Access Path Selection in System R

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Query Processing Phases

- Parsing
- Optimization
- Code Generation
- □ Execution



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Access Paths

- Segment (Relation) Scan each page is accessed exactly once
- □ Index Scan (B+ Tree)
 - □ Clustered.
 - $\ensuremath{\,\scriptscriptstyle\square}$ each index page is touched once
 - each data page is touched once
 - Unclustered.
 - $\ensuremath{\,\scriptscriptstyle\square}$ each index page is touched once
 - each tuple may be touched once, but each page may be fetched multiple times



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Join Methods

- Nested Loops
- □ Sort-merge
- Hash join
- Access path is orthogonal choice



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Useful Definitions

- A <u>SARGable predicate</u>: attribute op value
- A <u>SARG</u> (Search ARGument for scans):
 a boolean expression of the SARGable predicates in disjunctive normal form:
 SARG1 or SARG2 or ... or SARGn
 (SARG1 and ... and SARGn) or
 (SARGn+1 and ... and SARGq) or ...



Definitions (cont.)

 A predicate (or set of predicates) <u>matches</u> an index when

predicates are SARGable, and

columns in the predicate are initial substring of index key



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Example

□ Index: name, location

Predicates:

"name = smith" matches index

"name = smith or name = jones" matches

"name = smith and location = San Jose"

"(name = x and location = z) or (name = y and

location = q)" matches

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Definitions (cont.)

- An ordering of tuples is <u>interesting</u> if it is an ordered needed for a
 - □ GroupBy,
 - □ OrderBy, or
 - Join

er.

Single-Relation: Cost Model

- □ Cost of a Query = # page fetches + W(#RSI Calls)
- W is a weighting factor
- pages fetched vs. instructions executed
 - □ low for I/O bound machines
 - □ high for CPU bound machines

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Statistics for Optimization

- □ NCARD (T) cardinality of relation T in tuples
- □ TCARD (T) number of pages containing tuples from T
- P(T) = TCARD(T)/(# of non-empty pages in the segment)
 - If segments only held tuples from one relation there would be no need for P(T)
- □ ICARD(I) number of distinct keys in index I
- □ NINDX(I) number of pages in index I

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Comments

- statistics not updated with each insert/delete/modify statement
- generated at load time
- update periodically using the update statistics command

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Step #1 of Query Optimization

- Calculate a selectivity factor 'F' for each boolean factor in the predicate list
- Single-relation access paths
- □ Formulae on the board

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Predicate Selectivity Estimation F = 1/ICARD(attr index) - if index exists attr = value F = 1/10 otherwise attr1 = attr2F = 1/max(ICARD(I1),ICARD(I2)) or F = 1/ICARD(Ii) – if only index i exists, or F = 1/10 F = (value2-value1)/(high key-low key) val1 < attr < val2 F = 1/4 otherwise expr1 or expr2 F = F(expr1)+F(expr2)-F(expr1)*F(expr2)expr1 and expr2 F = F(expr1) * F(expr2) NOT expr F = 1 - F(expr)

Comments	
 □ Query cardinality is the product of the relation cardinalities times the selectivities of the query's boolean factor QCARD= R₁ * R₂ * * R_n *F_{R1}*F_{R2}* * F_{Rn}, 	
□ RSICARD (# RSI calls performed) = $ R_1 ^* R_2 ^*$.;* $ R_n ^*$ selectivity factors of all SARGABLE boolean factors	
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Step #2 of Query Optimization

- For each relation, calculate the cost of scanning the relation for each suitable index + a segment scan
- What is produced:
 - i) Cost C in the form of # pages fetched + W*RSICARD
 - ii) Ordering of tuples the access path will produce



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Costs per Access Path Case		
Unique index matching equal predicate	1+1+W	
Clustered index I matching >=1 preds	F(preds)*(NINDX(I)+TCARD)+W*RSICARD	
Non-clustered index I matching >=1 preds	F(preds)*(NINDX(I)+NCARD)+W*RSICARDor if buffer pool large enough F(preds)*(NINDX(I)+TCARD)+W*RSICARD	
Segment scan	TCARD/P + W*RSICARD	
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Joins - Definitions

- □ Outer relation tuple retrieved first from here
- Inner relation tuples retrieved (possible based on outer tuple join value)
- <u>Join predicate</u> relates columns of inner/outer relations



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Two join methods considered

- □ Nested loops scan inner for each outer tuple
- Merge scans scan in join column order (via index or after sorting)
- N-way joins are performed as a sequence of 2way joins
 - Can pipeline if no sort step is required



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Join Order Issues

- Cardinality of result is the same regardless of the join order
- □ N! orders for N-way join (in general)
- After k relations have been joined, method to add in (k+1)st is independent of the order for the 1st k (helps organize search)
- Join orders considered only when there is an inner - outer join predicate (and outer is all relations joined so far), except if all cross-products

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Example

R1 join R2 and R2 join R3 on a different column Consider

- □ R1 join R2 join R3
- □ R2 join R1 join R3
- □ R3 join R2 join R1
- □ R2 join R3 join R1

Forget

- □ R1 join R3 join R2
- □ R3 join R1 join R2

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Join Optimization Algorithm

- 1. Find best way to access <u>each</u> relation for each interesting tuple order and for the unordered case
- 2. Best way of join any relation to these if found → produces solutions for joining pairs of relations
- Find the best way of joining sets of three relations by considering all sets of two relations and joining in each third relation permitted by the join order heuristic
- 4. Continue adding additional relations via step 3
- 5. Choose cheapest path from root to leaf

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Cost Formulae for Joins

Pi=access path

 $\frac{\text{Nested Loops:}}{\text{N is the number of outer tuples satisfying predicate}} (\text{P1}) + \text{N*C}_{\text{inner}} (\text{P2})$

Merge Joins: $Cost_{MSjoin} = C_{outer}(P1) + N*C_{inner}(P2)$ Since both are assumed to be sorted,

C_{inner} = #inner pages/N +W*RSICARD

Note: same except for C_{inner}(P2) is cheaper (potentially) in merge joins case:

 $Cost_{Sort} = Cost_{ScanPath} + Cost_{DoSortItself} + Cost_{WriteTempFile}$

Search Tree

- □ Tree for possible query processing strategies:
 - □ Root -> leaf path represents a way of processing query
 - Label edges with costs, orderings
 - □ Tree considers all reasonable options
 - Access paths
 - Orderings of tuples
 - □ Join Orderings
 - $\hfill \square$ Trees for both nested loops and merge joins
 - Always take the cheapest way for the various interesting orders and prune more expensive equivalent plans

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Optimization Example

Assume the following database schema:

Emp (name, dno, job, salary), indices dno (clustered), job (unclustered)

Dept (dno, name, loc), indices dno (clustered) Job (job, title) index job (clustered)

Consider optimization of the following query:

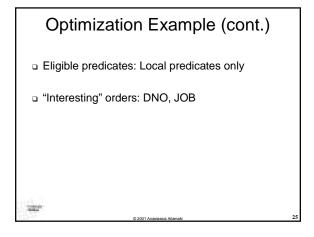
select Emp.name, Emp.salary, Job.title, Dept.name

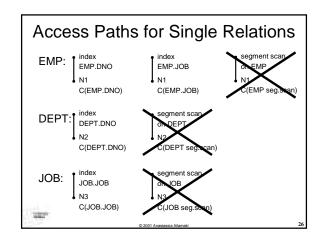
from Emp, Dept, Job

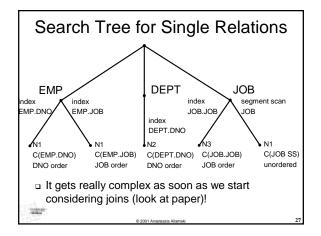
where title="clerk" and location ="Denver"

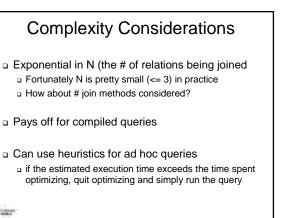
and Emp.dno = Dept.dno

and Emp.job = Job.job









Closing Remarks

- They also deal with "nested queries", both simple ones and "correlated" ones
- Cost turns out to be good for most reasonable queries
 - $\ensuremath{\text{\fontfamily{100}}}\xspace$ Relative (not absolute) accuracy is what matters
- use of statistics (newer, better work out now)
- consideration of CPU utilization and I/O activity
- □ selectivity factors, etc
- □ interesting orders save sorting unnecessarily

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Selectivity Histograms

- First found in Commercial INGRES (Koi, Ph.D. Thesis)
- Divide attribute domains into fixed range buckes, count number of hits for each bucket:
- Given a range query, base the selectivity estimate on the histogram data

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Example

Histogram on age (152 values total)

range	# of values in range
0-9	3
10-19	7
20-29	62
90-99	1

consider the selection:

EMP[15 <= AGE <= 25]

Est. Selectivity = [(5*7)/10+(6*62)/10]/152 = 0.27 (instead of using 0.10 w/ uniform assumption!)

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Overview of Query Optimization

- □ Chaudhuri, PODS 1998
- Query optimization =

search space of plans +

(low-cost plans)

cost estimation technique +

(accurate)

enumeration algorithm

(efficient)

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System R Optimizer

- □ Principle of optimality: To perform k joins
 - □ Find optimal plans for k-1 joins
 - □ Extend plans for one more join
- Interesting orders
 - □ Extended to *physical properties* in Exodus
 - □ Property that can impact subsequent operations

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