10-423/623: Generative Al Lecture 1 – Recurrent Neural Networks and Language Modelling

Henry Chai & Matt Gormley 8/26/24

What is Generative AI?

AI?

 The field of artificial intelligence is concerned with developing computer systems that mimic (or exceed) human behavior

Sub-goals:

Perception

Reasoning

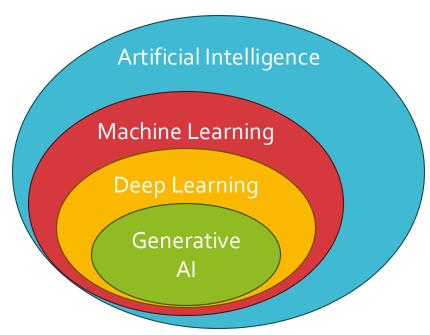
Planning

Communication

Creativity

Control / Motion / Manipulation

Learning



AI?

 The field of artificial intelligence is concerned with developing computer systems that mimic (or exceed) human behavior

- Sub-goals:
 - Perception
 - Reasoning
 - Planning
 - Communication
- Large language models are capable (to varying degrees) or comprehending and responding to natural language

- Creativity
- Control / Motion / Manipulation
- Learning

AI?

- The field of artificial intelligence is concerned with developing computer systems that mimic (or exceed) human behavior
- Sub-goals:
 - Perception
 - Reasoning
 - Planning
 - Communication
- Text-to-image models (e.g., Midjourney) or text-to-music models (MusicGen)

- Creativity
- Control / Motion / Manipulation
- Learning

AI?

- The field of artificial intelligence is concerned with developing computer systems that mimic (or exceed) human behavior
- Sub-goals:
 - Perception
 - Reasoning
 - Planning
 - Communication
 - Creativity

- Multimodal models can
 answer natural language
 questions about images and
 perform zero-shot
 classification
- Control / Motion / Manipulation
- Learning

AI?

 The field of artificial intelligence is concerned with developing computer systems that mimic (or exceed) human behavior

- Sub-goals:
 - Perception
 - Reasoning
 - Planning
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 - Creativity
 - Control / Motion / Manipulation
 - Learning

LLMs have opened new possibilities in how we approach the learning problem e.g., in-context learning

AI?

- The field of artificial intelligence is concerned with developing computer systems that mimic (or exceed) human behavior
- Sub-goals:
 - Perception
 - Reasoning
 - Planning
 - Communication
 - Creativity

- LLMs are decent at certain reasoning tasks using e.g., chain-of-thought prompting
- Control / Motion / Manipulation
- Learning

AI?

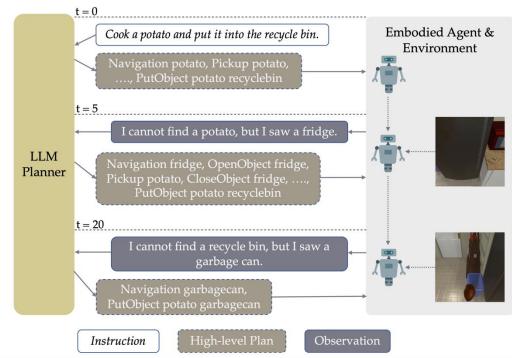
- The field of artificial intelligence is concerned with developing computer systems that mimic (or exceed) human behavior
- Sub-goals:
 - Perception
 - Reasoning
 - Planning
 - Communication
 - Creativity

- LLM-Planner: a modified
 LLM that can help embodied
 agents (i.e., robots) perform
 complex, multi-step tasks by
 generating high-level plans
- Control / Motion / Manipulation
- Learning

AI?

 The field of artificial intelligence is concerned with developing computer systems that mimic (or exceed) human behavior

- Sub-goals:
 - Perception
 - Reasoning
 - Planning
 - Communication
 - Creativity



- Control / Motion / Manipulation
- Learning

AI?

- The field of artificial intelligence is concerned with developing computer systems that mimic (or exceed) human behavior
- Sub-goals:
 - Perception
 - Reasoning
 - Planning
 - Communication
 - Creativity

- DayDreamer: learns a
 "World Model" for
 reinforcement learning
 without the need for
 simulated data; allows for
 rapid training of RL agents
- Control / Motion / Manipulation
- Learning

AI?

 The field of artificial intelligence is concerned with developing computer systems that mimic (or exceed) human behavior

- Sub-goals:
 - Perception
 - Reasoning
 - Planning
 - Communication
 - Creativity
 - Control / Motion / Manipulation
 - Learning

The ability to create or generate novel ideas/concepts (to "imagine") is central to how humans successfully perform these tasks!

Teach me about narwhals in the style of a Shakespearean sonnet



Behold the narwhal, monarch of the sea,

With spiral tusk that doth the waves adorn,

A unicorn of ocean's mystery,

By nature's hand so wondrously born.

Beneath the icy realms where cold winds blow,

This creature glides through waters dark and deep,

Its ivory lance, a silent, graceful show,

A secret kept where ancient legends sleep.

Yet not for battle is this horn designed,

But rather, like a herald in the night,

It senses all that swims or stirs behind,

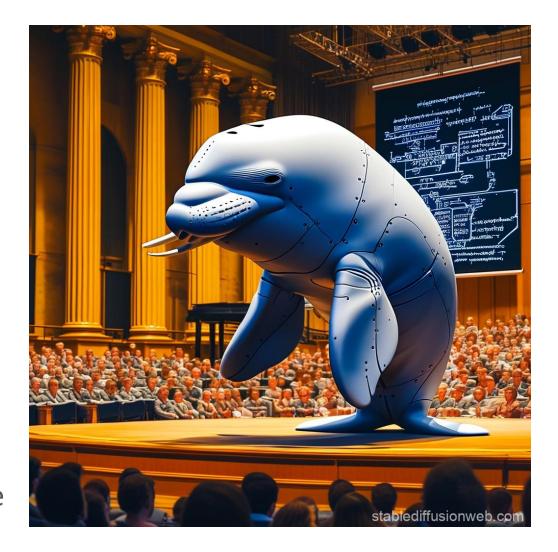
Guiding its path through realms devoid of light.

O narwhal, gentle giant of the brine,

In thee, both strength and beauty intertwine.

む □ □ □ □ ♥ ∨

Prompt: a picture of a narwhal giving a lecture on generative AI. Put the narwhal on a stage in front of a large audience. The narwhal should appear scholarly and is presenting off of a slide deck, gesturing at some dense equations on the slide





Whimsical Indie Folk acoustic guitar and ukulele accompaniment, playful and quirky, with a laid-back tempo around 90 BPM.



Epic cinematic score with a heavy, pulsing bassline and energetic trap beats, blending elements of electronic and orchestral music, in a 140-150 BPM tempo.



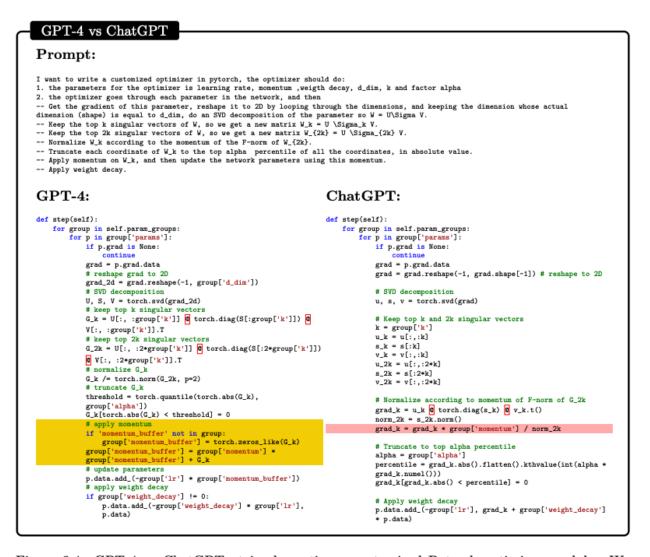


Figure 3.4: GPT-4 vs ChatGPT at implementing a customized Pytorch optimizer module. We highlight the astuteness of GPT-4 vs the mistake by ChatGPT at 'applying momentum'.



Figure 1.3: We queried GPT-4 three times, at roughly equal time intervals over the span of a month while the system was being refined, with the prompt "Draw a unicorn in TikZ". We can see a clear evolution in the sophistication of GPT-4's drawings.

GPT-4 vs ChatGPT

Prompt:

A function f is called {increasing}_{emphasize!} if f(s) = f(t) holds for every s = t. Consider the formula: limit_{x goes to 0} {limit when n approaches infinite} underscore{ \matrix[[sum of i from 1 to n (f(nx) - integral from 0 to x sin(nx) dx), ((x + 2/8)^2 - 5)/((4x-1/x^2) /(n xor 3)), \, ..., partial f(x/n) over partial x * (e^{-i*somega n x} + 3(x#7)), f inverse of (x mod n)]] multiply \matrix{1, 1, ..., 1 \\ 1, 1, ..., 1} } {grey_color{this gives us a good impression about the function}}

Convert the above paragraph to LaTeX.

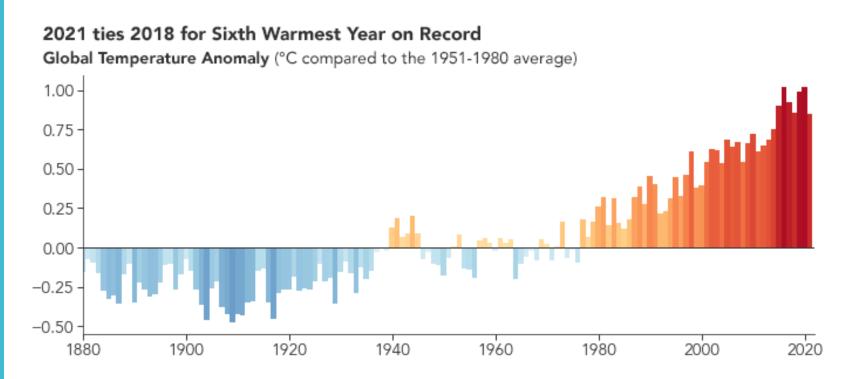
GPT-4:

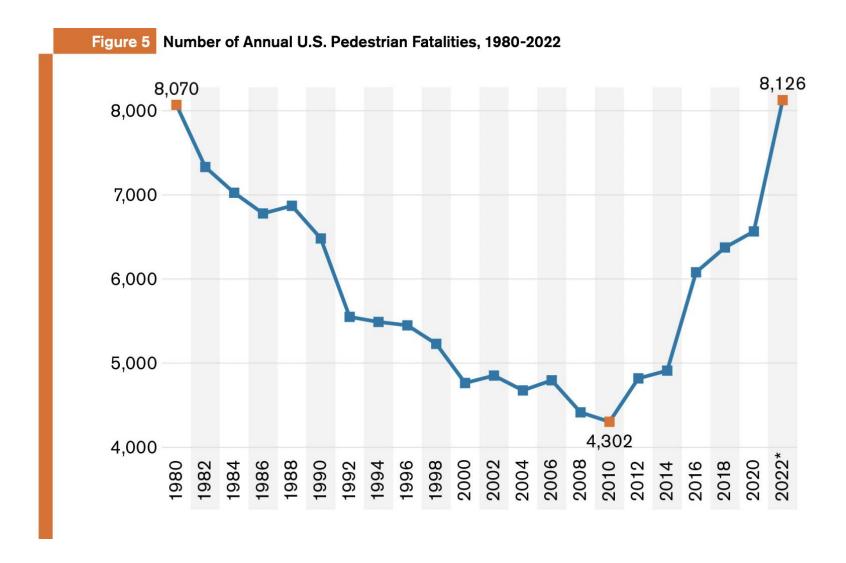
A function f is called increasing if $f(s) \leq f(t)$ holds for every $s \leq t$. Consider the formula:

$$\lim_{x \to 0} \lim_{n \to \infty} \left[\begin{array}{c} \sum_{i=1}^{n} \left(f(nx) - \int_{0}^{x} \sin(nx) \, dx \right), & \frac{\left(x + \frac{2}{8} \right)^{2} - 5}{\frac{4x - 1/x^{2}}{n \oplus 3}}, \\ \vdots & \vdots & \vdots \\ \frac{\partial f(x/n)}{\partial x} \cdot \left(e^{-i\omega nx} + 3(x\#7) \right), & f^{-1}(x \bmod n) \end{array} \right] \times \begin{bmatrix} 1 & 1 & \cdots & 1 \\ 1 & 1 & \cdots & 1 \end{bmatrix}$$
this gives us a good impression about the function











enaadget · 5d · on MSN

Waymo director says the company's cars won't honk at each other anymore

Waymo's self-driving cars no longer honk when near each other, Waymo's Director of Product and Operations Vishay Nihalani ...



STECHNICA - 12d

Self-driving Waymo cars keep SF resident honking at each other

Silicon Valley's latest disruption? Your sleep schedule. On reported that San Francisco's South of ...



ars PC +11 relevant news >

NEWS · 13d · on MSN

Waymo cars honk at each other throughou SF neighbors

San Francisco resident Randol White says he heard the ne weeks ago -- he was woken up around ...

Los Angeles Times · 13d · on MSN

Driverless Waymo taxis disturb peace, sle honking — at each other

Waymo's robotaxis have started occupying a new San Fra residents are finding the self-driving cars ...





yahoo! · 5d

Driverless Waymo cars still honking despite software fix



What is Generative Al 10-423/623: Topics

- Generative models of text
 - RNN LMs / Autodiff
 - Transformer LMs
 - Pre-training, fine-tuning, evaluation, decoding
- Generative models of images
 - CNNs / Transformers for vision
 - GANs, Conditional GANs
 - VAEs and Diffusion models
- Applying and adapting foundation models
 - Reinforcement learning with human feedback (RLHF)
 - Parameter-efficient fine tuning
 - In-context learning for text
 - In-context learning for vision
- Multimodal foundation models
 - Text-to-image generation
 - Aligning multimodal representations
 - Visual-language foundation models

- Scaling models
 - Efficient decoding strategies
 - Distributed training
 - Scaling laws and data
- What can go wrong?
 - Safety/bias/fairness
 - Hallucinations
 - Adversarial attacks
 - Cheating how to watermark,
 Legal issues, e.g., copyright,...
 - Drift in performance
 - Data contamination
- Advanced Topics
 - State space models
 - Code generation
 - Audio understanding and synthesis
 - Video synthesis

- https://www.cs.cmu.edu/~mgormley/courses/10423/
- Also http://423.mlcourse.org

What is

Generative
Al 10-423/623:
Website

https://www.cs.cmu.edu/~mgormley/courses/10423/syllabus.html

This entire page is required reading

What is Generative Al 10-423/623: Syllabus

What is Generative Al 10-423/623: Syllabus

- https://www.cs.cmu.edu/~mgormley/courses/10423/syllabus.html
- Assessments:
 - 40% homework
 - 10% quizzes
 - 20% exam
 - 25% project
 - 5% participation

What is Generative Al 10-423/623: Homework

• https://www.cs.cmu.edu/~mgormley/courses/10423/coursework.html

HW#	Topic	Model	Application	Туре
0	PyTorch Primer	image classifier + text classifier	Vision + language	written + programming
1	LLMs	Transformer with RoPE and GQA	Charater- level text generation	written + programming
2	Image Generation	Diffusion model	Infilling	written + programming
3	Adapters for LLMs	Llama with LoRA	Code	written + programming
4	Multimodal Foundation Models	Text-to- image model	Vision <i>and</i> language	written + programming
623 (623 students only)	Recent Research	N/A	Generative Al	video presentation

What is Generative Al 10-423/623: Homework

https://www.cs.cmu.edu/~mgormley/courses/10423/coursework.html

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Generative Al

10-423 + 10-623, Fall 2024 School of Computer Science Carnegie Mellon University

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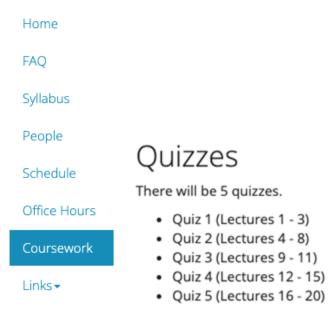
Assignments

There will be 5 homework assignments (and a special extra assignment for 10-623 only). The assignments will consist of both theoretical and programming problems. Homework assignments will be released via a Piazza announcement explaining where to find the handout, LaTeX template, etc.

- Homework 0: PyTorch Primer
- Homework 1: Large Language Models
- Homework 2: Image Generation
- · Homework 3: Applying and Adapting LLMs
- · Homework 4: Multimodal Foundation Models
- Homework 623: (10-623 only)

What is Generative Al 10-423/623: Quizzes

https://www.cs.cmu.edu/~mgormley/courses/10423/coursework.html



Quizzes will be held in-class, before the start of lecture

What is Generative Al 10-423/623: Quizzes

https://www.cs.cmu.edu/~mgormley/courses/10423/schedule.html

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Important Notes

This schedule is **tentative** and subject to change. Please check back often.

Tentative Schedule

Date	Lecture	Readings	Announcements
Generative models of text			
Mon, 26-Aug	Lecture 1 : RNN LMs / Autodiff	 Sequence Modeling: Recurrent and Recursive Nets. Ian Goodfellow, Yoshua Bengio, & Aaron Courville (2016). Deep Learning, Chapter 10.1-10.5. A Framework for the Cooperation of Learning Algorithms. Léon Bottou, Patrick Gallinari (1991). Advances in Neural Information Processing Systems. PyTorch: An Imperative Style, High- Performance Deep Learning Library. Paszke et al. (2019). Advances in Neural Information Processing Systems. 	
Wed, 28-Aug	Lecture 2 : Transformer LMs	 The Long Short-Term Memory and Other GatedRNNs. Ian Goodfellow, Yoshua Bengio, & Aaron Courville (2016). Deep Learning, Chapter 10.10-10.12. Attention Is All You Need. Vaswani et al. (2017). NeurIPS. The Illustrated Transformer. Alammar (2018). 	HW0 out
Fri, 30-Aug	Recitation: HW0		
Mon, 2-Sep	(Labor Day - No Class)		

What is Generative Al 10-423/623: Quizzes

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https://www.cs.cmu.edu/~mgormley/courses/10423/schedule.html

Wed, 11-Sep	Lecture 5 : Encoder-only Transformers / Vision Transformers	 BERT: Pre-training of Deep Bidirectional Transformers for Language Understanding. Devlin et al. (2018). NAACL. An Image is Worth 16x16 Words: Transformers for Image Recognition at Scale. Dosovitskiy et al. (2021). ICLR. 	Quiz 1 (in-class, L1-L4)
Fri, 13-Sep	Recitation: HW1		
Mon, 16-Sep	Lecture 6 : Generative Adversarial Networks (GANs) / PGM	 Generative Adversarial Nets. Goodfellow et al. (2014). NeurIPS. NuerIPS 2016 Tutorial: Generative Adversarial Networks. Goodfellow (2017). NeurIPS Tutorials. 	
Wed, 18-Sep	Lecture 7 : Variational Autoencoders (VAEs) / Diffusion models (Part I)	 Variational Inference: A Review for Statisticians. Blei, Kucukelbir, and McAuliffe (2018). High-Level Explanation of Variational Inference. Jason Eisner (2011). Tutorial on Variational Autoencoders. Carl Doersch (2016). 	
Fri, 20-Sep	(No Recitation)		
Mon, 23-Sep	Lecture 8 : Diffusion models (Part II)	 Deep Unsupervised Learning using Nonequilibrium Thermodynamics. Sohl- Dickstein et al. (2015). MLR. Denoising Diffusion Probabilistic Models. Ho et al. (2020). NeurIPS. 	HW1 due HW2 out (L4-L8)
	Applying and adapting	ng foundation models	
Wed, 25-Sep	Lecture 9 : In-context learning for text & for vision		Quiz 2 (in-class, L4-L8)

What is Generative Al 10-423/623: Exam

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Mon, 4-Nov	Lecture 18 : Efficient decoding strategies		HW4 due HW623 out
Advanced Topics			
Wed, 6-Nov	Lecture 19 : Long Context in LLM		
Fri, 8-Nov	(No Recitation)		
Mon, 11-Nov	In-Class Exam		Pass/no pass & withdrawal deadline
Wed, 13-Nov	Lecture 20 : State Space Models		
Fri, 15-Nov	(No Recitation)		Project proposal due

What is Generative Al 10-423/623: Project

• https://www.cs.cmu.edu/~mgormley/courses/10423/schedule.html

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Mon, 4-Nov	Lecture 18 : Efficient decoding strategies		HW4 due HW623 out
Advanced Topics			
Wed, 6-Nov	Lecture 19 : Long Context in LLM		
Fri, 8-Nov	(No Recitation)		
Mon, 11-Nov	In-Class Exam		Pass/no pass & withdrawal deadline
Wed, 13-Nov	Lecture 20 : State Space Models		
Fri, 15-Nov	(No Recitation)		Project proposal due

• Anr

What is Generative Al 10-423/623: Project

https://www.cs.cmu.edu/~mgormley/courses/10423/schedule.html

- Apply generative AI to a problem / setting of your choice
- Report back to the class during a poster session to be held sometime over finals period
- You must complete the project in groups of 3



Prompt to ChatGPT-4o: Create an image of three Scottish terriers in traditional Scottish outfits working collaboratively on a project for a generative AI course

What is Generative Al 10-423/623: Syllabus

- https://www.cs.cmu.edu/~mgormley/courses/10423/syllabus.html
- Assessments:
 - 40% homework
 - 10% quizzes
 - 20% exam
 - 25% project
 - 5% participation
 - Participation will be based on a few (out-of-class) surveys/polls and some project deliverables

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What is Generative Al 10-423/623: Prerequisites

- https://www.cs.cmu.edu/~mgormley/courses/10423/syllabus.html
- You must have taken either:
 - an introduction to machine learning course (e.g., 10-301 / 601 or 10-315 or 10-701 or 10-715) or
 - an introduction to deep learning course (e.g., 11-485 / 685 / 785)
- You do not need to have familiarity with deep learning or PyTorch

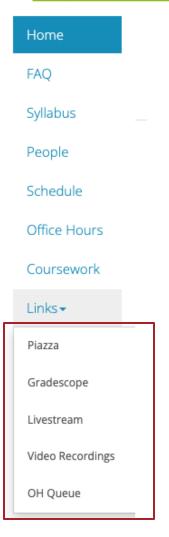
What is Generative Al 10-423/623: Collaboration

- https://www.cs.cmu.edu/~mgormley/courses/10423/syllabus.html
- Collaboration is strongly encouraged in this course!
- But collaboration must always be documented
- You must always write your own code/solutions
 - No re-use of found code or code written for previous assignments
- Please see the syllabus for
 - recommended collaboration practices and
 - penalties for violations
- Note the 10-423/623 collaboration policy is different (more lenient)
 than our 10-301/601 policies

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What is Generative Al 10-423/623: Technologies

https://www.cs.cmu.edu/~mgormley/courses/10423/



- Piazza (for Q&A)
- Gradescope (for submitting homework)
- Zoom (for livestreams)
- Panopto (for recordings)
- Google forms (for surveys/polls)

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What is **Generative** Al 10-423/623: Office Hours

https://www.cs.cmu.edu/~mgormley/courses/10423/officehours.html

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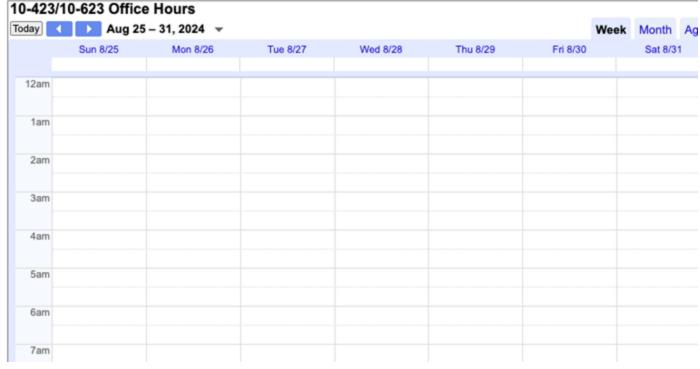
Schedule Sun 8/25 Office Hours

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What is Generative Al 10-423/623: Learning Objectives

You should be able to...

- 1. Differentiate between different mechanisms of learning such as parameter tuning and in-context learning.
- 2. Implement the foundational models underlying modern approaches to generative modeling, such as transformers and diffusion models.
- 3. Apply existing models to real-world generation problems for text, code, images, audio, and video.
- 4. Employ techniques for adapting foundation models to tasks such as fine-tuning, adapters, and in-context learning.
- 5. Enable methods for generative modeling to scale-up to large datasets of text, code, or images.
- 6. Use existing generative models to solve real-world discriminative problems and for other everyday use cases.
- 7. Analyze the theoretical properties of foundation models at scale.
- 8. Identify potential pitfalls of generative modeling for different modalities.
- 9. Describe societal impacts of large-scale generative AI systems.

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What is Generative AI?

• Generative AI is just modelling and sampling from probability distributions that look like

$$p(x_{t+1}, x_t, ..., x_1)$$
or
 $p(x_{t+1} | x_t, ..., x_1)$

Language Models

1. Convert raw text into a sequence of words (or "tokens")

$$\mathbf{x} = [x_1, x_2, \dots, x_t]$$

2. Learn (or approximate) a joint probability distribution over sequences

$$p(\mathbf{x}) = p(x_1, x_2, \dots, x_t)$$

3. Sample from the implied conditional distribution to generate new words (or "tokens")

$$p(x_{t+1}|x_1, x_2, ..., x_t) = \frac{p(x_1, x_2, ..., x_t, x_{t+1})}{p(x_1, x_2, ..., x_t)}$$

• In practice, it often makes more sense to learn (or approximate) this conditional distribution directly

Language Models

1. Convert raw text into a sequence of words (or "tokens")

$$\mathbf{x} = [x_1, x_2, \dots, x_t]$$

2. Learn (or approximate) a joint probability distribution over sequences

$$p(\mathbf{x}) = p(x_1, x_2, \dots, x_t)$$

• Use the chain rule of probability: predict the next word based on the previous words in the sequence

$$p(\mathbf{x}) = p(x_1)$$

$$* p(x_2|x_1)$$

$$* p(x_3|x_2, x_1)$$

$$\vdots$$

$$* p(x_t|x_{t-1}, ..., x_1)$$

Language Models

1. Convert raw text into a sequence of words (or "tokens")

$$\mathbf{x} = [x_1, x_2, \dots, x_t]$$

2. Learn (or approximate) a joint probability distribution over sequences

$$p(\mathbf{x}) = p(x_1, x_2, \dots, x_t)$$

 Use the chain rule of probability: predict the next word based on the previous words in the sequence

$$p(\mathbf{x}) = p(x_1) \prod_{i=2}^{t} p(x_i | x_{i-1}, \dots, x_1)$$

Language Models: Example

1. Convert raw text into a sequence of words (or "tokens")

Narwhals are way cooler than parrots x_1 x_2 x_3 x_4 x_5 x_6

2. Learn (or approximate) a joint probability distribution over sequences

$$p(x_1, x_2, x_3, x_4, x_5, x_6) =$$

Narwhals
$$p(x_1)$$
Narwhals are
$$p(x_2|x_1)$$
Narwhals are way
$$p(x_3|x_2,x_1)$$
Narwhals are way cooler
$$p(x_4|x_3,x_2,x_1)$$
Narwhals are way cooler than
$$p(x_5|x_4,x_3,x_2,x_1)$$
Narwhals are way cooler than parrots

 $p(x_6|x_5,x_4,x_3,x_2,x_1)$

n-GramLanguageModels

1. Convert raw text into a sequence of words (or "tokens")

$$\mathbf{x} = [x_1, x_2, \dots, x_t]$$

2. Idea: approximate the chain rule using conditional independence assumptions

bigram model
$$(n = 2)$$
: $p(x) \approx p(x_1) \prod_{i=2}^{t} p(x_i | x_{i-1})$

n-GramLanguageModels

1. Convert raw text into a sequence of words (or "tokens")

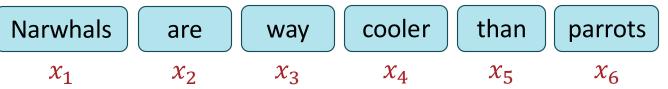
$$\mathbf{x} = [x_1, x_2, \dots, x_t]$$

2. Idea: approximate the chain rule using conditional independence assumptions

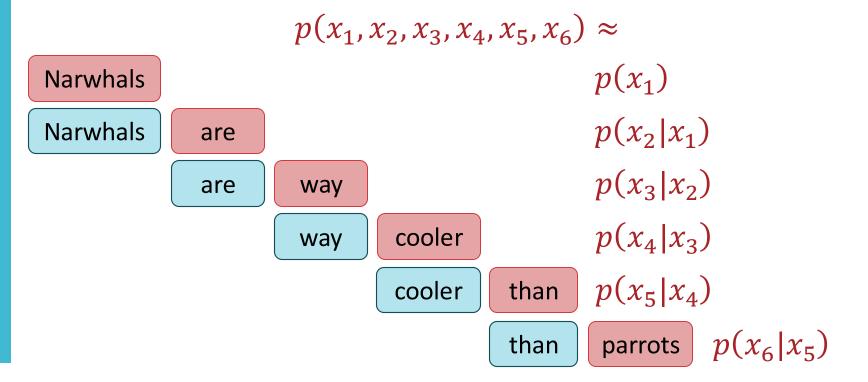
trigram model:
$$p(\mathbf{x}) \approx p(x_1)p(x_2|x_1) \prod_{i=3}^{t} p(x_i|x_{i-1}, x_{i-2})$$

Bigram Language Models: Example

1. Convert raw text into a sequence of words (or "tokens")

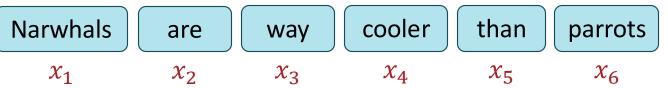


2. Idea: approximate the chain rule using conditional independence assumptions

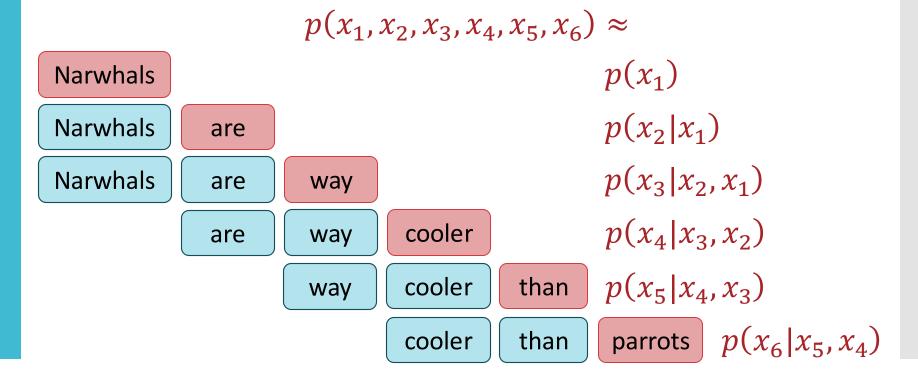


Trigram Language Models: Example

1. Convert raw text into a sequence of words (or "tokens")



2. Idea: approximate the chain rule using conditional independence assumptions



n-gramLanguageModels:Training

- What exactly are we learning when we train an n-gram language model?
- A *lot* of probability distributions...

x_t	$p(x_t \text{narwhals, are})$			
aquatic	0.04			
awesome	x_t	$p(x_t \text{cooler, than})$		
:	ice	0.01		
fish	cool	x_t	$p(x_t axo$	lotls, eat)
	:	shrimp	C).1
	Henry	narwhals	0.0	0005
		:		:
		Henry	0.0	0001



n-gramLanguageModels:Training

- How do we train an n-gram language model?
- Using training data! Simply count frequency of next words

Narwhals are big aquatic mammals that...

Who knows what **narwhals are** hiding?

Watch out, the **narwhals are** coming!

These narwhals are friendly!

Narwhals are a surprisingly large p
The narwhals are a punk rock band
Narwhals are big fans of machine
Narwhals are generated by AI.

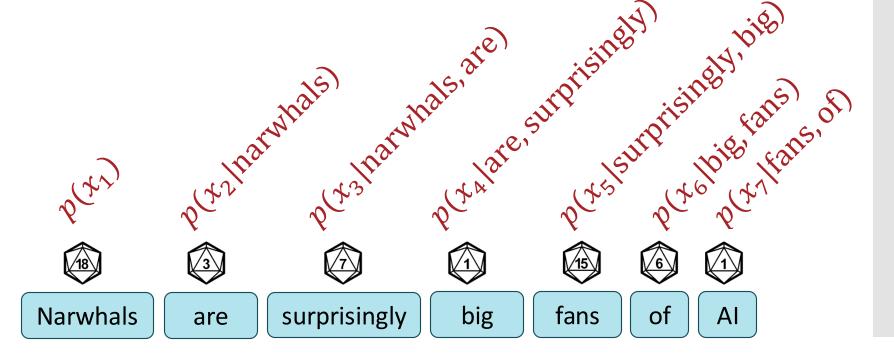
• Why are we counting?

x_t	$p(x_t \text{narwhals, are})$		
big	2/8		
hiding	1/8		
coming	1/8		
friendly	1/8		
а	2/8		
generated	1/8		

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n-gramLanguageModels:Generation

- How do we generate new sequences using an n-gram language model?
- Sample from the learned distributions and use the sampled words to determine what distribution to use next



n-gramLanguageModels:Generation?

- How do we generate new sequences using an n-gram language model?
- Sample from the learned distributions and use the sampled words to determine what distribution to use next

Training Data (Shakespeare)

I tell you, friends, most charitable care ave the patricians of you. For your wants, Your suffering in this dearth, you may as well Strike at the heaven with your staves as lift them Against the Roman state, whose course will on The way it takes, cracking ten thousand curbs Of more strong link asunder than can ever Appear in your impediment.

5-Gram Model

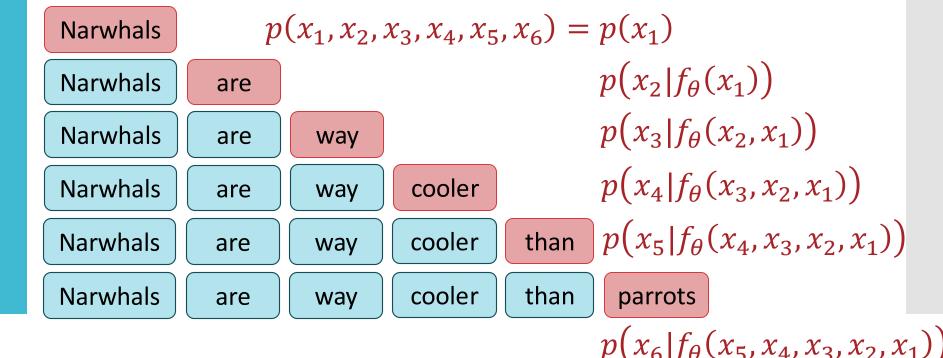
Approacheth, denay. dungy
Thither! Julius think:
grant,--O Yead linens,
sheep's Ancient, Agreed:
Petrarch plaguy Resolved
pear! observingly honourest
adulteries wherever scabbard
guess; affirmation--his
monsieur; died. jealousy,
chequins me.

Language Models

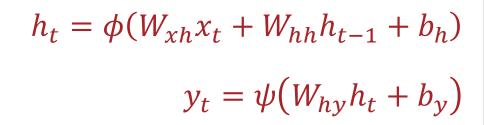
1. Convert raw text into a sequence of words (or "tokens")

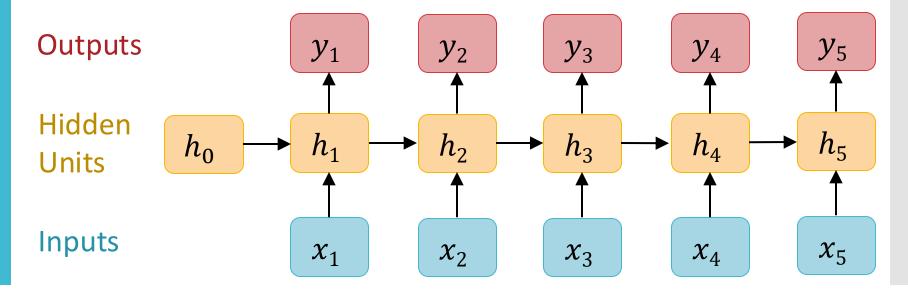
Narwhals are way cooler than parrots
$$x_1$$
 x_2 x_3 x_4 x_5 x_6

Idea: approximate the chain rule using a parametric
function to compute fixed-length representations of prior
words and condition on those to compute next words



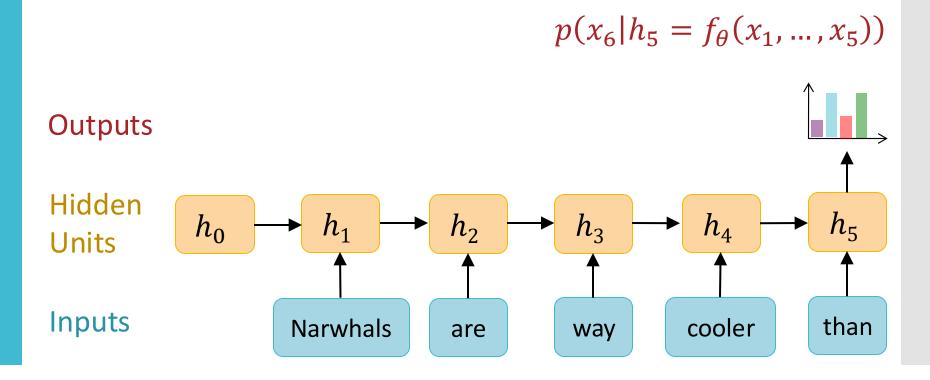
Recurrent Neural Networks



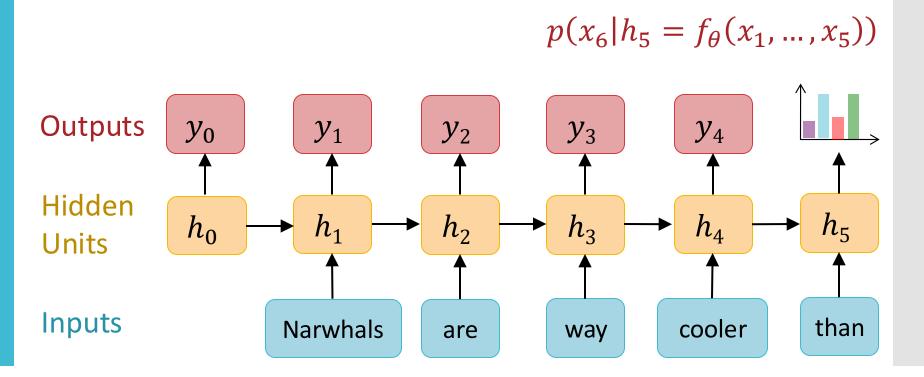


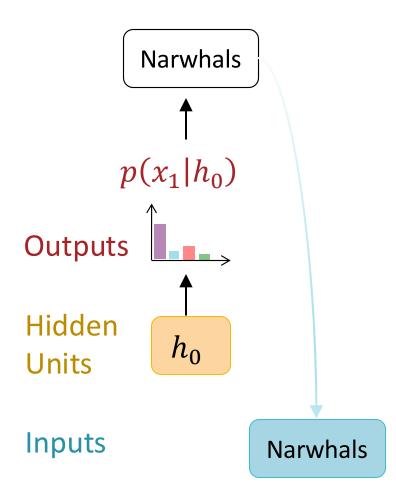
Recurrent Neural Network Language Models

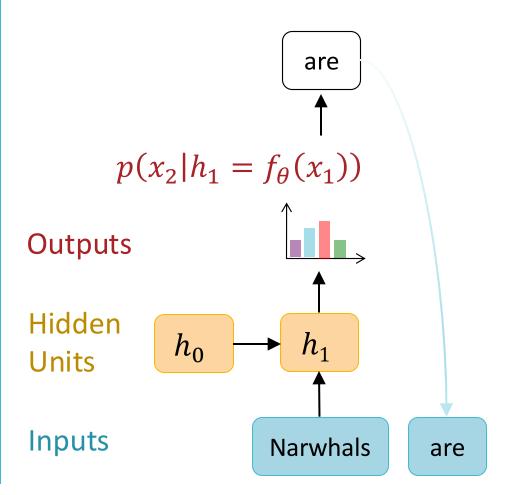
• How can we get a distribution $p(x_t|h_{t-1}=f_{\theta}(x_1,...,x_{t-1}))$ from some fixed-length vector h_{t-1} ?

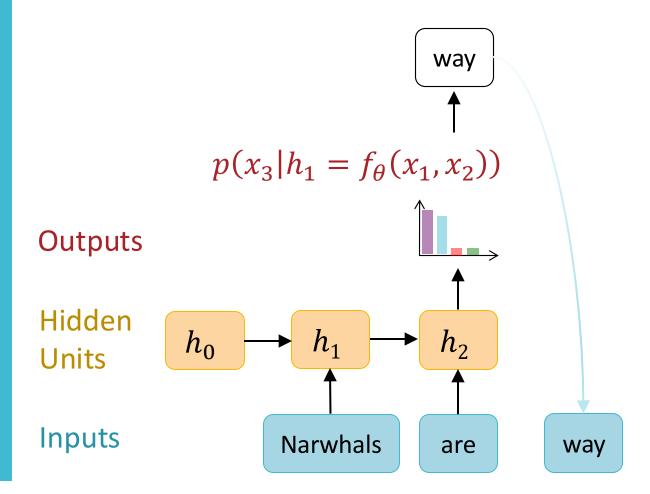


Recurrent Neural Network Language Models

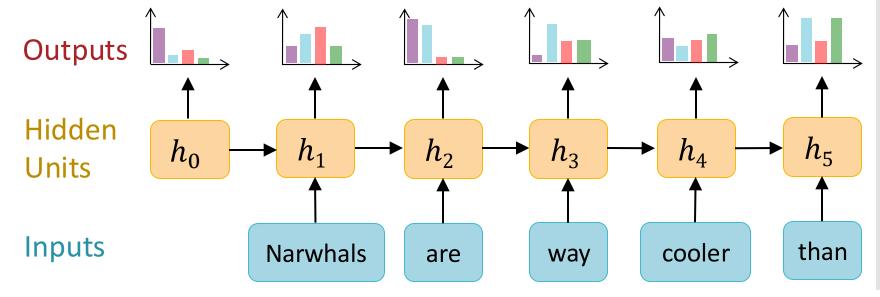








- How do we generate new sequences using an RNN language model?
- Exactly the same way we did for an *n*-gram language model, by sampling from some learned probability distributions over next words!



Shakespeare's As You Like It

VIOLA: Why, Salisbury must find his flesh and thought That which I am not aps, not a man and in fire, To show the reining of the raven and the wars To grace my hand reproach within, and not a fair are hand, That Caesar and my goodly father's world; When I was heaven of presence and our fleets, We spare with hours, but cut thy council I am great, Murdered and by thy master's ready there My power to give thee but so much as hell: Some service in the noble bondman here, Would show him to her wine.

KING LEAR: O, if you were a feeble sight, the courtesy of your law, Your sight and several breath, will wear the gods With his heads, and my hands are wonder'd at the deeds, So drop upon your lordship's head, and your opinion Shall be against your honour.

RNN-LM Sample

CHARLES: Marry, do I, sir; and I came to acquaint you with a matter. I am given, sir, secretly to understand that your younger brother Orlando hath a disposition to come in disguised against me to try a fall. Tomorrow, sir, I wrestle for my credit; and he that escapes me without some broken limb shall acquit him well. Your brother is but young and tender; and, for your love, I would be loath to foil him, as I must, for my own honour, if he come in: therefore, out of my love to you, I came hither to acquaint you withal, that either you might stay him from his intendment or brook such disgrace well as he shall run into, in that it is a thing of his own search and altogether against my will.

TOUCHSTONE: For my part, I had rather bear with you than bear you; yet I should bear no cross if I did bear you, for I think you have no money in your purse.

RNN Language Models: Generation

RNN-LM Sample?

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RNN Language Models: Training?

Backpropagation

Forward Computation

- 1. Write an **algorithm** for evaluating the function y = f(x).
 - The algorithm defines the **computation graph**, a **directed acyclic graph**, where each variable is a node
- 2. Visit each node in **topological order**:

For variable u_i with inputs $v_1, ..., v_N$ compute $u_i = g_i(v_1, ..., v_N)$ and store the result at that node

Backward Computation (Version A)

- 1. Initialize dy/dy = 1.
- 2. Visit each node v_i in reverse topological order:
 - Let u_1, \ldots, u_M denote all the nodes with v_j as an input Assume $y = h(\boldsymbol{u}) = h(u_1, \ldots, u_M)$ and $u_i = g(\boldsymbol{v}) = g_i(v_1, \ldots, v_j, \ldots, v_N) \ \forall \ i$
- 3. Compute $\frac{dy}{dv_j} = \sum_{i=1}^{M} \frac{dy}{du_i} \frac{du_i}{dv_j}$
 - We already know $dy/du_i \ \forall \ i$ and du_i/dv_j is (typically) easy to compute
- **4.** Return partial derivatives dy/du_i for all variables

Backpropagation

Forward Computation

- 1. Write an **algorithm** for evaluating the function y = f(x).
 - The algorithm defines the **computation graph**, a **directed acyclic graph**, where each variable is a node
- 2. Visit each node in **topological order**:

For variable u_i with inputs v_1, \dots, v_N compute $u_i = g_i(v_1, \dots, v_N)$ and store the result at that node

Backward Computation (Version B)

- 1. Initialize dy/dy = 1.
- 2. Visit each node v_i in reverse topological order
- 3. For each variable $u_i = g(\mathbf{v}) = g_i(v_1, ..., v_j, ..., v_N)$, increment dy/dv_j by $(dy/du_i)(du_i/dv_j)$
 - a) We already know $dy/du_i \ \forall \ i$ and du_i/dv_j is (typically) easy to compute
- **4.** Return partial derivatives dy/du_i for all variables
- Key takeaway: backpropagation makes efficient reuse of intermediate quantities when computing the necessary gradients to train a neural network

Backpropagation: Procedural Method

Algorithm 1 Forward Computation

```
1: procedure NNFORWARD(Training example (\mathbf{x}, \mathbf{y}), Params \alpha, \beta)
2: \mathbf{a} = \alpha \mathbf{x}
3: \mathbf{z} = \sigma(\mathbf{a})
4: \mathbf{b} = \beta \mathbf{z}
5: \hat{\mathbf{y}} = \operatorname{softmax}(\mathbf{b})
6: J = -\mathbf{y}^T \log \hat{\mathbf{y}}
7: \mathbf{o} = \operatorname{object}(\mathbf{x}, \mathbf{a}, \mathbf{z}, \mathbf{b}, \hat{\mathbf{y}}, J)
8: return intermediate quantities \mathbf{o}
```

Algorithm 2 Backpropagation

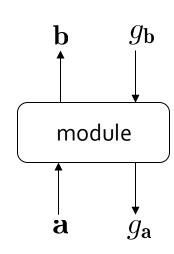
- 1: **procedure** NNBACKWARD(Training example (x, y), Params α, β , Intermediates o)
- 2: Place intermediate quantities $\mathbf{x}, \mathbf{a}, \mathbf{z}, \mathbf{b}, \hat{\mathbf{y}}, J$ in \mathbf{o} in scope
- 3: $\mathbf{g}_{\hat{\mathbf{y}}} = -\mathbf{y} \div \hat{\mathbf{y}}$
- 4: $\mathbf{g}_{\mathbf{b}} = \mathbf{g}_{\hat{\mathbf{y}}}^T \left(\mathsf{diag}(\hat{\mathbf{y}}) \hat{\mathbf{y}} \hat{\mathbf{y}}^T \right)$
- 5: $\mathbf{g}_{\boldsymbol{\beta}} = \mathbf{g}_{\mathbf{b}}^T \mathbf{z}^T$
- 6: $\mathbf{g}_{\mathbf{z}} = \boldsymbol{\beta}^T \mathbf{g}_{\mathbf{b}}^T$
- 7: $\mathbf{g_a} = \mathbf{g_z} \odot \mathbf{z} \odot (1 \mathbf{z})$
- 8: $\mathbf{g}_{\alpha} = \mathbf{g}_{\mathbf{a}} \mathbf{x}^T$
- 9: **return** parameter gradients $\mathbf{g}_{\alpha}, \mathbf{g}_{\beta}$

Issues:

- Hard to reuse /
 adapt for other
 models
- Hard to optimize individual steps
- 3. Hard to debug using the finite-difference check

Module-based AutoDiff

- Key Idea:
 - componentize the computation of the neuralnetwork into layers
 - each layer consolidates multiple real-valued nodes in the computation graph (a subset of them) into one vector-valued node (aka. a module)
- Each **module** is capable of two actions:
 - Forward computation of the output given some input
 - Backward computation of the gradient with respect to the input given the gradient with respect to the output



Module-based AutoDiff

Linear Module The linear layer has two inputs: a vector \mathbf{a} and parameters $\omega \in \mathbb{R}^{B \times A}$. The output \mathbf{b} is not used by LINEARBACKWARD, but we pass it in for consistency of form.

```
1: procedure LINEARFORWARD(\mathbf{a}, \boldsymbol{\omega})
2: \mathbf{b} = \boldsymbol{\omega} \mathbf{a}
3: return \mathbf{b}
4: procedure LINEARBACKWARD(\mathbf{a}, \boldsymbol{\omega}, \mathbf{b}, \mathbf{g_b})
5: \mathbf{g}_{\boldsymbol{\omega}} = \mathbf{g_b} \mathbf{a}^T
6: \mathbf{g}_{\mathbf{a}} = \boldsymbol{\omega}^T \mathbf{g_b}
7: return \mathbf{g}_{\boldsymbol{\omega}}, \mathbf{g_a}
```

Softmax Module The softmax layer has only one input vector \mathbf{a} . For any vector $\mathbf{v} \in \mathbb{R}^D$, we have that $\operatorname{diag}(\mathbf{v})$ returns a $D \times D$ diagonal matrix whose diagonal entries are v_1, v_2, \ldots, v_D and whose non-diagonal entries are zero.

```
1: procedure SOFTMAXFORWARD(a)
2: \mathbf{b} = \operatorname{softmax}(\mathbf{a})
3: return \mathbf{b}
4: procedure SOFTMAXBACKWARD(\mathbf{a}, \mathbf{b}, \mathbf{g_b})
5: \mathbf{g_a} = \mathbf{g_b}^T \left( \operatorname{diag}(\mathbf{b}) - \mathbf{bb}^T \right)
6: return \mathbf{g_a}
```

Sigmoid Module The sigmoid layer has only one input vector \mathbf{a} . Below σ is the sigmoid applied elementwise, and \odot is element-wise multiplication \mathbf{s} .t. $\mathbf{u} \odot$ $\mathbf{v} = [u_1v_1, \dots, u_Mv_M]$.

1: procedure SIGMOIDFORWARD(a)

2: $\mathbf{b} = \sigma(\mathbf{a})$ 3: return \mathbf{b} 4: procedure SIGMOIDBACKWARD(a, b, $\mathbf{g}_{\mathbf{b}}$)

5: $\mathbf{g}_{\mathbf{a}} = \mathbf{g}_{\mathbf{b}} \odot \mathbf{b} \odot (1 - \mathbf{b})$ 6: return $\mathbf{g}_{\mathbf{a}}$

Cross-Entropy Module The cross-entropy layer has two inputs: a gold one-hot vector \mathbf{a} and a predicted probability distribution $\hat{\mathbf{a}}$. It's output $b \in \mathbb{R}$ is a scalar. Below \div is element-wise division. The output b is not used by CrossentropyBackward, but we pass it in for consistency of form.

```
1: procedure CROSSENTROPYFORWARD(\mathbf{a}, \hat{\mathbf{a}})
2: b = -\mathbf{a}^T \log \hat{\mathbf{a}}
3: return \mathbf{b}
4: procedure CROSSENTROPYBACKWARD(\mathbf{a}, \hat{\mathbf{a}}, b, g_b)
5: \mathbf{g}_{\hat{\mathbf{a}}} = -g_b(\mathbf{a} \div \hat{\mathbf{a}})
6: return \mathbf{g}_{\mathbf{a}}
```

Module-based AutoDiff

```
Algorithm 1 Forward Computation

1: procedure NNFORWARD(Training example (x, y), Parameters \alpha, \beta)
```

- 2: $\mathbf{a} = \mathsf{LINEARFORWARD}(\mathbf{x}, \boldsymbol{\alpha})$ 3: $\mathbf{z} = \mathsf{SIGMOIDFORWARD}(\mathbf{a})$
- 4: $\mathbf{b} = \mathsf{LINEARFORWARD}(\mathbf{z}, \boldsymbol{\beta})$ 5: $\hat{\mathbf{y}} = \mathsf{SOFTMAXFORWARD}(\mathbf{b})$
- 6: $J = \text{CROSSENTROPYFORWARD}(\mathbf{y}, \hat{\mathbf{y}})$
- 7: $\mathbf{o} = \mathtt{object}(\mathbf{x}, \mathbf{a}, \mathbf{z}, \mathbf{b}, \hat{\mathbf{y}}, J)$
- 8: **return** intermediate quantities o

Algorithm 2 Backpropagation

```
1: procedure NNBACKWARD(Training example (x, y), Parameters \alpha, \beta, Intermediates o)
```

- Place intermediate quantities $\mathbf{x}, \mathbf{a}, \mathbf{z}, \mathbf{b}, \hat{\mathbf{y}}, J$ in \mathbf{o} in scope
- $g_J = \frac{dJ}{dJ} = 1$ ightharpoonup Base case
- 4: $\mathbf{g}_{\hat{\mathbf{y}}} = \mathsf{CROSSENTROPYBACKWARD}(\mathbf{y}, \hat{\mathbf{y}}, J, g_J)$
- 5: $\mathbf{g_b} = \mathsf{SOFTMAXBACKWARD}(\mathbf{b}, \hat{\mathbf{y}}, \mathbf{g}_{\hat{\mathbf{y}}})$
- 6: $\mathbf{g}_{oldsymbol{eta}}, \mathbf{g}_{\mathbf{z}} = \mathsf{LinearBackward}(\mathbf{z}, \mathbf{b}, \mathbf{g}_{\mathbf{b}})$
- 7: $\mathbf{g_a} = \mathsf{SIGMOIDBACKWARD}(\mathbf{a}, \mathbf{z}, \mathbf{g_z})$
- 8: $\mathbf{g}_{m{lpha}}, \mathbf{g}_{\mathbf{x}} = \mathsf{LINEARBACKWARD}(\mathbf{x}, \mathbf{a}, \mathbf{g}_{\mathbf{a}})$ hd We discard $\mathbf{g}_{\mathbf{x}}$
- 9: **return** parameter gradients $\mathbf{g}_{\alpha}, \mathbf{g}_{\beta}$

- Easy to reuse /
 adapt for other
 models
- Individual layers
 are easier to
 optimize
- 3. Simple to debug:just run a finite-difference checkon each layerseparately

Module-based AutoDiff (OOP Version)

Object-Oriented Implementation:

- Let each module be an object and allow the control flow of the program to define the computation graph
- No longer need to implement NNBackward(•), just follow the computation graph in reverse topological order

```
class Sigmoid (Module)

method forward (a)

\mathbf{b} = \sigma(\mathbf{a})

return \mathbf{b}

method backward (a, b, \mathbf{g_b})

\mathbf{g_a} = \mathbf{g_b} \odot \mathbf{b} \odot (1 - \mathbf{b})

return \mathbf{g_a}
```

```
class Softmax(Module)

method forward(a)

b = softmax(a)

return b

method backward(a, b, g_b)

g_a = g_b^T (diag(b) - bb^T)

return g_a
```

```
class Linear (Module)

method forward (\mathbf{a}, \boldsymbol{\omega})

\mathbf{b} = \boldsymbol{\omega} \mathbf{a}

return \mathbf{b}

method backward (\mathbf{a}, \boldsymbol{\omega}, \mathbf{b}, \mathbf{g}_{\mathbf{b}})

\mathbf{g}_{\boldsymbol{\omega}} = \mathbf{g}_{\mathbf{b}} \mathbf{a}^{T}

\mathbf{g}_{\mathbf{a}} = \boldsymbol{\omega}^{T} \mathbf{g}_{\mathbf{b}}

return \mathbf{g}_{\boldsymbol{\omega}}, \mathbf{g}_{\mathbf{a}}
```

```
class CrossEntropy (Module)

method forward (\mathbf{a}, \hat{\mathbf{a}})

b = -\mathbf{a}^T \log \hat{\mathbf{a}}

return \mathbf{b}

method backward (\mathbf{a}, \hat{\mathbf{a}}, b, g_b)

\mathbf{g}_{\hat{\mathbf{a}}} = -g_b(\mathbf{a} \div \hat{\mathbf{a}})

return \mathbf{g}_{\mathbf{a}}
```

Module-based AutoDiff (OOP Version)

```
class NeuralNetwork (Module):
 2
          method init()
 3
                lin1_layer = Linear()
                sig_layer = Sigmoid()
                lin2\_layer = Linear()
                soft_layer = Softmax()
                ce_layer = CrossEntropy()
 9
          method forward (Tensor x, Tensor y, Tensor \alpha, Tensor \beta)
10
                \mathbf{a} = \text{lin1}_{\text{layer.apply}_{\text{fwd}}}(\mathbf{x}, \boldsymbol{\alpha})
11
                z = sig_layer.apply_fwd(a)
12
                \mathbf{b} = \lim_{\mathbf{z}} \operatorname{layer.apply\_fwd}(\mathbf{z}, \boldsymbol{\beta})
13
                \hat{\mathbf{y}} = \text{soft}_{\text{layer.apply}_{\text{fwd}}}(\mathbf{b})
14
                J = \text{ce}_{\text{layer.apply}_{\text{fwd}}}(\mathbf{y}, \hat{\mathbf{y}})
15
                return J.out tensor
16
17
          method backward (Tensor x, Tensor y, Tensor \alpha, Tensor \beta)
18
                tape_bwd()
19
                return lin1_layer.in_gradients[1], lin2_layer.in_gradients[1]
20
```

Module-based AutoDiff (OOP Version)

```
global tape = stack()
2
   class Module:
       method init()
5
           out tensor = null
           out gradient = 1
7
8
       method apply_fwd(List in_modules)
9
           in_tensors = [x.out_tensor for x in in_modules]
10
           out tensor = forward(in tensors)
11
           tape.push(self)
12
           return self
13
14
       method apply bwd():
15
           in gradients = backward(in tensors, out tensor, out gradient)
16
           for i in 1, \ldots, len(in_modules):
17
               in modules[i].out gradient += in gradients[i]
18
           return self
19
20
   function tape_bwd():
21
       while len(tape) > 0
22
           m = tape.pop()
23
           m.apply bwd()
24
```

PyTorch

```
class NeuralNetwork(nn.Module):
    def __init__(self):
        super().__init__()
        self.flatten = nn.Flatten()
        self.linear1 = nn.Linear(28*28, 512)
        self.sigmoid = nn.Sigmoid()
        self.linear2 = nn.Linear(512, 512)
    def forward(self, x):
        x = self.flatten(x)
        a = self.linear1(x)
        z = self.sigmoid(a)
       b = self.linear2(z)
        return b
def one_step_of_sgd(X, y):
   model = NeuralNetwork()
    loss_fn = nn.CrossEntropyLoss()
    optimizer = torch.optim.SGD(model.parameters(), lr=1e-2)
    pred = model(X)
    loss = loss_fn(pred, y)
    optimizer.zero_grad()
    loss.backward()
    optimizer.step()
```

PyTorch: FAQ

- Q: Why don't we call linear.forward() in PyTorch?
- A: There's a special method in Python __call__ that allows you to define what happens when you treat an object as if it were a function so linear(x) is equivalent linear.__call__(x) and PyTorch defines every Module's __call__ method to be something like def __call__(self):

 self.forward()

PyTorch: FAQ

- Q: Why don't we pass in the parameters to a Module?
- A: This is just a design choice; in PyTorch, you store the parameters inside the Module and "mark" them as parameters that should contribute to the eventual gradient used by an optimizer