

# Section A

Monday, March 27, 2023 9:26 AM

## 3 Problems for an HMM

Evaluation:  $p(\vec{x}) = \sum_{\vec{y} \in \mathcal{Y}} p(\vec{x}, \vec{y})$

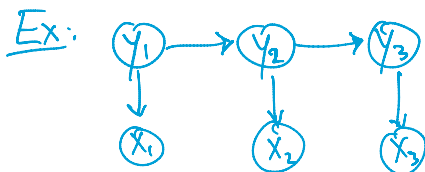
$$p(\vec{x}, \vec{y}) = p(y_1) \prod_{t=1}^T p(x_t | y_t) \prod_{t=1}^{T-1} p(y_{t+1} | y_t)$$

For  $|\vec{y}| = T$  and  $y_t \in \{1, \dots, K\}$   
there are  $K^T$  possible labels  $\vec{y}$   
 $|\mathcal{Y}| = K^T$

Viterbi Decoding:  $\hat{y} = \underset{\vec{y} \in \mathcal{Y}}{\text{argmax}} p(\vec{y} | \vec{x})$

Marginals:  $p(y_t = k | \vec{x}) = \sum_{\substack{\vec{y} \in \mathcal{Y} \\ \text{s.t. } y_t = k}} p(\vec{y} | \vec{x})$

$$\frac{p(\vec{x}, \vec{y})}{p(\vec{x})}$$



$y_t \in \{H, P, V\}$

$x_t \in \{C, N\}$

① Evaluation:  $p(x_1, x_2, x_3) = \sum_{y_1} \sum_{y_2} \sum_{y_3} p(\vec{x}, \vec{y})$

$$p(x_1, x_2, x_3, y_1, y_2, y_3) = p(y_1) p(y_2 | y_1) p(y_3 | y_2) p(x_1 | y_1) p(x_2 | y_2) p(x_3 | y_3)$$

② Viterbi Decoding:  $\hat{y} = \underset{y_1, y_2, y_3}{\text{argmax}} p(y_1, y_2, y_3 | x_1, x_2, x_3)$

③ Marginals:  $p(y_2 = k | x_1, x_2, x_3) = \sum_{y_1} \sum_{y_3} p(y_1, y_2, y_3 | x_1, x_2, x_3)$

## Public Service Announcement

BEFORE

implement the  
F-B Also

TTTCT

implement the

# FIRST

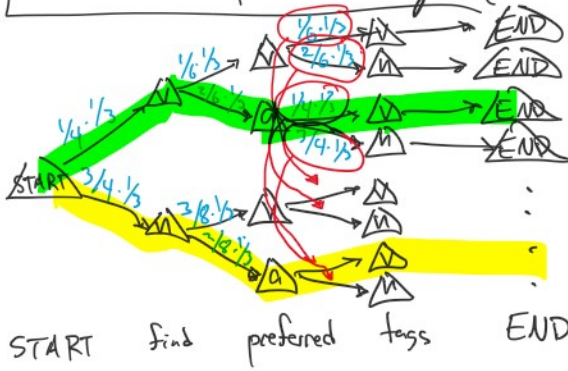
Implement the  
Brute Force also

## Brute Force for Evaluation

```
def eval(x):
    p-x = 0
    for y in all-y(x):
        p-x += joint(x, y)
    return p-x
```

Terrible Idea  
Good Idea

## F-B Search Space (aka $\mathcal{Y}_{\bar{x}}$ )



Why? 1st Order Markov Assumption

Key Idea: the current tag holds all the information for the scoring of the next tag (Markov Assumption)



## Given: Trained Model Parameters A and B

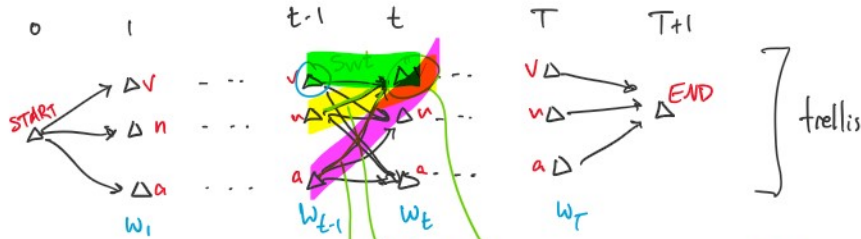
$y_{t-1}$	$y_t$	$p(y_t   y_{t-1})$
v	v	1/6
v	a	2/6
v	n	2/6
v	END	1/6
n	v	3/8
n	a	2/8
n	END	3/8
a	v	1/4
a	n	3/4
START	v	1/4
START	n	3/4

(A)

$y_t$	$x_t$	$p(x_t   y_t)$
v	find	1/3
v	preferred	1/3
v	tags	1/3
n	find	1/3
n	preferred	1/3
n	tags	1/3
...	...	...

## F-B Algo

# F-B Algo



forward (edge weights):

for  $t=1 \dots T$ :

for  $k=1 \dots K$ :

$$\alpha_t(k) = \sum_{j=1}^K \alpha_{t-1}(j) s_{kjt}$$

For HMM case:

$$s_{kjt} = p(y_t = k | y_{t-1} = j) p(x_t = w_k | y_t = k)$$

backward (edge weights):

same also, but on the mirror image of the trellis

$$\alpha_t(v) = \alpha_{t-1}(v) s_{vnt} + \alpha_{t-1}(n) s_{vnt} + \alpha_{t-1}(a) s_{vat}$$

= total weight of path prefixes entering node  $(t, v)$

# OH

$$p(\theta | \mathcal{D}) = p(x_1, \dots, x_N | \theta)$$

likelihood

$$l(\theta; \mathcal{D}) = l_{MLE}^{\mathcal{D}}(\theta) = p(x_1, \dots, x_N | \theta)$$

posterior

$$l_{MAP}(\theta; \mathcal{D}) = l_{MAP}^{\mathcal{D}}(\theta) = p(\theta | x_1, \dots, x_N) \propto \text{likelihood} \times \text{prior}$$

prior

$$p(\_ | \_)$$

$$l(\_ | \_)$$

$$l_{MAP}(\theta) = \log \left( \prod_{i=1}^N p(y^{(i)} | x^{(i)}, \theta) \right) + \log p(\theta)$$

$$p(\theta_m) \sim \text{Gaussian}(\mu=0, \sigma^2=1/2)$$

$$f(x) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2}\right)$$

$$p(\theta_m) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{\theta_m^2}{2}\right)$$

$$\log p(\theta_m) = \log\left(\frac{1}{\sqrt{2\pi}}\right) +$$

$$p(\theta) = \prod_{m=1}^M p(\theta_m)$$

$$\log p(\theta) = \left[ -\sum_{m=1}^M \frac{\theta_m^2}{2} \right] + M \log\left(\frac{1}{\sqrt{2\pi}}\right)$$

L2



$$\log p(\theta_m) = \log \left( \frac{2\pi}{\theta_m^2} \right) +$$

$$L_2 \quad \sum_{n=c}^M \theta_n^2$$

$$L_1 \quad \sum_{n=c}^M |\theta_n|$$

