10-301/601: Introduction to Machine Learning Lecture 4 – Overfitting & KNNs

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9/9/24

Front Matter

• Announcements:

- HW2 released 9/4, due 9/16 at 11:59 PM
 - Unlike HW1, you will only have:
 - 1 (graded) submission for the written portion
 - 10 submissions of the programming portion to our autograder

Recall: Decision Tree Pseudocode def train(\mathcal{D}): store root = tree recurse(\mathcal{D}) def tree recurse(\mathcal{D}'): q = new node()base case - if (SOME CONDITION): recursion - else: find best attribute to split on, x_d q.split = x_d for v in $V(x_d)$, all possible values of x_d : $\mathcal{D}_{v} = \left\{ \left(x^{(n)}, y^{(n)} \right) \in \mathcal{D}' \mid x_{d}^{(n)} = v \right\}$ q.children(v) = tree recurse(\mathcal{D}_{v})

Recall: Decision Tree Pseudocode def train(\mathcal{D}):

store root = tree recurse(\mathcal{D}) def tree recurse(\mathcal{D}'): q = new node()base case - if (\mathcal{D}') is empty OR all labels in \mathcal{D}' are the same OR all features in \mathcal{D}' are identical OR some other stopping criterion): q.label = majority vote(\mathcal{D}')

recursion - else:

return q

Q & A:

Wait, how could we end up calling tree recurse with an empty dataset in the first place?

- Given some subset of our dataset, it could be the case that we choose to split on some feature where not every value that the feature could take on appears in the subset
 This could happen if we know something about the
 - feature *a priori* or we observe that the feature takes on more values in a different subset/the entire training dataset.
- In this case we would still want to make a branch for it in our decision tree because at inference time, some new data point might come along that goes down that branch

Q & A:

Okay, so what should we predict in leaf nodes with no training data?

- Well, there isn't really a majority label, so we could return a random label or a majority vote over the entire training dataset.
- This is related to the question of "what should we predict if some feature in our test dataset takes on a value we didn't observe in the training dataset?"
 - Going down a branch corresponding to an unseen feature value is like hitting a leaf node with no training data.

Data Set	Classes	Attr.s	Training Set	Test Set
hypo	4	29	1000	2772
breast	2	9	200	86
tumor	22	18	237	102
lymph	4	18	103	45
LED	10	7	200	1800
mush	2	22	200	7924
votes	2	17	200	235
votes1	2	16	200	235
iris	3	4	100	50
glass	7	9	100	114
xd6	2	10	200	400
pole	2	4	200	1647

Table 1. Properties of the data set

Bluntine & Niblett (1992) Splitting Criteria Experiments Table 3. Error for different splitting rules (pruned trees).

Bluntine &
Niblett (1992)
Splitting
Criteria
Experiments

		ting Rule				
Data Set	GINI	Info. Gain	Random			
hypo	1.01 ± 0.29	0.95 ± 0.22	7.44 ± 0.53			
breast	28.66 ± 3.87	28.49 ± 4.28	29.65 ± 4.97			
tumor	60.88 ± 5.44	62.70 ± 3.89	67.94 ± 5.68			
lymph	24.44 ± 6.92	24.00 ± 6.87	32.33 ± 11.25			
LED	33.77 ± 3.06	32.89 ± 2.59	$38.18~\pm~4.57$			
mush	1.44 ± 0.47	1.44 ± 0.47	$8.77~\pm~4.65$			
votes	4.47 ± 0.95	4.57 ± 0.87	$12.40~\pm~4.56$			
votes1	12.79 ± 1.48	13.04 ± 1.65	15.62 ± 2.73			
iris	5.00 ± 3.08	4.90 ± 3.08	$14.20~\pm~~6.77$			
glass	39.56 ± 6.20	50.57 ± 6.73	53.20 ± 5.01			
xd6	22.14 ± 3.23	22.17 ± 3.36	31.86 ± 3.62			
pole	15.43 ± 1.51	15.47 ± 0.88	26.38 ± 6.92			
	Key takea	way: Gini				
	impuri	impurity and				
	Informatio					
	mutual inf	mutual information)				
	are nearly	are nearly identical				

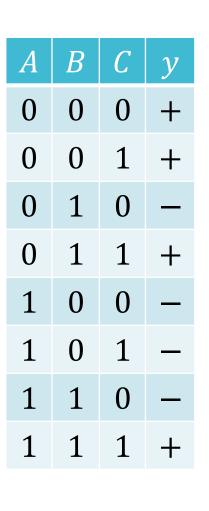
Table 4. Difference and significance of error for GINI splitting rule versus others.

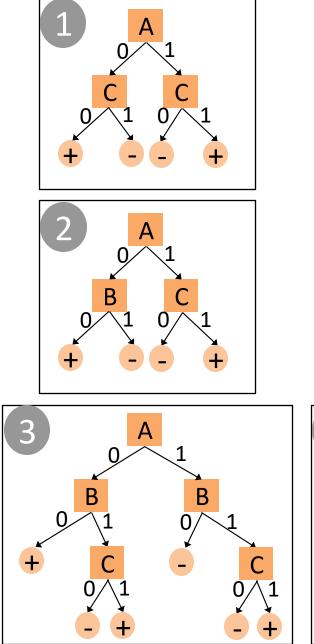
Bluntine & Niblett (1992) Splitting Criteria Experiments

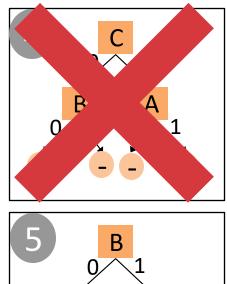
		Splitting Rule
Data Set	Info. Gain	Random
hypo	-0.06 (0.82)	6.43 (1.00)
breast	-0.17 (0.23)	0.99 (0.72)
tumor	1.81 (0.84)	7.06 (0.99)
lymph	-0.44 (0.83)	7.89 (0.99)
LED	0.12 (0.17)	5.41 (0.99)
mush	0.00 (0.00)	7.32 (0.99)
votes	0.11 (0.55)	7.94 (0.99)
votes1	0.26 (0.47)	2.83 (0.99)
iris	-0.10 (0.67)	9.20 (0.99)
glass	1.01 (0.50)	13.64 (0.99)
xd6	0.04 (0.11)	9.72 (0.99)
pole	0.03 (0.11)	10.95 (0.99)

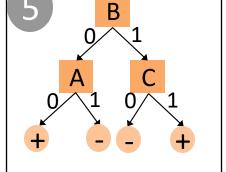
average difference in error between the splitting criteria statistical significance of the difference according to a two-sided paired t-test

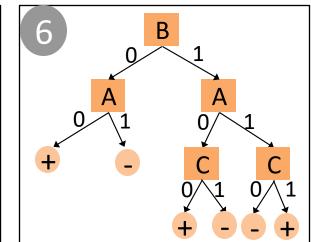
Poll Question 1: Which decision tree would you learn if you used training error rate as the splitting criterion? **Break ties** alphabetically.



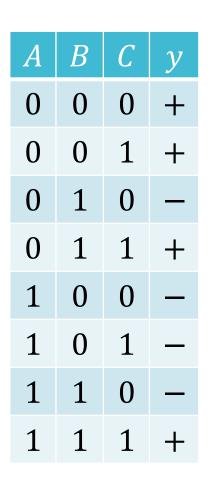


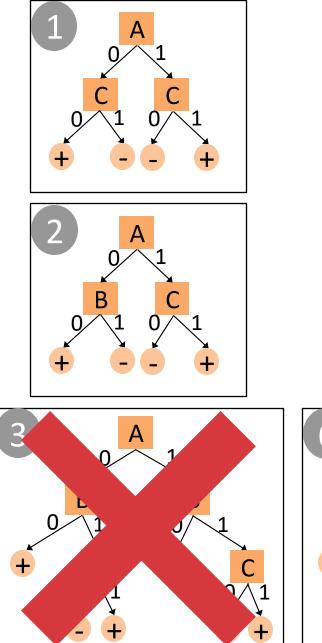


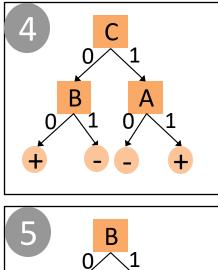


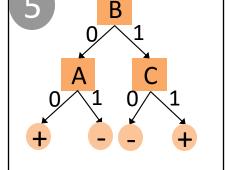


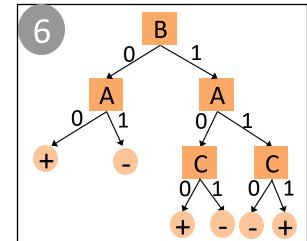
Poll Question 2: Which decision tree is the smallest decision tree that achieves the lowest possible training error?











Decision Trees: Inductive Bias

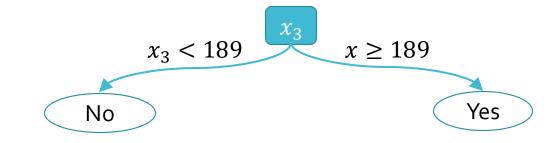
- The **inductive bias** of a machine learning algorithm is the principal by which it generalizes to unseen examples
- What is the inductive bias of the ID3 algorithm?

• Try to find the <u>smallert</u> decision tree that achieves $\frac{1}{\sqrt{2ev}}$ training <u>croc</u> with high motival information features at the top Decision Trees: Pros & Cons

- Pros
 - Interpretable
 - Efficient (computational cost and storage)
 - Can be used for classification and regression tasks
 - Compatible with categorical and real-valued features
- Cons
 - Learned greedily: each split only considers the immediate impact on the splitting criterion
 - Not guaranteed to find the smallest (fewest number of splits) tree that achieves a training error rate of 0.

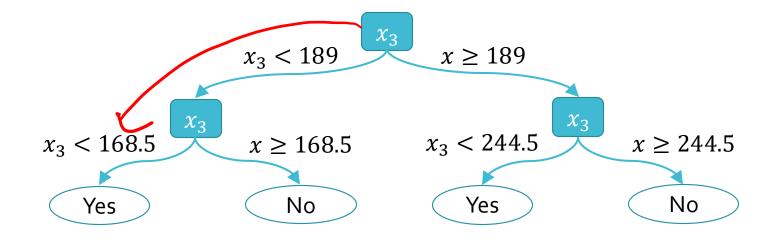
Real-Valued Features: Example

x ₃ holesterol	<i>y</i> Heart Disease?	x ₃ Cholesterol	<i>y</i> Heart Disease?
174	No	155	No
155	No	163	Yes
163	Yes	174	No
233	Yes	 178	No
197	Yes	181	No
181	No	197	Yes
244	Yes	221	Yes
245	No	233	Yes
178	No	244	Yes
221	Yes	245	No



Real-Valued Features: Example

x ₃ Cholesterol	<i>y</i> Heart Disease?	x ₃ Cholesterol	y Heart Disease?
174	No	155	THO)
155	No	163	Yes
163	Yes	174	No
233	Yes	 178	No
197	Yes	181	No
181	No	197	Yes
244	Yes	221	Yes
245	No	233	Yes
178	No	244	Yes
221	Yes	245	No



Decision Trees: Pros & Cons

- Pros
 - Interpretable
 - Efficient (computational cost and storage)
 - Can be used for classification and regression tasks
 - Compatible with categorical and real-valued features
- Cons
 - Learned greedily: each split only considers the immediate impact on the splitting criterion
 - Not guaranteed to find the smallest (fewest number of splits) tree that achieves a training error rate of 0.
 - Liable to overfit!

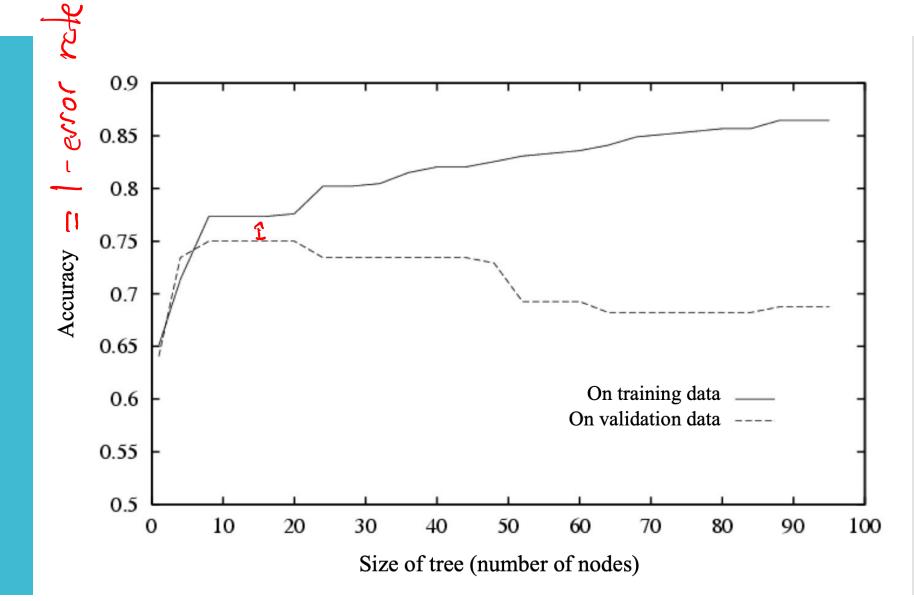
Overfitting

- Overfitting occurs when the classifier (or model)...
 - is too complex
 - fits noise or "outliers" in the training dataset as opposed to the actual pattern of interest
 - doesn't have enough inductive bias pushing it to generalize e.g., the memorizer
- Underfitting occurs when the classifier (or model)...
 - is too simple
 - can't capture the actual pattern of interest in the training dataset
 - has too much inductive bias e.g., the majority vote classifier

Recall: Different Kinds of Error

- Training error rate = $err(h, D_{train})$
- Test error rate = $err(h, \mathcal{D}_{test})$
- True error rate = err(h)
 - = the error rate of h on all possible examples
 - In machine learning, this is the quantity that we care about but, in most cases, it is unknowable.
- Overfitting occurs when err(h) > err(h, D_{train})
 err(h) err(h, D_{train}) can be thought of as a measure of overfitting

Overfitting in Decision Trees



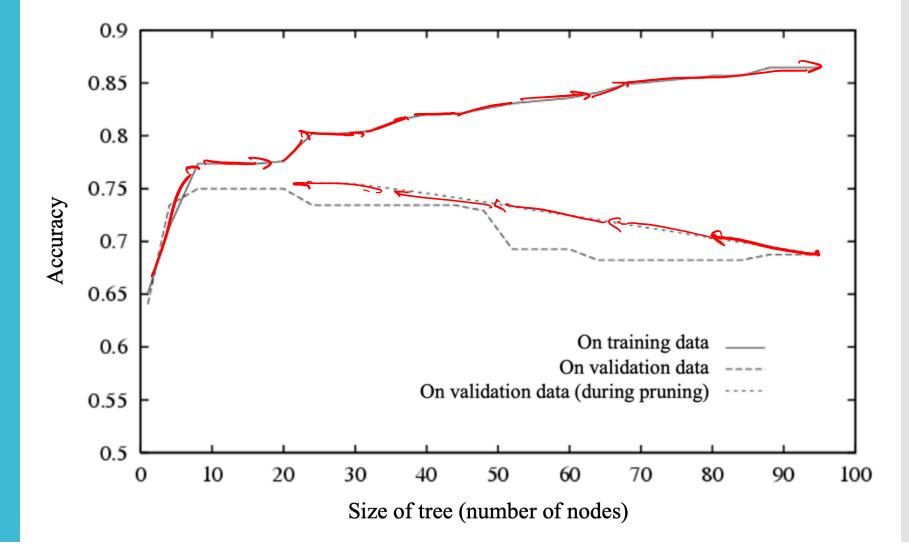
Combatting Overfitting in Decision Trees • Heuristics:

- Do not split leaves past a fixed depth, δ
- Do not split leaves with fewer than *c* data points
- Do not split leaves where the maximal information gain is less than au
- Take a majority vote in impure leaves

Combatting Overfitting in Decision Trees • Pruning:

- First, learn a decision tree
- Then, evaluate each split using a "validation" dataset by comparing the validation error rate with and without that split
- Greedily remove the split that most decreases the validation error rate
- Stop if no split is removed

Pruning Decision Trees



Decision Tree Learning Objectives You should be able to...

- 1. Implement decision tree training and prediction
- 2. Use effective splitting criteria for decision trees and be able to define entropy, conditional entropy, and mutual information / information gain
- 3. Explain the difference between memorization and generalization [CIML]
- 4. Describe the inductive bias of a decision tree
- 5. Formalize a learning problem by identifying the input space, output space, hypothesis space, and target function
- 6. Explain the difference between true error and training error
- 7. Judge whether a decision tree is "underfitting" or "overfitting"
- 8. Implement a pruning or early stopping method to combat overfitting in decision tree learning

Real-valued Features



Fisher Iris Dataset

Fisher (1936) used 150 measurements of flowersfrom 3 different species: Iris setosa (0), Iris virginica(1), Iris versicolor (2) collected by Anderson (1936)

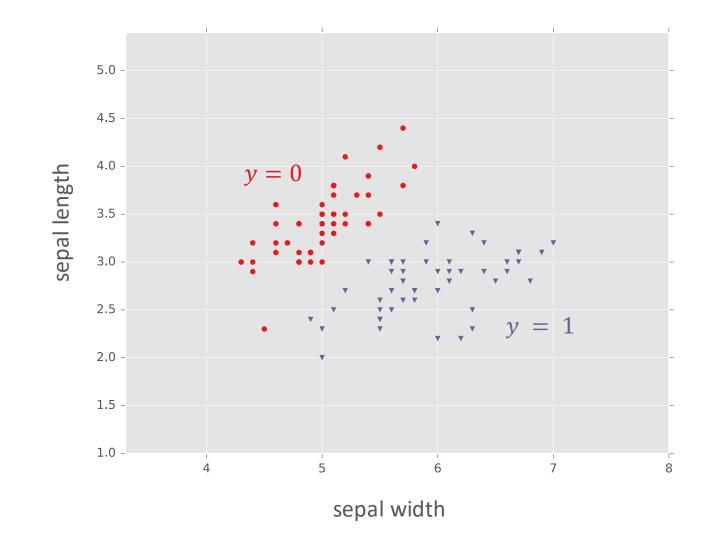
Species	Sepal Length	Sepal Width	Petal Length	Petal Width
0	4.3	3.0	1.1	0.1
0	4.9	3.6	1.4	0.1
0	5.3	3.7	1.5	0.2
1	4.9	2.4	3.3	1.0
1	5.7	2.8	4.1	1.3
1	6.3	3.3	4.7	1.6
1	6.7	3.0	5.0	1.7

Fisher Iris Dataset

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Species	Sepal Length	Sepal Width
0	4.3	3.0
0	4.9	3.6
0	5.3	3.7
1	4.9	2.4
1	5.7	2.8
1	6.3	3.3
1	6.7	3.0

Fisher Iris Dataset





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Duck test

From Wikipedia, the free encyclopedia

For the use of "the duck test" within the Wikipedia community, see Wikipedia:DUCK.

The duck test is a form of abductive reasoning. This is its usual expression:

If it looks like a duck, swims like a duck, and quacks like a duck, then it probably *is* a duck.

The Duck Test

*k*NN: In-class Activity

- 1. If you have either a red or blue folder, hold it above your head, high in the air
- 2. Note the location of the manilla folder
- 3. Raise your hand high in the air if you believe the manilla folder should be classified as red
- 4. Keep your hand raised until you believe the manilla folder should be classified as blue; then put it down

The Duck Test for Machine Learning

- Classify a point as the label of the "most similar" training point
- Idea: given real-valued features, we can use a distance metric to determine how similar two data points are
- A common choice is Euclidean distance:

$$d(\mathbf{x}, \mathbf{x}') = \|\mathbf{x} - \mathbf{x}'\|_2 = \sqrt{\sum_{d=1}^{D} (x_d - x'_d)^2}$$

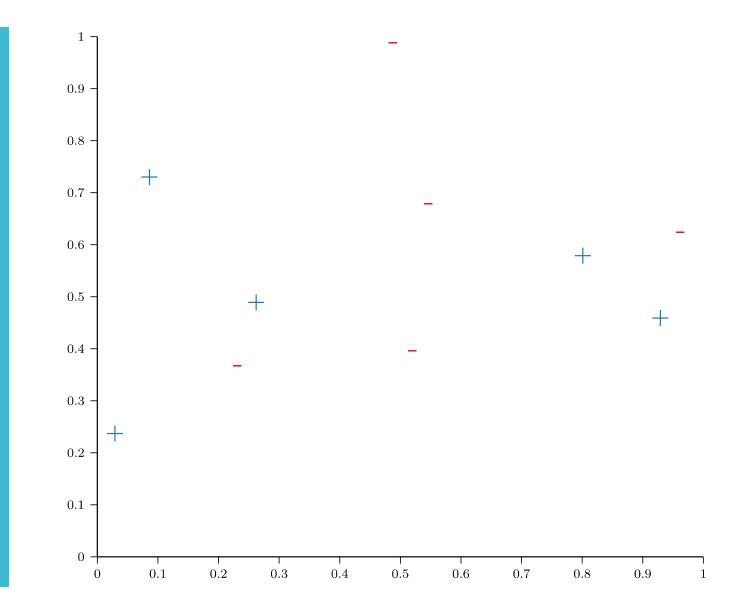
• An alternative is the Manhattan distance:

$$d(\mathbf{x}, \mathbf{x}') = \|\mathbf{x} - \mathbf{x}'\|_1 = \sum_{d=1}^{D} |x_d - x'_d|$$

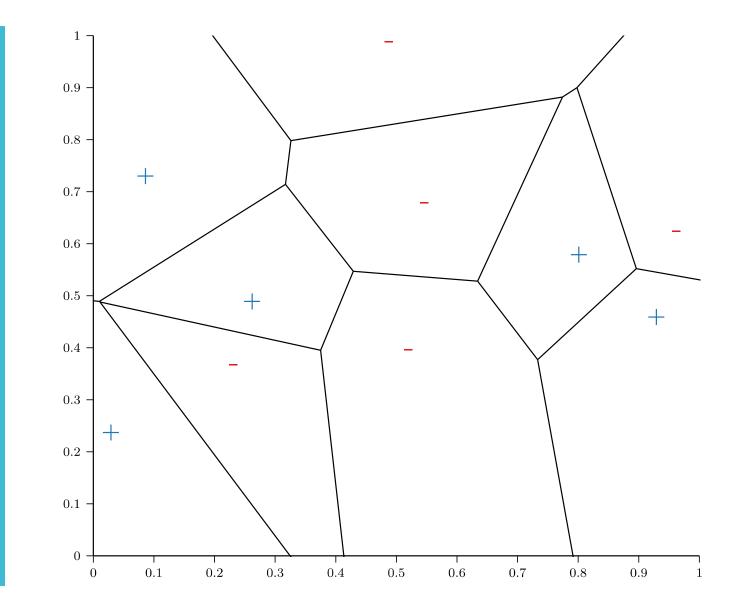
Nearest Neighbor: Pseudocode

def train (Dtrain): Store Dtrain def $h(\vec{x}')$: find the necrest dote point to x' in Dtrain, (x(i), y(i)) return y(i)

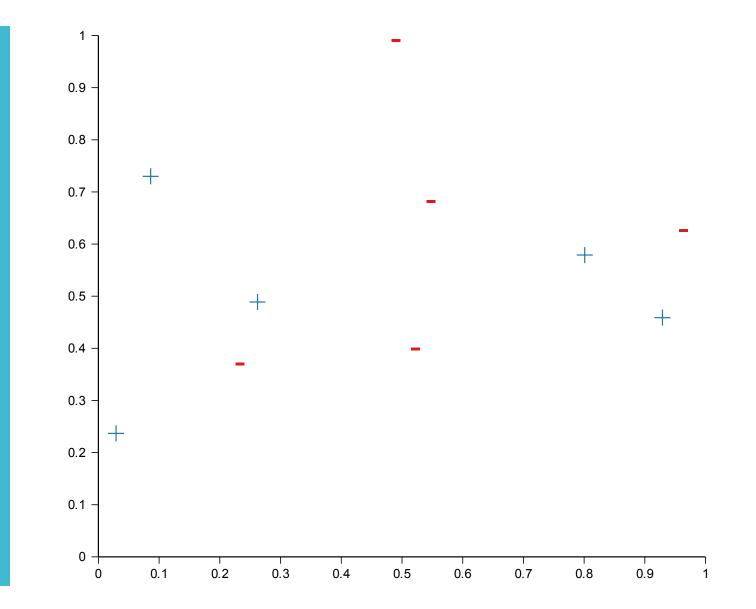
Nearest Neighbor: Example



Nearest Neighbor: Example



Nearest Neighbor: Example



The Nearest Neighbor Model • Requires no training!

- Always has zero training error!
 - A data point is always its own nearest neighbor