1 Learning Theory

1.1 Review

Def 1. *PAC Bound* - *Probably Approximately correct.* δ *parameter controls probability of correctness,* ϵ *parameter controls error rate.*

Different bounds for different use cases:

Prop 1. When $error_{train} = 0$ Haussler's bound tells us

$$error_{true}(h) \le \epsilon = \frac{\ln|H| + \ln(1/\delta)}{m}$$

Prop 2. In general Hoeffding's bound tells us

$$error_{true} \le \epsilon + error_{train} = error_{train} + \sqrt{\frac{\ln(|H|) + \ln(1/\delta)}{2m}}$$

What is the relationship between Haussler and Hoeffding? Which one is tighter when applicable?

Prop 3. When the model class is infinite use VC Dimension:

$$error_{true}(h) \le error_{train}(h) + 8\sqrt{\frac{VC(H)(ln(m/VC(H)) + 1) + ln(8/\delta)}{2m}}$$

Is VC bound tighter or weaker than the other bounds? What's a drawback to attempting to use the VC bound?

1.2 Problems

Problem 1. What is the VC Dimension of affine classifiers in \mathbb{R}^n ? Prove this

n+1. Consider the n simplex.

Problem 2. Consider classifier $f(sin(\alpha x))$ where f = 1 when x > 0 and 0 otherwise. α adjustble. What is the VC dimension?

Infinite since can adjust α .

For each of the below questions, **pick the formula** you would use to estimate the number of examples you would need to learn the concept. You do not need to do any computation or plug is any numbers. Explain your answer.

- 1. (2 pts) Consider instances with two Boolean variables $\{X_1, X_2\}$, and responses Y are given by the XOR function. We try to learn the function $f: X \to Y$ using a 2-layer neural network
- 2. (2 pts) Consider instances with two Boolean variables $\{X_1, X_2\}$, and responses Y are give by the XOR function. We try to learn the function $f : X \to Y$ using a *depth-two decisio tree*. This tree has four leaves, all distance two from the top.

Problem 3.

i) VC since dimension infinite

ii) Haussler since classifiers finite

2 Kernelization

2.1 Problems

Problem 4. Given kernel $K(x, y) = (1 + x \cdot y)^d$ what is the dimensionality of the corresponding feature map? Polynomial in n, d.

Problem 5. Prove a kernel K(x, y) is symmetric.

Write as feature map product.

Problem 6. Prove the kernel matrix A where $A_{ij} = K(x_i, x_j)$ is positive semi-definite.

 $A = B^T B$ where B is vector of feature maps. Then