{matrix} \quad A = LU \quad \det A = \det L \cdot \det U$$

$$dy = \langle A^{-1}, dA \rangle$$

$$dy = \left(\frac{dy}{dA} \right) dA = f'(A) dA$$

$$A = f(x) = B^T x B \quad \mathbb{R}^{n \times n}$$

$$dA = B^T dx B$$

$$\uparrow g'(x) dx$$

$$\rightarrow \langle BB^T, dx \rangle$$

$$\begin{aligned} dy &= \langle (B^T x B)^{-1}, B^T dx B \rangle \\ &= f'(g(x)) g'(x) dx \end{aligned}$$

$$\begin{aligned} u, v &\in \mathbb{R}^{n \times n} \\ \langle u, v \rangle &= \sum_{i,j} u_{ij} v_{ij} \end{aligned}$$

$$\begin{aligned} \det L &= \prod_i L_{ii} \\ \det U &= \prod_i U_{ii} \end{aligned}$$

$$X \in \mathbb{R}^{d \times T} \begin{pmatrix} | & | & & | \\ x_1 & x_2 & \dots & x_T \\ | & | & & | \end{pmatrix}$$

$$y \in \mathbb{R}^{1 \times T} (y_1 \dots y_T)$$

$$\hat{y} = w^T X \quad w \in \mathbb{R}^{d \times 1}$$

$$\varepsilon = y - \hat{y}$$

$$L = \varepsilon \cdot \varepsilon = (y - w^T X)(y - w^T X)^T$$

$$= yy^T + w^T X X^T w - 2w^T X y^T$$

$$dL = 0 +$$

$$- 2 dw^T X y^T$$

$$+ dw^T X X^T w$$

$$+ \underbrace{w^T d(X X^T w)}_{\rightarrow w^T X X^T dw}$$

$$w^T X X^T dw$$

$$= -2 dw^T X y^T + 2 dw^T X X^T w = 0$$

$$dw^T (-2 X y^T + 2 X X^T w) \rightarrow = 0$$

$$f(x, y) = \dots$$

$$df(x, y) = f_x(x, y) dx + f_y(x, y) dy$$

$$f(u) = \dots$$

$$df(u) = f'(u) du$$

$$u = \begin{pmatrix} x \\ y \end{pmatrix}$$

$$du = \begin{pmatrix} dx \\ dy \end{pmatrix}$$

$$(f_x(u) f_y(u)) \begin{pmatrix} dx \\ dy \end{pmatrix}$$

$$y = f\left(\underbrace{w_2 g(w_1 x + b_1)}_{u_1} + b_2\right) \rightarrow u_2$$

$$x \in \mathbb{R}^k$$

$$y \in \mathbb{R}^{d' \times k}$$

$$w_1 \in \mathbb{R}^{d' \times k}$$

$$w_2 \in \mathbb{R}^{d'}$$

$$b_1 \in \mathbb{R}^{d'}$$

$$b_2 \in \mathbb{R}^{d'}$$

$$y = f(u_2)$$

$$dy = f'(u_2) du_2$$

$$= f'(u_2) [w_2 dg(u_1)]$$

$$= f'(u_2) [w_2 g'(u_1) du_1]$$

$$= f'(u_2) w_2 g'(u_1) w_1 dx$$

$$f(z) = \begin{pmatrix} \frac{1}{1+e^{-z_1}} \\ \vdots \\ \frac{1}{1+e^{-z_i}} \end{pmatrix}$$

$$g(u) = \begin{pmatrix} \frac{1}{1+e^{-u_1}} \\ \vdots \\ \frac{1}{1+e^{-u_i}} \end{pmatrix}$$

$$\mathbb{R}^{d'}$$

$$u_2 = w_2 g(u_1) + b_2$$

$$f(z) = \begin{pmatrix} \vdots \\ \frac{1}{1+e^{-z_i}} \\ \vdots \end{pmatrix}$$

$$f'(z) = \begin{pmatrix} \vdots & & 0 \\ 0 & f_i(z)(1-f_i(z)) & \\ \vdots & & \vdots \end{pmatrix}$$

Jacobian of component wise f
is diagonal

$$X = \begin{pmatrix} | & | & | & | & | \\ | & | & | & | & | \\ | & | & | & | & | \end{pmatrix}$$

$$Y = X - \mu(X) e^T$$

\uparrow
 row-wise mean

$$e = \begin{pmatrix} | \\ | \\ | \\ | \\ | \end{pmatrix}$$

$$Z = \underbrace{V(Y)^{-\frac{1}{2}}}_\substack{\text{row-wise} \\ \text{variance}} \circ Y$$

$$\begin{pmatrix} 1 \\ 3 \\ -2 \end{pmatrix} \circ \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 2 & 3 \\ 12 & 15 & 18 \\ -14 & -16 & -18 \end{pmatrix}$$

$$\mu(X) = \frac{1}{n} X e$$

$$V(Y) = \frac{1}{n} \text{diag}(Y Y^T)$$

$$\begin{pmatrix} 1 & 1 & 1 \\ 3 & 3 & 3 \\ -2 & -2 & -2 \end{pmatrix}$$