10-315: Intro to Machine Learning



Probability Review

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Sources

Chris Cremer's slides

https://www.cs.toronto.edu/~urtasun/courses/CSC411/tutorial1.pdf

Jeff Howbert's slides

https://courses.washington.edu/css490/2012.Winter/lecture_slides/02_math_essentials.pdf

Aarti Singh's slides

https://www.cs.cmu.edu/~aarti/Class/10315_Fall19/lecs/Lecture2.pdf

Sample Space

- The sample space Ω is the set of possible outcomes of an experiment. Points ω in Ω are called sample outcomes, realizations, or elements. Subsets of Ω are called Events.
- Example. If we toss a coin twice then $\Omega = \{HH, HT, TH, TT\}$. The event that the first toss is heads is A = $\{HH, HT\}$
- We say that events A1 and A2 are disjoint (mutually exclusive) if Ai ∩ Aj = {}
 - Example: first flip being heads and first flip being tails

Probability

- We will assign a real number P(A) to every event A, called the probability of A.
- To qualify as a probability, P must satisfy three axioms:
 - Axiom 1: $P(A) \ge 0$ for every A
 - Axiom 2: P(Ω) = 1
 - Axiom 3: If A1, A2, . . . are disjoint then

$$\mathbb{P}\left(\bigcup_{i=1}^{\infty}A_i\right) = \sum_{i=1}^{\infty}\mathbb{P}(A_i)$$

Joint and Conditional Probabilities

- Joint Probability
 - P(X,Y)
 - Probability of X and Y
- Conditional Probability
 - P(X|Y)
 - Probability of X given Y

Example of multivariate distribution



Multivariate probability distributions

- Marginal probability
 - Probability distribution of a single variable in a joint distribution
 - Example: two random variables X and Y:

$$p(X = x) = \sum_{b=all \text{ values of } Y} p(X = x, Y = b)$$

Conditional probability

- Probability distribution of one variable given that another variable takes a certain value
- Example: two random variables X and Y:

$$p(X = x | Y = y) = p(X = x, Y = y) / p(Y = y)$$

Example of marginal probability





Example of conditional probability



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Complement rule

Given: event A, which can occur or not

$$p(\text{ not } A) = 1 - p(A)$$



Product rule

Given: events A and B, which can co-occur (or not)

 $p(A, B) = p(A | B) \cdot p(B)$

(same expression given previously to define conditional probability)



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Rule of total probability

Given: events A and B, which can co-occur (or not)

$$p(A) = p(A, B) + p(A, not B)$$

(same expression given previously to define marginal probability)



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Marginalization and Law of Total Probability

• Marginalization (Sum Rule)

$$p(x) = \sum_{y} p(x, y)$$

• Law of Total Probability

$$p(x) = \sum_{y} p(x \mid y) \cdot p(y)$$

Indicator Random Variables

Let *A* be an event. Then $\mathbf{1}_A$ is random variable such that -



Important!

$$\mathbb{E} \left[\mathbf{1}_{A} \right] = P(A)$$

Why? $\mathbb{E}[\mathbf{1}_{A}] = 1.P(A) + 0.P(\neg A) = P(A)$

Independence

Given: events A and B, which can co-occur (or not)

p(A | B) = p(A) or $p(A, B) = p(A) \cdot p(B)$



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Independent and Conditional Probabilities

- Assuming that P(B) > 0, the **conditional** probability of A given B:
- P(A|B)=P(AB)/P(B)
- P(AB) = P(A|B)P(B) = P(B|A)P(A)
 - Product Rule
- Two events A and B are independent if
- P(AB) = P(A)P(B)
 - Joint = Product of Marginals
- Two events A and B are conditionally independent given C if they are independent after conditioning on C
- P(AB|C) = P(B|AC)P(A|C) = P(B|C)P(A|C)

Example

- 60% of ML students pass the final and 45% of ML students pass both the final and the midterm *
- What percent of students who passed the final also passed the midterm?

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- 60% of ML students pass the final and 45% of ML students pass both the final and the midterm *
- What percent of students who passed the final also passed the midterm?
- Reworded: What percent of students passed the midterm given they passed the final?
- P(M|F) = P(M,F) / P(F)
- = .45 / .60
- = .75

* These are made up values.

Bayes' Rule

P(A|B) = P(AB) / P(B) P(A|B) = P(B|A)P(A) / P(B) $P(A|B) = P(B|A)P(A) / \Sigma P(B|A)P(A)$

(Conditional Probability) (Product Rule) (Law of Total Probability)

$$P(A|B) = \frac{P(A) P(B|A)}{P(B)}$$
$$P(B) = \sum_{j} P(B | A_j) P(A_j)$$



Rev. Thomas Bayes

Bayes' Rule

$$P(A|B) = \frac{P(A) P(B|A)}{P(B)}$$
$$p(\theta|x) = \frac{p(x|\theta)p(\theta)}{p(x)}.$$

Posterior = Likelihood * Prior Evidence

Posterior probability \propto Likelihood \times Prior probability



Image from xkcd.com

Example of Bayes rule

- Marie is getting married tomorrow at an outdoor ceremony in the desert. In recent years, it has rained only 5 days each year. Unfortunately, the weatherman is forecasting rain for tomorrow. When it actually rains, the weatherman has forecast rain 90% of the time. When it doesn't rain, he has forecast rain 10% of the time. What is the probability it will rain on the day of Marie's wedding?
- Event A: The weatherman has forecast rain.
- Event *B*: It rains.
- We know:
 - p(B) = 5/365 = 0.0137 [It rains 5 days out of the year.]
 - p(not B) = 360 / 365 = 0.9863
 - p(A | B) = 0.9 [When it rains, the weatherman has forecast rain 90% of the time.]
 - $p(A \mid \text{not } B) = 0.1$ [When it does not rain, the weatherman has forecast rain 10% of the time.]

Example of Bayes rule, cont'd.

- We want to know p(B | A), the probability it will rain on the day of Marie's wedding, given a forecast for rain by the weatherman. The answer can be determined from Bayes rule:
- 1. $p(B | A) = p(A | B) \cdot p(B) / p(A)$
- 2. $p(A) = p(A | B) \cdot p(B) + p(A | not B) \cdot p(not B) =$ (0.9)(0.014) + (0.1)(0.986) = 0.111
- 3. p(B | A) = (0.9)(0.0137) / 0.111 = 0.111
- The result seems unintuitive but is correct. Even when the weatherman predicts rain, it only rains only about 11% of the time. Despite the weatherman's gloomy prediction, it is unlikely Marie will get rained on at her wedding.

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Discrete vs Continuous Random Variables

- Discrete: can only take a countable number of values
- Example: number of heads
- Distribution defined by probability mass function (pmf)
- Marginalization: $p(x) = \sum_{y \in Y} p(x, y)$
- Continuous: can take infinitely many values (real numbers)
- Example: time taken to accomplish task
- Distribution defined by probability density function (pdf)
- Marginalization:

$$p(x) = \int_{y} p(x, y) dy$$

Probability Distribution Statistics

- Mean: $E[x] = \mu = first moment = \int_{-\infty}^{\infty} xf(x) dx$ Univariate continuous random variable $=\sum x_i p_i$ Univariate discrete random variable i=1• Variance: Var(X) = $E[(X - \mu)^2]$ $= \mathbf{E}\left[(X - \mathbf{E}[X])^2 \right]$ $= E [X^{2} - 2X E[X] + (E[X])^{2}]$ $= E[X^2] - 2E[X]E[X] + (E[X])^2$ $= \mathrm{E}\left[X^2\right] - (\mathrm{E}[X])^2$
- Nth moment = $\int_{-\infty}^{\infty} (x-c)^n f(x) dx$

Bernoulli Distribution

- Input: $x \in \{0, 1\}$
- Parameter: μ
- Example: Probability of flipping heads (x=1)

$$\operatorname{Bern}(x|\mu) = \mu^x (1-\mu)^{1-x}$$

- Mean = $E[x] = \mu$
- Variance = $\mu(1 \mu)$



Discrete Distribution

Binomial Distribution

- Input: m = number of successes
- Parameters: N = number of trials

 μ = probability of success



- Example: Probability of flipping heads m times out of N independent flips with success probability μ

$$\operatorname{Bin}(m|N,\mu) = \binom{N}{m} \mu^m (1-\mu)^{N-m}$$

- Mean = $E[x] = N\mu$
- Variance = $N\mu(1 \mu)$

Multinomial Distribution

- The multinomial distribution is a generalization of the binomial distribution to k categories instead of just binary (success/fail)
- For n independent trials each of which leads to a success for exactly one of k categories, the multinomial distribution gives the probability of any particular combination of numbers of successes for the various categories
- Example: Rolling a die N times

Multinomial Distribution

- Input: m₁ ... m_K (counts)
- Parameters: N = number of trials

 $\mu = \mu_1 \dots \mu_K$ probability of success for each category, $\Sigma \mu = 1$

Mult
$$(m_1, m_2, \dots, m_K | \mu, N) = \binom{N}{m_1 m_2 \dots m_K} \prod_{k=1}^K \mu_k^{m_k}$$

- Mean of m_k : $N\mu_k$
- Variance of m_k : $N\mu_k(1-\mu_k)$

1-dim Gaussian distribution

X is Gaussian N(μ , σ^2)

$$P(X = x | \mu, \sigma) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{\frac{-(x-\mu)^2}{2\sigma^2}}$$



Gaussian Distribution

• Gaussians with different means and variances



d-dim Gaussian distribution

X is Gaussian N(μ , Σ) μ is d-dim vector, Σ is dxd dim matrix

$$P(X = x | \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{\sqrt{(2\pi)^d |\boldsymbol{\Sigma}|}} \exp\left(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^{\mathrm{T}} \boldsymbol{\Sigma}^{-1}(\mathbf{x} - \boldsymbol{\mu})\right),$$

 $\begin{array}{c} X_{2} \\ d=2 \\ X = [X_{1}; X_{2}] \end{array}$

Questions?