

10-301/601: Introduction to Machine Learning Lecture 15 – Learning Theory (Finite Case)

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Front Matter

- Announcements
 - HW5 released 10/9, due 10/27 at 11:59 PM

What is Machine Learning 10-301/601?

- Supervised Models
 - Decision Trees
 - KNN
 - Naïve Bayes
 - Perceptron
 - Logistic Regression
 - Linear Regression
 - Neural Networks
- Unsupervised Learning
- Ensemble Methods
- Deep Learning & Generative AI
- Learning Theory
- Reinforcement Learning
- Important Concepts
 - Feature Engineering
 - Regularization and Overfitting
 - Experimental Design
 - Societal Implications

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- **Learning Theory**
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Statistical Learning Theory Model

1. Data points are generated i.i.d. from some *unknown* distribution

$$\mathbf{x}^{(n)} \sim p^*(\mathbf{x})$$

2. Labels are generated from some *unknown* function

$$y^{(n)} = c^*(\mathbf{x}^{(n)})$$

3. The learning algorithm chooses the hypothesis (or classifier) with lowest *training* error rate from a specified hypothesis set, \mathcal{H}
4. Goal: return a hypothesis (or classifier) with low *true* error rate

Types of Error

- True error rate
 - Actual quantity of interest in machine learning
 - How well your hypothesis will perform on average across all possible data points
- Test error rate
 - Used to evaluate hypothesis performance
 - Good estimate of your hypothesis's true error
- Validation error rate
 - Used to set hypothesis hyperparameters
 - Slightly “optimistic” estimate of your hypothesis's true error
- Training error rate
 - Used to set model parameters
 - Very “optimistic” estimate of your hypothesis's true error

Types of Risk (a.k.a. Error)

- Expected risk of a hypothesis h (a.k.a. true error)

$$R(h) = P_{\mathbf{x} \sim p^*}(c^*(\mathbf{x}) \neq h(\mathbf{x}))$$

- Empirical risk of a hypothesis h (a.k.a. training error)

$$\begin{aligned}\hat{R}(h) &= P_{\mathbf{x} \sim \mathcal{D}}(c^*(\mathbf{x}) \neq h(\mathbf{x})) \\ &= \frac{1}{N} \sum_{n=1}^N \mathbb{1}(c^*(\mathbf{x}^{(n)}) \neq h(\mathbf{x}^{(n)})) \\ &= \frac{1}{N} \sum_{n=1}^N \mathbb{1}(y^{(n)} \neq h(\mathbf{x}^{(n)}))\end{aligned}$$

where $\mathcal{D} = \{(\mathbf{x}^{(n)}, y^{(n)})\}_{n=1}^N$ is the training data set and $\mathbf{x} \sim \mathcal{D}$ denotes a point sampled uniformly at random from \mathcal{D}

Three Hypotheses of Interest

1. The *true function*, c^*

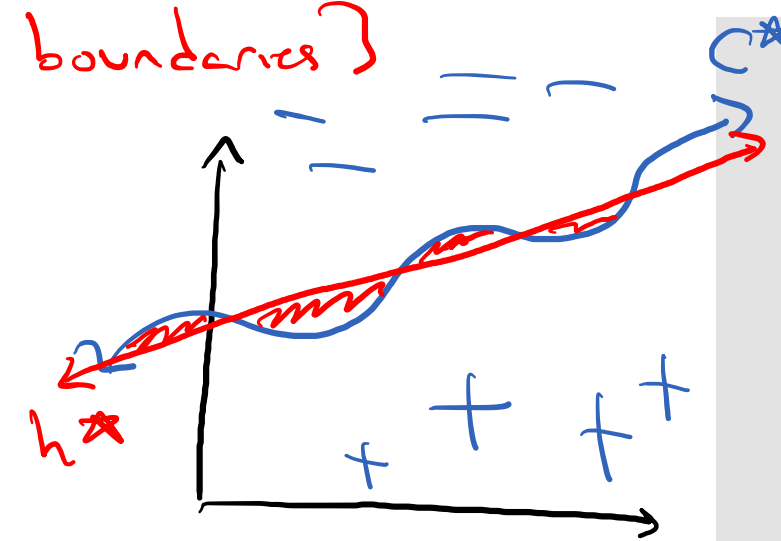
2. The *expected risk minimizer*,

$$h^* = \operatorname{argmin}_{h \in \mathcal{H}} R(h)$$

3. The *empirical risk minimizer*,

$$\hat{h} = \operatorname{argmin}_{h \in \mathcal{H}} \hat{R}(h)$$

$\mathcal{H} = \{ \text{all linear decision boundaries} \}$



Poll Question 1:
Which of the following are *always* true?

- A. $c^* = h^*$
- B. $c^* = \hat{h}$
- C. $h^* = \hat{h}$
- D. $c^* = h^* = \hat{h}$
- E. None of the above
- F. TOXIC

- The *true function*, c^*

- The *expected risk minimizer*,

$$h^* = \underset{h \in \mathcal{H}}{\operatorname{argmin}} R(h)$$

- The *empirical risk minimizer*,

$$\hat{h} = \underset{h \in \mathcal{H}}{\operatorname{argmin}} \hat{R}(h)$$

Key Question

- Given a hypothesis with zero/low training error, what can we say about its true error?

PAC Learning

- PAC = Probably Approximately Correct
- PAC Criterion:

$$P(|R(h) - \hat{R}(h)| \leq \epsilon) \geq 1 - \delta \forall h \in \mathcal{H}$$

for some ϵ (difference between expected and empirical risk) and δ (probability of “failure”)

- We want the PAC criterion to be satisfied for \mathcal{H} with small values of ϵ and δ

Sample Complexity

- The sample complexity of an algorithm/hypothesis set, \mathcal{H} , is the number of labelled training data points needed to satisfy the PAC criterion for some δ and ϵ
- Four cases
 - Realizable vs. Agnostic
 - Realizable $\rightarrow c^* \in \mathcal{H}$
 - Agnostic $\rightarrow c^*$ might or might not be in \mathcal{H}
 - Finite vs. Infinite
 - Finite $\rightarrow |\mathcal{H}| < \infty$
 - Infinite $\rightarrow |\mathcal{H}| = \infty$

Theorem 1: Finite, Realizable Case

- For a finite hypothesis set \mathcal{H} s.t. $c^* \in \mathcal{H}$ and arbitrary distribution p^* , if the number of labelled training data points satisfies

$$M \geq \frac{1}{\epsilon} \left(\ln(|\mathcal{H}|) + \ln\left(\frac{1}{\delta}\right) \right)$$

then with probability at least $1 - \delta$, all $h \in \mathcal{H}$ with $\hat{R}(h) = 0$ have $R(h) \leq \epsilon$

$$P(A \cup B) =$$

$$P(A) + P(B) - P(A \cap B)$$

$$\leq P(A) + P(B)$$

Proof of Theorem 1: Finite, Realizable Case

1. Assume there are K "bad" hypotheses in H $\{h_1, \dots, h_K\}$ that all have $R(h_i) > \epsilon$
2. Pick **one bad hypothesis** h_i
 - A. $P(h_i \text{ correctly classifies the first training data point}) < 1 - \epsilon$
 - B. $P(h_i \text{ correctly classifies all } M \text{ training data points}) < (1 - \epsilon)^M$
3. **P(at least one bad hypothesis correctly classifies all } M \text{ training data points)}**
 $= P(h_1 \text{ correctly classifies all } M \text{ training data points} \cup h_2 \text{ correctly classifies all } M \text{ training data points} \cup \dots \cup h_K \text{ correctly classifies all } M \text{ training data points})$

Proof of
Theorem 1:
Finite,
Realizable Case

$$4. P(\hat{R}(h_1) = 0 \cup \hat{R}(h_2) = 0 \cup \dots \cup \hat{R}(h_k) = 0) \\ \leq \sum_{i=1}^k P(\hat{R}(h_i) = 0) < \sum_{i=1}^k (1-\epsilon)^M$$

$$\approx k(1-\epsilon)^M \\ < |H|(1-\epsilon)^M$$

5. $P(\text{at least one bad hypothesis correctly classifies all } M \text{ training data points}) \\ < |H|(1-\epsilon)^M$

6. We want $|H|(1-\epsilon)^M \leq \delta$

Proof of
Theorem 1:
Finite,
Realizable Case

Using the fact that $1 - x \leq \exp(-x) \forall x$

$$|H| (1 - \epsilon)^M \leq |H| \exp(-\epsilon M)$$
$$\Rightarrow |H| \exp(-\epsilon M) \leq \delta$$
$$\Rightarrow \exp(-\epsilon M) \leq \frac{\delta}{|H|}$$
$$\Rightarrow -\epsilon M \leq \log \frac{\delta}{|H|}$$
$$\Rightarrow \epsilon M \geq \log \frac{|H|}{\delta}$$
$$\Rightarrow \epsilon M \geq \log |H| + \log \frac{1}{\delta}$$
$$\Rightarrow M \geq \frac{1}{\epsilon} (\log(|H|) + \log \frac{1}{\delta})$$

Proof of
Theorem 1:
Finite,
Realizable Case

8. Given $M \geq \frac{1}{\epsilon} (\log |H| + \log \frac{1}{\delta})$ labelled training data points, the probability \exists a bad hypothesis $h_i \in H$ where $R(h_i) > \epsilon$ and $\hat{R}(h_i) = 0 \leq \delta$



Given $M \geq \frac{1}{\epsilon} (\log |H| + \log \frac{1}{\delta})$ labelled training data points, the probability that all bad hypotheses $h_i \in H$ with $R(h_i) > \epsilon$ have $\hat{R}(h_i) > 0$ is $\geq 1 - \delta$

Proof of Theorem 1: Finite, Realizable Case

Aside: Proof by Contrapositive

- The contrapositive of a statement $A \Rightarrow B$ is $\neg B \Rightarrow \neg A$
- A statement and its contrapositive are logically equivalent, i.e., $A \Rightarrow B$ means that $\neg B \Rightarrow \neg A$
- Example: “it’s raining \Rightarrow Henry brings an umbrella”
is the same as saying
“Henry didn’t bring an umbrella \Rightarrow it’s not raining”

Proof of Theorem 1: Finite, Realizable Case

7. Given $M \geq \frac{1}{\epsilon} \left(\ln(|\mathcal{H}|) + \ln\left(\frac{1}{\delta}\right) \right)$ labelled training data points, the probability that all hypotheses $h_k \in \mathcal{H}$ with $R(h_k) > \epsilon$ have $\hat{R}(h_k) > 0$ is $\geq 1 - \delta$

$$A \Rightarrow B$$

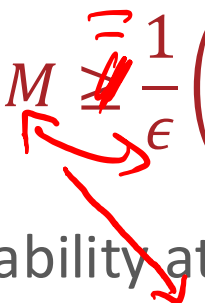


$$\neg B \Rightarrow \neg A$$

Given $M \geq \frac{1}{\epsilon} \left(\log |\mathcal{H}| + \log \frac{1}{\delta} \right)$ labelled training data points, the probability that all hypotheses $h_k \in \mathcal{H}$ with $\hat{R}(h_k) = 0$ have $R(h_k) \leq \epsilon$ is $\geq 1 - \delta$

Theorem 1: Finite, Realizable Case

- For a finite hypothesis set \mathcal{H} s.t. $c^* \in \mathcal{H}$ and arbitrary distribution p^* , if the number of labelled training data points satisfies

$$M \geq \frac{1}{\epsilon} \left(\ln(|\mathcal{H}|) + \ln\left(\frac{1}{\delta}\right) \right)$$


then with probability at least $1 - \delta$, all $h \in \mathcal{H}$ with $\hat{R}(h) = 0$ have $R(h) \leq \epsilon$

- Making the bound tight and solving for ϵ gives...

Statistical Learning Theory Corollary

- For a finite hypothesis set \mathcal{H} s.t. $c^* \in \mathcal{H}$ and arbitrary distribution p^* , given a training data set S s.t. $|S| = M$, all $h \in \mathcal{H}$ with $\hat{R}(h) = 0$ have

$$R(h) \leq \frac{1}{M} \left(\ln(|\mathcal{H}|) + \ln\left(\frac{1}{\delta}\right) \right)$$

with probability at least $1 - \delta$.

Theorem 2: Finite, Agnostic Case

- For a finite hypothesis set \mathcal{H} and arbitrary distribution p^* , if the number of labelled training data points satisfies

$$M \geq \frac{1}{2\epsilon^2} \left(\ln(|\mathcal{H}|) + \ln\left(\frac{2}{\delta}\right) \right)$$

then with probability at least $1 - \delta$, all $h \in \mathcal{H}$ satisfy

$$|R(h) - \hat{R}(h)| \leq \epsilon$$

- Bound is inversely quadratic in ϵ , e.g., halving ϵ means we need four times as many labelled training data points
- Again, making the bound tight and solving for ϵ gives...

Statistical Learning Theory Corollary

- For a finite hypothesis set \mathcal{H} and arbitrary distribution p^* , given a training data set S s.t. $|S| = M$, all $h \in \mathcal{H}$ have

$$R(h) \leq \hat{R}(h) + \sqrt{\frac{1}{2M} \left(\ln(|\mathcal{H}|) + \ln\left(\frac{2}{\delta}\right) \right)}$$

with probability at least $1 - \delta$.

What happens
when $|\mathcal{H}| = \infty$?

- For a finite hypothesis set \mathcal{H} and arbitrary distribution p^* , given a training data set S s.t. $|S| = M$, all $h \in \mathcal{H}$ have

$$R(h) \leq \hat{R}(h) + \sqrt{\frac{1}{2M} \left(\ln(|\mathcal{H}|) + \ln\left(\frac{2}{\delta}\right) \right)}$$

with probability at least $1 - \delta$.