Coordinate Transformations in Parietal Cortex

Computational Models of Neural Systems Lecture 7.1

David S. Touretzky November, 2019

Outline

- Anderson: parietal cells represent locations of visual stimuli.
- Zipser and Anderson: a backprop network trained to do parietallike coordinate transformations produces neurons whose responses look like parietal cells.
- Pouget and Sejnowski: the brain must transform between multiple coordinate systems to generate reaching to a visual target.
- A model of this transformation can be used to reproduce the effects of parietal lesions (hemispatial neglect).

The Parietal Lobe





Inferior Parietal Lobule

- Four sections of IPL (inferior parietal lobule):
 - 7a: visual, eye position
 - 7b: somatosensory, reaching
 - MST: visual motion, smooth pursuit
 - medial superior temporal area
 - 19/37/39 boundary in humans
 - V5a in monkeys
 - LIP: visual & saccade-related
 - lateral intra-parietal area



Monkey and Human Parietal Cortex



Computational models of meanar objecting

Inferior Parietal Lobule

- Posterior half of the posterior parietal cortex.
- Area 7a contains both visual and eye-position neurons.
- Non-linear interaction between retinal position and eye position.
 - Model this as a function of eye position <u>multiplied</u> by the retinal receptive field.
- No eye-position-independent coding in this area.



Computational Models of Neural Systems

Results from Recording in Area 7a (Anderson)

- Awake, unanesthetized monkeys shown points of light
- 15% eye position only
- 21% visual stimulus (retinal position) only
- 57% respond to a combination of eye position and stimulus
- Most cells have spatial gain fields; mostly planar
- Approx. 80% of eye-position gain fields are planar

Spatial Gain Fields



Spatial Gain Fields of 9 Neurons

- Cells b,e,f:
 - Evoked and background activity co-vary
- Cells a,c,d:
 - Background is constant
- Cells g,h,i:
 - Evoked and background activities are non-planar, but total activity is planar

a \odot \odot (\cdot) ٠ (•) ۲ 0 \odot \odot \odot 0 ′⊙ \odot Θ (\bullet) 0 0 ø

Types of Gain Fields



Computational Models of Neural Systems



Computational Models of Neural Systems

Simulation Details

- Three layer backprop net with sigmoid activation function
- Inputs: pairs of retinal position + eye position
- Desired output: stimulus position in head-centered coords.
- 25 hidden units
- ~ 1000 training patterns
- Tried two different output formats:
 - 2D Gaussian output
 - Monotonic outputs with positive and negative slopes

Hidden Unit Receptive Fields



Computational Models of Neural Systems

Real and Simulated Spatial Gain Fields



Computational Models of Neural Systems

Summary of Simulation Results

- Hidden unit receptive fields sort of look like the real data.
- All total-response gain fields were planar.
 - In the real data, 80% were planar
- With monotonic output, 67% of visual response fields planar
- With Gaussian output, 13% of visual response fields planar
- Real data: 55% of visual response fields planar
- Maybe monkeys use a combination of output functions?
- Pouget & Sejnowski: sampling a sigmoid function at 9 grid points can make it <u>appear</u> planar. Might be a sigmoid.

Discussion

- Note that the model is not topographically organized.
- The input and output encodings were not realistic, but the hidden layer does resemble the area 7a representation.
- Where does the model's output layer exist in the brain?
 - Probably in areas receiving projections from 7a.
 - Eye-position-independent (i.e., head-centered) coordinates will probably be hard to find, and may not exist at a single cell.
 - Cells might only be independent over a certain range.
- Prism experiments lead to rapid recalibration in adult humans, so the coordinate transformation should be plastic.

Pouget & Sejnowski: Synthesizing Coordinate Systems

- The brain requires multiple coordinate systems in order to reach to a visual target.
- Does it keep them all separate?
- These coordinate systems can all be synthesized from an appropriate set of basis functions.
- Maybe that's what the brain actually represents.



Basis Functions

- Any non-linear function can be approximated by a linear combination of <u>basis functions</u>.
- With an infinite number of basis functions you can synthesize any function.
- But often you only need a small number.
- Pouget & Sejnowski: use the <u>product</u> of gaussian and sigmoid functions as basis functions.
 - Retinotopic map encoded as a gaussian
 - Eye position encoded as a sigmoid

Gausian-Sigmoid Basis Function



Computational Models of Neural Systems

Coordinate Transformation Network



Computational Models of Neural Systems



Can derive either head-centered or retinotopic representations from the same set of basis functions. The model used 121 basis functions.

Summary of the Model

- Not a backprop model.
 - Input-to-hidden layer is fixed set of nonlinear basis functions
 - Output units are linear; can train with Widrow-Hoff (LMS algorithm)
- Less training required than for Zipser & Anderson, but model uses more hidden nodes.
- Assume sigmoid coding of eye position, unlike Zipser & Anderson who use a linear (planar) encoding.
 - But sigmoidal units can look planar depending on how they're measured.

Evidence for Saturation (Non-Linearity)

• Cells **B** and **C** show saturation, supporting the use of sigmoid rather than linear activation functions for eye position.









Sigmoidal Units Can Still Appear Planar







Map Representations

- Alternative to spatial gain fields idea.
- Localized "receptive fields", but in headcentered coordinates instead of retinal coordinates.
- Not common, but some evidence in VIP (ventral intraparietal area).



Vector Direction Representations

- Unit's response is the projection of stimulus vector A along the units' preferred direction: dot product.
- Units are therefore linear in a_x and a_y ; response to angle θ_A is a cosine function.
- 20% of real parietal neurons were non-linear.
- Motor cortex appears to use this vector representation to encode reaching direction.



Hemispatial Neglect

- Caused by posterior parietal lobe lesion (typically stroke).
- Can also be induced by TMS.
- Patient can't properly integrate body position information with visual input.



Copies of a clock and a daisy

Line Bisection Task



Artist's Rendition of Left Hemisphere Neglect (Depict Impaired Attention as Loss of Resolution)



Retinotopic Neglect Modulated By Egocentric Position



Computational Models of Neural Systems

30

Stimulus-Centered Neglect



Note that target **x** is in same retinal position in C1 vs. C2. Only the distractors have moved.

Computational Models of Neural Systems

Pouget & Sejnowski Model of Neglect

- Parietal cortex representations are biased toward the contralateral side.
- Similar model to previous paper, but...
- Neglect simulated by biasing the basis functions to favor right-side retinotopic and eye positions, simulating a right side parietal lesion (loss of left side representation).



Selection Mechanism

- Present the model with two simultaneous stimuli, causing two hills of activity in the output layers.
- Select the most active hill as the response. Zero the activities of those units to cause the model to move on. Allow them to slowly recover.



Simulation Results

- Right side stimuli are selected and activation set to zero.
- But stimuli eventually recover and are selected again.
- Left side stimuli have poor representations and are frozen out.



Simulation Results



Simulation Results



Discussion

- Neglect patients show a mixture of retinotopic, head-centered, trunk-centered, and object-centered effects.
- This argues for a representation that combines multiple types of information.
 - Damage to that area could explain the mixture of effects.
- The proposed parietal basis function representation encodes information in a way that allows any desired reference frame to be extracted by a simple linear output layer.
- Tradeoff: to encode more information, the basis functions must be more complex.
 - And you need more of them.
 - And decoding becomes more complex (even if linear).

Coordination of Saccades and Reaching

- Doe eye movements and reaching movements use independent spatial representations?
- Dean et al. (*Neuron,* 2012): if so, then reaction times should be uncorrelated. What do the data show?



Monkeys Performing (Reach and) Saccade Tasks



- Baseline: fixate and touch red/green start marker.
- Yellow target flashed briefly.
- Delay period.
- Go signal: red/green marker disppears. Monkey saccades and reaches to remembered target position.
- Target reappears; monkey must hold for 300 msec.
- Reward delivered.

Results

- During Reach & Saccade tasks, LIP cells whose spiking was coherent with the local beta rhythm (15 Hz) were predictive of both saccade reaction time (SRT) and reach reaction time (RRT).
- Lower beta power = faster reaction times.
- Cells whose spiking was not coherent with the beta rhythm did not correlate with SRT or RRT.
- In the pure Saccade task, there was no correlation between beta power and SRT.



Results (cont.)



Beta-coherent cells predicted RT <u>only</u> in the saccade+reaching trials, not in the pure saccade trials.

Computational Models of Neural Systems