

10-301/601: Introduction to Machine Learning

Lecture 27 – Random Forests

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8/1/23

Front Matter

- Announcements
 - PA7 released 7/27, due 8/3 at 11:59 PM
 - This is the last programming assignment!
 - Final on 8/11 (one week from Friday) in **POS 152 (here!) from 12 PM – 3 PM**
 - Practice problems for the Final were posted to the course website last Friday, under [Recitations](#)
 - All of this week's material is in-scope
- Recommended Readings
 - None

The Netflix Prize



Netflix Prize

Home Rules Leaderboard Update

- 500,000 users
- 20,000 movies
- 100 million ratings
- Goal: To obtain lower error than Netflix's existing system on 3 million held out ratings

Congratulations!

The Netflix Prize sought to substantially improve the accuracy of predictions about how much someone is going to enjoy a movie based on their movie preferences.

On September 21, 2009 we awarded the \$1M Grand Prize to team "BellKor's Pragmatic Chaos". Read about [their algorithm](#), checkout team scores on the [Leaderboard](#), and join the discussions on the [Forum](#).

We applaud all the contributors to this quest, which improves our ability to connect people to the movies they love.

The Netflix Prize

Netfix Prize **COMPLETED**

Home Rules Leaderboard Update Download

Leaderboard

Showing Test Score. [Click here to show quiz score](#)

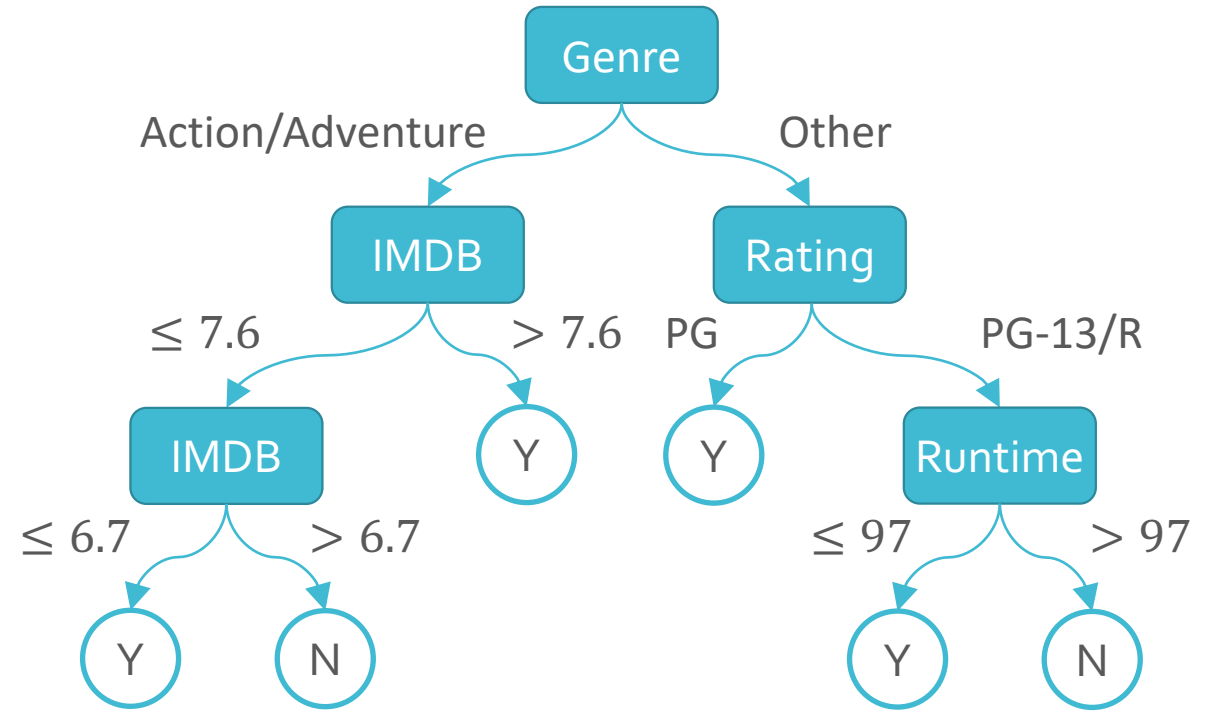
Display top leaders.

Rank	Team Name	Best Test Score	% Improvement	Best Submit Time
Grand Prize - RMSE = 0.8567 - Winning Team: BellKor's Pragmatic Chaos				
1	BellKor's Pragmatic Chaos	0.8567	10.06	2009-07-26 18:18:28
2	The Ensemble	0.8567	10.06	2009-07-26 18:38:22
3	Grand Prize Team	0.8582	9.90	2009-07-10 21:24:40
4	Opera Solutions and Vandelay United	0.8588	9.84	2009-07-10 01:12:31
5	Vandelay Industries !	0.8591	9.81	2009-07-10 00:32:20
6	PragmaticTheory	0.8594	9.77	2009-06-24 12:06:56
7	BellKor in BigChaos	0.8601	9.70	2009-05-13 08:14:09
8	Dace	0.8612	9.59	2009-07-24 17:18:43
9	Feeds2	0.8622	9.48	2009-07-12 13:11:51
10	BigChaos	0.8623	9.47	2009-04-07 12:33:59
11	Opera Solutions	0.8623	9.47	2009-07-24 00:34:07
12	BellKor	0.8624	9.46	2009-07-26 17:19:11

MovieID	Runtime	Genre	Budget	Year	IMDB	Rating	Liked?
1	124	Action	18M	1980	8.7	PG	Y
2	105	Action	30M	1984	7.8	PG	Y
3	103	Comedy	6M	1986	7.8	PG-13	N
4	98	Adventure	16M	1987	8.1	PG	Y
5	128	Comedy	16.4M	1989	8.1	PG	Y
6	120	Comedy	11M	1992	7.6	R	N
7	120	Drama	14.5M	1996	6.7	PG-13	N
8	136	Action	115M	1999	6.5	PG	Y
9	90	Action	90M	2001	6.6	PG-13	Y
10	161	Adventure	100M	2002	7.4	PG	N
11	201	Action	94M	2003	8.9	PG-13	Y
12	94	Comedy	26M	2004	7.2	PG-13	Y
13	157	Biography	100M	2007	7.8	R	N
14	128	Action	110M	2007	7.1	PG-13	N
15	107	Drama	39M	2009	7.1	PG-13	N
16	158	Drama	61M	2012	7.6	PG-13	N
17	169	Adventure	165M	2014	8.6	PG-13	Y
18	100	Biography	9M	2016	6.7	R	N
19	130	Action	180M	2017	7.9	PG-13	Y
20	141	Action	275M	2019	6.5	PG-13	Y

Movie Recommendations

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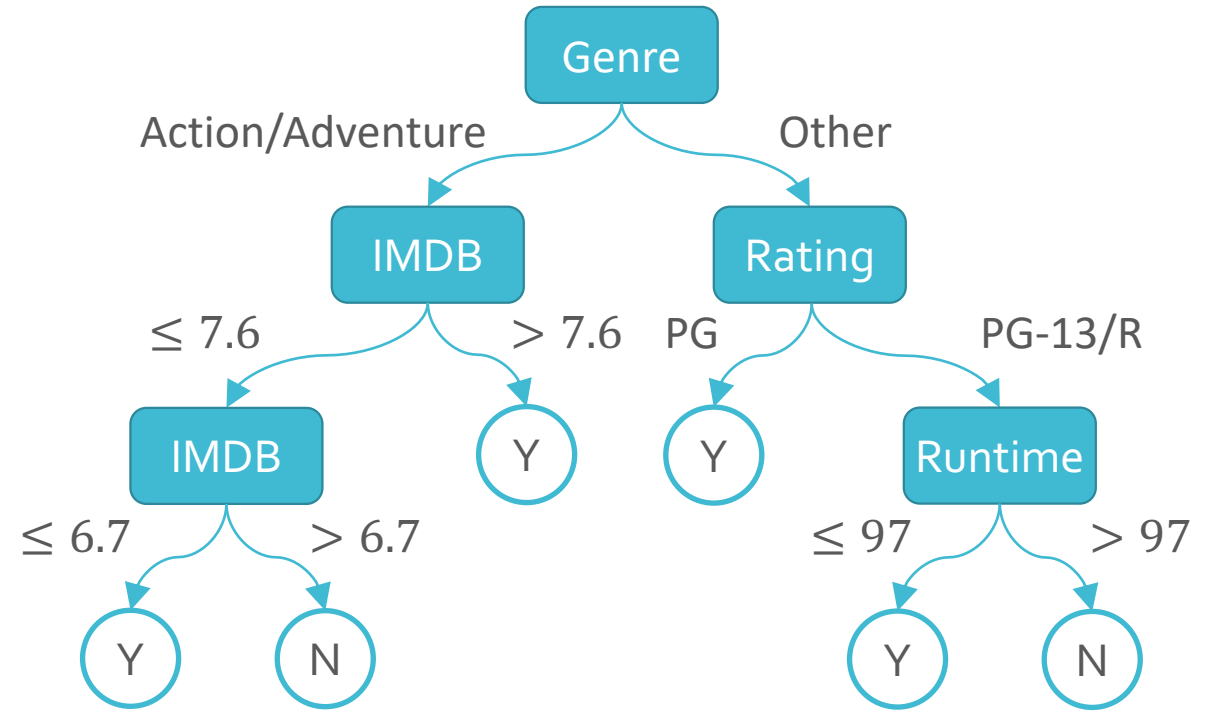


Decision Trees

Recall: Decision Tree Pros & Cons

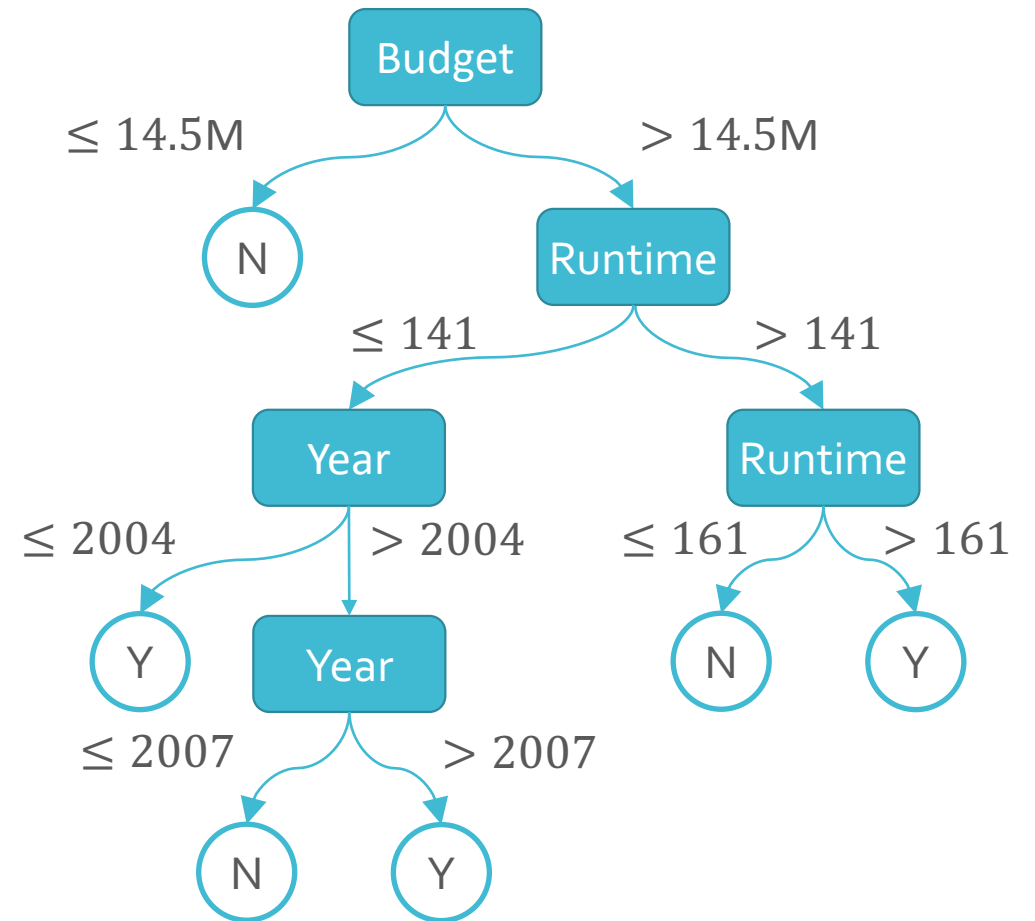
- Pros
 - Interpretable
 - Efficient (computational cost and storage)
 - Can be used for classification and regression tasks
 - Compatible with categorical and real-valued features
- Cons
 - Learned greedily: each split only considers the immediate impact on the splitting criterion
 - Not guaranteed to find the smallest (fewest number of splits) tree that achieves a training error rate of 0.
 - Prone to overfit
 - High variance

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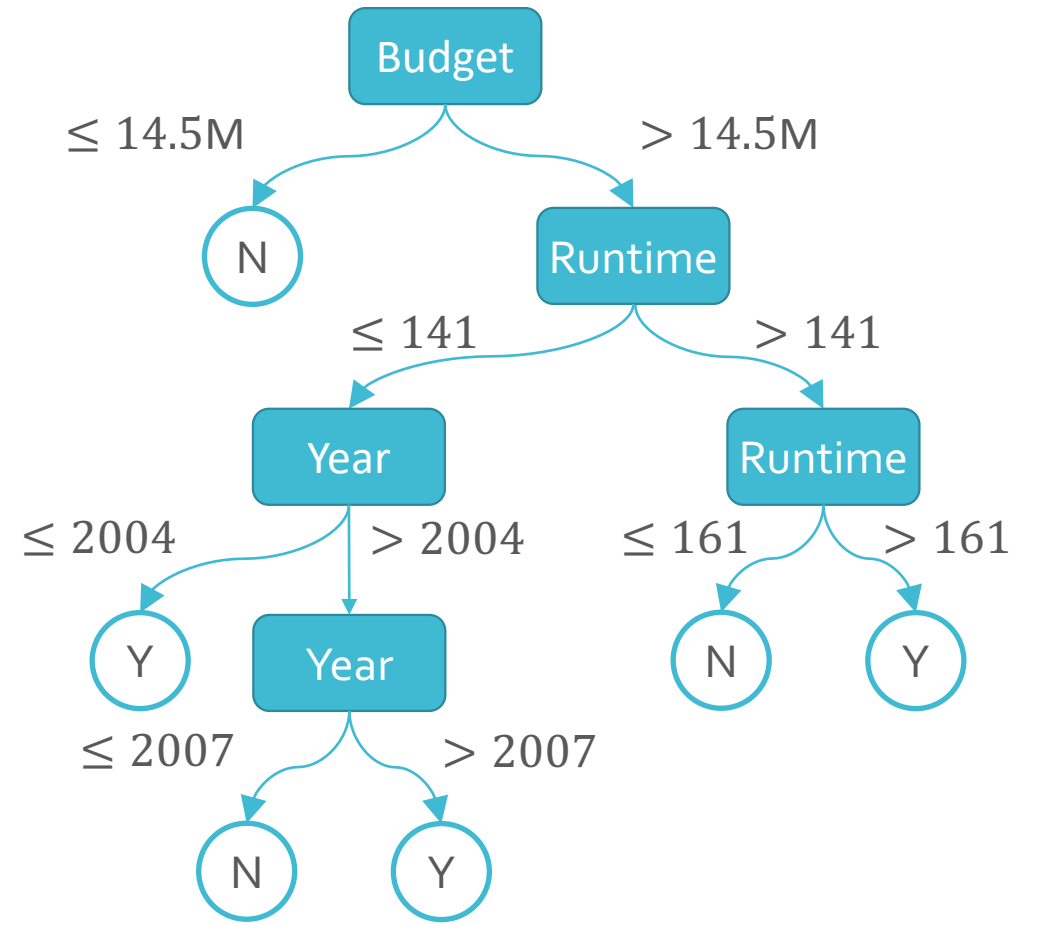
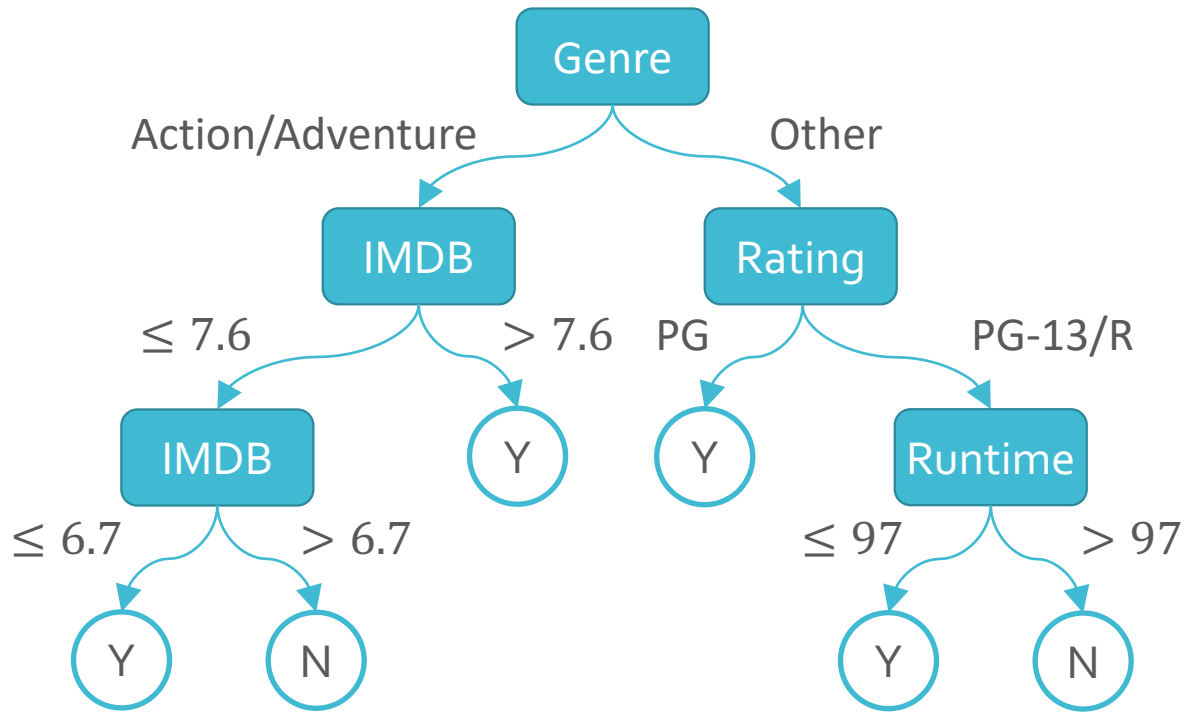


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Decision Trees: Pros & Cons

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 - Prone to overfit
 - High variance
 - Can be addressed via ensembles → random forests

Random Forests

- Combines the prediction of many diverse decision trees to reduce their variability
- If B independent random variables $x^{(1)}, x^{(2)}, \dots, x^{(B)}$ all have variance σ^2 , then the variance of $\frac{1}{B} \sum_{b=1}^B x^{(b)}$ is $\frac{\sigma^2}{B}$
- Random forests = bagging + split-feature randomization
= bootstrap aggregating + split-feature randomization

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Aggregating

- How can we combine multiple decision trees, $\{t_1, t_2, \dots, t_B\}$, to arrive at a single prediction?
- Regression - average the predictions:

$$\bar{t}(\mathbf{x}) = \frac{1}{B} \sum_{b=1}^B t_b(\mathbf{x})$$

- Classification - plurality (or majority) vote; for binary labels encoded as $\{-1, +1\}$:

$$\bar{t}(\mathbf{x}) = \text{sign} \left(\frac{1}{B} \sum_{b=1}^B t_b(\mathbf{x}) \right)$$

Random Forests

- Combines the prediction of many **diverse** decision trees to reduce their variability
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Bootstrapping

- Insight: one way of generating different decision trees is by changing the training data set
- Issue: often, we only have one fixed set of training data
- Idea: resample the data multiple times ***with replacement***

MovieID	...
1	...
2	...
3	...
⋮	⋮
19	...
20	...

Training data

MovieID	...
1	...
1	...
1	...
⋮	⋮
14	...
19	...

Bootstrapped
Sample 1

MovieID	...
4	...
4	...
5	...
⋮	⋮
16	...
16	...

Bootstrapped
Sample 2

...

...

Bootstrapping

- Idea: resample the data multiple times ***with replacement***
 - Each bootstrapped sample has the same number of data points as the original data set
 - Duplicated points cause different decision trees to focus on different parts of the input space

MovieID	...
1	...
2	...
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⋮	⋮
19	...
20	...

Training data

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1	...
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Bootstrapped
Sample 1

MovieID	...
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4	...
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16	...

Bootstrapped
Sample 2

...

...

Split-feature Randomization

- Issue: decision trees trained on bootstrapped samples still behave similarly
- Idea: in addition to sampling the data points (i.e., the rows), also sample the features (i.e., the columns)
- Each time a split is being considered, limit the possible features to a randomly sampled subset

Runtime	Genre	Budget	Year	IMDB	Rating
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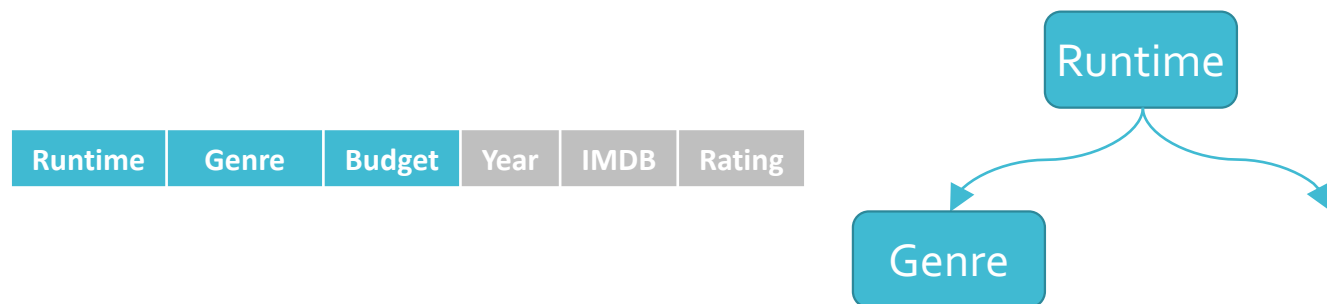
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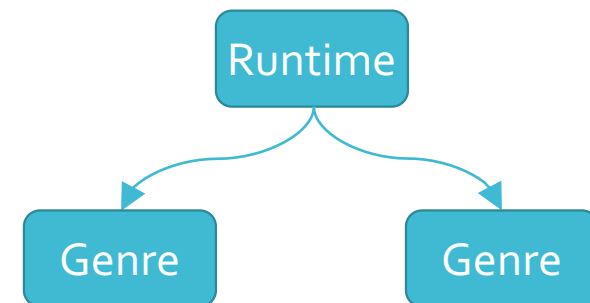
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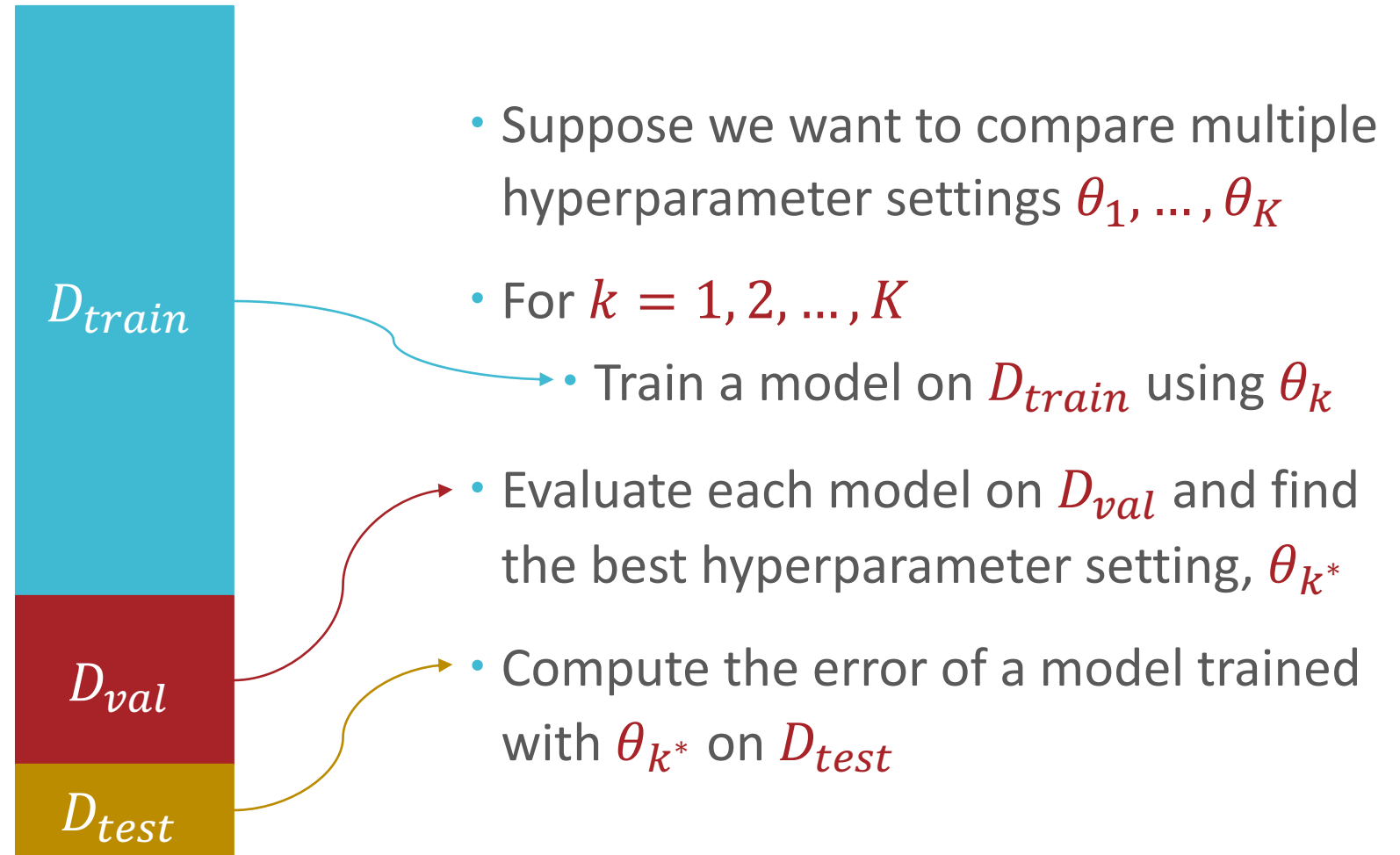
Random Forests

- Input: $\mathcal{D} = \{(\mathbf{x}^{(n)}, y^{(n)})\}_{n=1}^N, B, \rho$
- For $b = 1, 2, \dots, B$
 - Create a dataset, \mathcal{D}_b , by sampling N points from the original training data \mathcal{D} **with replacement**
 - Learn a decision tree, t_b , using \mathcal{D}_b and the ID3 algorithm **with split-feature randomization**, sampling ρ features for each split
- Output: $\bar{t} = f(t_1, \dots, t_B)$, the aggregated hypothesis

How can we set B and ρ ?

- Input: $\mathcal{D} = \{(\mathbf{x}^{(n)}, y^{(n)})\}_{n=1}^N, B, \rho$
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 - Create a dataset, \mathcal{D}_b , by sampling N points from the original training data \mathcal{D} **with replacement**
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- Output: $\bar{t} = f(t_1, \dots, t_B)$, the aggregated hypothesis

Recall: Validation Sets



Out-of-bag Error

- For each training point, $\mathbf{x}^{(n)}$, there are some decision trees which $\mathbf{x}^{(n)}$ was not used to train (roughly B/e trees or 37%)
 - Let these be $t^{(-n)} = \{t_1^{(-n)}, t_2^{(-n)}, \dots, t_{N-n}^{(-n)}\}$
- Compute an aggregated prediction for each $\mathbf{x}^{(n)}$ using the trees in $t^{(-n)}, \bar{t}^{(-n)}(\mathbf{x}^{(n)})$
- Compute the out-of-bag (OOB) error, e.g., for regression

$$E_{OOB} = \frac{1}{N} \sum_{n=1}^N (\bar{t}^{(-n)}(\mathbf{x}^{(n)}) - y^{(n)})^2$$

Out-of-bag Error

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- Compute an aggregated prediction for each $\mathbf{x}^{(n)}$ using the trees in $t^{(-n)}$, $\bar{t}^{(-n)}(\mathbf{x}^{(n)})$

- Compute the out-of-bag (OOB) error, e.g., for classification

$$E_{OOB} = \frac{1}{N} \sum_{n=1}^N \mathbb{1}(\bar{t}^{(-n)}(\mathbf{x}^{(n)}) \neq y^{(n)})$$

- E_{OOB} can be used for hyperparameter optimization!

Out-of-bag Error

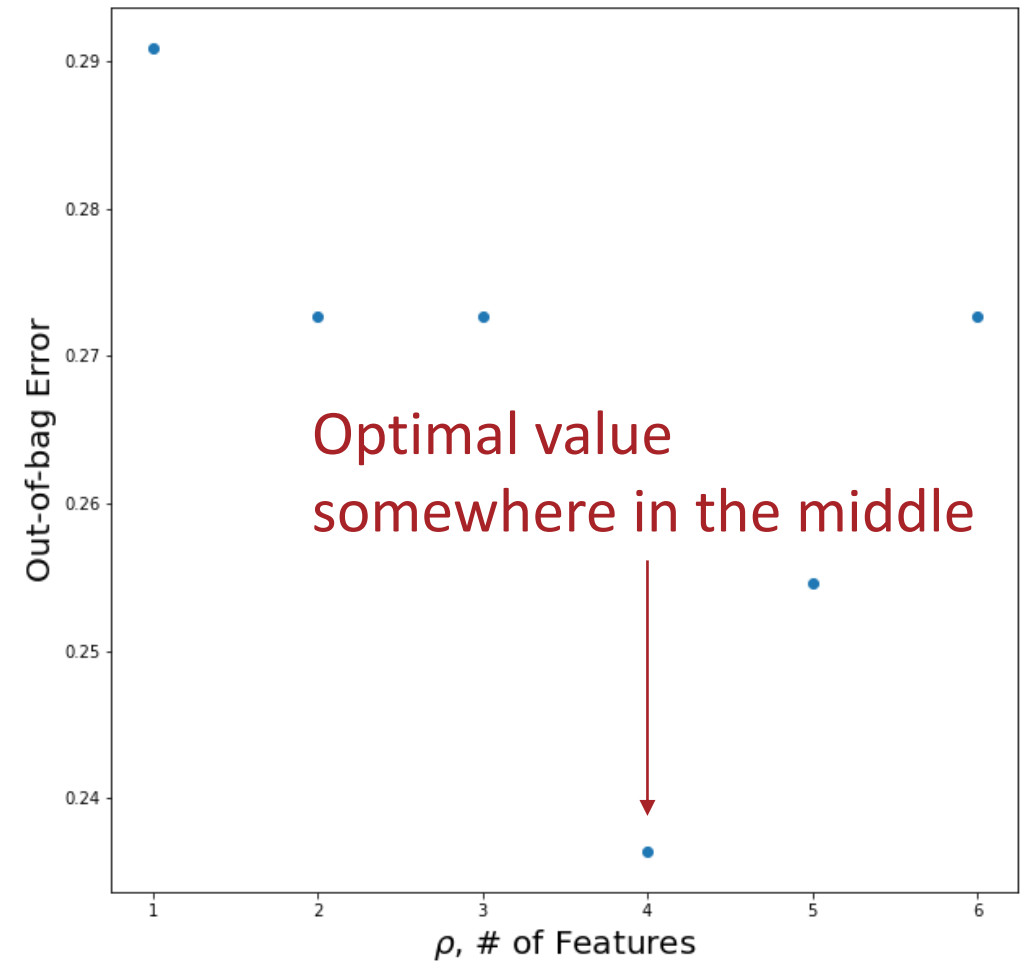
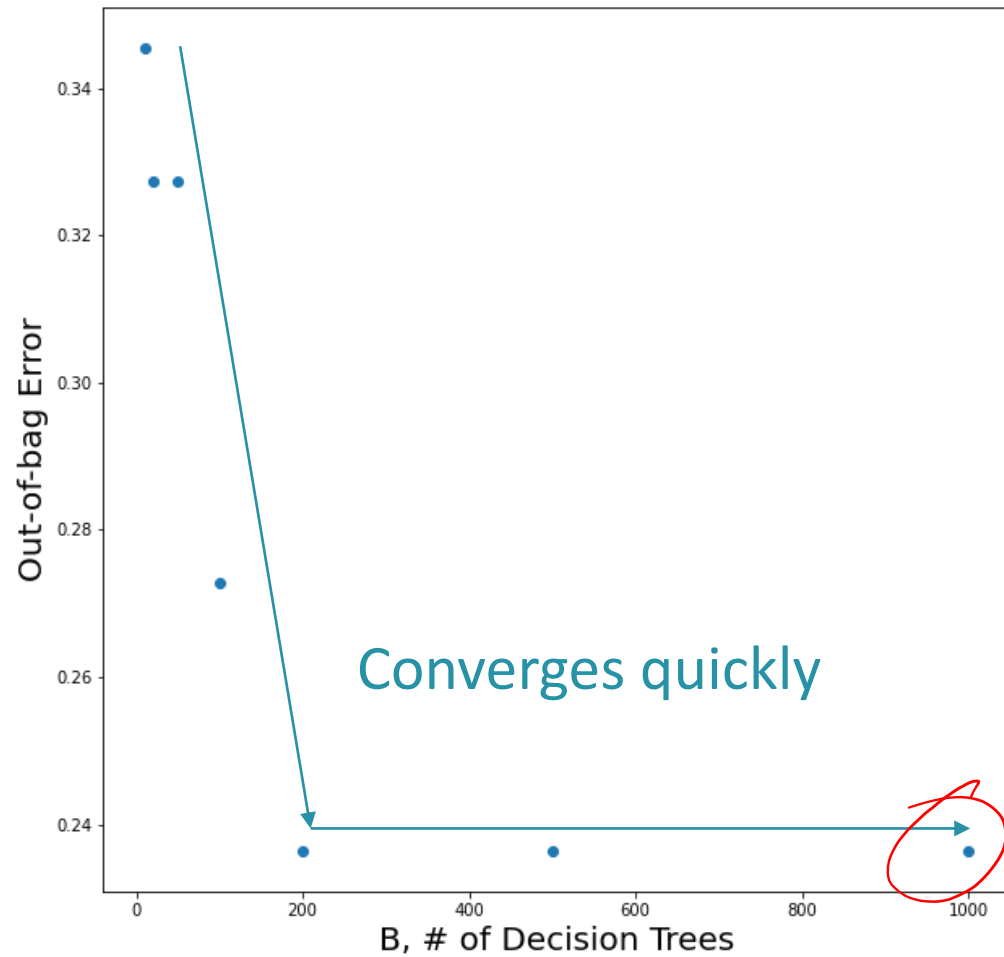


- Suppose we want to compare different numbers of trees in our random forest B_1, \dots, B_K
- For $k = 1, 2, \dots, K$
 - Train a random forest on D_{train} with B_k trees
 - Compute E_{OOB} for each random forest and find the best number of trees, B_{k^*}
- Evaluate the random forest with B_{k^*} trees on D_{test}

Out-of-bag Error



- Suppose we want to compare different numbers of trees in our random forest B_1, \dots, B_K
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- Evaluate the random forest with B_{k^*} trees on D_{test}



Setting Hyperparameters

Key Takeaways

- Ensemble methods employ a “wisdom of crowds” philosophy
 - Can reduce the variance of high variance methods
- Random forests = bagging + split-feature randomization
 - Aggregate multiple decision trees together
 - Bootstrapping and split-feature randomization increase diversity in the decision trees
 - Use out-of-bag errors for hyperparameter optimization

Feature Importance

- Some of the interpretability of decision trees gets lost when switching to random forests
- Random forests allow for the computation of “feature importance”, a way of ranking features based on how useful they are at predicting the target
- Initialize each feature’s importance to zero
- Each time a feature is chosen to be split on, add the reduction in Gini impurity (weighted by the number of data points in the split) to its importance

Feature Importance

