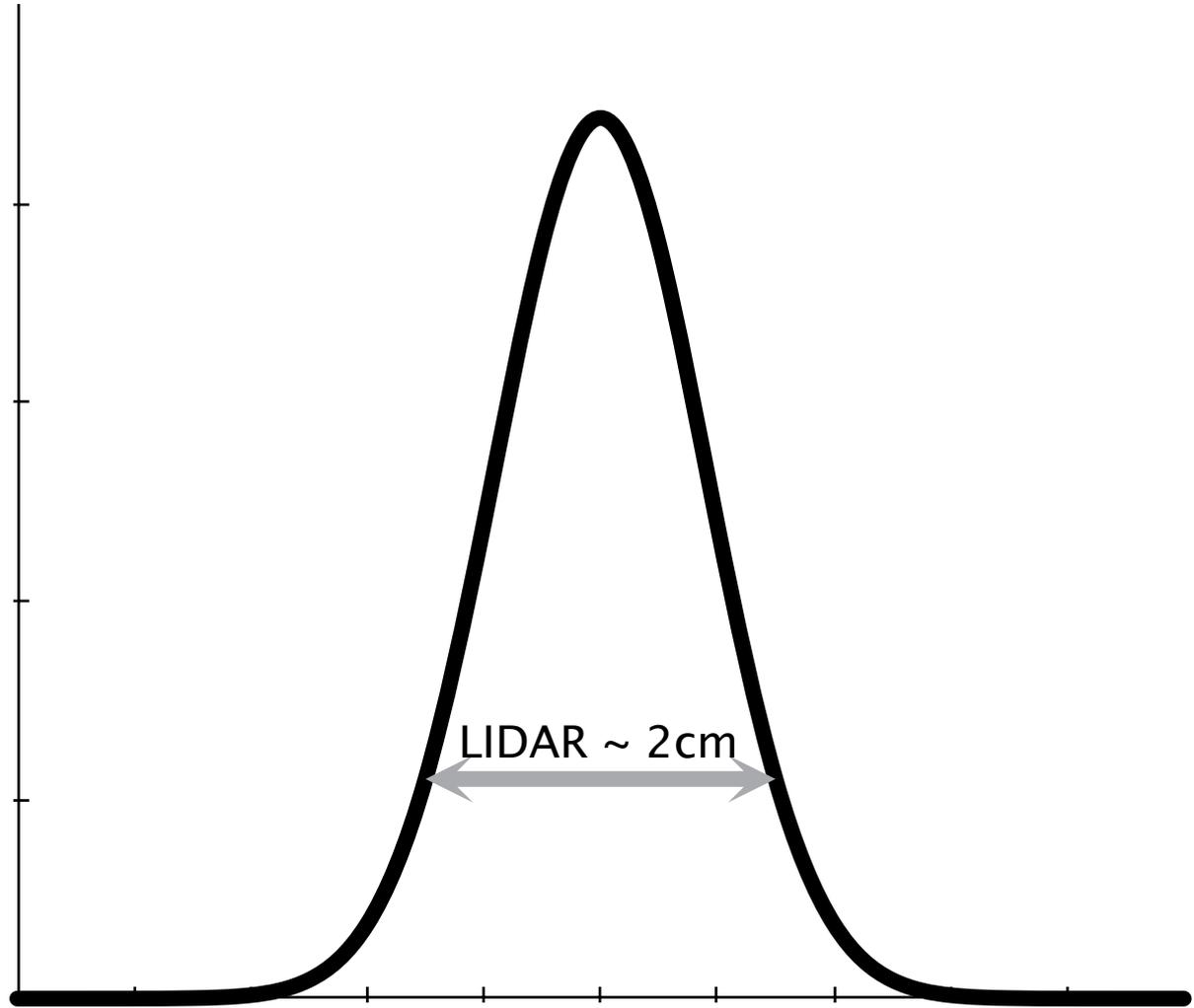


Probability



LIDAR ~ 2cm

z_{exp}

Measurement