



10-301/601 Introduction to Machine Learning

Machine Learning Department
School of Computer Science
Carnegie Mellon University

Hidden Markov Models

+

Exam 2 Review

Matt Gormley & Henry Chai

Lecture 18

Oct. 27, 2021

Reminders

- Lecture on Friday!
- Homework 6: Learning Theory / Generative Models
 - Out: Thu, Oct. 21
 - Due: Thu, Oct. 28 at 11:59pm
 - Same collaboration policy as Homework 3
 - Opt-in to homework groups on Piazza
 - **IMPORTANT: you may only use 2 grace days on Homework 6**
 - **Last possible moment to submit HW6: Sat, Oct. 30 at 11:59pm**
- Midterm Exam 2
 - Tue, Nov. 2, 6:30pm – 8:30pm
- Practice for Exam 2
 - Practice problems released on course website
 - (Tentatively) Out: Thu, Oct. 21
 - Mock Exam 2
 - (Tentatively) Out: Thu, Oct. 28
 - Due Sun, Oct. 31 at 11:59pm

MIDTERM EXAM LOGISTICS

Midterm Exam

- **Time / Location**
 - **Time:** Tue, Nov. 2, 6:30pm – 8:30pm
 - **Location & Seats:** You have all been split across multiple rooms. Everyone has an assigned seat in one of these room. Please watch Piazza carefully for announcements.
- **Logistics**
 - Covered material: Lecture 9 – Lecture 17
 - Format of questions:
 - Multiple choice
 - True / False (with justification)
 - Derivations
 - Short answers
 - Interpreting figures
 - Implementing algorithms on paper
 - No electronic devices
 - You are allowed to **bring** one 8½ x 11 sheet of notes (front and back)

Midterm Exam

- **How to Prepare**

- Attend the midterm review lecture (right now!)
- Review prior year's exam and solutions (we'll post them)
- Review this year's homework problems
- Consider whether you have achieved the “learning objectives” for each lecture / section

– *crowdsource exam questions*

Midterm Exam

- **Advice (for during the exam)**
 - Solve the easy problems first (e.g. multiple choice before derivations)
 - if a problem seems extremely complicated you're likely missing something
 - Don't leave any answer blank!
 - If you make an assumption, write it down
 - If you look at a question and don't know the answer:
 - we probably haven't told you the answer
 - but we've told you enough to work it out
 - imagine arguing for some answer and see if you like it

Topics for Midterm 1

- Foundations
 - Probability, Linear Algebra, Geometry, Calculus
 - Optimization
- Important Concepts
 - Overfitting
 - Experimental Design
- Classification
 - Decision Tree
 - KNN
 - Perceptron
- Regression
 - Linear Regression

Topics for Midterm 2

- Classification
 - Binary Logistic Regression
- Important Concepts
 - Stochastic Gradient Descent
 - Regularization
 - Feature Engineering
- Feature Learning
 - Neural Networks
 - Basic NN Architectures
 - Backpropagation
- Learning Theory
 - PAC Learning
- Generative Models
 - Generative vs. Discriminative
 - MLE / MAP
 - Naïve Bayes

SAMPLE QUESTIONS

Sample Questions

3.2 Logistic regression

Given a training set $\{(x_i, y_i), i = 1, \dots, n\}$ where $x_i \in \mathbb{R}^d$ is a feature vector and $y_i \in \{0, 1\}$ is a binary label, we want to find the parameters \hat{w} that maximize the likelihood for the training set, assuming a parametric model of the form

$$p(y = 1|x; w) = \frac{1}{1 + \exp(-w^T x)}.$$

The conditional log likelihood of the training set is

$$\ell(w) = \sum_{i=1}^n y_i \log p(y_i, |x_i; w) + (1 - y_i) \log(1 - p(y_i, |x_i; w)),$$

and the gradient is

$$\nabla \ell(w) = \sum_{i=1}^n (y_i - p(y_i|x_i; w))x_i.$$

(b) [5 pts.] What is the form of the classifier output by logistic regression?

$$h(\vec{x}) = \arg \max_y p(y|\vec{x}) = \begin{cases} 1 & \text{if } p(y=1|\vec{x}) > 0.5 \\ 0 & \text{otherwise} \end{cases}$$

linear decision boundary

(c) [2 pts.] **Extra Credit** Consider the case with binary features, i.e. $x \in \{0, 1\}^d \subset \mathbb{R}^d$, where feature x_1 is rare and happens to appear in the training set with only label 1. What is \hat{w}_1 ? Is the gradient ever zero for any finite w ? Why is it important to include a regularization term to control the norm of \hat{w} ?

Samples Questions

Q1

2.1 Train and test errors

In this problem, we will see how you can debug a classifier by looking at its train and test errors. Consider a classifier trained till convergence on some training data $\mathcal{D}^{\text{train}}$, and tested on a separate test set $\mathcal{D}^{\text{test}}$. You look at the test error, and find that it is very high. You then compute the training error and find that it is close to 0.

1. [4 pts] Which of the following is expected to help? Select all that apply.

- ✓ (a) Increase the training data size.
- (b) Decrease the training data size.
- (c) Increase model complexity (For example, if your classifier is an SVM, use a more complex kernel. Or if it is a decision tree, increase the depth).
- ✓ (d) Decrease model complexity.
- (e) Train on a combination of $\mathcal{D}^{\text{train}}$ and $\mathcal{D}^{\text{test}}$ and test on $\mathcal{D}^{\text{test}}$
- ~~(f) Conclude that Machine Learning does not work.~~

bxlc

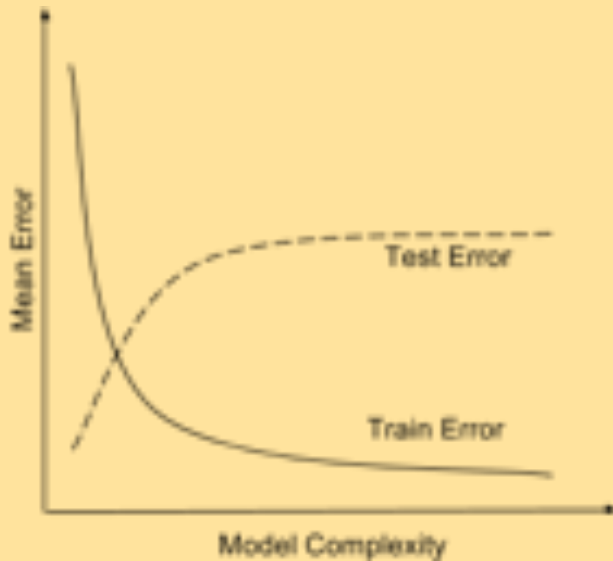
Samples Questions

2.1 Train and test errors

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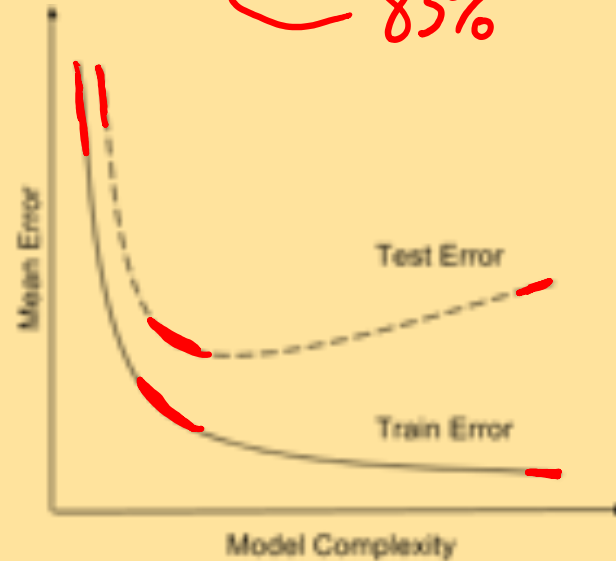
4. [1 pts] Say you plot the train and test errors as a function of the model complexity. Which of the following two plots is your plot expected to look like?

A



(a)

B 83% C = toxic



(b)

Sample Questions

5 Learning Theory [20 pts.]

- (a) [3 pts.] **T or F:** It is possible to label 4 points in \mathbb{R}^2 in all possible 2^4 ways via linear separators in \mathbb{R}^2 .

0 0
0 0

hypothesis class \mathcal{H}
hypothesis space

- (d) [3 pts.] **T or F:** The VC dimension of a concept class with infinite size is also infinite.

- (f) [3 pts.] **T or F:** Given a realizable concept class and a set of training instances, a consistent learner will output a concept that achieves 0 error on the training instances.

one that achieves 0 error in a realizable

Sample Questions

Q3

Neural Networks

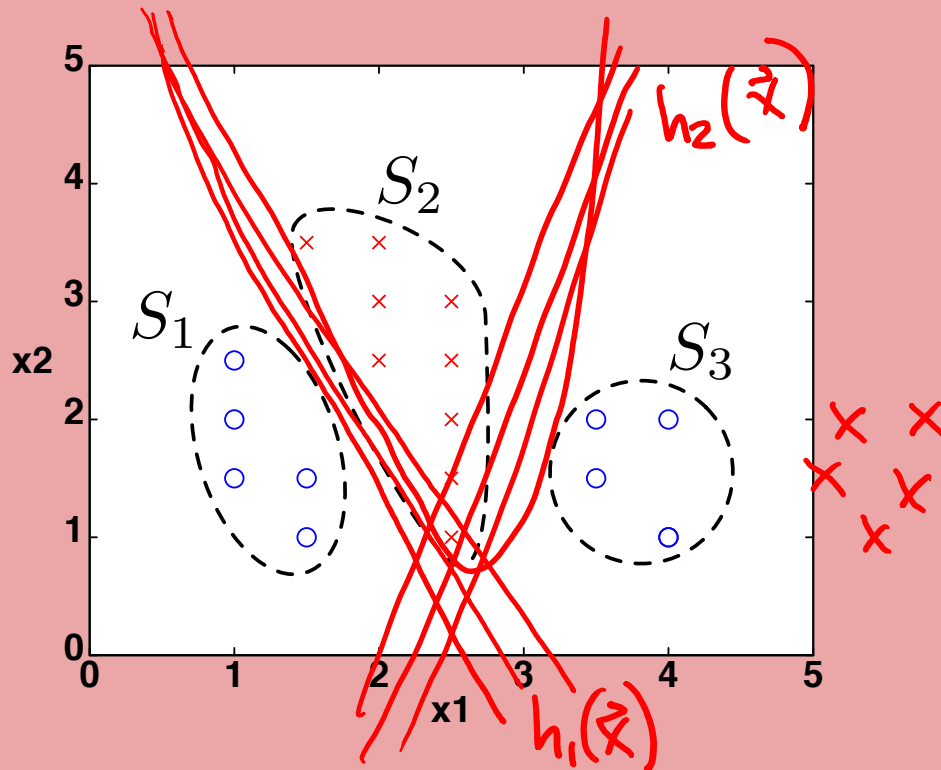
A = toxic

B = Yes

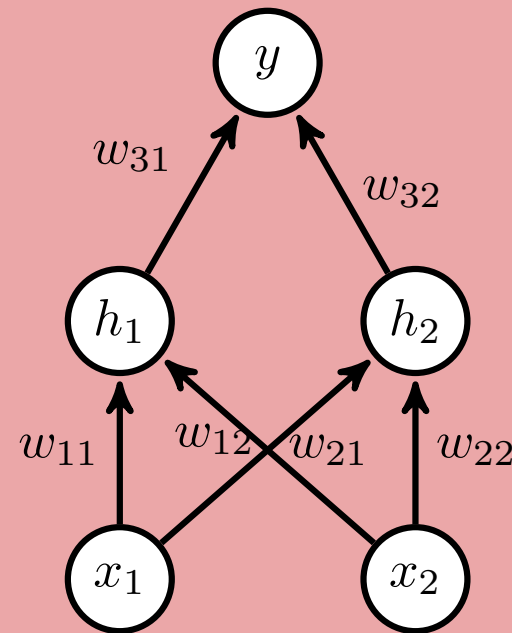
C = No

82%

Can the neural network in Figure (b) correctly classify the dataset given in Figure (a)?



(a) The dataset with groups S_1 , S_2 , and S_3 .

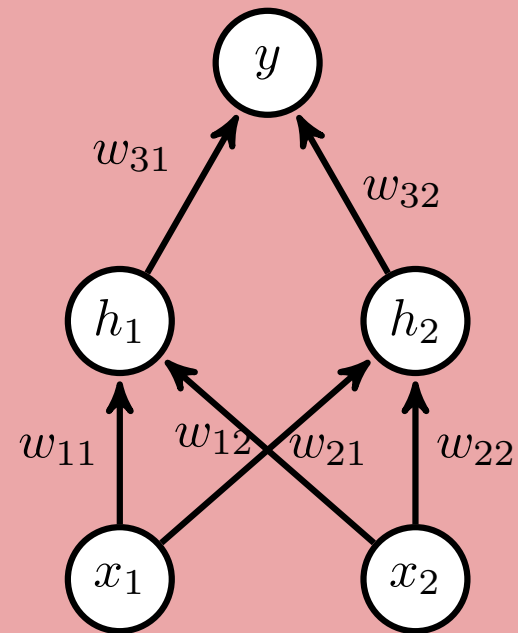


(b) The neural network architecture

Sample Questions

Neural Networks

Apply the backpropagation algorithm to obtain the partial derivative of the mean-squared error of y with the true value y^* with respect to the weight w_{22} assuming a sigmoid nonlinear activation function for the hidden layer.



(b) The neural network architecture

Sample Questions

1.2 Maximum Likelihood Estimation (MLE)

Assume we have a random sample that is Bernoulli distributed $X_1, \dots, X_n \sim \text{Bernoulli}(\theta)$. We are going to derive the MLE for θ . Recall that a Bernoulli random variable X takes values in $\{0, 1\}$ and has probability mass function given by

$$P(X; \theta) = \theta^X (1 - \theta)^{1-X}.$$

(a) [2 pts.] Derive the likelihood, $L(\theta; X_1, \dots, X_n)$.

(c) **Extra Credit:** [2 pts.] Derive the following formula for the MLE: $\hat{\theta} = \frac{1}{n} (\sum_{i=1}^n X_i)$.

Sample Questions

1.3 MAP vs MLE

Answer each question with **T** or **F** and provide a one sentence explanation of your answer:

- (a) [2 pts.] **T** or **F**: In the limit, as n (the number of samples) increases, the MAP and MLE estimates become the same.

Sample Questions

1.1 Naive Bayes

You are given a data set of 10,000 students with their sex, height, and hair color. You are trying to build a classifier to predict the sex of a student, so you randomly split the data into a training set and a testing set. Here are the specifications of the data set:

- $\text{sex} \in \{\text{male}, \text{female}\}$
- $\text{height} \in [0, 300]$ centimeters
- $\text{hair} \in \{\text{brown}, \text{black}, \text{blond}, \text{red}, \text{green}\}$
- 3240 men in the data set
- 6760 women in the data set

Under the assumptions necessary for Naive Bayes (not the distributional assumptions you might naturally or intuitively make about the dataset) answer each question with **T** or **F** and **provide a one sentence explanation of your answer**:

(a) [2 pts.] **T or F:** As height is a continuous valued variable, Naive Bayes is not appropriate since it cannot handle continuous valued variables.

(c) [2 pts.] **T or F:** $P(\text{height}|\text{sex}, \text{hair}) = P(\text{height}|\text{sex})$.

Naïve Bayes vs. Logistic Regression

Q4:

Question:

You just started working at a new company that manufactures comically large pennies. Your manager asks you to build a binary classifier that takes an image of a penny (on the factory assembly line) and predicts whether or not it has a defect.

What follow-up questions would you pose to your manager in order to decide between using a Naïve Bayes classifier and a Logistic Regression classifier?

Answer:

Question 4

Join by Web



- 1 Go to **PollEv.com**
- 2 Enter **10301601POLLS**
- 3 Respond to activity

i Instructions not active. **Log in** to activate

MOTIVATION: STRUCTURED PREDICTION

Structured Prediction

















































- Most of the models we've seen so far were for **classification**
 - Given observations: $\mathbf{x} = (x_1, x_2, \dots, x_K)$
 - Predict a (binary) **label**: y
- Many real-world problems require **structured prediction**
 - Given observations: $\mathbf{x} = (x_1, x_2, \dots, x_K)$
 - Predict a **structure**: $\mathbf{y} = (y_1, y_2, \dots, y_J)$
- Some *classification* problems benefit from **latent structure**

Structured Prediction Examples

- **Examples of structured prediction**
 - Part-of-speech (POS) tagging
 - Handwriting recognition
 - Speech recognition
 - Word alignment
 - Congressional voting
- **Examples of latent structure**
 - Object recognition

Dataset for Supervised Part-of-Speech (POS) Tagging

Data: $\mathcal{D} = \{x^{(n)}, y^{(n)}\}_{n=1}^N$

Sample 1:							$y^{(1)}$
							$x^{(1)}$
Sample 2:							$y^{(2)}$
							$x^{(2)}$
Sample 3:							$y^{(3)}$
							$x^{(3)}$
Sample 4:							$y^{(4)}$
							$x^{(4)}$

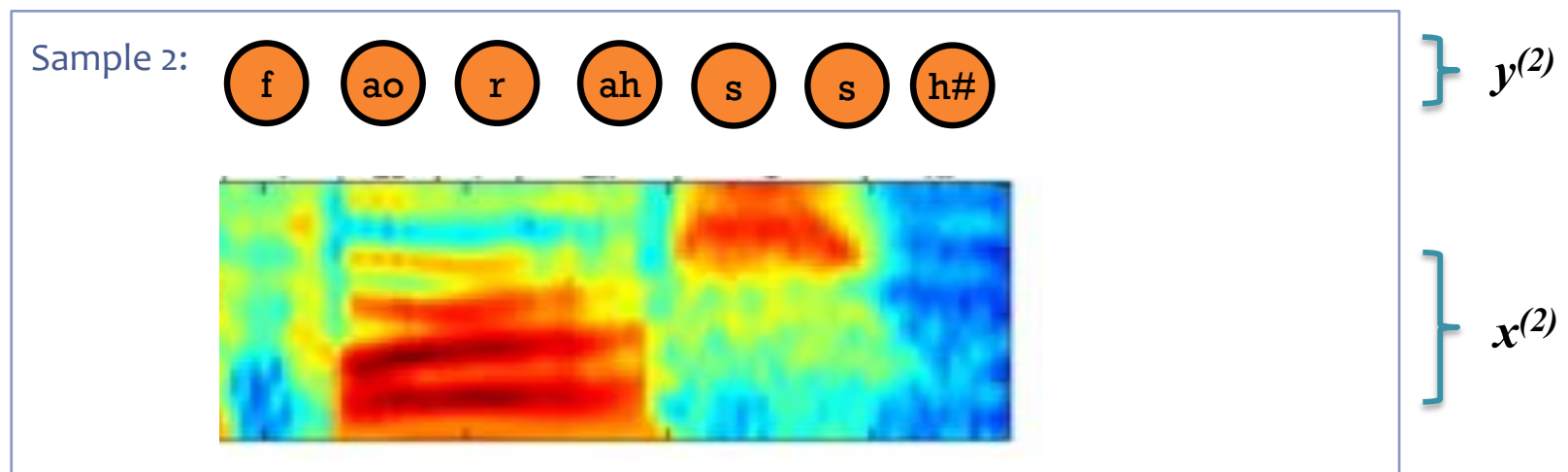
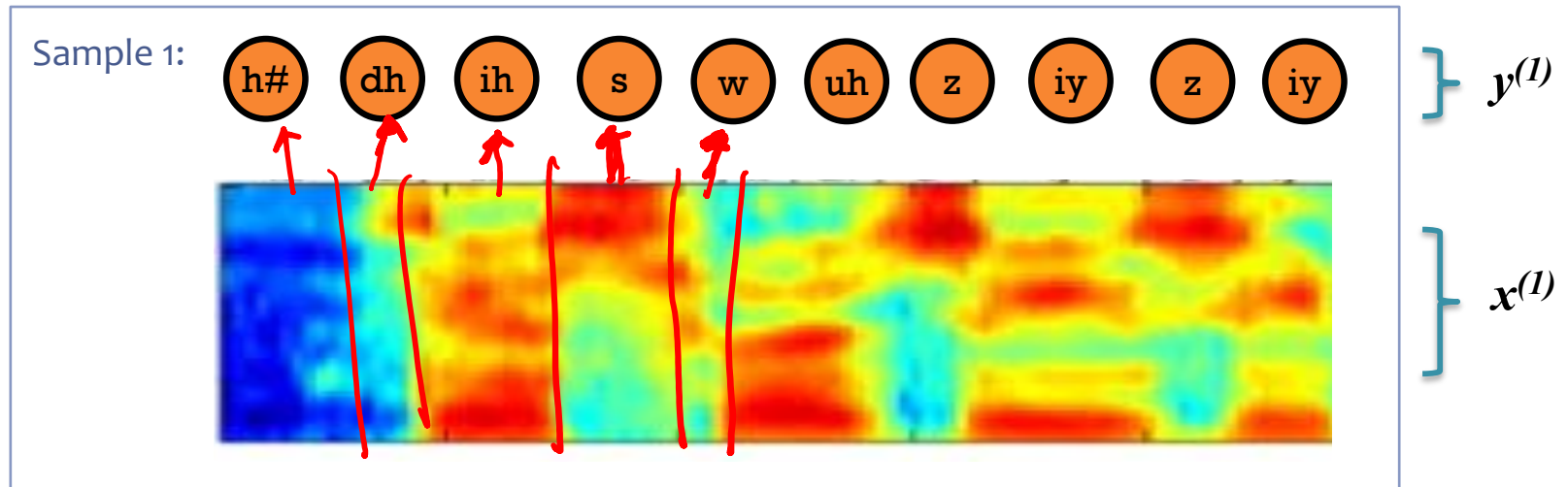
Dataset for Supervised Handwriting Recognition

Data: $\mathcal{D} = \{x^{(n)}, y^{(n)}\}_{n=1}^N$



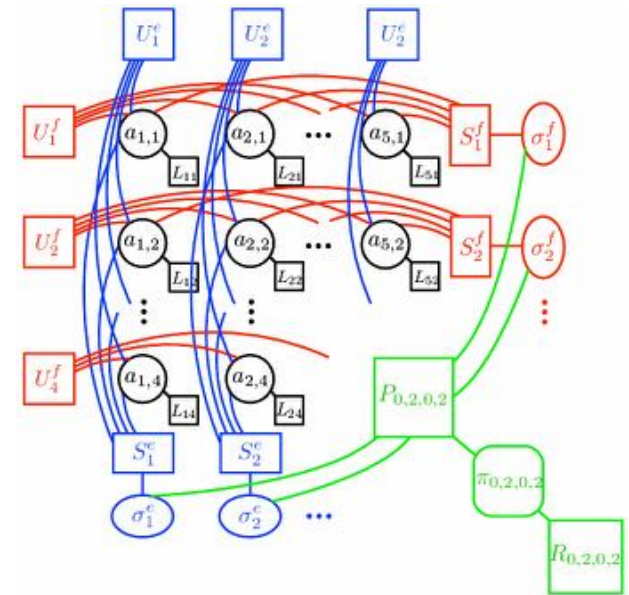
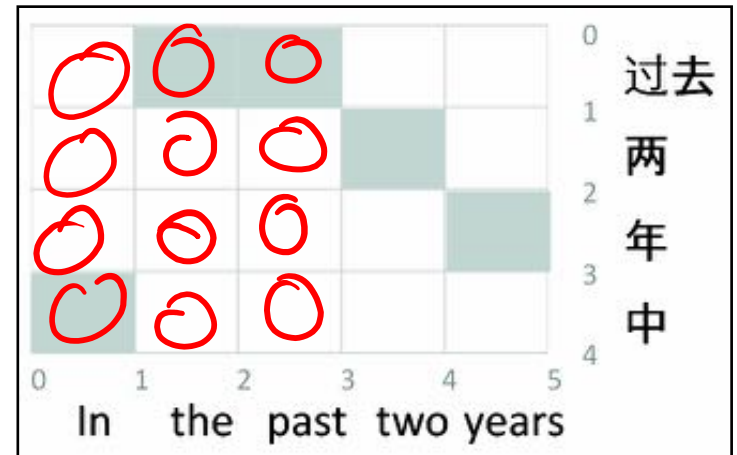
Dataset for Supervised Phoneme (Speech) Recognition

Data: $\mathcal{D} = \{x^{(n)}, y^{(n)}\}_{n=1}^N$

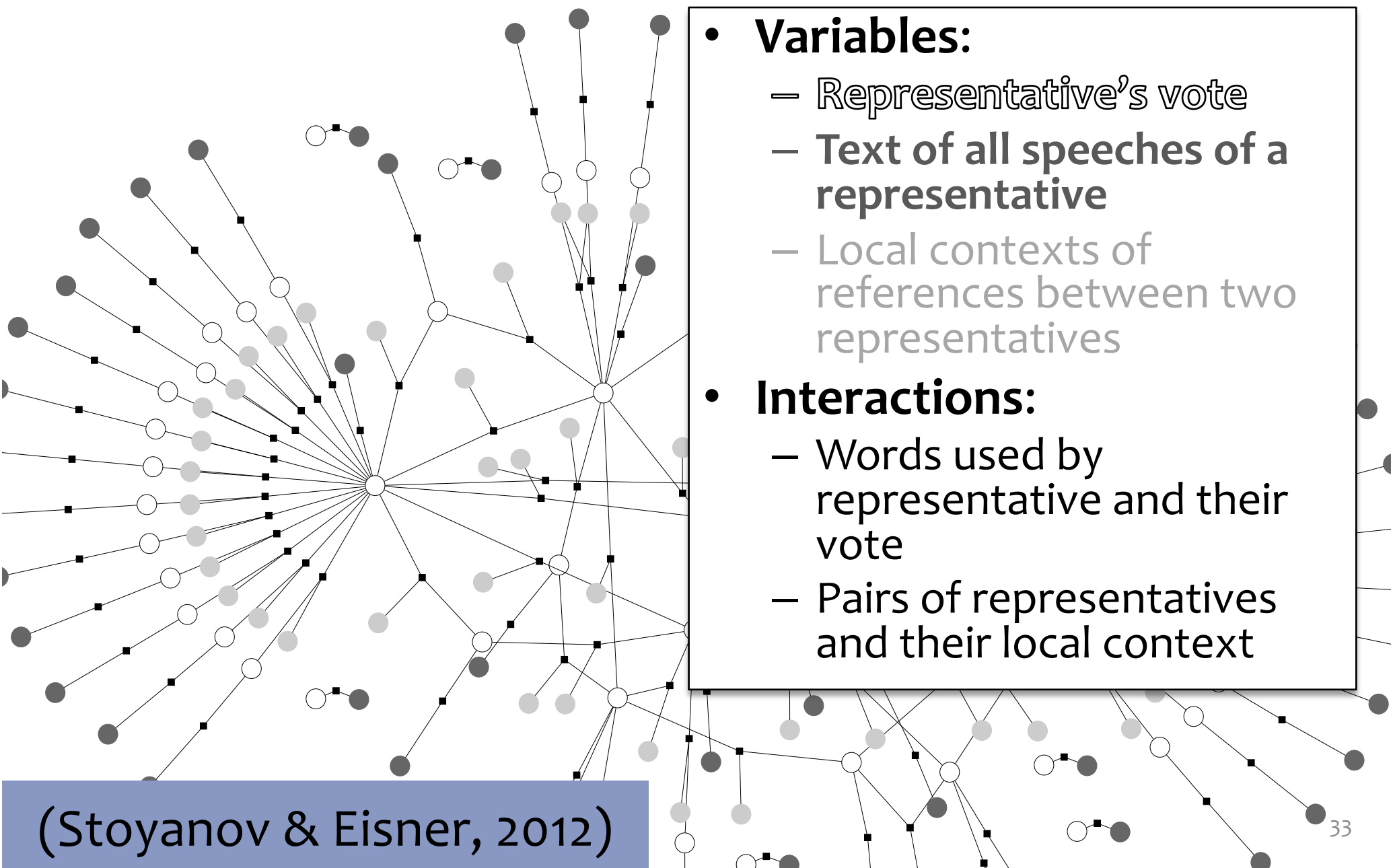


Word Alignment / Phrase Extraction

- **Variables (boolean):**
 - For each (Chinese phrase, English phrase) pair, are they linked?
- **Interactions:**
 - Word fertilities
 - Few “jumps” (discontinuities)
 - Syntactic reorderings
 - “ITG constraint” on alignment
 - Phrases are disjoint (?)



Congressional Voting



- **Variables:**
 - Representative's vote
 - Text of all speeches of a representative
 - Local contexts of references between two representatives
- **Interactions:**
 - Words used by representative and their vote
 - Pairs of representatives and their local context

(Stoyanov & Eisner, 2012)

Structured Prediction Examples

- **Examples of structured prediction**
 - Part-of-speech (POS) tagging
 - Handwriting recognition
 - Speech recognition
 - Word alignment
 - Congressional voting
- **Examples of latent structure**
 - Object recognition

Case Study: Object Recognition

Data consists of images x and labels y .



pigeon

$x^{(1)}$

$y^{(1)}$



rhinoceros

$x^{(2)}$

$y^{(2)}$



leopard

$x^{(3)}$

$y^{(3)}$



llama

$x^{(4)}$

$y^{(4)}$

Case Study: Object Recognition

Data consists of images x and labels y .

- Preprocess data into “patches”
- Posit a latent labeling z describing the object’s parts (e.g. head, leg, tail, torso, grass)
- Define graphical model with these latent variables in mind
- z is not observed at train or test time

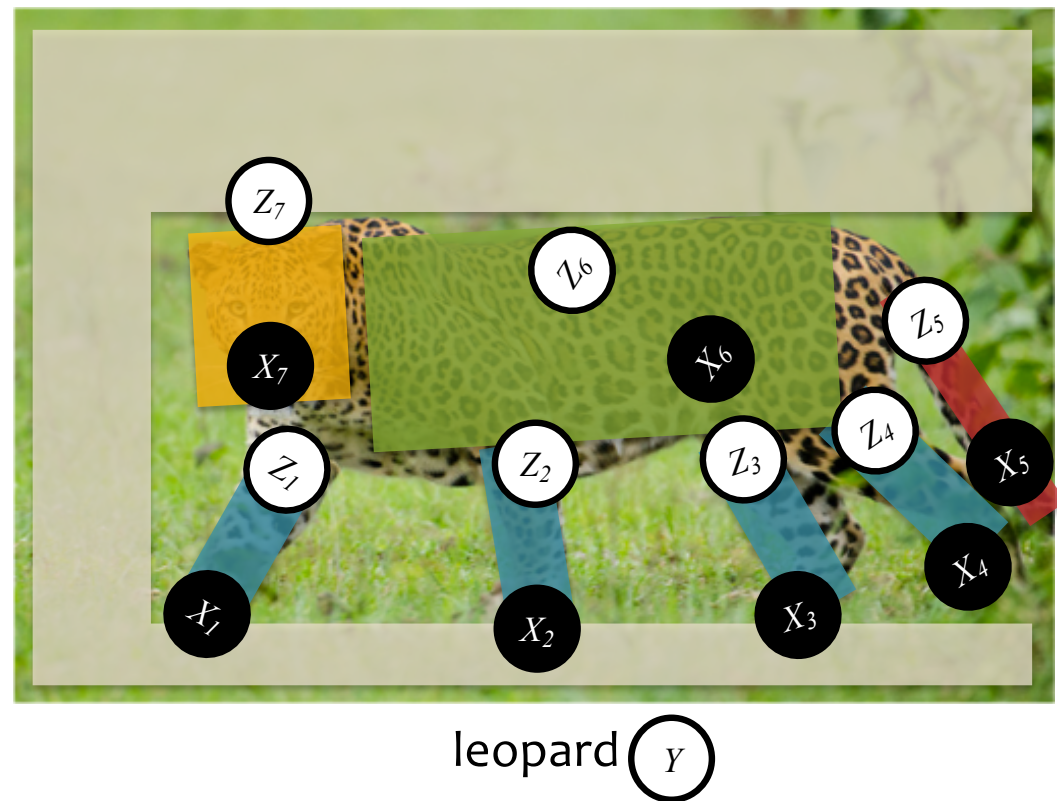


leopard

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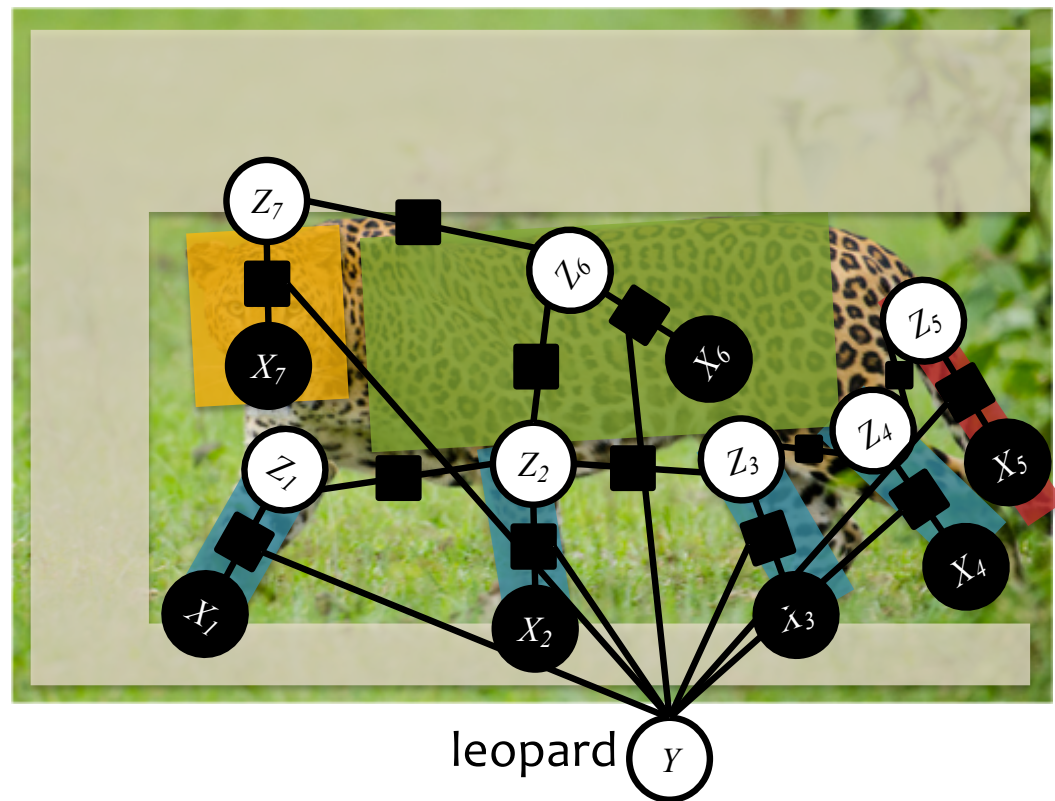
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Structured Prediction

Preview of challenges to come...

- Consider the task of finding the **most probable assignment** to the output

$p(y=+1|x)$
 $p(y=-1|x)$
Classification

$$\hat{y} = \operatorname{argmax}_y p(y|\mathbf{x})$$

where $y \in \{+1, -1\}$

for $y \in \mathcal{Y}$:
 $p(y|\mathbf{x})$

Structured Prediction

$$\hat{\mathbf{y}} = \operatorname{argmax}_{\mathbf{y} \in \mathcal{Y}} p(\mathbf{y}|\mathbf{x})$$

where $\mathbf{y} \in \mathcal{Y}$

and $|\mathcal{Y}|$ is very large

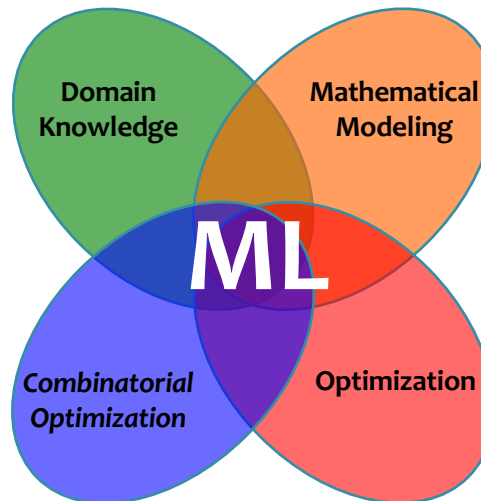
Machine Learning

The **data** inspires the structures we want to predict



Our **model** defines a score for each structure

It also tells us what to optimize



Inference finds {best structure, marginals, partition function} for a new observation

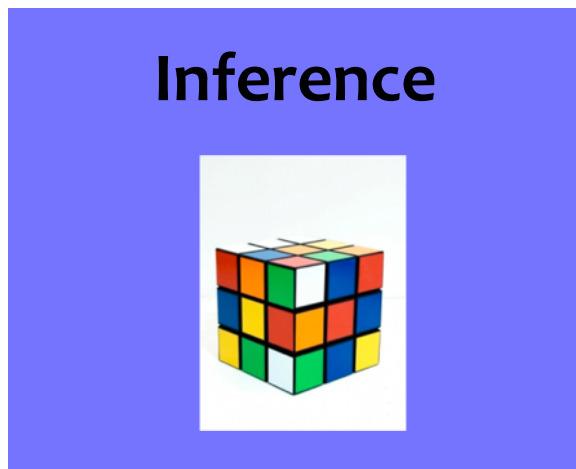
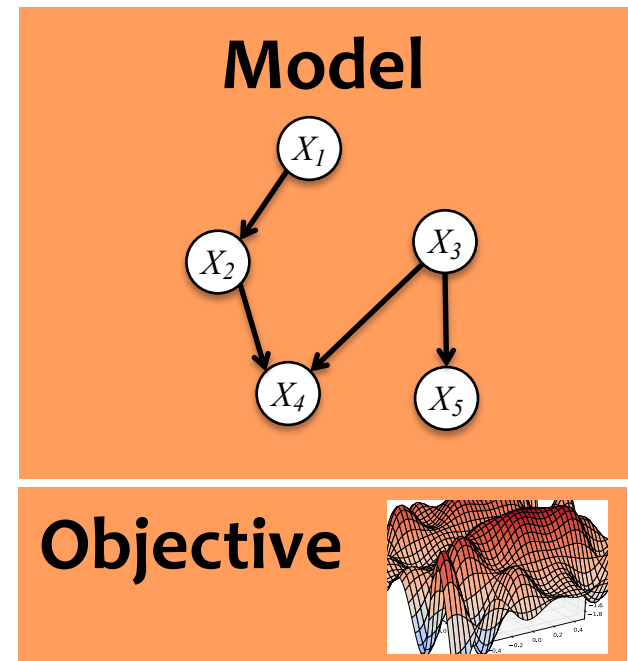
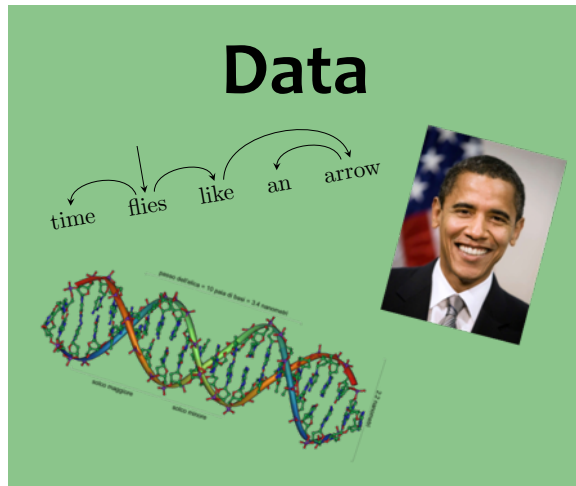
(**Inference** is usually called as a subroutine in learning)



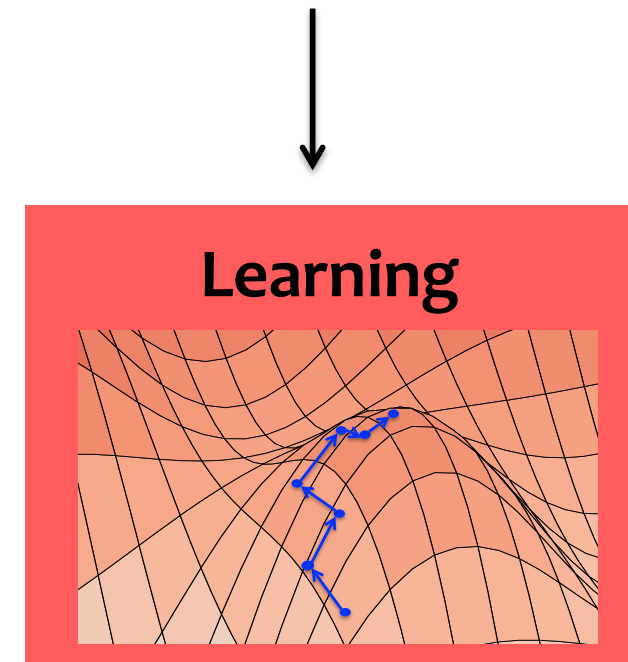
Learning tunes the parameters of the model



Machine Learning



(Inference is usually called as a subroutine in learning)



BACKGROUND

Background: Chain Rule of Probability

For random variables A and B :

$$P(A, B) = P(A|B)P(B)$$

For random variables X_1, X_2, X_3, X_4 :

$$\begin{aligned} \underline{P(X_1, X_2, X_3, X_4)} &= P(\underline{X_1} | \underline{X_2}, \underline{X_3}, \underline{X_4}) \\ &\quad P(\underline{X_2} | \underline{X_3}, \underline{X_4}) \\ &\quad P(\underline{X_3} | \underline{X_4}) \\ &\quad P(\underline{X_4}) \end{aligned}$$

Background: Conditional Independence

Random variables A and B are conditionally independent given C if:

$$P(A, B|C) = P(A|C)P(B|C) \quad (1)$$

or equivalently:

$$P(A|B, C) = P(A|C) \quad (2)$$

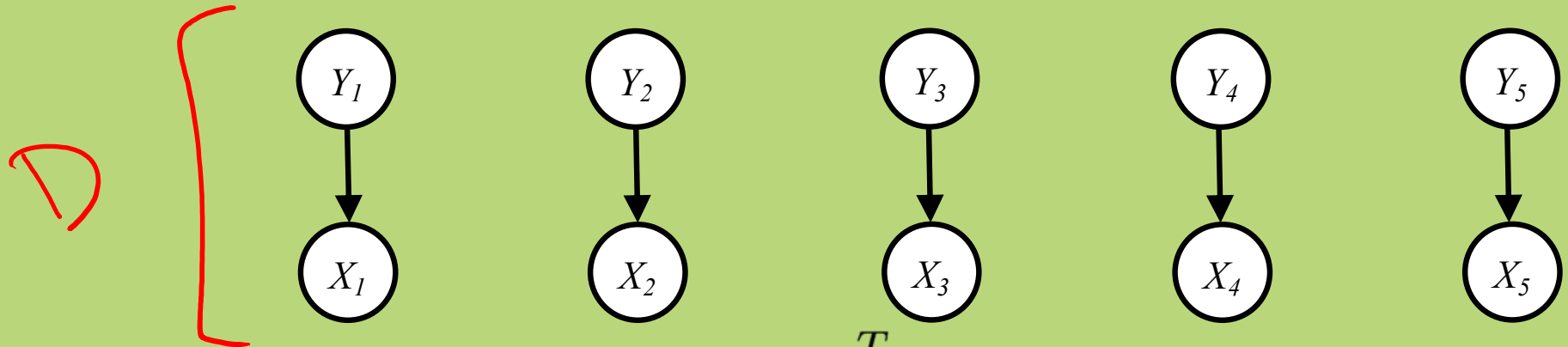
We write this as:

$$A \perp\!\!\!\perp B | C$$

Later we will also write: $I\langle A, \{C\}, B \rangle$

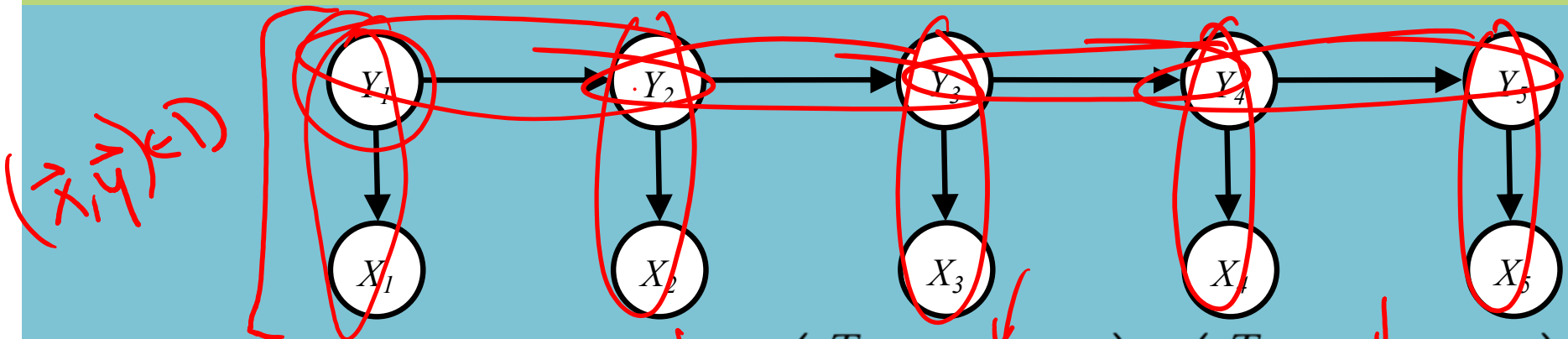
HIDDEN MARKOV MODEL (HMM)

From Mixture Model to HMM



“Naïve Bayes”:

$$P(\mathbf{X}, \mathbf{Y}) = \prod_{t=1}^T P(X_t|Y_t)p(Y_t)$$



HMM:

$$P(\mathbf{X}, \mathbf{Y}) = P(Y_1) \left(\prod_{t=1}^T P(X_t|Y_t) \right) \left(\prod_{t=2}^T p(Y_t|Y_{t-1}) \right)$$

HIDDEN MARKOV MODEL (HMM)

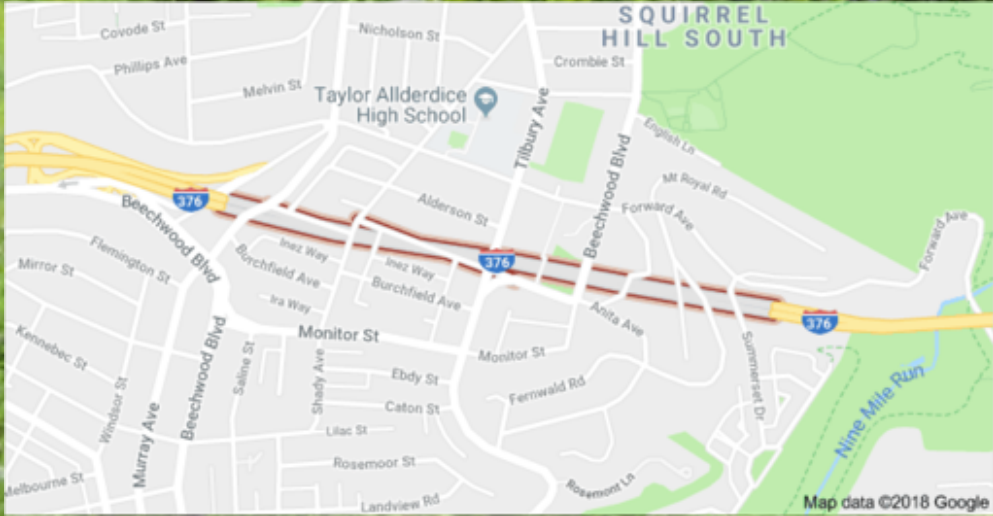
HMM Outline

- **Motivation**
 - Time Series Data
- **Hidden Markov Model (HMM)**
 - Example: Squirrel Hill Tunnel Closures [courtesy of Roni Rosenfeld]
 - Background: Markov Models
 - From Mixture Model to HMM
 - History of HMMs
 - Higher-order HMMs
- **Training HMMs**
 - (Supervised) Likelihood for HMM
 - Maximum Likelihood Estimation (MLE) for HMM
 - EM for HMM (aka. Baum-Welch algorithm)
- **Forward-Backward Algorithm**
 - Three Inference Problems for HMM
 - Great Ideas in ML: Message Passing
 - Example: Forward-Backward on 3-word Sentence
 - Derivation of Forward Algorithm
 - Forward-Backward Algorithm
 - Viterbi algorithm

Markov Models

Whiteboard

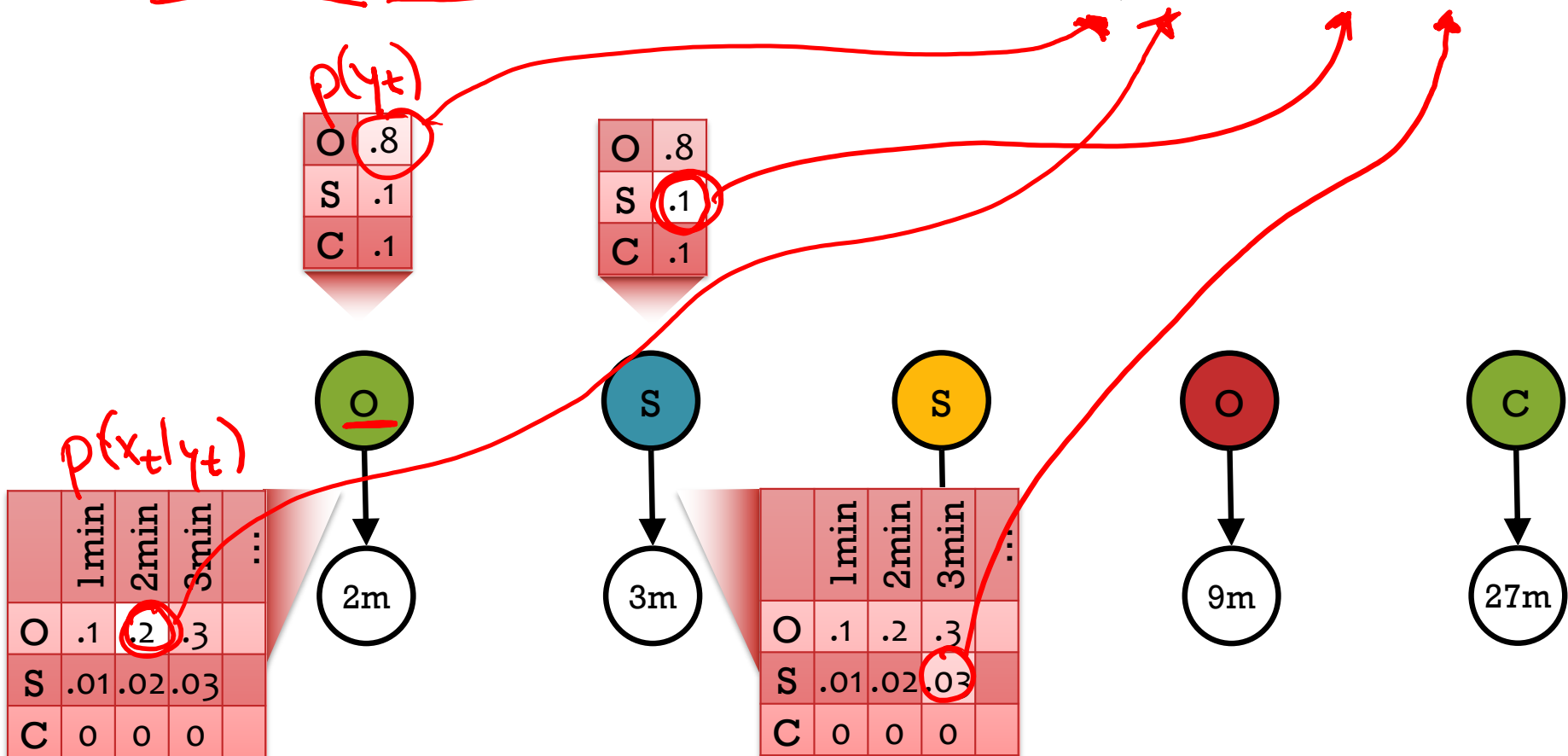
- Example: Tunnel Closures
[courtesy of Roni Rosenfeld]
- First-order Markov assumption
- Conditional independence assumptions



Mixture Model for Time Series Data

We could treat each (tunnel state, travel time) pair as independent. This corresponds to a Naïve Bayes model with a single feature (travel time).

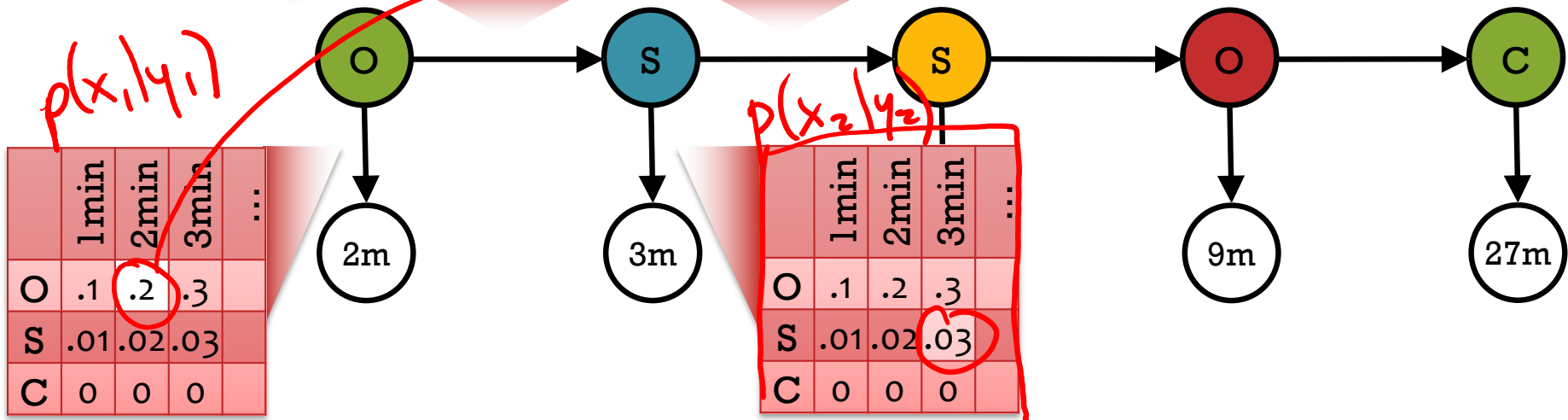
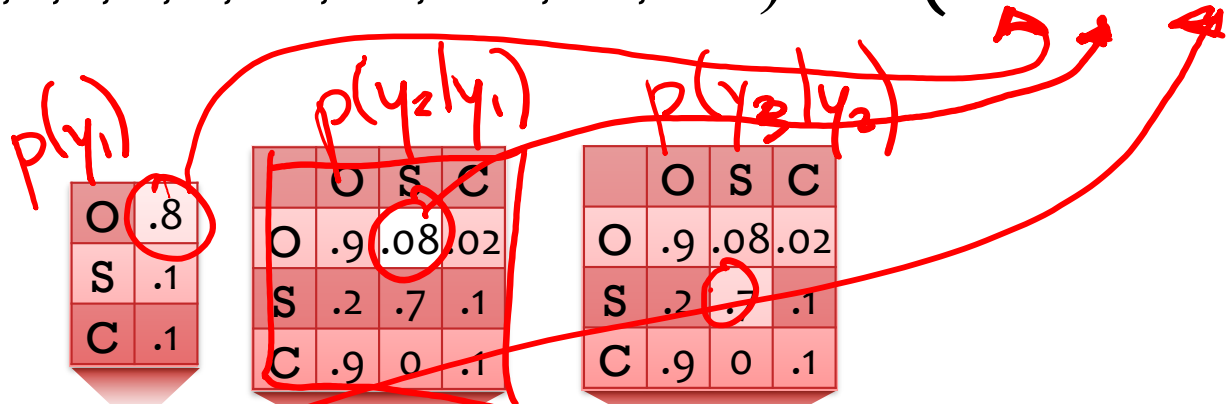
$$p(\underline{O, S, S, O, C}, \underline{2m, 3m, 18m, 9m, 27m}) = (.8 * .2 * .1 * .03 * \dots)$$



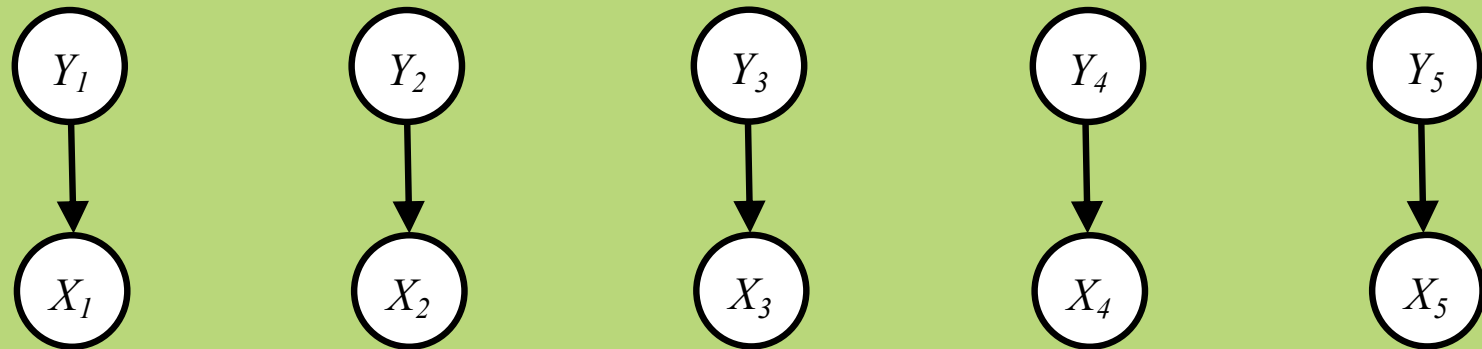
Hidden Markov Model

A Hidden Markov Model (HMM) provides a joint distribution over the the tunnel states / travel times with an assumption of dependence between adjacent tunnel states.

$$p(O, S, S, O, C, 2m, 3m, 18m, 9m, 27m) = (.8 * .08 * .2 * .7 * .03 * \dots)$$

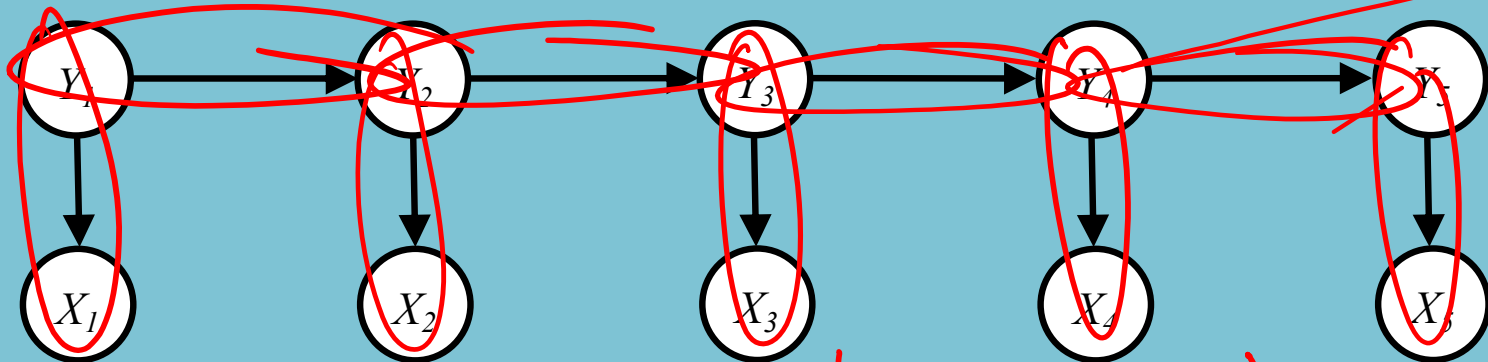


From Mixture Model to HMM



“Naïve Bayes”:

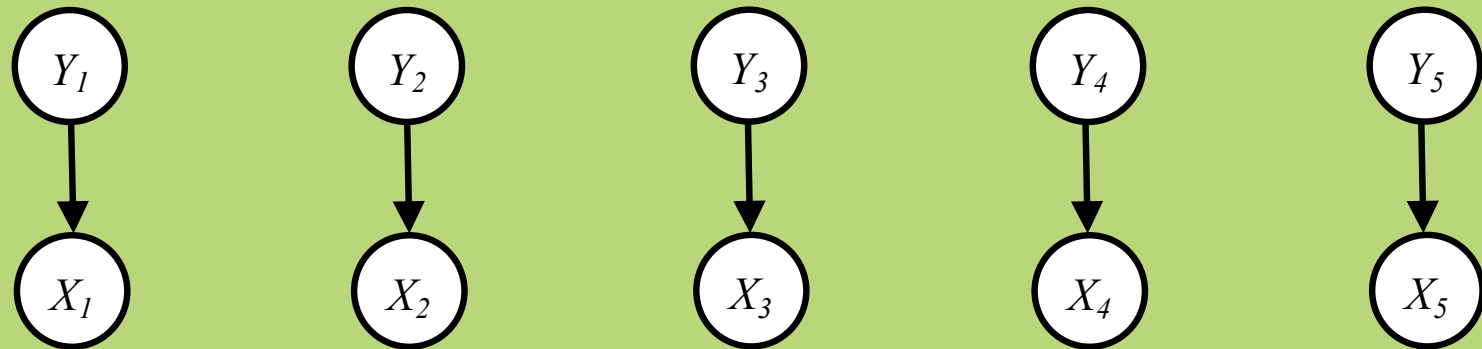
$$P(\mathbf{X}, \mathbf{Y}) = \prod_{t=1}^T P(X_t|Y_t)p(Y_t)$$



HMM:

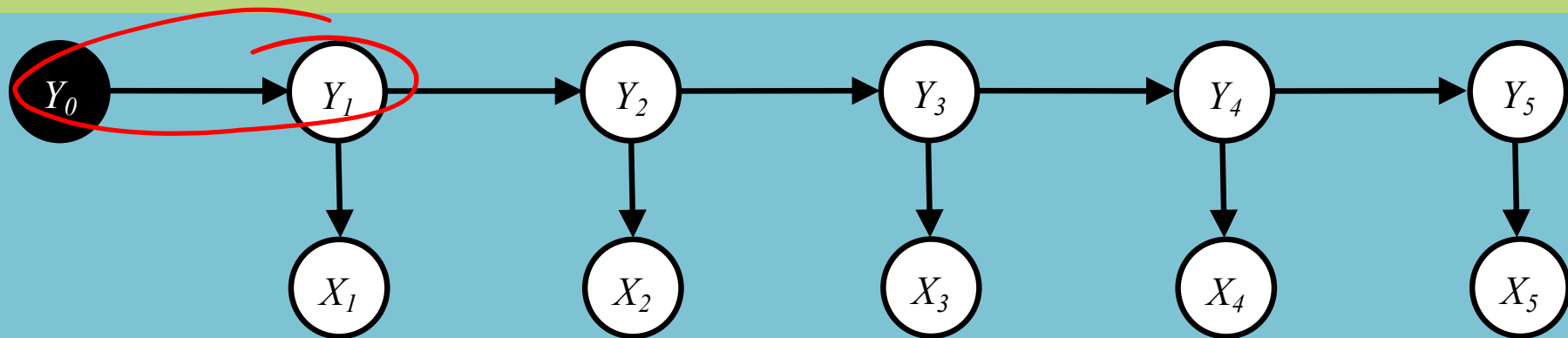
$$P(\mathbf{X}, \mathbf{Y}) = P(Y_1) \left(\prod_{t=1}^T P(X_t|Y_t) \right) \left(\prod_{t=2}^T p(Y_t|Y_{t-1}) \right)$$

From Mixture Model to HMM



“Naïve Bayes”:

$$P(\mathbf{X}, \mathbf{Y}) = \prod_{t=1}^T P(X_t|Y_t)p(Y_t)$$



HMM:

$$P(\mathbf{X}, \mathbf{Y}|Y_0) = \prod_{t=1}^T P(X_t|Y_t)p(Y_t|Y_{t-1})$$

SUPERVISED LEARNING FOR HMMS

Recipe for Closed-form MLE

1. Assume data was generated i.i.d. from some model (i.e. write the generative story) HMM
 $x^{(i)} \sim p(x|\boldsymbol{\theta})$
2. Write log-likelihood
 $\ell(\boldsymbol{\theta}) = \log p(x^{(1)}|\boldsymbol{\theta}) + \dots + \log p(x^{(N)}|\boldsymbol{\theta})$
3. Compute partial derivatives (i.e. gradient)
 $\partial \ell(\boldsymbol{\theta}) / \partial \theta_1 = \dots$
 $\partial \ell(\boldsymbol{\theta}) / \partial \theta_2 = \dots$
 \dots
 $\partial \ell(\boldsymbol{\theta}) / \partial \theta_M = \dots$
4. Set derivatives to zero and solve for $\boldsymbol{\theta}$
 $\partial \ell(\boldsymbol{\theta}) / \partial \theta_m = 0$ for all $m \in \{1, \dots, M\}$
 $\boldsymbol{\theta}^{\text{MLE}} = \text{solution to system of } M \text{ equations and } M \text{ variables}$
5. Compute the second derivative and check that $\ell(\boldsymbol{\theta})$ is concave down at $\boldsymbol{\theta}^{\text{MLE}}$

MLE of Categorical Distribution

1. Suppose we have a **dataset** obtained by repeatedly rolling a M -sided (weighted) die N times. That is, we have data

$$\mathcal{D} = \{x^{(i)}\}_{i=1}^N$$

vector

where $x^{(i)} \in \{1, \dots, M\}$ and $x^{(i)} \sim \text{Categorical}(\phi)$.

2. A random variable is **Categorical** written $X \sim \text{Categorical}(\phi)$ iff

$$P(X = x) = p(x; \phi) = \phi_x$$

where $x \in \{1, \dots, M\}$ and $\sum_{m=1}^M \phi_m = 1$. The **log-likelihood** of the data becomes:

$$\ell(\phi) = \sum_{i=1}^N \log \phi_{x^{(i)}} \text{ s.t. } \sum_{m=1}^M \phi_m = 1$$

$\phi_m \geq 0$

3. Solving this *constrained* optimization problem yields the **maximum likelihood estimator (MLE)**:

$$\phi_m^{MLE} = \frac{N_{x=m}}{N} = \frac{\sum_{i=1}^N \mathbb{I}(x^{(i)} = m)}{N}$$



Hidden Markov Model

HMM Parameters:

Emission matrix, **A**, where $P(X_t = k | Y_t = j) = \underline{A_{j,k}}, \forall t, k$

Transition matrix, **B**, where $P(Y_t = k | Y_{t-1} = j) = \underline{B_{j,k}}, \forall t, k$

Initial probs, **C**, where $P(Y_1 = k) = C_k, \forall k$

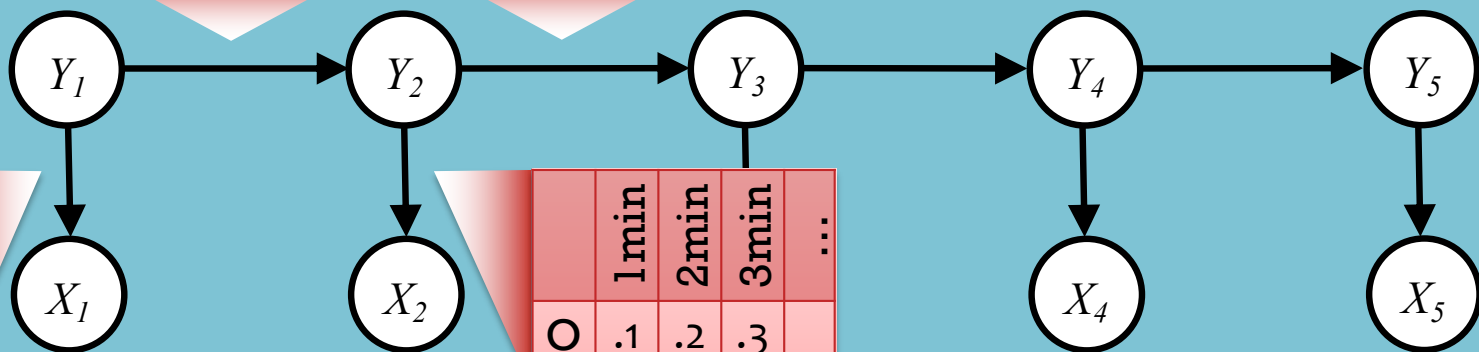
C

O	.8
S	.1
C	.1

B

	O	S	C
O	.9	.08	.02
S	.2	.7	.1
C	.9	0	.1

	O	S	C
O	.9	.08	.02
S	.2	.7	.1
C	.9	0	.1



A

	1min	2min	3min	...
O	.1	.2	.3	
S	.01	.02	.03	
C	0	0	0	

	1min	2min	3min	...
O	.1	.2	.3	
S	.01	.02	.03	
C	0	0	0	

Training HMMs

Whiteboard

- (Supervised) Likelihood for an HMM
- Maximum Likelihood Estimation (MLE) for HMM

Supervised Learning for HMMs

Learning an HMM decomposes into solving two (independent) Mixture Models

Data: $D = \{(\vec{x}^{(i)}, \vec{y}^{(i)})\}_{i=1}^N$ $\vec{x} = [x_1, \dots, x_T]^T$
 $\vec{y} = [y_1, \dots, y_T]^T$

Likelihood:

$$l(A, B, C) = \sum_{i=1}^N \log p(\vec{x}^{(i)}, y^{(i)} | A, B, C)$$

$$= \sum_{i=1}^N \left[\underbrace{\log p(y_1^{(i)} | C)}_{\text{initial}} + \underbrace{\left(\sum_{t=2}^T \log p(y_t^{(i)} | y_{t-1}^{(i)}, B) \right)}_{\text{transition}} + \underbrace{\left(\sum_{t=1}^T \log p(x_t^{(i)} | y_t^{(i)}, A) \right)}_{\text{emission}} \right]$$

MLE:

$$\hat{A}, \hat{B}, \hat{C} = \underset{A, B, C}{\operatorname{argmax}} l(A, B, C)$$

$$\Rightarrow \hat{C} = \underset{C}{\operatorname{argmax}} \sum_{i=1}^N \log p(y_1^{(i)} | C)$$

$$\hat{B} = \underset{B}{\operatorname{argmax}} \sum_{i=1}^N \sum_{t=2}^T \log p(y_t^{(i)} | y_{t-1}^{(i)}, B)$$

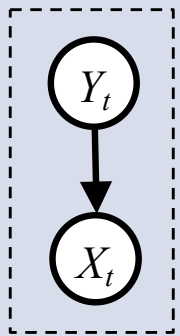
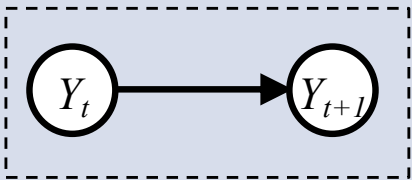
$$\hat{A} = \underset{A}{\operatorname{argmax}} \sum_{i=1}^N \sum_{t=1}^T \log p(x_t^{(i)} | y_t^{(i)}, A)$$

Can solve in closed form, which yields...

$$\hat{C}_k = \frac{\#(y_1^{(i)} = k)}{N} \quad \forall i, k$$

$$\hat{B}_{jk} = \frac{\#(y_t^{(i)} = k \text{ and } y_{t-1}^{(i)} = j)}{\#(y_{t-1}^{(i)} = j)} \quad \forall i, t > 1, j, k$$

$$\hat{A}_{jk} = \frac{\#(x_t^{(i)} = k \text{ and } y_t^{(i)} = j)}{\#(y_t^{(i)} = j)} \quad \forall i, t, j, k$$



Hidden Markov Model

HMM Parameters:

Emission matrix, \mathbf{A} , where $P(X_t = k | Y_t = j) = A_{j,k}, \forall t, k$

Transition matrix, \mathbf{B} , where $P(Y_t = k | Y_{t-1} = j) = B_{j,k}, \forall t, k$

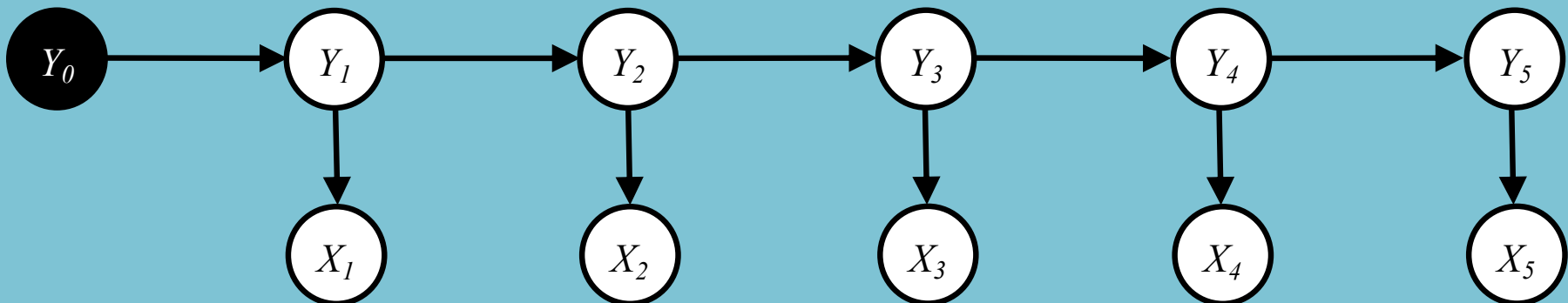
Assumption: $y_0 = \text{START}$

Generative Story:

$Y_t \sim \text{Multinomial}(\mathbf{B}_{Y_{t-1}}) \forall t$

$X_t \sim \text{Multinomial}(\mathbf{A}_{Y_t}) \forall t$

For notational convenience, we fold the initial probabilities \mathbf{C} into the transition matrix \mathbf{B} by our assumption.

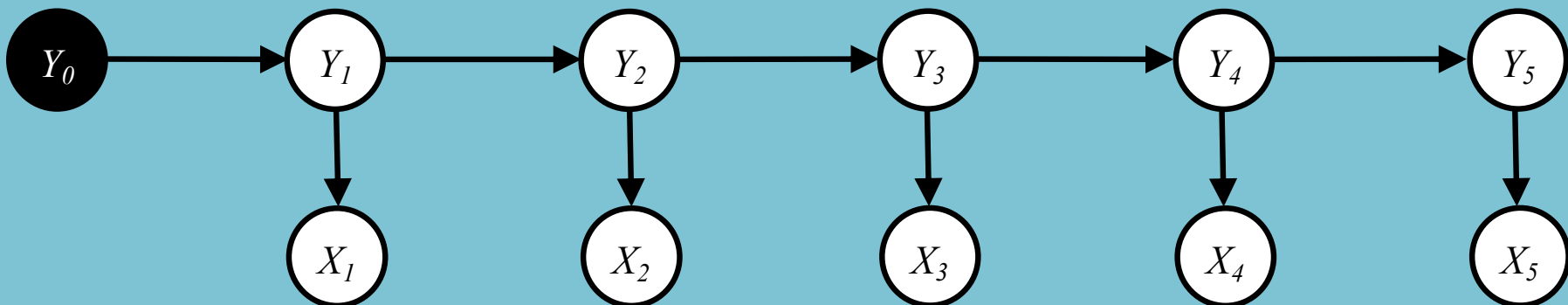


Hidden Markov Model

Joint Distribution:

$y_0 = \text{START}$

$$\begin{aligned} p(\mathbf{x}, \mathbf{y} | y_0) &= \prod_{t=1}^T p(x_t | y_t) p(y_t | y_{t-1}) \\ &= \prod_{t=1}^T A_{y_t, x_t} B_{y_{t-1}, y_t} \end{aligned}$$



Supervised Learning for HMMs

Learning an HMM decomposes into solving two (independent) Mixture Models

$$D = \{(\vec{x}^{(i)}, \vec{y}^{(i)})\}_{i=1}^N$$

$$\begin{aligned} \text{Likelihood} : \quad \ell(A, B) &= \sum_{i=1}^N \log p(\vec{x}^{(i)}, \vec{y}^{(i)}) \\ &= \sum_{i=1}^N \left[\sum_{t=1}^T \log p(y_t^{(i)} | y_{t-1}^{(i)}, B) + \log p(x_t^{(i)} | y_t^{(i)}, A) \right] \end{aligned}$$

$$\text{MLE} : \quad \hat{A}, \hat{B} = \underset{A, B}{\text{argmax}} \ell(A, B)$$

$$\hat{A} = \underset{A}{\text{argmax}} \sum_{i=1}^N \left[\sum_{t=1}^T \log p(x_t^{(i)} | y_t^{(i)}, A) \right]$$

$$\hat{B} = \underset{B}{\text{argmax}} \sum_{i=1}^N \left[\sum_{t=1}^T \log p(y_t^{(i)} | y_{t-1}^{(i)}, B) \right]$$

↑ can solve in closed form to get...

$$\hat{B}_{jk} = \frac{\#(y_t^{(i)} = k \text{ and } y_{t-1}^{(i)} = j)}{\#(y_{t-1}^{(i)} = j)}$$

$$\hat{A}_{jk} = \frac{\#(x_t^{(i)} = k \text{ and } y_t^{(i)} = j)}{\#(y_t^{(i)} = j)}$$

