

Modeling Datalog Assertion and Retraction in Linear Logic

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The Road Map

- 1 Introduction
- 2 Problem and Objective
- 3 Technical Hurdles
- 4 The IID^{Full} Interpretation
- 5 Discussions, Future works and Conclusion

Introduction

- Datalog, a Logic Programming Language
- Originally used for implementing deductive databases.
- Maintaining recursive views (logical consequences):
 $\mathcal{P}(\mathcal{B}) = \{p(\vec{t}) \mid \mathcal{P}, \mathcal{B} \vdash p(\vec{t})\}$
- Over past ten years, Datalog has been applied to new domains, e.g. :
 - Implementing network protocols [GW10, LCG⁺06]
 - Distributed ensemble programming [ARLG⁺09]
 - Deductive spreadsheets [Cer07]
- Fact bases \mathcal{B} of such domains are typically highly dynamic (i.e. **assertion** and **retraction**):

$$\begin{array}{lll} \mathcal{P}(\mathcal{B}) & \xrightarrow{+a}_{\mathcal{P}} & \mathcal{P}(\mathcal{B}, a) \quad (Infer) \\ \mathcal{P}(\mathcal{B}, a) & \xrightarrow{-a}_{\mathcal{P}} & \mathcal{P}(\mathcal{B}) \quad (Retract) \end{array}$$

Introduction

- Main challenge and focus so far:
 - Maintaining recursive views in presence of **assertion** and **retraction**.
 - Efficient algorithms and implementations are well-known [ARLG⁺09, CARG⁺12, GMS93, LCG⁺06]
- But...
 - while it is well-known how to implement...
 - lacks logical specification, specifically retraction.

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The Problem

- Consider the path relation, let E be *Edge* and P be *Path*:

$$\mathcal{P} = \begin{cases} r_1 : \forall x, y. E(x, y) \supset P(x, y) \\ r_2 : \forall x, y, z. E(x, y) \wedge P(y, z) \supset P(x, z) \end{cases}$$

- Computing inference: Base Facts \supset Inferred Facts

$$\frac{\mathcal{P}, E(2, 3), P(2, 3) \vdash C}{\boxed{\mathcal{P}}, \boxed{E(2, 3)} \vdash C}$$

- Forward-chaining application of inference rule, until *saturation*.

The Problem

$$\mathcal{P} = \begin{cases} r_1 : \forall x, y. E(x, y) \supset P(x, y) \\ r_2 : \forall x, y, z. E(x, y) \wedge P(y, z) \supset P(x, z) \end{cases}$$

- Assertion, e.g. adding of new base fact $E(3, 4)$:

$$\frac{\mathcal{P}, E(2, 3), P(2, 3), E(3, 4), P(3, 4), P(2, 4) \vdash C}{\frac{\boxed{\mathcal{P}, E(2, 3)}, P(2, 3), E(3, 4), \boxed{P(3, 4)} \vdash C}{\boxed{\mathcal{P}}, E(2, 3), P(2, 3), \boxed{E(3, 4)} \vdash C}}$$

- But what about retraction? E.g. removal of fact $E(2, 3)$:

$$\frac{\frac{\mathcal{P}, E(3, 4), P(3, 4) \vdash C}{??}}{\mathcal{P}, E(2, 3), P(2, 3), E(3, 4), P(3, 4), P(2, 4) \vdash C}$$

The Objective

- Define a logical specification of Datalog that supports **assertion** and **retraction** internally using linear logic.
- Linear logic because
 - Assumptions can grow or shrink as inference rules apply.
 - Facts are not permanent truths, but can be retracted (consumed)

The Objective

Example: Linear logic interpretation (simplified) of the Path program \mathcal{P} :

- $r_1 : \forall x, y. E(x, y) \supset P(x, y)$ interpreted as

$$\begin{aligned}\mathcal{I}_1^{(x,y)} &= E(x, y) \multimap P(x, y) \otimes E(x, y) \otimes \mathcal{R}_1^{(x,y)} \\ \mathcal{R}_1^{(x,y)} &= \boxed{(\tilde{E}(x, y) \multimap \tilde{P}(x, y) \otimes \tilde{E}(x, y))}\end{aligned}$$

- $r_2 : \forall x, y, z. E(x, y) \wedge P(y, z) \supset P(x, z)$ interpreted as

$$\begin{aligned}\mathcal{I}_2^{(x,y,z)} &= E(x, y) \otimes P(y, z) \multimap P(x, z) \otimes E(x, y) \otimes P(y, z) \otimes \mathcal{R}_2^{(x,y,z)} \\ \mathcal{R}_2^{(x,y,z)} &= \boxed{(\tilde{E}(x, y) \multimap \tilde{P}(x, z) \otimes \tilde{E}(x, y)) \& (\tilde{P}(y, z) \multimap \tilde{P}(x, z) \otimes \tilde{P}(y, z))}\end{aligned}$$

- Absorption rules:

$$\mathcal{A}_{\mathcal{P}} = \begin{cases} E(x, y) \otimes \tilde{E}(x, y) \multimap 1 \\ P(x, y) \otimes \tilde{P}(x, y) \multimap 1 \end{cases}$$

- Program interpretation denoted as:

$$\llbracket \mathcal{P} \rrbracket' = \forall x, y. \mathcal{I}_1^{(x,y)}, \forall x, y, z. \mathcal{I}_2^{(x,y,z)}$$

The Objective

- Two-sided intuitionistic linear logic sequent calculus, LV^{obs} :
 $\Gamma; \Delta \longrightarrow C$
- Assertion, e.g. adding of new base fact $E(4, 5)$:

$$\frac{\frac{\frac{\llbracket \mathcal{P} \rrbracket', \mathcal{A}_{\mathcal{P}}; E(2, 3), P(2, 3), \mathcal{R}_1^{(2,3)}, E(3, 4), P(3, 4), \mathcal{R}_1^{(3,4)}, P(2, 4), \mathcal{R}_2^{(2,3,4)} \longrightarrow C}{\llbracket \mathcal{P} \rrbracket', \mathcal{A}_{\mathcal{P}}; \boxed{E(2, 3)}, P(2, 3), \mathcal{R}_1^{(2,3)}, \boxed{E(3, 4)}, \boxed{P(3, 4)}, \mathcal{R}_1^{(3,4)} \longrightarrow C}}{\llbracket \mathcal{P} \rrbracket', \mathcal{A}_{\mathcal{P}}; E(2, 3), P(2, 3), \mathcal{R}_1^{(2,3)}, \boxed{E(3, 4)}} \longrightarrow C$$

- Inference of new facts leaves behind “bookkeeping” information:
 - Specifically retraction rules ($\mathcal{R}_1^{(2,3)}$, $\mathcal{R}_2^{(2,3,4)}$, etc..)
 - Act as “cookie crumbs” that guides retraction

The Objective

Retraction, e.g. removal of fact $E(2, 3)$:

$$\begin{array}{c}
\boxed{\mathbb{P}\mathcal{P}}', \boxed{\mathcal{A}_{\mathcal{P}}}; E(3, 4), P(3, 4), \mathcal{R}_1^{(3,4)} \longrightarrow C \\
\hline
\boxed{\mathbb{P}\mathcal{P}}', \boxed{\mathcal{A}_{\mathcal{P}}}; \boxed{E(2, 3)}, E(3, 4), P(3, 4), \mathcal{R}_1^{(3,4)}, \boxed{\tilde{E}(2, 3)} \longrightarrow C \\
\hline
\boxed{\mathbb{P}\mathcal{P}}', \boxed{\mathcal{A}_{\mathcal{P}}}; E(2, 3), \boxed{P(2, 3)}, E(3, 4), P(3, 4), \mathcal{R}_1^{(3,4)}, \boxed{\tilde{E}(2, 3)}, \boxed{\tilde{P}(2, 3)} \longrightarrow C \\
\hline
\boxed{\mathbb{P}\mathcal{P}}', \mathcal{A}_{\mathcal{P}}; E(2, 3), P(2, 3), \boxed{\mathcal{R}_1^{(2,3)}}, E(3, 4), P(3, 4), \mathcal{R}_1^{(3,4)}, \boxed{\tilde{E}(2, 3)} \longrightarrow C \\
\hline
\boxed{\mathbb{P}\mathcal{P}}', \boxed{\mathcal{A}_{\mathcal{P}}}; \left(\begin{array}{c} E(2, 3), P(2, 3), \mathcal{R}_1^{(2,3)}, E(3, 4), P(3, 4), \\ \mathcal{R}_1^{(3,4)}, \boxed{P(2, 4)}, \boxed{\tilde{E}(2, 3)}, \boxed{\tilde{P}(2, 4)} \end{array} \right) \longrightarrow C \\
\hline
\boxed{\mathbb{P}\mathcal{P}}', \mathcal{A}_{\mathcal{P}}; \left(\begin{array}{c} E(2, 3), P(2, 3), \mathcal{R}_1^{(2,3)}, E(3, 4), P(3, 4), \\ \mathcal{R}_1^{(3,4)}, P(2, 4), \boxed{\mathcal{R}_2^{(2,3,4)}}, \boxed{\tilde{E}(2, 3)} \end{array} \right) \longrightarrow C
\end{array}$$

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Technical Hurdles

Looks like we are done...

Technical Hurdles

Looks like we are done... But wait!

Technical Hurdle 1: Trivial non-termination in assertions

$$\begin{array}{c}
 \vdots \\
 \hline \hline
 \mathbb{P}\mathcal{P}', \mathcal{A}_{\mathcal{P}}; \left(\begin{array}{c} E(2,3), P(2,3), \mathcal{R}_1^{(2,3)}, E(3,4), P(3,4), \\ \mathcal{R}_1^{(3,4)}, P(2,4), \mathcal{R}_2^{(2,3,4)}, P(3,4), \mathcal{R}_1^{(3,4)} \end{array} \right) \longrightarrow C \\
 \hline \hline
 \boxed{\mathbb{P}\mathcal{P}'}; \mathcal{A}_{\mathcal{P}}; E(2,3), P(2,3), \mathcal{R}_1^{(2,3)}, E(3,4), \boxed{P(3,4)}, \mathcal{R}_1^{(3,4)}, P(2,4), \mathcal{R}_2^{(2,3,4)} \longrightarrow C \\
 \hline \hline
 \boxed{\mathbb{P}\mathcal{P}'}; \mathcal{A}_{\mathcal{P}}; \boxed{E(2,3)}, P(2,3), \mathcal{R}_1^{(2,3)}, \boxed{E(3,4)}, \boxed{P(3,4)}, \mathcal{R}_1^{(3,4)} \longrightarrow C \\
 \hline \hline
 \boxed{\mathbb{P}\mathcal{P}'}; \mathcal{A}_{\mathcal{P}}; E(2,3), P(2,3), \mathcal{R}_1^{(2,3)}, \boxed{E(3,4)} \longrightarrow C
 \end{array}$$

Technical Hurdle 2: Inexhaustive retraction

$$\begin{array}{c}
 \mathbb{P}\mathcal{P}', \mathcal{A}_{\mathcal{P}}; P(2,3), \mathcal{R}_1^{(2,3)}, E(3,4), P(3,4), \mathcal{R}_1^{(3,4)}, P(2,4), \mathcal{R}_2^{(2,3,4)} \longrightarrow C \\
 \hline \hline
 \mathbb{P}\mathcal{P}', \boxed{\mathcal{A}_{\mathcal{P}}}; \left(\begin{array}{c} \boxed{E(2,3)}, P(2,3), \mathcal{R}_1^{(2,3)}, E(3,4), P(3,4), \\ \mathcal{R}_1^{(3,4)}, P(2,4), \mathcal{R}_2^{(2,3,4)}, \boxed{\tilde{E}(2,3)} \end{array} \right) \longrightarrow C
 \end{array}$$

Termination in Assertions

- We define an immediate interpretation of Datalog program \mathcal{P} , denoted $\lceil \mathcal{P} \rceil$
- Extend linear logic with *guarded implications*: $A \multimap_a B$
- Can be treated as *negation-by-absence* (i.e. $\neg a \otimes A \multimap B \otimes a$)
- Inference rules in $\lceil \mathcal{P} \rceil$ are guarded by “witnesses”:

$$\begin{aligned}
 \lceil \mathcal{P} \rceil &= \forall x, y. \mathcal{I}_1^{(x,y)}, \forall x, y, z. \mathcal{I}_2^{(x,y,z)} \\
 \mathcal{I}_1^{(x,y)} &= E(x, y) \multimap_{\boxed{I_1^\#(x, y)}} P(x, y) \otimes E(x, y) \\
 \mathcal{I}_2^{(x,y,z)} &= E(x, y) \otimes P(y, z) \multimap_{\boxed{I_2^\#(x, y, z)}} P(x, z) \otimes E(x, y) \otimes P(y, z)
 \end{aligned}$$

- Witnesses $I_1^\#(x, y)$ and $I_2^\#(x, y, z)$ are just normal predicates.
- Derivations can reach *quiescence*: Inference rules can be applied at most once.

Termination in Assertions

Intuitionistic Linear Logic Sequent Calculus, LV^{obs-}

$$\frac{}{\Gamma; \Delta \longrightarrow \otimes \Delta} \text{ (obs)}$$

$$\frac{\Gamma; \Delta \longrightarrow C}{\Gamma; \Delta, 1 \longrightarrow C} (1_L)$$

$$\frac{\Gamma; \Delta, A_i \longrightarrow C}{\Gamma; \Delta, A_1 \& A_2 \longrightarrow C} (\&_{L_i})$$

$$\frac{\Gamma; \Delta, B \longrightarrow C}{\Gamma; \Delta, \Delta', (\otimes \Delta') \multimap B \longrightarrow C} (\multimap_L)$$

$$\frac{\Gamma, A; \Delta, A \longrightarrow C}{\Gamma, A; \Delta \longrightarrow C} \text{ (clone)}$$

$$\frac{\Gamma; \Delta, A_1, A_2 \longrightarrow C}{\Gamma; \Delta, A_1 \otimes A_2 \longrightarrow C} (\otimes_L)$$

$$\frac{t \in \Sigma \quad \Gamma; \Delta, [t/x]A \longrightarrow C}{\Gamma; \Delta, \forall x. A \longrightarrow C} (\forall_L)$$

$$\frac{a \notin \Delta \quad \Gamma; \Delta, B, a \longrightarrow C}{\Gamma; \Delta, \Delta', (\otimes \Delta') \multimap_a B \longrightarrow C} (\multimap_L^-)$$

Exhaustive Retraction

Look at the problem again:

$$\frac{\llbracket \mathcal{P} \rrbracket', \mathcal{A}_{\mathcal{P}}; P(2, 3), \mathcal{R}_1^{(2,3)}, E(3, 4), P(3, 4), \mathcal{R}_1^{(3,4)}, P(2, 4), \mathcal{R}_2^{(2,3,4)} \longrightarrow C}{\llbracket \mathcal{P} \rrbracket', \boxed{\mathcal{A}_{\mathcal{P}}}; \boxed{E(2, 3)}, P(2, 3), \mathcal{R}_1^{(2,3)}, E(3, 4), P(3, 4), \mathcal{R}_1^{(3,4)}, P(2, 4), \mathcal{R}_2^{(2,3,4)}, \boxed{\tilde{E}(2, 3)} \longrightarrow C}$$

- The culprit: **Absorption rule** for E was applied before retraction rules $\mathcal{R}_1^{(2,3)}$ and $\mathcal{R}_2^{(2,3,4)}$.
- We need to guarantee that **retraction rules** are exhaustively applied before **absorption rules**.

Exhaustive Retraction

The solution, use “witnesses” and guarded implications:

$$\begin{aligned}\mathcal{P} &= \boxed{I_1 : \forall x, y. E(x, y) \supset P(x, y)} \quad , \quad I_2 : \forall x, y, z. E(x, y) \wedge P(y, z) \supset P(x, z) \\ \llbracket \mathcal{P} \rrbracket &= \boxed{\forall x, y. \mathcal{I}_1^{(x, y)}} \quad , \quad \forall x, y, z. \mathcal{I}_2^{(x, y, z)}\end{aligned}$$

$$\mathcal{I}_1^{(x, y)} = E(x, y) \multimap_{I_1^\sharp(x, y)} P(x, y) \otimes E(x, y) \otimes \mathcal{R}_1^{(x, y)} \otimes \boxed{E^\sharp(x, y)}$$

$$\mathcal{R}_1^{(x, y)} = (\tilde{E}(x, y) \otimes I_1^\sharp(x, y) \otimes \boxed{E^\sharp(x, y)} \multimap \tilde{P}(x, y) \otimes \tilde{E}(x, y))$$

$$\mathcal{A}_E^{(x, y)} = E(x, y) \otimes \tilde{E}(x, y) \multimap_{\boxed{E^\sharp(x, y)}} (E^\sharp(x, y) \multimap 1)$$

- Witness $E^\sharp(x, y)$ is added when $\mathcal{I}_1^{(x, y)}$ is applied.
- Witness $E^\sharp(x, y)$ is consumed when $\mathcal{R}_1^{(x, y)}$ is applied.
- $\mathcal{A}_E^{(x, y)}$ cannot be applied as long as there is some $E^\sharp(x, y)$.
- Retraction rules involving $E^\sharp(x, y)$ must be applied before absorption rule $\mathcal{A}_E^{(x, y)}$.

Exhaustive Retraction

The solution, use “witnesses” and guarded implications:

$$\begin{aligned}\mathcal{P} &= \boxed{I_1 : \forall x, y. E(x, y) \supset P(x, y)} \quad , \quad I_2 : \forall x, y, z. E(x, y) \wedge P(y, z) \supset P(x, z) \\ \llbracket \mathcal{P} \rrbracket &= \boxed{\forall x, y. \mathcal{I}_1^{(x, y)}} \quad , \quad \forall x, y, z. \mathcal{I}_2^{(x, y, z)}\end{aligned}$$

$$\mathcal{I}_1^{(x, y)} = E(x, y) \multimap_{I_1^\#(x, y)} P(x, y) \otimes E(x, y) \otimes \mathcal{R}_1^{(x, y)} \otimes E^\#(x, y)$$

$$\mathcal{R}_1^{(x, y)} = (\tilde{E}(x, y) \otimes I_1^\#(x, y) \otimes E^\#(x, y) \multimap \tilde{P}(x, y) \otimes \tilde{E}(x, y))$$

$$\mathcal{A}_E^{(x, y)} = E(x, y) \otimes \tilde{E}(x, y) \multimap_{E^\#(x, y)} \boxed{(E^\#(x, y) \multimap 1)}$$

$(E^\#(x, y) \multimap 1)$ eliminates the trailing $E^\#(x, y)$ produced by $\mathcal{A}_E^{(x, y)}$ itself.

$$\frac{a \notin \Delta \quad \Gamma; \Delta, B, \boxed{a} \longrightarrow C}{\Gamma; \Delta, \Delta', (\otimes \Delta') \multimap_a B \longrightarrow C} (\multimap_L^-)$$

Exhaustive Retraction

The solution, use “witnesses” and guarded implications:

$$\begin{aligned}\mathcal{P} &= \boxed{I_1 : \forall x, y. E(x, y) \supset P(x, y)} \quad , \quad I_2 : \forall x, y, z. E(x, y) \wedge P(y, z) \supset P(x, z) \\ \llbracket \mathcal{P} \rrbracket &= \boxed{\forall x, y. \mathcal{I}_1^{(x, y)}} \quad , \quad \forall x, y, z. \mathcal{I}_2^{(x, y, z)}\end{aligned}$$

$$\mathcal{I}_1^{(x, y)} = E(x, y) \multimap_{I_1^\#(x, y)} P(x, y) \otimes E(x, y) \otimes \mathcal{R}_1^{(x, y)} \otimes E^\#(x, y)$$

$$\mathcal{R}_1^{(x, y)} = (\tilde{E}(x, y) \otimes \boxed{I_1^\#(x, y)} \otimes E^\#(x, y) \multimap \tilde{P}(x, y) \otimes \tilde{E}(x, y))$$

$$\mathcal{A}_E^{(x, y)} = E(x, y) \otimes \tilde{E}(x, y) \multimap_{E^\#(x, y)} (E^\#(x, y) \multimap 1)$$

- $I_1^\#(x, y)$ is consumed when retraction rule $\mathcal{R}_1^{(x, y)}$ is applied.
- This allows $E(x, y)$ to be re-asserted in the future.

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The IID^{Full} Interpretation

$\llbracket \mathcal{P} \rrbracket$ is defined as follows:

$$\begin{array}{ll}
 \text{Fact} & \llbracket p(\vec{t}) \rrbracket = p(\vec{t}) \\
 \text{Program} & \left\{ \begin{array}{l} \llbracket D, \mathcal{P} \rrbracket = \llbracket D \rrbracket, \llbracket \mathcal{P} \rrbracket \\ \llbracket \cdot \rrbracket = \cdot \end{array} \right. \\
 \text{Conjunction} & \llbracket b \wedge B \rrbracket = \llbracket b \rrbracket \otimes \llbracket B \rrbracket \\
 \text{Clause} & \left\{ \begin{array}{l} \llbracket r : \forall \vec{x}. B \supset h \rrbracket = \\ \quad \forall \vec{x}. \llbracket B \rrbracket \multimap_{r^\#(\vec{x})} \llbracket h \rrbracket \otimes \llbracket B \rrbracket \otimes \llbracket B^\# \rrbracket \otimes \text{Ret}(B, B, r^\#(\vec{x}), h) \end{array} \right. \\
 \text{Fact base} & \left\{ \begin{array}{l} \llbracket \mathcal{B}, a \rrbracket = \llbracket \mathcal{B} \rrbracket, \llbracket a \rrbracket \\ \llbracket \emptyset \rrbracket = \cdot \end{array} \right.
 \end{array}$$

$$\text{where } \text{Ret}(b \wedge B', B, r^\#(\vec{x}), h) = (\llbracket \tilde{b} \rrbracket \otimes r^\#(\vec{x}) \otimes \llbracket B^\# \rrbracket \multimap \llbracket \tilde{h} \rrbracket \otimes \llbracket \tilde{b} \rrbracket) \& \text{Ret}(B', B, r^\#(\vec{x}), h)$$

$$\text{Ret}(b, B, r^\#(\vec{x}), h) = (\llbracket \tilde{b} \rrbracket \otimes r^\#(\vec{x}) \otimes \llbracket B^\# \rrbracket \multimap \llbracket \tilde{h} \rrbracket \otimes \llbracket \tilde{b} \rrbracket)$$

The IID^{Full} Interpretation

- Dynamic (assertion and retraction) Datalog state transition system:

$$\begin{array}{c}
 \frac{a \notin \Delta \quad \llbracket \mathcal{P} \rrbracket, \mathcal{A}_{\mathcal{P}}; \Delta, a \longrightarrow \otimes \Delta' \quad Quiescent(\Delta', (\llbracket \mathcal{P} \rrbracket, \mathcal{A}_{\mathcal{P}}))}{\Delta \xrightarrow{+a}^{LL} \llbracket \mathcal{P} \rrbracket \Delta'} (Infer) \\
 \frac{a \in \Delta \quad \llbracket \mathcal{P} \rrbracket, \mathcal{A}_{\mathcal{P}}; \Delta, \tilde{a} \longrightarrow \otimes \Delta' \quad Quiescent(\Delta', (\llbracket \mathcal{P} \rrbracket, \mathcal{A}_{\mathcal{P}}))}{\Delta \xrightarrow{-a}^{LL} \llbracket \mathcal{P} \rrbracket \Delta'} (Retract)
 \end{array}$$

- Correctness of assertion and retraction:

Given a Datalog Program \mathcal{P} , for reachable states $\Delta_1, \Delta_1^{\mathcal{R}}, \Delta_1^{\#}$ and $\Delta_2, \Delta_2^{\mathcal{R}}, \Delta_2^{\#}$ such that $\Delta_1 = \llbracket \mathcal{P}(\mathcal{B}_1) \rrbracket$ and $\Delta_2 = \llbracket \mathcal{P}(\mathcal{B}_2) \rrbracket$, then we have the following:

$$\begin{array}{c}
 (\Delta_1, \Delta_1^{\mathcal{R}}, \Delta_1^{\#}) \xrightarrow{\alpha}^{LL} \llbracket \mathcal{P} \rrbracket (\Delta_2, \Delta_2^{\mathcal{R}}, \Delta_2^{\#}) \text{ iff } \mathcal{P}(\mathcal{B}_1) \xrightarrow{\alpha}_{\mathcal{P}} \mathcal{P}(\mathcal{B}_2) \\
 \text{where } \mathcal{P}(\mathcal{B}) = \{p(\vec{t}) \mid \mathcal{P}, \mathcal{B} \vdash p(\vec{t})\}
 \end{array}$$

Note if $\alpha = +a$ we have $\mathcal{B}_2 = \mathcal{B}_1, a$. If $\alpha = -a$ we have $\mathcal{B}_1 = \mathcal{B}_2, a$.

- See Tech-Report for details of the proofs.

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Discussions

- **Cycles** are terminating, thanks to guarded implications:

$$\begin{aligned}\mathcal{P} &= I_1 : \forall x, y. P(x, y) \supset P(y, x) \\ \llbracket \mathcal{P} \rrbracket &= P(x, y) \multimap \boxed{I_1^\#(x, y)} P(y, x) \otimes P(x, y) \otimes P^\#(x, y) \otimes \dots\end{aligned}$$

- **Re-assertions** needed during retraction:
 - Retraction may be excessive.
 - Quiescence only reached after some reassertion of facts:
 - Cause: Multiple inference dependencies, e.g.

$$\begin{aligned}I_1 &: \forall x. A(x) \supset C(x) \\ I_2 &: \forall x. B(x) \supset C(x) \\ I_3 &: \forall x. C(x) \supset D(x)\end{aligned}$$

- See Tech-Report for more details.

Future works and conclusion

- We formalized a Linear Logic interpretation of Datalog:
 - Internally supports assertion and retraction (dynamic updates on base facts)
 - Soundness and completeness
- Future works:
 - Improving the IID^{Full} interpretation: No reassertion.
 - Implementation based on higher order multiset rewritings

A simplified example of our Linear Logic Interpretation

Datalog program \mathcal{P} :

$$\begin{aligned} P(x, y) &:- E(x, y). & - r_1 \\ P(x, z) &:- E(x, y), P(y, z). & - r_2 \end{aligned}$$

Linear logic interpretation $\llbracket \mathcal{P} \rrbracket$:

$$\llbracket \mathcal{P} \rrbracket = \forall x, y. \mathcal{I}_1^{(x, y)} , \forall x, y, z. \mathcal{I}_2^{(x, y, z)}$$

$$\mathcal{I}_1^{(x, y)} = E(x, y) \multimap P(x, y) \otimes E(x, y) \otimes \mathcal{R}_1^{(x, y)}$$

$$\mathcal{R}_1^{(x, y)} = (\tilde{E}(x, y) \multimap \tilde{P}(x, y) \otimes \tilde{E}(x, y))$$

$$\mathcal{I}_2^{(x, y, z)} = E(x, y) \otimes P(y, z) \multimap P(x, z) \otimes E(x, y) \otimes P(y, z) \otimes \mathcal{R}_2^{(x, y, z)}$$

$$\mathcal{R}_2^{(x, y, z)} = (\tilde{E}(x, y) \multimap \tilde{P}(x, z) \otimes \tilde{E}(x, y)) \& (\tilde{P}(y, z) \multimap \tilde{P}(x, z) \otimes \tilde{P}(y, z))$$

$$\mathcal{A}_{\mathcal{P}} = \begin{cases} E(x, y) \otimes \tilde{E}(x, y) \multimap 1 \\ P(x, y) \otimes \tilde{P}(x, y) \multimap 1 \end{cases}$$

Example of Retraction, as Forward-Chaining Proof Search

Intuitionistic Linear Logic Sequent Judgements: $\Gamma; \Delta \longrightarrow C$

Retraction, e.g. removal of fact $E(2, 3)$:

$$\begin{array}{c}
\begin{array}{c} \llbracket \mathcal{P} \rrbracket, \boxed{\mathcal{A}_{\mathcal{P}}} ; E(3, 4), P(3, 4), \mathcal{R}_1^{(3,4)} \longrightarrow C \end{array} \\
\hline
\begin{array}{c} \llbracket \mathcal{P} \rrbracket, \boxed{\mathcal{A}_{\mathcal{P}}} ; \boxed{E(2, 3)}, E(3, 4), P(3, 4), \mathcal{R}_1^{(3,4)}, \boxed{\tilde{E}(2, 3)} \longrightarrow C \end{array} \\
\hline
\begin{array}{c} \llbracket \mathcal{P} \rrbracket, \boxed{\mathcal{A}_{\mathcal{P}}} ; E(2, 3), \boxed{P(2, 3)}, E(3, 4), P(3, 4), \mathcal{R}_1^{(3,4)}, \tilde{E}(2, 3), \boxed{\tilde{P}(2, 3)} \longrightarrow C \end{array} \\
\hline
\begin{array}{c} \llbracket \mathcal{P} \rrbracket, \mathcal{A}_{\mathcal{P}} ; E(2, 3), P(2, 3), \boxed{\mathcal{R}_1^{(2,3)}}, E(3, 4), P(3, 4), \mathcal{R}_1^{(3,4)}, \boxed{\tilde{E}(2, 3)} \longrightarrow C \end{array} \\
\hline
\begin{array}{c} \llbracket \mathcal{P} \rrbracket, \boxed{\mathcal{A}_{\mathcal{P}}} ; \left(\begin{array}{c} E(2, 3), P(2, 3), \mathcal{R}_1^{(2,3)}, E(3, 4), P(3, 4), \\ \mathcal{R}_1^{(3,4)}, \boxed{P(2, 4)}, \tilde{E}(2, 3), \boxed{\tilde{P}(2, 4)} \end{array} \right) \longrightarrow C \end{array} \\
\hline
\begin{array}{c} \llbracket \mathcal{P} \rrbracket, \mathcal{A}_{\mathcal{P}} ; \left(\begin{array}{c} E(2, 3), P(2, 3), \mathcal{R}_1^{(2,3)}, E(3, 4), P(3, 4), \\ \mathcal{R}_1^{(3,4)}, P(2, 4), \boxed{\mathcal{R}_2^{(2,3,4)}}, \boxed{\tilde{E}(2, 3)} \end{array} \right) \longrightarrow C \end{array}
\end{array}$$



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