10-301/601: Introduction to Machine Learning Lecture 4 –KNNs

Front Matter

- Announcements:
 - HW2 released on 5/16, due 5/23 at 11:59 PM
 - Unlike HW1 you will only have...
 - 1 graded submission for the written portion
 - 10 submissions to the autograder
 - Mini-lecture on 5/21 (tomorrow), instructor OH after
- Recommended Readings:
 - Daumé III, <u>Chapter 2: Geometry and Nearest Neighbors</u>

Real-valued Features



Fisher Iris Dataset

Fisher (1936) used 150 measurements of flowers from 3 different species: Iris setosa (0), Iris virginica (1), Iris versicolor (2) collected by Anderson (1936)

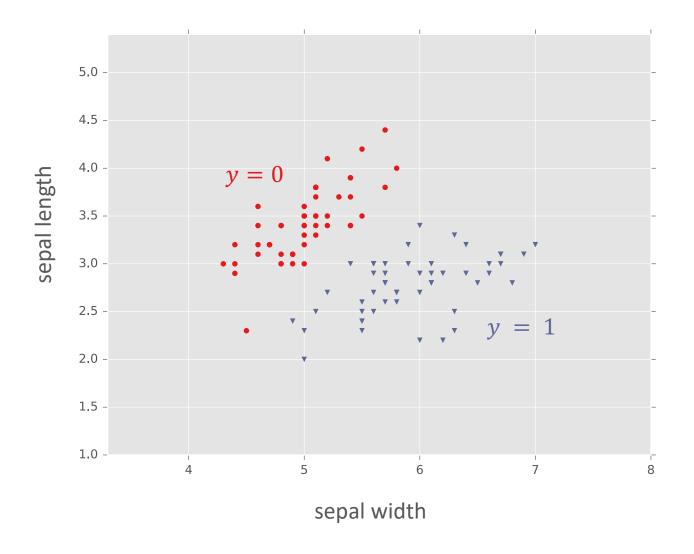
Species	Sepal Length	Sepal Width	Petal Length	Petal Width
0	4.3	3.0	1.1	0.1
0	4.9	3.6	1.4	0.1
0	5.3	3.7	1.5	0.2
1	4.9	2.4	3.3	1.0
1	5.7	2.8	4.1	1.3
1	6.3	3.3	4.7	1.6
1	6.7	3.0	5.0	1.7

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Fisher Iris Dataset



Henry Chai - 5/20/24 Figure courtesy of Matt Gormley



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Duck test

From Wikipedia, the free encyclopedia

For the use of "the duck test" within the Wikipedia community, see Wikipedia:DUCK.

The **duck test** is a form of abductive reasoning. This is its usual expression:

If it looks like a duck, swims like a duck, and quacks like a duck, then it probably is a duck.

The Duck Test

The Duck Test for Machine Learning

- Classify a point as the label of the "most similar" training point
- Idea: given real-valued features, we can use a distance metric to determine how similar two data points are
- A common choice is Euclidean distance:

$$d(\mathbf{x}, \mathbf{x}') = \|\mathbf{x} - \mathbf{x}'\|_2 = \sqrt{\sum_{d=1}^{D} (x_d - x_d')^2}$$

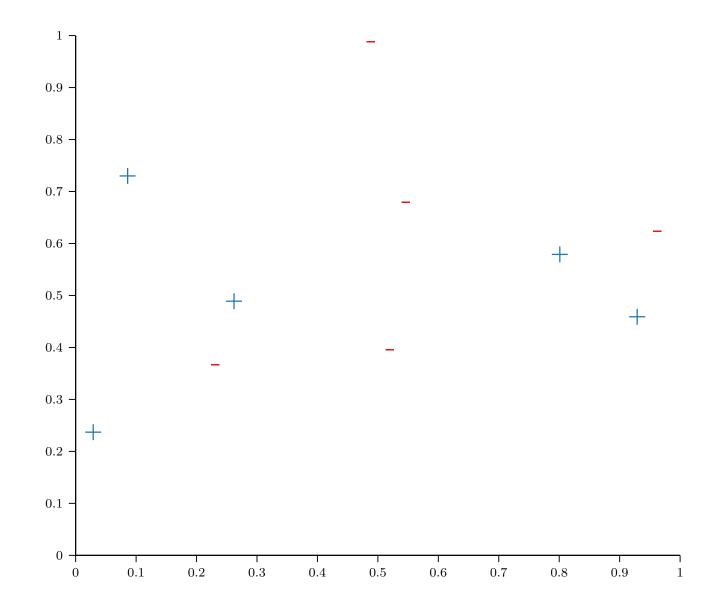
An alternative is the Manhattan distance:

$$d(x, x') = ||x - x'||_1 = \sum_{d=1}^{D} |x_d - x'_d|$$

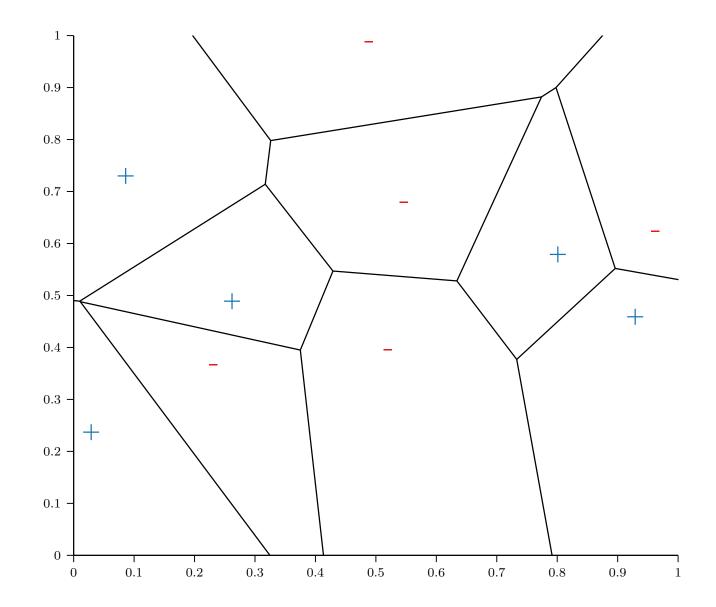
Nearest Neighbor: Pseudocode

```
def train(\mathcal{D}): store \mathcal{D} def predict(\mathbf{x}'): find the nearest neighbor to \mathbf{x}' in \mathcal{D}, \mathbf{x}^{(i)} return \mathbf{y}^{(i)}
```

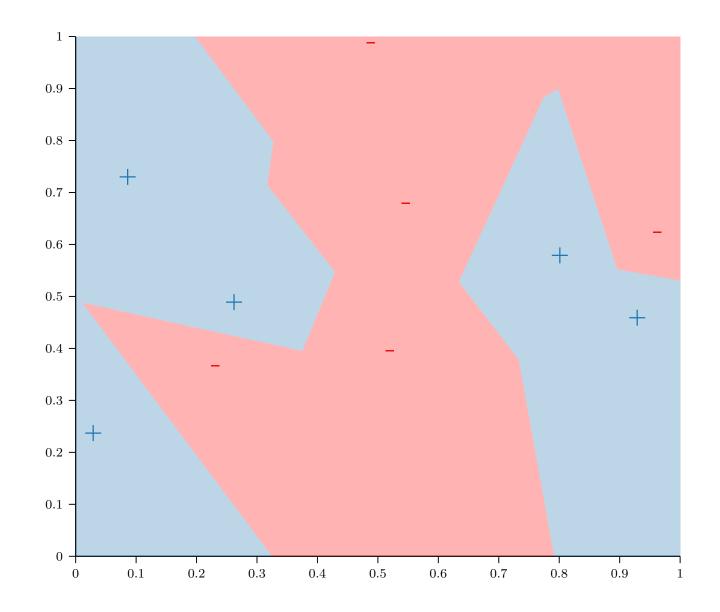
Nearest Neighbor: Example



Nearest Neighbor: Example



Nearest Neighbor: Example



The Nearest Neighbor Model

- Requires no training!
- Always has zero training error!
 - · A data point is always its own nearest neighbor

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Always has zero training error...

Generalization of Nearest Neighbor (Cover and Hart, 1967)

- Claim: under certain conditions, as $N \to \infty$, with high probability, the true error rate of the nearest neighbor model ≤ 2 * the Bayes error rate (the optimal classifier)
- Interpretation: "In this sense, it may be said that half the classification information in an infinite sample set is contained in the nearest neighbor."

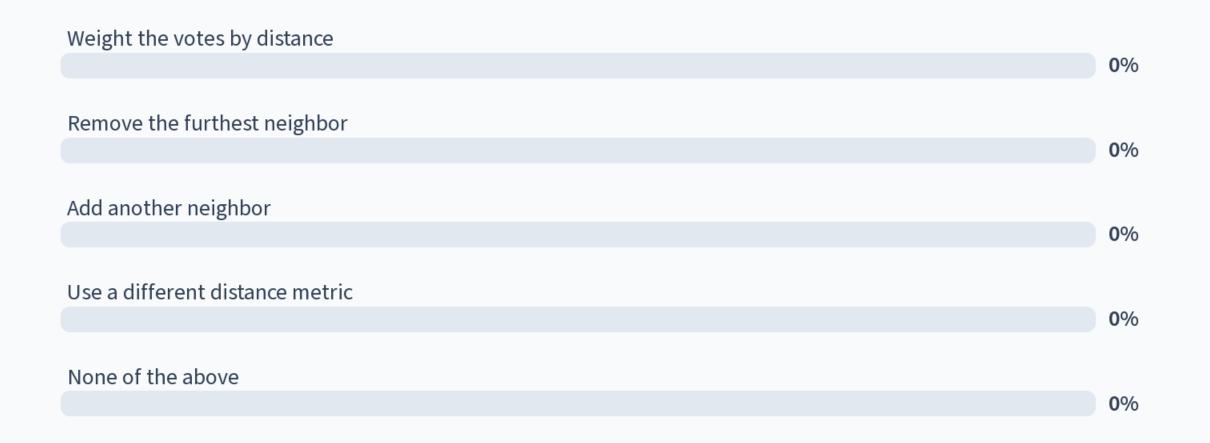
But why limit ourselves to just one neighbor?

- Claim: under certain conditions, as $N \to \infty$, with high probability, the true error rate of the nearest neighbor model ≤ 2 * the Bayes error rate (the optimal classifier)
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k-NearestNeighbors(kNN)

- Classify a point as the most common label among the labels of the ${\it k}$ nearest training points
- Tie-breaking (in case of even k and/or more than 2 classes)
 - Weight votes by distance
 - Remove furthest neighbor
 - Add next closest neighbor
 - Use a different distance metric

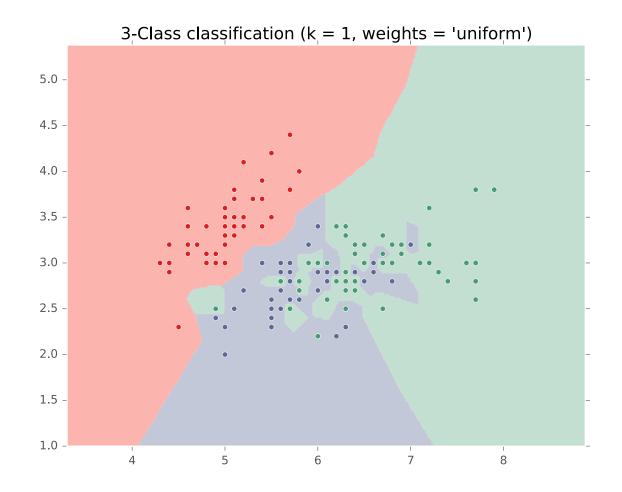
Suppose you have a kNN model with k>1 and 3 possible classes. Which of the following tiebreaking methods is $\it guaranteed$ to break a tie in the majority vote? Select all that apply.

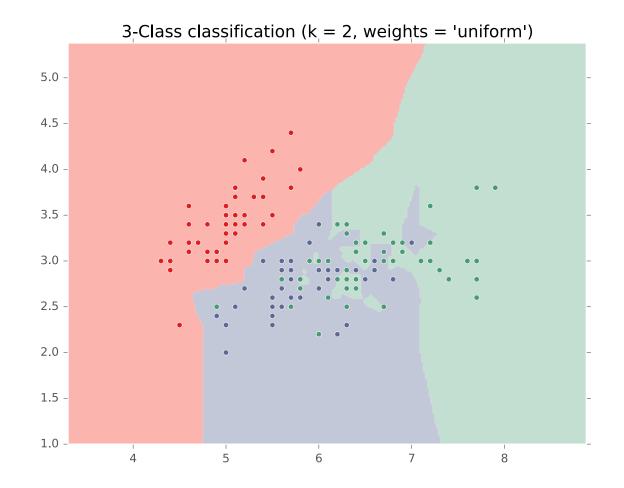


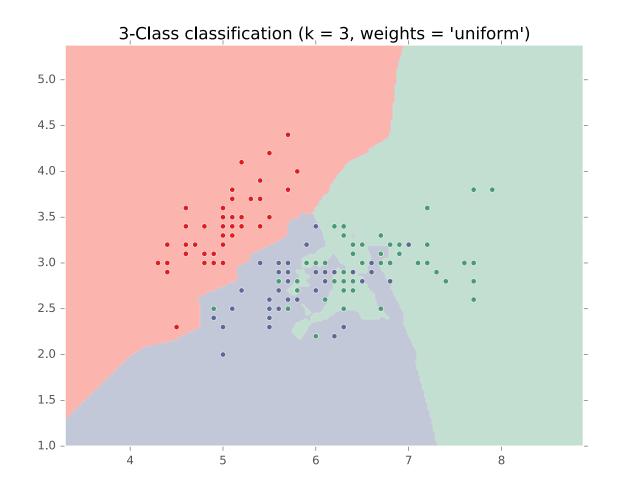
k-NearestNeighbors(kNN):Pseudocode

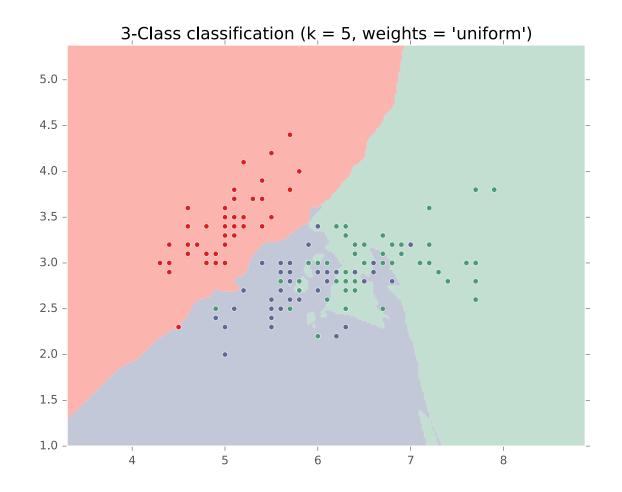
```
def train(\mathcal{D}):
    store \mathcal{D}

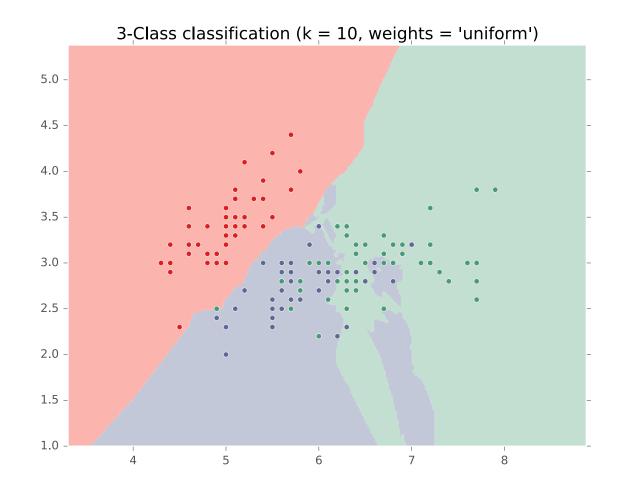
def predict(\mathbf{x}'):
    return majority_vote(labels of the k
    nearest neighbors to \mathbf{x}' in \mathcal{D})
```











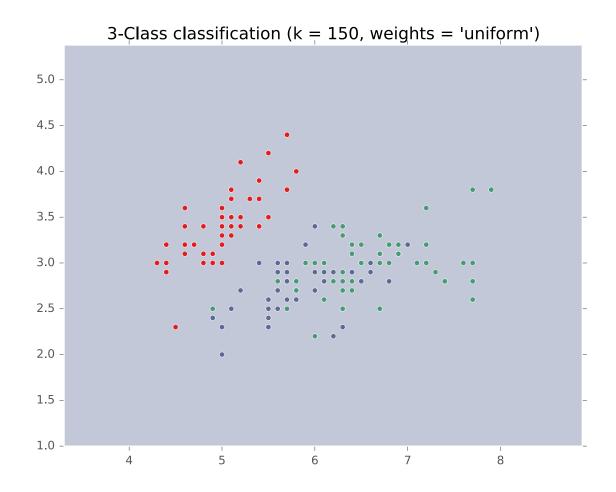












Setting *k*

- When k=1:
 - many, complicated decision boundaries
 - may overfit
- When k = N:
 - no decision boundaries; always predicts the most common label in the training data
 - may underfit
- k controls the complexity of the hypothesis set $\Longrightarrow k$ affects how well the learned hypothesis will generalize

Setting *k*

• Theorem:

- If k is some function of N s.t. $k(N) \to \infty$ and $\frac{k(N)}{N} \to 0$ as $N \to \infty$...
- ... then (under certain assumptions) the true error of a kNN model → the Bayes error rate
- Practical heuristics:

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$$k = \left| \sqrt{N} \right|$$

- k = 3
- Can also set k through (cross-)validation (stay tuned)

kNN and Categorical Features

- kNNs are compatible with categorical features, either by:
 - 1. Converting categorical features into binary ones:

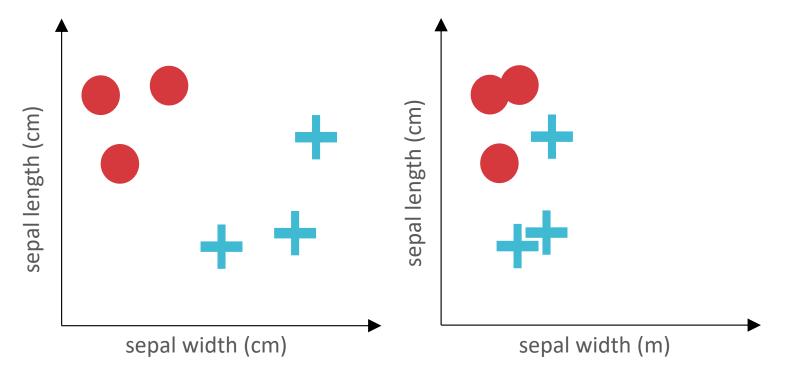
Cholesterol	Normal Cholesterol?	Abnormal Cholesterol?
Normal	 1	0
Normal	1	0
Abnormal	0	1

2. Using a distance metric that works over categorical features e.g., the Hamming distance:

$$d(\mathbf{x}, \mathbf{x}') = \sum_{d=1}^{D} \mathbb{1}(x_d = x'_d)$$

*k*NN: Inductive Bias

• Similar points should have similar labels and *all features* are equivalently important for determining similarity

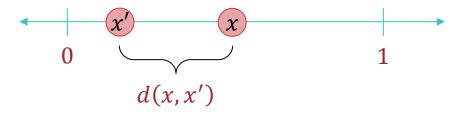


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Feature scale can dramatically influence results!

- The fundamental assumption of kNN is that "similar" points or points close to one another should have the same label
- The closer two points are, the more confident we can be that they will have the same label
- As the dimensionality of the input grows, the less likely it is that two random points will be close
- As the dimensionality of the input grows, it takes more points to "cover" the input space

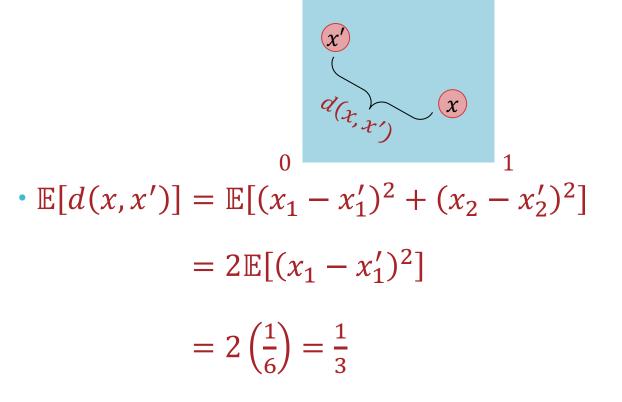
 Suppose you independently draw two one-dimensional points between 0 and 1 uniformly at random:



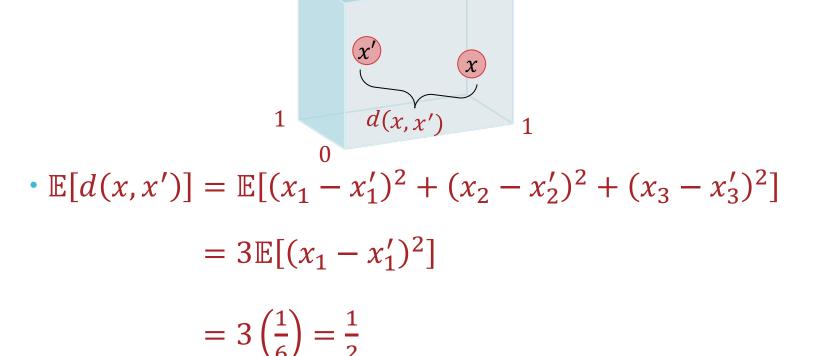
•
$$\mathbb{E}[d(x, x')] = \mathbb{E}[(x - x')^2]$$

= $\mathbb{E}[x^2] - 2\mathbb{E}[x]\mathbb{E}[x'] + \mathbb{E}[x'^2]$
= $2\mathbb{E}[x^2] - 2\mathbb{E}[x]^2 = 2\left(\frac{1}{3}\right) - 2\left(\frac{1}{2}\right)^2 = \frac{1}{6}$

• Suppose you independently draw two two-dimensional points in the unit square uniformly at random:



• Suppose you independently draw two three-dimensional points in the unit cube uniformly at random:



- Assume all dimensions of the input are independent and identically distributed.
- Given N+1 data points, $\mathcal{D}=\{x^{(1)},...,x^{(N)}\}$ and x^* , let $d_+=\max_{x\in\mathcal{D}}\,d(x,x^*)$ and $d_-=\min_{x\in\mathcal{D}}\,d(x,x^*)$
- Then

$$\lim_{D\to\infty} \mathbb{E}\left[\frac{d_+ - d_-}{d}\right] \to 0$$

Curing the Curse of Dimensionality

- More data
- Fewer dimensions
- Blessing of non-uniformity: data from the real world is rarely uniformly distributed across the input space

*k*NN: Pros and Cons

- Pros:
 - Intuitive / explainable
 - No training / retraining
 - Provably near-optimal in terms of true error rate
- Cons:
 - Computationally expensive
 - Always needs to store all data: O(ND)
 - Finding the k closest points in D dimensions: $O(ND + N \log(k))$
 - Can be sped up through clever use of data structures (trades off training and test costs)
 - Can be approximated using stochastic methods
 - Affected by feature scale
 - Suffers from the curse of dimensionality

Key Takeaways

- Real-valued features and decision boundaries
- Nearest neighbor model and generalization guarantees
- kNN "training" and prediction
- Effect of *k* on model complexity
- kNN inductive bias
- Curse of dimensionality