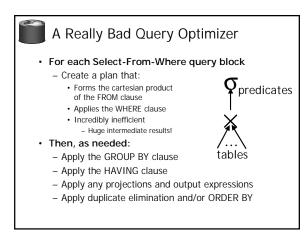
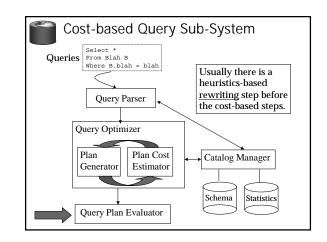


Introduction

- We've covered the basic underlying storage, buffering, and indexing technology.
 Now we can move on to query processing.
- Some database operations are EXPENSIVE
- Can greatly improve performance by being "smart"
- e.g., can speed up 1,000,000x over naïve approach
 Main weapons are:
 - 1. clever implementation techniques for operators
 - 2. exploiting "equivalencies" of relational operators
 - 3. using statistics and cost models to choose among these.





The Query Optimization Game

- "Optimizer" is a bit of a misnomer...
- Goal is to pick a "good" (i.e., low expected cost) plan.
 - Involves choosing access methods, physical operators, operator orders, ...
 - Notion of cost is based on an abstract "cost model"
- Roadmap for this topic:
 - First: basic operators
 - Then: joins
 - After that: optimizing multiple operators

Relational Operations

• We will consider how to implement:

- $\underline{\mathit{Selection}}$ (σ) Selects a subset of rows from relation.
- <u>Projection</u> (π) Deletes unwanted columns from relation.
- Join (×) Allows us to combine two relations.
- <u>Set-difference</u> (-) Tuples in reln. 1, but not in reln. 2.
- <u>Union</u> (\cup) Tuples in reln. 1 and in reln. 2.
- Aggregation (SUM, MIN, etc.) and GROUP BY
- Since each op returns a relation, ops can be *composed*!
 After we cover the operations, we will discuss how to *optimize* queries formed by composing them.

Schema for Examples

Sailors (<u>sid: integer</u>, sname: string, rating: integer, age: real) Reserves (<u>sid: integer</u>, <u>bid: integer</u>, <u>day: dates</u>, rname: string)

- Similar to old schema; *rname* added for variations.
 Sailors:
- Each tuple is 50 bytes long, 80 tuples per page, 500 pages.
- Reserves:
- Each tuple is 40 bytes long, 100 tuples per page, 1000 pages.

Simple Selections SELECT * FROM Reserves R WHERE R.rname < 'C%' Of the form σ_{R.attr op value} (R) Question: how best to perform? Depends on: what indexes/access paths are available what is the expected size of the result (in terms of number of tuples and/or number of pages) Size of result approximated as size of R * reduction factor "reduction factor" is usually called <u>selectivity</u>. estimate of reduction factors is based on statistics – we will discuss shortly.

Alternatives for Simple Selections

With no index, unsorted:

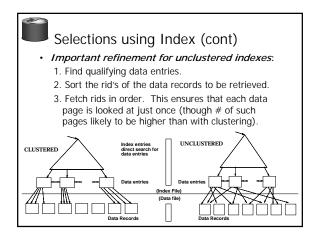
Must essentially scan the whole relation
 cost is M (#pages in R). For "reserves" = 1000 I/Os.

- With no index, sorted:
 cost of binary search + number of pages containing results.
 - For reserves = 10 I/Os + [selectivity*#pages]
- With an index on selection attribute:
 - Use index to find qualifying data entries,
 - then retrieve corresponding data records.
 - (Hash index useful only for equality selections.)



Cost depends on #qualifying tuples, and clustering. – Cost:

- Cost:
- finding qualifying data entries (typically small)
 plus cost of retrieving records (could be large w/o clustering).
- In example "reserves" relation, if 10% of tuples qualify (100 pages, 10000 tuples).
 - With a *clustered* index, cost is little more than 100 I/Os;
 - if unclustered, could be up to 10000 I/Os! unless...



General Selection Conditions

☑ (day<8/9/94 AND rname='Paul') OR bid=5 OR sid=3

- Such selection conditions are first converted to <u>conjunctive normal form (CNF)</u>:
- (day<8/9/94 OR bid=5 OR sid=3) AND (rname='Paul' OR bid=5 OR sid=3)
- We only discuss the case with no ORs (a conjunction of *terms* of the form *attr op value*).
- A B-tree index <u>matches</u> (a conjunction of) terms that involve only attributes in a *prefix* of the search key.
 Index on <a, b, c> matches a=5 AND b= 3, but not b=3.
- For Hash index, must have all attributes in search key

Two Approaches to General Selections

- <u>First approach</u>: Find the *most selective access path*, retrieve tuples using it, and apply any remaining terms that don't match the index:
- *Most selective access path:* An index or file scan that we estimate will require the fewest page I/Os.
- Terms that match this index reduce the number of tuples retrieved; other terms are used to discard some retrieved tuples, but do not affect number of tuples/pages fetched.

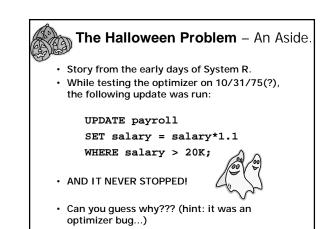
Most Selective Index - Example

- Consider day < 8/9/94 AND bid=5 AND sid=3.
- A B+ tree index <u>on day</u> can be used;
 - then, bid=5 and sid=3 must be checked for each retrieved tuple.
- Similarly, a hash index on < bid, sid> could be used;
- Then, day<8/9/94 must be checked.
- How about a B+tree on <rname,day>?
- How about a B+tree on <day, rname>?
- How about a Hash index on <day, rname>?

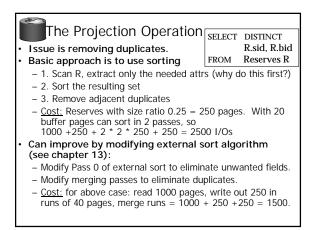
Intersection of Rids

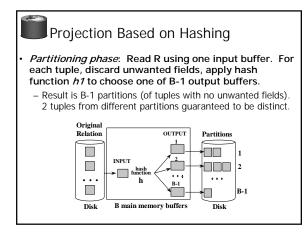
Second approach: if we have 2 or more matching indexes (w/Alternatives (2) or (3) for data entries):

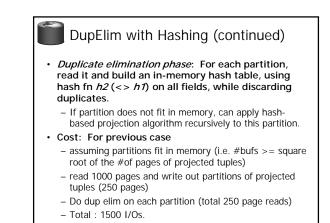
- Get sets of rids of data records using each matching index.
- Then intersect these sets of rids.
- Retrieve the records and apply any remaining terms.
- Consider day<8/9/94 AND bid=5 AND sid=3. With a B+ tree index on day and an index on sid, we can retrieve rids of records satisfying day<8/9/94 using the first, rids of recs satisfying sid=3 using the second, intersect, retrieve records and check bid=5.
- Note: commercial systems use various tricks to do this:
 bit maps, bloom filters, index joins



Schema for Examples Sailors (<u>sid: integer</u>, sname: string, rating: integer, age: real) Reserves (<u>sid: integer</u>, <u>bid: integer</u>, <u>day: dates</u>, rname: string) Similar to old schema; *rname* added for variations. Sailors: Each tuple is 50 bytes long, 80 tuples per page, 500 pages. N=500, p_s=80. Reserves: Each tuple is 40 bytes long, 100 tuples per page, 1000 pages. M=1000, p_R=100.





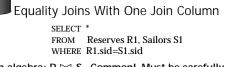


Discussion of Projection

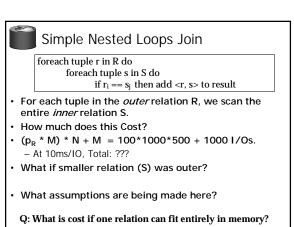
- Sort-based approach is the standard; better handling of skew and result is sorted.
- If enough buffers, both have same I/O cost: M + 2T where M is #pgs in R, T is #pgs of R with unneeded attributes removed.
- Although many systems don't use the specialized sort.
- If an index on the relation contains all wanted attributes in its search key, can do *index-only* scan.
- Apply projection techniques to data entries (much smaller!)
- If an ordered (i.e., tree) index contains all wanted attributes as *prefix* of search key, can do even better:
- Retrieve data entries in order (index-only scan), discard unwanted fields, compare adjacent tuples to check for duplicates.

Joins

- · Joins are very common.
- Joins can be very expensive (cross product in worst case).
- Many approaches to reduce join cost.



- In algebra: R ⋈ S. Common! Must be carefully optimized. R x S is large; so, R x S followed by a selection is inefficient.
- Remember, join is associative and commutative.
- Assume:
- M pages in R, p_R tuples per page.
- N pages in S, p_s tuples per page.
- In our examples, R is Reserves and S is Sailors.
- We will consider more complex join conditions later.
- Cost metric : # of I/Os. We will ignore output costs.



Page-Oriented Nested Loops Join

 $\begin{array}{l} \mbox{foreach page } b_{R} \mbox{ in } R \mbox{ do} \\ \mbox{foreach page } b_{S} \mbox{ in } S \mbox{ do} \\ \mbox{foreach tuple } r \mbox{ in } b_{R} \mbox{ do} \\ \mbox{foreach tuple } s \mbox{ in } b_{S} \mbox{do} \\ \mbox{ if } r_{i} = s_{j} \mbox{ then add } < r, s > to result \\ \end{array}$

- For each *page* of R, get each *page* of S, and write out matching pairs of tuples <r, s>, where r is in R-page and S is in S-page.
- · What is the cost of this approach?
- M*N + M= 1000*500 + 1000
 - If smaller relation (S) is outer, cost = 500*1000 + 500



Index Nested Loops Join

 $\begin{array}{l} \mbox{for each tuple } r \mbox{ in } R \mbox{ do} \\ \mbox{for each tuple } s \mbox{ in } S \mbox{ where } r_i == s_j \mbox{ do} \\ \mbox{ add } < r, s> \mbox{ to result } \end{array}$

- If there is an index on the join column of one relation (say S), can make it the inner and exploit the index.
 Cost: M + ((M*p_p) * cost of finding matching S tuples)
- For each R tuple, cost of probing S index is about 1.2 for hash index, 2-4 for B+ tree. Cost of then finding S tuples (assuming Alt. (2) or (3) for data entries) depends on clustering.
- Clustered index: 1 I/O per page of matching S tuples.
- Unclustered: up to 1 I/O per matching S tuple.

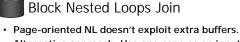


- Scan Reserves: 1000 page I/Os, 100*1000 tuples.

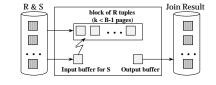
 For each Reserves. 1000 page 1/05, 100 1000 tiples.
 For each Reserves tuple: 1.2 I/Os to get data entry in index, plus 1 I/O to get (the exactly one) matching Sailors tuple. Total:

Hash-index (Alt. 2) on sid of Reserves (as inner):

- Scan Sailors: 500 page I/Os, 80*500 tuples.
- For each Sailors tuple: 1.2 I/Os to find index page with data entries, plus cost of retrieving matching Reserves tuples. Assuming uniform distribution, 2.5 reservations per sailor (100,000 / 40,000). Cost of retrieving them is 1 or 2.5 I/Os depending on whether the index is clustered.
- Totals:



- Alternative approach: Use one page as an input buffer for scanning the inner S, one page as the output buffer, and use all remaining pages to hold ``block" of outer R.
- For each matching tuple r in R-block, s in S-page, add <r, s> to result. Then read next R-block, scan S, etc.



Examples of Block Nested Loops

- Cost: Scan of outer + #outer blocks * scan of inner
- #outer blocks = $\lceil \# of pages of outer / blocksize \rceil$
- With Reserves (R) as outer, and 100 pages of R:
 - Cost of scanning R is 1000 I/Os; a total of 10 blocks.
 - Per block of R, we scan Sailors (S); 10*500 I/Os.
 If space for just 90 pages of R, we would scan S 12
 - times.
- With 100-page block of Sailors as outer:
 - Cost of scanning S is 500 I/Os; a total of 5 blocks.
 - Per block of S, we scan Reserves; 5*1000 I/Os.
- With <u>sequential reads</u> considered, analysis changes: may be best to divide buffers evenly between R and S.

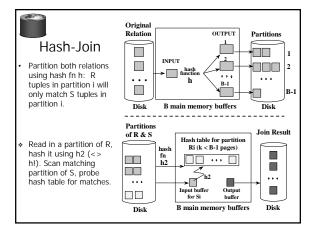
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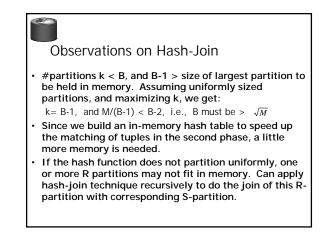
Sort-Merge Join (R $\bowtie_{i=1}$ S)

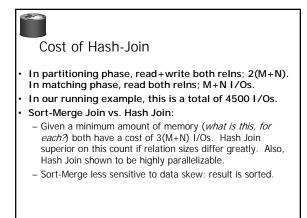
- Sort R and S on the join column, then scan them to do a ``merge" (on join col.), and output result tuples.
- Useful if
- one or both inputs are already sorted on join attribute(s)
- output is required to be sorted on join attributes(s)
- "Merge" phase can require some back tracking if duplicate values appear in join column
- R is scanned once; each S group is scanned once per matching R tuple. (Multiple scans of an S group will probably find needed pages in buffer.)

Example of Sort-Merge Join								
				sid	<u>bid</u>	<u>day</u>	rname	
sid	sname	rating	age	28	103	12/4/96	guppy	
22	dustin	7	45.0	28	103	11/3/96	yuppy	
28	yuppy	9	35.0	31	101	10/10/96	dustin	
31	lubber	8	55.5	31	102	10/12/96	lubber	
44	guppy	5	35.0	31	101	10/11/96	lubber	
58	rusty	10	35.0	58	103	11/12/96	dustin	
 Cost: Sort R + Sort S + (M+N) The cost of scanning, M+N, could be M*N (very unlikely!) With 35, 100 or 300 buffer pages, both Reserves and Sailors can be sorted in 2 passes; total join cost: 7500. (BNL cost: 2500 to 15000 I/Os) 								

	Refinement of Sort-Merge Join
•	We can combine the merging phases in the <i>sorting</i> of R and S with the merging required for the join.
	 Allocate 1 page per run of each relation, and `merge' while checking the join condition
	- With B > \sqrt{L} , where <i>L</i> is the size of the larger relation, using the sorting refinement that produces runs of length 2B in Pass 0, #runs of each relation is < B/2.
	 Cost: read+write each relation in Pass 0 + read each relation in (only) merging pass (+ writing of result tuples).
	 In example, cost goes down from 7500 to 4500 I/Os.
•	In practice, cost of sort-merge join, like the cost of external sorting, is <i>linear</i> .







General Join Conditions

• Equalities over several attributes (e.g., *R.sid=S.sid* AND *R.rname=S.sname*):

- For Index NL, build index on <*sid*, *sname*> (if S is inner); or use existing indexes on *sid* or *sname*.
- For Sort-Merge and Hash Join, sort/partition on combination of the two join columns.
- Inequality conditions (e.g., *R.rname < S.sname*):
- For Index NL, need (clustered!) B+ tree index.
- Range probes on inner; # matches likely to be much higher than for equality joins.
- Hash Join, Sort Merge Join not applicable!
- Block NL quite likely to be the best join method here.

Set Operations

- Intersection and cross-product special cases of join.
- Union (Distinct) and Except similar; we'll do union.

Sorting based approach to union:

- Sort both relations (on combination of all attributes).
- Scan sorted relations and merge them.
- Alternative: Merge runs from Pass 0 for both relations.

Hash based approach to union:

- Partition R and S using hash function h.
- For each S-partition, build in-memory hash table (using *h2*), scan corr. R-partition and add tuples to table while discarding duplicates.

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Aggregate Operations (AVG, MIN, etc.)

Without grouping:

- In general, requires scanning the relation.
- Given index whose search key includes all attributes in the
- SELECT or WHERE clauses, can do index-only scan.

With grouping:

- Sort on group-by attributes, then scan relation and compute aggregate for each group. (Can improve upon this by combining sorting and aggregate computation.)
- Similar approach based on hashing on group-by attributes.
- Given tree index whose search key includes all attributes in SELECT, WHERE and GROUP BY clauses, can do index-only scan; if group-by attributes form prefix of search key, can retrieve data entries/tuples in group-by order.

Impact of Buffering

- If several operations are executing concurrently, estimating the number of available buffer pages is guesswork.
- Repeated access patterns interact with buffer replacement policy.
 - e.g., Inner relation is scanned repeatedly in Simple Nested Loop Join. With enough buffer pages to hold inner, replacement policy does not matter. Otherwise, MRU is best, LRU is worst (*sequential flooding*).
 - Does replacement policy matter for Block Nested Loops?
 - What about Index Nested Loops? Sort-Merge Join?

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Summary

- A virtue of relational DBMSs: *queries are composed of a few basic operators*; the implementation of these operators can be carefully tuned (and it is important to do this!).
- Many alternative implementation techniques for each operator; no universally superior technique for most operators.
- Must consider available alternatives for each operation in a query and choose best one based on system statistics, etc. This is part of the broader task of optimizing a query composed of several ops.