

# MLE/MAP for learning distributions

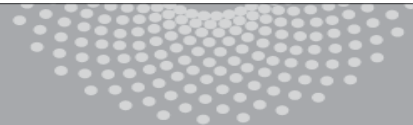
Aarti Singh

Machine Learning 10-701

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**MACHINE LEARNING** DEPARTMENT



**Carnegie Mellon.**  
School of Computer Science

# Distribution of Inputs

Input  $X \in \mathcal{X}$

Discrete Probability Distribution  $P(X) = P(X=x)$

e.g.  $P(\text{head}) = \frac{1}{2}$ ,  $P(\text{word } x \text{ in text}) = p_x$



Probabilities in a distribution sum to 1

$$\sum_x P(X=x) = 1 \quad P(\text{tail}) = 1 - p(\text{head}), \sum_x p_x = 1$$

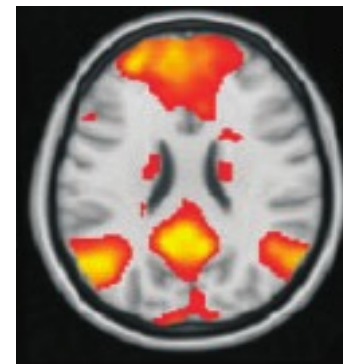
Continuous Probability density  $p(x)$

e.g.  $p(\text{brain activity})$

$$P(a \leq X \leq b) = \int_a^b p(x) dx$$

Probability density integrate to 1

$$\int p(x) dx = 1$$



# Distributions in Supervised tasks

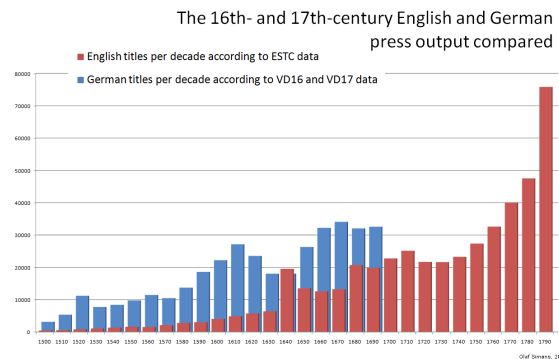
**Input**  $X \in \mathcal{X}$

- Distribution learning also arises in supervised learning tasks e.g. classification

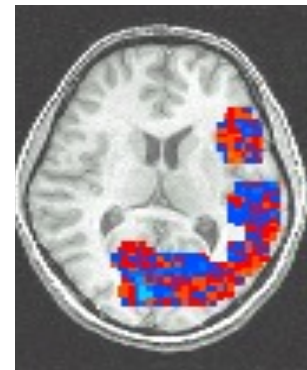
$P(Y = y)$                       Distribution of class labels

$P(X = x \mid Y = y)$       Distribution of words in 'news' documents

                                         Distribution of brain activity under 'stress'



Olaf simons'10



$P(Y = y \mid X = x)$       Distribution of topics given document

**How to learn parameters from data?**

**MLE**

**(Discrete case)**

# Learning parameters in distributions

$$P(Y = \bullet) = \theta$$

$$P(Y = \bullet) = 1 - \theta$$

Learning  $\theta$  is equivalent to learning probability of head in coin flip.

➤ How do you learn that?

Data =



Answer: 3/5

➤ Why??

# Bernoulli distribution

Data,  $D =$



- Parameter  $\theta$  :  $P(\text{Heads}) = \theta$ ,  $P(\text{Tails}) = 1-\theta$
- Flips are **i.i.d.**:
  - **Independent** events
  - **Identically distributed** according to Bernoulli distribution

Choose  $\theta$  that maximizes the probability of observed data  
aka Likelihood

# Maximum Likelihood Estimation (MLE)

Choose  $\theta$  that maximizes the probability of observed data (aka likelihood)

$$\hat{\theta}_{MLE} = \arg \max_{\theta} P(D | \theta)$$

MLE of probability of head:

$$\hat{\theta}_{MLE} = \frac{\alpha_H}{\alpha_H + \alpha_T} = 3/5$$

"Frequency of heads"

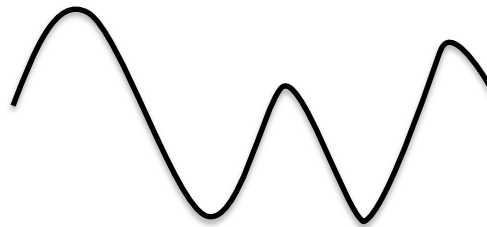
# Derivation

$$\hat{\theta}_{MLE} = \arg \max_{\theta} P(D | \theta)$$

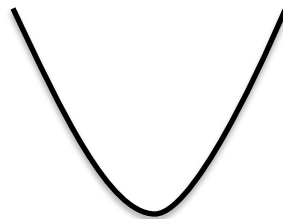


# Short detour - Optimization

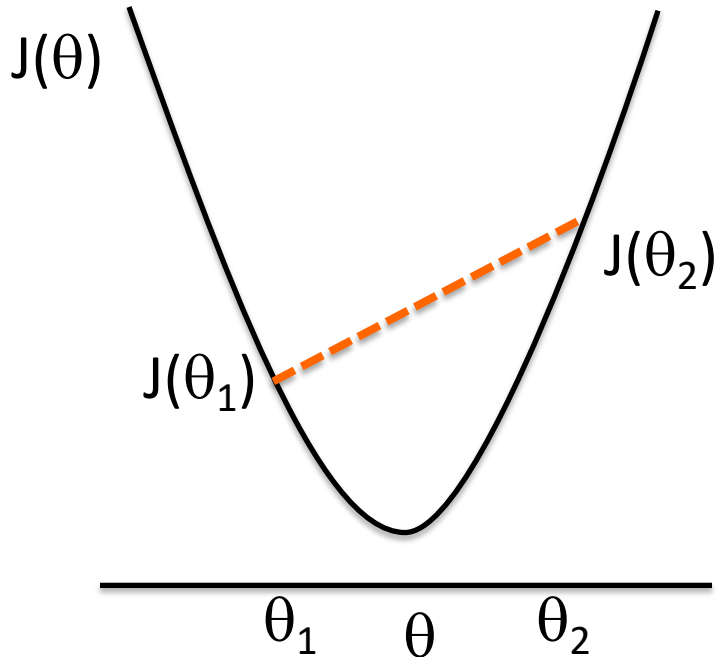
- Optimization objective  $J(\theta)$
- Minimum value  $J^* = \min_{\theta} J(\theta)$
- Minima (points at which minimum value is achieved) may not be unique



- If function is strictly convex, then minimum is unique

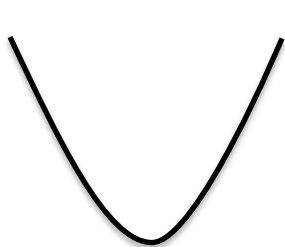


# Convex functions

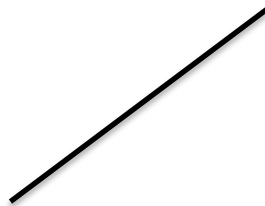


A function  $J(\theta)$  is called **convex** if the line joining two points  $J(\theta_1), J(\theta_2)$  on the function does not go below the function on the interval  $[\theta_1, \theta_2]$

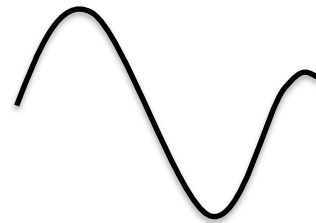
(Strictly) Convex functions have a unique minimum!



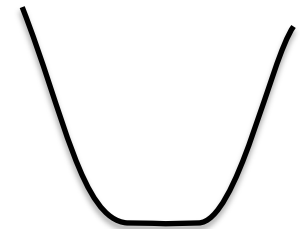
Convex



Both Concave & Convex



Neither



Convex but not strictly convex<sup>10</sup>

# Optimizing convex (concave) functions

- Derivative of a function
- Derivative is zero at minimum of a convex function
- Second derivative is positive at minimum of a convex function

# Optimizing convex (concave) functions

➤ What about

concave functions?

non-convex/non-concave functions?

derivative = 0 may not have analytic solution?

functions that are not differentiable?

optimizing a function over a bounded domain aka  
constrained optimization?

# Derivation

$$\hat{\theta}_{MLE} = \arg \max_{\theta} P(D | \theta)$$

# Categorical distribution

Data,  $D$  = rolls of a dice



- $P(1) = p_1, P(2) = p_2, \dots, P(6) = p_6 \quad p_1 + \dots + p_6 = 1$
- Rolls are **i.i.d.**:
  - **Independent** events
  - **Identically distributed** according to Categorical( $\theta$ ) distribution where

$$\theta = \{p_1, p_2, \dots, p_6\}$$

Choose  $\theta$  that maximizes the probability of observed data  
aka “Likelihood”

# Maximum Likelihood Estimation (MLE)

Choose  $\theta$  that maximizes the probability of observed data

$$\hat{\theta}_{MLE} = \arg \max_{\theta} P(D | \theta)$$

MLE of probability of rolls:

$$\hat{\theta}_{MLE} = \hat{p}_{1,MLE}, \dots, \hat{p}_{6,MLE}$$

$$\hat{p}_{y,MLE} = \frac{\alpha_y \leftarrow \text{Rolls that turn up } y}{\sum_y \alpha_y \leftarrow \text{Total number of rolls}}$$

“Frequency of roll  $y$ ”

**How to learn parameters from data?**

**MLE**

**(Continuous case)**

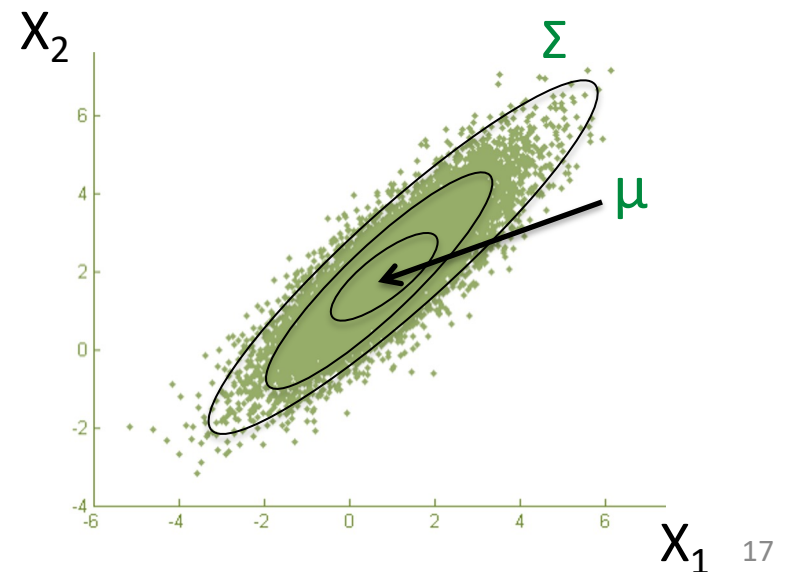
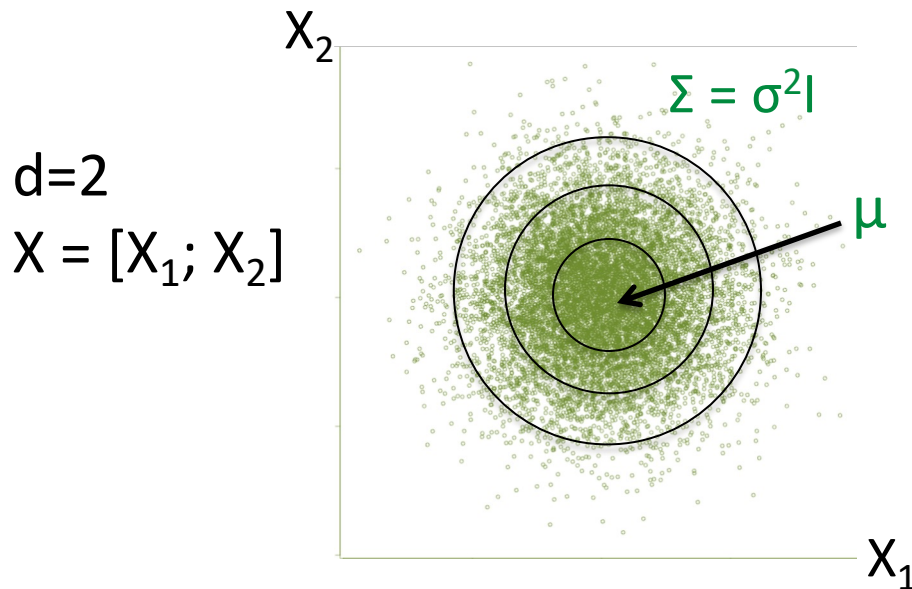


# d-dim Gaussian distribution

$X$  is Gaussian  $N(\mu, \Sigma)$

$\mu$  is d-dim vector,  $\Sigma$  is dxd dim matrix

$$P(X = x | \mu, \Sigma) = \frac{1}{\sqrt{(2\pi)^d |\Sigma|}} \exp\left(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{x} - \boldsymbol{\mu})\right),$$

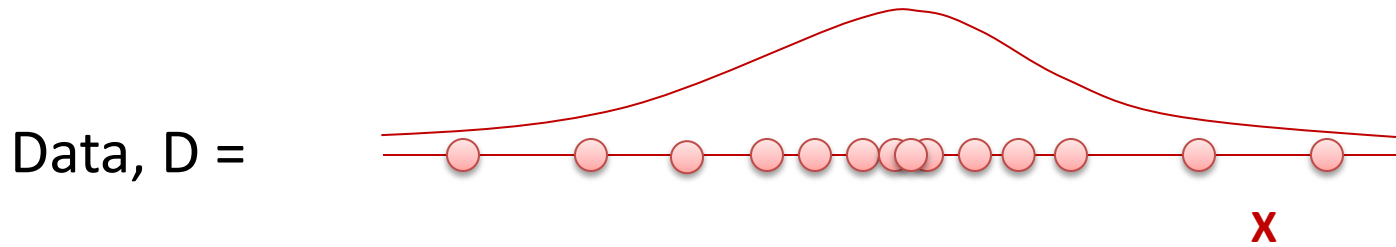


**How to learn parameters from data?**

**MLE**

**(Continuous case)**

# Gaussian distribution



- Parameters:  $\mu$  – mean,  $\sigma^2$  - variance
- Data are **i.i.d.**:
  - **Independent** events
  - **Identically distributed** according to Gaussian distribution

# Maximum Likelihood Estimation (MLE)

Choose  $\theta = (\mu, \sigma^2)$  that maximizes the probability of observed data

$$\begin{aligned}\hat{\theta}_{MLE} &= \arg \max_{\theta} P(D | \theta) \\ &= \arg \max_{\theta} \prod_{i=1}^n P(X_i | \theta) \quad \text{Independent draws}\end{aligned}$$

# Maximum Likelihood Estimation (MLE)

Choose  $\theta = (\mu, \sigma^2)$  that maximizes the probability of observed data

$$\begin{aligned}\hat{\theta}_{MLE} &= \arg \max_{\theta} P(D | \theta) \\ &= \arg \max_{\theta} \prod_{i=1}^n P(X_i | \theta) && \text{Independent draws} \\ &= \arg \max_{\theta} \prod_{i=1}^n \frac{1}{\sqrt{2\pi\sigma^2}} e^{-(X_i - \mu)^2 / 2\sigma^2} && \text{Identically distributed}\end{aligned}$$

# Maximum Likelihood Estimation (MLE)

Choose  $\theta = (\mu, \sigma^2)$  that maximizes the probability of observed data

$$\begin{aligned}\hat{\theta}_{MLE} &= \arg \max_{\theta} P(D | \theta) \\ &= \arg \max_{\theta} \prod_{i=1}^n P(X_i | \theta) \quad \text{Independent draws} \\ &= \arg \max_{\theta} \prod_{i=1}^n \frac{1}{\sqrt{2\pi\sigma^2}} e^{-(X_i - \mu)^2 / 2\sigma^2} \quad \text{Identically distributed} \\ &= \arg \max_{\theta = (\mu, \sigma^2)} \underbrace{\frac{1}{(2\pi\sigma^2)^{n/2}} e^{-\sum_{i=1}^n (X_i - \mu)^2 / 2\sigma^2}}_{J(\theta)}\end{aligned}$$

# MLE for Gaussian mean

➤ Poll

$$P(D|\theta) = \frac{1}{(2\pi\sigma^2)^{n/2}} e^{-\sum_{i=1}^n (X_i - \mu)^2 / 2\sigma^2}$$

A.  $\max_{\mu} \sum_{i=1}^n (X_i - \mu)^2$

C.  $\max_{\mu} \mu^2 - 2\mu \sum_{i=1}^n X_i$

B.  $\min_{\mu} \sum_{i=1}^n (X_i - \mu)^2$

D.  $\max_{\mu} n\mu^2 - 2\mu \sum_{i=1}^n X_i$

# MLE for Gaussian mean and variance

$$\hat{\mu}_{MLE} = \frac{1}{n} \sum_{i=1}^n x_i$$

$$\hat{\sigma}_{MLE}^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \hat{\mu})^2$$

Self exercise:

Derive MLE of variance?

Is the MLE of mean unbiased?

Is the MLE of variance unbiased?

How can you make it unbiased?

d-dimensional versions?

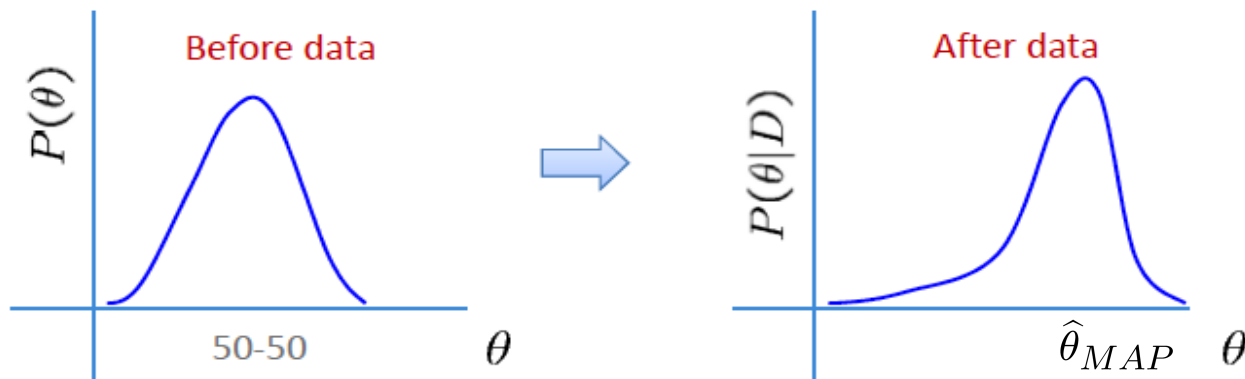
MLE for uniform or  
exponential  
distribution?



# Max A Posteriori (MAP) estimation

Can we bring in prior knowledge if data is not enough?

- Assume a prior (before seeing data  $D$ ) distribution  $P(\theta)$  for parameters  $\theta$



- Choose value that maximizes a posterior distribution  $P(\theta|D)$  of parameters  $\theta$

$$\begin{aligned}\hat{\theta}_{MAP} &= \arg \max_{\theta} P(\theta | D) \\ &= \arg \max_{\theta} P(D | \theta)P(\theta)\end{aligned}$$

# How to choose prior distribution?

- $P(\theta)$

- Prior knowledge about domain e.g. unbiased coin  $P(\theta) = 1/2$

- A mathematically convenient form e.g. “conjugate” prior

If  $P(\theta)$  is conjugate prior for  $P(D|\theta)$ , then Posterior has same form as prior

$$\text{Posterior} \propto \text{Likelihood} \times \text{Prior}$$

$$P(\theta|D) \propto P(D|\theta) \times P(\theta)$$

e.g.	Beta	Bernoulli	Beta	$\theta = \text{bias}$
	Dirichlet	Categorical	Dirichlet	$\theta = \text{bias vector}$
	Gaussian	Gaussian	Gaussian	$\theta = \text{mean } \mu$ (known $\Sigma$ )
	inv-Wishart	Gaussian	inv-Wishart	$\theta = \text{cov matrix } \Sigma$ (known $\mu$ )

# MAP estimation for Bernoulli r.v.

Choose  $\theta$  that maximizes a posterior probability

$$\begin{aligned}\hat{\theta}_{MAP} &= \arg \max_{\theta} P(\theta | D) \\ &= \arg \max_{\theta} P(D | \theta)P(\theta)\end{aligned}$$

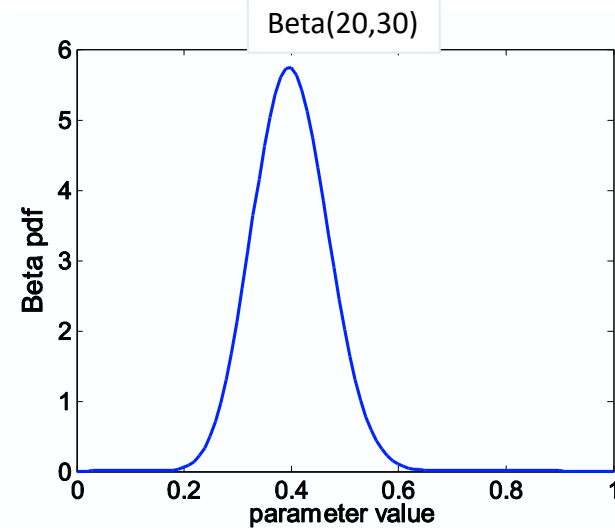
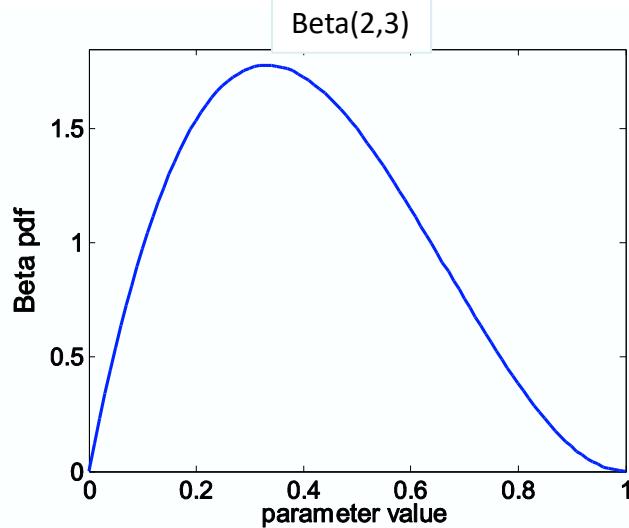
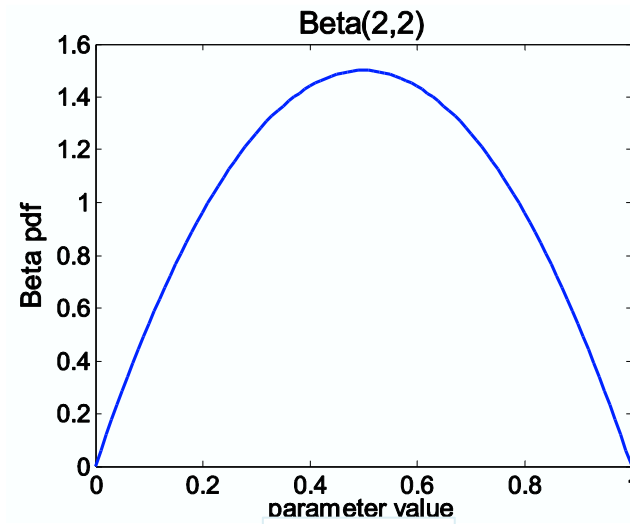
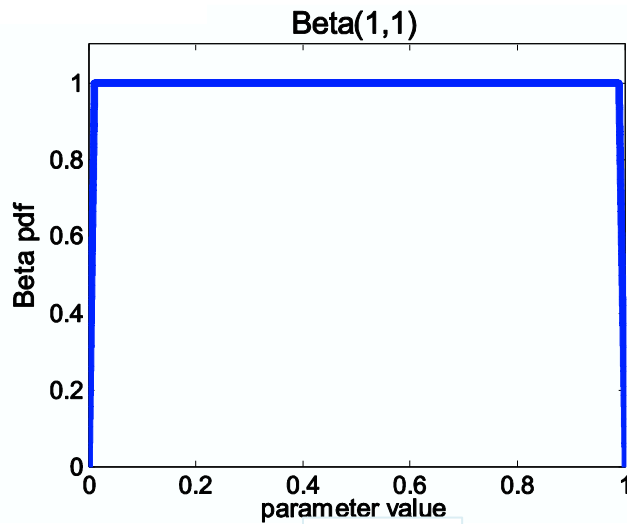
MAP estimate of probability of head (using Beta conjugate prior):

$$P(\theta) \sim \text{Beta}(\beta_H, \beta_T)$$

# Beta distribution

$Beta(\beta_H, \beta_T)$

More concentrated as values of  $\beta_H, \beta_T$  increase



# MAP estimation for Bernoulli r.v.

Choose  $\theta$  that maximizes a posterior probability

$$\begin{aligned}\hat{\theta}_{MAP} &= \arg \max_{\theta} P(\theta | D) \\ &= \arg \max_{\theta} P(D | \theta)P(\theta)\end{aligned}$$

MAP estimate of probability of head (using Beta conjugate prior):

$$P(\theta) \sim \text{Beta}(\beta_H, \beta_T)$$

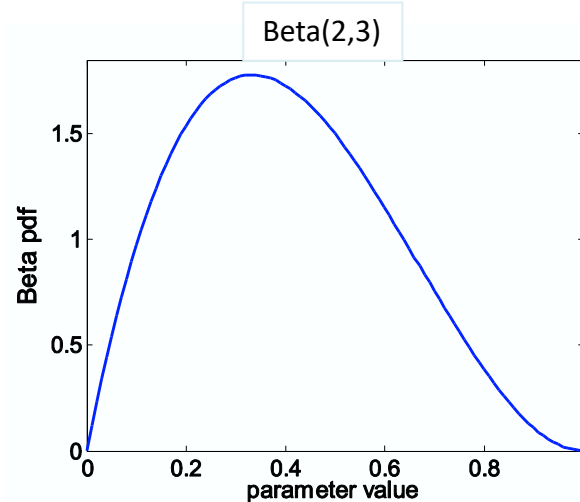
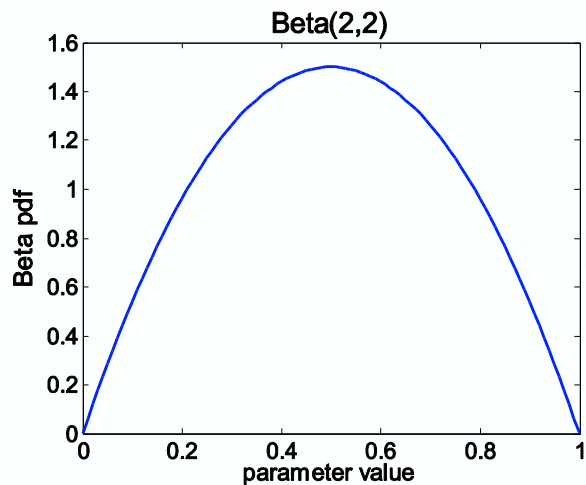
Count of H/T simply get  
added to parameters

$$P(\theta|D) \sim \text{Beta}(\beta_H + \alpha_H, \beta_T + \alpha_T)$$

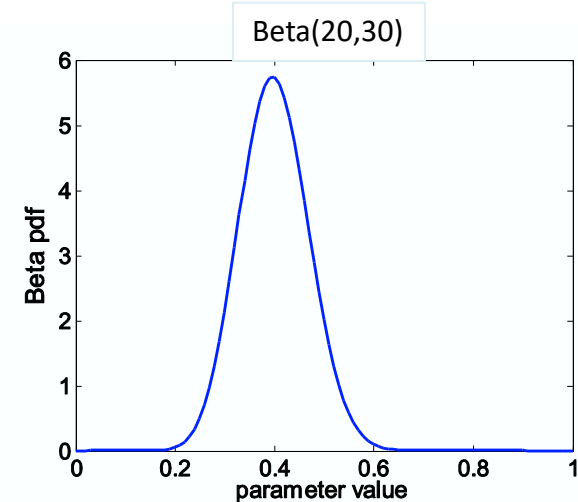
# Beta conjugate prior

$$P(\theta) \sim \text{Beta}(\beta_H, \beta_T)$$

$$P(\theta|D) \sim \text{Beta}(\beta_H + \alpha_H, \beta_T + \alpha_T)$$



After observing 1 Tail



After observing  
18 Heads and  
28 Tails

As  $n = \alpha_H + \alpha_T$  increases, posterior distribution becomes more concentrated

# MAP estimation for Bernoulli r.v.

Choose  $\theta$  that maximizes a posterior probability

$$\begin{aligned}\hat{\theta}_{MAP} &= \arg \max_{\theta} P(\theta | D) \\ &= \arg \max_{\theta} P(D | \theta)P(\theta)\end{aligned}$$

MAP estimate of probability of head:

$$P(\theta) \sim \text{Beta}(\beta_H, \beta_T)$$

Count of H/T simply get added to parameters

$$P(\theta|D) \sim \text{Beta}(\beta_H + \alpha_H, \beta_T + \alpha_T)$$

$$\hat{\theta}_{MAP} = \frac{\alpha_H + \beta_H - 1}{\alpha_H + \beta_H + \alpha_T + \beta_T - 2}$$

Mode of Beta distribution

Equivalent to adding extra coin flips ( $\beta_H - 1$  heads,  $\beta_T - 1$  tails)

**As we get more data, effect of prior is “washed out”**

# MAP estimation for Gaussian r.v.

Parameters  $\theta = (\mu, \sigma^2)$

- Mean  $\mu$  (known  $\sigma^2$ ): Gaussian prior  $P(\mu) = N(\eta, \lambda^2)$

$$P(\mu | \eta, \lambda) = \frac{1}{\lambda\sqrt{2\pi}} e^{-\frac{(\mu-\eta)^2}{2\lambda^2}}$$

$$\hat{\mu}_{MAP} = \frac{\frac{1}{\sigma^2} \sum_{i=1}^n x_i + \frac{\eta}{\lambda^2}}{\frac{n}{\sigma^2} + \frac{1}{\lambda^2}} \quad \hat{\mu}_{MLE} = \frac{1}{n} \sum_{i=1}^n x_i$$

**As we get more data, effect of prior is “washed out”**

- Variance  $\sigma^2$  (known  $\mu$ ): inv-Wishart Distribution



# MLE vs. MAP

- Maximum Likelihood estimation (MLE)

Choose value that maximizes the probability of observed data

$$\hat{\theta}_{MLE} = \arg \max_{\theta} P(D|\theta)$$

- Maximum *a posteriori* (MAP) estimation

Choose value that is most probable given observed data and prior belief

$$\begin{aligned}\hat{\theta}_{MAP} &= \arg \max_{\theta} P(\theta|D) \\ &= \arg \max_{\theta} P(D|\theta)P(\theta)\end{aligned}$$

When is MAP same as MLE?