## **Decision Trees**

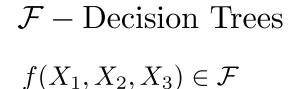
Aarti Singh, Eric Xing

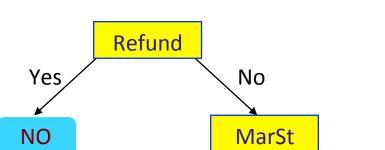
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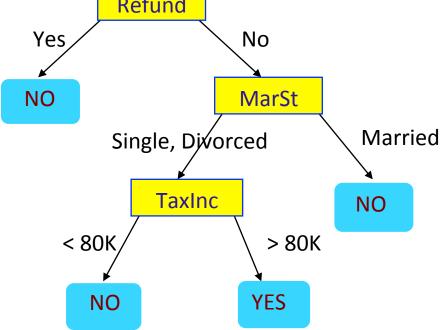




# How does a decision tree represent a prediction rule?







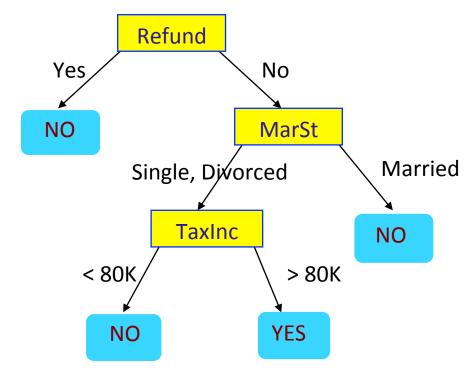
Refund		Taxable Income	Cheat
$X_1$	$X_2$	$X_3$	Y
Data	3		

- Each internal node: test one feature X<sub>i</sub>
- Each branch from a node: selects one value for X<sub>i</sub>
- Each leaf node: predict Y

# Given a decision tree, how do we assign label to a test point?

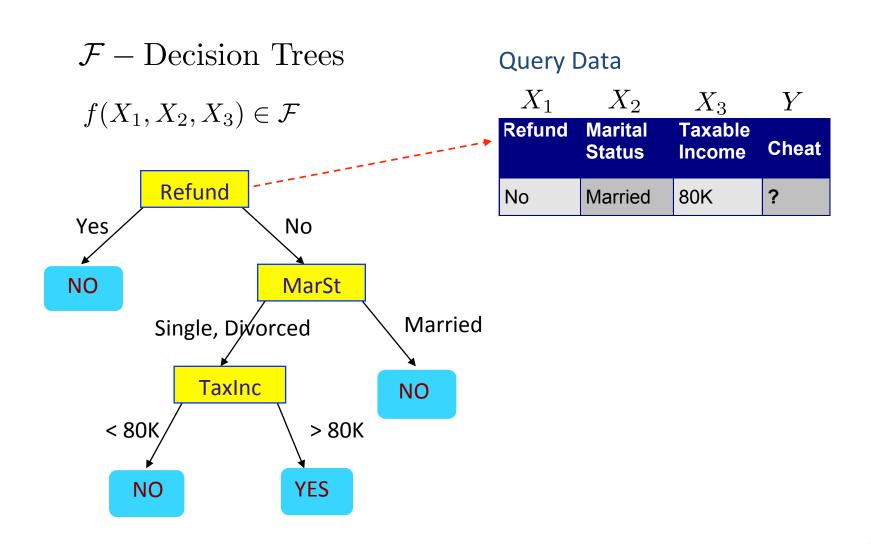


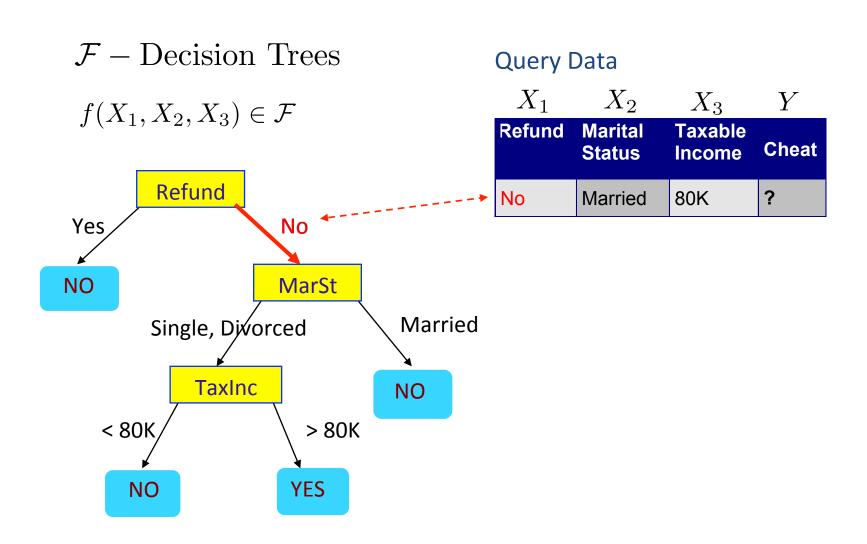
$$f(X_1, X_2, X_3) \in \mathcal{F}$$

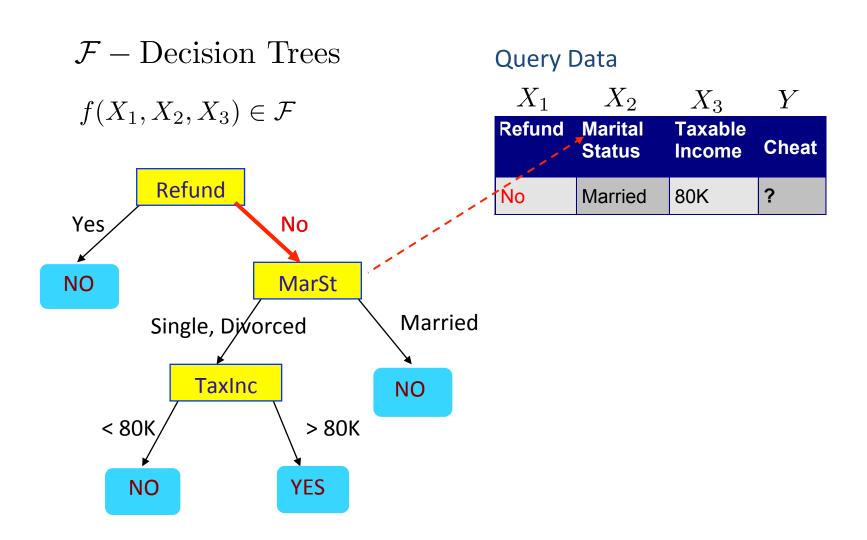


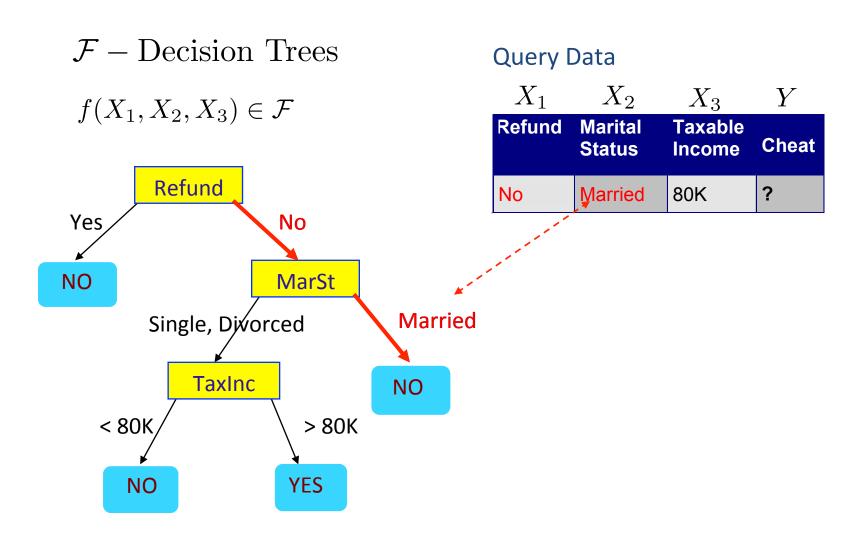
#### **Query Data**

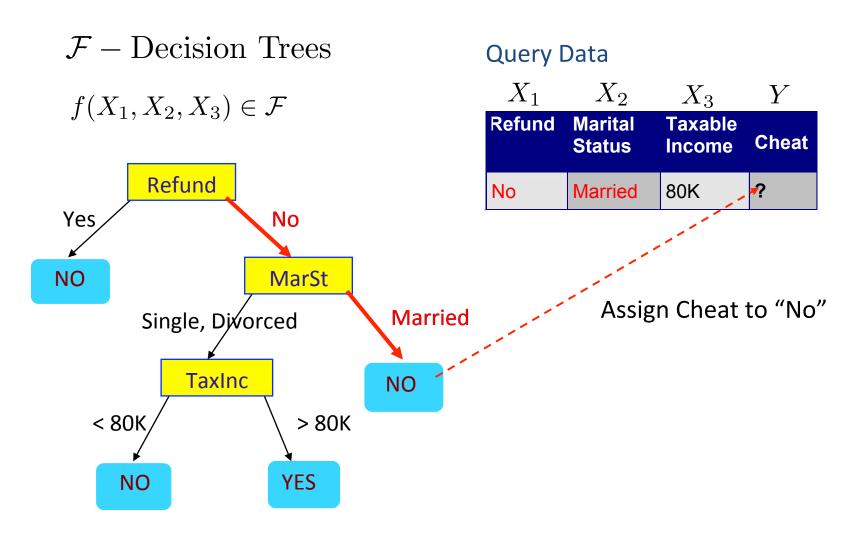
$X_1$	$X_2$	$X_3$	Y
Refund	Marital Status	Taxable Income	Cheat
No	Married	80K	?











# How do we learn a decision tree from training data?

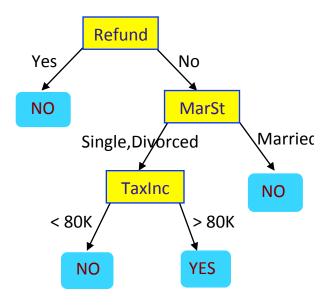
### How to learn a decision tree

Top-down induction [many algorithms ID3, C4.5, CART, ...]

#### We will focus on ID3 algorithm

#### Repeat:

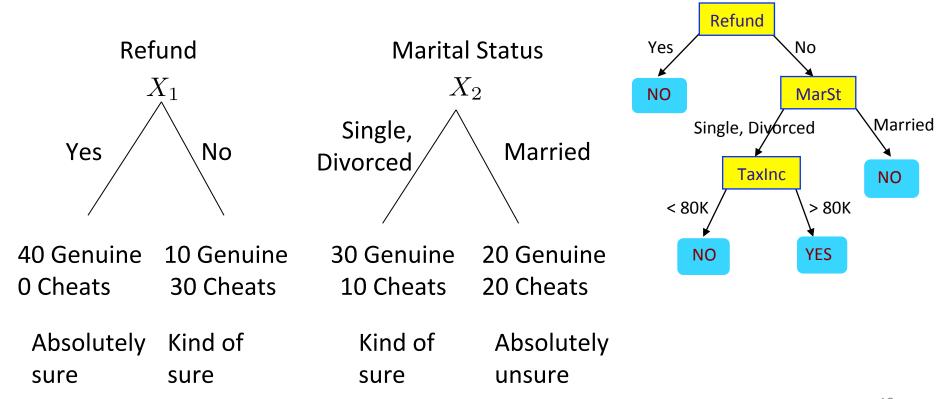
- 1. Select "best feature"  $(X_1, X_2 \text{ or } X_3)$  to split
- 2. For each value that feature takes, sort training examples to leaf nodes
- Stop if leaf contains all training examples with same label or if all features are used up
- 4. Assign leaf with majority vote of labels of training examples



## Which feature is best to split?

Good split if we are less uncertain about classification after split

#### 80 training people



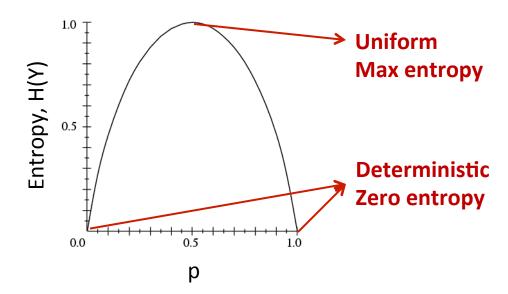
## **Entropy**

Entropy of a random variable Y

$$H(Y) = -\sum_{y} P(Y = y) \log_2 P(Y = y)$$

More uncertainty, more entropy!

Y ~ Bernoulli(p)



<u>Information Theory interpretation</u>: H(Y) is the expected number of bits needed to encode a randomly drawn value of Y (under most efficient code)

## **Information Gain**

- Advantage of attribute = decrease in uncertainty
  - Entropy of Y before split

$$H(Y) = -\sum_{y} P(Y = y) \log_2 P(Y = y)$$

- Entropy of Y after splitting based on X<sub>i</sub>
  - Weight by probability of following each branch

$$H(Y \mid X_i) = \sum_{x} P(X_i = x) H(Y \mid X_i = x)$$
  
=  $-\sum_{x} P(X_i = x) \sum_{y} P(Y = y \mid X_i = x) \log_2 P(Y = y \mid X_i = x)$ 

Information gain is difference

$$I(Y, X_i) = H(Y) - H(Y \mid X_i)$$

Max Information gain = min conditional entropy

## Which feature is best to split?

Pick the attribute/feature which yields maximum information gain:

$$\arg\max_{i} I(Y, X_i) = \arg\max_{i} [H(Y) - H(Y|X_i)]$$

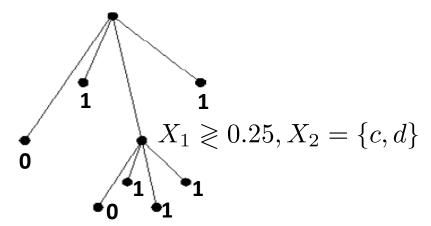
H(Y) – entropy of Y  $H(Y|X_i)$  – conditional entropy of Y

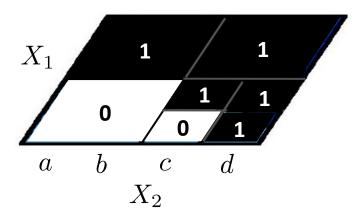
Feature which yields maximum reduction in entropy provides maximum information about Y

## More generally...

## Decision Tree more generally...

$$X_1 \ge 0.5, X_2 = \{a, b\} \text{or} \{c, d\}$$



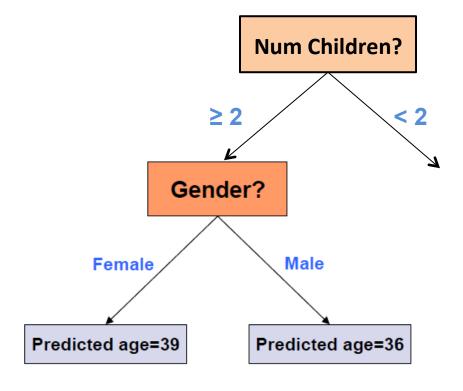


- Features can be discrete or continuous
- Each internal node: test some set of features {X<sub>i</sub>}
- Each branch from a node: selects a set of value for {X<sub>i</sub>}
- Each leaf node: predict Y
   Majority vote
   (classification)
  - Average or Polynomial fit (regression)

## Regression trees

 $\mathsf{X_1} \qquad \qquad \mathsf{X_p} \qquad Y$ 

Gender	Rich?	Num. Children	# travel per yr.	Age
F	No	2	5	38
M	No	0	2	25
M	Yes	1	0	72
:	:	:	:	:

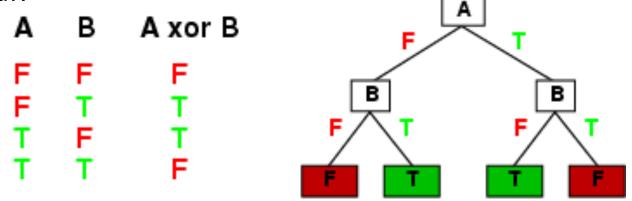


Average (fit a constant ) using training data at the leaves

## **Overfitting**

## **Expressiveness of General Decision Trees**

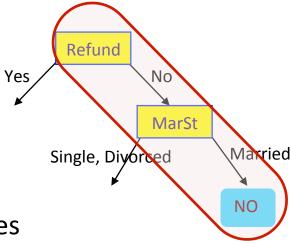
- Decision trees can express any function of the input features.
- E.g., for Boolean features and labels, truth table row → path to leaf:



- There is a decision tree which perfectly classifies a training set with one path to leaf for each example
- But it won't generalize well to new examples prefer to find more compact decision trees

## When to Stop?

- Many strategies for picking simpler trees:
  - Pre-pruning
    - Fixed depth
    - Fixed number of leaves
  - Post-pruning
    - Chi-square test
      - Convert decision tree to a set of rules
      - Eliminate variable values in rules which are independent of label (using chi-square test for independence)
      - Simplify rule set by eliminating unnecessary rules
  - Model Selection by complexity penalization



## **Model Selection**

Penalize complex models by introducing cost

$$\widehat{f} = \arg\min_{T} \left\{ \frac{1}{n} \sum_{j=1}^{n} loss(\widehat{f}_{T}(X^{(j)}), Y^{(j)}) + pen(T) \right\}$$

$$\log likelihood \qquad cost$$

$$\begin{array}{rcl} \operatorname{loss}(\widehat{f}_T(X^{(\mathbf{j})},Y^{(\mathbf{j})}) &=& (\widehat{f}_T(X^{(\mathbf{j})}) - Y^{(\mathbf{j})})^2 & \operatorname{regression} \\ &=& \mathbf{1}_{\widehat{f}_T(X^{(\mathbf{j})}) \neq Y^{(\mathbf{j})}} & \operatorname{classification} \end{array}$$

 $pen(T) \propto |T|$  penalize trees with more leaves

## What you should know

- Decision trees are one of the most popular data mining tools
  - Simplicity of design
  - Interpretability
  - Ease of implementation
  - Good performance in practice (for small dimensions)
- Information gain to select attributes (ID3, C4.5,...)
- Can be used for classification, regression and density estimation too
- Decision trees will overfit!!!
  - Must use tricks to find "simple trees", e.g.,
    - Pre-Pruning: Fixed depth/Fixed number of leaves
    - Post-Pruning: Chi-square test of independence
    - Complexity Penalized model selection