#### 10-301/601: Introduction to Machine Learning Lecture 4 – KNNs

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#### **Front Matter**

#### • Announcements:

- PA1 released 5/18, due 5/25 at 11:59 PM
- Quiz 1: Decision Trees on 5/19 (tomorrow!)
  - The quiz will begin promptly at 11 AM, please show up on time!
  - Closed book, closed notes, no calculators.
- Recommended Readings:
  - Daumé III, Chapter 2: Geometry and Nearest Neighbors

#### Real-valued Features



#### Fisher Iris Dataset

Fisher (1936) used 150 measurements of flowersfrom 3 different species: Iris setosa (0), Iris virginica(1), Iris versicolor (2) collected by Anderson (1936)

Species	Sepal Length	Sepal Width	Petal Length	Petal Width
0	4.3	3.0	1.1	0.1
0	4.9	3.6	1.4	0.1
0	5.3	3.7	1.5	0.2
1	4.9	2.4	3.3	1.0
1	5.7	2.8	4.1	1.3
1	6.3	3.3	4.7	1.6
1	6.7	3.0	5.0	1.7

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#### Fisher Iris Dataset





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#### Duck test

From Wikipedia, the free encyclopedia

For the use of "the duck test" within the Wikipedia community, see Wikipedia:DUCK.

The duck test is a form of abductive reasoning. This is its usual expression:

If it looks like a duck, swims like a duck, and quacks like a duck, then it probably *is* a duck.

#### The Duck Test

The Duck Test for Machine Learning

- Classify a point as the label of the "most similar" training point
- Idea: given real-valued features, we can use a distance metric to determine how similar two data points are
- A common choice is Euclidean distance:

$$d(\mathbf{x}, \mathbf{x}') = \|\mathbf{x} - \mathbf{x}'\|_2 = \sqrt{\sum_{d=1}^{D} (x_d - x'_d)^2}$$

• An alternative is the Manhattan distance:

$$d(\mathbf{x}, \mathbf{x}') = \|\mathbf{x} - \mathbf{x}'\|_1 = \sum_{d=1}^{D} |x_d - x'_d|$$

Nearest Neighbor: Pseudocode def train( $\mathcal{D}$ ):
 store  $\mathcal{D}$ def predict(x'):
 find the nearest neighbor to x' in  $\mathcal{D}$ ,  $x^{(i)}$  return  $y^{(i)}$ 

#### Nearest Neighbor: Example



#### Nearest Neighbor: Example



#### Nearest Neighbor: Example



The Nearest Neighbor Model • Requires no training!

- Always has zero training error!
  - A data point is always its own nearest neighbor

•

• Always has zero training error...

Generalization of Nearest Neighbor (Cover and Hart, 1967)

- Claim: under certain conditions, as  $n \to \infty$ , with high probability, the true error rate of the nearest neighbor model  $\leq 2$  \* the Bayes error rate (the optimal classifier)
- Interpretation: "In this sense, it may be said that half the classification information in an infinite sample set is contained in the nearest neighbor."

But why limit ourselves to just one neighbor?

- Claim: under certain conditions, as  $n \to \infty$ , with high probability, the true error rate of the nearest neighbor model  $\leq 2$  \* the Bayes error rate (the optimal classifier)
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k-Nearest Neighbors (kNN)  Classify a point as the most common label among the labels of the k nearest training points

- Tie-breaking (in case of even k and/or more than 2 classes)
  - Weight votes by distance
  - Remove furthest neighbor
  - Add next closest neighbor
  - Use a different distance metric

k-Nearest
Neighbors
(kNN):
Pseudocode

def train(D):
 store D
def predict(x'):
 return majority\_vote(labels of the k
 nearest neighbors to x' in D)

3-Class classification (k = 1, weights = 'uniform')



3-Class classification (k = 2, weights = 'uniform')



3-Class classification (k = 3, weights = 'uniform')



3-Class classification (k = 5, weights = 'uniform')



3-Class classification (k = 10, weights = 'uniform')



3-Class classification (k = 20, weights = 'uniform')



3-Class classification (k = 30, weights = 'uniform')



3-Class classification (k = 50, weights = 'uniform')



3-Class classification (k = 100, weights = 'uniform')



3-Class classification (k = 120, weights = 'uniform')



3-Class classification (k = 150, weights = 'uniform')



#### Setting k

- When k = 1:
  - many, complicated decision boundaries
  - may overfit
- When k = N:
  - no decision boundaries; always predicts the most common label in the training data
  - may underfit
- k controls the complexity of the hypothesis set  $\implies k$ affects how well the learned hypothesis will generalize

#### Setting k

- Theorem:
  - If k is some function of N s.t.  $k(N) \to \infty$  and  $\frac{k(N)}{N} \to 0$ as  $N \to \infty$  ...
  - … then (under certain assumptions) the true error of a
     kNN model → the Bayes error rate
- Practical heuristics:
  - $k = \left\lfloor \sqrt{N} \right\rfloor$
  - *k* = 3
- Can also set k through (cross-)validation (stay tuned)

Aside: *k*NN and Categorical Features

- *k*NNs are compatible with categorical features, either by:
  - 1. Converting categorical features into binary ones:



2. Using a distance metric that works over categorical features e.g., the Hamming distance:

$$d(x, x') = \sum_{d=1}^{D} \mathbb{1}(x_d = x'_d)$$

#### *k*NN: Inductive Bias

• Similar points should have similar labels and *all features are equivalently important for determining similarity* 



• Feature scale can dramatically influence results!

- The fundamental assumption of *k*NN is that "similar" points or points close to one another should have the same label
- The closer two points are, the more confident we can be that they will have the same label
- As the dimensionality of the input grows, the less likely it is that two random points will be close
- As the dimensionality of the input grows, it takes more points to "cover" the input space

 Suppose you independently draw two one-dimensional points between 0 and 1 uniformly at random:

$$\begin{array}{c|c} x' & x \\ 0 & & 1 \\ d(x, x') \end{array}$$

•  $\mathbb{E}[d(x, x')] = \mathbb{E}[(x - x')^2]$ =  $\mathbb{E}[x^2] - 2\mathbb{E}[x]\mathbb{E}[x'] + \mathbb{E}[x'^2]$ =  $2\mathbb{E}[x^2] - 2\mathbb{E}[x]^2 = 2\left(\frac{1}{3}\right) - 2\left(\frac{1}{2}\right)^2 = \frac{1}{6}$ 

 Suppose you independently draw two two-dimensional points in the unit square uniformly at random:



• Suppose you independently draw two three-dimensional points in the unit cube uniformly at random:

• 
$$\mathbb{E}[d(x, x')] = \mathbb{E}[(x_1 - x_1')^2 + (x_2 - x_2')^2 + (x_3 - x_3')^2]$$
  
=  $3\mathbb{E}[(x_1 - x_1')^2]$   
=  $3\mathbb{E}[(x_1 - x_1')^2]$ 

• Assume all dimensions of the input are independent and identically distributed.

• Given N + 1 data points,  $\mathcal{D} = \{x^{(1)}, \dots, x^{(N)}\}$  and  $x^*$ , let  $d_+ = \max_{x \in \mathcal{D}} d(x, x^*)$  and  $d_- = \min_{x \in \mathcal{D}} d(x, x^*)$ 

Then

$$\lim_{D \to \infty} \mathbb{E}\left[\frac{d_+ - d_-}{d_-}\right] \to 0$$

Curing the Curse of Dimensionality

- More data
- Fewer dimensions
- Blessing of non-uniformity: data from the real world is rarely uniformly distributed across the input space

# *k*NN: Pros and Cons

- Pros:
  - Intuitive / explainable
  - No training / retraining
  - Provably near-optimal in terms of true error rate

• Cons:

- Computationally expensive
  - Always needs to store all data: O(ND)
  - Finding the k closest points in D dimensions:  $O(ND + N \log(k))$ 
    - Can be sped up through clever use of data structures (trades off training and test costs)
    - Can be approximated using stochastic methods
- Affected by feature scale
- Suffers from the curse of dimensionality

#### Key Takeaways

- Real-valued features and decision boundaries
- Nearest neighbor model and generalization guarantees
- *k*NN "training" and prediction
- Effect of k on model complexity
- *k*NN inductive bias
- Curse of dimensionality