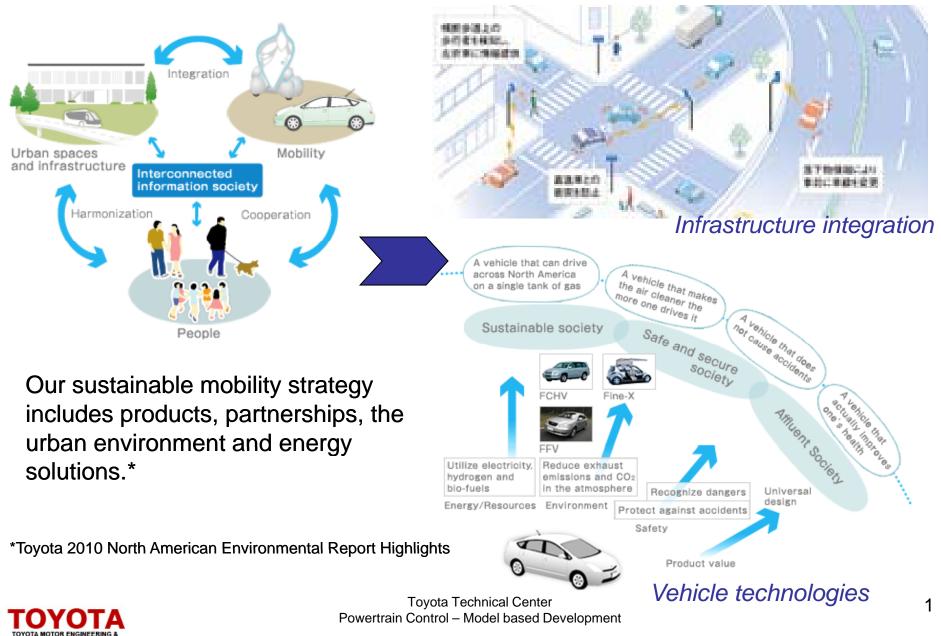
Toyota's Direction

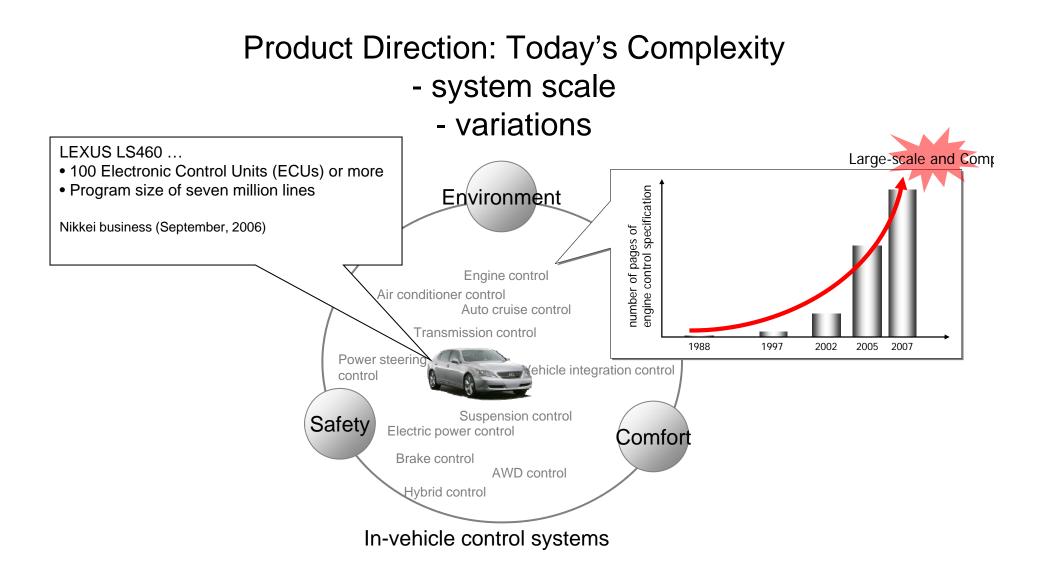


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Presentation Flow

- 1. Development Challenges
- 2. Focus on Verification and Validation
- Open Challenge: Engineering Processes for Verification and Validation of Cyber-Physical Systems



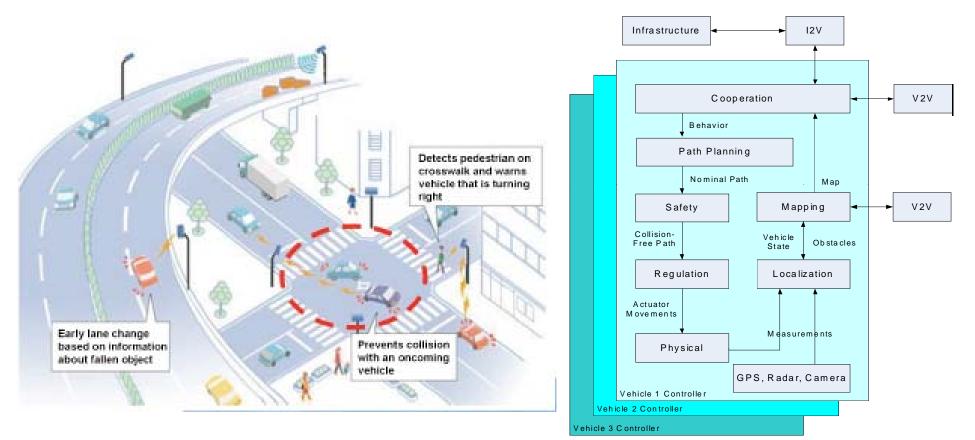


Control, integration, and complexity are accelerating in order to improve vehicle performance and provide new features.



Product Direction: Tomorrow's Complexity: Cyber-Physical Systems

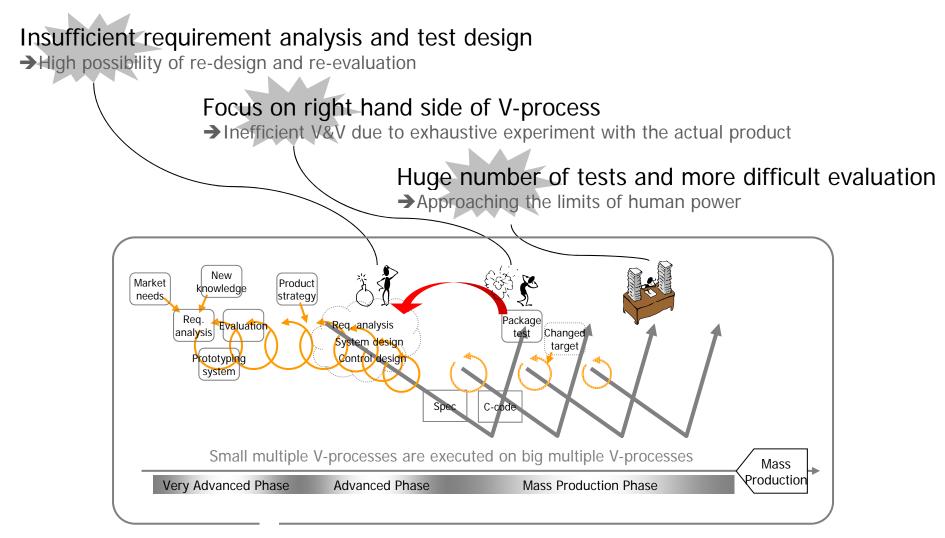
- Vehicle to Infrastructure and Vehicle to Vehicle
 - Collision Avoidance and Cooperative Driving



CPS: distributed computation nodes operating in a control hierarchy that interact with the vehicle's physical processes in real-time to provide critical function.

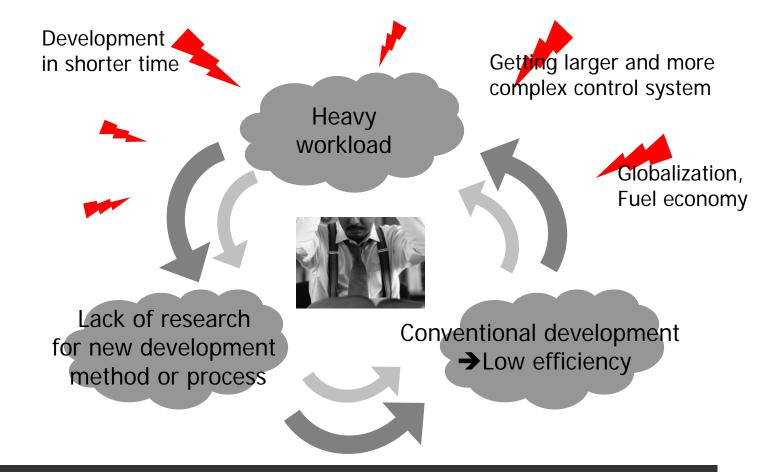


Today's Situation: Control Development Process Overview





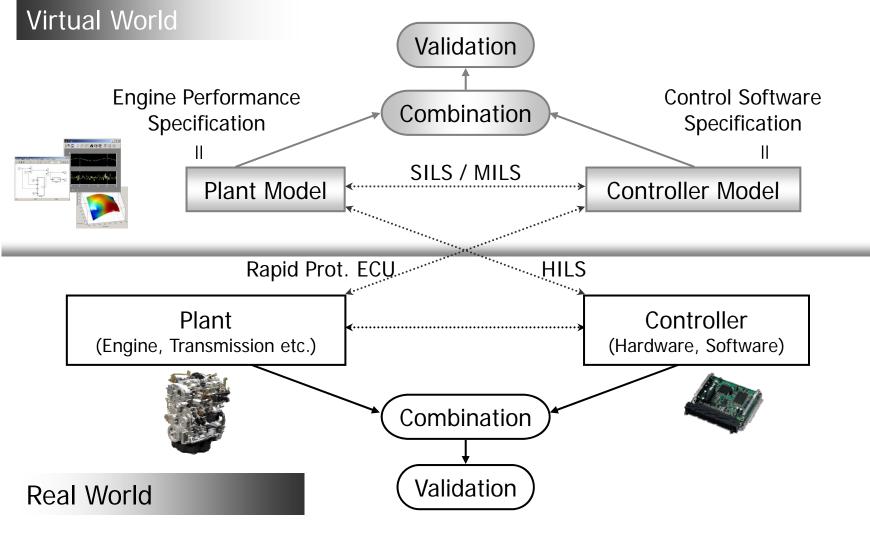
Consequence of Development Complexity



A shift in paradigm is needed to overcome the above "Demon Cycle" Toyota has been pushing ahead with MBD as an essential solution.



Model-Based Development: Basic Tooling





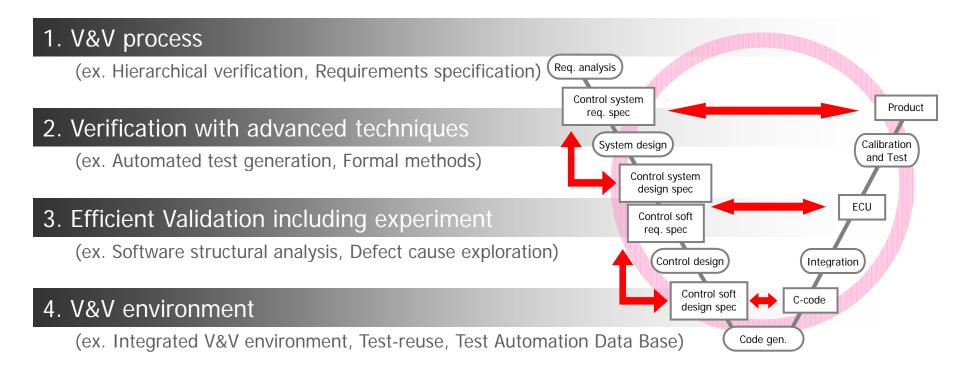
Toyota Technical Center Powertrain Control – Model based Development

MBD Focus areas

- 1. Process and Information Management
- 2. Plant Modeling
- 3. Model-based control design
- 4. Calibration
- 5. Verification and Validation



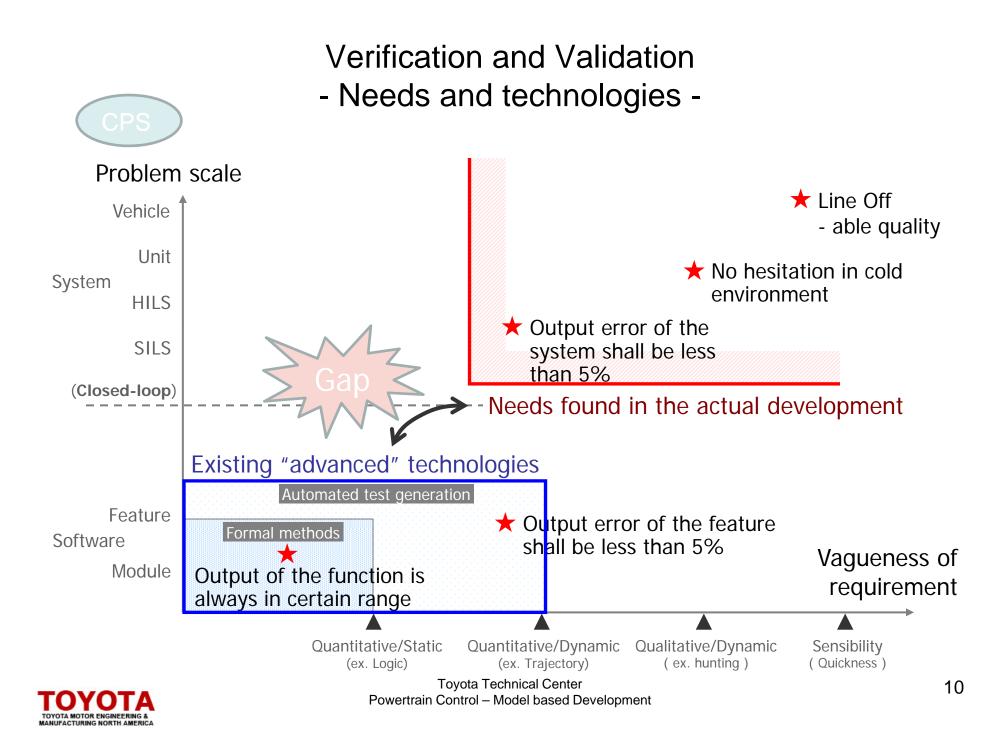
Verification and Validation - Strategy -



Renew development process by applying advanced V&V technologies to improve:

- → Quality no defects allowed in product
- → Efficiency minimized development cost





Verification of Cyber-physical systems (e.g. collision avoidance)

- The systems are **vastly heterogeneous** in nature. What mathematical or modeling representations should be used to admit validation and verification?
- The systems are **complex**. What is the maximum complexity that can be validated and verified? How do we quantify complexity?
- Given detailed design models of the system components (these are the most readily available in today's processes) how does the engineer *properly* abstract the models to satisfy the complexity constraint?
- The system functionality is **hierarchically structured**. Are there validation and verification techniques that accommodate (and possibly exploit) this structure?
- The systems are **comprised of outside elements** (e.g. infrastructure, unknown vehicles) that cannot be brought in-house for analysis or testing. How do we parameterize the outside element's performance envelope for validation and verification?
- The systems rely on **lossy wireless communication**. How do we characterize the worst-case scenarios so that we can validate and verify the dynamic behavior of the system?
- This system configuration is **multi-agent and dynamic**. How do we validate and verify given the untold number of agent scenarios?
- The systems are subject to **malicious interaction**. How do we validate and verify the system's countermeasures?
- The vehicle performance envelopes are subject to several **uncertain parameters** such as weight, road coefficient, road grade, tire wear. Are there validation and verification techniques able to accommodate these uncertainties?



Open Challenge: Engineering Processes for Verification and Validation of Cyber-Physical Systems

- a) We propose a community challenge to:
 - a) describe what it means to validate and verify cyberphysical systems in concrete terms,
 - b) develop engineering processes that practicing engineers can use to conduct the validation and verification, and
 - c) track progress by publishing metrics on the scale and complexity of systems than can be validated and verified using the processes.
- b) Collision avoidance systems could be used as a representative application test-bed:
 - a) much of the work is already government sponsored, and
 - b) the benefits are societal.



Perhaps we need to generate a Moore's Law for Validation and Verification of Cyber-Physical Systems ?

Thank you

