

Distributed Training for Large-scale Logistic Models

Siddharth Gopal

Carnegie Mellon University

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Outline of the Talk

- Logistic Models
- Maximum Likelihood Estimation
- Parallelization
- Experiments

Logistic Models

Logistic Models model probability of an outcome Y given a predictor x .

$$P(Y = y|x; \mathbf{w}) \propto \exp(\mathbf{w}^\top \phi(y, x))$$

Subsumes Multinomial Logistic Regression, Conditional Random fields and Maximum entropy Models.

For example, in Multinomial Logistic Regression

$$P(Y = k|x; \mathbf{w}) = \frac{\exp(w_k^\top x)}{\sum_j \exp(w_j^\top x)}$$

Train Logistic models on large-scale data.

What is Large-scale ?

- Large number of Training Examples
- High dimensionality
- Large number of Outcomes

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- **High dimensionality**
- **Large number of Outcomes**

Some commonly used data on the web,

Dataset	#Instances	#Labels	#Features	#Parameters
ODP subset	93,805	12,294	347,256	4,269,165,264
Wikipedia subset	2,365,436	325,056	1,617,899	525,907,777,344
Image-net	14,197,122	21,841	-	-

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- How can we parallelize the training of such models ?
- How can we optimize different subsets of parameters simultaneously ?

Maximum Likelihood Estimation (MLE)

Typical MLE estimation

- N training examples, K classes.
- x_i denotes the i^{th} training example.
- Indicator variable y_{ik} denotes whether x_i belongs to class k .
- Estimate parameters \mathbf{w} by maximizing the log-likelihood,

$$\max_{\mathbf{w}} \sum_{i=1}^N \sum_{k=1}^K y_{ik} \log P(y_{ik} | x_i; \mathbf{w}) - \frac{\lambda}{2} \|\mathbf{w}\|^2$$

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$$[\text{OPT1}] \quad \min_{\mathbf{w}} \frac{\lambda}{2} \|\mathbf{w}\|^2 - \sum_{i=1}^N \sum_{k=1}^K y_{ik} w_k^\top x_i + \sum_{i=1}^N \log \left(\sum_{k=1}^K \exp(w_k^\top x_i) \right)$$

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- The log-sum-exp (LSE) function couples all the class-level parameter w_k 's together.

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- The log-sum-exp (LSE) function couples all the class-level parameter w_k 's together.
- Replace LSE by a parallelizable function
 - This parallelizable function should be an upper-bound
 - It should not make the optimization harder - like introduce non-convexity, non-differentiability etc.

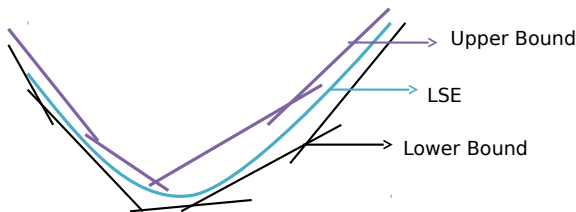
Bound 1 - Piecewise Linear Bound (Hsiung et al)

Properties used

- LSE is a convex-function
- Convex function can be approximated to any precision by piecewise linear functions.

$$\max_j \{a_j^\top \gamma + b_j\} \leq \log \left(\sum_{k=1}^K \exp(\gamma_k) \right) \leq \max_{j'} \{c_{j'}^\top \gamma + d_{j'}\}$$

$a, c \in \mathcal{R}^K \quad b, d \in \mathcal{R}$



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Advantages

- The bound can be made arbitrarily accurate by increasing the number of pieces.

Disadvantages

- Max-function makes the objective non-differentiable.
- The number of variational parameters grows with the approximation level.
- Optimizing the variational parameter is hard.

Bound 2 - Double Majorization (Bouchard 2007)

The LSE is bound by,

$$\log \left(\sum_{k=1}^K \exp(w_k^\top x_i) \right) \leq a_i + \sum_{k=1}^K \log(1 + \exp(w_k^\top x_i - a_i)) \quad , \quad a_i \in \mathcal{R}$$

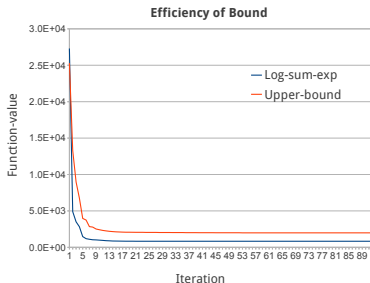
Advantages

- The bound is parallelizable.
- It is an upper bound.
- It is differentiable and **convex**.

Bound 2 - Double Majorization (Bouchard 2007)

Disadvantage

- The bound is not tight enough.

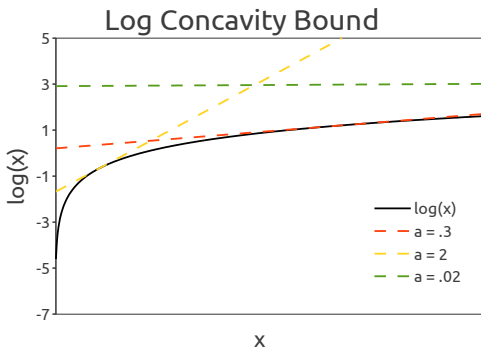


The gap between true objective and upper-bounded objective on the 20-newsgroup dataset.

Bound 3 - Log Concavity

A relatively famous bound using the concavity of the log-function

$$\log(x) \leq ax - \log(a) - 1 \quad \forall x, a > 0$$



Bound 3 - Log Concavity

Applying to the LSE function,

$$\log \left(\sum_{k=1}^K \exp(w_k^\top x_i) \right) \leq a_i \sum_{k=1}^K \exp(w_k^\top x_i) - \log(a_i) - 1$$

Advantages

- The bound is parallelizable.
- It is differentiable.
- Optimizing the variational parameter a_i is easy.
- The upper bound is exact at $a_i = \frac{1}{\sum_{k=1}^K \exp(w_k^\top x_i)}$.

Disadvantage

- The combined objective is non-convex.

MLE estimation $\min_{\mathbf{w}} \frac{\lambda}{2} \|\mathbf{w}\|^2 - \sum_{i=1}^N \sum_{k=1}^K y_{ik} w_k^\top x_i + \sum_{i=1}^N \log \left(\sum_{k=1}^K \exp(w_k^\top x_i) \right)$

Log-concavity Bound $\log \left(\sum_{k=1}^K \exp(w_k^\top x_i) \right) \leq a_i \sum_{k=1}^K \exp(w_k^\top x_i) - \log(a_i) - 1$

Reaching Optimality

$$\text{MLE estimation } \min_{\mathbf{w}} \frac{\lambda}{2} \|\mathbf{w}\|^2 - \sum_{i=1}^N \sum_{k=1}^K y_{ik} \mathbf{w}_k^\top \mathbf{x}_i + \sum_{i=1}^N \log \left(\sum_{k=1}^K \exp(\mathbf{w}_k^\top \mathbf{x}_i) \right)$$

$$\text{Log-concavity Bound } \log \left(\sum_{k=1}^K \exp(\mathbf{w}_k^\top \mathbf{x}_i) \right) \leq a_i \sum_{k=1}^K \exp(\mathbf{w}_k^\top \mathbf{x}_i) - \log(a_i) - 1$$

Combined Objective

$$F(W, A) = \frac{\lambda}{2} \sum_{k=1}^K \|\mathbf{w}_k\|^2 + \sum_{i=1}^N \left[- \sum_{k=1}^K y_{ik} \mathbf{w}_k^\top \mathbf{x}_i + a_i \sum_{k=1}^K \exp(\mathbf{w}_k^\top \mathbf{x}_i) - \log(a_i) - 1 \right]$$

$$\text{MLE estimation } \min_{\mathbf{w}} \frac{\lambda}{2} \|\mathbf{w}\|^2 - \sum_{i=1}^N \sum_{k=1}^K y_{ik} \mathbf{w}_k^\top \mathbf{x}_i + \sum_{i=1}^N \log \left(\sum_{k=1}^K \exp(\mathbf{w}_k^\top \mathbf{x}_i) \right)$$

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Despite the non-convexity, we can show that

- The combined objective has a unique minima.
- This minimum coincides with the optimal MLE solution.

An iterative and **parallel** block coordinate descent algorithm to converge to the unique minimum.

Algorithm 1 A parallel block coordinate descent

Initialize : $t \leftarrow 0, \mathbf{A}^0 \leftarrow \frac{1}{K}, \mathbf{W}^0 \leftarrow 0.$

While : Not converged

In parallel : $\mathbf{W}^{t+1} \leftarrow \arg \min_W F(W, \mathbf{A}^t)$

$\mathbf{A}^{t+1} \leftarrow \arg \min_A F(\mathbf{W}^{t+1}, A)$

$t \leftarrow t + 1$

Datasets

Dataset	# instances	#Leaf-labels	#Features	#Parameters	Parameter Size (approx)
CLEF	10,000	63	80	5,040	40KB
NEWS20	11,260	20	53,975	1,079,500	4MB
LSHTC-small	4,463	1,139	51,033	227,760,279	911MB
LSHTC-large	93,805	12,294	347,256	4,269,165,264	17GB

Optimization Methods

- Double Majorization Bound (DM)
- Log concavity Bound (LC)
- Limited Memory BFGS (LBFGS) - the most widely used method.
- Alternating Direction Method of Multipliers (ADMM)

Time Complexity

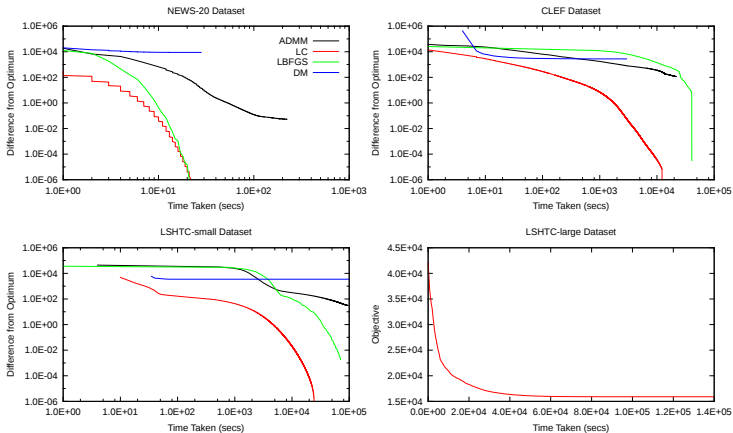


Figure : The difference from the true optimum vs time

Conclusion

- Discussed multiple ways to perform distributed training of large-scale Logistic Models.
- The LC method seem to offer the best trade-off between accuracy and time.
- Several open questions,
 - Effect of the regularization parameter λ .
 - Effect of the correlation between the parameters.

Binary vs Multiclass

