

Machine-Level Programming IV: Data

15-213/18-213/15-513: Introduction to Computer Systems
8th Lecture, June 4, 2020

Today

■ Arrays

- One-dimensional
- Multi-dimensional (nested)
- Multi-level

■ Structures

- Allocation
- Access
- Alignment

■ Floating Point

Array Allocation

■ Basic Principle

$T \mathbf{A}[L];$

- Array of data type T and length L
- Contiguously allocated region of $L * \text{sizeof}(T)$ bytes in memory

`char string[12];`



`int val[5];`



`double a[3];`



`char *p[3];`

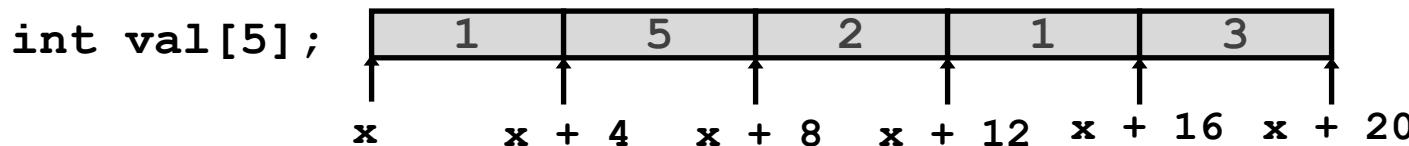


Array Access

■ Basic Principle

$T \mathbf{A}[L]$;

- Array of data type T and length L
- Identifier \mathbf{A} can be used as a pointer to array element 0: Type T^*



■ Reference Type Value

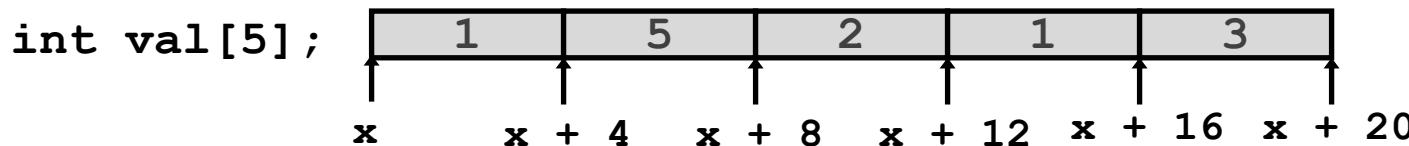
<code>val[4]</code>	<code>int</code>	
<code>val</code>	<code>int *</code>	
<code>val+1</code>	<code>int *</code>	
<code>&val[2]</code>	<code>int *</code>	
<code>val[5]</code>	<code>int</code>	
<code>*(val+1)</code>	<code>int</code>	
<code>val + i</code>	<code>int *</code>	

Array Access

■ Basic Principle

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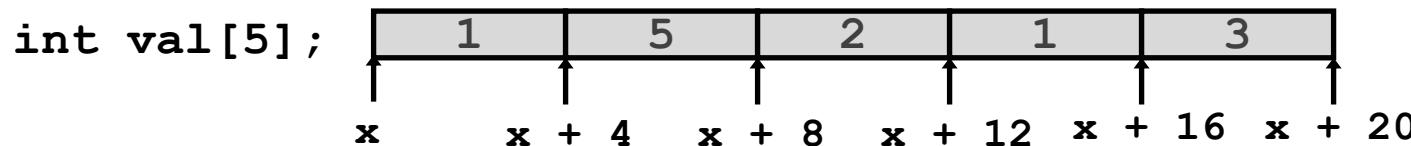
<code>val[4]</code>	<code>int</code>	3
<code>val</code>	<code>int *</code>	
<code>val+1</code>	<code>int *</code>	
<code>&val[2]</code>	<code>int *</code>	
<code>val[5]</code>	<code>int</code>	
<code>*(val+1)</code>	<code>int</code>	
<code>val + i</code>	<code>int *</code>	

Array Access

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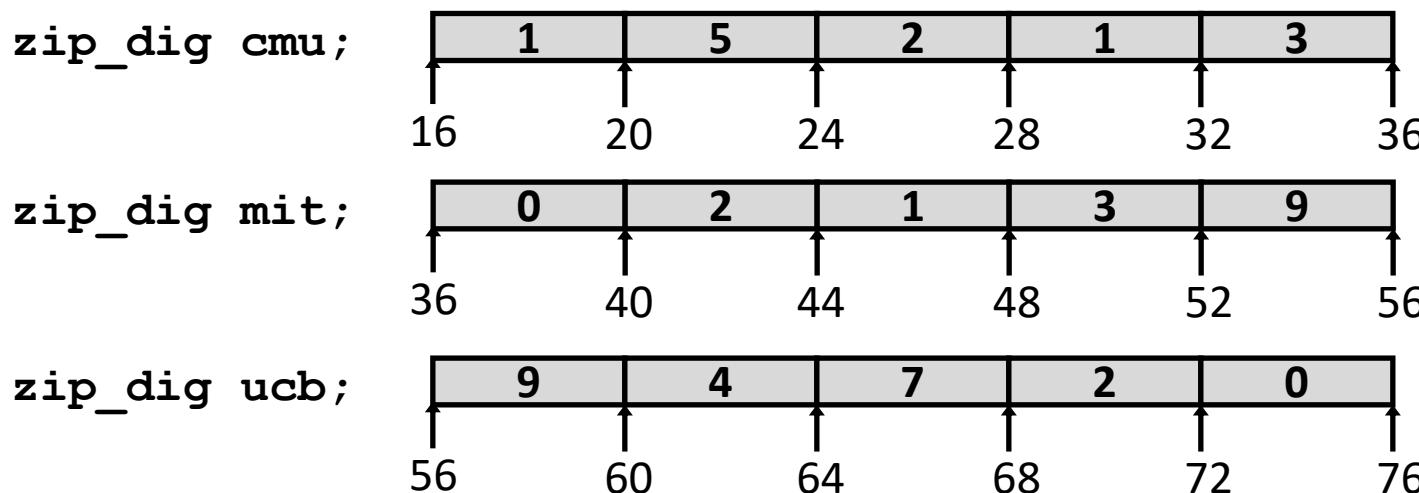
■ Reference Type Value

<code>val[4]</code>	<code>int</code>	3
<code>val</code>	<code>int *</code>	<code>x</code>
<code>val+1</code>	<code>int *</code>	<code>x + 4</code>
<code>&val[2]</code>	<code>int *</code>	<code>x + 8</code>
<code>val[5]</code>	<code>int</code>	??
<code>*(val+1)</code>	<code>int</code>	5 // <code>val[1]</code>
<code>val + i</code>	<code>int *</code>	<code>x + 4 * i</code> // <code>&val[i]</code>

Array Example

```
#define ZLEN 5
typedef int zip_dig[ZLEN];

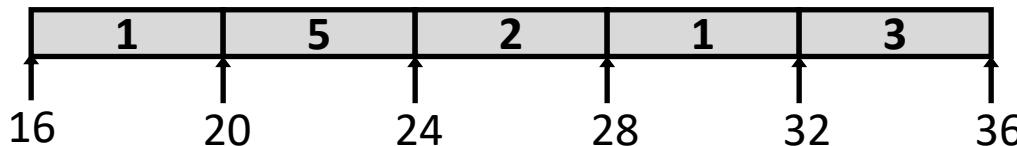
zip_dig cmu = { 1, 5, 2, 1, 3 };
zip_dig mit = { 0, 2, 1, 3, 9 };
zip_dig ucb = { 9, 4, 7, 2, 0 };
```



- Declaration “`zip_dig cmu`” equivalent to “`int cmu[5]`”
- Example arrays were allocated in successive 20 byte blocks
 - Not guaranteed to happen in general

Array Accessing Example

```
zip_dig cmu;
```



```
int get_digit
    (zip_dig z, int digit)
{
    return z[digit];
}
```

x86-64

```
# %rdi = z
# %rsi = digit
movl (%rdi,%rsi,4), %eax # z[digit]
```

- Register **%rdi** contains starting address of array
- Register **%rsi** contains array index
- Desired digit at **%rdi + 4*%rsi**
- Use memory reference (**%rdi, %rsi, 4**)

Array Loop Example

```
void zincr(zip_dig z) {
    size_t i;
    for (i = 0; i < ZLEN; i++)
        z[i]++;
}
```

```
# %rdi = z
movl    $0, %eax
jmp     .L3
.L4:
    addl    $1, (%rdi,%rax,4)
    addq    $1, %rax
.L3:
    cmpq    $4, %rax
    jbe     .L4
rep; ret
```

Array Loop Example

```
void zincr(zip_dig z) {
    size_t i;
    for (i = 0; i < ZLEN; i++)
        z[i]++;
}
```

```
# %rdi = z
movl    $0, %eax          # i = 0
jmp     .L3                # goto middle
.L4:               # loop:
    addl    $1, (%rdi,%rax,4) # z[i]++
    addq    $1, %rax          # i++
.L3:               # middle
    cmpq    $4, %rax          # i:4
    jbe     .L4                # if <=, goto loop
rep; ret
```

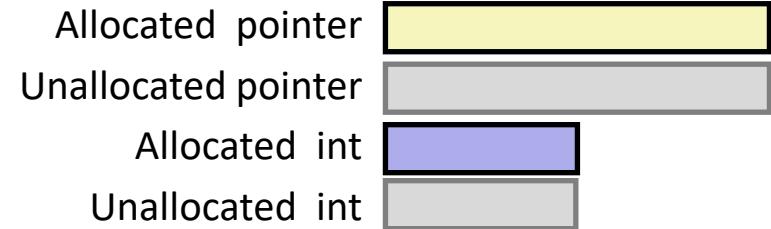
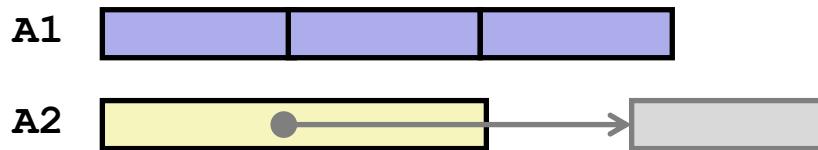
Understanding Pointers & Arrays #1

Decl	A1 , A2			*A1 , *A2		
	Comp	Bad	Size	Comp	Bad	Size
<code>int A1[3]</code>						
<code>int *A2</code>						

- **Comp: Compiles (Y/N)**
- **Bad: Possible bad pointer reference (Y/N)**
- **Size: Value returned by `sizeof`**

Understanding Pointers & Arrays #1

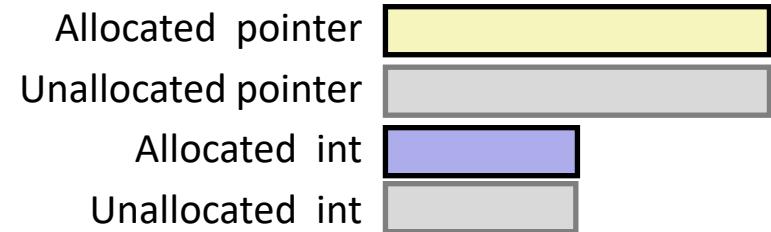
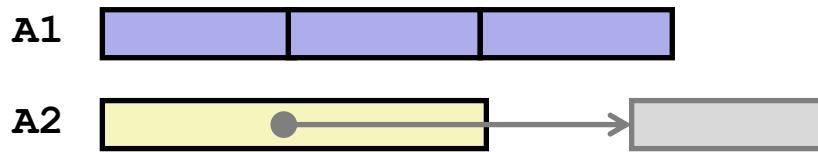
Decl	A1 , A2			*A1 , *A2		
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int A1[3]						
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- **Comp: Compiles (Y/N)**
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- **Size: Value returned by sizeof**

Understanding Pointers & Arrays #1

Decl	A1 , A2			*A1 , *A2		
	Comp	Bad	Size	Comp	Bad	Size
int A1[3]	Y	N	12	Y	N	4
int *A2	Y	N	8	Y	Y	4



- **Comp: Compiles (Y/N)**
- **Bad: Possible bad pointer reference (Y/N)**
- **Size: Value returned by `sizeof`**

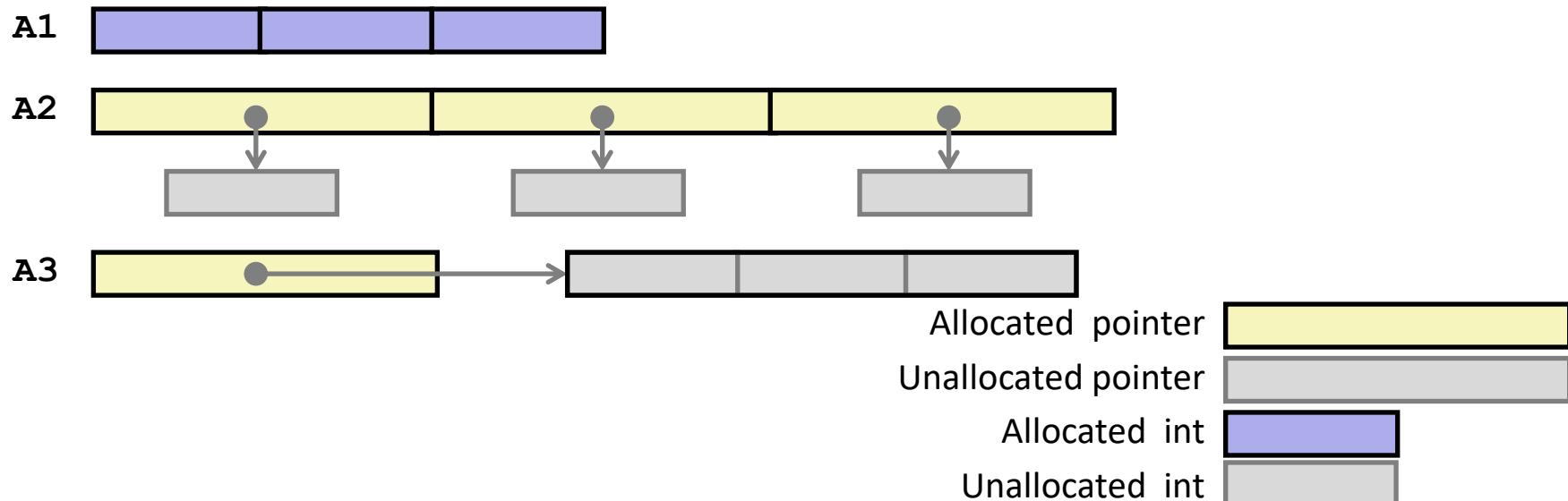
Understanding Pointers & Arrays #2

Decl	An			*An			**An		
	Cmp	Bad	Size	Cmp	Bad	Size	Cmp	Bad	Size
<code>int A1[3]</code>									
<code>int *A2[3]</code>									
<code>int (*A3)[3]</code>									



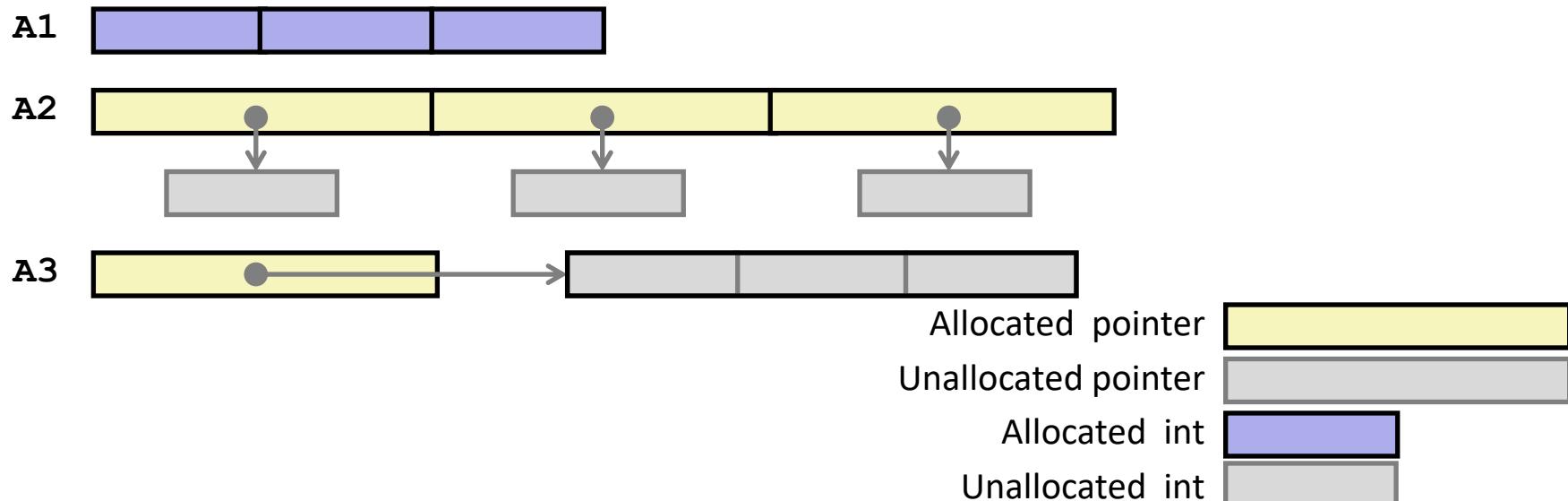
Understanding Pointers & Arrays #2

Decl	An			*An			**An		
	Cmp	Bad	Size	Cmp	Bad	Size	Cmp	Bad	Size
<code>int A1[3]</code>									
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Understanding Pointers & Arrays #2

Decl	An			*An			**An		
	Cmp	Bad	Size	Cmp	Bad	Size	Cmp	Bad	Size
<code>int A1[3]</code>	Y	N	12	Y	N	4	N	-	-
<code>int *A2[3]</code>	Y	N	24	Y	N	8	Y	Y	4
<code>int (*A3)[3]</code>	Y	N	8	Y	Y	12	Y	Y	4



Multidimensional (Nested) Arrays

■ Declaration

$T \ A[R][C];$

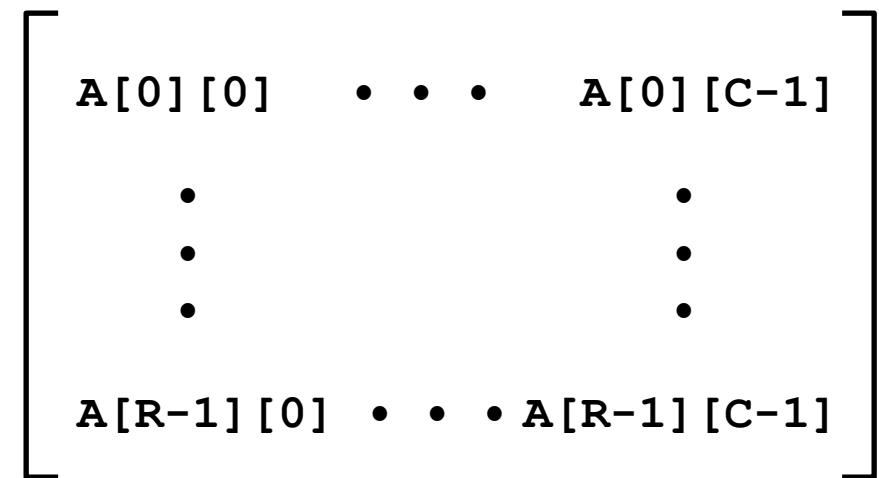
- 2D array of data type T
- R rows, C columns

■ Array Size

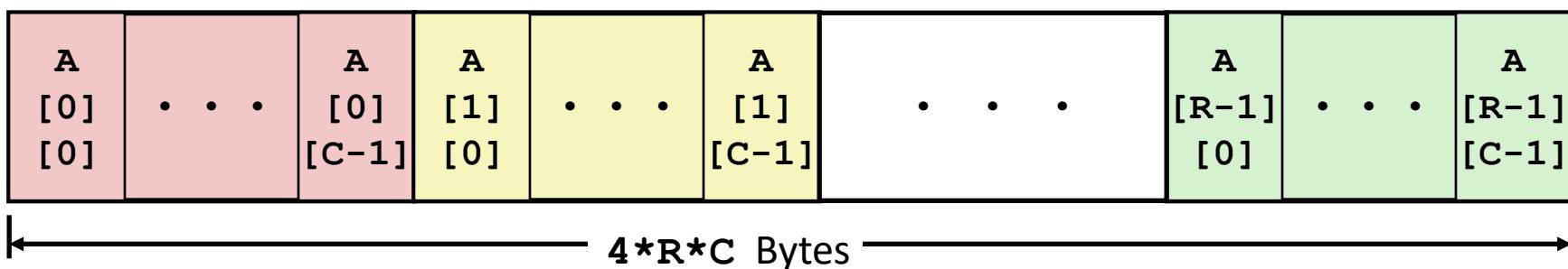
- $R * C * \text{sizeof}(T)$ bytes

■ Arrangement

- Row-Major Ordering



```
int A[R][C];
```

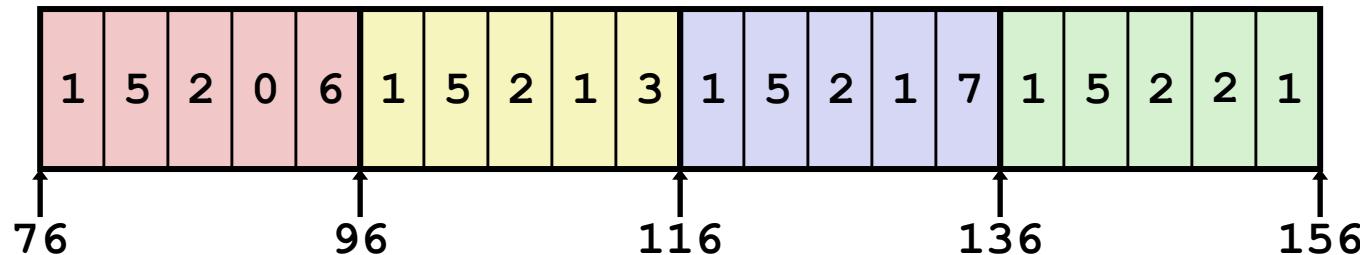


Nested Array Example

```
#define PCOUNT 4
typedef int zip_dig[5];

zip_dig pgh[PCOUNT] =
{{1, 5, 2, 0, 6},
 {1, 5, 2, 1, 3 },
 {1, 5, 2, 1, 7 },
 {1, 5, 2, 2, 1 }};
```

`zip_dig
pgh[4];`



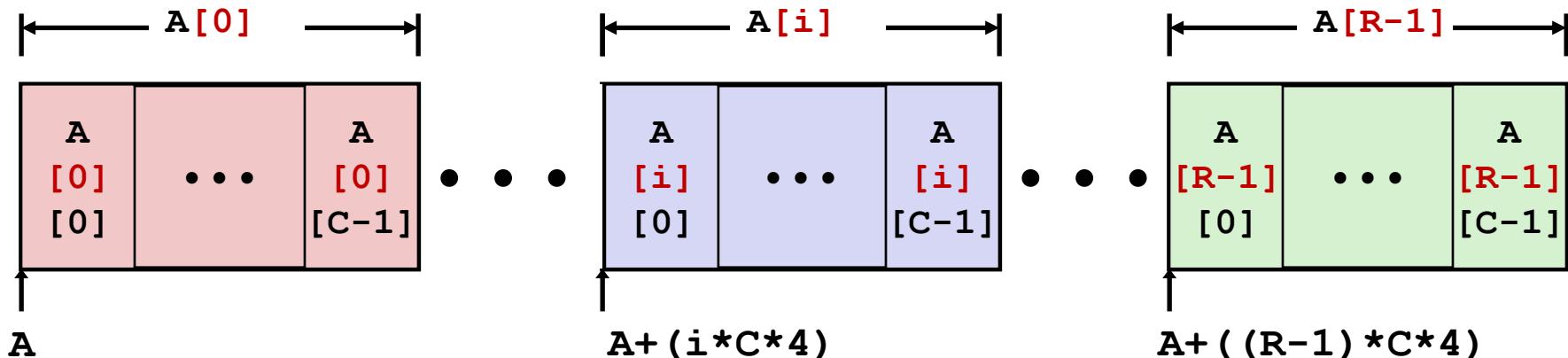
- “`zip_dig pgh [4]`” equivalent to “`int pgh [4] [5]`”
 - Variable `pgh`: array of 4 elements, allocated contiguously
 - Each element is an array of 5 `int`’s, allocated contiguously
- “Row-Major” ordering of all elements in memory

Nested Array Row Access

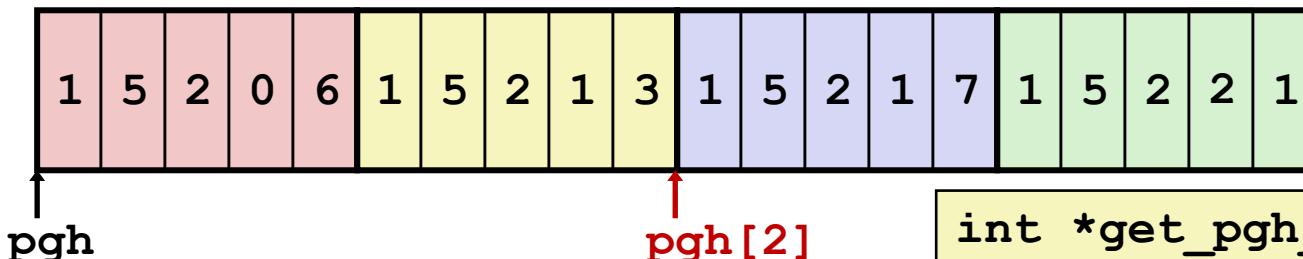
■ Row Vectors

- $\mathbf{A[i]}$ is array of C elements of type T
- Starting address $\mathbf{A} + \mathbf{i} * (\mathbf{C} * \mathbf{sizeof}(T))$

```
int A[R][C];
```



Nested Array Row Access Code



```
int *get_pgh_zip(int index)
{
    return pgh[index];
}
```

```
# %rdi = index
leaq (%rdi,%rdi,4),%rax # 5 * index
leaq pgh(%rax,4),%rax   # pgh + (20 * index)
```

■ Row Vector

- `pgh[index]` is array of 5 `int`'s
- Starting address `pgh+20*index`

■ Machine Code

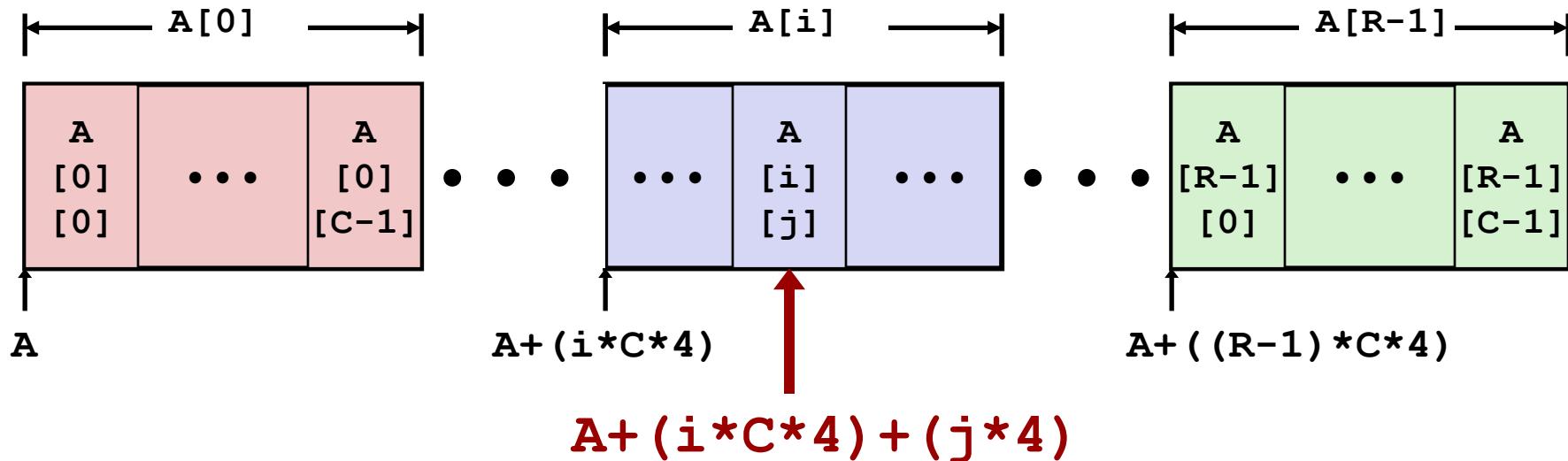
- Computes and returns address
- Compute as `pgh + 4*(index+4*index)`

Nested Array Element Access

■ Array Elements

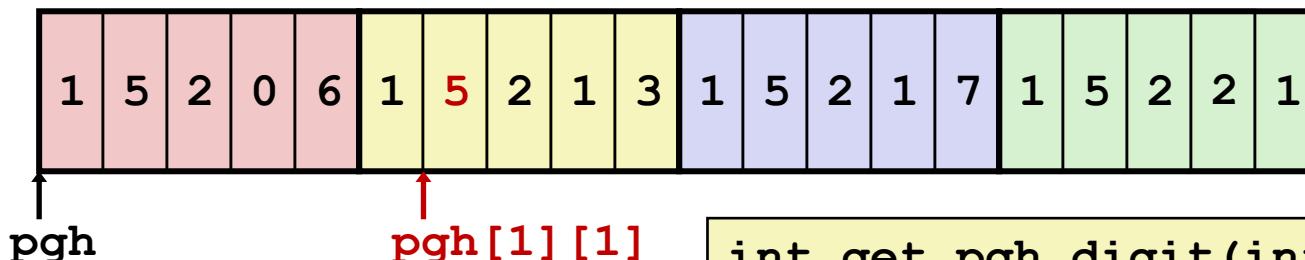
- $A[i][j]$ is element of type T , which requires K bytes
- Address $A + i * (C * K) + j * K$
 $= A + (i * C + j) * K$

```
int A[R][C];
```



$$A + (i * C * 4) + (j * 4)$$

Nested Array Element Access Code



`pgh[1][1]`

```
int get_pgh_digit(int index, int dig)
{
    return pgh[index][dig];
}
```

```
leaq (%rdi,%rdi,4), %rax      # 5*index
addl %rax, %rsi                # 5*index+dig
movl pgh(,%rsi,4), %eax       # M[pgh + 4*(5*index+dig)]
```

■ Array Elements

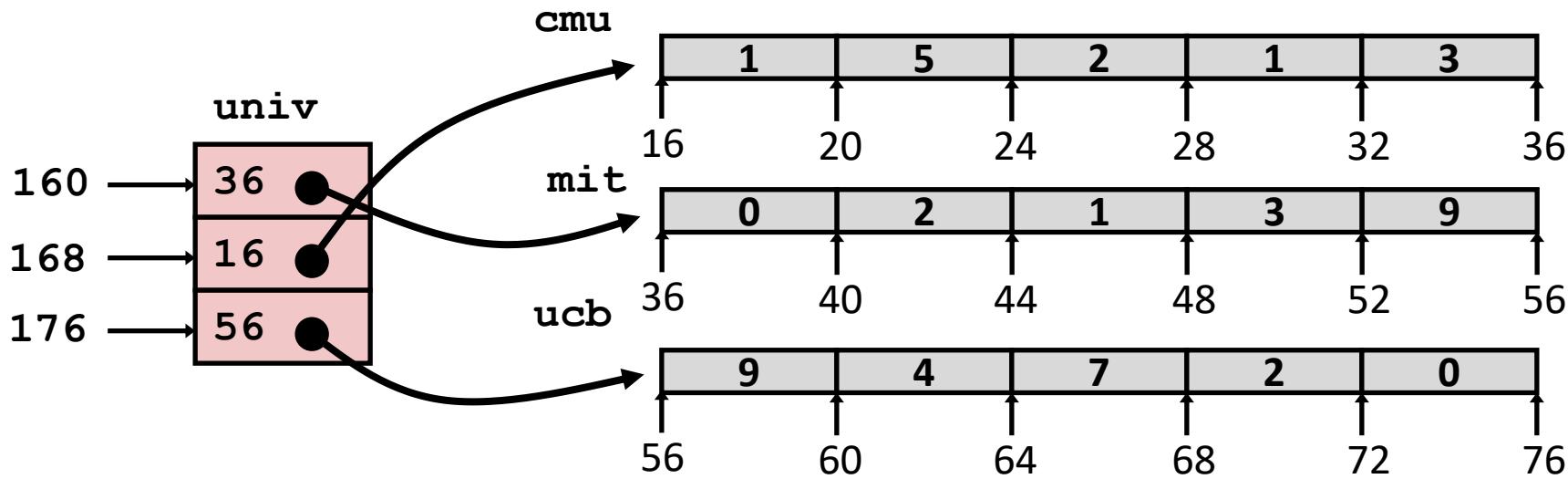
- `pgh[index][dig]` is `int`
- Address: $pgh + 20*index + 4*dig$
 $= pgh + 4*(5*index + dig)$

Multi-Level Array Example

```
zip_dig cmu = { 1, 5, 2, 1, 3 };
zip_dig mit = { 0, 2, 1, 3, 9 };
zip_dig ucb = { 9, 4, 7, 2, 0 };
```

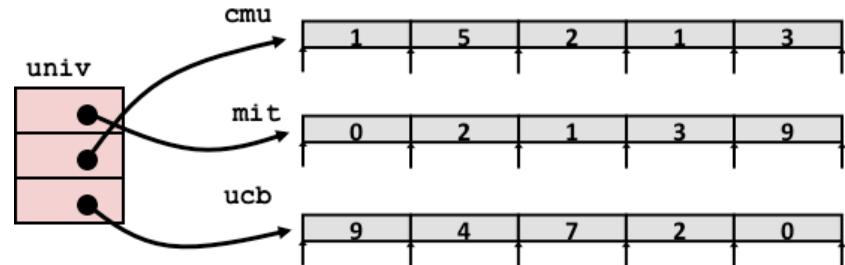
```
#define UCOUNT 3
int *univ[UCOUNT] = {mit, cmu, ucb};
```

- Variable **univ** denotes array of 3 elements
- Each element is a pointer
 - 8 bytes
- Each pointer points to array of int's



Element Access in Multi-Level Array

```
int get_univ_digit
    (size_t index, size_t digit)
{
    return univ[index][digit];
}
```



```
salq    $2, %rsi          # 4*digit
addq    univ(%rdi,8), %rsi # p = univ[index] + 4*digit
movl    (%rsi), %eax      # return *p
ret
```

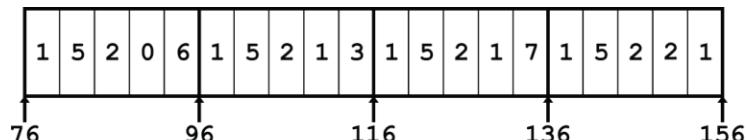
■ Computation

- Element access **Mem[Mem[univ+8*index]+4*digit]**
- Must do two memory reads
 - First get pointer to row array
 - Then access element within array

Array Element Accesses

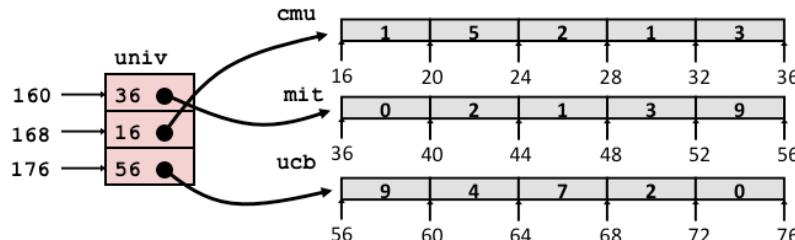
Nested array

```
int get_pgh_digit
    (size_t index, size_t digit)
{
    return pgh[index][digit];
}
```



Multi-level array

```
int get_univ_digit
    (size_t index, size_t digit)
{
    return univ[index][digit];
}
```



Accesses looks similar in C, but address computations very different:

`Mem[pgh+20*index+4*digit]`

`Mem[Mem[univ+8*index]+4*digit]`

$N \times N$ Matrix

Code

■ Fixed dimensions

- Know value of N at compile time

```
#define N 16
typedef int fix_matrix[N][N];
/* Get element A[i][j] */
int fix_ele(fix_matrix A,
            size_t i, size_t j)
{
    return A[i][j];
}
```

■ Variable dimensions, explicit indexing

- Traditional way to implement dynamic arrays

```
#define IDX(n, i, j) ((i)*(n)+(j))
/* Get element A[i][j] */
int vec_ele(size_t n, int *A,
            size_t i, size_t j)
{
    return A[IDX(n,i,j)];
}
```

■ Variable dimensions, implicit indexing

- Now supported by gcc

```
/* Get element A[i][j] */
int var_ele(size_t n, int A[n][n],
            size_t i, size_t j) {
    return A[i][j];
}
```

16 X 16 Matrix Access

■ Array Elements

- `int A[16][16];`
- Address `A + i * (C * K) + j * K`
- $C = 16, K = 4$

```
/* Get element A[i][j] */  
int fix_ele(fix_matrix A, size_t i, size_t j) {  
    return A[i][j];  
}
```

```
# A in %rdi, i in %rsi, j in %rdx  
salq    $6, %rsi          # 64*i  
addq    %rsi, %rdi        # A + 64*i  
movl    (%rdi,%rdx,4), %eax # Mem[A + 64*i + 4*j]  
ret
```

$n \times n$ Matrix Access

■ Array Elements

- `size_t n;`
- `int A[n][n];`
- Address `A + i * (C * K) + j * K`
- $C = n, K = 4$
- Must perform integer multiplication

```
/* Get element A[i][j] */
int var_ele(size_t n, int A[n][n], size_t i, size_t j)
{
    return A[i][j];
}
```

```
# n in %rdi, A in %rsi, i in %rdx, j in %rcx
imulq    %rdx, %rdi          # n*i
leaq     (%rsi,%rdi,4), %rax # A + 4*n*i
movl     (%rax,%rcx,4), %eax # A + 4*n*i + 4*j
ret
```

Example: Array Access

```
#include <stdio.h>
#define ZLEN 5
#define PCOUNT 4
typedef int zip_dig[ZLEN];

int main(int argc, char** argv) {
    zip_dig pgm =
        {{1, 5, 2, 0, 6},
         {1, 5, 2, 1, 3 },
         {1, 5, 2, 1, 7 },
         {1, 5, 2, 2, 1 }};
    int *linear_zip = (int *) pgm;
    int *zip2 = (int *) pgm[2];
    int result =
        pgm[0][0] +
        linear_zip[7] +
        *(linear_zip + 8) +
        zip2[1];
    printf("result: %d\n", result);
    return 0;
}
```

```
linux> ./array
```

Example: Array Access

```
#include <stdio.h>
#define ZLEN 5
#define PCOUNT 4
typedef int zip_dig[ZLEN];

int main(int argc, char** argv) {
    zip_dig pgm[PCOUNT] =
        {{1, 5, 2, 0, 6},
         {1, 5, 2, 1, 3},
         {1, 5, 2, 1, 7},
         {1, 5, 2, 2, 1}};
    int *linear_zip = (int *) pgm;
    int *zip2 = (int *) pgm[2];
    int result =
        pgm[0][0] +
        linear_zip[7] +
        *(linear_zip + 8) +
        zip2[1];
    printf("result: %d\n", result);
    return 0;
}
```

```
linux> ./array
result: 9
```

Today

■ Arrays

- One-dimensional
- Multi-dimensional (nested)
- Multi-level

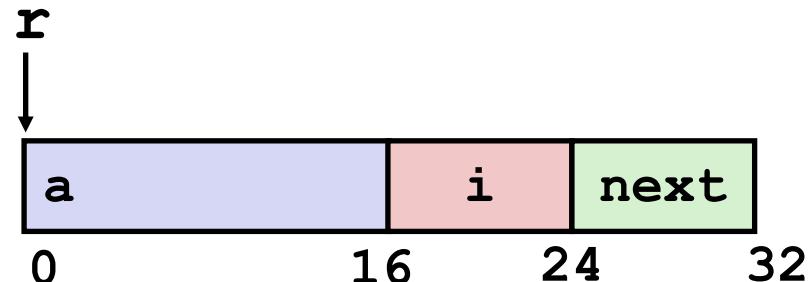
■ Structures

- Allocation
- Access
- Alignment

■ Floating Point

Structure Representation

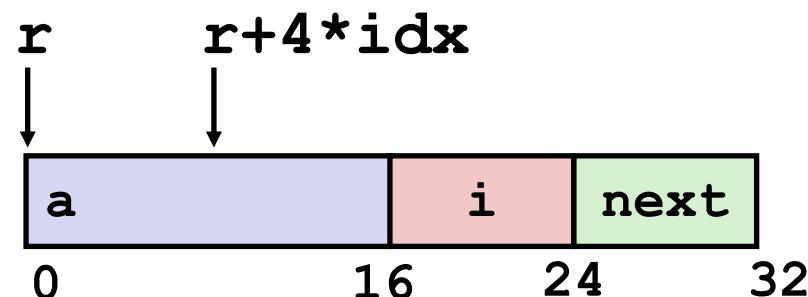
```
struct rec {  
    int a[4];  
    size_t i;  
    struct rec *next;  
};
```



- Structure represented as block of memory
 - Big enough to hold all of the fields
- Fields ordered according to declaration
 - Even if another ordering could yield a more compact representation
- Compiler determines overall size + positions of fields
 - Machine-level program has no understanding of the structures in the source code

Generating Pointer to Structure Member

```
struct rec {
    int a[4];
    size_t i;
    struct rec *next;
};
```



■ Generating Pointer to Array Element

- Offset of each structure member determined at compile time
- Compute as $r + 4*idx$

```
int *get_ap
(struct rec *r, size_t idx)
{
    return &r->a[idx];
}
```

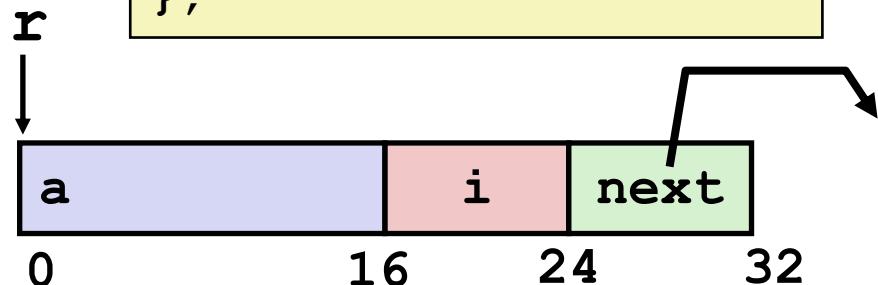
```
# r in %rdi, idx in %rsi
leaq (%rdi,%rsi,4), %rax
ret
```

Following Linked List #1

■ C Code

```
long length(struct rec*r) {
    long len = 0L;
    while (r) {
        len++;
        r = r->next;
    }
    return len;
}
```

```
struct rec {
    int a[4];
    size_t i;
    struct rec *next;
};
```



Register	Value
%rdi	r
%rax	len

■ Loop assembly code

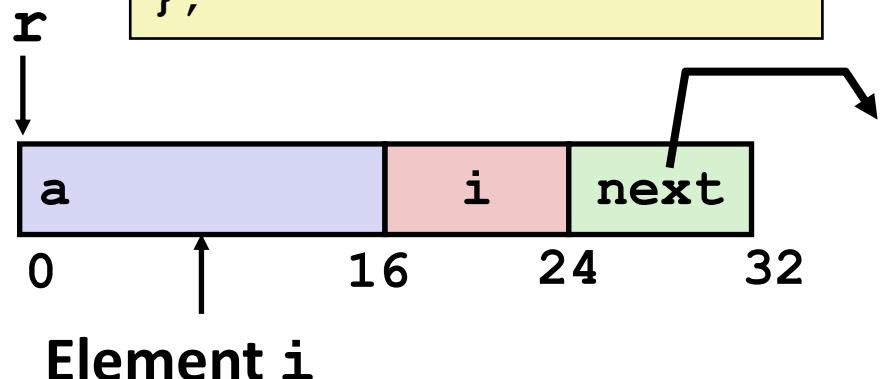
.L11:	# loop:
addq \$1, %rax	# len ++
movq 24(%rdi), %rdi	# r = Mem[r+24]
testq %rdi, %rdi	# Test r
jne .L11	# If != 0, goto loop

Following Linked List #2

■ C Code

```
void set_val
  (struct rec *r, int val)
{
    while (r) {
        size_t i = r->i;
        // No bounds check
        r->a[i] = val;
        r = r->next;
    }
}
```

```
struct rec {
    int a[4];
    size_t i;
    struct rec *next;
};
```

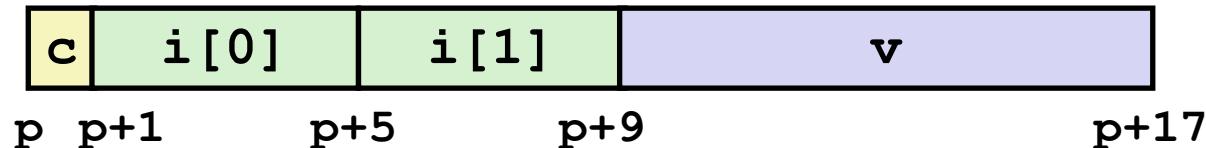


Register	Value
%rdi	r
%rsi	val

.L11: movq 16(%rdi), %rax movl %esi, (%rdi,%rax,4) movq 24(%rdi), %rdi testq %rdi, %rdi jne .L11	# loop: # i = Mem[r+16] # Mem[r+4*i] = val # r = Mem[r+24] # Test r # if !=0 goto loop
--	--

Structures & Alignment

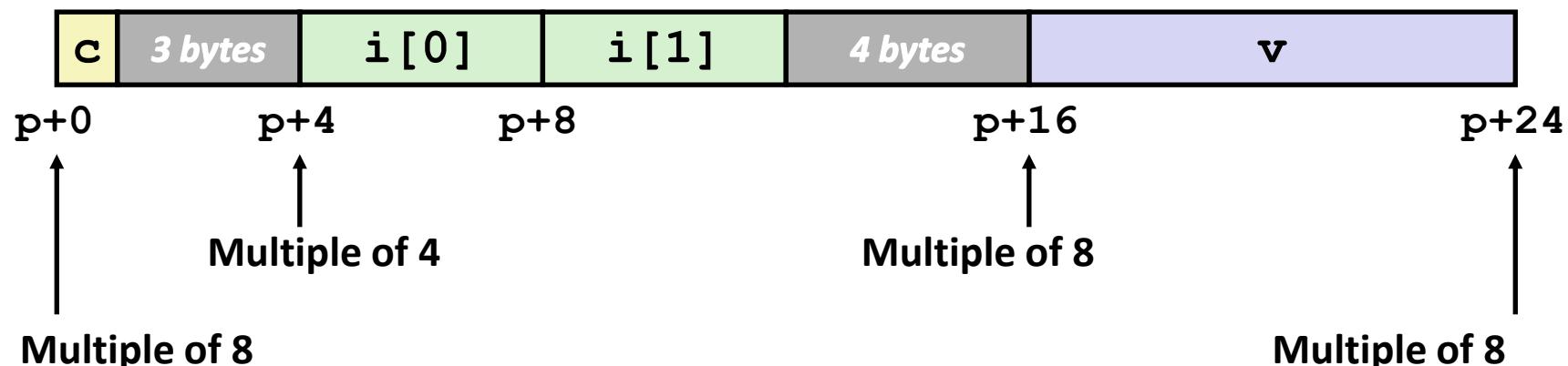
■ Unaligned Data



```
struct S1 {
    char c;
    int i[2];
    double v;
} *p;
```

■ Aligned Data

- Primitive data type requires B bytes implies
Address must be multiple of B



Alignment Principles

■ Aligned Data

- Primitive data type requires B bytes
- Address must be multiple of B
- Required on some machines; advised on x86-64

■ Motivation for Aligning Data

- Memory accessed by (aligned) chunks of 4 or 8 bytes (system dependent)
 - Inefficient to load or store datum that spans cache lines (64 bytes).
Intel states should avoid crossing 16 byte boundaries.

[Cache lines will be discussed in Lecture 11.]

- Virtual memory trickier when datum spans 2 pages (4 KB pages)

[Virtual memory pages will be discussed in Lecture 17.]

■ Compiler

- Inserts gaps in structure to ensure correct alignment of fields

Specific Cases of Alignment (x86-64)

- **1 byte: `char`, ...**
 - no restrictions on address
- **2 bytes: `short`, ...**
 - lowest 1 bit of address must be 0_2
- **4 bytes: `int`, `float`, ...**
 - lowest 2 bits of address must be 00_2
- **8 bytes: `double`, `long`, `char *`, ...**
 - lowest 3 bits of address must be 000_2

Satisfying Alignment with Structures

■ Within structure:

- Must satisfy each element's alignment requirement

■ Overall structure placement

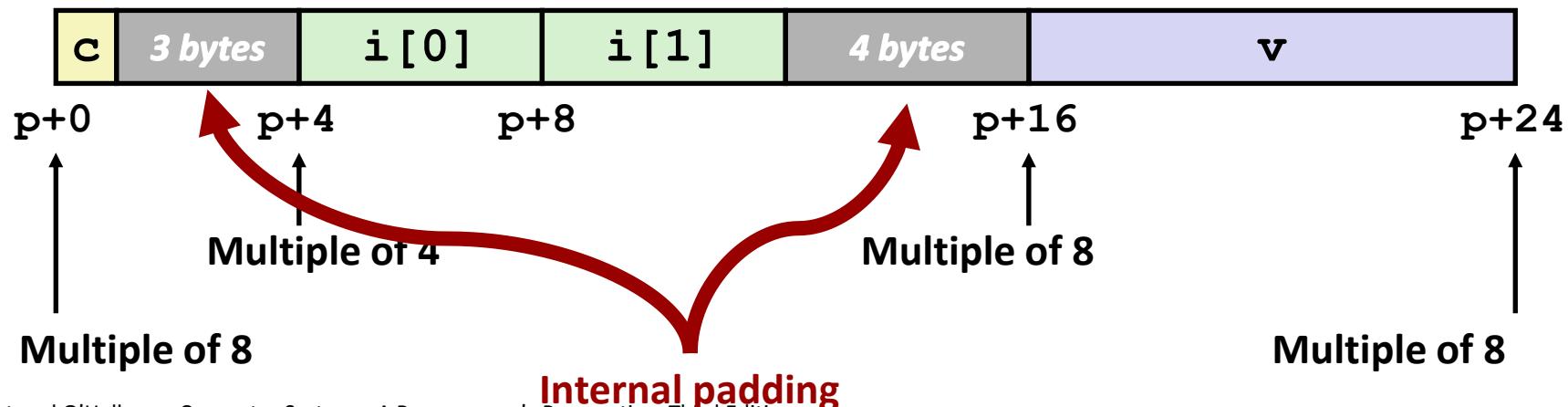
- Each structure has alignment requirement K
 - $K = \text{Largest alignment of any element}$
- Initial address & structure length must be multiples of K

■ Example:

- $K = 8$, due to **double** element

NOTE: $K < \text{sizeof}(\text{struct S1})$

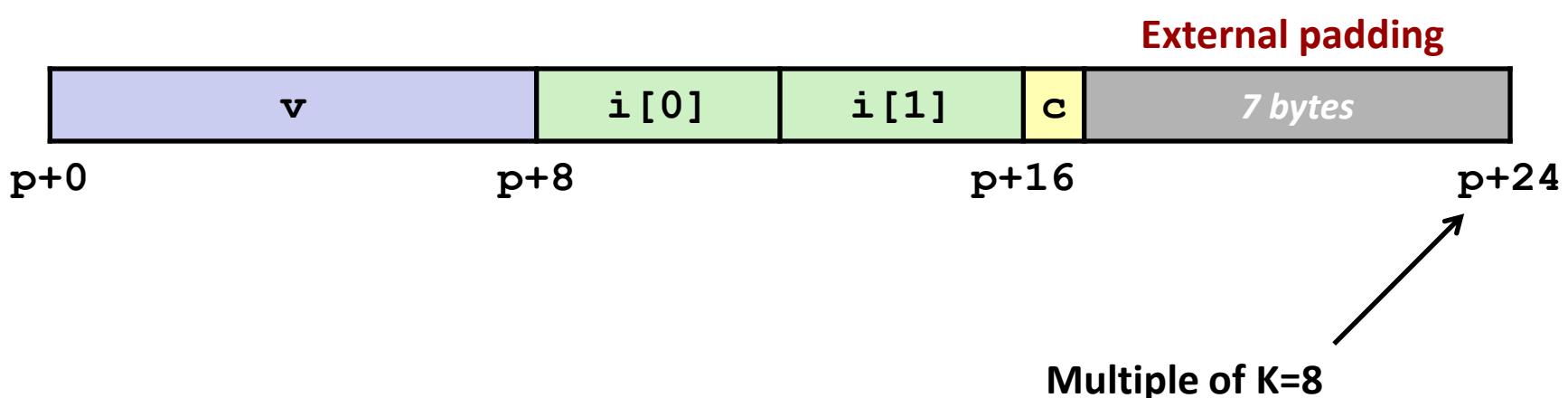
```
struct S1 {
    char c;
    int i[2];
    double v;
} *p;
```



Meeting Overall Alignment Requirement

- For largest alignment requirement K
- Overall structure must be multiple of K

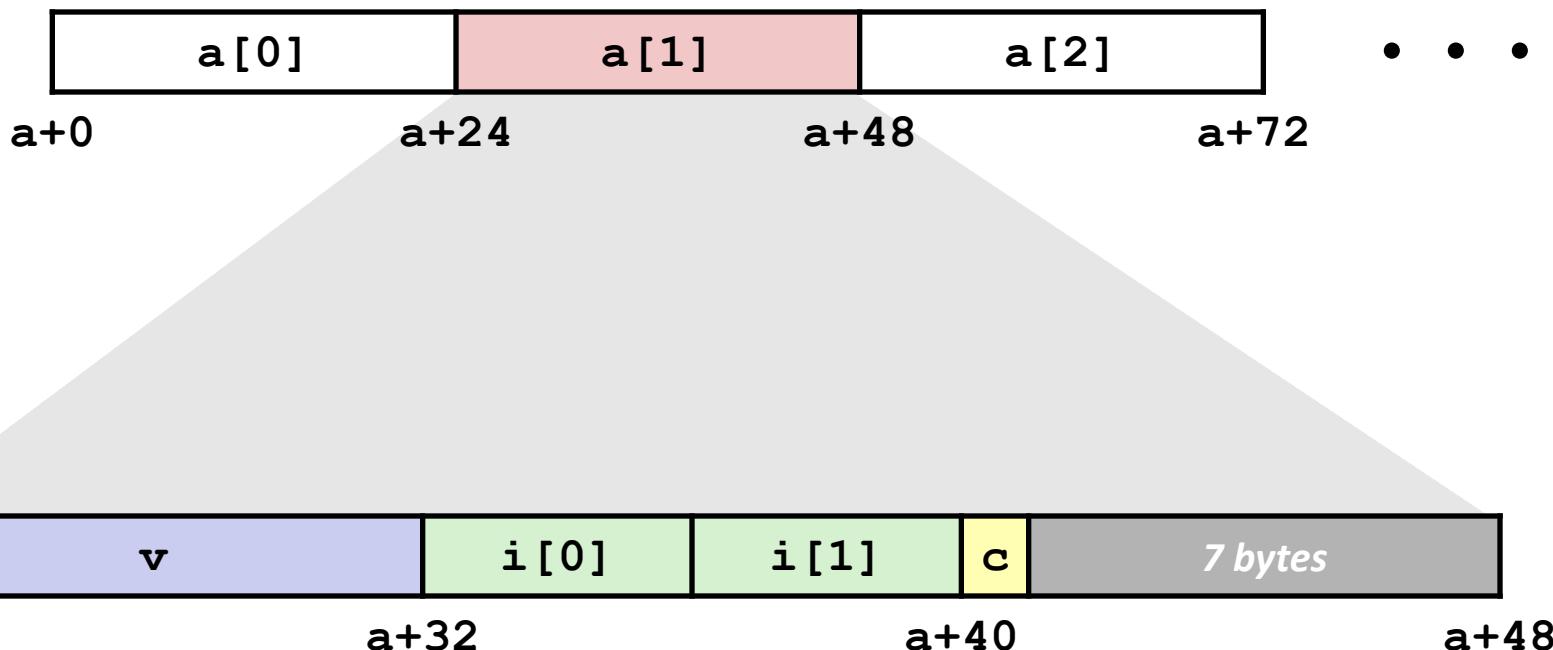
```
struct s2 {  
    double v;  
    int i[2];  
    char c;  
} *p;
```



Arrays of Structures

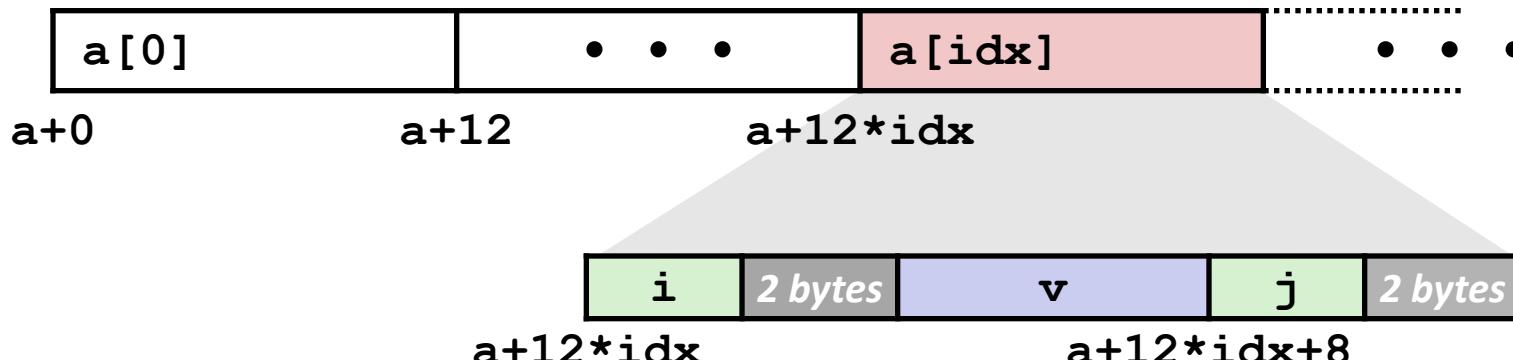
- Overall structure length multiple of K
- Satisfy alignment requirement for every element

```
struct S2 {  
    double v;  
    int i[2];  
    char c;  
} a[10];
```



Accessing Array Elements

- Compute array offset $12 * \text{idx}$
 - `sizeof(S3)`, including alignment spacers
- Element `j` is at offset 8 within structure
- Assembler gives offset `a+8`
 - Resolved during linking



```
short get_j(int idx)
{
    return a[idx].j;
}
```

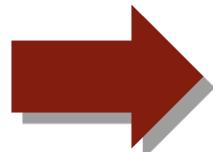
```
# %rdi = idx
leaq (%rdi,%rdi,2),%rax # 3*idx
movzwl a+8(%rax,4),%eax
```

```
struct S3 {
    short i;
    float v;
    short j;
} a[10];
```

Saving Space

- Put large data types first

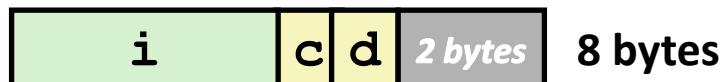
```
struct S4 {  
    char c;  
    int i;  
    char d;  
} *p;
```



```
struct S5 {  
    int i;  
    char c;  
    char d;  
} *p;
```



- Effect (largest alignment requirement K=4)



Activity

Today

■ Arrays

- One-dimensional
- Multi-dimensional (nested)
- Multi-level

■ Structures

- Allocation
- Access
- Alignment

■ Floating Point

Background

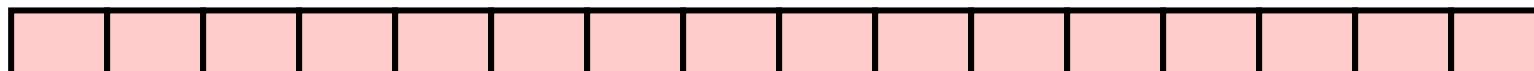
■ History

- x87 FP
 - Legacy, very ugly
- SSE FP
 - Supported by Shark machines
 - Special case use of vector instructions
- AVX FP
 - Newest version
 - Similar to SSE (but registers are 32 bytes instead of 16)
 - Documented in book

Programming with SSE4

XMM Registers

- 16 total, each 16 bytes
- 16 single-byte integers



- 8 16-bit integers



- 4 32-bit integers



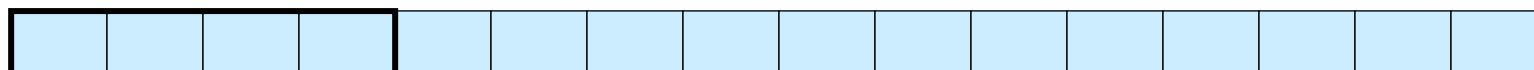
- 4 single-precision floats



- 2 double-precision floats



- 1 single-precision float

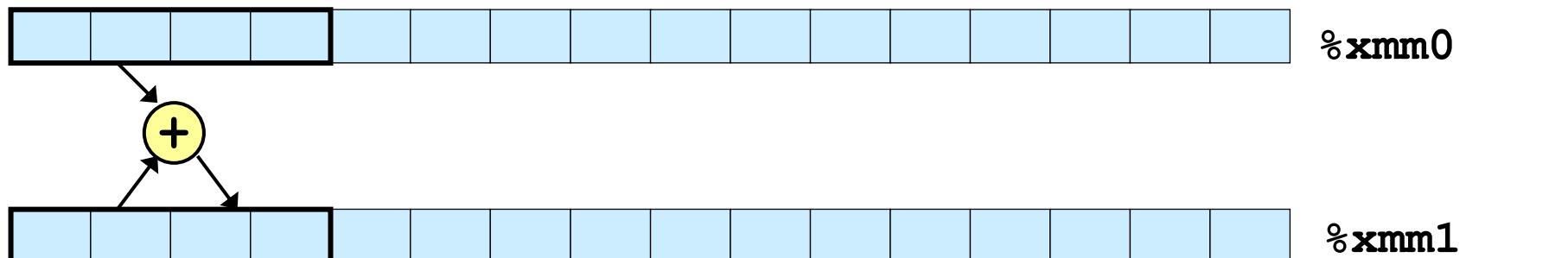


- 1 double-precision float

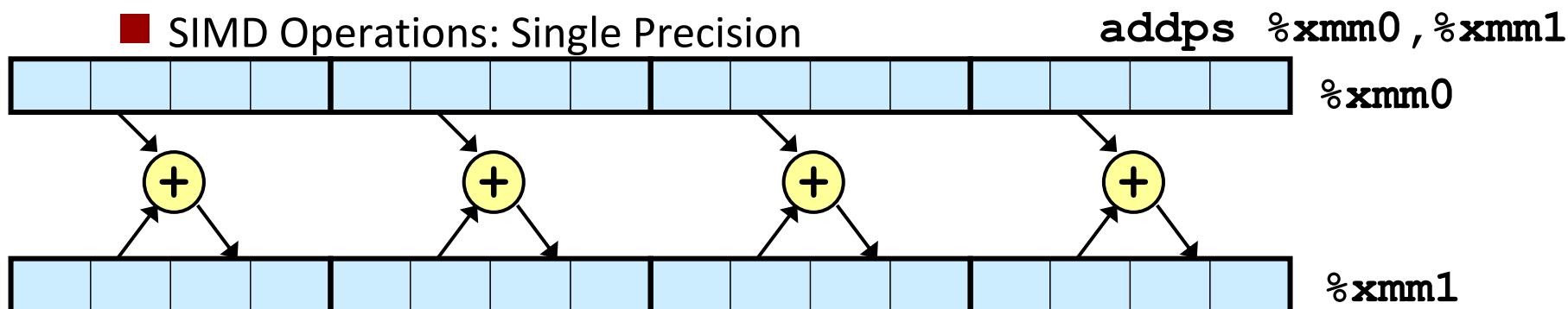


Scalar & SIMD Operations

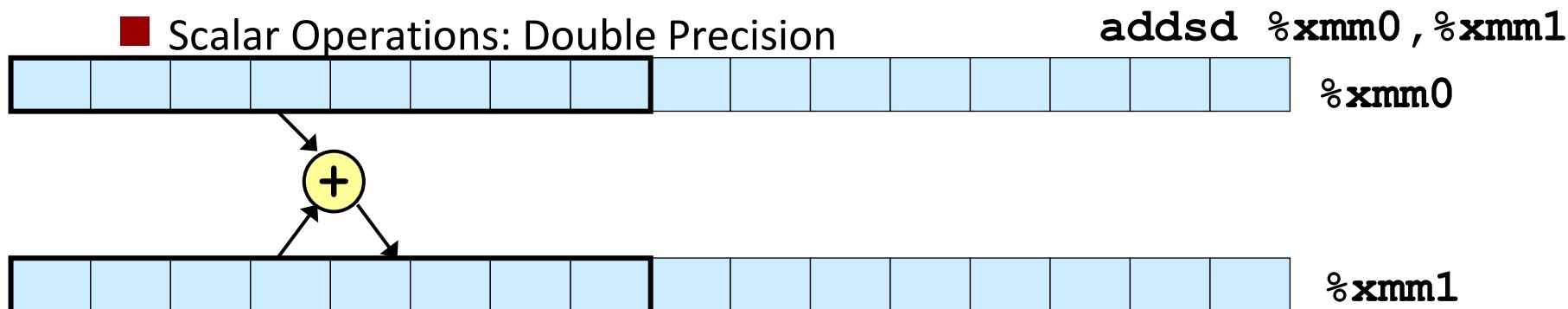
Scalar Operations: Single Precision



SIMD Operations: Single Precision



Scalar Operations: Double Precision



FP Basics

- Arguments passed in %xmm0, %xmm1, ...
- Result returned in %xmm0
- All XMM registers caller-saved

```
float fadd(float x, float y)
{
    return x + y;
}
```

```
double dadd(double x, double y)
{
    return x + y;
}
```

```
# x in %xmm0, y in %xmm1
addss    %xmm1, %xmm0
ret
```

```
# x in %xmm0, y in %xmm1
addsd    %xmm1, %xmm0
ret
```

FP Memory Referencing

- Integer (and pointer) arguments passed in regular registers
- FP values passed in XMM registers
- Different mov instructions to move between XMM registers, and between memory and XMM registers

```
double dincr(double *p, double v)
{
    double x = *p;
    *p = x + v;
    return x;
}
```

```
# p in %rdi, v in %xmm0
movapd  %xmm0, %xmm1    # Copy v
movsd   (%rdi), %xmm0  # x = *p
addsd   %xmm0, %xmm1    # t = x + v
movsd   %xmm1, (%rdi)  # *p = t
ret
```

Other Aspects of FP Code

■ Lots of instructions

- Different operations, different formats, ...

■ Floating-point comparisons

- Instructions **ucomiss** and **ucomisd**
- Set condition codes ZF, PF and CF
- Zeros OF and SF

Parity Flag

UNORDERED: ZF,PF,CF \leftarrow 111
GREATER_THAN: ZF,PF,CF \leftarrow 000
LESS_THAN: ZF,PF,CF \leftarrow 001
EQUAL: ZF,PF,CF \leftarrow 100

■ Using constant values

- Set XMM0 register to 0 with instruction **xorpd %xmm0, %xmm0**
- Others loaded from memory

Summary

■ Arrays

- Elements packed into contiguous region of memory
- Use index arithmetic to locate individual elements

■ Structures

- Elements packed into single region of memory
- Access using offsets determined by compiler
- Possible require internal and external padding to ensure alignment

■ Combinations

- Can nest structure and array code arbitrarily

■ Floating Point

- Data held and operated on in XMM registers