Announcements

Assignments

- HW3
  - Mon, 9/28, 11:59 pm

Midterm 1

- Mon, 10/5
- See Piazza for details
- Fill out swap-section / conflict form by Friday

Plan

Last time

- Regression
- Linear regression
- Optimization for linear regression

Today

- Optimization for linear regression
  - Linear and convex function
  - (Batch) Gradient descent
  - Closed-form solution
  - Stochastic gradient descent

Introduction to Machine Learning

Linear Regression and Optimization

Instructor: Pat Virtue

Linear Regression

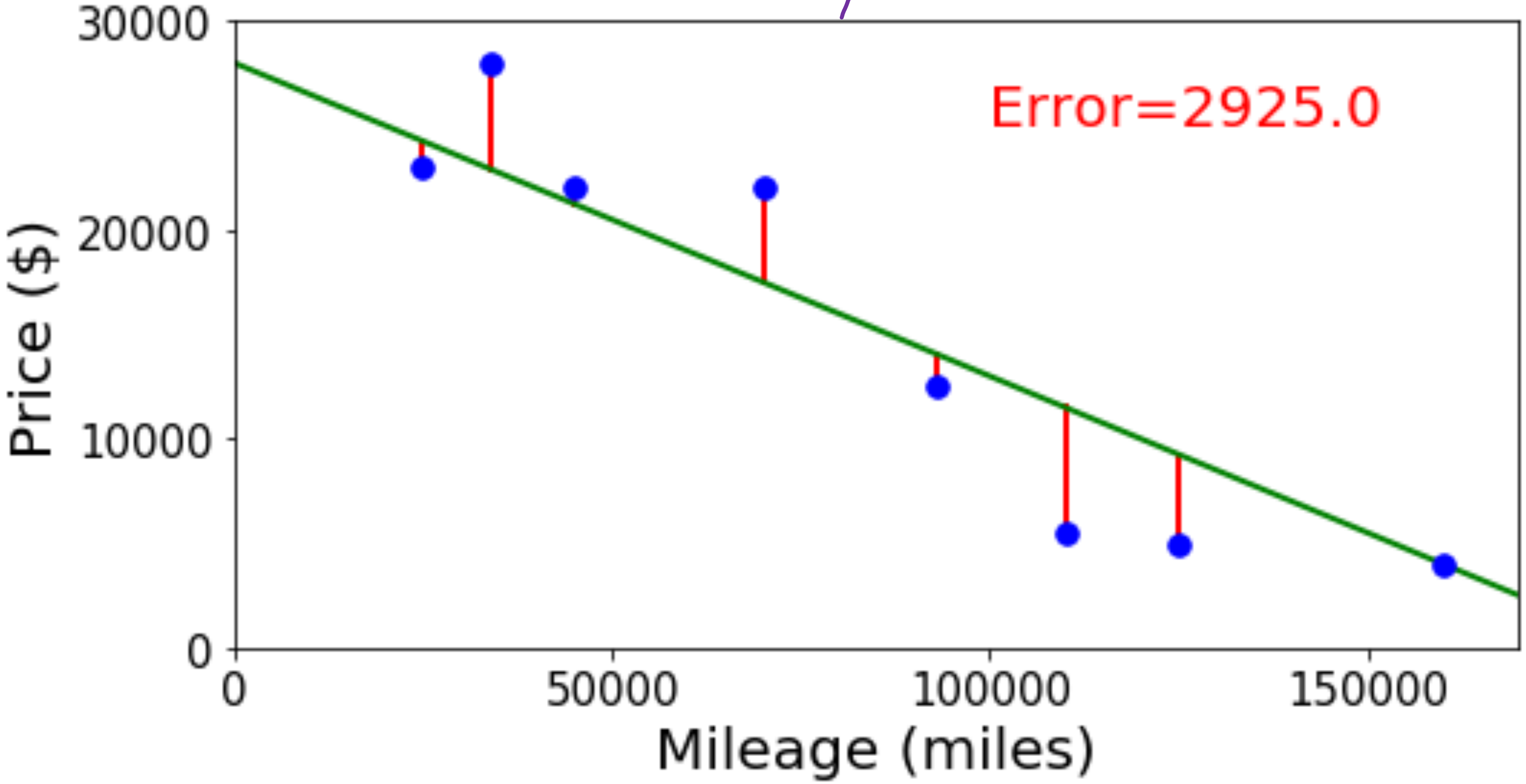
$y = mx + b$

$y = wx + b$

$y = w_1 x + w_0$

$y = \theta_1 x + \theta_0$

Selling my car



Linear in Higher Dimensions

1-D $y = wx + b$

2-D $y = w_1 x_1 + w_2 x_2 + b$

What are these linear shapes called for 1-D, 2-D, 3-D, M-D input?

	$\boldsymbol{x} \in \mathbb{R}$	$\boldsymbol{x} \in \mathbb{R}^2$	$\boldsymbol{x} \in \mathbb{R}^3$	$\boldsymbol{x} \in \mathbb{R}^M$
$y = \boldsymbol{w}^T\boldsymbol{x} + b$	line	plane	hyperplane	hyperplane
$\boldsymbol{w}^T\boldsymbol{x} + b = 0$	point	line	plane	hyperplane
$\boldsymbol{w}^T\boldsymbol{x} + b \geq 0$	halfline	halfplane	halfspace	halfspace

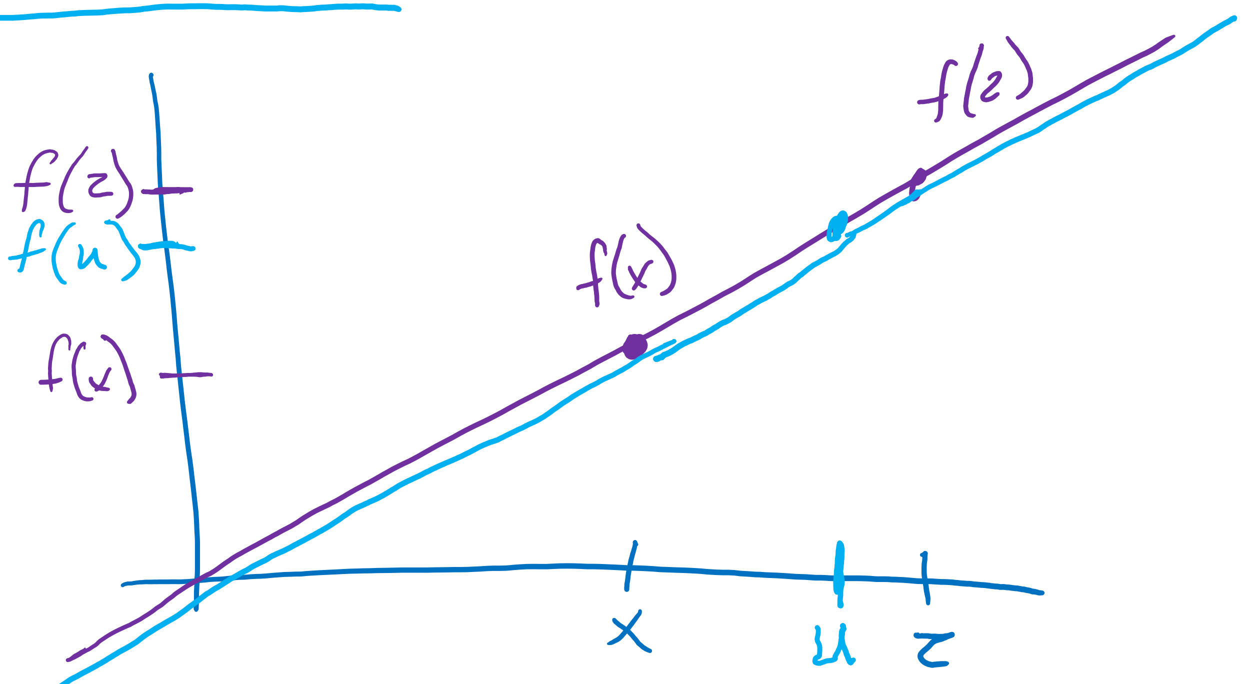
Linear Function

Linear function

If $f(\boldsymbol{x})$ is linear, then:

- $f(\boldsymbol{x}+\boldsymbol{z}) = f(\boldsymbol{x}) + f(\boldsymbol{z})$
- $f(\alpha\boldsymbol{x}) = \alpha f(\boldsymbol{x}) \quad \forall\alpha$
- $f(\alpha\boldsymbol{x}+(1-\alpha)\boldsymbol{z}) = \alpha f(\boldsymbol{x}) + (1-\alpha)f(\boldsymbol{z}) \quad \forall\alpha$

$\alpha = 0.25$



Piazza Poll 1

Based on the following definition of a linear, is the equation for a line, $y = wx + b$, linear? Example: $y = 3x + 5$

$f(\boldsymbol{x})$ is linear if and only if:

- $f(\boldsymbol{x} + \boldsymbol{z}) = f(\boldsymbol{x}) + f(\boldsymbol{z})$ and
- $f(\alpha\boldsymbol{x}) = \alpha f(\boldsymbol{x}) \quad \forall \alpha$

Linear Regression

Linear algebra formulation

$$y = \vec{w}^T x_{orig} + b$$

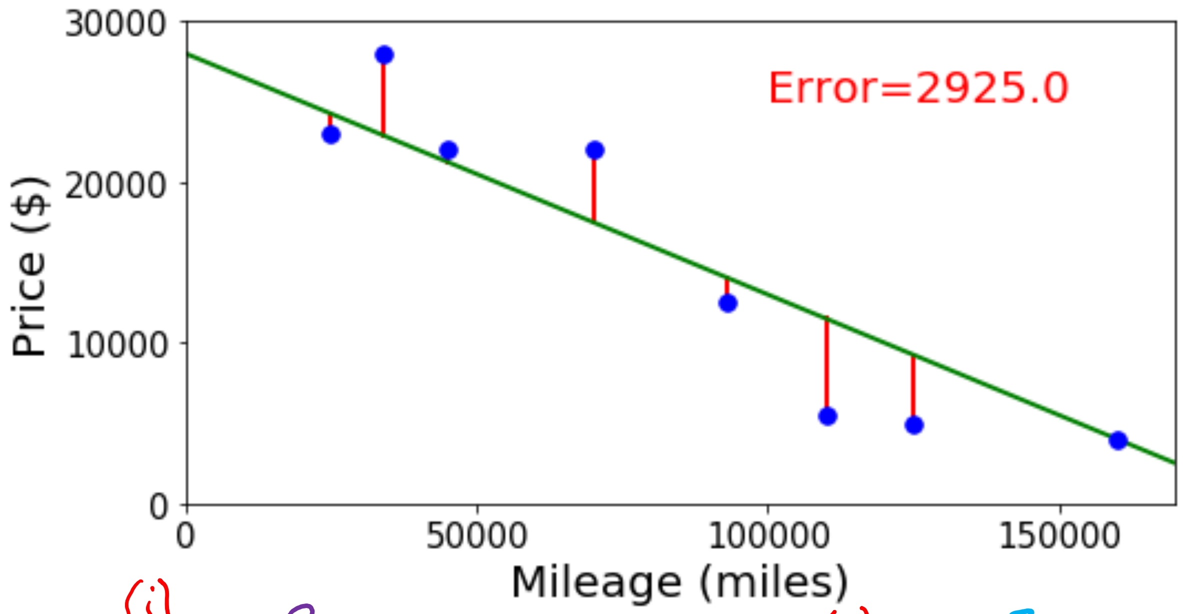
$$y^{(i)} = \vec{w}^T x_{orig}^{(i)} + b$$

$$y^{(i)} = \vec{\theta}^T \vec{x} = \vec{x}^T \vec{\theta}$$

$$\begin{bmatrix} y^{(1)} \\ \vdots \\ y^{(N)} \end{bmatrix} = \begin{bmatrix} - & x^{(1)T} & - \\ & \vdots & \\ - & x^{(N)T} & - \end{bmatrix} \begin{bmatrix} b \\ w_1 \\ \vdots \\ w_M \end{bmatrix}$$

$$\vec{y} = X \vec{\theta}$$

Design Matrix X



$$\vec{x}_{orig}^{(i)} \in \mathbb{R}^2 \longrightarrow \vec{x}^{(i)} \in \mathbb{R}^3$$

$$\vec{x}_{orig}^{(i)} = \begin{bmatrix} x_1^{(i)} \\ x_2^{(i)} \end{bmatrix} \longrightarrow \vec{x}^{(i)} = \begin{bmatrix} 1 \\ x_1^{(i)} \\ x_2^{(i)} \end{bmatrix}$$

$$\vec{w} = \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} \longrightarrow \vec{\theta} = \begin{bmatrix} b \\ w_1 \\ w_2 \end{bmatrix}$$

b

Linear Regression

Error and objectives

$$J(w, b) = \frac{1}{N}\sum_{i=1}^{N}\left(y^{(i)} - \hat{y}^{(i)}\right)^2$$

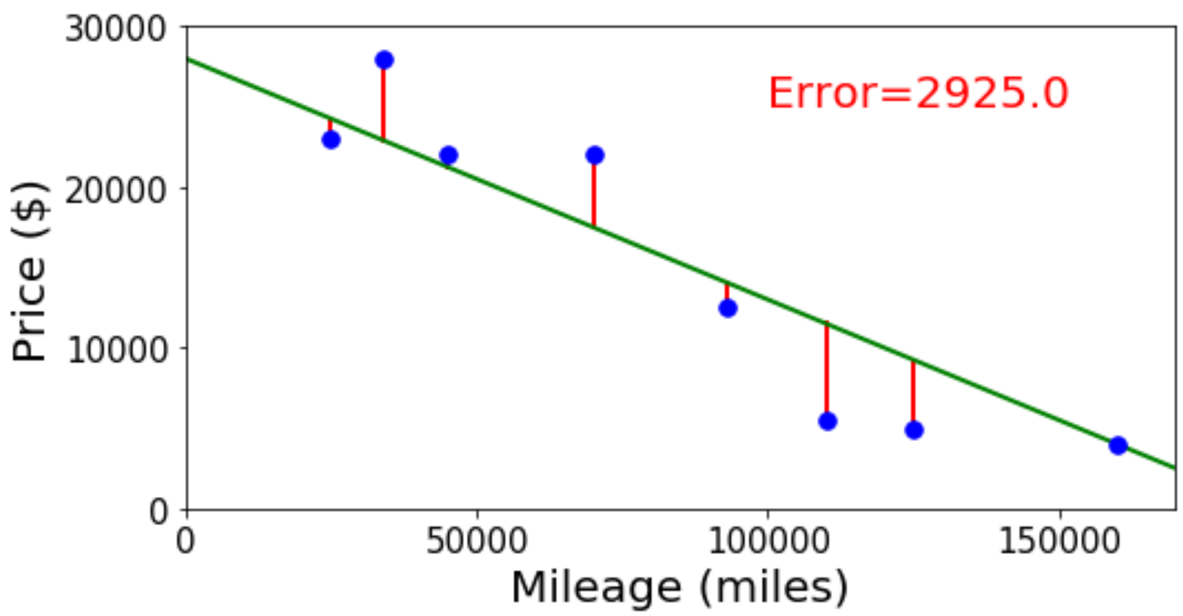
$$\hat{y}^{(i)} = w x^{(i)} + b$$

$$J(w_1, w_2, b) = \frac{1}{N}\sum\left(y^{(i)} - \hat{y}^{(i)}\right)^2$$

$$\hat{y}^{(i)} = w_1 x_1^{(i)} + w_2 x_2^{(i)} + b$$

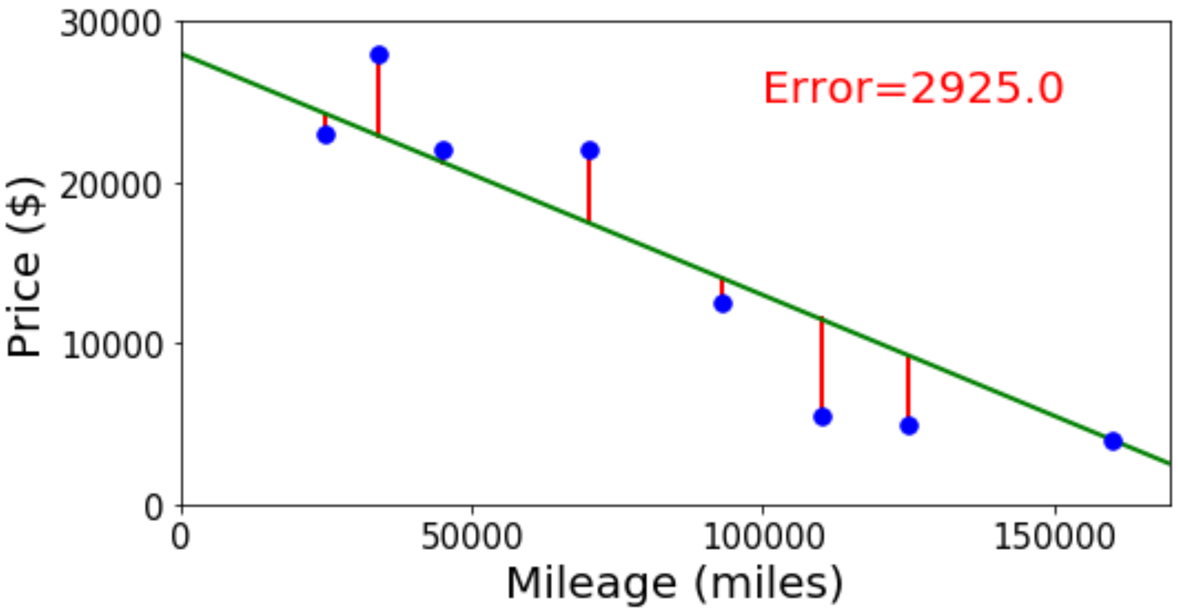
$$J(w_1, \ldots, w_m, b) =$$

$$\hat{y}^{(i)} = \sum_{j=1}^{m} w_j x_j^{(i)} + b$$



Linear Regression

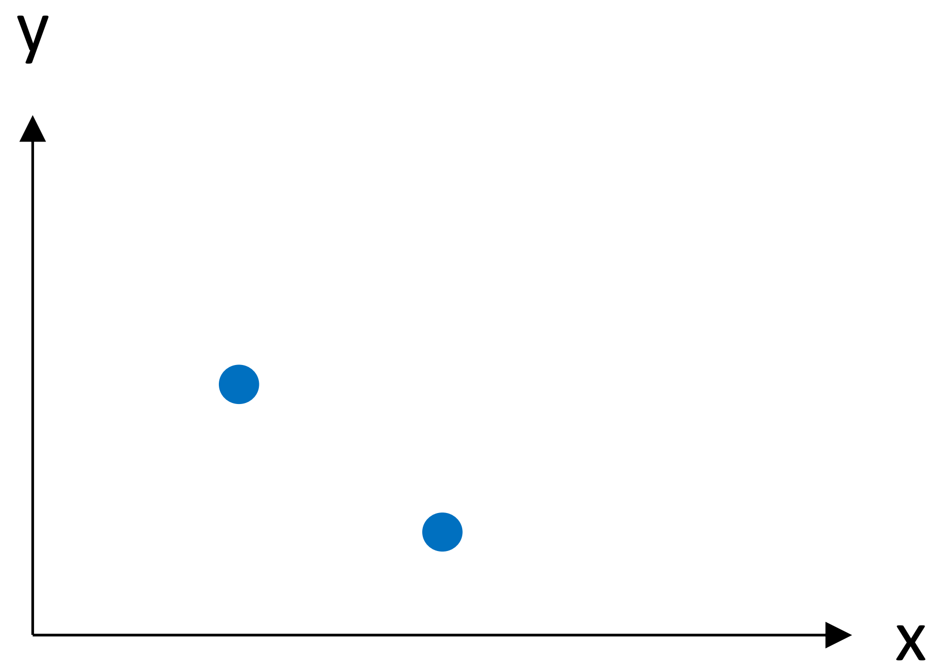
Linear algebra formulation



Previous Piazza Poll

For fixed data and fixed slope, w, what shape do we get by plotting MSE objective vs intercept, b?

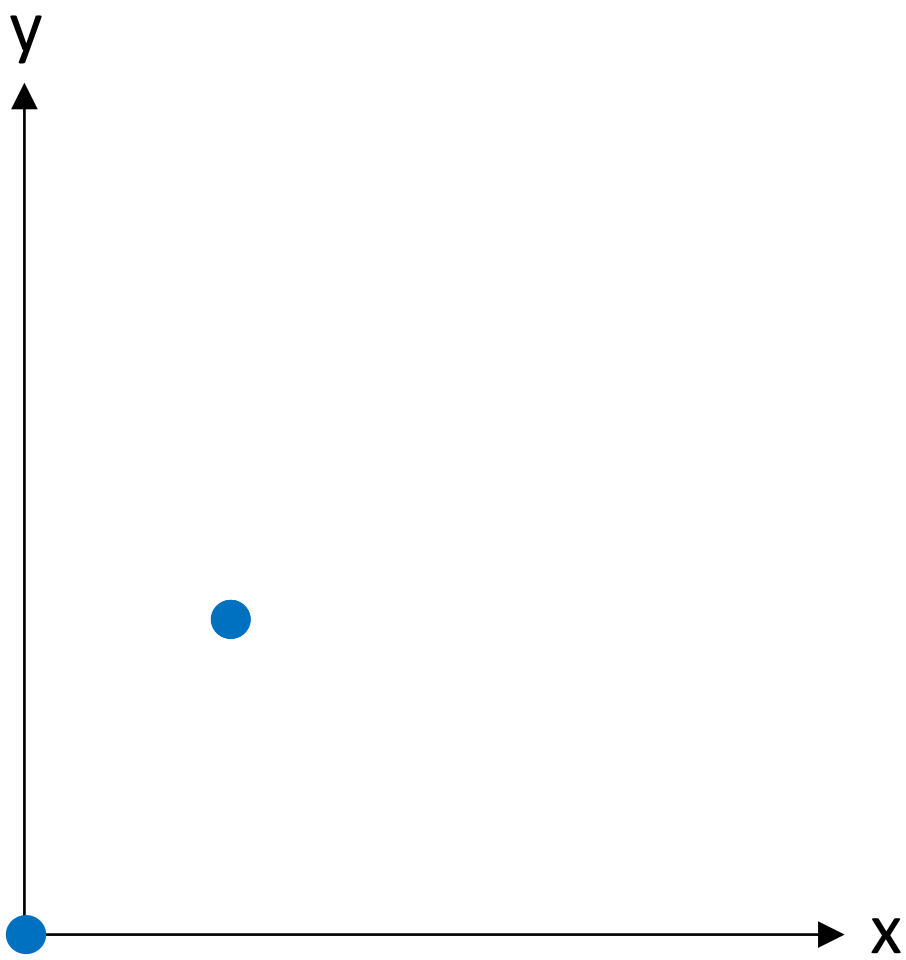
A. Line
B. Plane
C. Half-plane
D. Convex Parabola (U-shape)
E. Concave parabola (up-side-down U)
F. None of the above



Linear Regression

Optimizing the objective

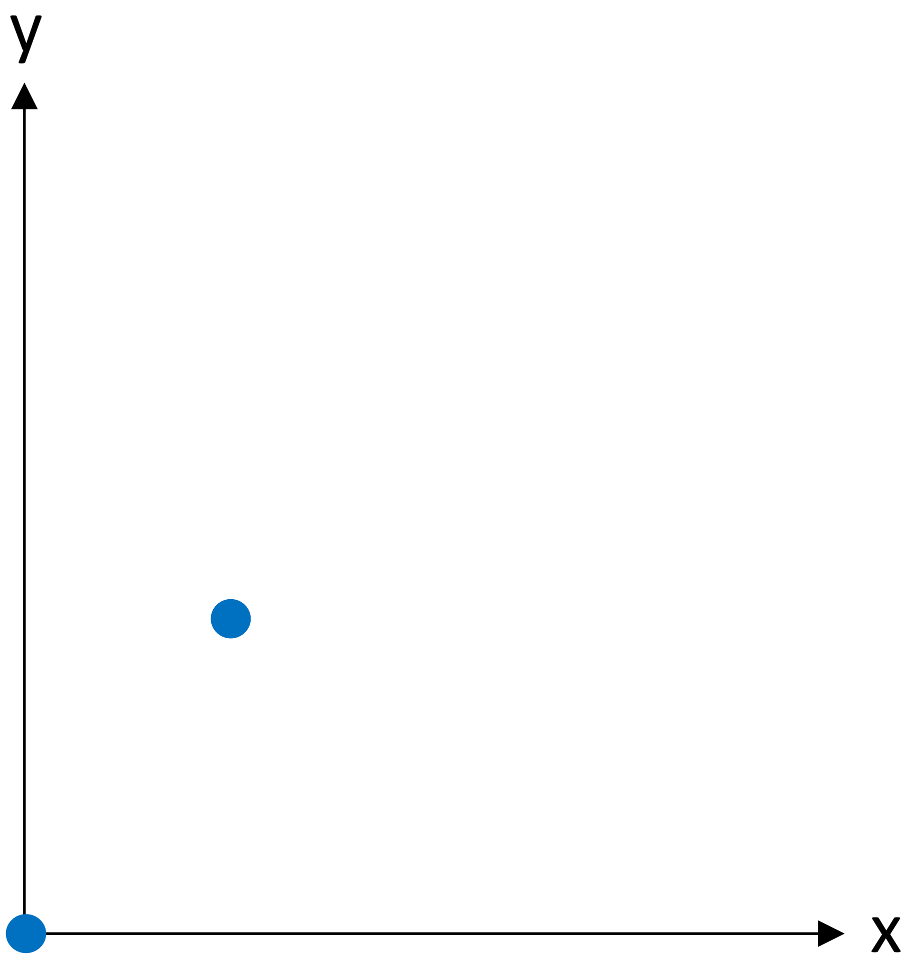
$$J(w,b) = \frac{1}{2}\left[\left(y^{(1)} - \left(wx^{(1)} + b\right)\right)^2 + \left(y^{(2)} - \left(wx^{(2)} + b\right)\right)^2\right]$$



Linear Regression

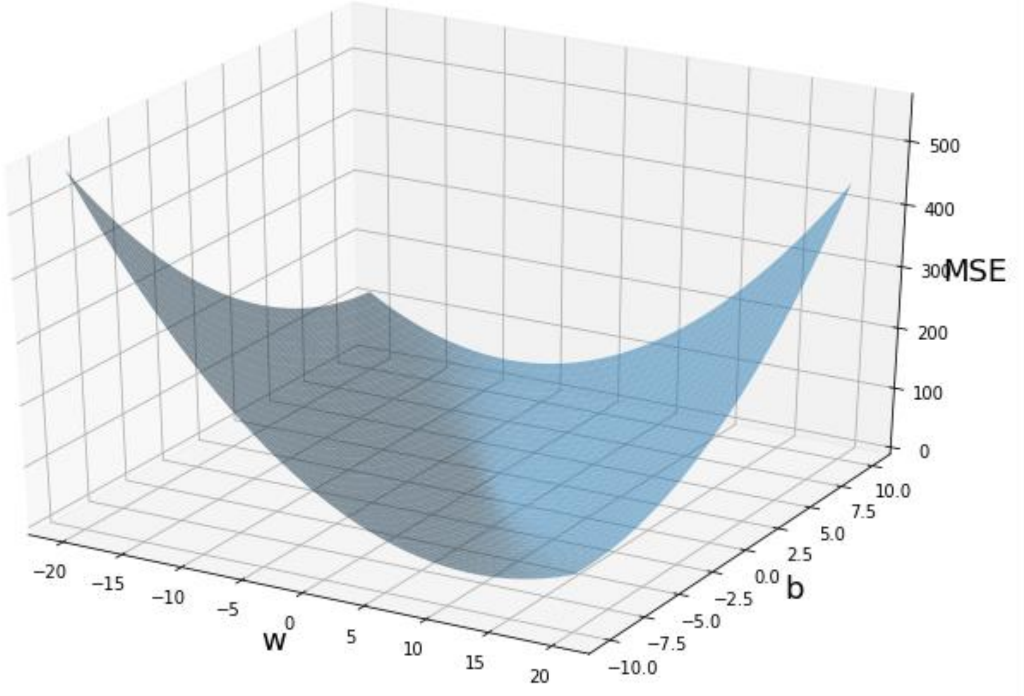
Optimizing the objective

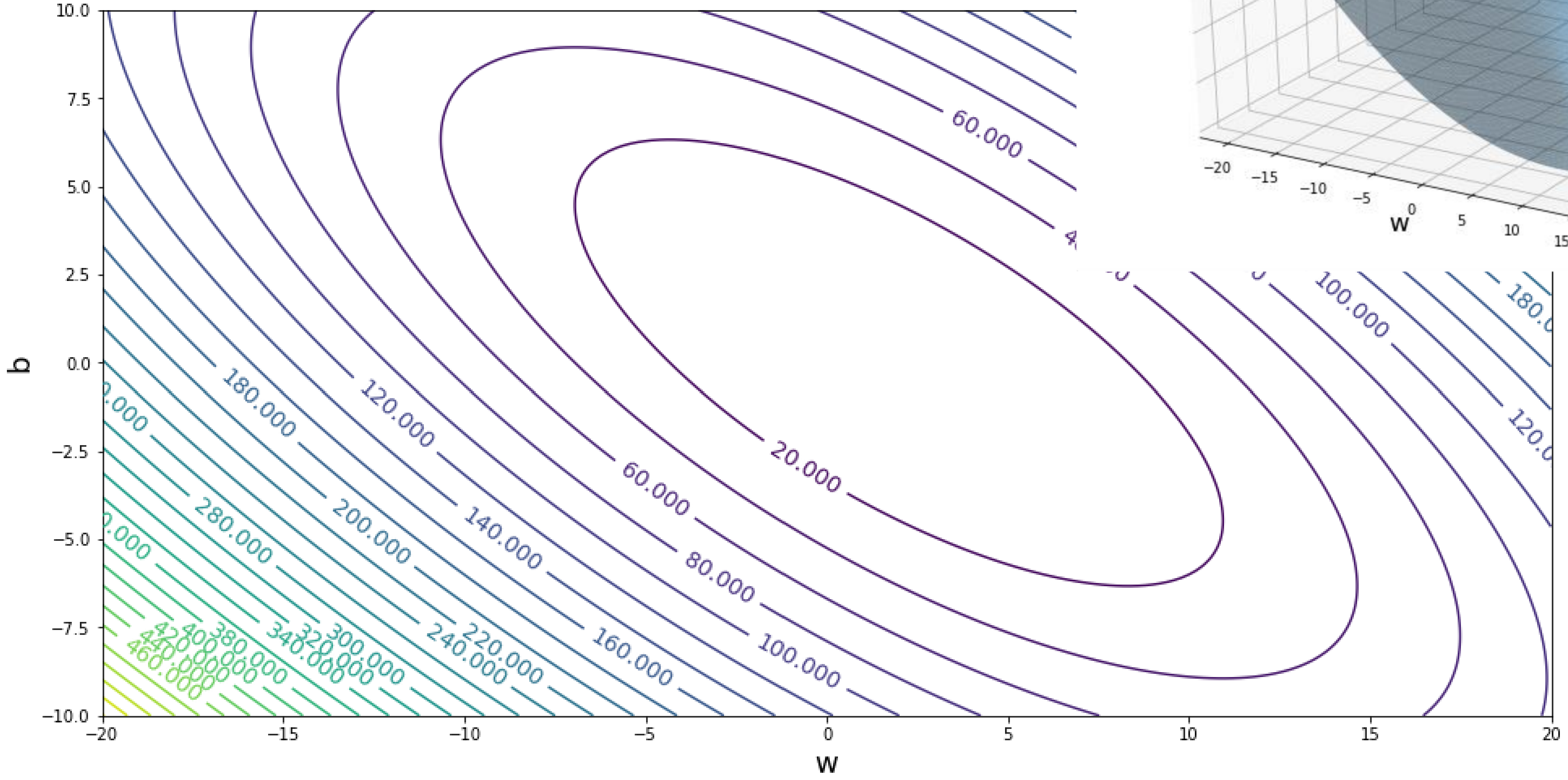
$$J(w,b) = \frac{1}{2}\left[\left(y^{(1)} - \left(wx^{(1)} + b\right)\right)^2 + \left(y^{(2)} - \left(wx^{(2)} + b\right)\right)^2\right]$$



Linear Regression

Optimizing the objective

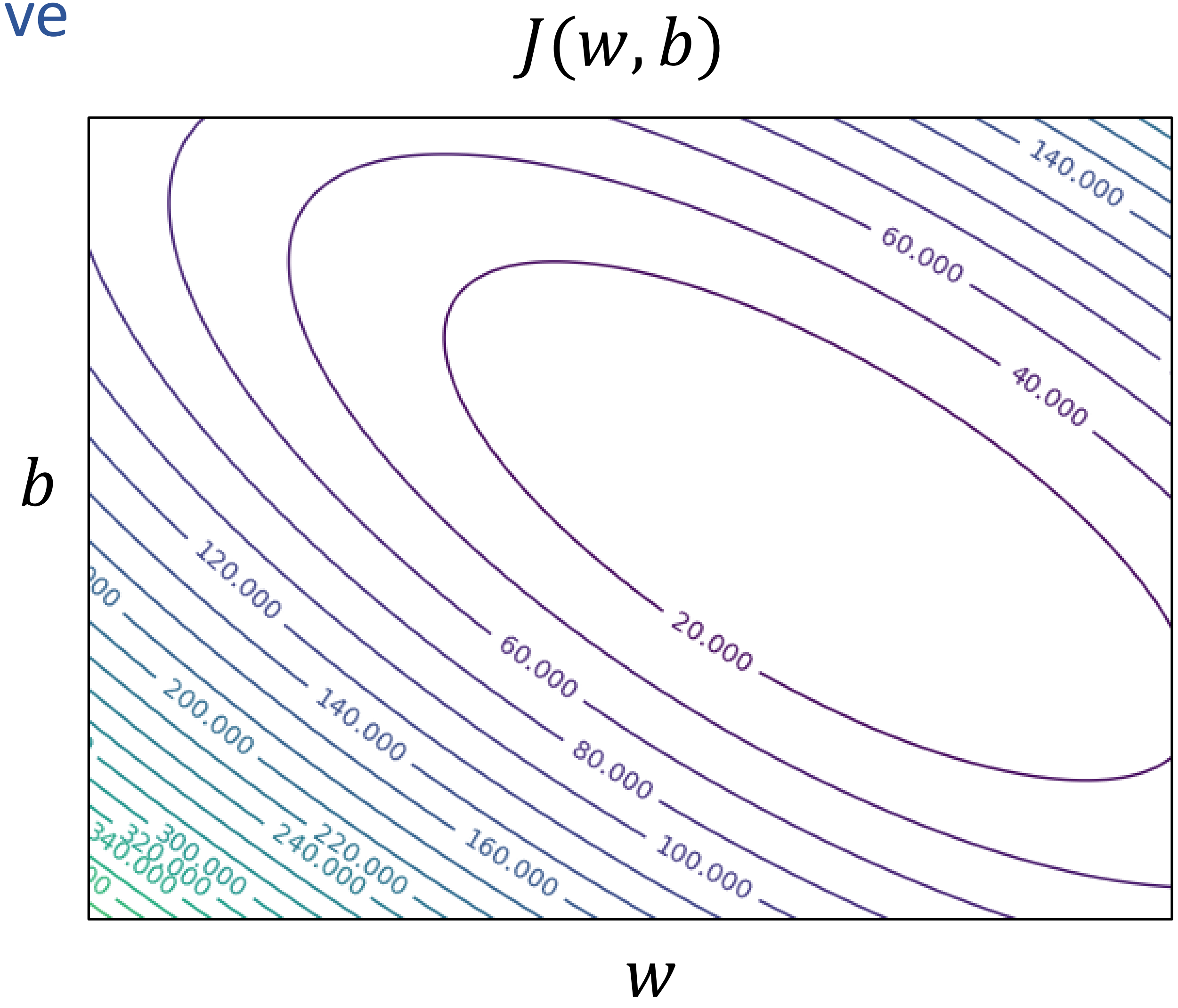




Linear Regression

Methods for optimizing the objective

- Grid search
- Random search
- Closed-form solution
- (Batch) Gradient descent
- Stochastic gradient descent



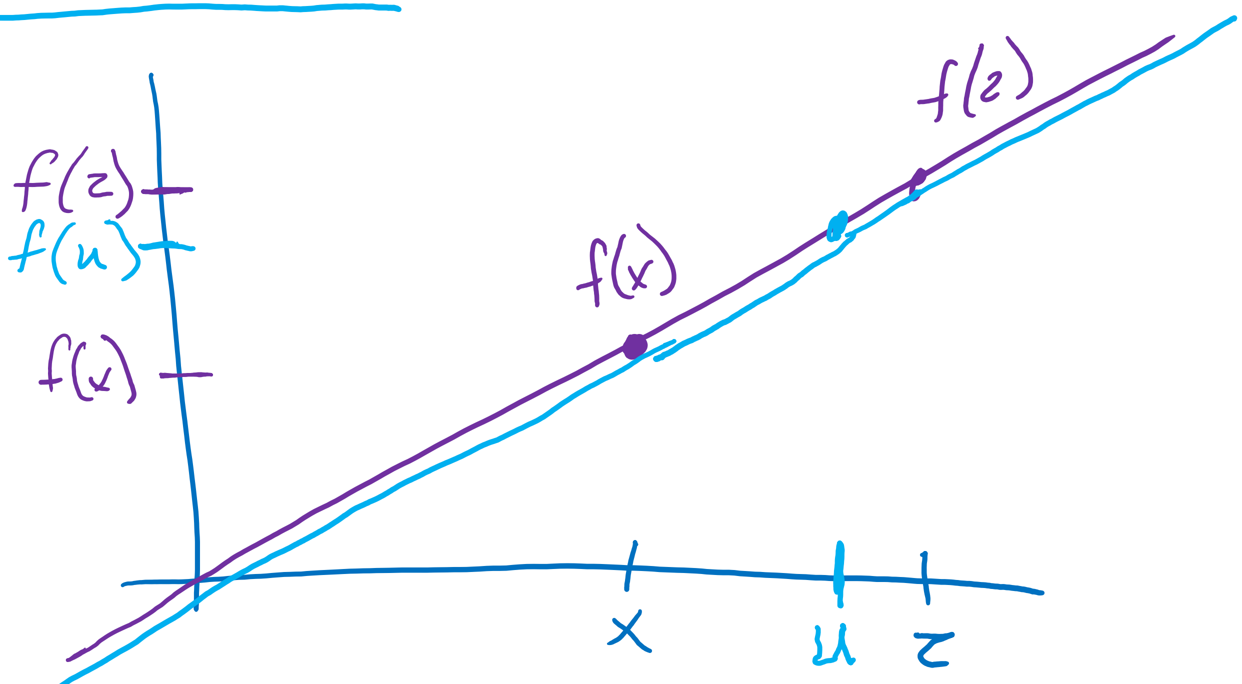
Optimization

Linear function

If $f(\boldsymbol{x})$ is linear, then:

- $f(\boldsymbol{x}+\boldsymbol{z}) = f(\boldsymbol{x}) + f(\boldsymbol{z})$
- $f(\alpha\boldsymbol{x}) = \alpha f(\boldsymbol{x}) \quad \forall\alpha$
- $\underline{f(\alpha\boldsymbol{x}+(1-\alpha)\boldsymbol{z})} = \underline{\alpha f(\boldsymbol{x}) + (1-\alpha) f(\boldsymbol{z})} \quad \forall\alpha$

$\alpha = 0.25$



Optimization

Convex function

If $f(\boldsymbol{x})$ is convex, then:

- $f(\alpha\boldsymbol{x} + (1-\alpha)\boldsymbol{z}) \leq \alpha f(\boldsymbol{x}) + (1-\alpha)f(\boldsymbol{z}) \quad \forall\ 0 \leq \alpha \leq 1$

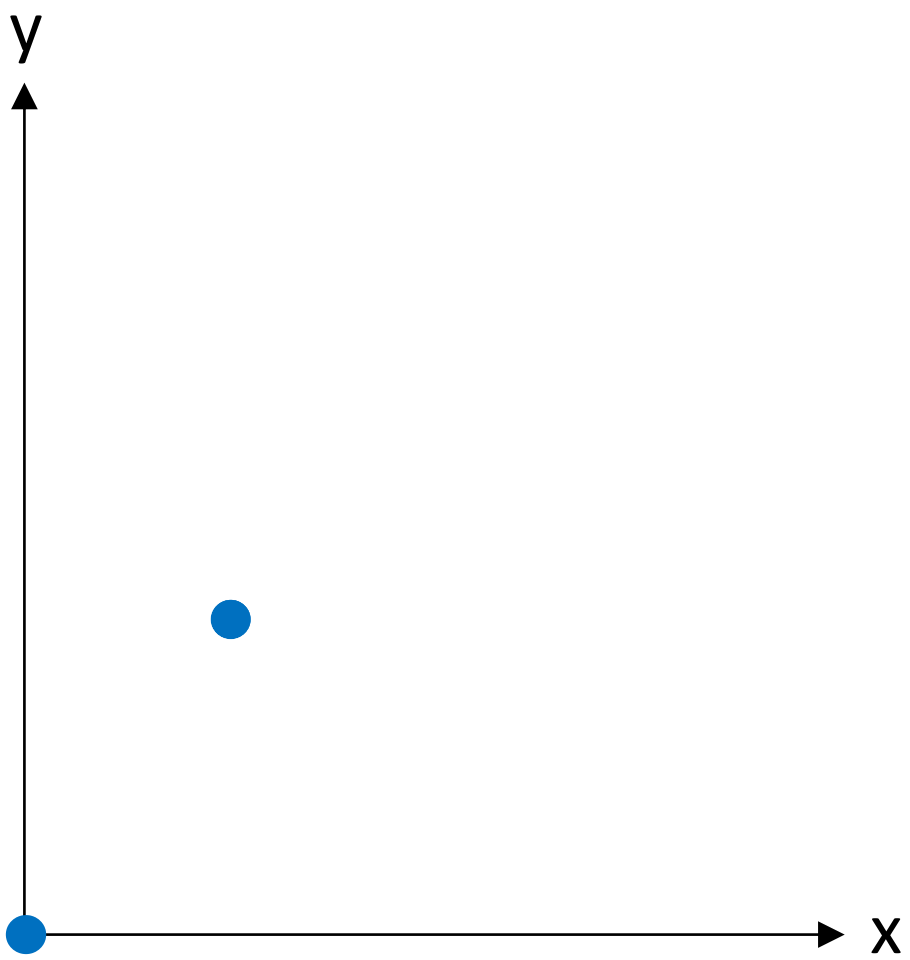
Convex optimization

If $f(\boldsymbol{x})$ is convex, then:

- Every local minimum is also a global minimum ☺

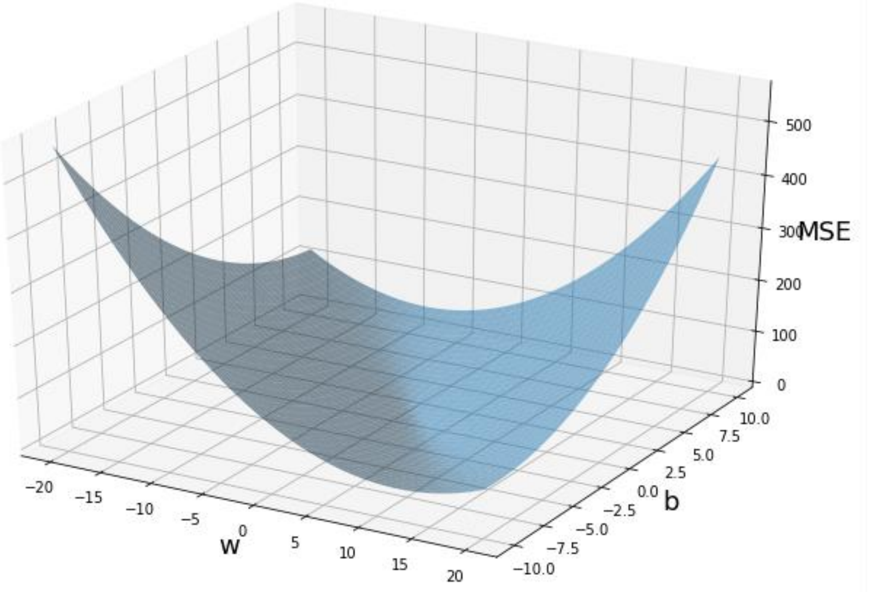
Linear Regression

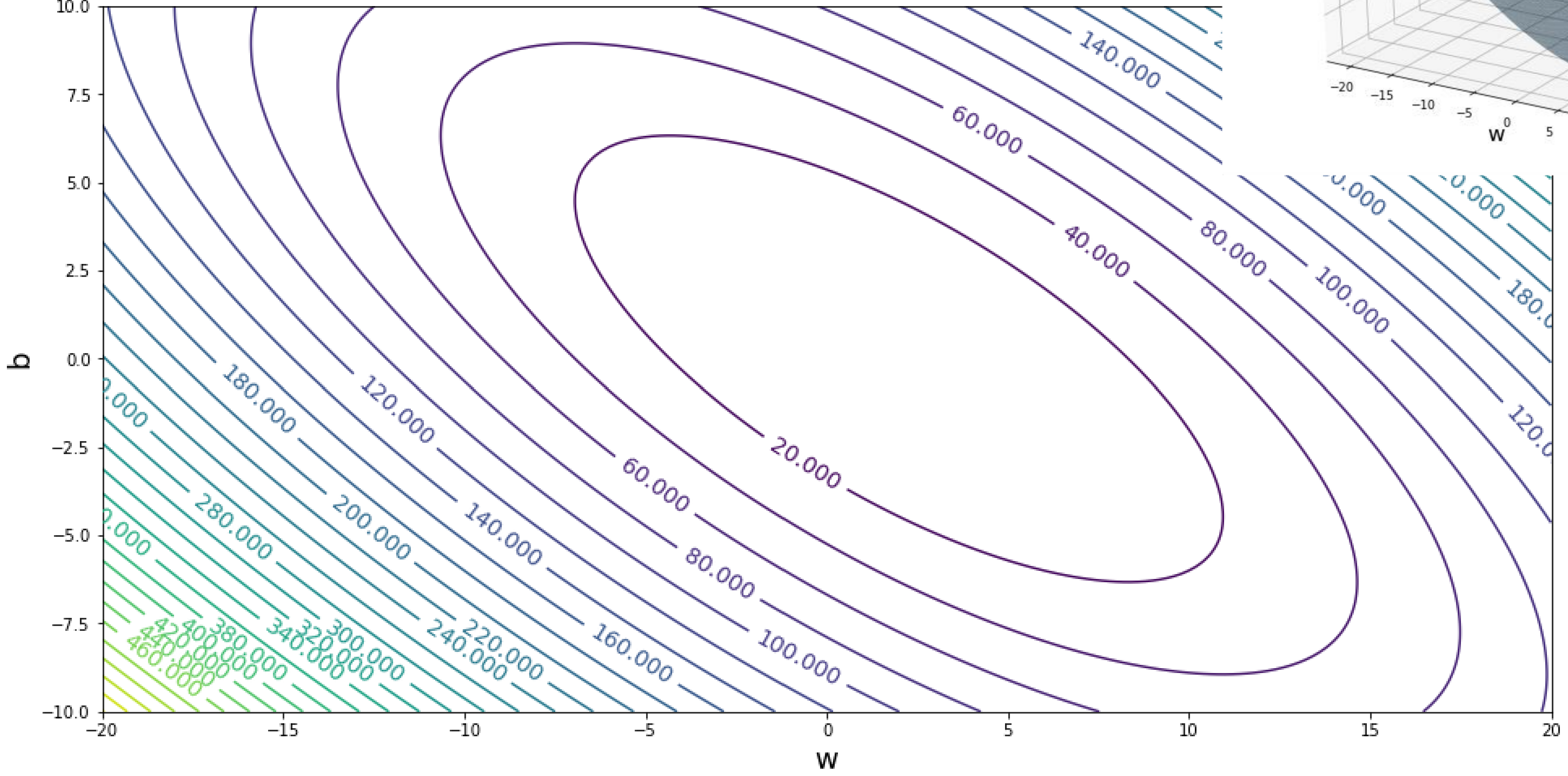
Optimizing the objective



Optimization

Gradients



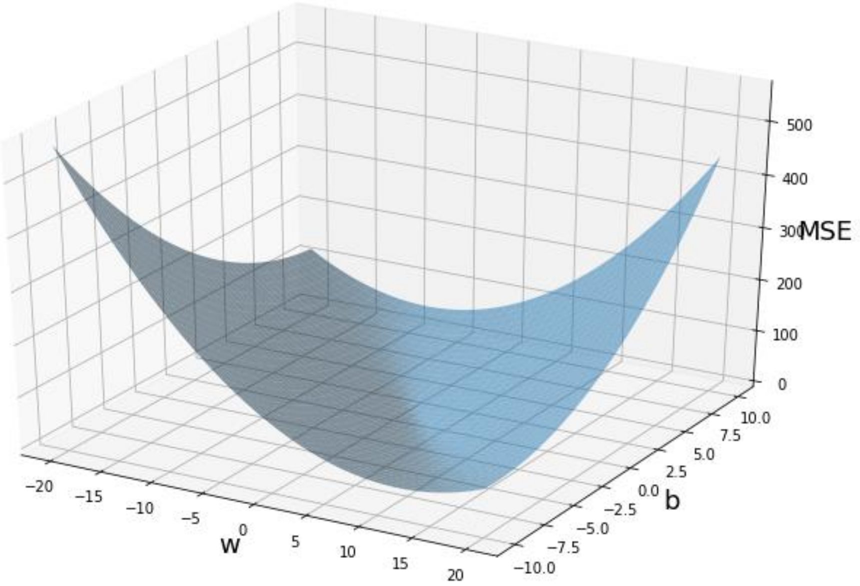


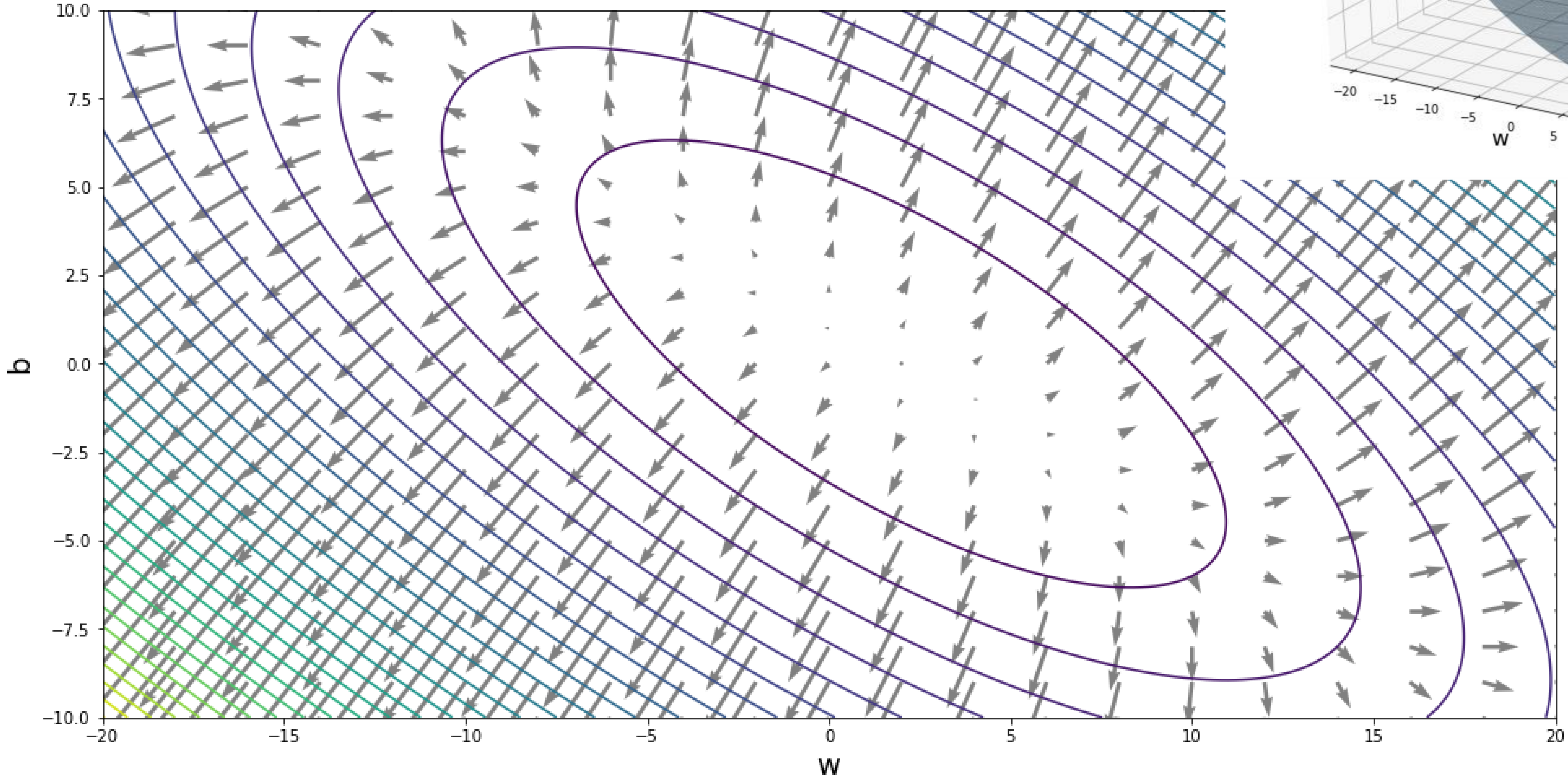
Optimization

Gradients

Optimization

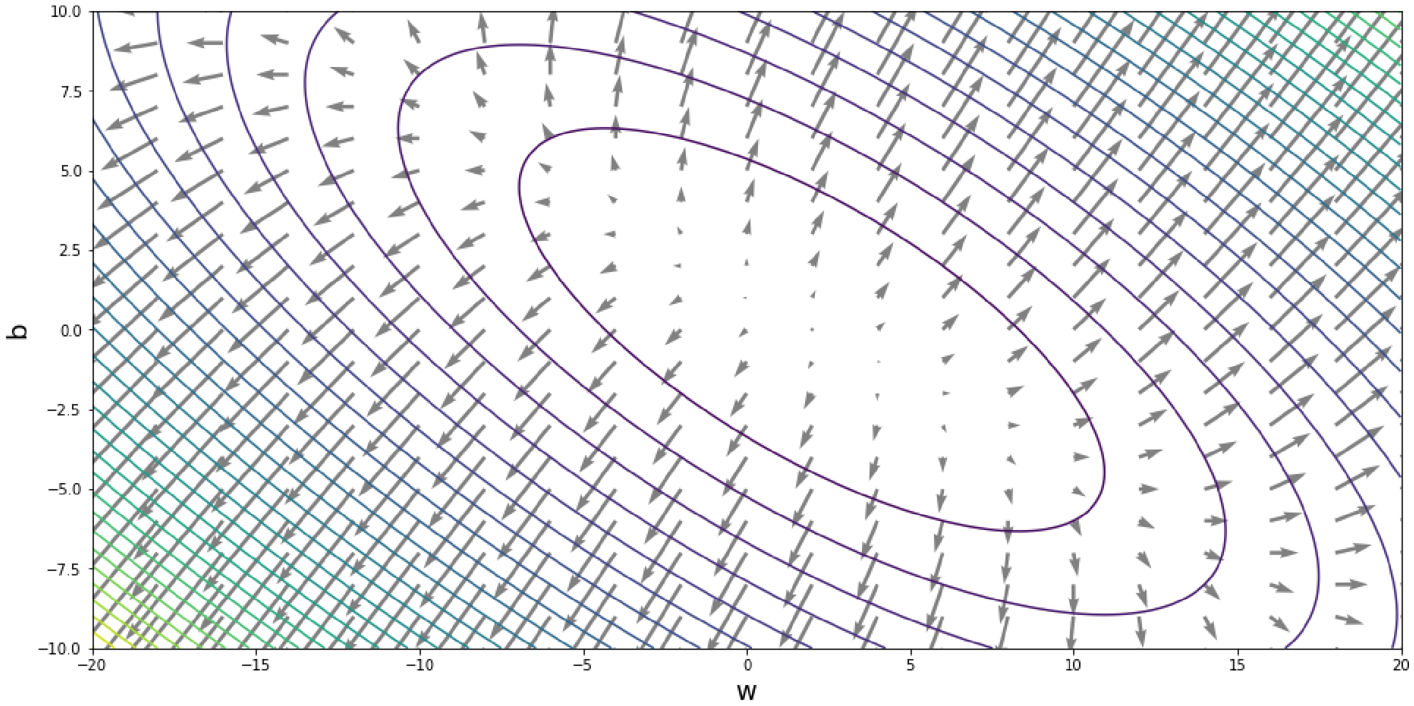
Gradients





Optimization

Gradient descent



Linear Regression

Expanding objective before computing gradient

$$
\begin{aligned}
J(\boldsymbol{\theta}) &= \frac{1}{N}\|\boldsymbol{y}-\boldsymbol{X\theta}\|_2^2 \\
&= \frac{1}{N}(\boldsymbol{y}-\boldsymbol{X\theta})^T(\boldsymbol{y}-\boldsymbol{X\theta}) \\
&= \frac{1}{N}\left(\boldsymbol{y}^T-\boldsymbol{\theta}^T\boldsymbol{X}^T\right)(\boldsymbol{y}-\boldsymbol{X\theta}) \\
&= \frac{1}{N}\left(\boldsymbol{y}^T\boldsymbol{y}\;-\boldsymbol{\theta}^T\boldsymbol{X}^T\boldsymbol{y}\;-\boldsymbol{y}^T\boldsymbol{X\theta}+\boldsymbol{\theta}^T\boldsymbol{X}^T\boldsymbol{X\theta}\right) \\
&= \frac{1}{N}\left(\boldsymbol{y}^T\boldsymbol{y}\;-2\boldsymbol{\theta}^T\boldsymbol{X}^T\boldsymbol{y}+\boldsymbol{\theta}^T\boldsymbol{X}^T\boldsymbol{X\theta}\right)
\end{aligned}
$$

Linear Regression

Gradient of objective with respect to parameters

$$J(\boldsymbol{\theta}) = \frac{1}{N} \|\boldsymbol{y} - \boldsymbol{X\theta}\|_2^2$$

$$= \frac{1}{N}\left(\boldsymbol{y}^T\boldsymbol{y} - 2\boldsymbol{\theta}^T\boldsymbol{X}^T\boldsymbol{y} + \boldsymbol{\theta}^T\boldsymbol{X}^T\boldsymbol{X\theta}\right)$$

$$\nabla J(\boldsymbol{\theta}) = \frac{1}{N}\left(0 - 2\boldsymbol{X}^T\boldsymbol{y} + \cancel{2\boldsymbol{\theta}^T\boldsymbol{X}^T\boldsymbol{X}}\right)$$

$$= \frac{1}{N}\left(0 - 2\boldsymbol{X}^T\boldsymbol{y} + 2\boldsymbol{X}^T\boldsymbol{X\theta}\right)$$

$$= \frac{2}{N}\left(-\boldsymbol{X}^T\boldsymbol{y} + \boldsymbol{X}^T\boldsymbol{X\theta}\right)$$

$$\frac{\partial \boldsymbol{z}^T\boldsymbol{u}}{\partial \boldsymbol{z}} = \boldsymbol{u}$$

-- or --

$$\frac{\partial \boldsymbol{z}^T\boldsymbol{u}}{\partial \boldsymbol{z}} = \boldsymbol{u}^T$$

$$\frac{\partial \boldsymbol{z}^T\boldsymbol{A}\boldsymbol{z}}{\partial \boldsymbol{z}} = (\boldsymbol{A} + \boldsymbol{A}^T)\boldsymbol{z}$$

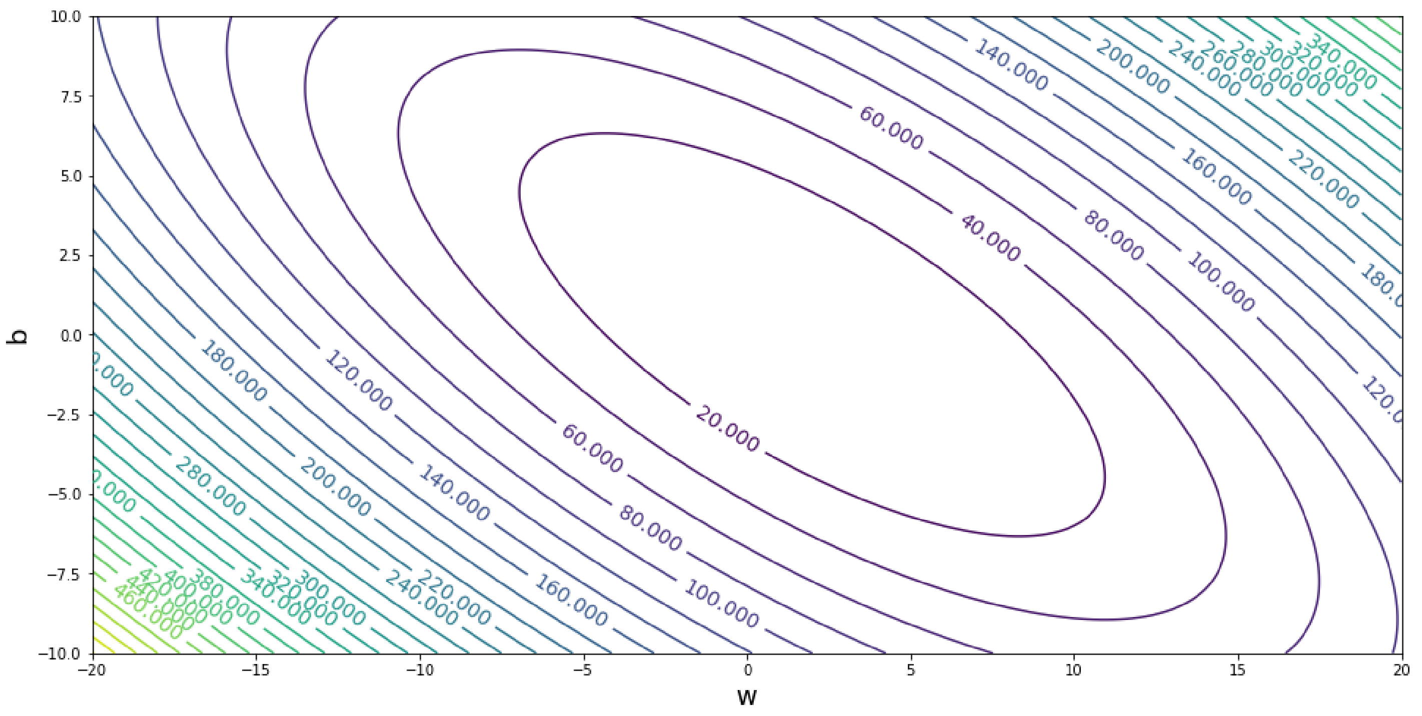
-- or --

$$\frac{\partial \boldsymbol{z}^T\boldsymbol{A}\boldsymbol{z}}{\partial \boldsymbol{z}} = \boldsymbol{z}^T(\boldsymbol{A} + \boldsymbol{A}^T)$$

Linear Regression

Closed-form solution

$$\nabla J(\boldsymbol{\theta}) = \frac{2}{N}\left(-\boldsymbol{X}^T\boldsymbol{y} + \boldsymbol{X}^T\boldsymbol{X}\boldsymbol{\theta}\right)$$



Linear Regression

Number of solutions

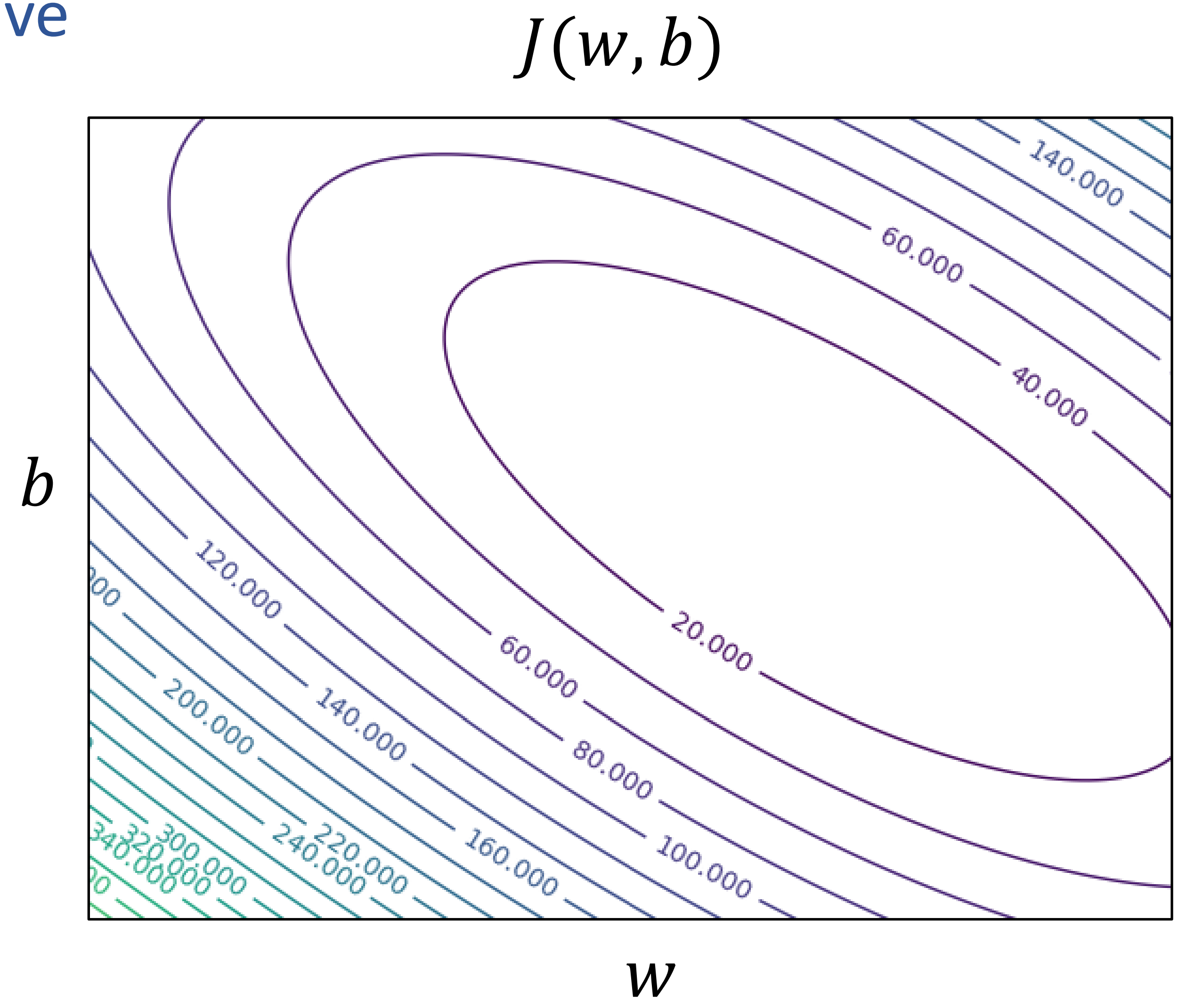
A Note on Matrix Rank

Underlying dimensionality of the data

Linear Regression

Methods for optimizing the objective

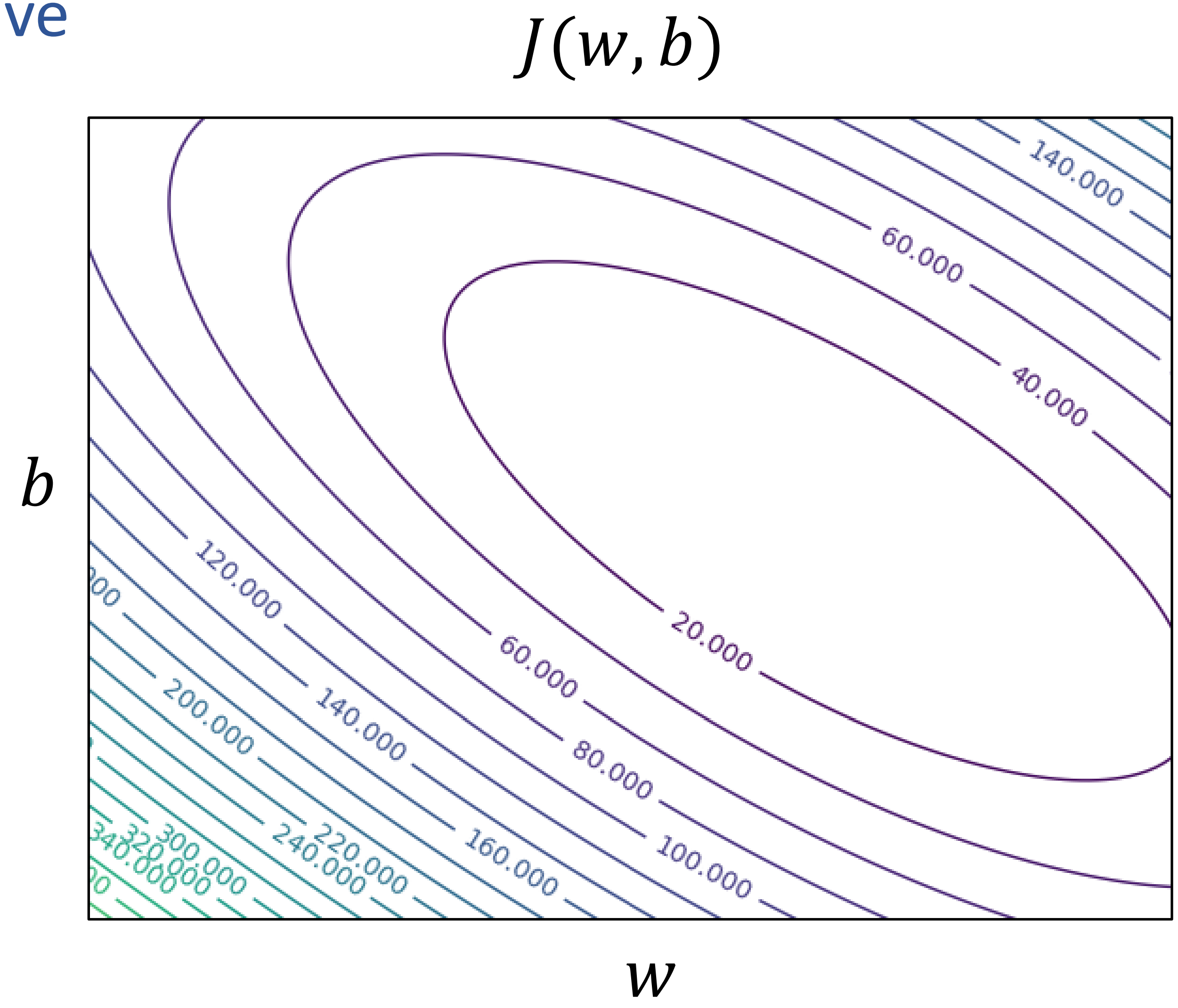
- Grid search
- Random search
- Closed-form solution
- (Batch) Gradient descent
- Stochastic gradient descent



Linear Regression

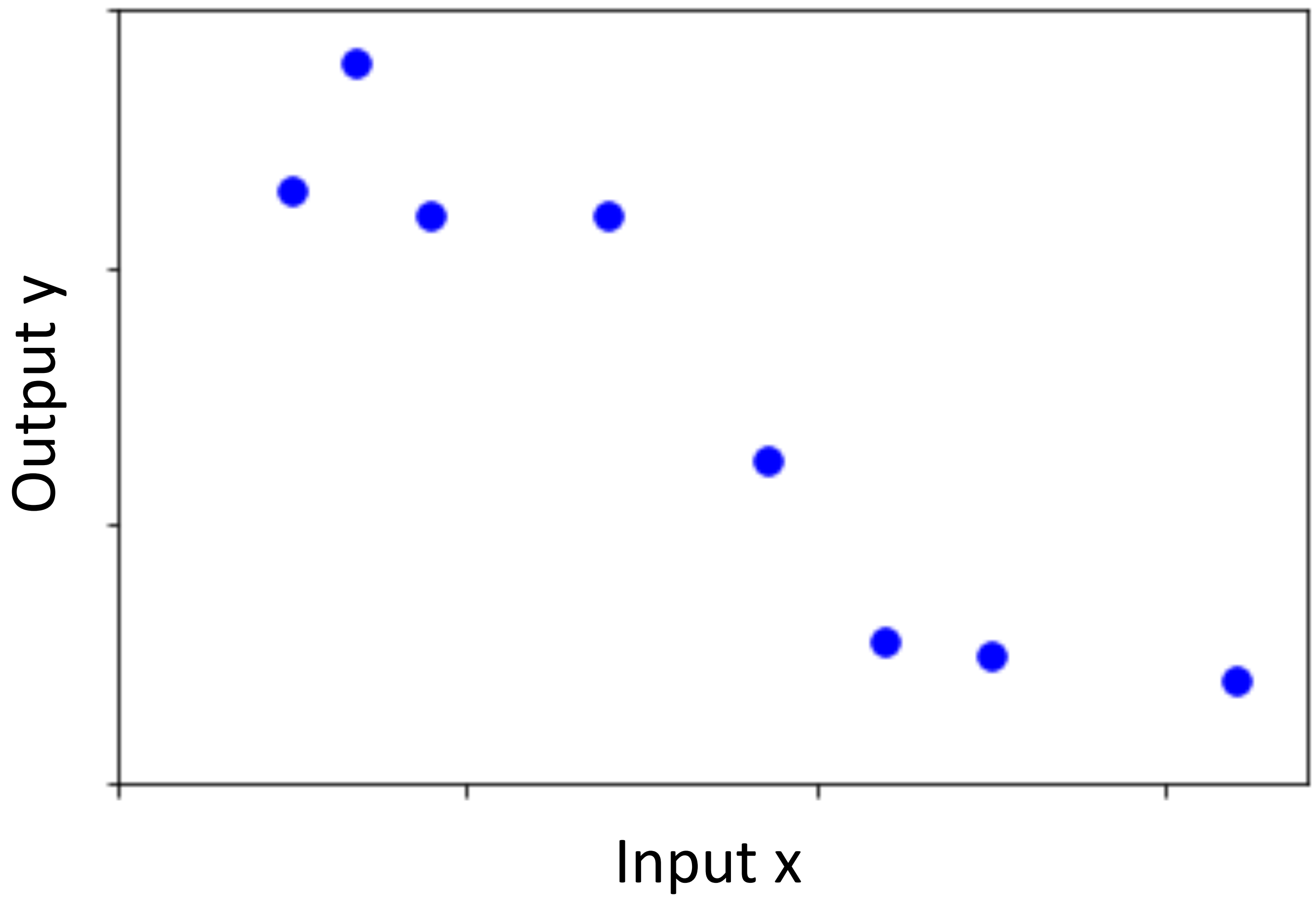
Methods for optimizing the objective

- Grid search
- Random search
- Closed-form solution
- (Batch) Gradient descent
- **Stochastic gradient descent**



Linear Regression Gradient Descent

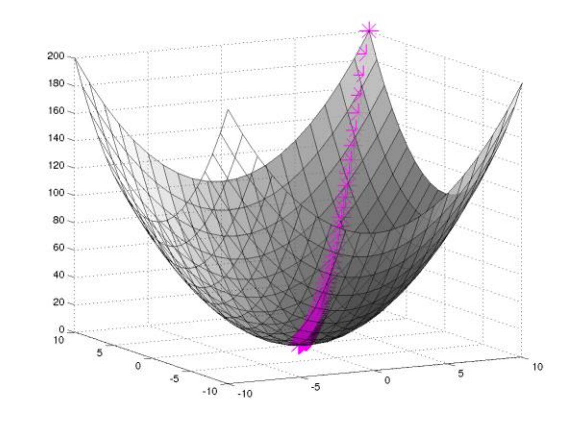
What happens in gradient descent when we have N=1,000,000 training points?



(Batch) Gradient Descent

Algorithm 1 Gradient Descent

procedure GD($\mathcal{D}$, $\boldsymbol{\theta}^{(0)}$)
    $\boldsymbol{\theta} \leftarrow \boldsymbol{\theta}^{(0)}$
    while not converged **do**
        $\boldsymbol{\theta} \leftarrow \boldsymbol{\theta} - \gamma \nabla_{\boldsymbol{\theta}} J(\boldsymbol{\theta})$
    return $\boldsymbol{\theta}$



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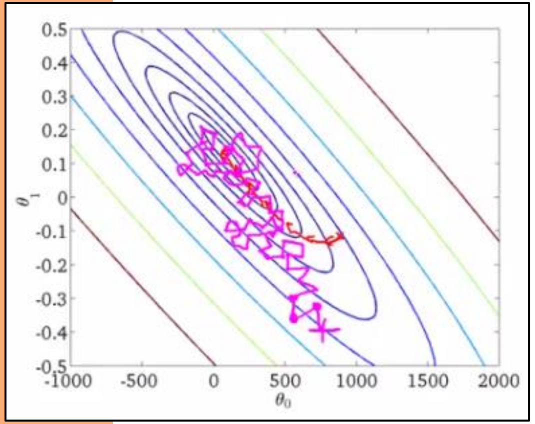
Stochastic Gradient Descent (SGD)

Algorithm 2 Stochastic Gradient Descent (SGD)

1: **procedure** SGD($\mathcal{D}, \boldsymbol{\theta}^{(0)}$)
2: $\quad \boldsymbol{\theta} \leftarrow \boldsymbol{\theta}^{(0)}$
3: $\quad$ **while** not converged **do**
4: $\quad\quad i \sim$ Uniform($\{1, 2, \ldots, N\}$)
5: $\quad\quad \boldsymbol{\theta} \leftarrow \boldsymbol{\theta} - \lambda \nabla_{\boldsymbol{\theta}} J^{(i)}(\boldsymbol{\theta})$
6: $\quad$ **return** $\boldsymbol{\theta}$

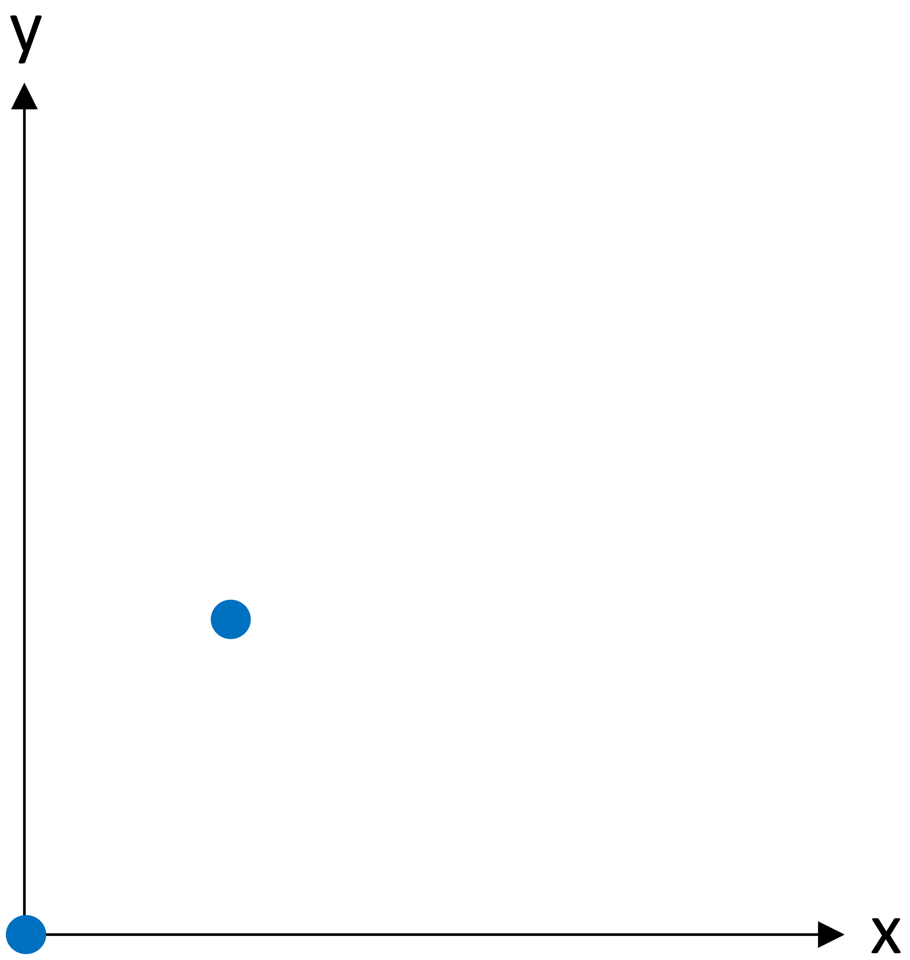


We need a per-example objective:

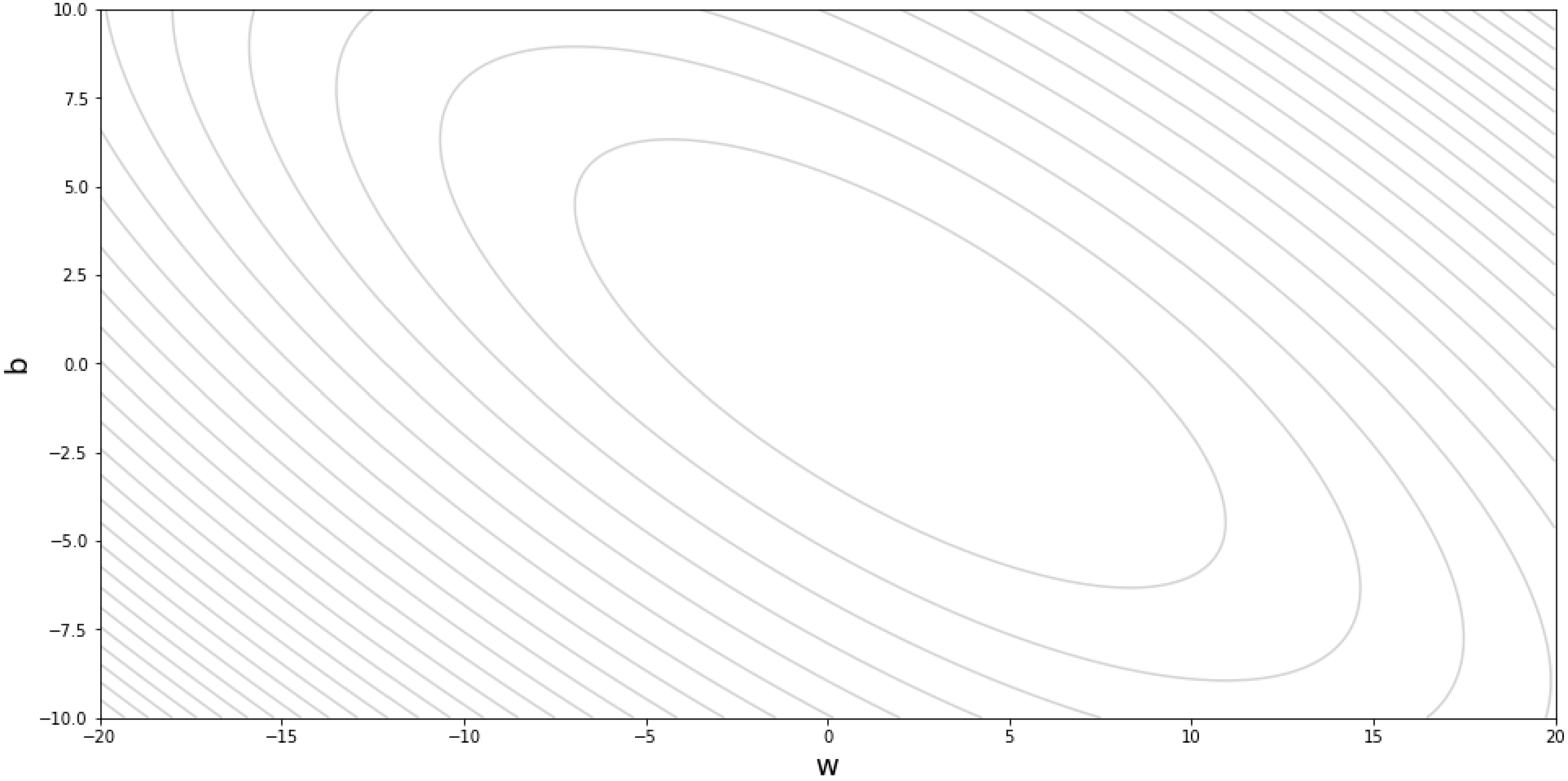
$$\text{Let } J(\boldsymbol{\theta}) = \sum_{i=1}^{N} J^{(i)}(\boldsymbol{\theta})$$

Linear Regression

Optimizing the objective

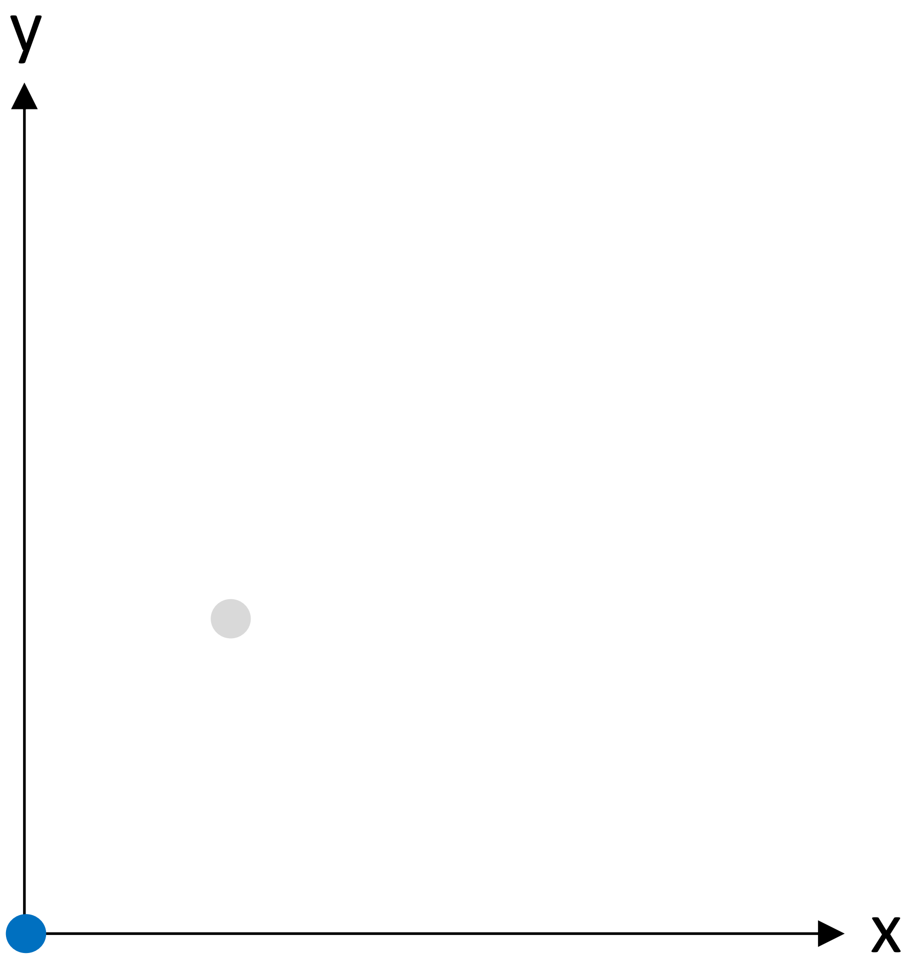


Stochastic Gradient Descent

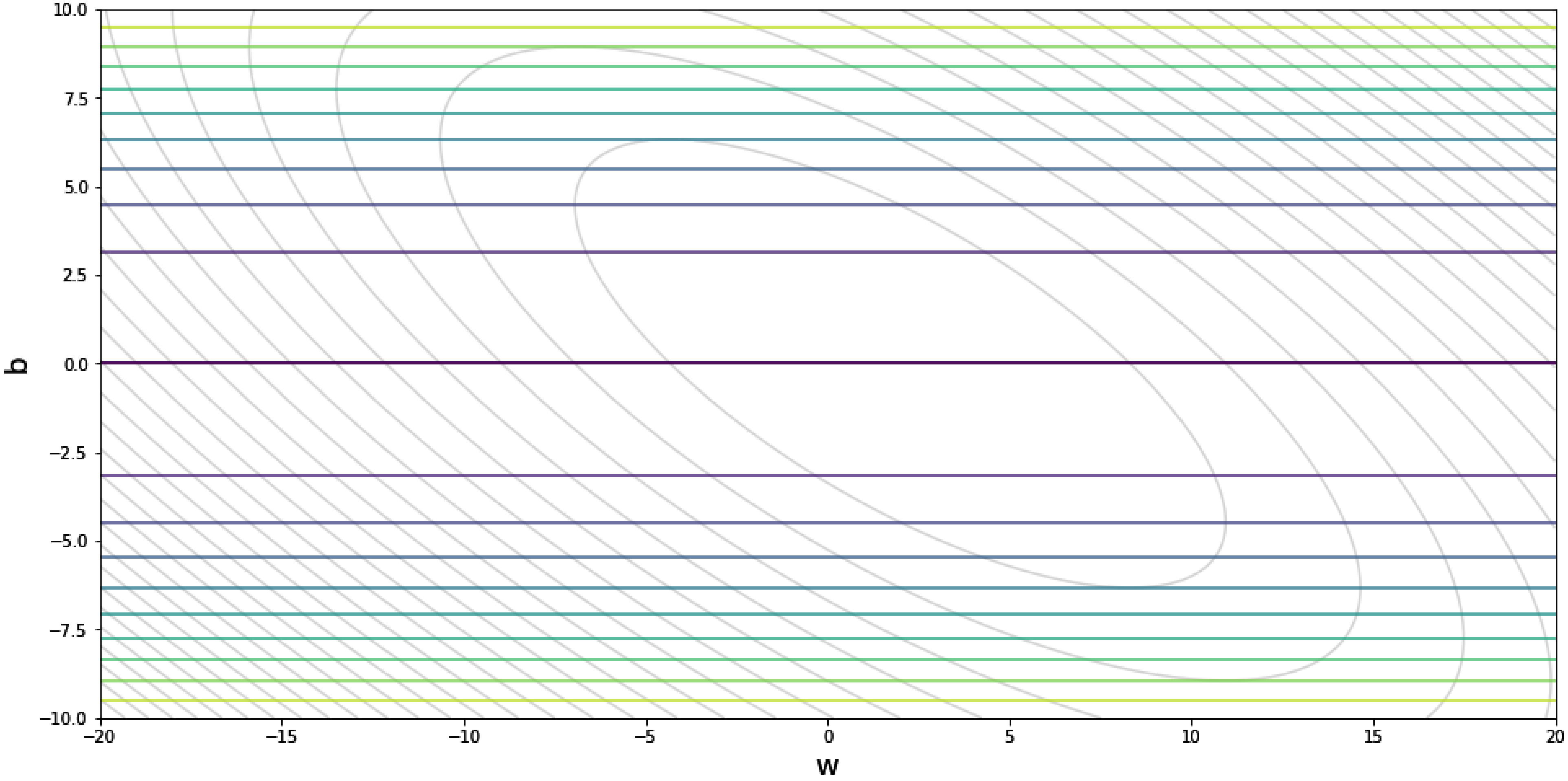


Linear Regression

Optimizing the objective

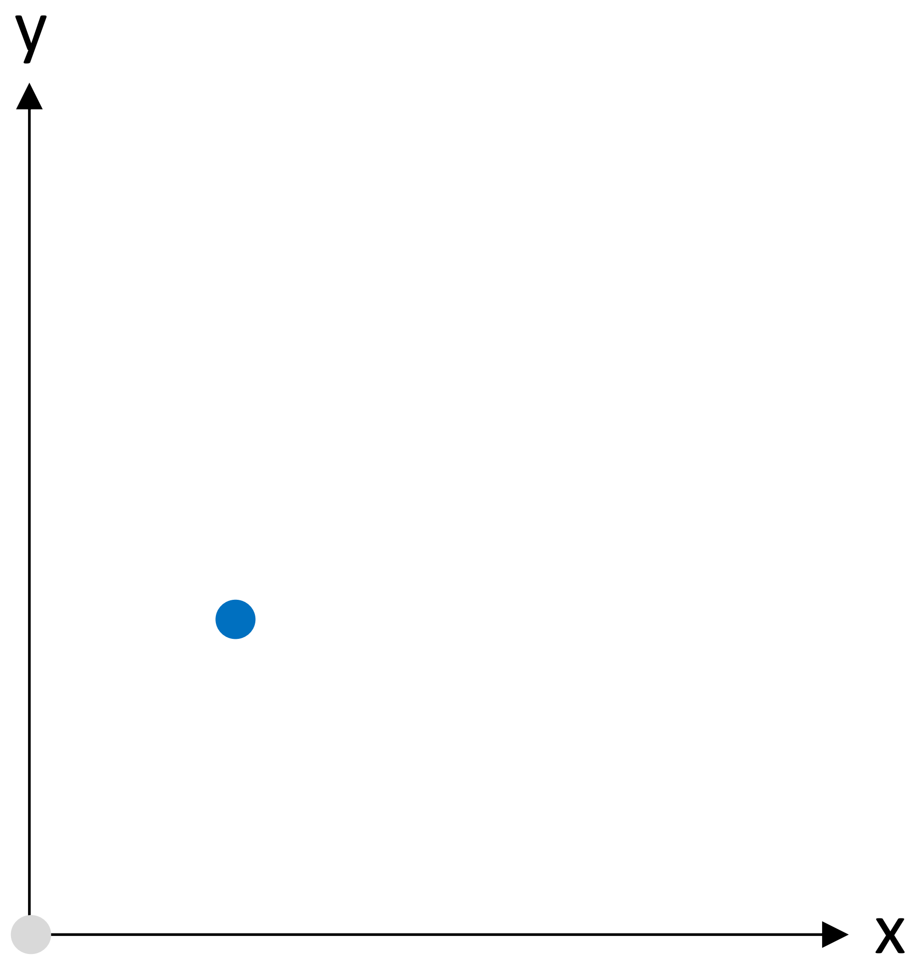


Stochastic Gradient Descent

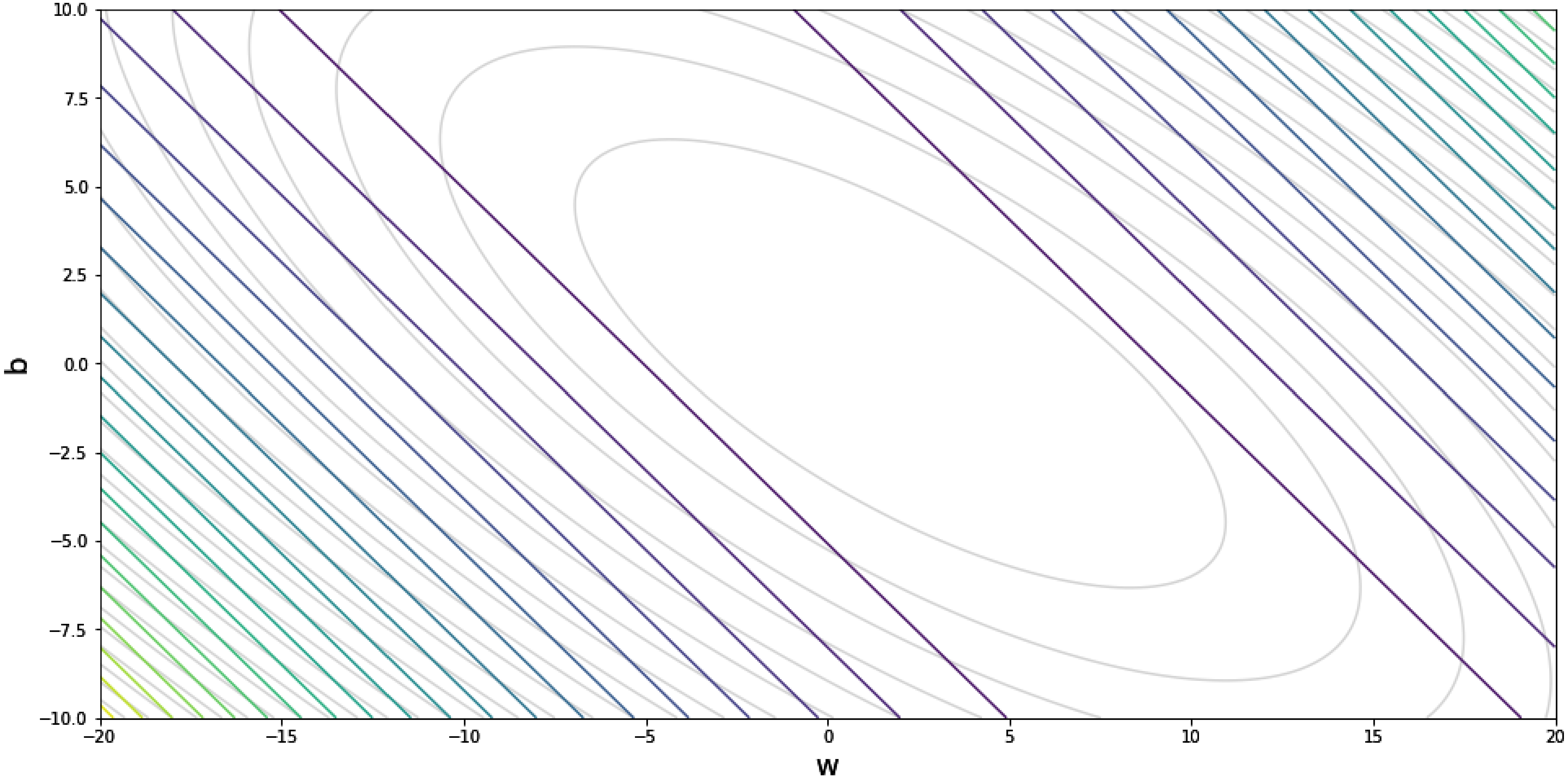


Linear Regression

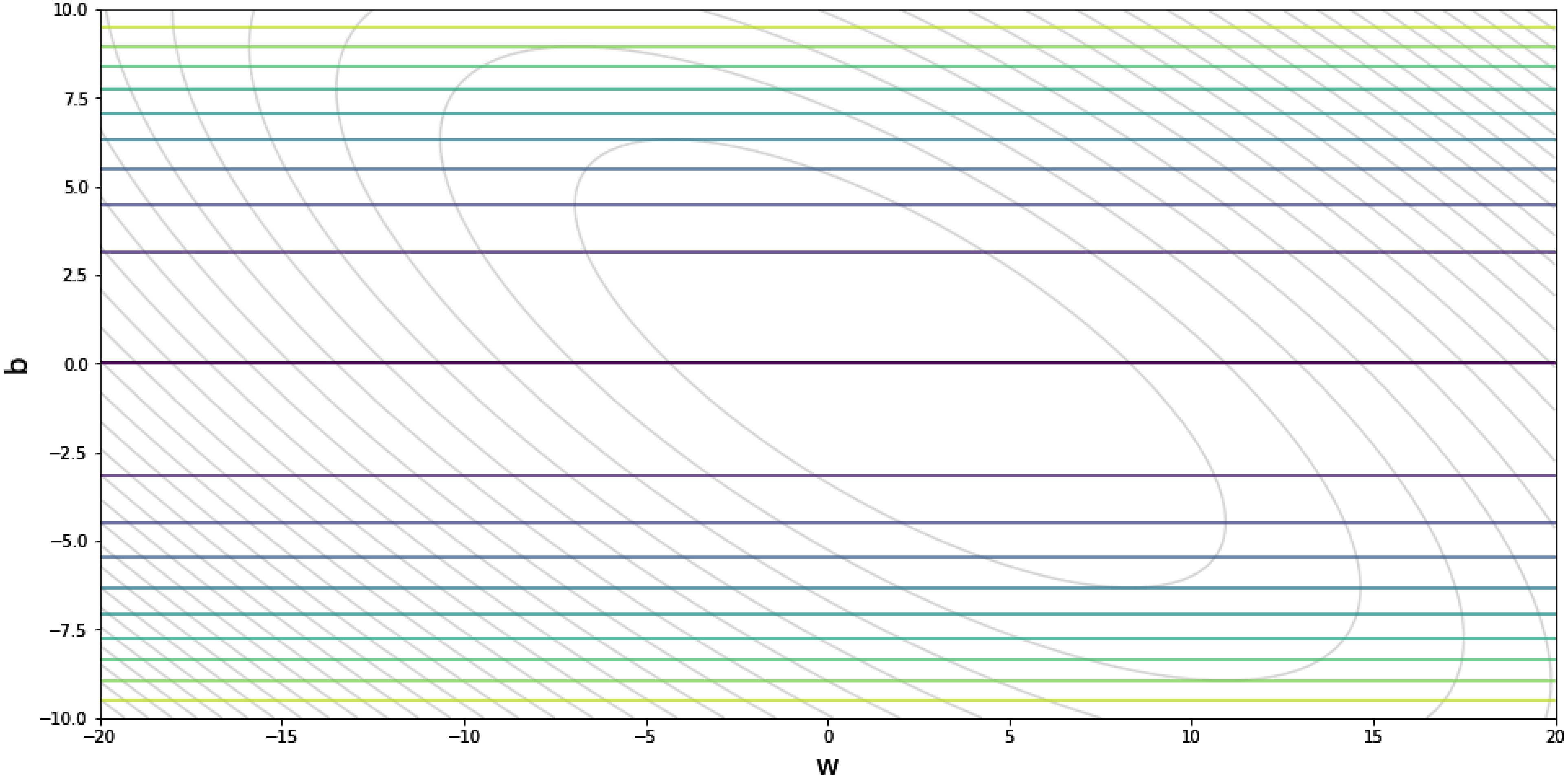
Optimizing the objective



Stochastic Gradient Descent



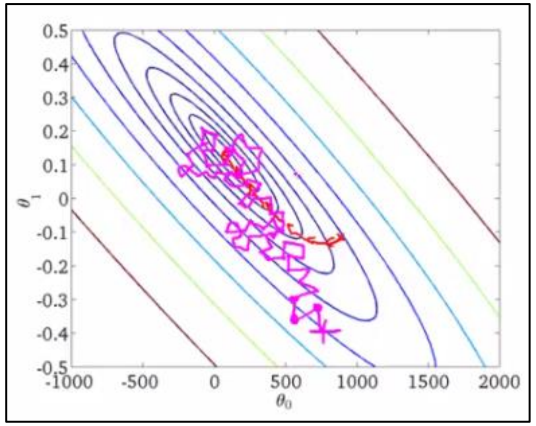
Stochastic Gradient Descent



Stochastic Gradient Descent (SGD)

Algorithm 2 Stochastic Gradient Descent (SGD)

procedure SGD($\mathcal{D}, \boldsymbol{\theta}^{(0)}$)
  $\boldsymbol{\theta} \leftarrow \boldsymbol{\theta}^{(0)}$
  while not converged **do**
    $i \sim$ Uniform$(\{1, 2, \ldots, N\})$
    $\boldsymbol{\theta} \leftarrow \boldsymbol{\theta} - \lambda \nabla_{\boldsymbol{\theta}} J^{(i)}(\boldsymbol{\theta})$
  return θ



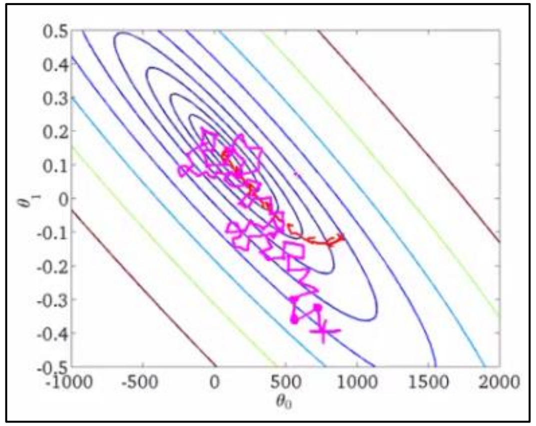
We need a per-example objective:

$$\text{Let } J(\boldsymbol{\theta}) = \sum_{i=1}^{N} J^{(i)}(\boldsymbol{\theta})$$

Stochastic Gradient Descent (SGD)

Algorithm 2 Stochastic Gradient Descent (SGD)

procedure SGD($\mathcal{D}$, $\boldsymbol{\theta}^{(0)}$)
    $\boldsymbol{\theta} \leftarrow \boldsymbol{\theta}^{(0)}$
    while not converged **do**
        for $i \in$ shuffle$(\{1, 2, \ldots, N\})$ **do**
            $\boldsymbol{\theta} \leftarrow \boldsymbol{\theta} - \gamma \nabla_{\boldsymbol{\theta}} J^{(i)}(\boldsymbol{\theta})$
    return $\boldsymbol{\theta}$

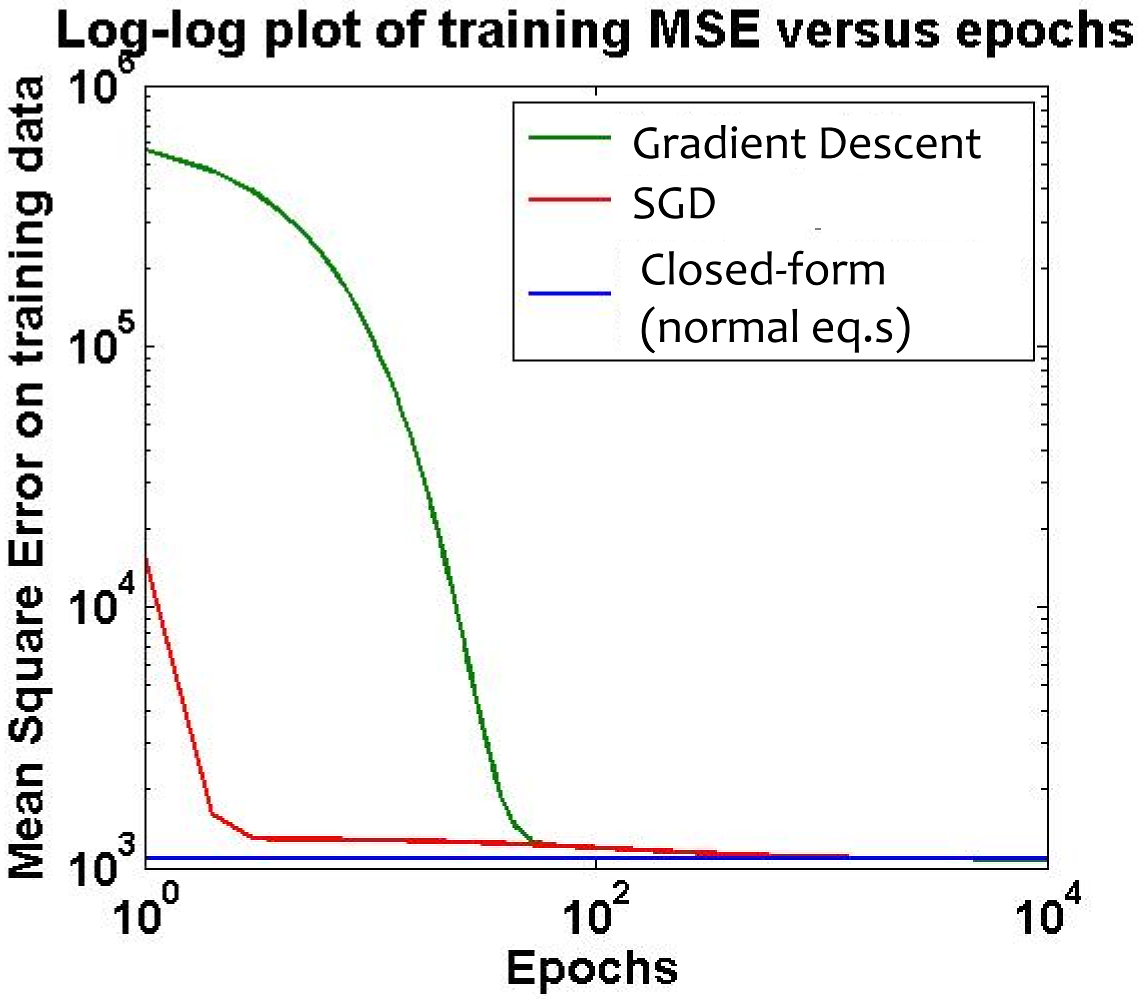


In practice, it is common to implement SGD using sampling **without** replacement (i.e. shuffle({1,2,…N}), even though most of the theory is for sampling **with** replacement (i.e. Uniform({1,2,…N}).

We need a per-example objective:

$$\text{Let } J(\boldsymbol{\theta}) = \sum_{i=1}^{N} J^{(i)}(\boldsymbol{\theta})$$

Convergence Curves



- *Def*: an **epoch** is a single pass through the training data

1. For GD, only **one update** per epoch
2. For SGD, ***N* updates** per epoch
   N = (# train examples)

- SGD reduces MSE much more rapidly than GD
- For GD / SGD, training MSE is initially large due to uninformed initialization

Slide credit: CMU MLD Matt Gormley and Eric P. Xing