

# Graduate AI

Lecture 21:

Game Theory IV

Teachers:

Zico Kolter

Ariel Procaccia (this time)

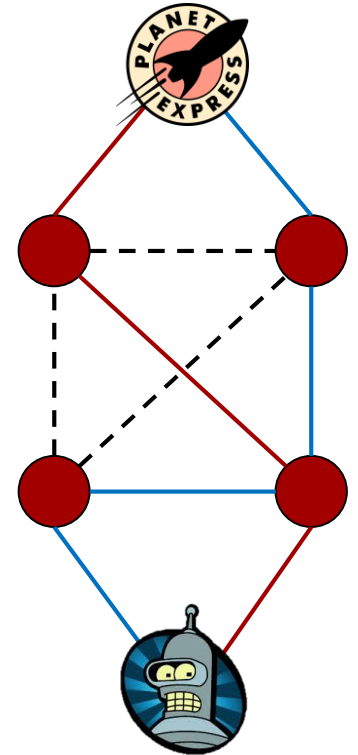
# REMINDER: THE MINIMAX THEOREM

- Theorem [von Neumann, 1928]: Every 2-player zero-sum game has a unique value  $v$  such that:
  - Player 1 can guarantee value at least  $v$
  - Player 2 can guarantee loss at most  $v$
- We will prove the theorem via no-regret learning



# HOW TO REACH YOUR SPACESHIP

- Each morning pick one of  $n$  possible routes
- Then find out how long each route took
- Is there a strategy for picking routes that does almost as well as the best fixed route **in hindsight**?



53 minutes

47 minutes

...

# THE MODEL

- View as a matrix (maybe infinite #columns)

Adversary

Algorithm								

- Algorithm picks row, adversary column
- Alg pays cost of (row,column) and gets column as feedback
- Assume costs are in  $[0,1]$

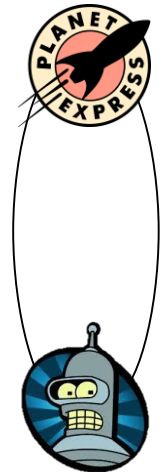
# THE MODEL

- Define **average regret** in  $T$  time steps as (average per-day cost of alg) – (average per-day cost of best fixed row in hindsight)
- **No-regret algorithm**:  $\text{regret} \rightarrow 0$  as  $T \rightarrow \infty$
- Not competing with adaptive strategy, just the best **fixed** row



# EXAMPLE

- **Algorithm 1:** Alternate between U and D
- **Poll 1:** What is algorithm 1's worst-case average regret?
  1.  $\Theta(1/T)$
  2.  $\Theta(1)$
  3.  $\Theta(T)$
  4.  $\infty$

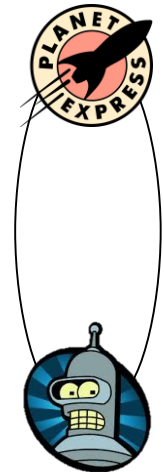


Adversary

	1	0
Algorithm	0	1

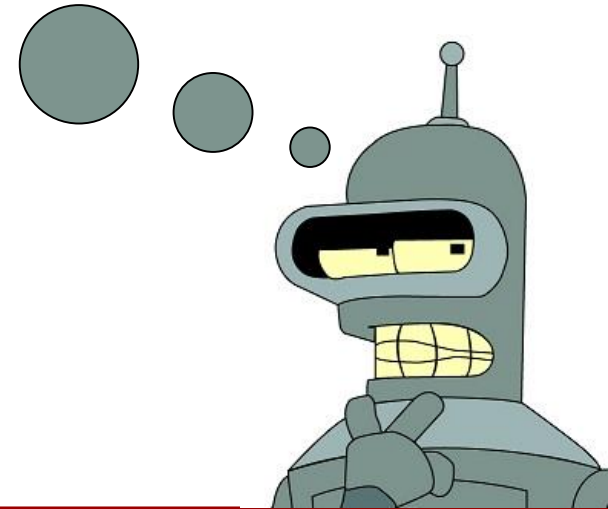
# EXAMPLE

- **Algorithm 2:** Choose action that has lower cost so far
- **Poll 2:** What is algorithm 2's worst-case average regret?
  1.  $\Theta(1/T)$
  2.  $\Theta(1/\sqrt{T})$
  3.  $\Theta(1/\log T)$
  4.  $\Theta(1)$



		Adversary	
Algorithm	1	1	0
	0	0	1

What can we say  
more generally  
about deterministic  
algorithms?





# USING EXPERT ADVICE

- Want to predict the stock market
- Solicit advice from  $n$  experts
  - Expert = someone with an opinion



Day	Expert 1	Expert 2	Expert 3	Charlie	Truth
1	-	-	+	+	+
2	+	-	+	-	-
...	...	...	...	...	...

- Can we do as well as best in hindsight?

# SIMPLER QUESTION

- One of the  $n$  experts never makes a mistake
- We want to find out which one
- **Algorithm 3:** Take majority vote over experts that have been correct so far
- **Poll 3:** What is algorithm 3's worst-case number of mistakes?
  1.  $\Theta(1)$
  2.  $\Theta(\log n)$
  3.  $\Theta(n)$
  4.  $\Theta(2^n)$



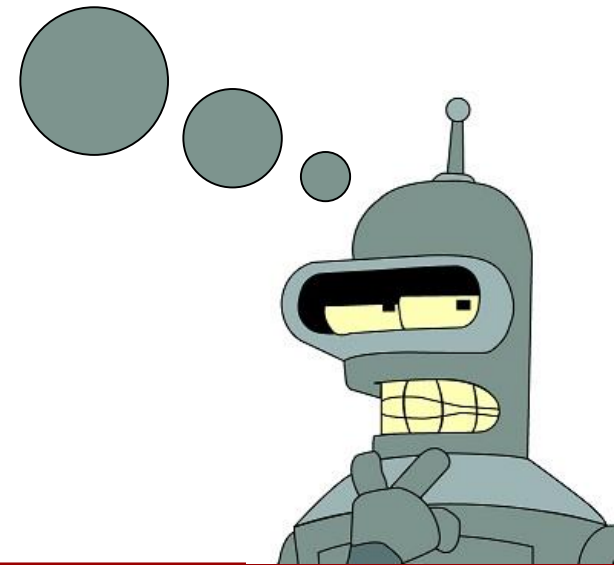
# WHAT IF NO EXPERT IS PERFECT?

- Idea: Run algorithm 3 until all experts are crossed off, then repeat
- Makes at most  $\log n$  mistakes per mistake of the best expert
- But this is wasteful: we keep forgetting what we've learned



Reprise:

Algorithms that  
forget their history  
are doomed to  
repeat it!



# WEIGHTED MAJORITY

- **Intuition:** Making a mistake doesn't disqualify an expert, just lowers its weight
- **Weighted Majority Algorithm:**
  - Start with all experts having weight 1
  - Predict based on weighted majority vote
  - Penalize mistakes by cutting weight in half

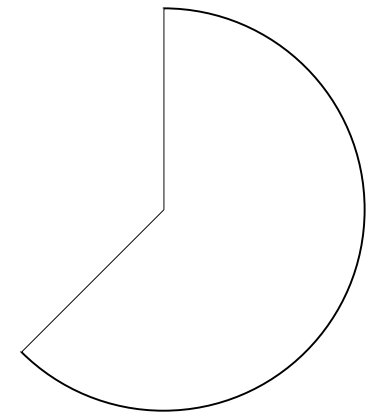
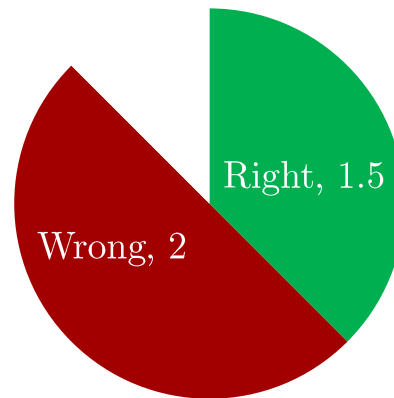
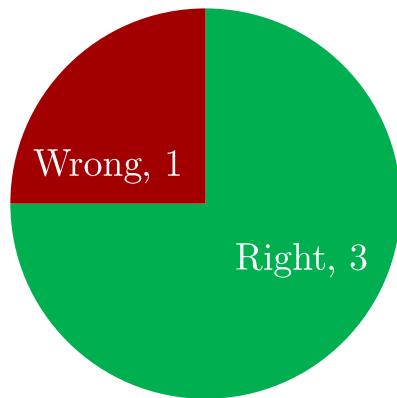


	Expert 1	Expert 2	Expert 3	Charlie
Weights	1	1	1	1
Prediction	-	+	+	+
Weights	0.5	1	1	1
Prediction	+	+	-	-
Weights	0.5	1	0.5	0.5

Alg	Truth
-----	-------

+	+
---	---

-	+
---	---



# WEIGHTED MAJORITY: ANALYSIS

- $M = \#$ mistakes we've made so far
- $m = \#$ mistakes of best expert so far
- $W =$  total weight (starts at  $n$ )
- For each mistake,  $W$  drops by at least 25%  
 $\Rightarrow$  after  $M$  mistakes:  $W \leq n(3/4)^M$
- Weight of best expert is  $(1/2)^m$

$$\left(\frac{1}{2}\right)^m \leq n \left(\frac{3}{4}\right)^M \Rightarrow \left(\frac{4}{3}\right)^M \leq n2^m \Rightarrow M \leq 2.5(m + \lg n)$$



# RANDOMIZED WEIGHTED MAJORITY

- Randomized Weighted Majority

## Algorithm:

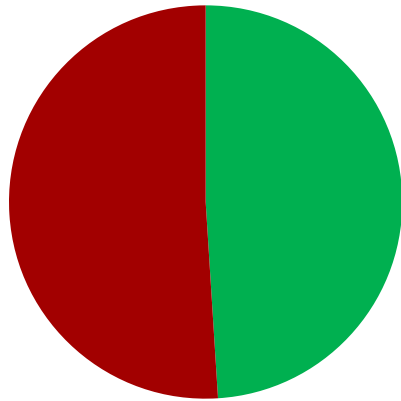
- Start with all experts having weight 1
- Predict **proportionally** to weights: the total weight of + is  $w_+$  and the total weight of - is  $w_-$ , predict + with probability  $\frac{w_+}{w_+ + w_-}$  and - with probability  $\frac{w_-}{w_+ + w_-}$
- Penalize mistakes by removing  **$\epsilon$  fraction** of weight



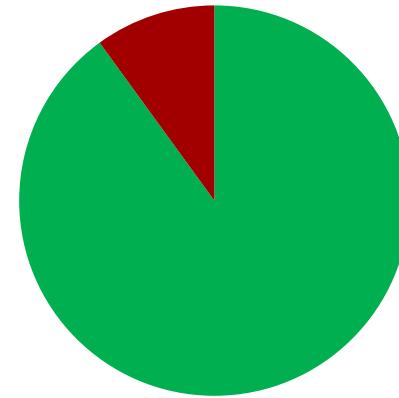


# RANDOMIZED WEIGHTED MAJORITY

Idea: smooth out the worst case



The worst-case is  
~50-50: now we have  
a 50% chance of  
getting it right



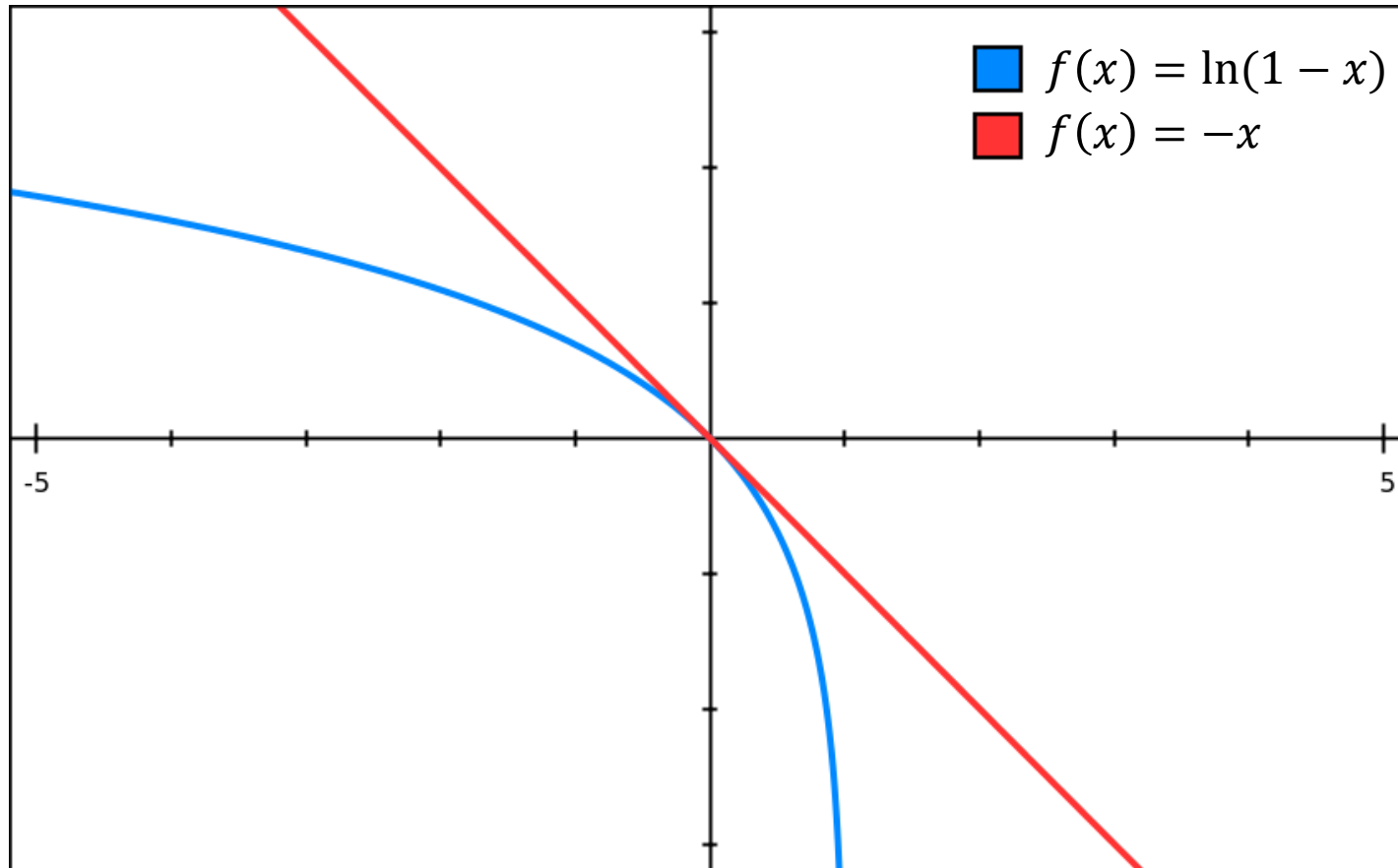
What about 90-10?  
We're very likely to  
agree with the  
majority

# ANALYSIS

- At time  $t$  we have a fraction  $F_t$  of weight on experts that made a mistake
- Prob.  $F_t$  of making a mistake, remove  $\epsilon F_t$  fraction of total weight
- $W_{final} = n \prod_t (1 - \epsilon F_t)$
- $\ln W_{final} = \ln n + \sum_t \ln(1 - \epsilon F_t)$   
 $\leq \ln n - \epsilon \sum_t F_t = \ln n - \epsilon M$

↑  
 $\ln(1 - x) \leq -x$   
(next slide)

# ANALYSIS



# ANALYSIS

- Weight of best expert is  $W_{best} = (1 - \epsilon)^m$
- $\ln n - \epsilon M \geq \ln W_{final} \geq \ln W_{best} = m \ln(1 - \epsilon)$
- By setting  $\epsilon = \sqrt{\ln n / m}$  and solving, we get
$$M \leq m + 2\sqrt{m \ln n}$$
- Since  $m \leq T$ ,  $M \leq m + 2\sqrt{T \ln n}$
- Average regret is  $(2\sqrt{T \ln n})/T \rightarrow 0$  ■

# MORE GENERALLY

- Each **expert** is an **action** with cost in  $[0,1]$
- Run Randomized Weighted Majority
  - Choose expert  $i$  with probability  $w_i/W$
  - Update weights:  $w_i \leftarrow w_i(1 - c_i\epsilon)$
- Same analysis applies:
  - Our expected cost:  $\sum_j c_j w_j / W$
  - Fraction of weight removed:  $\epsilon \sum_j c_j w_j / W$
  - So, fraction removed =  $\epsilon \cdot$  (our cost)

# PROOF OF THE MINIMAX THM

- Suppose for contradiction that zero-sum game  $G$  has  $V_C > V_R$  such that:
  - If column player commits first, there is a row that guarantees row player at least  $V_C$
  - If row player commits first, there is a column that guarantees row player at most  $V_R$
- Scale matrix so that payoffs to row player are in  $[-1,0]$ , and let  $V_C = V_R + \delta$



# PROOF OF THE MINIMAX THM

- Row player plays RWM, and column player responds optimally to current mixed strategy
- After  $T$  steps
  - $\text{ALG} \geq \text{best row in hindsight} - 2\sqrt{T \log n}$
  - $\text{ALG} \leq T \cdot V_R$
  - $\text{Best row in hindsight} \geq T \cdot V_C$
- It follows that  $T \cdot V_R \geq T \cdot V_C - 2\sqrt{T \log n}$
- $\delta T \leq 2\sqrt{T \log n}$  – contradiction for large enough  $T$  ■



# SUMMARY

- Terminology:
  - Regret
  - No-regret learning
- Algorithms:
  - Randomized weighted majority
- Big ideas:
  - It is possible to achieve no-regret learning guarantees!
  - Connections between game theory and learning theory

