1 Logic Recap

- 1. Vocabulary check: Are you familiar with the following terms?
 - Symbols:

Variables that can be T/F (capital letter)

• Operators:

And (\wedge) , Or (\vee) , Implies (\Rightarrow) , Equivalent (\iff)

• Sentences:

Symbols connected with operators, can be T/F

• Equivalence:

True in all models that A and B imply each other (A equivalent to B)

• Literals:

Atomic Sentence

• Knowledge Base:

Sentences known to be true

• Entailment:

A entails B iff for every model that satisfies A, B is also true

• Clauses (Definite vs. Horn Clauses):

Clause: A conjunction of literals **Definite Clause**: Clause with exactly one positive literal **Horn Clause**: Clause with at most one positive literal

• Model Checking:

Check if sentences are true in given model/check entailment

• Theorem Proving:

Search for sequence of proof steps (e.g. Forward Chaining)

• Modus Ponens:

From P and $(P \Rightarrow Q)$, infer Q

- 2. Recall the definitions of satisfiability and entailment.
 - Satisfiability:

A sentence is *satisfied by* some model (an assignment of values to variables) m if m makes the sentence true.

A sentence is satisfiable if there exists a model that satisfies it.

• Entailment:

Entailment: $a \models b$ ("a entails b" or "b follows from a") iff every model that satisfies a also satisfies b. In other words, the a-worlds (worlds where a is true) are a subset of the b-worlds [models(a) \subseteq models(b)].

3. What is the difference between satisfiability and entailment?

Satisfiability holds if there exists a single model that in which the sentence is true. This is a property of a sentence (a sentence is satisfiable or it is not).

Entailment holds if all models which satisfy one sentence (query) also satisfy another sentence (knowledge base). It relates two sentences (sentence a entails b, or a does not entail b), and requires checking all models that satisfy a.

4. Suppose $A \models B$. Consider all models assigning values to variables in sentences A and B. Which of the following sentences must be true in all possible models (even if either or both A/B are false)?

(a) $A \wedge B$	(c) $B \Rightarrow A$	(e) B
(b) $A \Rightarrow B$	(d) $A \lor B$	

(b) $A \Rightarrow B$

By definition of implication, in all models (i.e., truth assignments) where A is true, B is also true. Thus in all models, $A \Rightarrow B$ is satisfied.

(Thinking of it conversely, there would never be a model where B is false and A is true. By definition of implication, this means no model the rule $A \Rightarrow B$.)

- 5. Determine which of the following are correct, and explain your reasoning.
 - $(A \lor B) \models (A \Rightarrow B)$

False (when A is true and B is False, $A \lor B$ is true but $A \Rightarrow B$ is false)

• $A \iff B \models A \lor \neg B$

True (the RHS is $B \Rightarrow A$, which is one of the conjuncts in the definition of $A \iff B$)

• $(A \lor B) \land \neg (A \Rightarrow B)$ is satisfiable

True (the model has A and $\neg B$)

6. How would we formulate the SAT problem as a CSP? What are the variables? Domains? Constraints?

SAT can be modeled as a CSP in which the variables are literals with domain $\{\top, \bot\}$, and the constraints are the clauses themselves.

7. Suppose we have an algorithm which determines whether a sentence is satisfiable or not. Given two sentences A and B, how could we determine whether $A \models B$?

If $A \models B$, then $A \land \neg B$ should be unsatisfiable (this is proof via reductio ad absurdum - reduction to an absurd thing).

2 SATurdays are for everyone

1. Determine whether the sentences below are satisfiable or unsatisfiable (using any method you like).

(a)
$$(\neg (Y \lor \neg Y) \lor X) \land (X \lor (Z \iff \neg Z))$$

Satisfiable

Logical reduction:

 $(\neg (Y \lor \neg Y) \lor X) \land (X \lor (Z \iff \neg Z))$ original sentence $((\neg Y \land Y) \lor X) \land (X \lor (Z \iff \neg Z))$ De Morgan's Law $(\bot \lor X) \land (X \lor (Z \iff \neg Z))$ $(\neg Y \land Y)$ reduces to \bot $X \land (X \lor (Z \iff \neg Z))$ $(\perp \lor X)$ reduces to X $X \land (X \lor ((Z \Rightarrow \neg Z) \land (\neg Z \Rightarrow Z)))$ **Biconditional Elimination** $X \wedge (X \vee ((\neg Z \vee \neg Z) \wedge (Z \vee Z)))$ $(\neg Z \vee \neg Z)$ reduces to $\neg Z$, $(Z \vee Z)$ reduces to Z $X \wedge (X \vee (\neg Z \wedge Z))$ $(\neg Z \land Z)$ reduces to \bot $X \wedge (X \vee \bot)$ $(X \lor \bot)$ reduces to X $X \wedge X$ $(X \wedge X)$ reduces to X X

Assign $X = \top$. Then, we can choose any arbitrary assignment for Y and Z, and the sentence will be satisfied.

(b)
$$\neg (X \lor \neg (X \land (Z \lor \top))) \Longrightarrow \neg (Y \land (\neg Y \lor (\top \Longrightarrow \bot)))$$

Satisfiable

Logical reduction:

We can choose any arbitrary assignment for X, Y and Z and the sentence will be satisfied.

(c)
$$(((\top \iff \neg(X \lor \neg X)) \lor Z) \lor Z) \land \neg(Z \land ((Z \land \neg Z) \Longrightarrow X))$$

Unsatisfiable

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Logical reduction:

$(((\top \iff \neg(X \lor \neg X)) \lor Z) \lor Z) \land \neg(Z \land ((Z \land \neg Z) \Rightarrow X)))$	original sentence
$(((\top \iff \neg(\top)) \lor Z) \lor Z) \land \neg(Z \land ((Z \land \neg Z) \Rightarrow X))$	$(X \lor \neg X) \ reduces \ to \ \top$
$(((\top \iff \bot) \lor Z) \lor Z) \land \neg (Z \land ((Z \land \neg Z) \Rightarrow X))$	$\neg(\top) \ reduces \ to \perp$
$(((\top \Rightarrow \bot) \land (\bot \Rightarrow \top)) \lor Z) \lor Z) \land \neg (Z \land ((Z \land \neg Z) \Rightarrow X))$	Biconditional Elimination
$(((\bot \lor \bot) \land (\top \lor \top)) \lor Z) \lor Z) \land \neg (Z \land ((Z \land \neg Z) \Rightarrow X))$	Implication Elimination
$((\bot \land \top) \lor Z) \lor Z) \land \neg (Z \land ((Z \land \neg Z) \Rightarrow X))$	$(\perp \lor \perp)$ reduces to \perp , $(\top \lor \top)$ reduces to \top
$(\bot \lor Z) \lor Z) \land \neg (Z \land ((Z \land \neg Z) \Rightarrow X))$	$(\perp \wedge \top) \ reduces \ to \perp$
$Z \land \neg (Z \land ((Z \land \neg Z) \Rightarrow X))$	$((\perp \lor Z) \lor Z) \ reduces \ to \ Z$
$Z \land \neg (Z \land (\bot \Rightarrow X))$	$(Z \wedge \neg Z) \ reduces \ to \perp$
$Z \wedge \neg (Z \wedge (\top \lor X))$	Implication Elimination
$Z \wedge \neg (Z \wedge \top)$	$(\top \lor X) \ reduces \ to \ \top$
$Z \wedge \neg Z$	$(Z \wedge \top)$ reduces to Z
L	$Z \wedge \neg Z \ reduces \ to \perp$

This sentence is logically equivalent to $\bot,$ and therefore cannot be satisfied.

3 Wandering in Wumpus World

We bring together what we have learned in lecture as well as the ideas of search so far in order to construct wumpus world agents that use propositional logic. The first step is to enable the agent to deduce, to the extent possible, the state of the world given its percept history. This requires writing down a complete logical model of the effects of actions. We also show how the agent can keep track of the world efficiently without going into the percept history for each inference. Finally, we show how the agent can use logical inference to construct plans that are guaranteed to achieve its goals.

Try it out: http://thiagodnf.github.io/wumpus-world-simulator/ Note that there are some slight differences between this online version and the version we describe below.

Throughout this question, we will present several screenshots from the Wumpus World simulator linked previously. In each of these, assume that you *do* have an arrow on hand (as an extra exercise, consider how the answers might be different if you did not have an arrow). Also, note that the location of the explorer can be ignored. We just tried to place him somewhere where he wouldn't be blocking the text!

Recall that an agent in the Wumpus World has access to the following percepts:

- In the square containing the wumpus and in the directly (not diagonally) adjacent squares, the agent will perceive a Stench.
- In the squares directly adjacent to a pit, the agent will perceive a Breeze.
- In the square where the gold is, the agent will perceive a Glitter.
- When an agent walks into a wall, it will perceive a Bump.
- When the wumpus is killed, it emits a woeful Scream that can be perceived anywhere in the cave.
- 1. Consider the following Wumpus World state:



Figure 1: Entailment vs. Satisfiability?

Based on our previous discussion around entailment and satisfiability, identify locations where our knowledge base entails that there must be a Wumpus, Pit, or safe path. Additionally, identify locations where Wumpuses, Pit, and safe paths are not entailed but could be satisfied.

We've marked places where a pit (PT), wumpus (WP), safe (SF) can be satisfied with S-values. Entailments are indicated with E-values.



2. Take a moment to familiarize yourself with the pseudocode below to understand how we might decide to act in Wumpus World. You'll notice that we have labeled the key decision-making portions of this code, and that different decisions need to be made given the state of our knowledge base.

On the next page, match each of the following states to one of the labeled code chunks in the pseudocode, and explain your reasoning.

function HYBRID-WUMPUS-AGENT(percept) returns an action **inputs**: *percept*, a list, [*stench*, *breeze*, *qlitter*, *bump*, *scream*] **persistent**: *KB*, a knowledge base, initially the atemporal "wumpus physics" t, a counter, initially 0, indicating time plan, an action sequence, initially empty TELL(*KB*, MAKE-PERCEPT-SENTENCE(*percept*, *t*)) TELL the KB the temporal "physics" sentences for time t $\mathit{safe} \leftarrow \{[x, y] : \mathsf{ASK}(\mathit{KB}, \mathit{OK}^t_{x, y}) = \mathit{true}\}$ **if** ASK $(KB, Glitter^t) = true$ **then** Α $plan \leftarrow [Grab] + PLAN-ROUTE(current, \{[1,1]\}, safe) + [Climb]$ if *plan* is empty then $unvisited \leftarrow \{[x, y] : ASK(KB, L_{x,y}^{t'}) = false \text{ for all } t' \leq t\}$ В $plan \leftarrow PLAN-ROUTE(current, unvisited \cap safe, safe)$ if plan is empty and ASK $(KB, HaveArrow^t) = true$ then $possible_wumpus \leftarrow \{[x, y] : ASK(KB, \neg W_{x,y}) = false\}$ С $plan \leftarrow PLAN-SHOT(current, possible_wumpus, safe)$ if plan is empty then // no choice but to take a risk $not_unsafe \leftarrow \{[x, y] : ASK(KB, \neg OK_{x, y}^t) = false\}$ D $plan \leftarrow PLAN-ROUTE(current, unvisited \cap not_unsafe, safe)$ if *plan* is empty then E $plan \leftarrow PLAN-ROUTE(current, \{[1, 1]\}, safe) + [Climb]$ $action \leftarrow POP(plan)$ TELL(KB, MAKE-ACTION-SENTENCE(action, t)) $t \leftarrow t + 1$ return action

function PLAN-ROUTE(current,goals,allowed) returns an action sequence inputs: current, the agent's current position goals, a set of squares; try to plan a route to one of them allowed, a set of squares that can form part of the route

 $problem \leftarrow \text{ROUTE-PROBLEM}(current, goals, allowed)$ return A*-GRAPH-SEARCH(problem)

Figure 2: Hybrid-Wumpus-Agent from AIMA 3rd ed. It uses a propositional knowledge base to infer the state of the world, and a combination of problem-solving search and domain-specific code to decide what actions to take.

State	Code Chunk
Inter See 1 <td< th=""><th>C: There are two stenches within reasonable distance; therefore, based on satisfiability, it is possi- ble for a Wumpus to exist in the unvisited square diagonal from our explorer. There are also no guaranteed safe spaces. Since we have an arrow that we can use in case of Wumpus, we plan to shoot our arrow.</th></td<>	C: There are two stenches within reasonable distance; therefore, based on satisfiability, it is possi- ble for a Wumpus to exist in the unvisited square diagonal from our explorer. There are also no guaranteed safe spaces. Since we have an arrow that we can use in case of Wumpus, we plan to shoot our arrow.
	B: We have found an unvisited square free from breeze or stench. We know, based on our knowl- edge base, that this unvisited square must therefore also be safe and we can visit it.
	A: We have found gold, and we can grab it, and then plan the shortest, safest route out.
	D: There is no guaranteed safe square; therefore, we must take a risk.

Table 1: Which code chunk is applicable for each of these states?

4 Journey to Success(or-State Axioms)

1. First, let's review some definitions. What are successor-state axioms?

Successor-state axioms are axioms outlining what preconditions must be true in order to ensure that the state at the next time step will be specified. By definition, it is an axiom that sets the truth value of F^{t+1} (where F is some fluent, or changeable variable in an environment) in one of two ways:

- The action at time t causes F to be true at t + 1 (which refers to $ActionCausesF^t$)
- F was already true at time t and the action at time t does not cause it to be false.

It has the following schema: $F^{t+1} \iff ActionCausesF^t \lor (F^t \land \neg ActionCausesNotF^t)$. We use successor-state axioms to ensure that each state we compute is the result of legal action.

2. Consider the following Mini Pacman grid. In this simplified world, the only available actions are *Left*, *Right*, and *Stay*. The only possible states are $Pacman_{(1,1)}$ and $Pacman_{(2,1)}$. If Pacman tries to move into a wall, he will stay in the same state.

Notice that Pacman's state and actions are both fluent, so we can set up successor-state axioms to define how Pacman moves in this world. Write the successor-state axiom corresponding to Figure 4.







State at time t (Option 2)





 $\textbf{Successor-state axiom:} \quad Pacman^{t+1}_{(2,1)} \iff Right^t \lor (Pacman^t_{(2,1)} \land \neg Left^t)$

 $\begin{array}{l} F^{t+1} \text{ is } Pacman^{t+1}_{(2,1)} \\ ActionCausesF^t \text{ is } Right^t \\ (F^t \wedge \neg ActionCausesNotF^t) \text{ is } (Pacman^t_{(2,1)} \wedge \neg Left^t) \end{array}$

Think about how you could prevent Pacman from being in multiple states or taking multiple actions at the same time. You will get to explore this in P3!

3. Suppose that at time 0, Pacman is somewhere on a 5x5 grid ((1,1) at the bottom left, (5,5) at the top right) with only walls on the borders.

For each of the following, state whether the entailment relation is correct. Explain your reasoning.

(a) $Up^t \vee Right^t \models \neg Pacman^{t+1}_{(1,1)}$

True, there is no square that would lead to square (1,1) after moving up or right

(b) $\neg Pacman^{t+1}_{(1,1)} \models Up^t \lor Right^t$

False, a counterexample would be starting at square (3,2), and an action left leading to square (2,2)

(c) $Up^0 \wedge Up^2 \wedge Up^3 \models Pacman^4_{(x,y)} : x \in [1,5], y \in [4,5]$

False, this is almost true, however, if Pacman starts at row 1 and the action at step 1 was down, Pacman would end at row 3

(d) $Up^t \wedge Right^t \models \neg Pacman^{t+1}_{(5,5)}$

True

There is no model that fits the action at a time step being both Up and Right. Therefore, for every model that fits this, the right side must also be true (similar to being vacuously true for implications)

(e) $\neg Pacman^{t+1}_{(5,5)} \models Up^t \land Right^t$

False, since there is no model such that the right side is true, and there is at least one model such that the left side is true

(f) $Down^{t+1} \wedge Left^{t+1} \models Up^t \wedge Right^t$

True, since there are no valid models in the left or the right (similar to False \implies False)