

Submodularity

Recall definitions:

$$\forall A, B, \text{ with } A \subseteq B, \quad F(A \cup \{x\}) - F(A) \geq F(B \cup \{x\}) - F(B)$$

supermodularity $\left\{ \begin{array}{l} \leq \\ = \end{array} \right.$ modularity $\left\{ \begin{array}{l} \leq \\ = \end{array} \right.$

$$\hookrightarrow F(A) = \sum_{A_i \in A} F(\{A_i\})$$

"diminishing returns"

Equivalent definition: $\forall A, B, \quad F(A) + F(B) \geq F(A \cup B) + F(A \cap B)$

In class, we looked at:

$$\textcircled{1} \begin{cases} \max_A F(A) \\ \text{s.t. } |A| \leq k \end{cases} \quad \text{where } F \text{ is submodular}$$

 \hookrightarrow water quality sensing problem \hookrightarrow greedy algorithm optimal unless $P=NP$

$$\textcircled{2} \begin{cases} \min_{A \subseteq V} F(A) \\ F \text{ submodular} \end{cases}$$

 \hookrightarrow solvable in polytime (but with ellipsoid algorithm) \hookrightarrow If F symmetric, Queryanne's Algorithm is $O(n^3)$

In this recitation,

• examples of submodular functions

• closer look at minimizing submodular functions

Examples of submodular functions

ex →

Given graph $G = (V, E)$,

let $S = (V, F)$ be a subgraph $= F \subseteq E$.

S is a forest iff it contains no cycles.

e.g. spanning tree is forest with $|F| = |V| - 1$

Define graphic rank function of $A \subseteq E$:

$$r(A) = \max \{ |F| : F \subseteq A, (V, F) \text{ is forest} \}$$

Then $r(A)$ is submodular.

Note: $nc(A) = |V| - r(A) = \#$ connected components in subgraph (V, A) is supermodular.

ex →

Let V be collection of random variables.

Entropy $H(S)$ where $S \subseteq V$ is submodular.

Proof:

$$0 \leq I(A; B) = H(A) + H(B) - H(A \cup B) - H(A \cap B)$$

ex →

Let $f(A)$ where $A \subseteq V$ be mutual information:

$f(A) = I(A, V \setminus A)$. Then $f(A)$ is submodular.
Proof:

$$I(A, V \setminus A) = H(A) + H(V \setminus A) - H(V) - H(\emptyset)$$

$$\text{So, } f(A) + f(B) = [H(A) + H(B)] + [H(V \setminus A) + H(V \setminus B)] - 2H(V)$$

Since $H(\cdot)$ is submodular,

$$H(A) + H(B) \geq H(A \cap B) + H(A \cup B)$$

$$H(V \setminus A) + H(V \setminus B) \geq H(V \setminus (A \cup B)) + H(V \setminus (A \cap B))$$

$$\text{So } f(A) + f(B) \geq \cancel{[H(A \cap B) + H(A \cup B) - H(V)]}$$

$$\begin{aligned} & [H(A \cap B) + H(V \setminus (A \cap B)) - H(V)] \\ & + [H(A \cup B) + H(V \setminus (A \cup B)) - H(V)] \\ & = f(A \cap B) + f(A \cup B) \end{aligned}$$

Minimizing submodular functions

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Submodular polyhedron P_F

Let: $|V|=n$ $x \in \mathbb{R}^n$ where $x = \begin{pmatrix} x(V_1) \\ \vdots \\ x(V_n) \end{pmatrix}$

$$x(A) = \sum_{i \in A} x(V_i)$$

e.g. $V = \{V_1, V_2, V_3\}$ $n=3$ $x = \begin{pmatrix} 2 \\ 4 \\ 5 \end{pmatrix}$
 $A = \{1, 3\}$
 $x(A) = 7$

If F is a set function,

$$P_F = \{x \in \mathbb{R}^n \mid x(A) \leq F(A), \forall A \subseteq V\}$$

e.g. define F as:

v_1	v_2	v_3	$F(A)$
0	0	0	0
0	0	1	3
0	1	0	2 \rightarrow e.g. $F(\{V_2\}) = 2$
0	1	1	4
1	0	0	1
1	0	1	4
1	1	0	3
1	1	1	5

Then P_F is
 $\{x \in \mathbb{R}^n \mid x(V_1) \leq 1,$
 $x(V_2) \leq 2,$
 $x(V_3) \leq 3,$
 $x(V_2) + x(V_3) \leq 4,$
 $\dots\}$

Let $c \in \mathbb{R}_+^n$ be positive cost vector. Suppose we want

$$\left\{ \begin{array}{l} \max_x c^T x \\ \text{s.t. } x \in P_F \end{array} \right\} \rightarrow \text{LP with } 2^n \text{ constraints (in general)}$$

e.g. $\max_x (2, 9, 8) \cdot x$
 $\text{s.t. } x \in P_F$

Solve: Order v_2, v_3, v_1 , since $c(v_2) = 9 \geq c(v_3) \geq c(v_1)$

Optimal x^* is: $x^*(V_2) = F(\{V_2\}) = 2$

$$x^*(V_3) = F(\{V_2, V_3\}) - F(\{V_2\}) = 4 - 2 = 2$$

$$x^*(V_1) = F(\{V_1, V_2, V_3\}) - F(\{V_2, V_3\}) = 5 - 4 = 1$$

$$x^* = \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix}_{v_1, v_2, v_3}$$

Suppose $c_A = c_A(i) = \begin{cases} 1 & \text{if } i \in A \\ 0 & \text{otherwise} \end{cases}$

Consider $\begin{cases} \max_x c_A^T x \\ \text{s.t. } x \in P_F \end{cases}$

Then $c_A^T x^* = F(A)$, i.e. $A = \{V_1, V_3\}$

e.g. Let $c_A = (1, 0, 1)$ instead of previous value.

Solve for x^* :

Order V_1, V_3, V_2 since $c(V_1) \geq c(V_3) \geq c(V_2)$.

$$x^*(V_1) = F(\{V_1\}) = 1$$

$$x^*(V_3) = F(\{V_1, V_3\}) - F(\{V_1\}) = 4 - 1 = 3$$

$$x^*(V_2) = F(\{V_1, V_2, V_3\}) - F(\{V_1, V_3\}) = 5 - 4 = 1$$

So $c_A^T x^* = 4 = F(A)$

Note sum in $c_A^T x^*$ telescopes.

Define $\hat{f}(c_A) = \begin{cases} \max_x c_A^T x \\ \text{s.t. } x \in P_F \end{cases}$

Now extend to general cost vectors c :

$$c = \sum_i \lambda_i c_{A_i} \text{ where } c_{A_i} \text{ is 0-1-cost, } A_1 \supset A_2 \supset \dots$$

e.g. $c = \begin{pmatrix} 7 \\ 1.5 \\ 2 \end{pmatrix} \leftarrow$ pick smallest $c(i)$

$$c_{A_1} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \lambda_1 = 1.5$$

Now recurse on $c - \lambda_1 c_{A_1} = \begin{pmatrix} 5.5 \\ 0 \\ .5 \end{pmatrix}$

to get:

$$c_{A_2} = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}, \lambda_2 = .5$$

$$c_{A_3} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \lambda_3 = 5$$

Then $\hat{f}(c) = \sum_i \lambda_i \hat{f}(c_{A_i}) = \sum_i \lambda_i F(A_i)$

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[Thm: $\hat{f}(c)$ is convex in $c \in \mathbb{R}_+^n$ iff
 F is submodular.]

(I'm not posting notes on Queyranne's Algorithm, so if you're interested in learning more about it, look up: Maurice Queyranne. "Minimizing symmetric submodular functions." Math. Prog. 82 (1998).