



# 10-301/10-601 Introduction to Machine Learning

Machine Learning Department  
School of Computer Science  
Carnegie Mellon University

# Linear Regression + Optimization for ML

Matt Gormley  
Lecture 8  
Feb. 13, 2023

# Q&A

**Q:** Could we just get rid of that pesky step size hyperparameter  $\gamma^{(t)}$  in gradient descent?

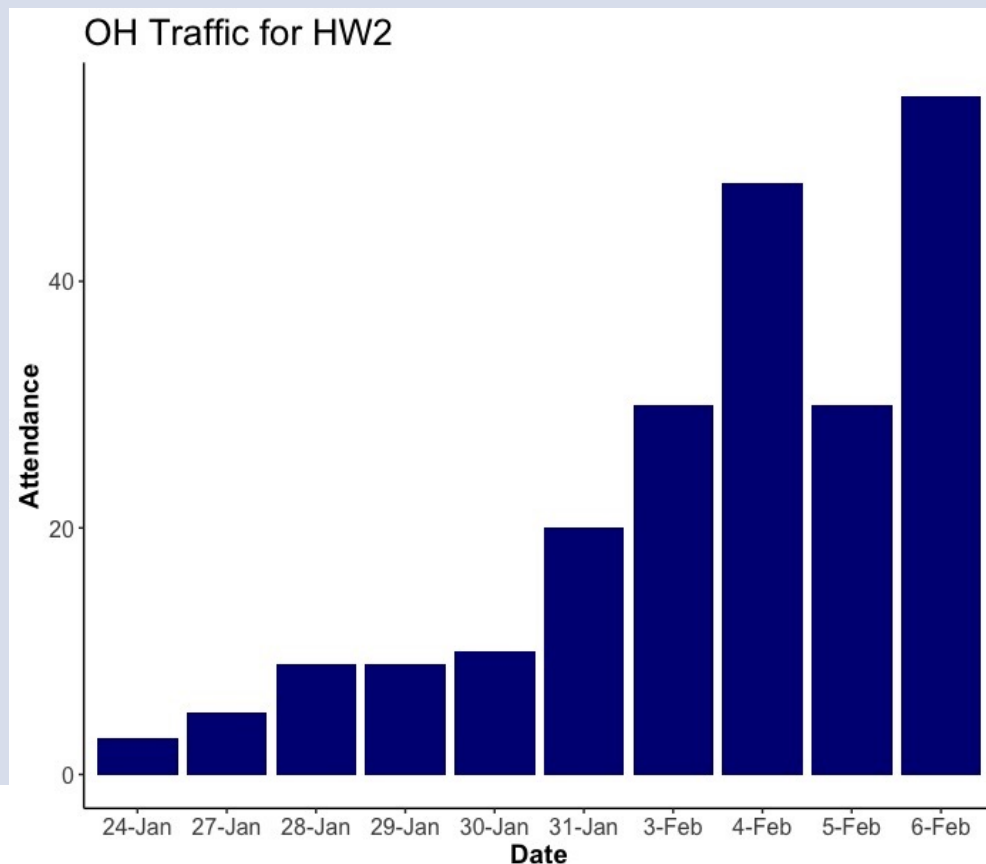
**A:** No!

In order to **prove** that gradient descent converges to a local minimum of a function, we need to **assume** gamma is properly defined.

# Q&A

**Q:** How can I get more one-on-one interaction with the course staff?

**A:** Attend office hours as soon after the homework release as possible!



# Q&A

**Q:** Can I email, tweeter, instasnap, or facetok my favorite TA directly about the course?

**A:** No. All course communication should be directed through one of the following channels:

- Piazza (public post)
- Piazza (private instructor post)
- Email to EAs [eas-10-601@cs.cmu.edu](mailto:eas-10-601@cs.cmu.edu)
- Email to Matt (delays likely)
- In-person communication at OHs

# Q&A

**Q:** I just asked a question in OH and now my TA is crying quietly -- what did I do wrong?

**A:** You've just committed the worst of crimes: asking a question that was directly answered in a recitation.

The TA you asked spent hours carefully writing careful recitation notes and solutions, practicing their recitation, responding to criticism / changes from me, etc.

To increase OH efficiency, please review the HW recitation before asking HW questions in OHs.

# Reminders

- **Practice Problems 1**
  - released on course website
- **Exam 1: Thu, Feb. 16**
  - Time: 6:30 – 8:30pm
  - Location: Your room/seat assignment will be announced on Piazza

# **EXAM 1 LOGISTICS**

# Exam 1

- **Time / Location**
  - **Time: Thu, Feb 16, at 6:30pm - 8:30pm**
  - **Location & Seats:** You have all been split across multiple rooms. Everyone has an assigned seat in one of these room.
  - Please watch Piazza carefully for announcements.
- **Logistics**
  - Covered material: Lecture 1 – Lecture 7
  - Format of questions:
    - Multiple choice
    - True / False (with justification)
    - Derivations
    - Short answers
    - Interpreting figures
    - Implementing algorithms on paper
  - No electronic devices
  - You are allowed to **bring** one 8½ x 11 sheet of notes (front and back)



# Exam 1

- **How to Prepare**

- Attend the midterm review lecture (right now!)
- Review exam practice problems
- Review this year's homework problems
- Consider whether you have achieved the “learning objectives” for each lecture / section
- Write your one-page cheat sheet (back and front)

# Exam 1

- **Advice (for during the exam)**
  - Solve the easy problems first (e.g. multiple choice before derivations)
    - if a problem seems extremely complicated you're likely missing something
  - Don't leave any answer blank!
  - If you make an assumption, write it down
  - If you look at a question and don't know the answer:
    - we probably haven't told you the answer
    - but we've told you enough to work it out
    - imagine arguing for some answer and see if you like it

# Topics for Exam 1

- Foundations
  - Probability, Linear Algebra, Geometry, Calculus
  - Optimization
- Important Concepts
  - Overfitting
  - Experimental Design
- Classification
  - Decision Tree
  - KNN
  - Perceptron
- Regression
  - KNN Regression
  - Decision Tree Regression
  - Linear Regression

# **SAMPLE QUESTIONS**

# Sample Questions

## 5.2 Constructing decision trees

Consider the problem of predicting whether the university will be closed on a particular day. We will assume that the factors which decide this are whether there is a snowstorm, whether it is a weekend or an official holiday. Suppose we have the training examples described in the Table 5.2.

Snowstorm	Holiday	Weekend	Closed
T	T	F	F
T	T	F	T
F	T	F	F
T	T	F	F
F	F	F	F
F	F	F	T
T	F	F	T
F	F	F	T

Table 1: Training examples for decision tree

Q1

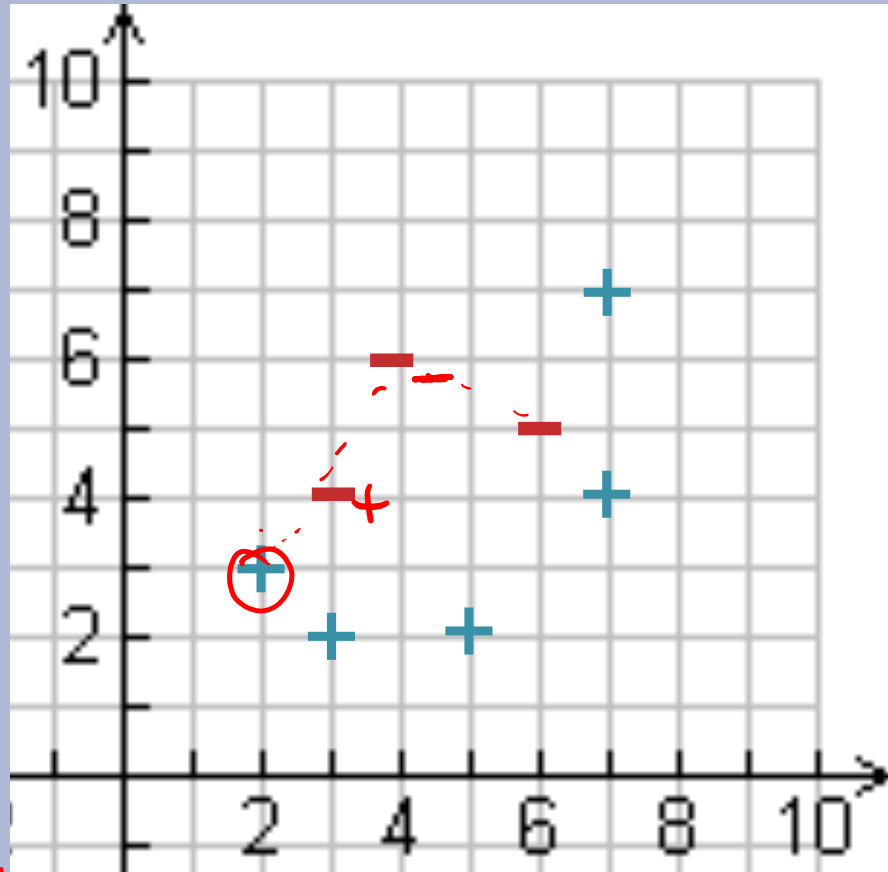
- [2 points] What would be the effect of the Weekend attribute on the decision tree if it were made the root? Explain in terms of ~~information gain~~. *→ mutual information*
- [8 points] If we cannot make Weekend the root node, which attribute should be made the root node of the decision tree? Explain your reasoning and show your calculations. (You may use  $\log_2 0.75 = -0.4$  and  $\log_2 0.25 = -2$ )



# Sample Questions

## 4 K-NN [12 pts]

Now we will apply K-Nearest Neighbors using Euclidean distance to a binary classification task. We assign the class of the test point to be the class of the majority of the  $k$  nearest neighbors.



$$N = \# \text{ train} = 8$$

3. [2 pts] What is the N-fold cross-validation error for the dataset shown in Figure 5? Assume  $k=1$ .

# Sample Questions

Q2

## 4.1 True or False

Answer each of the following questions with **T** or **F** and provide a one line justification.

- (a) [2 pts.] Consider two datasets  $D^{(1)}$  and  $D^{(2)}$  where  $D^{(1)} = \{(x_1^{(1)}, y_1^{(1)}), \dots, (x_n^{(1)}, y_n^{(1)})\}$  and  $D^{(2)} = \{(x_1^{(2)}, y_1^{(2)}), \dots, (x_m^{(2)}, y_m^{(2)})\}$  such that  $x_i^{(1)} \in \mathbb{R}^{d_1}$ ,  $x_i^{(2)} \in \mathbb{R}^{d_2}$ . Suppose  $d_1 > d_2$  and  $n > m$ . Then the maximum number of mistakes a perceptron algorithm will make is higher on dataset  $D^{(1)}$  than on dataset  $D^{(2)}$ .

A = True

B = toxic

75%  
C = False

Q

# Sample Questions

## 3.1 Linear regression

Consider the dataset  $S$  plotted in Fig. 1 along with its associated regression line. For each of the altered data sets  $S^{\text{new}}$  plotted in Fig. 3, indicate which regression line (relative to the original one) in Fig. 2 corresponds to the regression line for the new data set. Write your answers in the table below.

Dataset	(a)	(b)	(c)	(d)	(e)
Regression line					

$S$

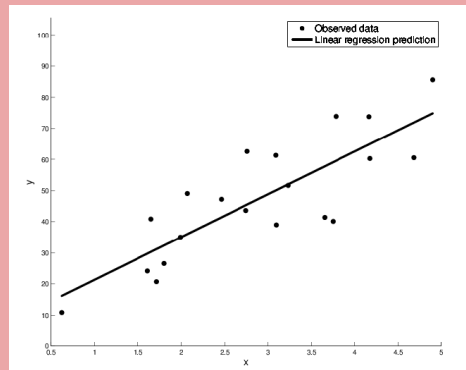


Figure 1: An observed data set and its associated regression line.

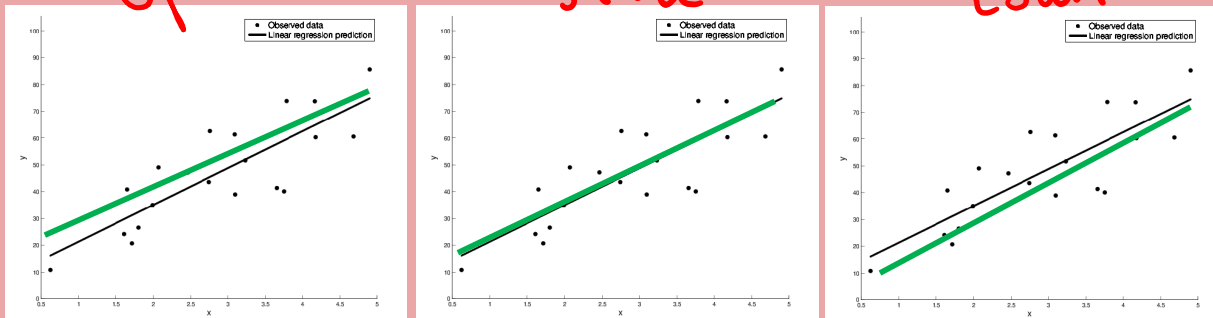
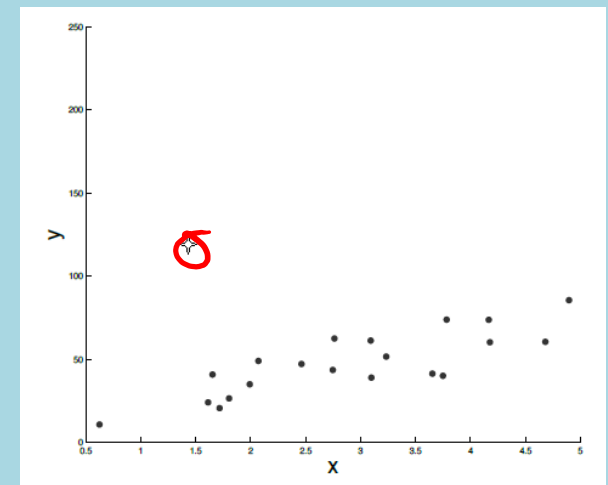


Figure 2: New regression lines for altered data sets  $S^{\text{new}}$ .

## Dataset

$S^{\text{new}}$



(a) Adding one outlier to the original data set.



# Sample Questions

## 3.1 Linear regression

Consider the dataset  $S$  plotted in Fig. 1 along with its associated regression line. For each of the altered data sets  $S^{\text{new}}$  plotted in Fig. 3, indicate which regression line (relative to the original one) in Fig. 2 corresponds to the regression line for the new data set. Write your answers in the table below.

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Regression line					

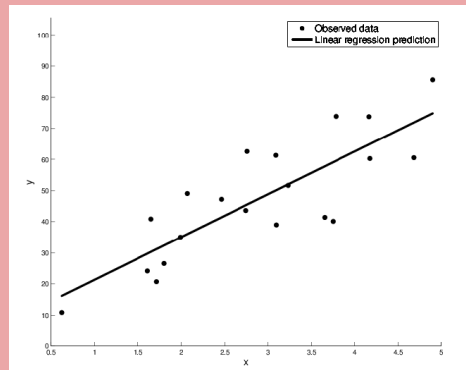


Figure 1: An observed data set and its associated regression line.

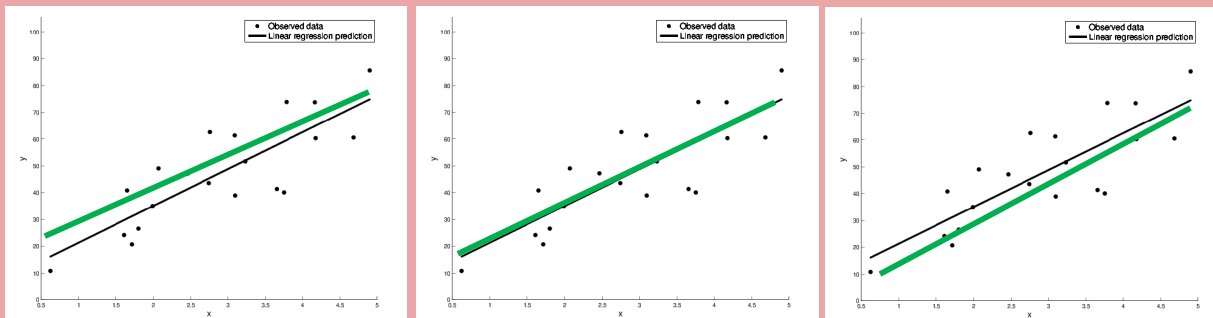
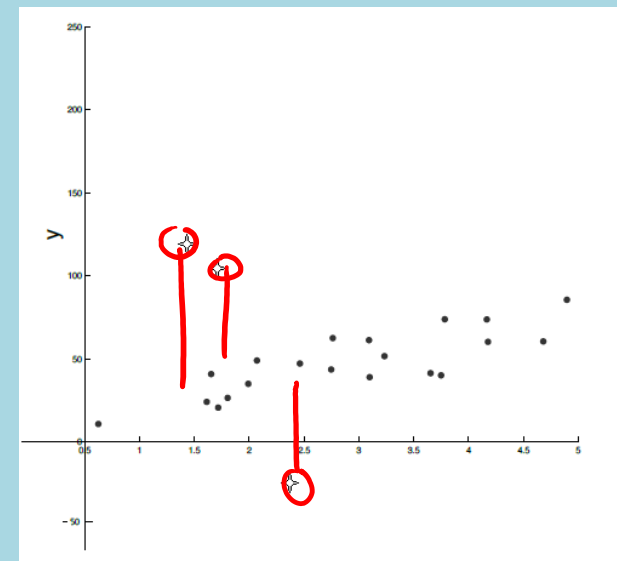


Figure 2: New regression lines for altered data sets  $S^{\text{new}}$ .

## Dataset



(c) Adding three outliers to the original data set. Two on one side and one on the other side.

# Sample Questions

## 3.1 Linear regression

Consider the dataset  $S$  plotted in Fig. 1 along with its associated regression line. For each of the altered data sets  $S^{\text{new}}$  plotted in Fig. 3, indicate which regression line (relative to the original one) in Fig. 2 corresponds to the regression line for the new data set. Write your answers in the table below.

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Regression line					

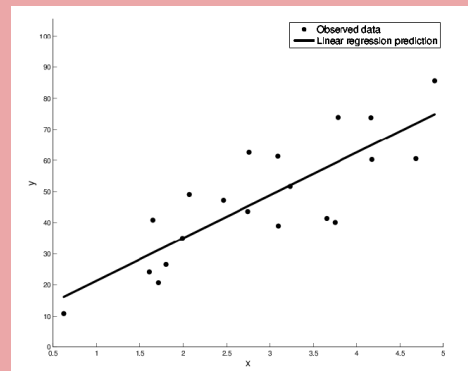


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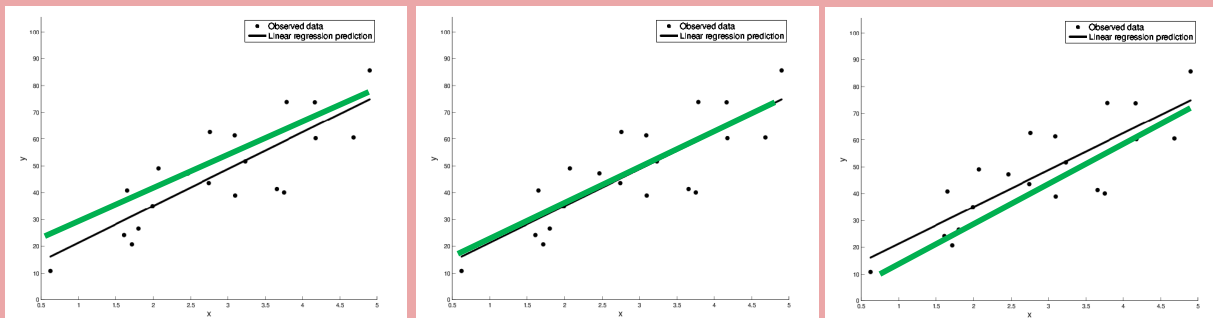
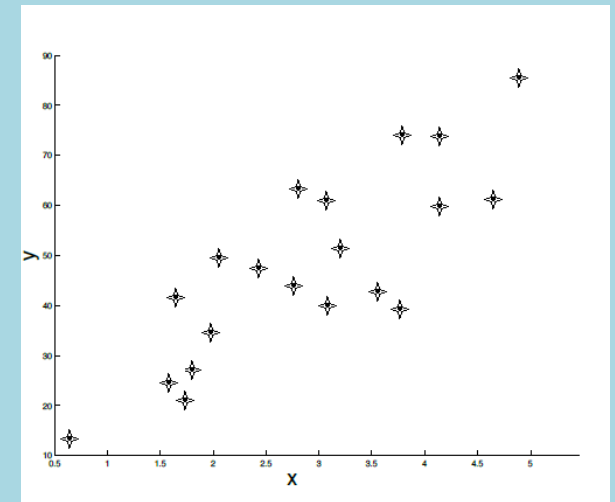


Figure 2: New regression lines for altered data sets  $S^{\text{new}}$ .

## Dataset



(d) Duplicating the original data set.

# Sample Questions

## 3.1 Linear regression

Consider the dataset  $S$  plotted in Fig. 1 along with its associated regression line. For each of the altered data sets  $S^{\text{new}}$  plotted in Fig. 3, indicate which regression line (relative to the original one) in Fig. 2 corresponds to the regression line for the new data set. Write your answers in the table below.

Dataset	(a)	(b)	(c)	(d)	(e)
Regression line					

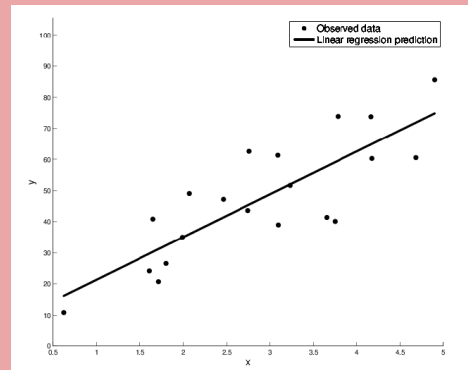


Figure 1: An observed data set and its associated regression line.

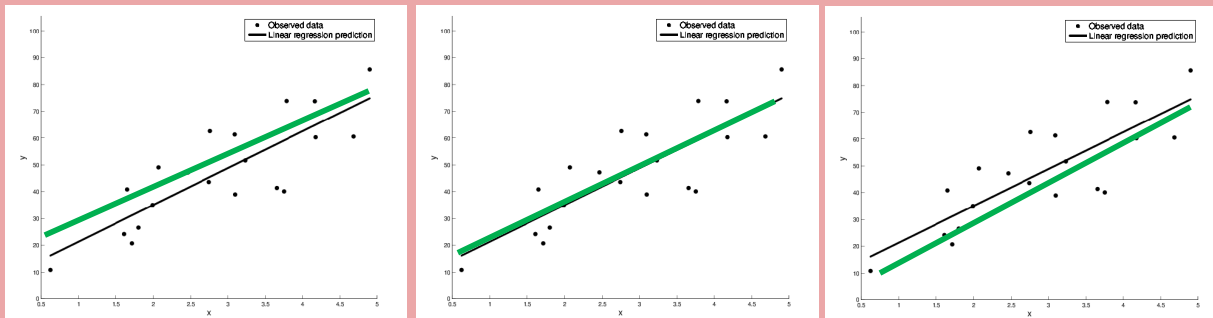
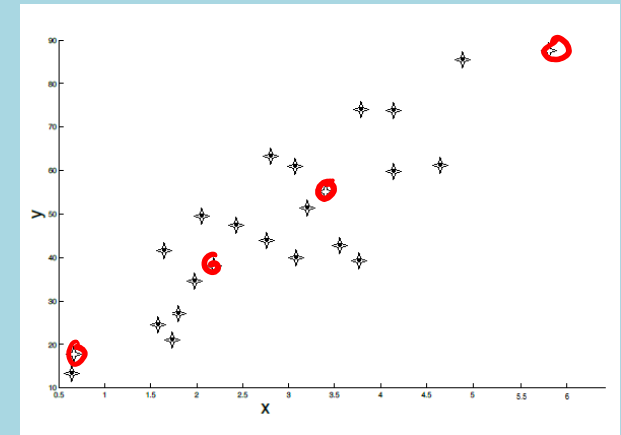


Figure 2: New regression lines for altered data sets  $S^{\text{new}}$ .

## Dataset



(e) Duplicating the original data set and adding four points that lie on the trajectory of the original regression line.

# Q&A

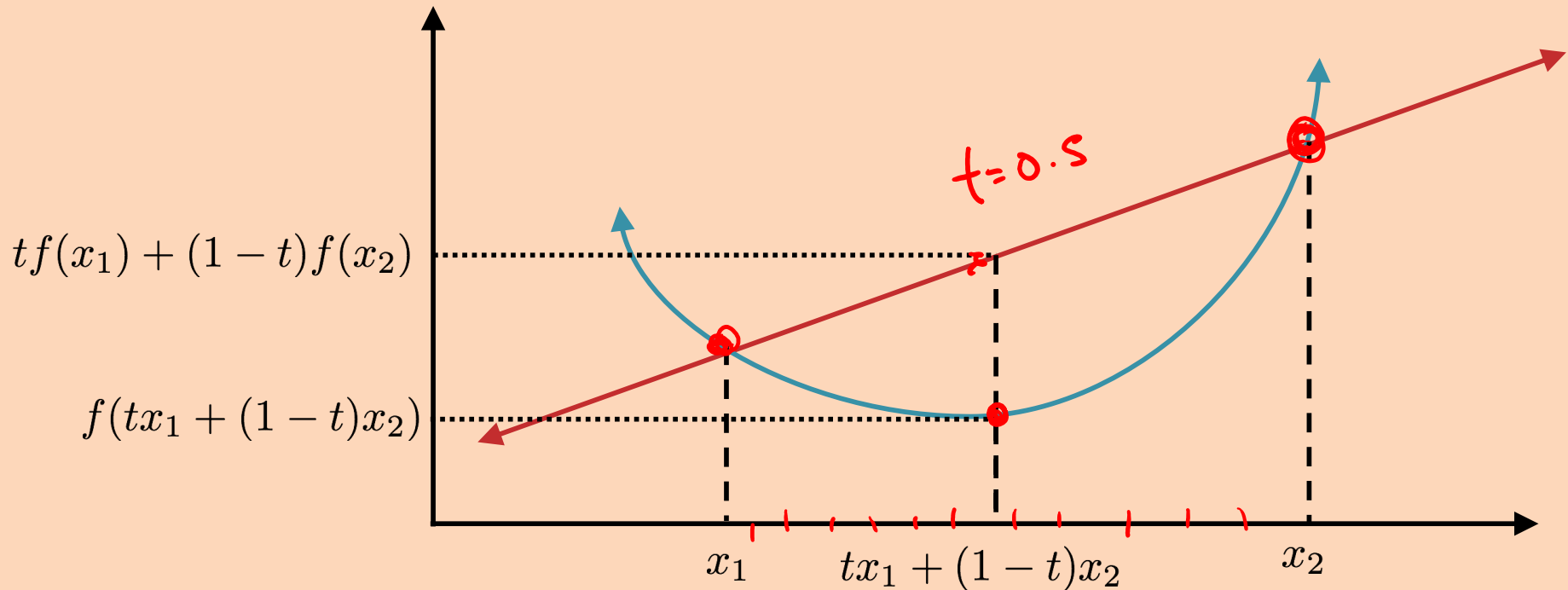
# CONVEXITY

# Convexity

Function  $f : \mathbb{R}^M \rightarrow \mathbb{R}$  is **convex**

if  $\forall \mathbf{x}_1 \in \mathbb{R}^M, \mathbf{x}_2 \in \mathbb{R}^M, 0 \leq t \leq 1$ :

$$\underline{f(t\mathbf{x}_1 + (1-t)\mathbf{x}_2)} \leq \underline{tf(\mathbf{x}_1) + (1-t)f(\mathbf{x}_2)}$$

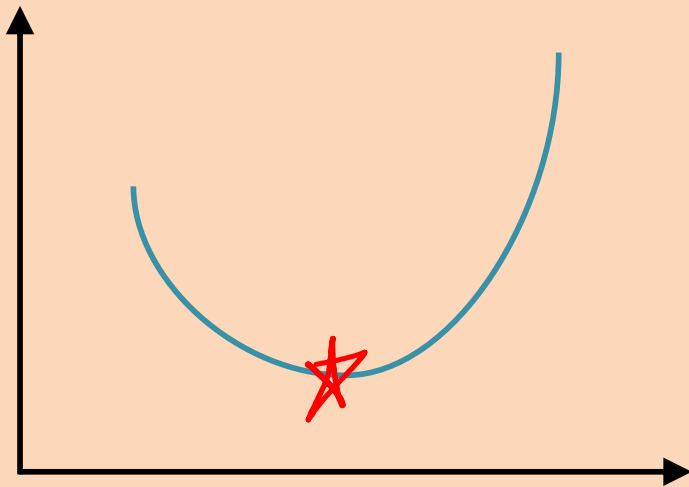


# Convexity

Suppose we have a function  $f(x) : \mathcal{X} \rightarrow \mathcal{Y}$ .

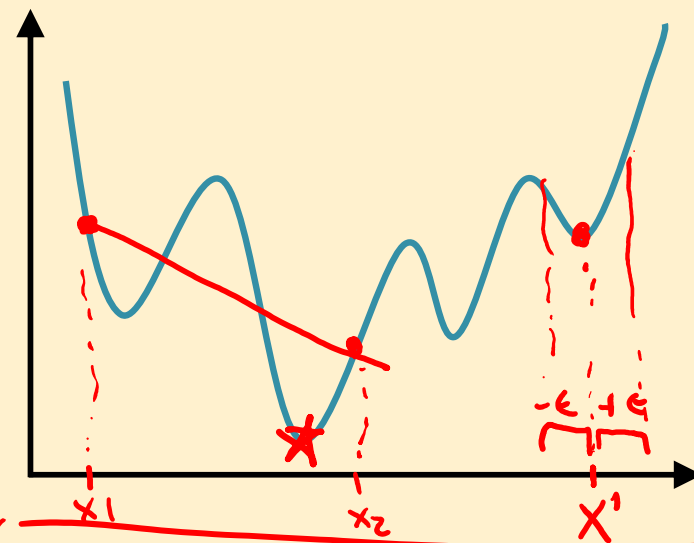
- The value  $x^*$  is a **global minimum** of  $f$  iff  $f(x^*) \leq f(x), \forall x \in \mathcal{X}$ .
- The value  $x^*$  is a **local minimum** of  $f$  iff  $\exists \epsilon$  s.t.  $f(x^*) \leq f(x), \forall x \in [x^* - \epsilon, x^* + \epsilon]$ .

## Convex Function



- Each **local minimum** is a **global minimum**

## Nonconvex Function

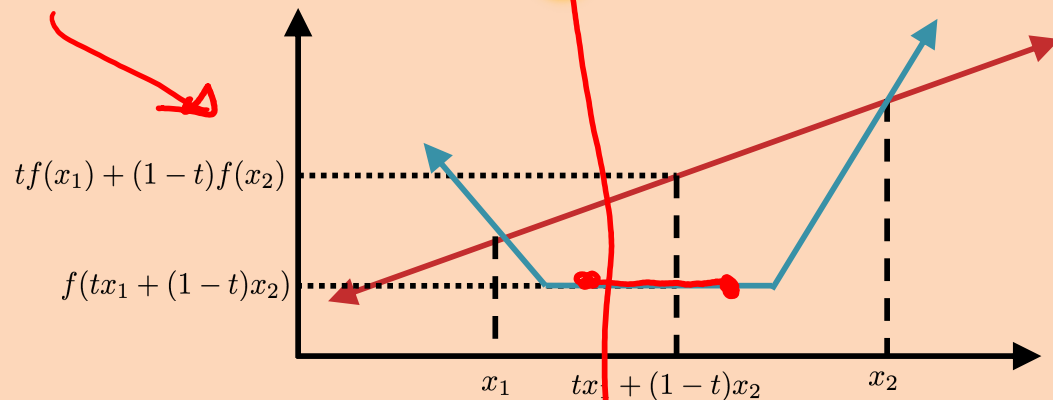


- A nonconvex function is **not convex**
- Each **local minimum** is **not necessarily a global minimum**

# Convexity

Function  $f : \mathbb{R}^M \rightarrow \mathbb{R}$  is **convex**  
if  $\forall \mathbf{x}_1 \in \mathbb{R}^M, \mathbf{x}_2 \in \mathbb{R}^M, 0 \leq t \leq 1$ :

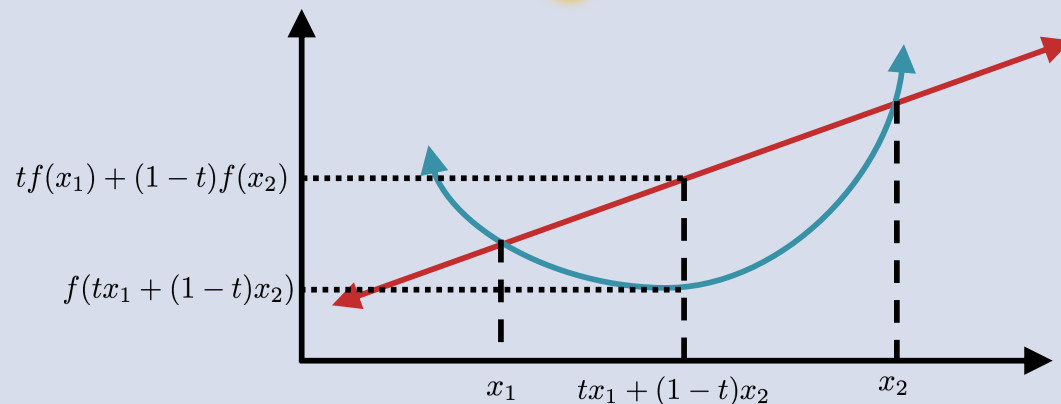
$$f(t\mathbf{x}_1 + (1-t)\mathbf{x}_2) \leq tf(\mathbf{x}_1) + (1-t)f(\mathbf{x}_2)$$



Each **local** minimum of a **convex** function is also a **global** minimum.

Function  $f : \mathbb{R}^M \rightarrow \mathbb{R}$  is **strictly convex**  
if  $\forall \mathbf{x}_1 \in \mathbb{R}^M, \mathbf{x}_2 \in \mathbb{R}^M, 0 \leq t \leq 1$ :

$$f(t\mathbf{x}_1 + (1-t)\mathbf{x}_2) < tf(\mathbf{x}_1) + (1-t)f(\mathbf{x}_2)$$



A **strictly convex** function has a **unique global** minimum.



# **CONVEXITY AND LINEAR REGRESSION**

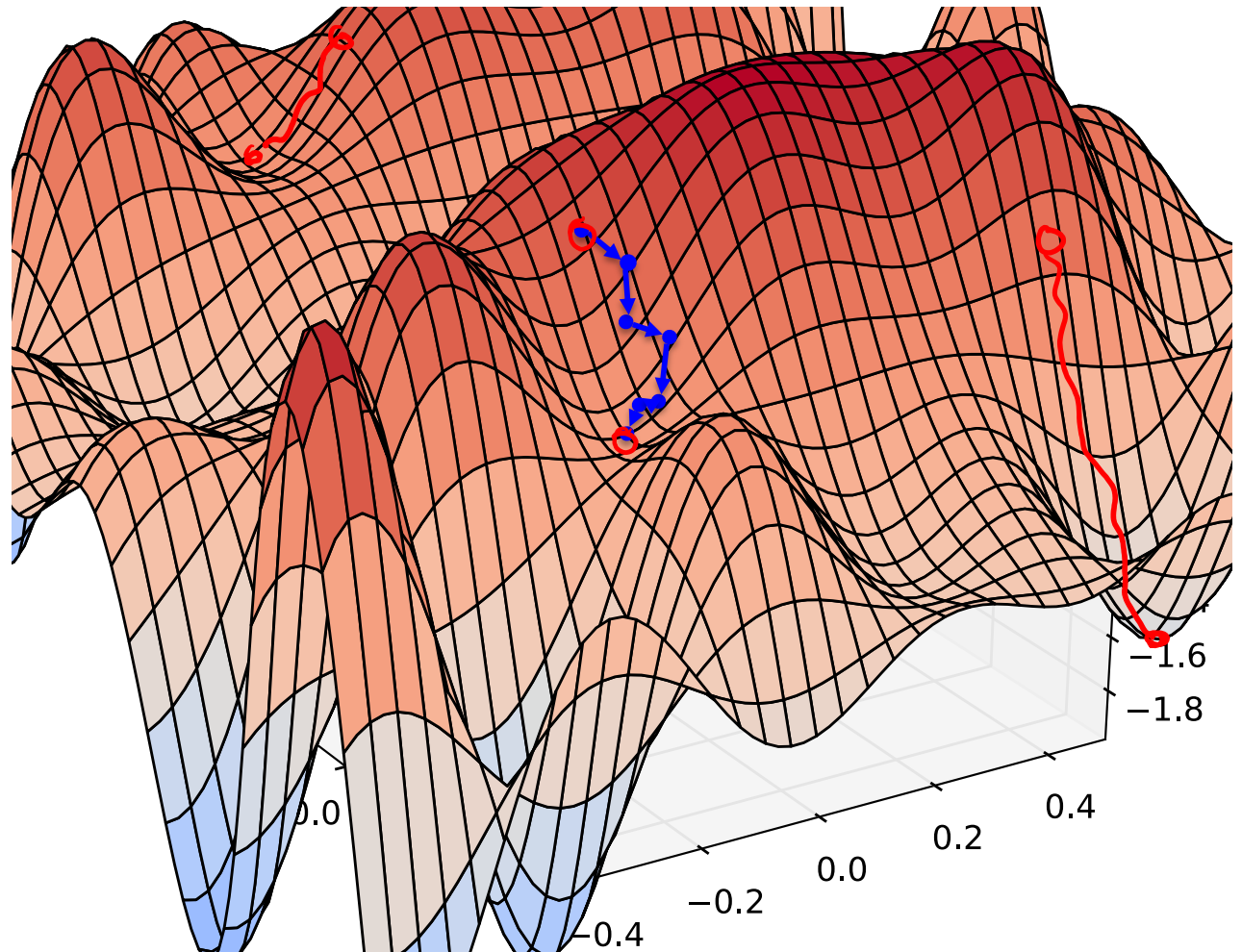
# Convexity and Linear Regression

The **Mean Squared Error** function, which we minimize for learning the parameters of Linear Regression, **is convex!**

... but in the general case it is **not strictly convex.**

# Gradient Descent & Convexity

- Gradient descent is a **local optimization algorithm**
- If the function is **nonconvex**, it will find a local minimum, not necessarily a global minimum
- If the function is **convex**, it will find a global minimum



# Regression Loss Functions

Q3

## In-Class Exercise:

Which of the following could be used as loss functions for training a linear regression model?

Select all that apply.

~~A.  $\ell(\hat{y}, y) = \|\hat{y} - y\|_2$~~  toxic

B.  $\ell(\hat{y}, y) = |\hat{y} - y|$  (MAE)

C.  $\ell(\hat{y}, y) = \frac{1}{2}(\hat{y} - y)^2$  (MSE) 93%  $\hat{y}^{(i)} = \theta^T x^{(i)}$

D.  $\ell(\hat{y}, y) = \frac{1}{4}(\hat{y} - y)^4$

E.  $\ell(\hat{y}, y) = \begin{cases} \frac{1}{2}(\hat{y} - y)^2 & \text{if } |\hat{y} - y| \leq \delta \\ \delta|\hat{y} - y| - \frac{1}{2}\delta^2 & \text{otherwise} \end{cases}$

F.  $\ell(\hat{y}, y) = \log(\cosh(\hat{y} - y))$

G.  $\ell(\hat{y}, y) = \sin(\hat{y} - y)$

$J(\vec{\theta}) = \frac{1}{N} \sum_{i=1}^N \ell(y^{(i)}, \hat{y}^{(i)})$

# **OPTIMIZATION METHOD #2: CLOSED FORM SOLUTION**

# Calculus and Optimization

## In-Class Exercise

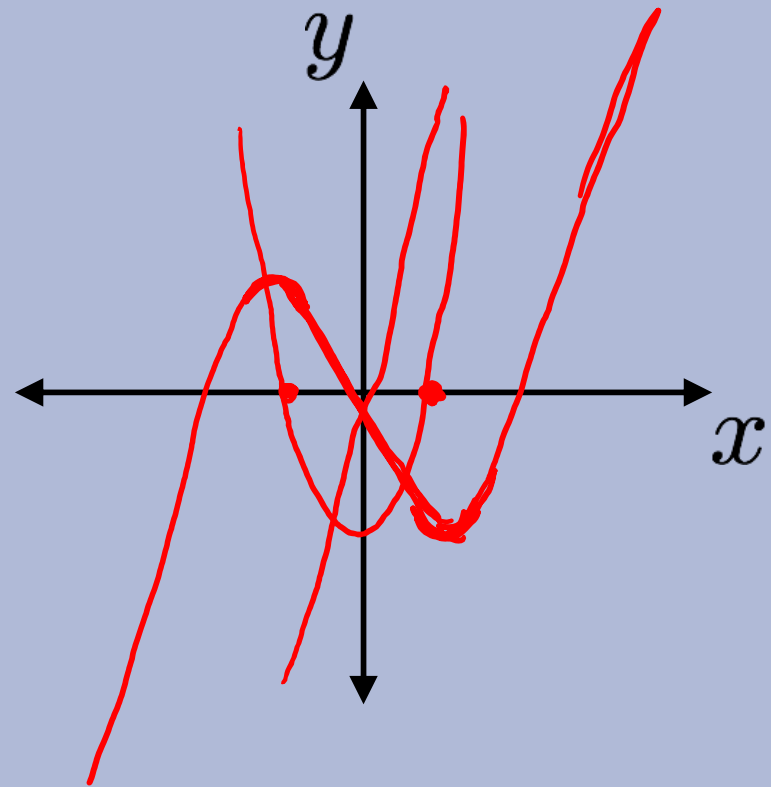
Plot three functions:

1.  $f(x) = x^3 - x$

2.  $f'(x) = \frac{\partial y}{\partial x} = 3x^2 - 1$

3.  $f''(x) = \frac{\partial^2 y}{\partial x^2} = 6x$

## Answer Here:



# Optimization: Closed form solutions

## *Chalkboard*

- Zero Derivatives
- Example: 1-D function
- Example: higher dimensions

# **CLOSED FORM SOLUTION FOR LINEAR REGRESSION**



# Linear Regression as Function Approximation

$$\mathcal{D} = \{\mathbf{x}^{(i)}, y^{(i)}\}_{i=1}^N$$

where  $\mathbf{x} \in \mathbb{R}^M$  and  $y \in \mathbb{R}$

1. Assume  $\mathcal{D}$  generated as:

$$\mathbf{x}^{(i)} \sim p^*(\cdot)$$

$$y^{(i)} = h^*(\mathbf{x}^{(i)})$$

2. Choose hypothesis space,  $\mathcal{H}$ :

*all linear functions in  $M$ -dimensional space*

$$\mathcal{H} = \{h_{\boldsymbol{\theta}} : h_{\boldsymbol{\theta}}(\mathbf{x}) = \boldsymbol{\theta}^T \mathbf{x}, \boldsymbol{\theta} \in \mathbb{R}^M\}$$

3. Choose an objective function:

*mean squared error (MSE)*

$$\begin{aligned} J(\boldsymbol{\theta}) &= \frac{1}{N} \sum_{i=1}^N e_i^2 \\ &= \frac{1}{N} \sum_{i=1}^N \left( y^{(i)} - h_{\boldsymbol{\theta}}(\mathbf{x}^{(i)}) \right)^2 \\ &= \frac{1}{N} \sum_{i=1}^N \left( y^{(i)} - \boldsymbol{\theta}^T \mathbf{x}^{(i)} \right)^2 \end{aligned}$$

4. Solve the unconstrained optimization problem via favorite method:

- gradient descent
- closed form
- stochastic gradient descent
- ...

$$\hat{\boldsymbol{\theta}} = \underset{\boldsymbol{\theta}}{\operatorname{argmin}} J(\boldsymbol{\theta})$$

5. Test time: given a new  $\mathbf{x}$ , make prediction  $\hat{y}$

$$\hat{y} = h_{\hat{\boldsymbol{\theta}}}(\mathbf{x}) = \hat{\boldsymbol{\theta}}^T \mathbf{x}$$

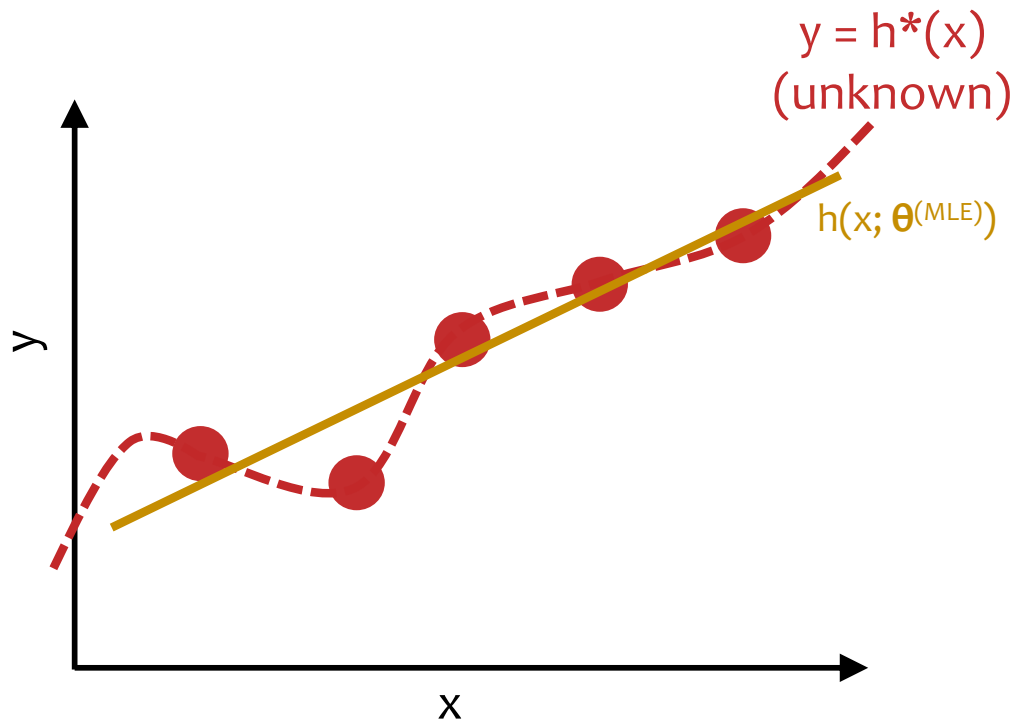
# Linear Regression: Closed Form

## Optimization Method #2: Closed Form

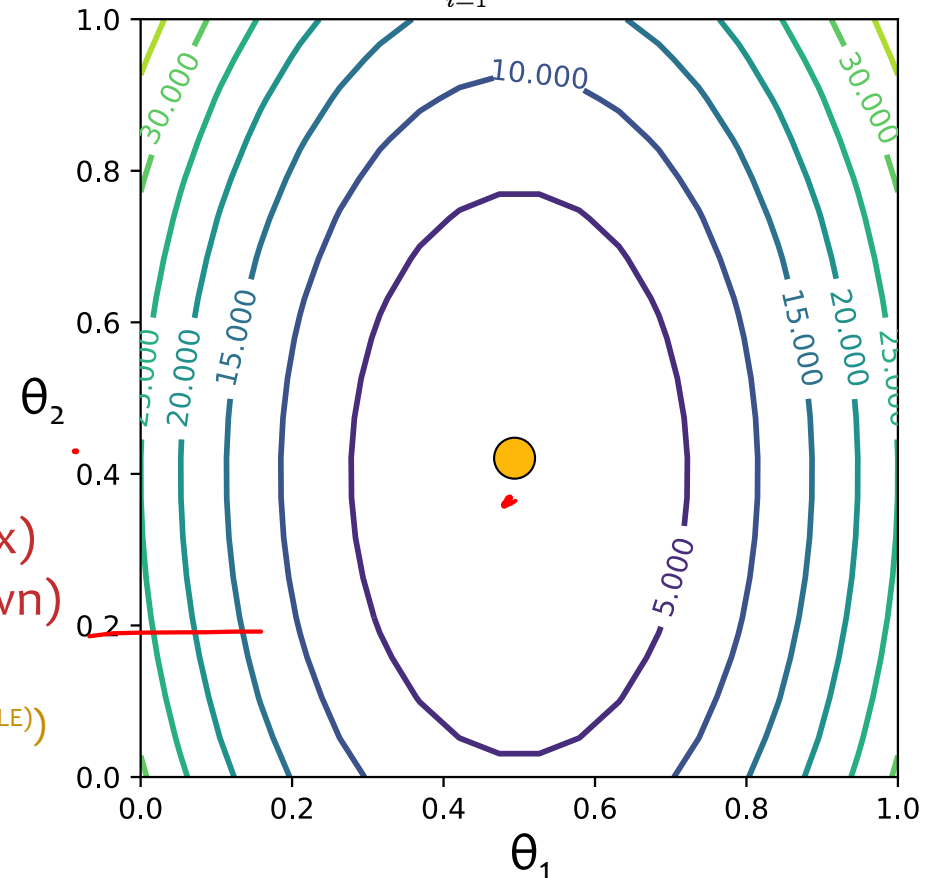
1. Evaluate

$$\theta^{\text{MLE}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

2. Return  $\theta^{\text{MLE}}$



$$J(\theta) = J(\theta_1, \theta_2) = \frac{1}{N} \sum_{i=1}^N (y^{(i)} - \theta^T \mathbf{x}^{(i)})^2$$



t	$\theta_1$	$\theta_2$	$J(\theta_1, \theta_2)$
MLE	0.59	0.43	0.2

# Background: Linear Algebra

- **Definition:** the **identity matrix**  $I$  is a diagonal matrix with 1's on the diagonal and 0's everywhere else.

Example of ~~3x3~~ identity matrix:

$$I = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$IA = A$$

- **Definition:** the **inverse** of a matrix  $A$  is  $A^{-1}$  when
$$A^{-1}A = AA^{-1} = I$$
  - The inverse of a matrix does not always exist.
- There is no division of matrices, but we can...
  - pre-multiply by an inverse:
$$AC = B$$
$$\Rightarrow A^{-1}(AC) = A^{-1}B$$
$$\Rightarrow C = A^{-1}B$$
  - post-multiply by an inverse
$$AC = B$$
$$\Rightarrow (AC)C^{-1} = BC^{-1}$$
$$\Rightarrow A = BC^{-1}$$

# Optimization for Linear Regression

## *Chalkboard*

- Closed-form (Normal Equations)

# COMPUTATIONAL COMPLEXITY

# Computational Complexity of OLS

To solve the Ordinary Least Squares problem we compute:

$$\hat{\theta} = \underset{\theta}{\operatorname{argmin}} = \frac{1}{N} \sum_{i=1}^N \frac{1}{2} (y^{(i)} - (\theta^T \mathbf{x}^{(i)}))^2$$

$$= (\mathbf{X}^T \mathbf{X})^{-1} (\mathbf{X}^T \mathbf{Y})$$

The resulting shape of the matrices:

$$\underbrace{\left( \begin{array}{cc} \mathbf{X}^T & \mathbf{X} \\ \hline M \times N & N \times M \end{array} \right)^{-1}}_{M \times M} \underbrace{\left( \begin{array}{cc} \mathbf{X}^T & \mathbf{Y} \\ \hline M \times N & N \times 1 \end{array} \right)}_{M \times 1}$$

**Background: Matrix Multiplication** Given matrices **A** and **B**

- If **A** is  $q \times r$  and **B** is  $r \times s$ , computing **AB** takes  $O(qrs)$
- If **A** and **B** are  $q \times q$ , computing **AB** takes  $O(q^{2.373})$
- If **A** is  $q \times q$ , computing  $A^{-1}$  takes  $O(q^{2.373})$ .

## Computational Complexity of OLS:

$\mathbf{X}^T \mathbf{X}$	$O(M^2 N)$
$(\quad)^{-1}$	$O(M^{2.373})$
$\mathbf{X}^T \mathbf{Y}$	$O(MN)$
$(\quad)^{-1}(\quad)$	$O(M^2)$
total	$O(M^2 N + M^{2.373})$

Linear in # of examples, N  
Polynomial in # of features, M

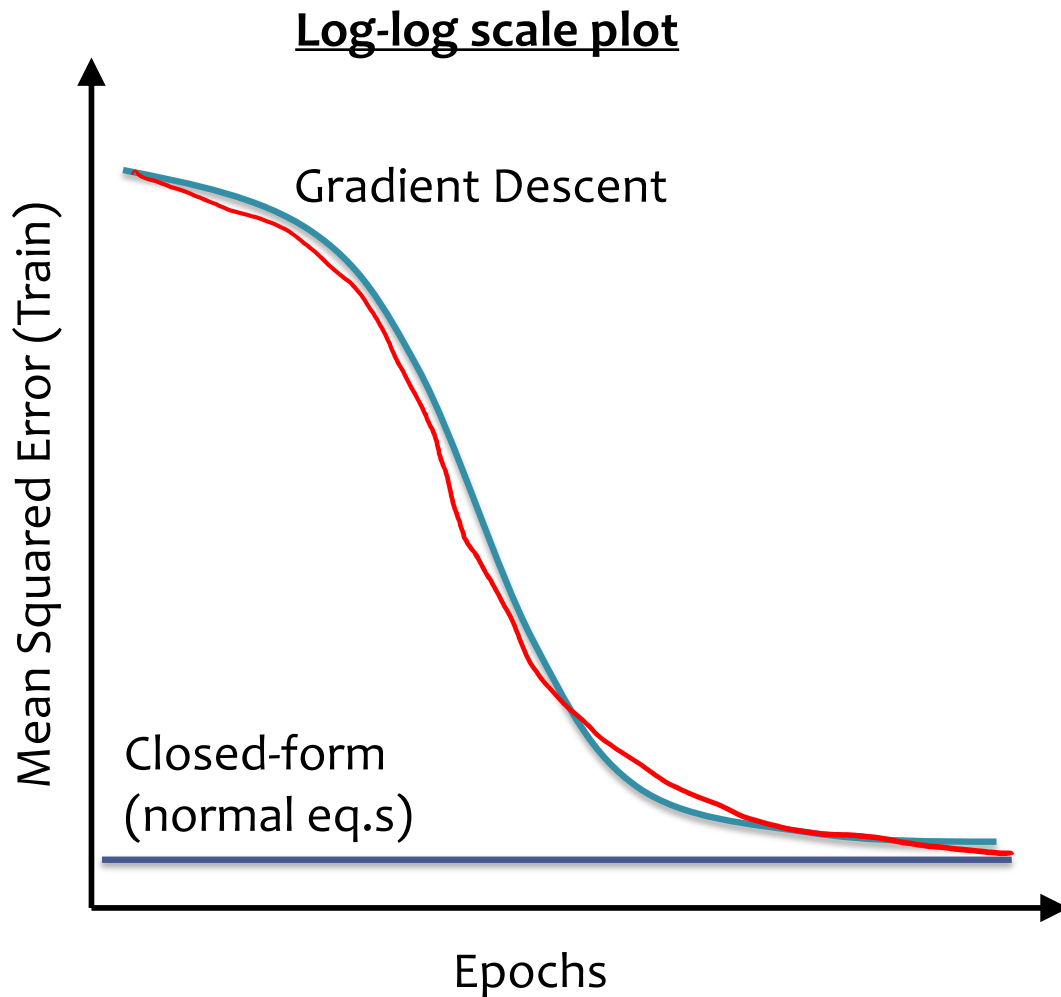


# Gradient Descent

Cases to consider gradient descent:

1. What if we **can not** find a closed-form solution?
2. What if we **can**, but it's inefficient to compute?
3. What if we **can**, but it's numerically unstable to compute?

# Empirical Convergence



- Def: an **epoch** is a single pass through the training data
- 1. For GD, only **one update** per epoch
- 2. For SGD,  **$N$  updates** per epoch  
 $N = (\# \text{ train examples})$

- SGD reduces MSE much more rapidly than GD
- For GD / SGD, training MSE is initially large due to uninformed initialization



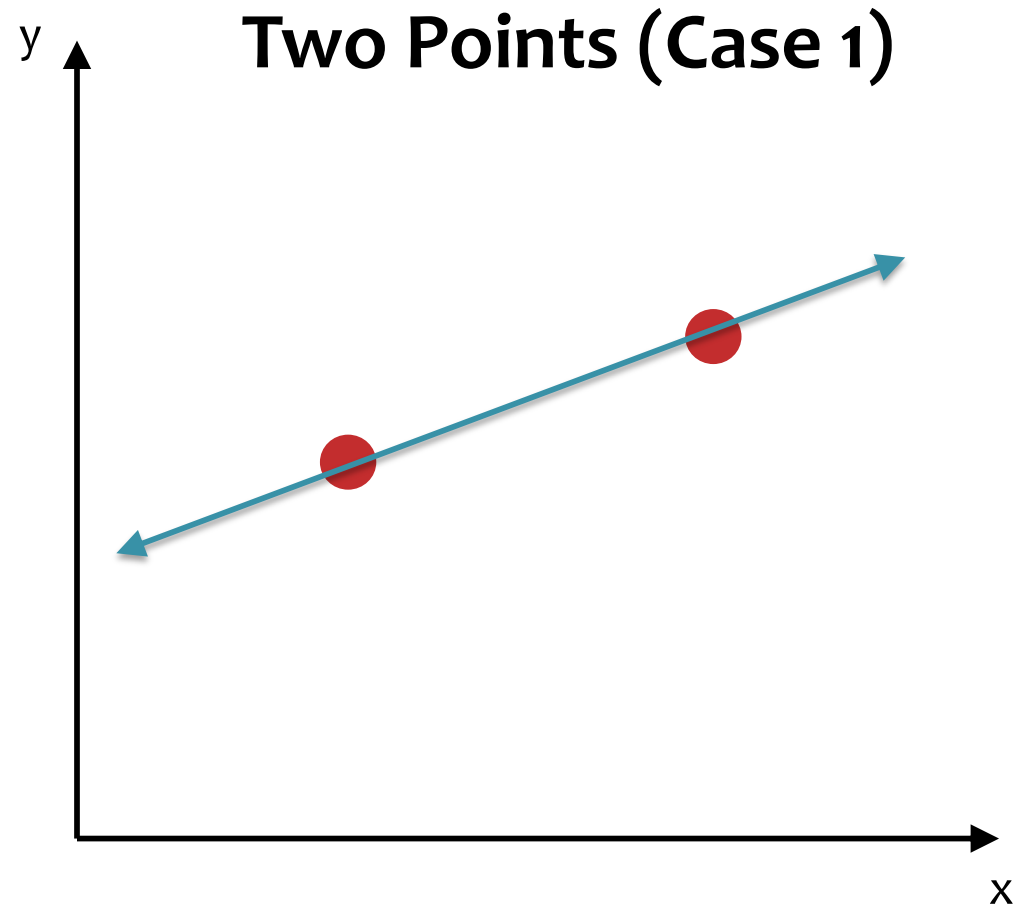
# **LINEAR REGRESSION: SOLUTION UNIQUENESS**

# Linear Regression: Uniqueness

## Question:

Consider a 1D linear regression model trained to minimize MSE.

How many solutions (i.e. sets of parameters  $w, b$ ) are there for the given dataset?

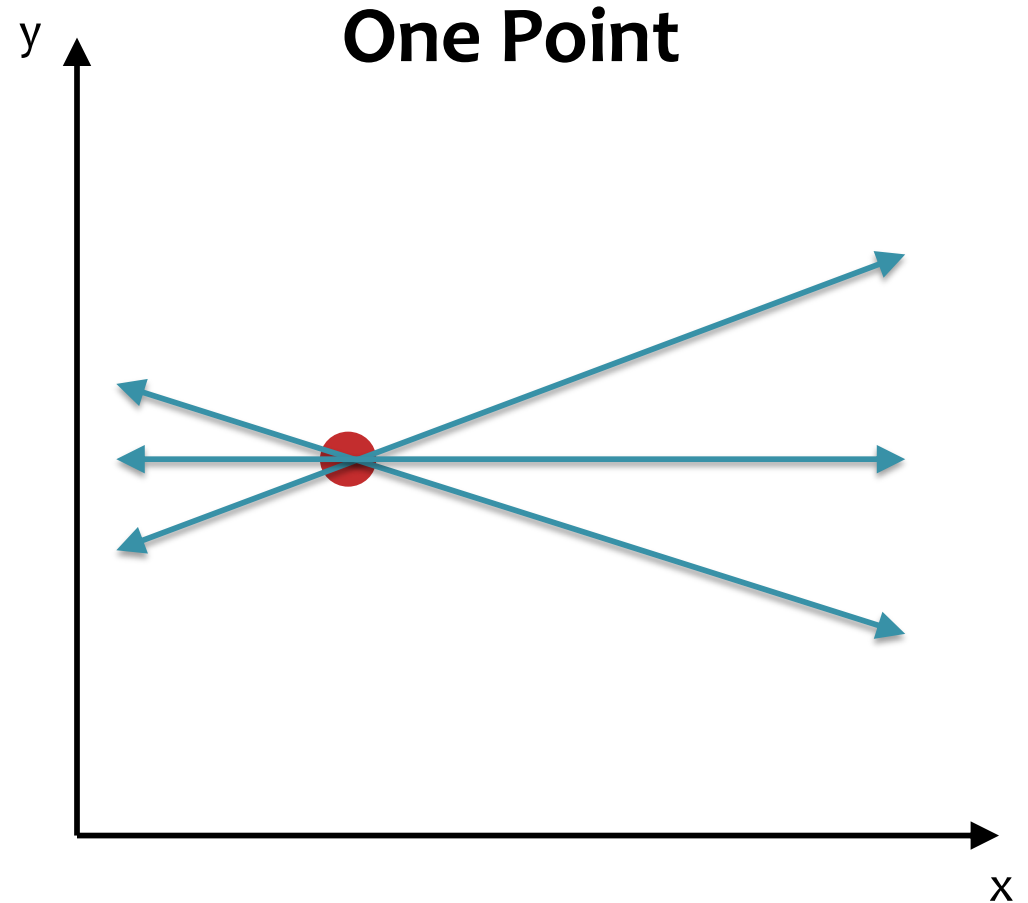


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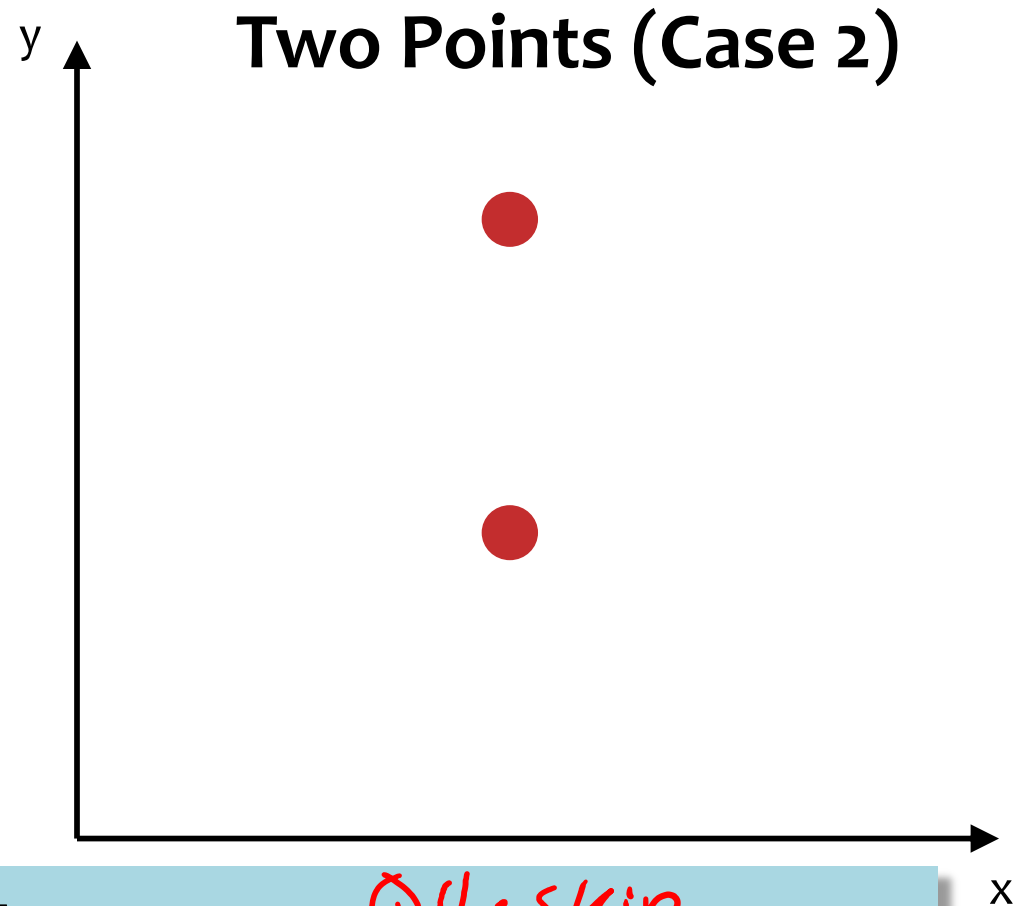


# Linear Regression: Uniqueness

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**Answer:** Q4: skip

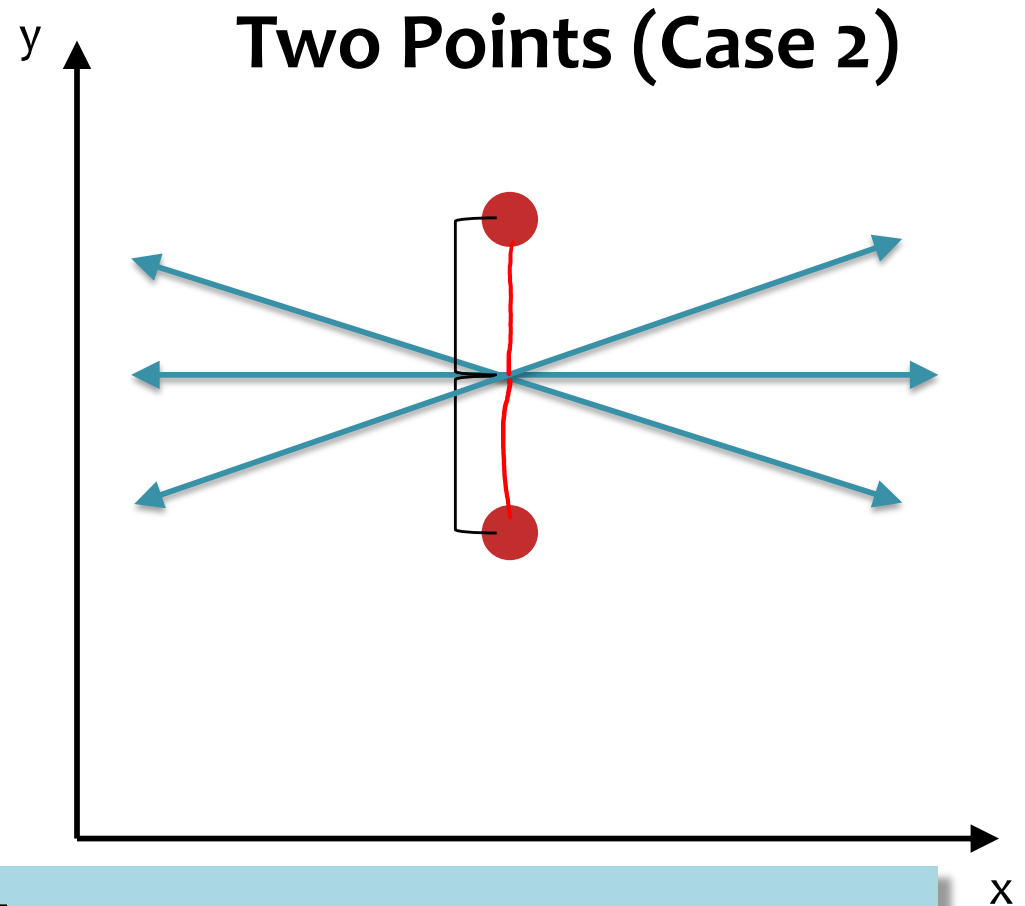
A: 0    B: 1    C: 2    D:  $+\infty$

# Linear Regression: Uniqueness

## Question:

Consider a 1D linear regression model trained to minimize MSE.

How many solutions (i.e. sets of parameters  $w, b$ ) are there for the given dataset?



## Answer:

A: 0

B: 1

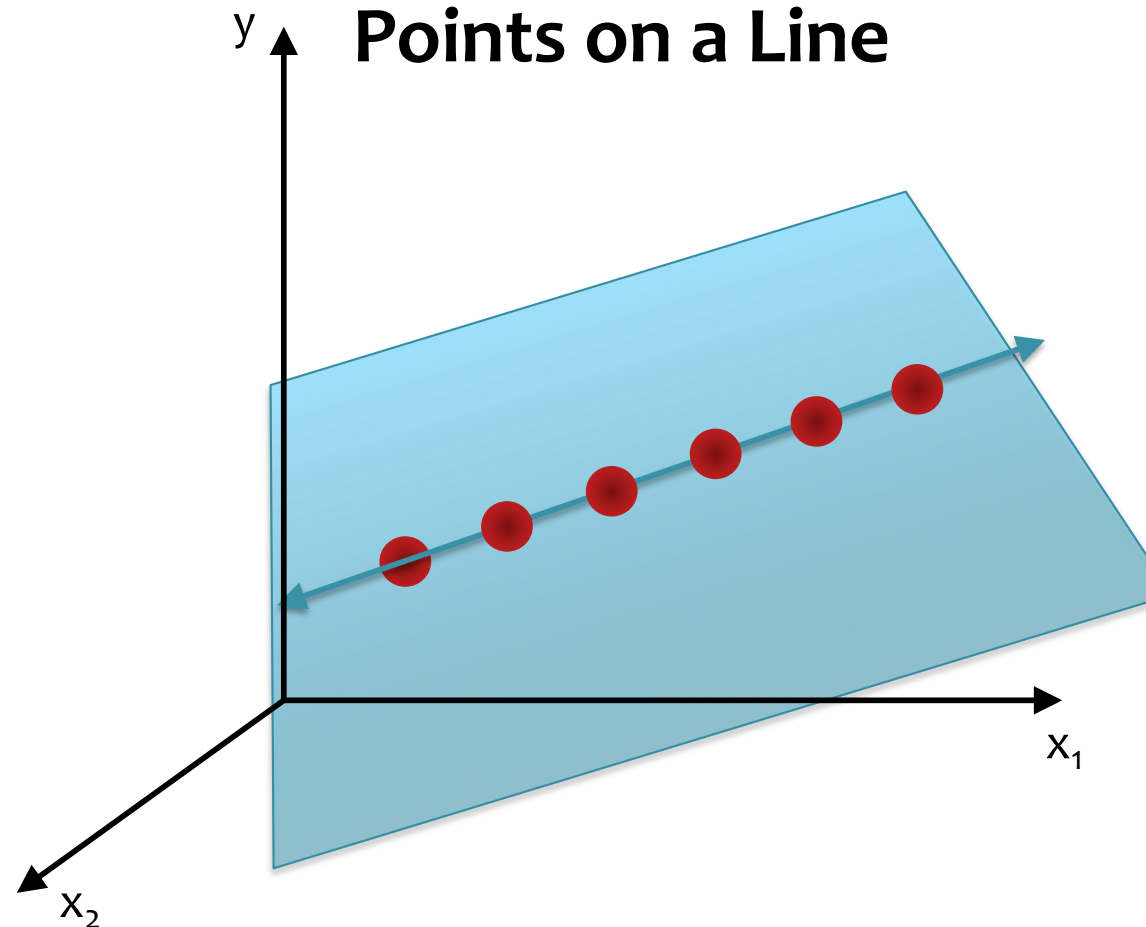
C: 2

D:  $+\infty$

# Linear Regression: Uniqueness

## Question:

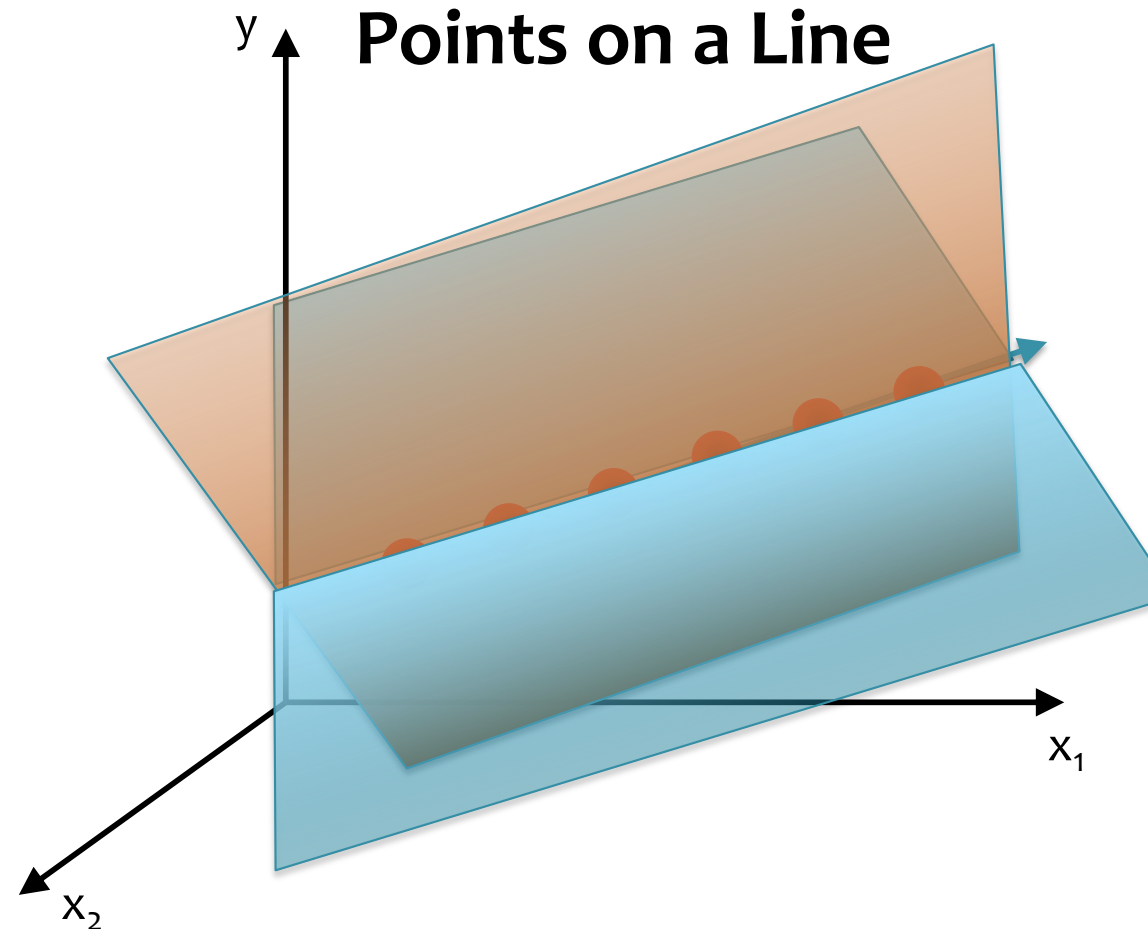
- Consider a **2D** linear regression model trained to minimize MSE
- How many solutions (i.e. sets of parameters  $w_1$ ,  $w_2$ ,  $b$ ) are there for the given dataset?



# Linear Regression: Uniqueness

## Question:

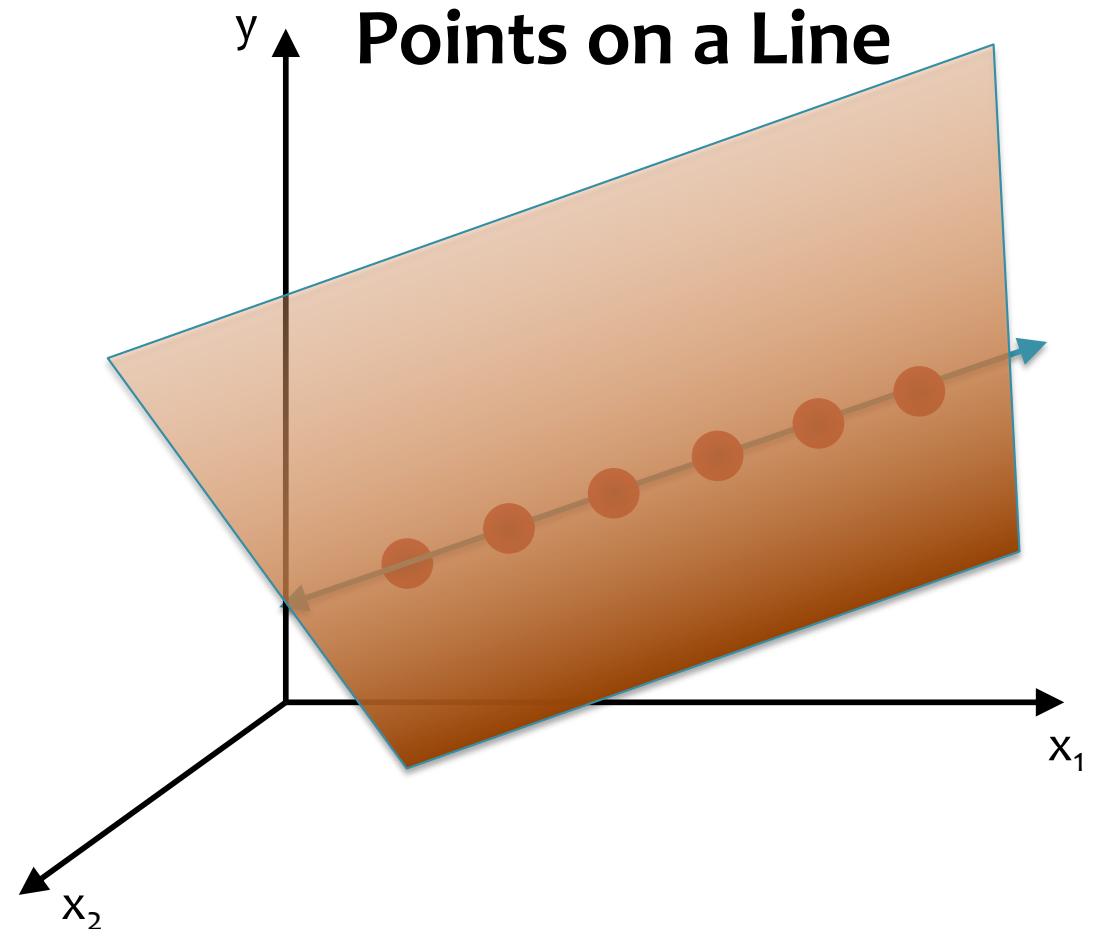
- Consider a **2D** linear regression model trained to minimize MSE
- How many solutions (i.e. sets of parameters  $w_1$ ,  $w_2$ ,  $b$ ) are there for the given dataset?



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# Linear Regression: Uniqueness

To solve the Ordinary Least Squares problem we compute:

$$\begin{aligned}\hat{\boldsymbol{\theta}} = \underset{\boldsymbol{\theta}}{\operatorname{argmin}} &= \frac{1}{N} \sum_{i=1}^N \frac{1}{2} (y^{(i)} - (\boldsymbol{\theta}^T \mathbf{x}^{(i)}))^2 \\ &= (\mathbf{X}^T \mathbf{X})^{-1} (\mathbf{X}^T \mathbf{Y})\end{aligned}$$

These geometric intuitions align with the linear algebraic intuitions we can derive from the normal equations.

1. If  $(\mathbf{X}^T \mathbf{X})$  is **invertible**, then there is exactly one solution.
2. If  $(\mathbf{X}^T \mathbf{X})$  is **not invertible**, then there are either no solutions or infinitely many solutions.


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Invertability of  $(\mathbf{X}^T \mathbf{X})$  is equivalent to  $X$  being **full rank**. That is, there is **no feature that is a linear combination of the other features**.

# Solving Linear Regression

**Question:**

QS: skip

**True or False:** If Mean Squared Error (i.e.  $\frac{1}{N} \sum_{i=1}^N (y^{(i)} - h(\mathbf{x}^{(i)}))^2$ ) has a unique minimizer (i.e. argmin), then Mean Absolute Error (i.e.  $\frac{1}{N} \sum_{i=1}^N |y^{(i)} - h(\mathbf{x}^{(i)})|$ ) must also have a unique minimizer.

**Answer:**

# Linear Regression Objectives

*You should be able to...*

- Design k-NN Regression and Decision Tree Regression
- Implement learning for Linear Regression using three optimization techniques: (1) closed form, (2) gradient descent, (3) stochastic gradient descent
- Choose a Linear Regression optimization technique that is appropriate for a particular dataset by analyzing the tradeoff of computational complexity vs. convergence speed
- Identify situations where least squares regression has exactly one solution or infinitely many solutions