

Synchronization: Advanced

15-213/15-513: Introduction to Computer Systems
25th Lecture, July 27, 2023

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Announcements

- **Proxy lab checkpoint released tomorrow (7/28)**
- **Final exam Aug 10 / 26**

Today

- **Review: Races, Mutual Exclusion**
- Deadlock
- Semaphores, Events, and Queues
- Reader-Writer Locks and Starvation
- Thread-Safe API Design

Races

- A *race* occurs when correctness of the program depends on one thread reaching point x before another thread reaches point y

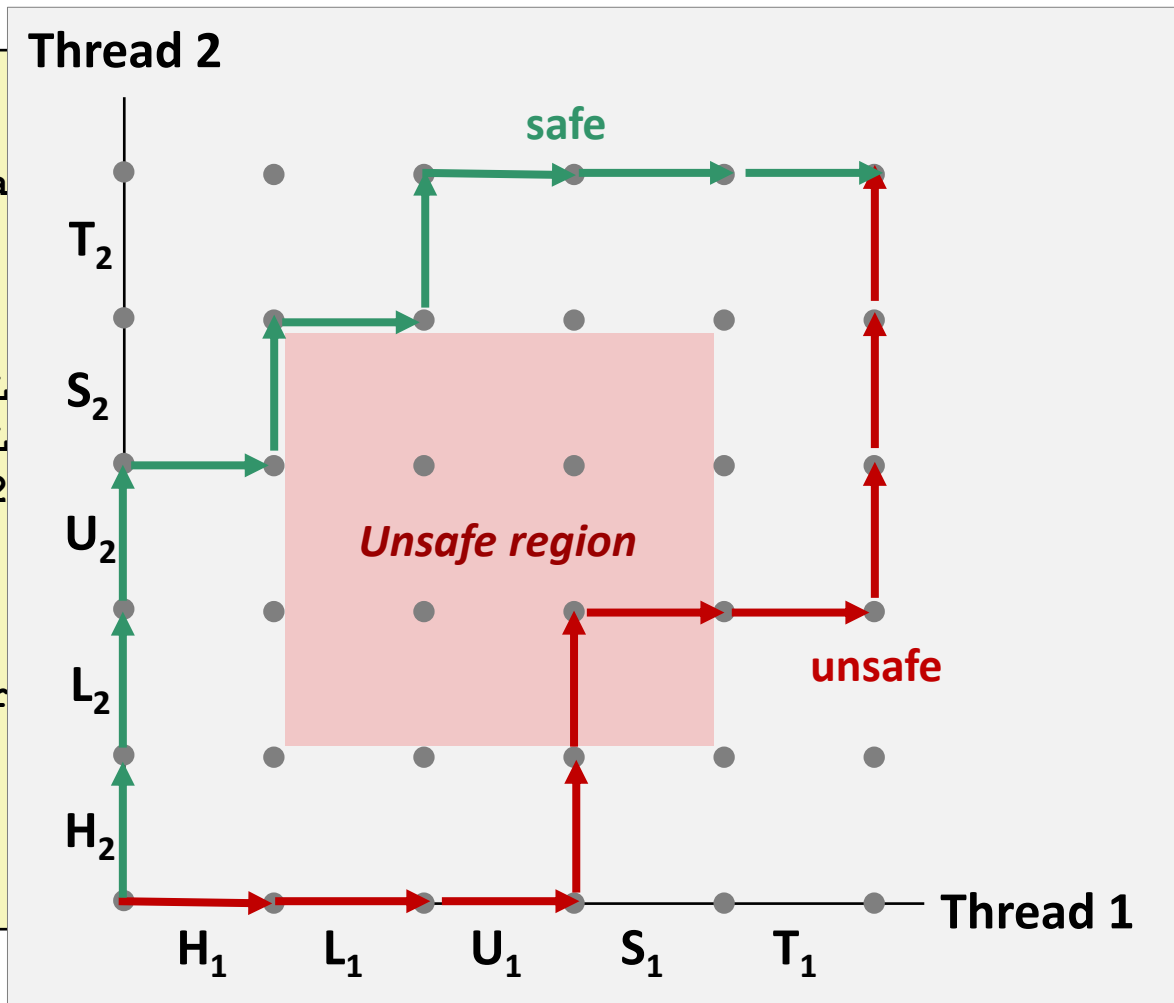
```

int cnt;

int main(int argc, char *argv[]) {
    pthread_t t1, t2;
    pthread_create(&t1, NULL, thread, NULL);
    pthread_create(&t2, NULL, thread, NULL);
    pthread_join(t1, NULL);
    pthread_join(t2, NULL);
    return (cnt != 2);
}

/* thread routine */
void *thread(void *var) {
    for (int i = 0; i < cnt; i++)
        cnt++;
    return NULL;
}

```



Races

- Some races can be fixed with mutual exclusion

```
int cnt;
pthread_mutex_t lock = PTHREAD_MUTEX_INITIALIZER;
int main(int argc, char** argv) {
    pthread_t t1, t2;
    Pthread_create(&t1, NULL, thread, NULL);
    Pthread_create(&t2, NULL, thread, NULL);
    Pthread_join(t1, NULL);
    Pthread_join(t2, NULL);
    return (counter != 20000);
}

void *thread(void *vargp) {
    for (int i = 0; i < 10000; i++) {
        pthread_mutex_lock(&lock);
        cnt++;
        pthread_mutex_unlock(&lock);
    }
    return NULL;
}
```

Races

- Not all races can be addressed with mutual exclusion

```
int main(int argc, char** argv) {
    pthread_t tid[N];
    int i;
    for (i = 0; i < N; i++)
        Pthread_create(&tid[i], NULL, thread, &i);
    for (i = 0; i < N; i++)
        Pthread_join(tid[i], NULL);
    return 0;
}

/* thread routine */
void *thread(void *vargp) {
    int myid = *(int *)vargp;
    printf("Hello from thread %d\n", myid);
    return NULL;
}
```

Races

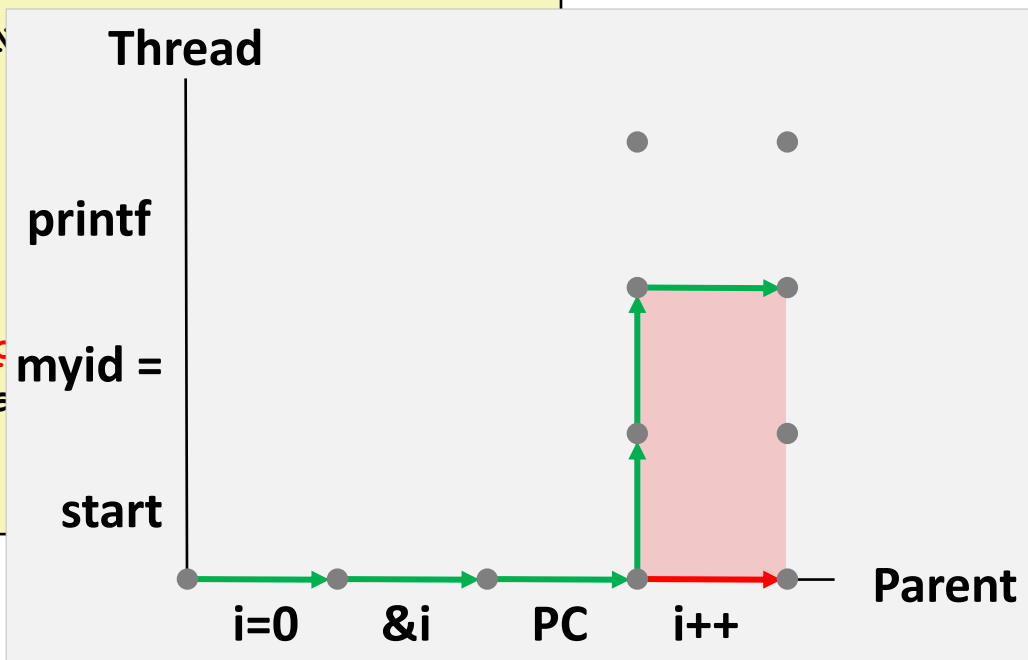
- Not all races can be addressed with mutual exclusion

```

int main(int argc, char** argv) {
    pthread_t tid[N];
    int i;
    for (i = 0; i < N; i++)
        Pthread_create(&tid[i], NULL, thread, &i);
    for (i = 0; i < N; i++)
        Pthread_join(tid[i], NULL);
    return 0;
}

/* thread routine */
void *thread(void *vargp)
{
    int myid = *(int *)vargp;
    printf("Hello from thread %d\n", myid);
    return NULL;
}

```



Races

- This race can be fixed by copying data

```
int main(int argc, char** argv) {
    pthread_t tid[N];
    int i;
    for (i = 0; i < N; i++)
        Pthread_create(&tid[i], NULL, thread, (void *)i);
    for (i = 0; i < N; i++)
        Pthread_join(tid[i], NULL);
    return 0;
}

/* thread routine */
void *thread(void *vargp) {
    int myid = (int)vargp;
    printf("Hello from thread %d\n", myid);
    return NULL;
}
```


Races

- This race can also be fixed with a semaphore

```
sem_t sem;
int main(int argc, char** argv) {
    pthread_t tid[N];
    int i;
    Sem_init(&sem, 0, 0); // initially closed
    for (i = 0; i < N; i++) {
        Pthread_create(&tid[i], NULL, thread, &i);
        sem_wait(&sem);
    }
    for (i = 0; i < N; i++)
        Pthread_join(tid[i], NULL);
    return 0;
}

void *thread(void *vargp) {
    int myid = *(int *)vargp;
    sem_post(&sem);
    printf("Hello from thread %d\n", myid);
    return NULL;
}
```

Not all races involve *threads*

■ Time of check to time of use (TOCTOU)

```

if (access("myfile.txt", R_OK) == 0) {
    FILE *fp = fopen("myfile.txt", "r");
    while (fgets(fp, buf, sizeof buf) != NULL)
        process_line(buf);
    fclose(fp);
} else {
    fprintf(stderr, "myfile.txt not found\n");
}

```

\$ rm myfile.txt

← Check
← Use

■ Fix: *Don't check, just use (but be ready for failure)*

```

FILE *fp = fopen("myfile.txt", "r");
if (fp) {
    while (fgets(fp, buf, sizeof buf) != NULL)
        process_line(buf);
    fclose(fp);
} else {
    fprintf(stderr, "myfile.txt: %s\n", strerror(errno));
}

```

Races involving signal handlers

- Event happens earlier than anticipated

```
void sigchld_handler(int unused) {
    int status;
    pid_t pid;
    while ((pid = waitpid(-1, &status, WNOHANG|WUNTRACED)) > 0)
        job_status_change(pid, status);
}

void start_fg_job(char **argv) {
    pid_t pid = fork();
    if (pid == -1) {
        perror("fork");
        return;
    } else if (pid == 0) {
        execve(argv[0], argv, environ);
        perror("execve");
        exit(127);
    } else {
        add_job(pid, argv);
    }
}
```

SIGCHLD delivered

Race Elimination

- **Don't share state**
 - e.g. use malloc to generate separate copy of argument for each thread
- **Don't check before using**
 - Attempt to use, see if it failed
- **Use synchronization primitives**
 - Which synchronization primitive? Depends on the situation

Today

- Review: Races, Mutual Exclusion
- **Deadlock**
- Semaphores, Events, and Queues
- Reader-Writer Locks and Starvation
- Thread-Safe API Design

Deadlock

- A program is *deadlocked* when it is waiting for an event which *cannot* ever happen
 - Mathematical impossibility, not just practical
- **Most common form:**
 - Thread A is waiting for thread B to do something
 - Thread B is waiting for thread A to do something
 - Neither can make forward progress

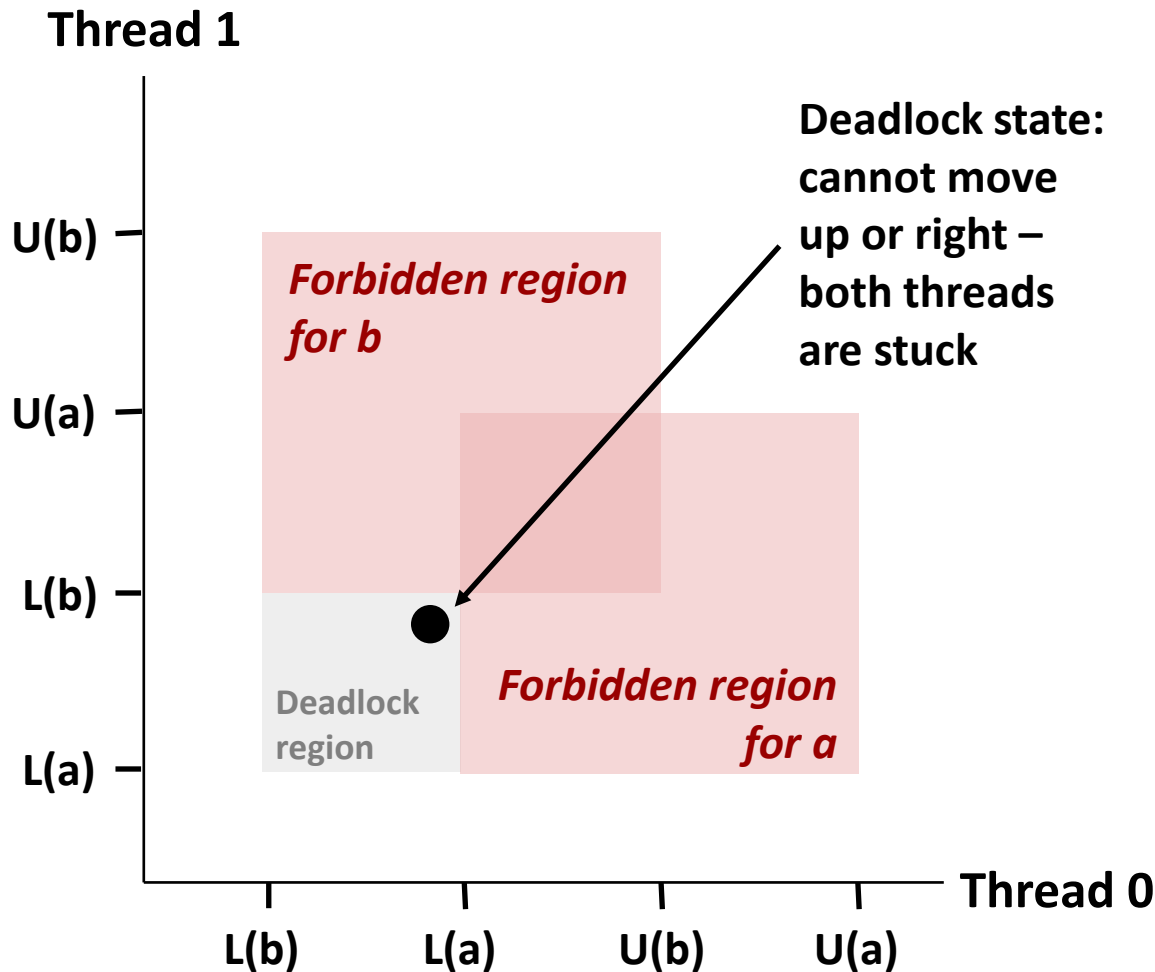


Deadlock caused by wrong locking order

```
void *thread_1(void *arg) {  
    pthread_mutex_lock(&mA);  
    pthread_mutex_lock(&mB);  
  
    // do stuff ...  
  
    pthread_mutex_unlock(&mA);  
    pthread_mutex_unlock(&mB);  
}
```

```
void *thread_2(void *arg) {  
    pthread_mutex_lock(&mB);  
    pthread_mutex_lock(&mA);  
  
    // do stuff ...  
  
    pthread_mutex_unlock(&mB);  
    pthread_mutex_unlock(&mA);  
}
```

Deadlock Visualized in Progress Graph



Any trajectory that enters the **deadlock region** will eventually reach the **deadlock state** where each thread is waiting for the other to release a lock

Other trajectories luck out and skirt the deadlock region

Unfortunate fact: trajectory variations may mean deadlock bugs are nondeterministic (don't always manifest, making them hard to debug)

Fix *this* deadlock with consistent ordering

```
void *thread_1(void *arg) {
    pthread_mutex_lock(&mA);
    pthread_mutex_lock(&mB);

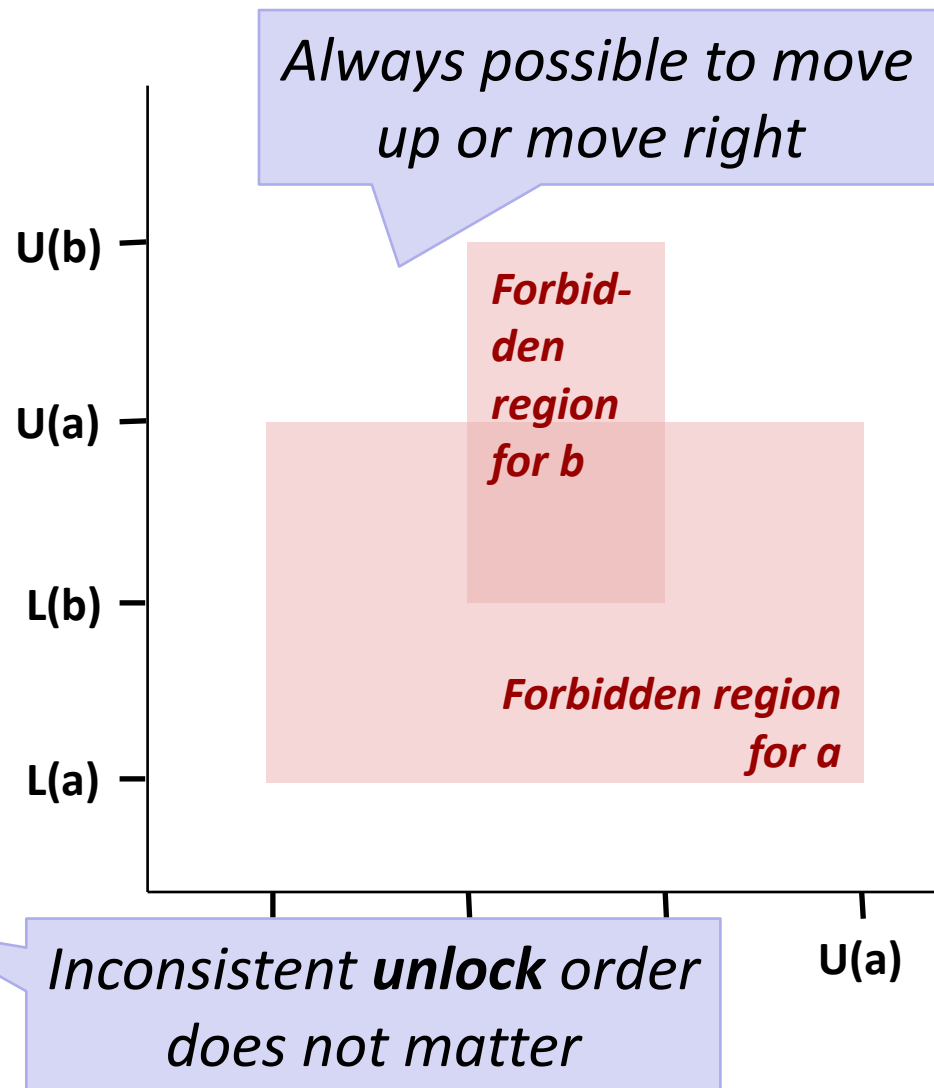
    // do stuff ...

    pthread_mutex_unlock(&mA);
    pthread_mutex_unlock(&mB);
}
```

```
void *thread_2(void *arg) {
    pthread_mutex_lock(&mA);
    pthread_mutex_lock(&mB);

    // do stuff ...

    pthread_mutex_unlock(&mB);
    pthread_mutex_unlock(&mA);
}
```



Today

- Review: Races, Mutual Exclusion
- Deadlock
- **Semaphores, Events, and Queues**
- Reader-Writer Locks and Starvation
- Thread-Safe API Design

Recall: Semaphores

- Integer value, always ≥ 0
- **P(s) operation (aka `sem_wait`)**
 - If s is zero, wait for a V operation to happen.
 - Then subtract 1 from s and return.
- **V(s) operation (aka `sem_post`)**
 - Add 1 to s .
 - If there are any threads waiting inside a P operation, resume one of them
- **Any thread may call P; any thread may call V; no ordering requirements**
 - Key difference from mutexes

Semaphores for Events

- Remember this program from Tuesday's quiz?

```
#define N 4
long *pointers[N];

void *thread(void *vargp) {
    long myid = (long) vargp;
    pointers[myid] = &myid;
    sleep(2);
    return NULL;
}
```

```
int main(void) {
    long i;
    pthread_t tids[N];

    for (i = 0; i < N; i++)
        Pthread_create(&tids[i], NULL,
                       thread, (void *) i);
    sleep(1);
    for (i = 0; i < N; i++)
        printf("Thread #%ld has "
              "local value %ld\n",
              i, *pointers[i]);
    for (i = 0; i < N; i++)
        Pthread_join(tids[i], NULL);
    return 0;
}
```

- Let's fix it.
- With semaphores.

Semaphores for Events

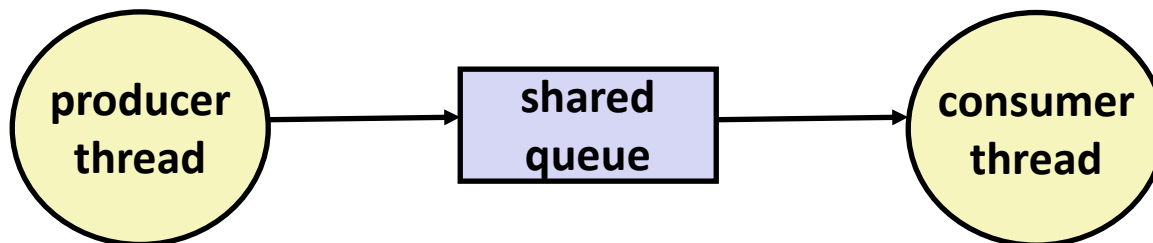
```
#define N 4
long *pointers[N];
sem_t ready[N];
sem_t finish;

void *thread(void *vargp) {
    long myid = (long) vargp;
    pointers[myid] = &myid;
    sem_post(&ready[myid]);
    sem_wait(&finish);
    return NULL;
}
```

```
int main(void) {
    long i;
    pthread_t tids[N];

    Sem_init(&finish, 0, 0);
    for (i = 0; i < N; i++) {
        Sem_init(&ready[i], 0, 0);
        Pthread_create(&tids[i], NULL,
            thread, (void *) i);
    }
    for (i = 0; i < N; i++) {
        sem_wait(&ready[i]);
        printf("Thread #%ld has "
            "local value %ld\n",
            i, *pointers[i]);
    }
    for (i = 0; i < N; i++)
        sem_post(&finish);
    for (i = 0; i < N; i++)
        Pthread_join(tids[i], NULL);
    return 0;
}
```

Queues, Producers, and Consumers



■ Common synchronization pattern:

- Producer waits for empty *slot*, inserts item in queue, and notifies consumer
- Consumer waits for *item*, removes it from queue, and notifies producer

■ Examples

- Multimedia processing:
 - Producer creates video frames, consumer renders them
- Event-driven graphical user interfaces
 - Producer detects mouse clicks, mouse movements, and keyboard hits and inserts corresponding events in queue
 - Consumer retrieves events from queue and paints the display

Producer-Consumer on 1-entry Queue

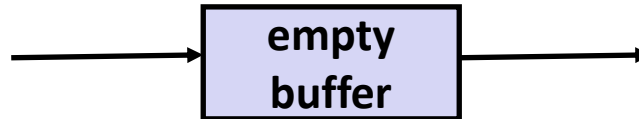
- Maintain two semaphores: `full` + `empty`

`full`

0

`empty`

1



`full`

1

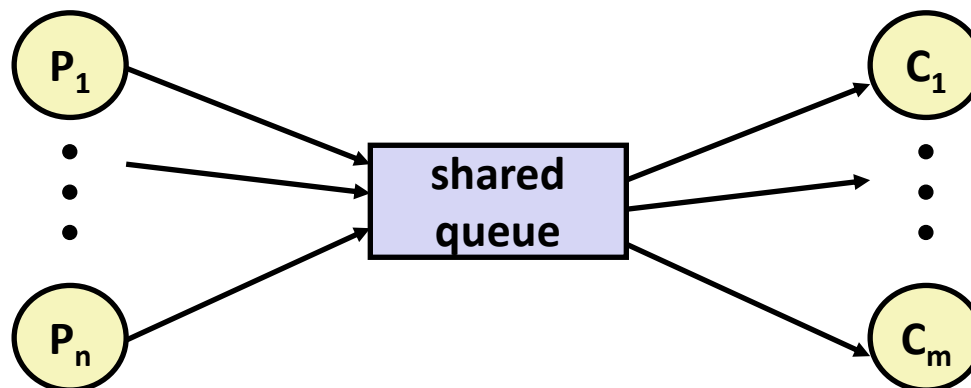
`empty`

0



Why 2 Semaphores for 1-entry Queue?

- Consider multiple producers & multiple consumers



- Producers will contend with each to get **empty**
- Consumers will contend with each other to get **full**

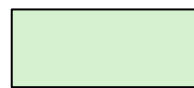
Producers

```
P(&shared.empty);
shared.buf = item;
V(&shared.full);
```

empty



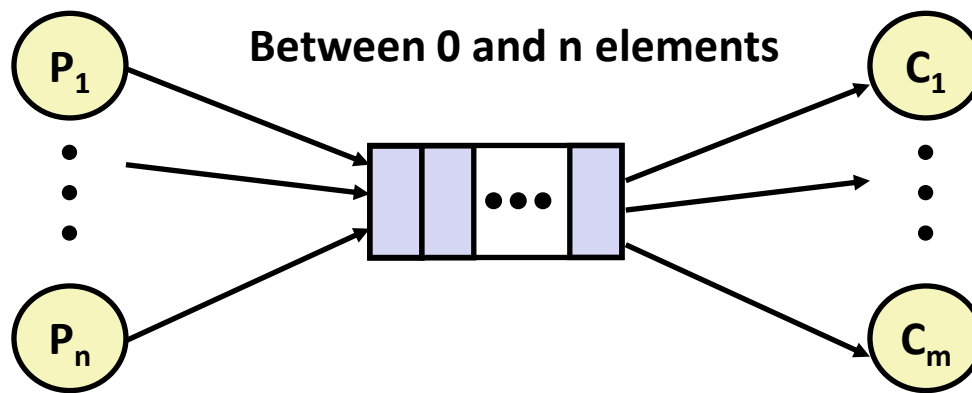
full



Consumers

```
P(&shared.full);
item = shared.buf;
V(&shared.empty);
```


Producer-Consumer on n -element Queue

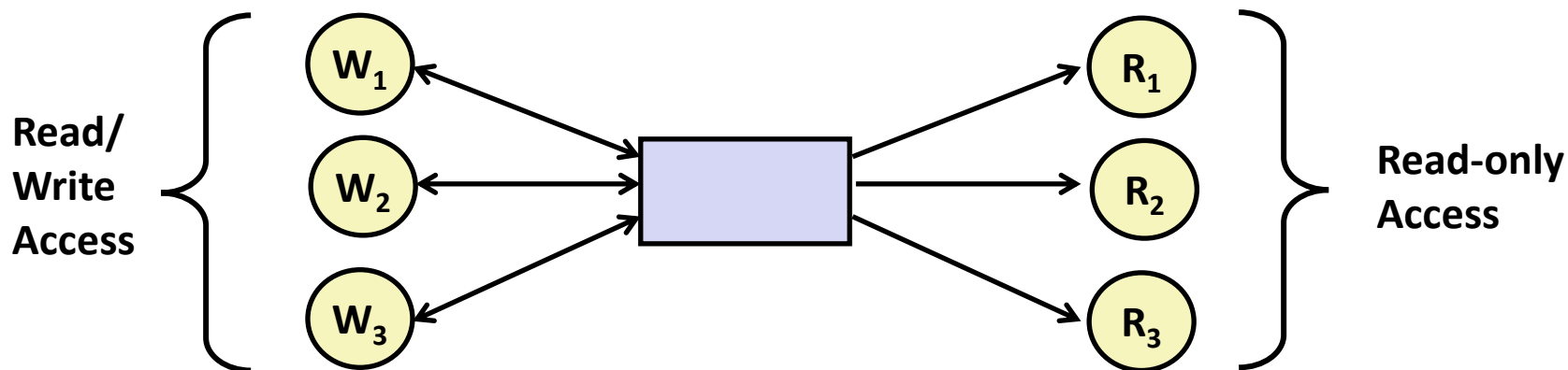


- **Requires a mutex and two counting semaphores:**
 - `mutex`: enforces mutually exclusive access to the queue's innards
 - `slots`: counts the available slots in the queue
 - `items`: counts the available items in the queue
- **Makes use of semaphore values > 1 (up to n)**

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- **Reader-Writer Locks and Starvation**
- Thread-Safe API Design

Readers-Writers Problem



■ Problem statement:

- *Reader* threads only read the object
- *Writer* threads modify the object (read/write access)
- Writers must have exclusive access to the object
- Unlimited number of readers can access the object

■ Occurs frequently in real systems, e.g.,

- Online airline reservation system
- Multithreaded caching Web proxy

Pthreads Reader/Writer Lock

- Data type `pthread_rwlock_t`

- Operations

- Acquire read lock

```
pthread_rwlock_rdlock(pthread_rwlock_t *rwlock)
```

- Acquire write lock

```
pthread_rwlock_wrlock(pthread_rwlock_t *rwlock)
```

- Release (either) lock

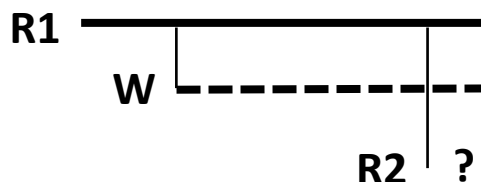
```
pthread_rwlock_unlock(pthread_rwlock_t *rwlock)
```

- **Must be used correctly!**

- Up to programmer to decide what requires read access and what requires write access

Reader/Writer Starvation

- Thread 1 has a read lock. Thread 2 is waiting for a write lock. Thread 3 tries to take a read lock. What happens?



- Option 1: R2 gets read lock immediately**

- Endless stream of overlapping readers → W waits forever



- Option 2: Writer always gets lock as soon as possible**

- Endless stream of overlapping writers → readers wait forever



Starvation

- A thread is *starved* when it makes no forward progress for an unacceptably long time
 - Unlike deadlock, it's possible for it to get unstuck eventually
 - “Unacceptably long” depends on the application
- Algorithms that guarantee no starvation are called *fair*
 - Fair R/W locks: every waiter receives the lock in first-come first-served order (several readers can receive the lock at the same time)



- Fairness is more complicated to implement
- Fairness can mean *all* threads are slower than they would be in an unfair system (e.g. “lock convoy problem”)

Quiz

<https://canvas.cmu.edu/courses/34989/quizzes/103049>

Today

- Review: Races, Mutual Exclusion
- Deadlock
- Semaphores, Events, and Queues
- Reader-Writer Locks and Starvation
- **Thread-Safe API Design**

Thread-Safe APIs

- A function is *thread-safe* if it always produces correct results when called repeatedly from multiple concurrent threads.

- **Reasons for a function *not* to be thread-safe:**
 1. Internal shared state, no locking (e.g. your `malloc`)
 2. Internal state modified across multiple uses (e.g. `rand`)
 3. Returns a pointer to a static variable (e.g. `strtok`)
 4. Calls a function that does any of the above

Thread-Unsafe Functions (Class 1)

- These functions *would* be thread-safe if they began with `pthread_mutex_lock (&L)` and ended with `pthread_mutex_unlock (&L)` for some lock L
- **Good example: `malloc`, `realloc`, `free`**
 - Your implementation will crash if called from multiple concurrent threads
 - The C library's implementation won't; it has internal locks
- **Locking slows things down, of course**

Thread-Unsafe Functions (Class 2)

- **Relying on persistent state across multiple function invocations**
 - Example: Random number generator that relies on static state

```
static unsigned int next = 1;

/* rand: return pseudo-random integer on 0..32767 */
int rand(void) {
    next = next*1103515245 + 12345;
    return (unsigned int)(next/65536) % 32768;
}

/* srand: set seed for rand() */
void srand(unsigned int seed) {
    next = seed;
}
```

- **Difference from class 1: locking would not fix the problem**
 - 2 threads call rand() simultaneously, both get different results than if only one made a sequence of calls to rand()

Fixing Class 2 Thread-Unsafe Functions

- Pass state as part of argument
 - and, thereby, eliminate static state

```
/* rand_r - return pseudo-random integer on 0..32767 */  
  
int rand_r(int *nextp)  
{  
    *nextp = *nextp*1103515245 + 12345;  
    return (unsigned int)(*nextp/65536) % 32768;  
}
```

- Requires API change
- Callers responsible for allocating space for state

Thread-Unsafe Functions (Class 3)

- Returning a pointer to a static variable
- Like class 2, locking inside function would not help
 - Race between *use of result* and calls from another thread
- Fix: make caller supply space for result
 - Requires API change (also like class 2)
 - Can be awkward for caller: how much space is required?

```
/* Convert integer to string */  
char *itoa(int x)  
{  
    static char buf[11];  
    sprintf(buf, "%d", x);  
    return buf;  
}
```

```
/* Convert integer to string  
   (thread-safe) */  
void itoa_r(int x, char *buf,  
            size_t bufsz)  
{  
    sprintf(buf, buf, bufsz, "%d", x);  
}
```

Thread-Unsafe Functions (Class 4)

■ Calling thread-unsafe functions

- Any function that uses a class 1, 2, or 3 function internally is just as thread-unsafe as that function itself
- This applies transitively

■ Only fix is to modify the function to use only thread-safe functions

- This may or may not involve API changes

Thread-Safe Library Functions

- **Most ISO C library functions are thread-safe**
 - Examples: `malloc`, `free`, `printf`, `scanf`
 - Exceptions: `strtok`, `rand`, `asctime`, ...
- **Many older Unix C library functions are unsafe**
 - There is usually a safe replacement

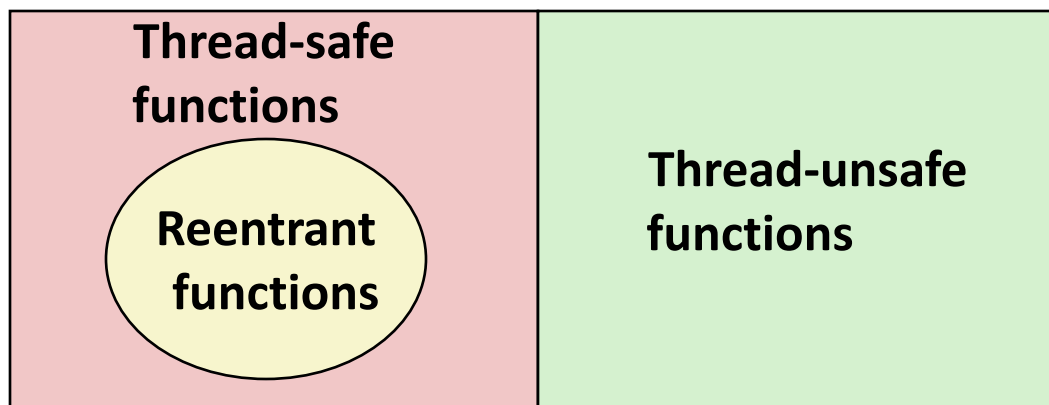
Thread-unsafe function	Class	Reentrant version
<code>asctime</code>	3	<code>strftime</code>
<code>ctime</code>	3	<code>strftime</code>
<code>localtime</code>	3	<code>strftime</code>
<code>gethostbyname</code>	3	<code>getaddrinfo</code>
<code>gethostbyaddr</code>	3	<code>getnameinfo</code>
<code>inet_ntoa</code>	3	<code>getnameinfo</code>
<code>rand</code>	2	<code>rand_r*</code>

* *The C library's random number generators are all old and not very "strong". Use a modern CSPRNG instead.*

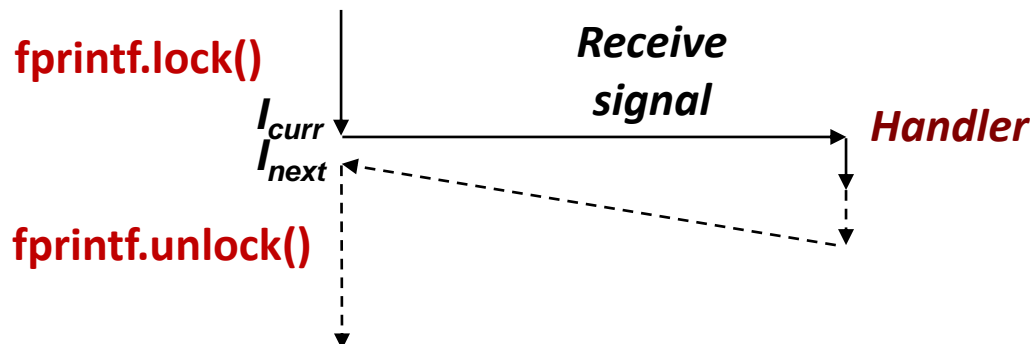
Reentrant Functions

- Def: A function is *reentrant* if it accesses no shared variables when called by multiple threads.
 - Important subset of thread-safe functions
 - Require no synchronization operations
 - Only way to make a Class 2 function thread-safe is to make it reentrant (e.g., `rand_r`)

All functions

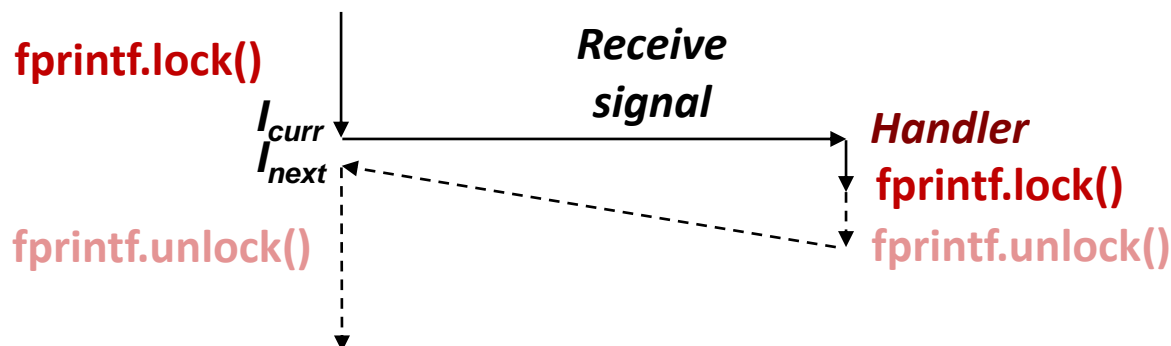


Threads / Signals Interactions



- **Many library functions use lock-and-copy for thread safety**
 - malloc
 - Free lists
 - fprintf, printf, puts
 - So that outputs from multiple threads don't interleave
 - snprintf
 - Calls malloc internally for scratch space
- **OK to interrupt them with locks held**
 - ... as long as the handler doesn't use them itself!

Bad Thread / Signal Interactions



■ What if:

- Signal received while library function holds lock
- Handler calls same (or related) library function

■ Deadlock!

- Signal handler cannot proceed until it gets lock
- Main program cannot proceed until handler completes

■ Key Point

- Threads employ symmetric concurrency
- Signal handling is asymmetric